

Lecture 6: Martingale

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Contents

1	Conditional Expectation	2
2	Martingale	4

1 Conditional Expectation

- **Definition** (*Conditional Expectation*) [Resnick, 2013]

Let $(\Omega, \mathcal{F}, \mathcal{P})$ be a probability space and $\mathcal{G} \subset \mathcal{F}$ be a sub- σ -algebra. Suppose $X \in L^1(\Omega, \mathcal{F}, \mathcal{P})$. There exists a function $\mathbb{E}[X|\mathcal{G}]$, called the **conditional expectation** of X **with respect to** \mathcal{G} such that

1. $\mathbb{E}[X|\mathcal{G}]$ is \mathcal{G} -**measurable** and **integrable with respect to** \mathcal{P} .
2. $\mathbb{E}[X|\mathcal{G}]$ satisfies **the functional equation**:

$$\int_G X d\mathcal{P} = \int_G \mathbb{E}[X|\mathcal{G}] d\mathcal{P}, \quad \forall G \in \mathcal{G}.$$

- **Remark** To *prove the existence* of such a random variable,

1. consider first the case of **nonnegative** X . Define a measure ν on \mathcal{G} by

$$\nu(G) = \int_G X d\mathcal{P} = \int_\Omega X \mathbf{1}_G d\mathcal{P}.$$

This measure is *finite* because X is *integrable*, and it is **absolutely continuous** with respect to \mathcal{P} . By the *Lebesgue-Radon-Nikodym Theorem*, there is a \mathcal{G} -measurable function f such that

$$\nu(G) = \int_G f d\mathcal{P}.$$

This f has properties (1) and (2).

2. If X is *not necessarily nonnegative*, $\mathbb{E}[X_+|\mathcal{G}] - \mathbb{E}[X_-|\mathcal{G}]$ clearly has the required properties.

- **Remark** As \mathcal{G} increases, condition (1) becomes **weaker** and condition (2) becomes **stronger**.

- **Remark** Let $(\Omega, \mathcal{F}, \mathcal{P})$ be a probability space, with $\mathcal{G} \subset \mathcal{F}$ a sub- σ -algebra, define

$$\mathcal{P}[A|\mathcal{G}] = \mathbb{E}[\mathbf{1}_A|\mathcal{G}]$$

for all $A \in \mathcal{F}$.

- **Remark** By definition, the conditional expectation is a **Radon-Nikodym derivative** of $d\nu|_{\mathcal{G}} = X d\mathcal{P}|_{\mathcal{G}}$ w.r.t. $d\mathcal{P}|_{\mathcal{G}}$ within \mathcal{G} .

$$\mathbb{E}[X|\mathcal{G}] := \frac{X d\mathcal{P}|_{\mathcal{G}}}{d\mathcal{P}|_{\mathcal{G}}} = X|_{\mathcal{G}}.$$

Thus $\mathbb{E}[X|\mathcal{G}]$ is the **projection of X on sub σ -algebra \mathcal{G}** .

- **Remark** (*Conditioning on Random Variables*)

By definition, conditioning on random variables $(X_t, t \in T)$ on (Ω, \mathcal{B}) can be expressed as

$$\mathbb{E}[X|X_t, t \in T] \equiv \mathbb{E}[X|\sigma(X_t, t \in T)],$$

where $\sigma(X_t, t \in T)$ is the σ -algebra generated by the cylinder set

$$C_n[A] \equiv \{\omega : (X_t(\omega), 1 \leq t \leq n) \in A\} \in \mathcal{B}, \quad A \in \mathcal{B}(\mathbb{R}^n), \forall n$$

- **Remark** (*σ -Algebra Generated by Partition of Sample Space*)

As above, assume that the sub σ -algebra \mathcal{G} is generated by a **partition** B_1, B_2, \dots of Ω , then for $X \in L^1(\Omega, \mathcal{F}, \mathcal{P})$,

$$\mathbb{E}[X|B_i] = \int X d\mathcal{P}(X|B_i) = \int_{B_i} X d\mathcal{P} / \mathcal{P}(B_i)$$

where $\mathcal{P}(X|B_i)$ is the conditional probability defined in previous section. If $\mathcal{P}(B_i) = 0$, then $\mathbb{E}[X|B_i] = 0$. We claim that

1.

$$\mathbb{E}[X|\mathcal{G}] = \sum_{i=1}^{\infty} \mathbb{E}[X|B_i] \mathbb{1}_{B_i}, \quad a.s.$$

2. For any $A \in \mathcal{F}$,

$$\mathcal{P}(A|\mathcal{G}) = \sum_{i=1}^{\infty} \mathcal{P}(A|B_i) \mathbb{1}_{B_i}, \quad a.s.$$

- **Remark** Both $P[A|\mathcal{F}]$ and $\mathbb{E}[X|\mathcal{F}]$ are random variables from $\Omega \rightarrow \mathbb{R}$. Formally speaking,

$$\begin{aligned} P[(X, Y) \in A | \sigma(X)]_{\omega} &\equiv P[(X(\omega), Y) \in A] \\ &= P\{\omega' : (X(\omega), Y(\omega')) \in A\} \\ &\equiv f(X(\omega)) \\ &= \nu|_{\sigma(X)}(A) \\ \mathbb{E}[(X, Y) | \sigma(X)]_{\omega} &= \lim_{\substack{m(A) \rightarrow 0 \\ \omega \in A \in \sigma(X)}} \frac{P\{\omega' : (X(\omega), Y(\omega')) \in A\}}{m(A)} \end{aligned}$$

It is the expected value of X for someone who knows for each $E \in \mathcal{F}$, whether or not $\omega \in E$, which E itself remains unknown.

- **Proposition 1.1** (*Properties of Conditional Expectation*) [Resnick, 2013]

Let $(\Omega, \mathcal{F}, \mathcal{P})$ be a probability space and $\mathcal{G} \subset \mathcal{F}$ be a sub- σ -algebra. Suppose $X, Y \in L^1(\Omega, \mathcal{F}, \mathcal{P})$ and $\alpha, \beta \in \mathbb{R}$.

1. (**Linearity**): $\mathbb{E}[\alpha X + \beta Y | \mathcal{G}] = \alpha \mathbb{E}[X | \mathcal{G}] + \beta \mathbb{E}[Y | \mathcal{G}]$;
2. (**Projection**): If X is \mathcal{G} -measurable, then $\mathbb{E}[X | \mathcal{G}] = X$ almost surely.
3. (**Conditioning on Indiscrete σ -Algebra**):

$$\mathbb{E}[X | \{\emptyset, \Omega\}] = \mathbb{E}[X].$$

4. (**Monotonicity**): If $X \geq 0$, then $\mathbb{E}[X | \mathcal{G}] \geq 0$ almost surely. Similarly, if $X \geq Y$, then $\mathbb{E}[X | \mathcal{G}] \geq \mathbb{E}[Y | \mathcal{G}]$ almost surely.
5. (**Modulus Inequality**):

$$|\mathbb{E}[X | \mathcal{G}]| \leq \mathbb{E}[|X| | \mathcal{G}].$$

6. (**Monotone Convergence Theorem**): If $\{X_n\}_{n=1}^\infty \subset L^1(\Omega, \mathcal{F}, \mathcal{P})$, $0 \leq X_1 \leq X_2 \leq \dots$ is a **monotone sequence of non-negative** random variables and $X_n \rightarrow X$ then

$$\lim_{n \rightarrow \infty} \mathbb{E}[X_n | \mathcal{G}] = \mathbb{E}\left[\lim_{n \rightarrow \infty} X_n | \mathcal{G}\right] = \mathbb{E}[X | \mathcal{G}].$$

7. (**Fatou Lemma**): If $\{X_n\}_{n=1}^\infty \subset L^1(\Omega, \mathcal{F}, \mathcal{P})$, and $X_n \geq 0$ for all n , then

$$\mathbb{E}\left[\liminf_{n \rightarrow \infty} X_n | \mathcal{G}\right] \leq \liminf_{n \rightarrow \infty} \mathbb{E}[X_n | \mathcal{G}]$$

8. (**Dominated Convergence Theorem**): If $\{X_n\}_{n=1}^\infty \subset L^1(\Omega, \mathcal{F}, \mathcal{P})$ and $|X_n| \leq Z$, where $Z \in L^1(\Omega, \mathcal{F}, \mathcal{P})$ is a random variable, $X_n \rightarrow X$ almost surely, then

$$\lim_{n \rightarrow \infty} \mathbb{E}[X_n | \mathcal{G}] = \mathbb{E}\left[\lim_{n \rightarrow \infty} X_n | \mathcal{G}\right] = \mathbb{E}[X | \mathcal{G}], \quad a.s.$$

9. (**Product Rule**): If Y is \mathcal{G} -measurable,

$$\mathbb{E}[X Y | \mathcal{G}] = Y \mathbb{E}[X | \mathcal{G}], \quad a.s.$$

10. (**Smoothing**): For $\mathcal{F}_1 \subset \mathcal{F}_0 \subset \mathcal{F}$,

$$\begin{aligned} \mathbb{E}[\mathbb{E}[X | \mathcal{F}_0] | \mathcal{F}_1] &= \mathbb{E}[X | \mathcal{F}_1] \\ \mathbb{E}[\mathbb{E}[X | \mathcal{F}_1] | \mathcal{F}_0] &= \mathbb{E}[X | \mathcal{F}_1]. \end{aligned}$$

Note that $\mathbb{E}[X | \mathcal{F}_1]$ is **smoother** than $\mathbb{E}[X | \mathcal{F}_0]$. Moreover

$$\mathbb{E}[X] = \mathbb{E}[X | \{\emptyset, \Omega\}] = \mathbb{E}[\mathbb{E}[X | \mathcal{F}_0] | \{\emptyset, \Omega\}] = \mathbb{E}[\mathbb{E}[X | \mathcal{F}_0]].$$

11. (**The Conditional Jensen's Inequality**). Let ϕ be a **convex** function, $\phi(X) \in L^1(\Omega, \mathcal{F}, \mathcal{P})$. Then almost surely

$$\phi(\mathbb{E}[X | \mathcal{G}]) \leq \mathbb{E}[\phi(X) | \mathcal{G}]$$

2 Martingale

References

Sidney I Resnick. *A probability path*. Springer Science & Business Media, 2013.