

# Lecture 4: Gaussian measure

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# 1 Definitions

## 1.1 Probability measure on infinite dimensional function space

- Denote  $\mathcal{B}^1 \equiv \mathcal{B}(\mathbb{R})$  as the Borel  $\sigma$ -algebra on  $\mathbb{R}$  and  $\mathcal{B}^n \equiv \mathcal{B}(\mathbb{R}^n)$  as the Borel  $\sigma$ -algebra on  $\mathbb{R}^n, n \geq 1$ . Consider the sample space  $\Omega$  as a locally convex Hausdorff topological space, where the algebra of cylinders  $\mathcal{C}_0$  and cylindrical  $\sigma$ -algebra  $\mathcal{C}$  is defined. Note that  $\mathcal{C}$  is the  $\sigma$ -algebra generated by  $\mathcal{C}_0$  and  $\mathcal{C} \subset \mathcal{B} \equiv \mathcal{B}(\Omega)$ , where  $\mathcal{B}(\Omega)$  is the Borel  $\sigma$ -algebra on  $\Omega$ . Let  $\Omega^*$  be the dual space of continuous linear functionals on  $\Omega$  consists of the random variable  $\xi : \Omega \rightarrow \mathbb{R}$ , which is  $(\mathcal{B}, \mathcal{B}^1)$  measurable. Here

Note that the cylinder set

$$C_\xi[A; t_1, \dots, t_n] \equiv \{\omega \mid (\xi_{t_1}(\omega), \dots, \xi_{t_n}(\omega)) \in A\} \in \mathcal{C}; \quad A \in \mathcal{B}^n, \forall n \geq 1$$

- Here consider the random function as  $\xi : T \times \Omega \rightarrow \mathbb{R}$ , and for each subset  $N = \{t_1, \dots, t_n\}$ ,  $\xi_N : (\Omega, \mathcal{B}) \rightarrow (\mathbb{R}^n, \mathcal{B}^n)$ ,  $n \geq 1$ . On the other hand, for fixed  $\omega$ , the whole sample-path  $\xi_t(\omega)$  is seen as a function in  $\mathbb{R}^T$  (usually smooth, or integrable functions s.t. structure of  $T$ ). Therefore, the random function  $\xi$  is a mapping  $(\Omega, \mathcal{B}) \rightarrow (\mathbb{R}^T, \mathcal{B}^T)$ . Here  $\mathcal{B}^T \equiv \mathcal{B}(\mathbb{R}^T)$  is the Borel  $\sigma$ -algebra on function space  $\mathbb{R}^T$ , with respect to which each coordinate functional (evaluation functional)  $\pi_t : \mathbb{R}^T \rightarrow \mathbb{R}$ ,  $\pi_t(x) = x(t)$ , are  $(\mathcal{B}^T, \mathcal{B}^1)$  measurable.
- We can define the probability measure  $\mathcal{P}$  on the cylindrical  $\sigma$ -algebra  $\mathcal{C}$  and for locally convex Hausdorff topological space  $\Omega$ ,  $\mathcal{P}$  can be uniquely extended to the Borel  $\sigma$ -algebra  $\mathcal{B}$ . Therefore, the probability measure  $\mathbb{P}$  on Borel set of  $\mathbb{R}$  can be induced from  $\mathcal{P}$  via the measurable function  $\xi \in \Omega^*$ ; i.e.,

$$\mathbb{P}(A) \equiv \mathcal{P}\{\omega \in \Omega \mid \xi(\omega) \in A\} = \mathcal{P} \circ \xi^{-1}(A), \quad A \in \mathcal{B}^1, \quad (1)$$

- Similarly, the probability measure  $\mathbb{P}$  on function space  $\mathbb{R}^T$  can be induced from the measurable random function  $\xi : (\Omega, \mathcal{B}) \rightarrow (\mathbb{R}^T, \mathcal{B}^T)$ ; i.e.,

$$\mathbb{P}(A) \equiv \mathcal{P}\{\omega \in \Omega \mid \xi \equiv \xi(\cdot, \omega) \in A\} = \mathcal{P} \circ \xi^{-1}(A), \quad A \in \mathcal{B}^T.$$

The above  $\mathbb{P}$  is said to be the *distribution of random function*  $\xi \equiv \xi(\cdot, \omega)$ .

- In particular, for any  $n \geq 1$ , any  $A \in \mathcal{B}^n \subset \mathcal{B}^T$ ,  $\mathbb{P}$  can be defined via each  $n$ -dimensional cylinder set  $C_\xi[A; t_1, \dots, t_n] \in \mathcal{C}$ .

$$\begin{aligned} \mathbb{P}(A) &\equiv \mathcal{P}(C_\xi[A_n; t_1, \dots, t_n]) \\ &= \mathcal{P}\{\omega \in \Omega \mid (\xi_{t_1}(\omega), \dots, \xi_{t_n}(\omega)) \in A_n\} \\ &= \mathcal{P} \circ \xi_{T_n}^{-1}(A), \quad A_n \in \mathcal{B}^n \\ &= \mathcal{P}[(\xi_{t_1}, \dots, \xi_{t_n}) \in A_n], \end{aligned} \quad (2)$$

where  $\xi_{T_n} = \xi \circ \pi_{T_n}$ ,  $\xi : (\Omega, \mathcal{B}) \rightarrow (\mathbb{R}^T, \mathcal{B}^T)$  and  $\pi_N : (\mathbb{R}^T, \mathcal{B}^T) \rightarrow (\mathbb{R}^n, \mathcal{B}^n)$  as  $\pi_{T_n}(f) = (f_{t_1}, \dots, f_{t_n})$ ,  $T_n = \{t_1, \dots, t_n\} \subset T$ ,  $n \geq 1$  is the evaluation map. The above formula holds for all  $n \geq 1$ ,  $(t_1, \dots, t_n) \subset T$ .

This is called a *finite  $n$ -dimensional joint distribution* of random function  $\xi$ .

Note that each cylinder set can be obtained from the evaluation map . Then

$$C_\xi[A; N] = (\hat{\pi}_{T_n}(\xi))^{-1}(A); A \in \mathcal{B}^n$$

where  $\hat{\pi}_t : \mathbb{R}^{T \times \Omega} \rightarrow \mathbb{R}^\Omega : \xi. \mapsto \xi_t$  is considered as the coordinate operator (evaluation operator).

- For a nondecreasing sequence of sets  $A_n \uparrow A$ ,  $A_n = \pi_{T_n} A_{n+1} \subset A_{n+1}$ ,  $n \geq 1$  and  $T_n = [t_1, \dots, t_n] \uparrow T$ , where  $T_{n+1} = T_n \cup \{t_{n+1}\}$ , the cylinder sets  $C_\xi[A_n; T_n] \downarrow C_\xi[A; T] \equiv \bigcap_{n=1}^\infty C_\xi[A_n; T_n]$ .

Therefore the *distribution of random function*  $\xi.$ ,  $\mathbb{P}$ , is completely determined by all its finite  $n$ -dimensional joint distribution; i.e.,

$$\begin{aligned} \mathbb{P}(A) &= \mathcal{P}(C_\xi[A; T]) \\ &= \mathcal{P}\left(\lim_{n \rightarrow \infty} C_\xi[A_n; T_n]\right) \\ &= \sum_{n \rightarrow \infty} \mathcal{P}(C_\xi[A_n; T_n]) \\ &= \sum_{n \rightarrow \infty} \mathbb{P}(A_n), \end{aligned}$$

where  $A_n = \pi_{T_n} A$  for any  $n \geq 1$ , any  $T_n \subset T$ , any  $A \in \mathcal{B}^T$ .

## 1.2 Important functional, operators

- Define the *barycenter*  $\omega_a \in \Omega$  of a measure  $\mathcal{P}$  if for any continuous linear functional (random variable)  $\xi \in \Omega^*$ ,

$$\xi(\omega_a) = \int_\Omega \xi(\omega) \mathcal{P}(d\omega) \equiv m(\xi), \quad (3)$$

where  $m \in \Omega^{**}$  is a linear functional on random variable  $\xi \in \Omega^*$ , called *mean* functional.

- The linear operator  $K : \Omega^* \rightarrow \Omega$  is called the *covariance operator* of a measure  $\mathcal{P}$  if for any  $\xi, \eta \in \Omega^*$ , the following equality holds,

$$\begin{aligned} \xi(K(\eta)) &= \int_\Omega \xi(\omega - \omega_a) \eta(\omega - \omega_a) \mathcal{P}(d\omega) \\ &= \int_\Omega (\xi(\omega) - \xi(\omega_a)) (\eta(\omega) - \eta(\omega_a)) \mathcal{P}(d\omega) \\ &= \int_\Omega (\xi(\omega) - m(\xi)) (\eta(\omega) - m(\eta)) \mathcal{P}(d\omega) \end{aligned} \quad (4)$$

- For  $\xi$  and  $\eta \in \Omega^*$ , so  $\xi(\omega) = \langle \omega, \xi \rangle$  and  $\eta(\omega) = \langle \omega, \eta \rangle$ , where  $\langle \cdot, \cdot \rangle : \Omega \times \Omega^* \rightarrow \mathbb{R}$  is the *duality bilinear products*, so the covariance operator  $K$  corresponds to

$$\begin{aligned} \hat{K}(\xi, \eta) &= \int_\Omega \xi(\omega - \omega_a) \eta(\omega - \omega_a) \mathcal{P}(d\omega) \\ &= \int_\Omega \langle \omega - \omega_a, \xi \rangle \langle \omega - \omega_a, \eta \rangle \mathcal{P}(d\omega) \\ &= \langle K\eta, \xi \rangle \equiv \xi(K(\eta)) \end{aligned} \quad (5)$$

where  $\widehat{K} : \Omega^* \times \Omega^* \rightarrow \mathbb{R}$  is a functional on  $\Omega^* \times \Omega^*$ .

- Note that  $K$  is self-adjoint, i.e.  $\xi(K\eta) = \eta(K\xi)$ , or  $\langle K\eta, \xi \rangle = \langle K\xi, \eta \rangle$ .
- Define the *characteristic functional* of measure  $\mathcal{P}$  as a complex-valued functional on  $\Omega^*$  given by the formula,

$$\phi_{\mathcal{P}}(\xi) = \int_{\Omega} \exp(j \xi(\omega)) \mathcal{P}(d\omega). \quad (6)$$

### 1.3 Gaussian measure

- A measure  $\mathcal{P}$  defined on some algebra that contains  $\mathcal{C}$  is called *Gaussian* if the distribution for any (continuous) *linear* functional  $\xi \in X^*$  with respect to the measure  $\mathcal{P}$  is a Gaussian distribution in  $\mathbb{R}$ ; i.e.,

$$\mathcal{P} \circ \xi^{-1} = \mathcal{N}(\omega_a, \sigma^2) \quad (7)$$

for some  $m, \sigma$ .

- For any *finite-dimensional joint distribution*, we see that

$$\mathcal{P} \circ \xi_T^{-1} = \mathcal{N}(m, K), \quad (8)$$

where  $m$  is the mean functional and  $K$  is covariance operator.

- Denote the class of all Radon Gaussian measures on the Borel  $\sigma$ -algebra  $\mathcal{B}$  of  $\Omega$  as  $\mathcal{G}(\Omega)$ , and the subclass of all centered Radon Gaussian measures as  $\mathcal{G}_0(\Omega)$ .

## 2 Theorem

### 3 Examples