

Lecture 4: Compactness in Function Spaces

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1 Complete Metric Spaces and Function Spaces

1.1 Complete Metric Space

- **Definition (Cauchy Net in Topological Vector Space)**

A net $\{x_\alpha\}_{\alpha \in I}$ in **topological vector space** X is called **Cauchy** if the net $\{x_\alpha - x_\beta\}_{(\alpha, \beta) \in I \times I}$ **converges to zero**. (Here $I \times I$ is **directed** in the usual way: $(\alpha, \beta) \prec (\alpha', \beta')$ if and only if $\alpha \prec \alpha'$ and $\beta \prec \beta'$.)

- **Definition (Completeness)**

A topological vector space X is **complete** if every Cauchy net converges.

- **Proposition 1.1 (Complete First Countable Topological Vector Space)**

If X is a **first-countable topological vector space** and every **Cauchy sequence** in X converges, then every **Cauchy net** in X converges.

- **Proposition 1.2 (Completeness of Euclidean Space)** [Munkres, 2000]

Euclidean space \mathbb{R}^k is **complete** in either of its usual **metrics**, the **euclidean metric** d or the **square metric** ρ .

- **Lemma 1.3 (Convergence in Product Space is Weak Convergence)** [Munkres, 2000]

Let X be the product space $X = \prod_{\alpha} X_{\alpha}$; let x_n be a sequence of points of X . Then $x_n \rightarrow x$ if and only if $\pi_{\alpha}(x_n) \rightarrow \pi_{\alpha}(x)$ for each α .

- **Proposition 1.4 (Completeness of Countable Product Space)** [Munkres, 2000]

There is a metric for the product space \mathbb{R}^{ω} relative to which \mathbb{R}^{ω} is **complete**.

- **Definition (Uniform Metric in Function Space)**

Let (Y, d) be a metric space; let $\bar{d}(a, b) = \min\{d(a, b), 1\}$ be the **standard bounded metric** on Y derived from d . If $x = (x_{\alpha})_{\alpha \in J}$ and $y = (y_{\alpha})_{\alpha \in J}$ are points of the cartesian product Y^J , let

$$\bar{\rho}(x, y) = \sup \{ \bar{d}(x_{\alpha}, y_{\alpha}) : \alpha \in J \}.$$

It is easy to check that $\bar{\rho}$ is a metric; it is called **the uniform metric** on Y^J corresponding to the metric d on Y .

Note that **the space of all functions** $f : J \rightarrow Y$, **denoted** as Y^J , is a subset of the product space $J \times Y$. We can define uniform metric in the function space: if $f, g : J \rightarrow Y$, then

$$\bar{\rho}(f, g) = \sup \{ \bar{d}(f(\alpha), g(\alpha)) : \alpha \in J \}.$$

- **Proposition 1.5 (Completeness of Function Space Under Uniform Metric)** [Munkres, 2000]

If the space Y is **complete** in the metric d , then the space Y^J is **complete** in the **uniform metric** $\bar{\rho}$ corresponding to d .

- **Definition (Space of Continuous Functions and Bounded Functions)**

Let Y^X be the space of all functions $f : X \rightarrow Y$, where X is a **topological space** and Y is a **metric space with metric** d . Denote the **subspace** of Y^X consisting of all **continuous functions** f as $\mathcal{C}(X, Y)$.

Also denote the set of all **bounded functions** $f : X \rightarrow Y$ as $\mathcal{B}(X, Y)$. (A function f is said to be **bounded** if its image $f(X)$ is a **bounded subset** of the metric space (Y, d) .)

- **Proposition 1.6 (Completeness of $\mathcal{C}(X, Y)$ and $\mathcal{B}(X, Y)$ Under Uniform Metric)** [Munkres, 2000]

Let X be a topological space and let (Y, d) be a metric space. The set $\mathcal{C}(X, Y)$ of **continuous functions** is **closed** in Y^X under the **uniform metric**. So is the set $\mathcal{B}(X, Y)$ of **bounded functions**. Therefore, if Y is **complete**, these spaces are **complete** in the **uniform metric**.

- **Definition (Sup Metric on Bounded Functions)**

If (Y, d) is a metric space, one can define another metric on the set $\mathcal{B}(X, Y)$ of **bounded functions** from X to Y by the equation

$$\rho(x, y) = \sup \{d(f(x), g(x)) : x \in X\}.$$

It is easy to see that ρ is well-defined, for the set $f(X) \cup g(X)$ is **bounded** if both $f(X)$ and $g(X)$ are. The metric ρ is called the sup metric.

- **Theorem 1.7 (Existence of Completion)** [Munkres, 2000]

Let (X, d) be a metric space. There is an **isometric embedding** of X into a **complete metric space**.

- **Definition (Completion)**

Let X be a metric space. If $h : X \rightarrow Y$ is an **isometric embedding** of X into a **complete metric space** Y , then the **subspace** $h(X)$ of Y is a **complete metric space**. It is called the completion of X .

1.2 Compactness in Metric Spaces

- **Remark (Compactness and Completeness)**

How is **compactness** of a metric space X related to **completeness** of X ?

The followings is from the *sequential compactness* and definition of *completeness*:

Proposition 1.8 Every **compact metric space** is **complete**.

The *converse* does not hold – a **complete metric space need not be compact**. It is reasonable to ask what **extra condition** one needs to impose on a complete space to be assured of its compactness. Such a condition is the one called *total boundedness*.

- **Definition (Total Boundedness)**

A metric space (X, d) is said to be **totally bounded** if for every $\epsilon > 0$, there is a **finite covering** of X by ϵ -balls.

- **Theorem 1.9** [Munkres, 2000]

A metric space (X, d) is **compact** if and only if it is **complete** and **totally bounded**.

- **Remark** We now apply this result to find **the compact subspaces** of the space $\mathcal{C}(X, \mathbb{R}^n)$, in the **uniform topology**. We know that a subspace of \mathbb{R}^n is compact if and only if it is **closed** and **bounded**.

One might hope that an analogous result holds for $\mathcal{C}(X, \mathbb{R}^n)$. **But** it does not, even if X is **compact**. One needs to assume that the subspace of $\mathcal{C}(X, \mathbb{R}^n)$ satisfies an **additional**

condition, called *equicontinuity*.

- **Definition (*Equicontinuity*)** [Reed and Simon, 1980, Munkres, 2000]

Let (Y, d) be a *metric space*. Let \mathcal{F} be a *subset* of the function space $\mathcal{C}(X, Y)$ (i.e. $f \in \mathcal{F}$ is continuous). If $x_0 \in X$, the set \mathcal{F} of functions is said to be *equicontinuous at x_0* if given $\epsilon > 0$, there is a neighborhood U of x_0 such that for all $x \in U$ and *all $f \in \mathcal{F}$* ,

$$d(f(x), f(x_0)) < \epsilon.$$

If the set \mathcal{F} is *equicontinuous at x_0* for each $x_0 \in X$, it is said simply to be *equicontinuous* or \mathcal{F} is an *equicontinuous family*.

We say \mathcal{F} is a *uniformly equicontinuous family* if and only if for all $\epsilon > 0$, there exists $\delta > 0$ such that $d(f(x), f(x')) < \epsilon$ whenever $p(x, x') < \delta$ for all $x, x' \in X$ and *every* $f \in \mathcal{F}$.

- **Remark** An *equicontinuous family* of functions is a *family of continuous functions*.
- **Remark *Continuity*** of the function f at x_0 means that *given* f and given $\epsilon > 0$, there exists a neighborhood U of x_0 such that $d(f(x), f(x_0)) < \epsilon$ for $x \in U$. ***Equicontinuity of \mathcal{F}*** means that **a single neighborhood U can be chosen that will work for all the functions f in the collection \mathcal{F} .**
- **Lemma 1.10 (*Total Boundedness \Rightarrow Equicontinuous*)** [Munkres, 2000]
Let X be a *space*; let (Y, d) be a *metric space*. If the subset \mathcal{F} of $\mathcal{C}(X, Y)$ is **totally bounded** under the **uniform metric** corresponding to d , then \mathcal{F} is *equicontinuous* under d .
- **Lemma 1.11 (*Equicontinuous + Compactness \Rightarrow Total Boundedness*)** [Munkres, 2000]
Let X be a *space*; let (Y, d) be a *metric space*; assume X and Y are **compact**. If the subset \mathcal{F} of $\mathcal{C}(X, Y)$ is *equicontinuous* under d , then \mathcal{F} is **totally bounded** under the **uniform** and **sup** metrics corresponding to d .
- **Definition (*Pointwise Bounded*)**
If (Y, d) is a *metric space*, a subset \mathcal{F} of $\mathcal{C}(X, Y)$ is said to be *pointwise bounded* under d if for each $x \in X$, the subset

$$F_a = \{f(a) : f \in \mathcal{F}\}$$

of Y is *bounded* under d .

- **Theorem 1.12 (*Ascoli's Theorem, Classical Version*)**. [Munkres, 2000]
Let X be a **compact** space; let (\mathbb{R}^n, d) denote euclidean space in either the square metric or the euclidean metric; give $\mathcal{C}(X, \mathbb{R}^n)$ the corresponding **uniform topology**. A subspace \mathcal{F} of $\mathcal{C}(X, \mathbb{R}^n)$ has **compact closure** if and only if \mathcal{F} is *equicontinuous* and *pointwise bounded* under d .
- **Corollary 1.13** Let X be **compact**; let d denote either the square metric or the euclidean metric on \mathbb{R}^n ; give $\mathcal{C}(X, \mathbb{R}^n)$ the corresponding **uniform topology**. A subspace \mathcal{F} of $\mathcal{C}(X, \mathbb{R}^n)$ is **compact** if and only if it is **closed, bounded** under the **sup metric ρ** , and *equicontinuous* under d .
- **Remark (*Ascoli's Theorem, Sequence Version*)** [Reed and Simon, 1980]
Let $\{f_n\}$ be a family of **uniformly bounded equicontinuous functions** on $[0, 1]$. Then **some subsequence $\{f_{n,m}\}$ converges uniformly** on $[0, 1]$.

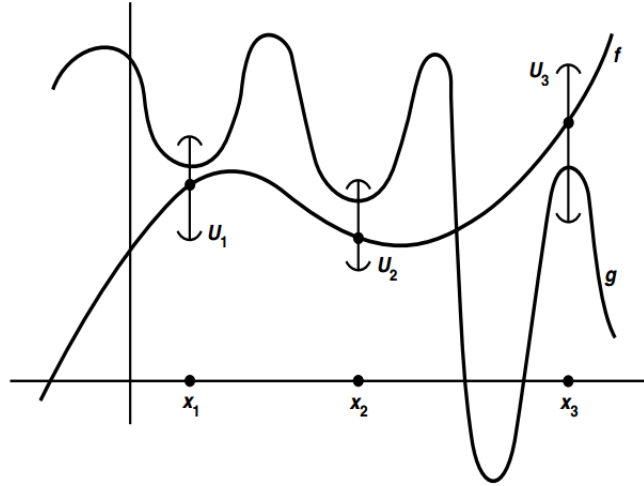


Figure 1: The function g in neighborhood of f in topology of pointwise convergence. [Munkres, 2000]

1.3 Pointwise and Compact Convergence

- **Definition** (*Topology of Pointwise Convergence / Point-Open Topology*)

Given a point x of the set X and an open set U of the space Y , let

$$S(x, U) = \{f : f \in Y^X \text{ and } f(x) \in U\}.$$

The sets $S(x, U)$ are a **subbasis** for *topology* on Y^X , which is called the topology of pointwise convergence (or the point-open topology)

- **Remark** (*Basis of Point-Open Topology*)

The general *basis element* for this topology is a *finite intersection* of subbasis elements $S(x, U)$. Thus a typical **basis element** about the function f consists of all functions g that are “close” to f at **finitely many points**. Such a *neighborhood* is illustrated in Figure 1; it consists of all functions g whose graphs *intersect the three vertical intervals* pictured.

- **Remark** *The topology of pointwise convergence on Y^X is the product topology.*

If we replace X by J and denote the general element of J by α to make it look more familiar, then the set $S(\alpha, U)$ of all functions $x : J \rightarrow Y$ such that $x(\alpha) \in U$ is just the subset $\pi_\alpha^{-1}(U)$ of Y^J , which is the *standard subbasis element* for the product topology.

- **Proposition 1.14** (*Pointwise Convergence Topology*)[Munkres, 2000]

A sequence f_n of functions **converges** to the function f in the **topology of pointwise convergence** **if and only if** for **each** x in X , the sequence $f_n(x)$ of **points of** Y converges to the point $f(x)$.

- **Remark** Compare the *subbasis* of the *point-open topology* on function space Y^X and the *weak topology* on space X

$$S(x, U) = \{f : f \in Y^X \text{ and } f(x) \in U\} \quad \text{point-open topology.}$$

$$B(f, U) = \{x : x \in X \text{ and } f(x) \in U\} \quad \text{weak topology.}$$

- **Example** (Pointwise Convergence Does Not Preserve Continuity)

Consider the space \mathbb{R}^I , where $I = [0, 1]$. The sequence (f_n) of continuous functions given by $f_n(x) = x^n$ converges in the **topology of pointwise convergence** to the function f defined by

$$f(x) = \begin{cases} 0 & \text{for } 0 \leq x < 1 \\ 1 & \text{for } x = 1 \end{cases},$$

This example shows that the subspace $\mathcal{C}(I, \mathbb{R})$ of continuous functions is **not closed** in \mathbb{R}^I in the topology of pointwise convergence. Note that $\mathcal{C}(I, \mathbb{R})$ is **closed** in \mathbb{R}^I under **uniform topology** due to *Uniform Limit theorem*.

- **Definition (Topology of Compact Convergence)**

Let (Y, d) be a metric space; let X be a topological space. Given an element f of Y^X , a **compact subspace** C of X , and a number $\epsilon > 0$, let $B_C(f, \epsilon)$ denote the set of all those elements g of Y^X for which

$$\sup\{d(f(x), g(x)) : x \in C\} < \epsilon.$$

The sets $B_C(f, \epsilon)$ form a **basis** for a topology on Y^X . It is called the **topology of compact convergence** (or sometimes the “**topology of uniform convergence on compact sets**”).

- **Proposition 1.15 (Topology of Uniform Convergence in Compact Sets)** [Munkres, 2000]

A sequence $f_n : X \rightarrow Y$ of functions converges to the function f in the **topology of compact convergence** if and only if for **each compact subspace** C of X , the sequence $f_n|_C$ converges **uniformly** to $f|_C$.

- **Definition** A space X is said to be **compactly generated** if it satisfies the following condition: A set A is **open** in X if $A \cap C$ is **open** in C for each **compact subspace** C of X .

- **Lemma 1.16** [Munkres, 2000]

If X is **locally compact**, or if X satisfies the **first countability axiom**, then X is **compactly generated**.

- The crucial fact about compactly generated spaces is the following:

- **Lemma 1.17 (Continuous Extension on Compact Generated Space)** [Munkres, 2000]

If X is compactly generated, then a function $f : X \rightarrow Y$ is **continuous** if for each **compact subspace** C of X , the restricted function $f|_C$ is **continuous**.

- **Theorem 1.18 ($\mathcal{C}(X, Y)$ on Compact Generated Space)** [Munkres, 2000]

Let X be a **compactly generated space**: let (Y, d) be a metric space. Then $\mathcal{C}(X, Y)$ is **closed** in Y^X in the **topology of compact convergence**.

- **Corollary 1.19 (Compact Convergence Limit)** [Munkres, 2000]

Let X be a **compactly generated space**; let (Y, d) be a metric space. If a sequence of **continuous** functions $f_n : X \rightarrow Y$ converges to f in the **topology of compact convergence**, then f is **continuous**.

- **Remark (Useful Topologies on Y^X)**

1. **Uniform Topology**: generated by the **basis**

$$B_U(f, \epsilon) = \left\{ g \in Y^X : \sup_{x \in X} \bar{d}(f(x), g(x)) < \epsilon \right\}$$

It corresponds to **the uniform convergence** of f_n to f in Y^X . $\mathcal{C}(X, Y)$ is **closed** in Y^X under the *uniform topology*, following the *Uniform Limit Theorem*.

2. **Topology of Pointwise Convergence**: generated by the **basis**

$$\begin{aligned} B_{U_1, \dots, U_n}(x_1, \dots, x_n, \epsilon) &= \bigcap_{i=1}^n S(x_i, U_i) \\ &= \{f \in Y^X : f(x_1) \in U_1, \dots, f(x_n) \in U_n\}, \quad 1 \leq n < \infty. \end{aligned}$$

It corresponds to **the pointwise convergence** of f_n to f in Y^X . $\mathcal{C}(X, Y)$ is **not closed** in Y^X under the *topology of pointwise convergence*

3. **Topology of Compact Convergence**: generated by the **basis**

$$B_C(f, \epsilon) = \left\{ g \in Y^X : \sup_{x \in C} d(f(x), g(x)) < \epsilon \right\}.$$

It corresponds to **the uniform convergence** of f_n to f in Y^X for $x \in C$. $\mathcal{C}(X, Y)$ is **closed** in Y^X under the *topology of compact convergence* **if X is compactly generated**.

- **Theorem 1.20 (Relationship between Topologies on Y^X)** [Munkres, 2000]
Let X be a space; let (Y, d) be a metric space. For the function space Y^X , one has the following **inclusions of topologies**:

$$(\text{uniform}) \supseteq (\text{compact convergence}) \supseteq (\text{pointwise convergence}).$$

If X is **compact**, the **first two** coincide, and if X is **discrete**, the **second two** coincide.

- **Remark** Note that both *uniform topology* and *topology of compact convergence* made specific use of the metric d for the space Y , i.e. it can only be defined when the image of function Y is a metric space.

But **the topology of pointwise convergence** does not use the definition of metric d in Y . In fact, **it is defined for any image space Y** .

- **Definition (Compact-Open Topology on Continuous Function Space)**
Let X and Y be topological spaces. If C is a **compact subspace** of X and U is an *open* subset of Y , define

$$S(C, U) = \{f \in \mathcal{C}(X, Y) : f(C) \subseteq U\}.$$

The sets $S(C, U)$ form a **subbasis** for a *topology* on $\mathcal{C}(X, Y)$ that is called **the compact-open topology**.

- **Proposition 1.21 (Compact-Open on $\mathcal{C}(X, Y) = \text{Compact Convergence}$)** [Munkres, 2000]
Let X be a space and let (Y, d) be a metric space. On the set $\mathcal{C}(X, Y)$, the **compact-open topology** and the **topology of compact convergence** coincide.

- **Corollary 1.22** (*Compact Convergence on $\mathcal{C}(X, Y)$ Need Not d*) [Munkres, 2000]
Let Y be a metric space. The **compact convergence topology** on $\mathcal{C}(X, Y)$ does **not** depend on the **metric** of Y . Therefore if X is **compact**, the **uniform topology** on $\mathcal{C}(X, Y)$ does not depend on the metric of Y .

- **Remark** The fact that the definition of *the compact-open topology* does not involve a *metric* is just one of its useful features.

Another is the fact that it satisfies the requirement of “**joint continuity**”. Roughly speaking, this means that the expression $f(x)$ is *continuous* not only in the *single* “variable x ”, but is *continuous jointly in both* the x and f .

- **Theorem 1.23** (*Compact-Open Topology \Rightarrow Joint Continuity for x and f*)
Let X be **locally compact Hausdorff**; let $\mathcal{C}(X, Y)$ have the **compact-open topology**. Then the map

$$e : X \times \mathcal{C}(X, Y) \rightarrow Y$$

defined by the equation

$$e(x, f) = f(x)$$

is **continuous**. The map e is called the evaluation map.

- **Definition** Given a function $f : X \times Z \rightarrow Y$, there is a corresponding function $F : Z \rightarrow \mathcal{C}(X, Y)$, defined by the equation

$$(F(z))(x) = f(x, z).$$

Conversely, given $F : Z \rightarrow \mathcal{C}(X, Y)$, this equation defines a corresponding function $f : X \times Z \rightarrow Y$. We say that F is the map of Z into $\mathcal{C}(X, Y)$ that is induced by f .

- **Proposition 1.24** Let X and Y be spaces; give $\mathcal{C}(X, Y)$ the **compact-open topology**. If $f : X \times Z \rightarrow Y$ is **continuous**, then **so is** the induced function $F : Z \rightarrow \mathcal{C}(X, Y)$. The **converse** holds if X is **locally compact Hausdorff**.
- **Theorem 1.25** (*Ascoli’s Theorem, General Version*). [Munkres, 2000]
Let X be a space and let (Y, d) be a **metric** space. Give $\mathcal{C}(X, Y)$ the **topology of compact convergence**; let \mathcal{F} be a subset of $\mathcal{C}(X, Y)$.

1. If \mathcal{F} is **equicontinuous** under d and the set

$$F_a = \{f(a) : f \in \mathcal{F}\}$$

has **compact closure** for each $a \in X$, then \mathcal{F} is **contained in a compact subspace** of $\mathcal{C}(X, Y)$.

2. The **converse** holds if X is **locally compact Hausdorff**.

- **Remark** Compare with classical version, we see generalizations:

1. X need not to be **compact**; \Rightarrow does not even need X to be topological. \Leftarrow holds when X is **locally compact Hausdorff**.

2. $\mathcal{C}(X, Y)$ is under **compact-open topology** which is *weaker* than **uniform topology**, i.e. we does not require convergence of sequence *uniformly* but only *uniformly in a compact subset*.
3. \mathcal{F} does not need to be **pointwise bounded** under d . In other word, the set

$$F_a = \{f(a) : f \in \mathcal{F}\}$$

need not to be **bounded** but need to have **compact closure** for each $a \in X$. Note that for metric space Y , if Y is finite dimensional, it is the same requirement as boundness. But compact closure is stronger than bounded.

- **Proposition 1.26** (**Equicontinuity + Pointwise Convergence \Rightarrow Compact Convergence**) [Munkres, 2000]
 Let (Y, d) be a metric space; let $f_n : X \rightarrow Y$ be a sequence of **continuous** functions; let $f : X \rightarrow Y$ be a function (not necessarily continuous). Suppose f_n converges to f in the **topology of pointwise convergence**. If $\{f_n\}$ is **equicontinuous**, then f is **continuous** and f_n converges to f in the **topology of compact convergence**.

2 Compactness in Banach Space

Remark (**Compactness in Function Space**)

The importance of **compactness** in analysis is well-known, and the fact tha *closed bounded sets* are *compact* in *finite dimensional spaces* lies at the heart of much of the analysis on these spaces. **Unfortunately**, as we have seen, this is *not true* in *infinite dimensional spaces*.

There are **two main compactness results** in *function space*:

1. The **Ascoli's theorem**: Let X be a *compact Hausdorff space*; let d denote either the square metric or the euclidean metric on \mathbb{R}^n ; give $\mathcal{C}(X, \mathbb{R}^n)$ the corresponding **uniform topology**. A subspace \mathcal{F} of $\mathcal{C}(X, \mathbb{R}^n)$ is **compact** if and only if it is **closed, bounded** under the **sup metric ρ** , and **equicontinuous** under d .
2. The **Banach-Alaoglu theorem**: Let X be a *Banach space*. The **unit ball** in X^* , $\{f \in X^* : \|f\| \leq 1\}$ is **compact** in the **weak* topology**.

In this section we will show that a *partial analogue* of this result can be obtained in **infinite dimensions** if we adopt a *weaker definition of the convergence* of a sequence than the usual definition.

2.1 Strong and Weak Convergence

- **Definition** (**Strong Convergence**). [Kreyszig, 1989]
 A sequence (x_n) in a normed space X is said to be **strongly convergent** (or **convergent in the norm**) if there is an $x \in X$ such that

$$\lim_{n \rightarrow \infty} \|x_n - x\| = 0.$$

This is written $\lim_{n \rightarrow \infty} x_n = x$ or simply $x_n \rightarrow x$ is called the **strong limit** of (x_n) , and we say that (x_n) *converges strongly* to x .

- **Definition (Weak Convergence).** [Kreyszig, 1989]

A sequence (x_n) in a normed space X is said to be **weakly convergent** if there is an $x \in X$ such that for **every** $f \in X^*$,

$$\lim_{n \rightarrow \infty} f(x_n) = f(x).$$

This is written $x_n \xrightarrow{w} x$ or $x_n \rightharpoonup x$. The element x is called **the weak limit** of (x_n) , and we say that (x_n) **converges weakly to x** .

- **Remark** For weak convergence, we see it as convergence of *real numbers* $s_n = f(x_n)$ in \mathbb{R} .
- **Remark (Weak Convergence Analysis is Common)**

Weak convergence has various applications throughout analysis (for instance, in the *calculus of variations, the general theory of differential equations and probability theory*).

The concept illustrates **a basic principle of functional analysis**, namely, the fact that **the investigation of spaces is often related to that of their dual spaces**, i.e. *probing a variable by using a test functional*.

- **Remark** In *Hilbert space* \mathcal{H} , we say $x_n \xrightarrow{w} x$ if there exists an $x \in \mathcal{H}$ such that for all $y \in \mathcal{H}$

$$\lim_{n \rightarrow \infty} \langle x_n, y \rangle = \langle x, y \rangle.$$

Note that given a set of orthonormal basis (e_n) , we have $f(e_n) := \langle e_n, y \rangle$ and from Bessel inequality

$$\begin{aligned} \sum_{n=1}^{\infty} |\langle e_n, y \rangle|^2 &\leq \|y\|^2 < \infty \\ \Rightarrow \lim_{n \rightarrow \infty} |\langle e_n, y \rangle| &\rightarrow 0 \\ \Rightarrow e_n &\xrightarrow{w} 0. \end{aligned}$$

But $\|e_n - e_m\| \not\rightarrow 0$, (e_n) does not converge in norm (strongly).

- **Lemma 2.1 (Weak Convergence).**

Let (x_n) be a **weakly convergent** sequence in a normed space X , say, $x_n \xrightarrow{w} x$. Then:

1. The weak limit x of (x_n) is **unique**.
2. Every **subsequence** of (x_n) converges weakly to x .
3. The sequence $(\|x_n\|)$ is **bounded**.

- **Proposition 2.2 (Strong and Weak Convergence).** [Kreyszig, 1989]

Let (x_n) be a sequence in a normed space X . Then:

1. **Strong convergence implies weak convergence with the same limit.**
2. The converse of (1) is **not** generally true.
3. If $\dim X < \infty$, then **weak convergence implies strong convergence**.

- **Remark** From above, we see that in **finite dimensional normed spaces** the distinction between **strong** and **weak convergence** disappears completely.

2.2 Weak Topology

- **Remark** The weak convergence, $x_n \xrightarrow{w} x$, can be considered as *convergence of net* $\{x_n\}_{n=1}^{\infty}$ in the **weak topology**.
- **Definition** (**Weak Topology on a Set S**) [Reed and Simon, 1980]
Let \mathcal{F} be a family of functions from a set S to a topological vector space (X, \mathcal{T}) . The **\mathcal{F} -weak** (or simply **weak**) **topology** on S is the weakest topology for which **all the functions** $f \in \mathcal{F}$ are **continuous**.
- **Remark** (**Construction of Weak Topology**) [Reed and Simon, 1980]
To construct a **\mathcal{F} -weak topology** on S , we take the family of **all finite intersections of sets** of the form $f^{-1}(U)$ where $f \in \mathcal{F}$ and $U \in \mathcal{T}$. The collections of these finite intersections of sets **form a basis of the \mathcal{F} -weak topology**.

In other word, **the subbasis** for the **\mathcal{F} -weak topology** on S is of form

$$\mathcal{S} = \{f^{-1}(U) : f \in \mathcal{F}, \text{ and } U \in \mathcal{T}\}$$

And the basis of \mathcal{T}

$$\begin{aligned} \mathcal{B} &= \{f_1^{-1}(U_1) \cap \dots \cap f_k^{-1}(U_k) : f_1, \dots, f_k \in \mathcal{F}, U_1, \dots, U_k \in \mathcal{T}, 1 \leq k < \infty\} \\ B \in \mathcal{B} &\Rightarrow B = \{x : f_1(x) \in U_1, \dots, f_k(x) \in U_k\}, 1 \leq k < \infty \\ &= \{x : (f_1(x), \dots, f_k(x)) \in U\}. \end{aligned}$$

The basis element is called a **k -dimensional cylinder set**.

- **Remark** Given a topology on Y and a family of functions in $Y^X = \{f : X \rightarrow Y\}$, \mathcal{F} -weak topology is **a natural topology** on X without additional information.

A product topology on Y^ω can be seen as a \mathcal{F} -weak topology when $\mathcal{F} = \{\pi_\alpha : \prod_i Y_i \rightarrow Y_\alpha\}$.

- **Remark** A set S equipped with **\mathcal{F} -weak topology** **has little knowledge on itself besides the output of functions** $f \in \mathcal{F}$ from a family \mathcal{F} . The induced topology through a family of functions thus does not tell much besides the behavior of its output.

For instance, S is the space of hidden states, $\mathcal{F} = \{f_1, \dots, f_n\} \subset 2^S$ is a series of binary statistical tests, the weak topology on S *partition the domain according to the output of each test*.

- **Remark** By construction, the **neighborhood base** of each point $x \in S$ under the **\mathcal{F} -weak topology** is contained in the pre-images $\{f_n^{-1}(U_n)\}$ for **finitely many** of $(f_n) \in \mathcal{F}$.
- **Definition** (**Weak Topology on Banach Space**)
Let X be a **Banach space** with dual space X^* . The **weak topology** on X is the **weakest topology** on X so that **$f(x)$ is continuous for all $f \in X^*$** .
- **Remark** For infinite dimensional Banach spaces, **the weak topology does not arise from a metric**. This is one of the main reasons we have introduced topological spaces.
- **Remark** Thus a **neighborhood base at zero** for **the weak topology** is given by the sets of the form

$$N(f_1, \dots, f_n; \epsilon) = \{x : |f_j(x)| < \epsilon; j = 1, \dots, n\}$$

that is, neighborhoods of zero contain *cylinders with finite-dimensional open bases*. A net $\{x_\alpha\}$ converges *weakly* to x , written $x_\alpha \xrightarrow{w} x$, if and only if $f(x_\alpha) \rightarrow f(x)$ for all $f \in X^*$.

• **Proposition 2.3** [Reed and Simon, 1980]

1. The weak topology is **weaker** than **the norm topology**, that is, every weakly open set is norm open.
2. Every **weakly convergent** sequence is **norm bounded**.
3. The weak topology is a **Hausdorff** topology.

• **Proposition 2.4 (Weak Topology on Hilbert Space)** [Reed and Simon, 1980]

Let \mathcal{H} be a **Hilbert space**. Let $\{\varphi_\alpha\}_{\alpha \in I}$ be an **orthonormal basis** for \mathcal{H} . Given a sequence $\psi_n \in \mathcal{H}$, let

$$\psi_n^{(\alpha)} = \langle \psi_n, \varphi_\alpha \rangle$$

be the coordinates of ψ_n . Then $\psi_n \rightarrow \psi$ in the **weak topology** (or $\psi_n \xrightarrow{w} \psi$) **if and only if**

1. $\psi_n^{(\alpha)} \rightarrow \psi^{(\alpha)}$ for each α ; and
2. $\|\psi_n\|$ is **bounded**.

Proof: Suppose $\psi_n \xrightarrow{w} \psi$; then (1) follows by definition and (2) comes from the fact that every weakly convergent sequence is norm bounded.

On the other hand, let (1) and (2) hold and let $\mathcal{F} \subset \mathcal{H}$ be the subspace of *finite linear combinations* of the φ_α . By (1), $\langle \psi_n, \varphi_\alpha \rangle \rightarrow \langle \psi, \varphi_\alpha \rangle$ if $\varphi \in \mathcal{F}$. Using the fact that \mathcal{F} is dense, (2), and an $\epsilon/3$ argument, the weak convergence follows. ■

• **Proposition 2.5 (Weak Topology of $\mathcal{C}(X)$ on Compact Hausdorff Space)** [Reed and Simon, 1980]

Let X be a **compact Hausdorff** space and consider the **weak topology on $\mathcal{C}(X)$** (i.e. $\mathcal{C}(X, \mathbb{R})$). Let $\{f_n\}$ be a sequence in $\mathcal{C}(X)$. Then $f_n \rightarrow f$ in the **weak topology** (or $f_n \xrightarrow{w} f$) **if and only if**

1. $f_n(x) \rightarrow f(x)$ for each $x \in X$; and
2. $\|f_n\|$ is **bounded**.

Proof: For if $f_n \xrightarrow{w} f$, then (1) holds since $f \rightarrow f(x)$ is an element of $\mathcal{C}(X)^*$ and (2) comes from the fact that every weakly convergent sequence is norm bounded.

On the other hand, if (1) and (2) hold, then

$$|f_n(x)| \leq \sup_n \|f_n\|_\infty$$

which is L^1 with respect to any *Baire measure* μ . Thus, by the *dominated convergence theorem*, for any $\mu \in \mathcal{M}_+(X)$, $\int f_n d\mu \rightarrow \int f d\mu$. Since any $\lambda \in \mathcal{M}(X) = \mathcal{C}(X)^*$ is a *finite linear combination* of measures in $\mathcal{M}_+(X)$, we conclude that $f_n \rightarrow f$ weakly. ■

• **Proposition 2.6 (Banach Space Weak Continuity = Norm Continuity)** [Reed and Simon, 1980]

A linear functional f on a **Banach space** is **weakly continuous** if and only if it is **norm continuous**.

2.3 Weak* Topology

- **Definition (Weak* Topology on Banach Space)**

Let X be a *normed vector space* and X^* be its dual space. The weak* topology on X^* is the *weakest topology on X^** so that $f(x)$ is **continuous for all $x \in X$** .

- **Remark** The *weak* topology* can be considered as a topology induced by $x \in X$ on dual space X^* , i.e. a topology on functional space on X induced by point in X .

In fact, the weak* topology is the topology of pointwise convergence:

$$f_\alpha \rightarrow f \quad \Leftrightarrow \quad f_\alpha(x) \rightarrow f(x) \text{ for all } x \in X.$$

Moreover, the weak* topology is the product topology on product space \mathbb{R}^X .

- **Definition (Y -Weak Topology $\sigma(X, Y)$)**

Let X be a *vector space* and let Y be a *family of linear functionals* on X which **separates points** of X . That is, for any $x_1 \neq x_2$ in X , there exists a $f \in Y$ so that $f(x_1) \neq f(x_2)$. Then the Y -weak topology on X , written $\sigma(X, Y)$, is the *weakest topology on X* for which all the functionals in Y are *continuous*.

- **Remark** Y -weak topology $\sigma(X, Y)$ is the \mathcal{F} -weak topology when domain of \mathcal{F} is a *vector space* and \mathcal{F} is a *family of linear functionals*.
- **Remark** Because Y is assumed to *separate points*, $\sigma(X, Y)$ is a **Hausdorff topology** on X . Note that

1. the weak topology on X is the $\sigma(X, X^*)$ topology
2. the weak* topology on X^* is the $\sigma(X^*, X)$ topology

The $\sigma(X, Y)$ topology depends only on **the vector space generated by Y** so we henceforth suppose that Y is a *vector space*.

- **Remark** Notice that *the weak* topology is even weaker than the weak topology*.

$$\text{the norm topology} \subset \text{the weak topology} \subseteq \text{the weak* topology}$$

- **Remark** As one might expect, X is reflexive if and only if the *weak* and *weak* topologies coincide*, and many *characterizations of reflexivity* depend on relations involving the *weak* and *weak* topologies*.

- **Proposition 2.7** ($\sigma(X, Y)$ Topology = Pointwise Convergence Topology on X) [Reed and Simon, 1980]

The $\sigma(X, Y)$ -continuous linear functionals on X are **precisely Y** , in particular the only *weak* continuous functionals on X^** are the **elements of X** .

- **Theorem 2.8 (The Banach-Alaoglu Theorem)** [Reed and Simon, 1980]

Let X^* be the dual of some Banach space, X . Then **the unit ball in X^*** , $\{f \in X^* : \|f\| \leq 1\}$ is compact in the weak* topology.

- **Corollary 2.9 (The Banach-Alaoglu Theorem, Sequential Version)** [Rynne and Youngson, 2007]

If X is **separable** and $\{f_n\}$ is a **bounded sequence** in X^* , then $\{f_n\}$ has a weak* convergent subsequence.

- **Theorem 2.10 (Kakutani's Theorem)** [Rynne and Youngson, 2007]
 X is **reflexive** Banach space if and only if the unit ball in X , $\{x \in X : \|x\| \leq 1\}$ is compact in the weak topology.
- **Corollary 2.11** [Rynne and Youngson, 2007]
If X is **reflexive** Banach space and $\{x_n\}$ is a **bounded** sequence in X , then $\{x_n\}$ has a **weakly convergent subsequence**.
- **Corollary 2.12** [Rynne and Youngson, 2007]
If X is **reflexive** Banach space and $M \subseteq X$ is **bounded, closed and convex**, then any sequence in M has a **subsequence** which is **weakly convergent** to an element of M .
- **Exercise 2.13** [Rynne and Youngson, 2007]
Suppose that X is **reflexive** Banach space, M is a **closed, convex subset** of X , and $y \in X \setminus M$. Show that there is a point $y_M \in M$ such that

$$y - y_M = \inf \{y - x : x \in M\}.$$

Show that this result is **not true** if the assumption that M is **convex** is omitted.

- **Example (Convergence in Distribution)**
Convergence in distribution is also called **weak convergence** in probability theory [Folland, 2013]. In functional analysis, however, **weak convergence** is actually reserved for a different mode of convergence, while **the convergence in distribution** is **the weak* convergence** on $\mathcal{M}(X)$.

In general, it is actually **not a mode of convergence of functions f_n itself** but instead is **the convergence of bounded linear functionals $\int f d\mu_n$** . Equivalently, it is **the convergence of measures F_n on $\mathcal{B}(\mathbb{R})$** .

$$\begin{array}{ll} \text{weak convergence} & \int f_n d\mu \rightarrow \int f d\mu, \quad \forall \mu \in \mathcal{M}(X), \\ \text{convergence in distribution} & \int f d\mu_n \rightarrow \int f d\mu, \quad \forall f \in \mathcal{C}_0(X) \end{array}$$

Definition (Cumulative Distribution Function) [Van der Vaart, 2000]

Let $(\Omega, \mathcal{F}, \mu)$ be a probability space. Given any real-valued measurable function $\xi : \Omega \rightarrow \mathbb{R}$, we define the **cumulative distribution function** $F : \mathbb{R} \rightarrow [0, \infty]$ of ξ to be the function

$$F_\xi(\lambda) := \mu(\{x \in X : \xi(x) \leq \lambda\}) = \int_X \mathbf{1}_{\{\xi(x) \leq \lambda\}} d\mu(x).$$

Definition (Converge in Distribution) [Van der Vaart, 2000]

Let $\xi_n : \Omega \rightarrow \mathbb{R}$ be a sequence of real-valued *measurable functions*, and $\xi : \Omega \rightarrow \mathbb{R}$ be another measurable function. We say that ξ_n **converges in distribution** to ξ if the cumulative distribution function $F_n(\lambda)$ of ξ_n converges pointwise to the cumulative distribution function $F(\lambda)$ of ξ at all $\lambda \in \mathbb{R}$ for which F is continuous. Denoted as $\xi_n \xrightarrow{F} \xi$ or $\xi_n \xrightarrow{d} \xi$ or $\xi_n \rightsquigarrow \xi$.

$$\xi_n \xrightarrow{d} \xi \Leftrightarrow F_n(\lambda) \rightarrow F(\lambda), \text{ for all } \lambda \in \mathbb{R}$$

Theorem 2.14 (The Portmanteau Theorem). [Van der Vaart, 2000]

The following statements are equivalent.

1. $X_n \rightsquigarrow X$.
2. $\mathbb{E}[h(X_n)] \rightarrow \mathbb{E}[h(X)]$ for all **continuous functions** $h : \mathbb{R}^d \rightarrow \mathbb{R}$ that are non-zero only on a **closed and bounded** set.
3. $\mathbb{E}[h(X_n)] \rightarrow \mathbb{E}[h(X)]$ for all **bounded continuous functions** $h : \mathbb{R}^d \rightarrow \mathbb{R}$.
4. $\mathbb{E}[h(X_n)] \rightarrow \mathbb{E}[h(X)]$ for all **bounded measurable functions** $h : \mathbb{R}^d \rightarrow \mathbb{R}$ for which $\mathbb{P}(X \in \{x : h \text{ is continuous at } x\}) = 1$.

We can reformulate the definition of *convergence in distribution* as below:

Definition [Wellner et al., 2013]

Let (\mathcal{X}, d) be a *metric space*, and $(\mathcal{X}, \mathcal{B})$ be a *measurable space*, where \mathcal{B} is **the Borel σ -field on \mathcal{X}** , the smallest σ -field containing *all the open balls* (as the basis of *metric topology* on \mathcal{X}). Let $\{\mathcal{P}_n\}$ and \mathcal{P} be **Borel probability measures** on $(\mathcal{X}, \mathcal{B})$.

Then the sequence \mathcal{P}_n **converges in distribution** to \mathcal{P} , which we write as $\mathcal{P}_n \rightsquigarrow \mathcal{P}$, if and only if

$$\int_{\Omega} f d\mathcal{P}_n \rightarrow \int_{\Omega} f d\mathcal{P}, \quad \text{for all } f \in \mathcal{C}_b(\mathcal{X}).$$

Here $\mathcal{C}_b(\mathcal{X})$ denotes the set of *all bounded, continuous, real functions on \mathcal{X}* .

We can see that **the convergence in distribution** is actually **a weak* convergence**. That is, it is **the weak convergence of bounded linear functionals** $I_{\mathcal{P}_n} \xrightarrow{w^*} I_{\mathcal{P}}$ on the space of all probability measures $\mathcal{P}(\mathcal{X}) \simeq (\mathcal{C}_b(\mathcal{X}))^*$ on $(\mathcal{X}, \mathcal{B})$ where

$$I_{\mathcal{P}} : f \mapsto \int_{\Omega} f d\mathcal{P}.$$

Note that the $I_{\mathcal{P}_n} \xrightarrow{w^*} I_{\mathcal{P}}$ is equivalent to $I_{\mathcal{P}_n}(f) \rightarrow I_{\mathcal{P}}(f)$ for all $f \in \mathcal{C}_b(\mathcal{X})$.

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