# Lecture 2: Banach Space

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## 1 Normed Linear Space

- **Definition** A *metric space* is a set M and a real-valued function  $d(\cdot, \cdot): M \times M \to \mathbb{R}$  which satisfies:
  - 1. (Non-Negativity)  $d(x,y) \geq 0$
  - 2. (**Definiteness**) d(x,y) = 0 if and only if x = y
  - 3. (**Symmetric**) d(x,y) = d(y,x)
  - 4. (Triangle Inequality)  $d(x, z) \le d(x, y) + d(y, z)$

The function d is called a <u>metric</u> on M. The metric space M equipped with metric d is denoted as (M, d).

- Remark Note that the definition of a *metric space* is only about the *topology* of the space. In the field of functional analysis, we are mostly concerned about *the vector space*, i.e. a space that equipped with algebraic operations such as vector addition and scalar multiplications. In order to make the *metric topological structure compatible* with *the algebraic structure of vector space*, we need to introduce additional function such as the *norm*.
- Definition (Normed Linear Space)

A <u>normed linear space</u> is a vector space, V, over  $\mathbb{R}$  (or  $\mathbb{C}$ ) and a function,  $\|\cdot\|:V\to\mathbb{R}$  which satisfies:

- 1. (*Non-Negativity*):  $||v|| \ge 0$  for all v in V;
- 2. (**Positive Definiteness**): ||v|| = 0 if and only if v = 0;
- 3. (Absolute Homogeneity)  $\|\alpha v\| = |\alpha| \|v\|$  for all v in V and  $\alpha$  in  $\mathbb{R}$  (or  $\mathbb{C}$ )
- 4. (Subadditivity / Triangle Inequality)  $||v + w|| \le ||v|| + ||w||$  for all v and w in V

We denote the normed linear space as  $(V, \|\cdot\|)$ .

- Remark If the function  $p: V \to \mathbb{R}$  only satisfies the condition 1, 3 and 4 (without positive definiteness), it is called a <u>semi-norm</u>. The 1. non-negativity condition can be derived by the 3. homogeneity and 4. subadditivity conditions.
- Remark A normed linear space  $(V, \|\cdot\|)$  is a metric space with induced metric

$$d(x,y) = ||x - y||$$
, for all  $x, y \in V$ 

• Definition (Bounded Linear Operator)

A <u>bounded linear transformation</u> (or <u>bounded operator</u>) is a mapping  $T:(X, \|\cdot\|_X) \to (Y, \|\cdot\|_Y)$  from a normed linear space X to a normed linear space Y that satisfies

- 1. (*Linearity*)  $T(\alpha x + \beta y) = \alpha T(x) + \beta T(y)$  for all  $x, y \in X$ ,  $\alpha, \beta \in \mathbb{R}$  or  $\mathbb{C}$
- 2. (**Boundedness**)  $||Tx||_Y \leq C ||x||_X$  for small  $C \geq 0$ .

The smallest such C is called the **norm** of T, written ||T|| or  $||T||_{X,Y}$ . Thus

$$||T|| := \sup_{||x||_X = 1} ||Tx||_Y$$

- Remark A linear operator T is a homomorphism of a vector space (its domain) into another vector space, that is, T preserves the two operations of vector space.
- Proposition 1.1 [Reed and Simon, 1980, Kreyszig, 1989]

  Let T be a linear transformation between two normed linear spaces. The following are equivalent:
  - 1. T is continuous at one point.
  - 2. T is continuous at all points.
  - 3. T is bounded.
- **Definition** A normed linear space  $(V, \|\cdot\|)$  is <u>complete</u> if it is complete as a metric space in the induced metric.
- Theorem 1.2 (The B.L.T. Theorem) [Reed and Simon, 1980] Suppose T is a bounded linear transformation from a normed linear space (V<sub>1</sub>, ||·||<sub>1</sub>) to a complete normed linear space (V<sub>2</sub>, ||·||<sub>2</sub>). Then T can be uniquely extended to a bounded linear transformation (with the same bound), T, from the completion of V<sub>1</sub> to (V<sub>2</sub>, ||·||<sub>2</sub>).

## 2 Banach Space

### 2.1 Definition and Examples

- Definition A complete normed linear space is called a Banach space.
- Example (C(X)) and its subspace  $C_{\mathbb{R}}(X)$  Let C(X) be the set of all *complex-valued continuous functions* on X and  $C_{\mathbb{R}}(X) \subseteq C(X)$  be the set of all *real-valued continuous functions* on X. Also define  $C^b(X)$  as the set of all *complex-valued bounded continuous functions* on X. When X is a *compact space*,  $C^b(X) = C(X)$ . Define the norm as

$$||f||_{\infty} = \sup_{x \in X} |f(x)|.$$

Then for <u>compact Hausdorff space</u> X, C(X) is a (complex) <u>Banach space</u> and C(X) is a (real) <u>Banach space</u>.

• Example  $(L^{\infty}(\mathbb{R})$  and its subspace  $C^{0}(\mathbb{R})$ ) Let  $L^{\infty}(\mathbb{R})$  be the set of (equivalence classes of) complex-valued measurable functions on  $\mathbb{R}$  such that  $|f(x)| \leq M$  a.e. with respect to Lebesgue measure for some  $M < \infty$  (f = g means f(x) = g(x) a.e.). Let  $||f||_{\infty}$  be the smallest such M.  $L^{\infty}(\mathbb{R})$  is a Banach space with norm  $||\cdot||_{\infty}$ .

The bounded continuous functions  $C^0(\mathbb{R})$  is a subspace of  $L^\infty(\mathbb{R})$  and restricted to  $C^0(\mathbb{R})$  the  $\|\cdot\|_{\infty}$ -norm is just the usual supremum norm under which  $C^0(\mathbb{R})$  is complete (since the uniform limit of continuous functions is continuous See proof in chapter 1.). Thus,  $C^0(\mathbb{R})$  is a closed subspace of  $L^\infty(\mathbb{R})$ .

Consider the set  $\kappa(\mathbb{R})$  of **continuous functions** with **compact support**, that is, the continuous functions that vanish outside of some closed interval.  $\kappa(\mathbb{R})$  is a **normed linear space** 

under  $\|\cdot\|_{\infty}$ ; but is **not complete**, The **completion** of  $\kappa(\mathbb{R})$  is **not all** of  $\mathcal{C}^0(\mathbb{R})$ ; for example, if f is the function which is identically equal to one, then I cannot be approximated by a function in  $\kappa(\mathbb{R})$  since  $\|f-g\|_{\infty} \geq 1$  for all  $g \in \kappa(\mathbb{R})$ . The **completion** of  $\kappa(\mathbb{R})$  is just  $\mathcal{C}_{\infty}(\mathbb{R})$ , the continuous functions which **approach zero** at  $\infty$ .

Some of the most powerful theorems in functional analysis (Riesz-Markov, Stone-Weierstrass) are generalizations of properties of  $C^0(\mathbb{R})$ .

## • Example $(L^p \ spaces)$

Let  $(X, \mu)$  be a measure space and  $p \ge 1$ . We denote by  $L^p(X, \mu)$  the set of equivalence classes of measurable functions which satisfy:

$$||f||_p := \left( \int_X |f(x)|^p d\mu(x) \right)^{\frac{1}{p}} < \infty$$

Two functions are equivalent if they differ only on a set of measure zero.

The following theorem collects many of the standard facts about  $L^p$  spaces.

**Theorem 2.1** Let  $1 \le p < \infty$ , then

1. (The Minkowski Inequality): If  $f, g \in L^p(X, \mu)$ , then

$$||f + g||_p \le ||f||_p + ||g||_p$$

- 2. (Riesz-Fisher):  $L^p(X, \mu)$  is complete.
- 3. <u>(The Hölder Inequality)</u> Let p, q, and r be positive numbers satisfying  $p, q, r \ge 1$  and  $p^{-1} + q^{-1} = r^{-1}$ . Suppose  $f \in L^p(X, \mu)$ ,  $g \in L^q(X, \mu)$ . Then  $fg \in L^r(X, \mu)$  and

$$||fg||_r \le ||f||_p ||g||_q$$

Remark The Minkowski inequality shows that  $L^p(X,\mu)$  is a vector space and  $\|\cdot\|_p$  satisfies the triangle inequality. This together with Riesz-Fisher theorem shows that  $L^p(X,\mu)$  is a Banach space.

#### • Example (Sequence Spaces)

There is a nice class of spaces which is easy to describe and which we will often use to illustrate various concepts. In the following definitions,

$$a := (a_n)_{n=1}^{\infty}$$

always denotes a sequence of complex numbers.

$$\ell^{\infty} := \left\{ a : \|a\|_{\infty} := \sup_{n} |a_{n}| < \infty \right\}$$

$$c_{0} := \left\{ a : \lim_{n \to \infty} a_{n} = 0 \right\}$$

$$\ell^{p} := \left\{ a : \|a\|_{p} := \left( \sum_{n=1}^{\infty} |a_{n}|^{p} \right)^{\frac{1}{p}} < \infty \right\}$$

$$s := \left\{ a : \lim_{n \to \infty} n^{p} a_{n} = 0 \text{ for all positive integers } p \right\}$$

$$f := \left\{ a : a_{n} = 0 \text{ for all but a finite number of } n \right\}$$

It is clear that as sets  $f \subseteq s \subseteq \ell^p \subseteq c_0 \subseteq \ell^{\infty}$ .

The spaces  $\ell^{\infty}$  and  $c_0$  are Banach spaces with the  $\|\cdot\|_{\infty}$  norm;  $\ell^p$  is a Banach space with the  $\|\cdot\|_p$  norm (note that  $\ell^p = L^p(\mathbb{R}, \mu)$  where  $\mu$  is the measure with mass one at each positive integer and zero everywhere else). It will turn out that s is a Frechet space.

One of the reasons that these spaces are easy to handle is that  $\underline{f}$  is **dense** in  $\ell^p$  (in  $\|\cdot\|_p$ ;  $p < \infty$  and  $\underline{f}$  is **dense** in  $c_0$  (in the  $\|\cdot\|_{\infty}$  norm). Actually, the set of elements of f with only rational entries is also **dense** in  $\ell^p$  and  $c_0$ . Since this set is **countable**,  $\ell^p$  and  $c_0$  are **separable**.  $\ell^\infty$  is not separable.

## • Example (The Bounded Operators)

In above we defined the concept of a bounded linear transformation or bounded operator from one normed linear space, X, to another Y; we will denote the set of all bounded linear operators from X to Y by  $\mathcal{L}(X,Y)$ . We can introduce a norm on  $\mathcal{L}(X,Y)$  by defining

$$||A|| := \sup_{x \neq 0, x \in X} \frac{||Ax||_Y}{||x||_X}.$$

This norm is often called *the operator norm*.

We have the following proposition

**Proposition 2.2** If Y is complete,  $\mathcal{L}(X,Y)$  is a Banach space.

## • Example (*Hilbert Space*)

All *Hilbert spaces*  $(\mathcal{H}, \langle \cdot, \cdot \rangle)$  are *Banach spaces* with *induced norm* as

$$||x|| = (\langle x, x \rangle)^{\frac{1}{2}}.$$

#### 2.2 Isomorphism and Equivalence of Norms

#### • Definition (Absolutely Summable)

A sequence of elements  $(x_n)_{n=1}^{\infty}$  in a normed linear space X is called **absolutely summable**  $\sum_{n=1}^{\infty} ||x_n|| < \infty$ . It is called **summable** if  $\sum_{n=1}^{N} x_n$  converges as  $N \to \infty$  to an  $x \in X$ .

• Proposition 2.3 (Criterion of Completeness for Normed Linear Space) [Reed and Simon, 1980]

A normed linear space is **complete** if and only if every **absolutely summable** sequence is **summable**.

#### • Definition (Isomorphism between Normed Linear Spaces)

A **bounded linear operator** from a normed linear space X to a normed linear space Y is called an  $\underline{isomorphism}$  if it is a bijection which is continuous and which has a continuous inverse.

If it is **norm preserving**, it is called **an isometric isomorphism** (any norm preserving map is called an **isometry**).

- Remark The *isomorphism* is defined in above way is essentially a *linear homemorphism*.
- Definition (*Norm Equivalence*)

Two norms,  $\|\cdot\|_1$  and  $\|\cdot\|_2$ , on a normed linear space X are called **equivalent** if there are

positive constants C and C' such that, for all  $x \in X$ ,

$$C \|x\|_2 \le \|x\|_1 \le C' \|x\|_2$$

• **Remark** This concept is motivated by the following fact.

Equivalent norms on X define the same topology for X.

- Proposition 2.4 The completions of the space in the two norms will be isomorphic if and only if the norms are equivalent.
- Proposition 2.5 Two norms,  $\|\cdot\|_1$  and  $\|\cdot\|_2$ , on a normed linear space X are equivalent if and only if the identity map is an isomorphism.
- Remark An example is provided by the sequence spaces. The completion of f in the  $\|\cdot\|_{\infty}$  norm is  $c_0$  while the completion in the  $\|\cdot\|_p$  norm is  $\ell^p$ .

### 2.3 Subspace of a Banach Space

• **Definition** A *subspace* Y of a normed space X is a subspace of X considered as a *vector* space, with the *norm* obtained by *restricting* the *norm* on X to the subset Y. This norm on Y is said to be *induced* by the *norm* on X.

If Y is closed in X, then Y is called a closed subspace of X.

- **Remark** A subspace Y of a **Banach space** X is a subspace of X considered as a normed space. Hence we do not require Y to be complete.
- Proposition 2.6 (Subspace of a Banach space). [Kreyszig, 1989]

  A subspace Y of a Banach space X is complete if and only if the set Y is closed in X.

#### 2.4 Basis and Separability

• Definition (Basis of Normed Space)

If a normed space X contains a sequence  $(e_i)$  with the property that for every  $x \in X$  there is a **unique** sequence of scalars  $(u^i)$  such that

$$\lim_{n \to \infty} \left\| x - \sum_{i=1}^{n} u^{i} e_{i} \right\| = 0, \tag{1}$$

then  $(e_i)$  is called a **Schauder basis** (or basis) for X. The series  $\sum_{i=1}^{\infty} u^i e_i$  which has the sum x is then called the **expansion** of x with respect to  $(e_i)$ , and we write

$$x = \sum_{i=1}^{\infty} u^i e_i$$

• Example The (Schauder) basis of  $\ell^p$  is  $(e_n)$  and

$$e_n := (\delta_{n,i}) = (0, \dots, 0, 1, 0, \dots)$$

where the i-th component is 1 and the others are all zeros.

- Proposition 2.7 If a normed space X has a Schauder basis, then X is separable.
- Theorem 2.8 (Completion). [Kreyszig, 1989]

  Let X = (X, ||·||) be a normed space. Then there is a Banach space X and an isometry A from X onto a subspace W of X which is dense in X. The space X is unique, except for isometries.

### 2.5 Finite Dimensional Normed Spaces and Subspaces

• Lemma 2.9 (Linear combinations). [Kreyszig, 1989] Let  $(x_1, ..., x_n)$  be a linearly independent set of vectors in a normed space X (of any dimension). Then there is a number c > 0 such that for every choice of scalars  $\alpha_1, ..., \alpha_n$  we have

$$\left\| \sum_{i=1}^{n} \alpha_i x_i \right\| \ge c \sum_{i=1}^{n} |\alpha_i|. \tag{2}$$

- Theorem 2.10 (Completeness). [Kreyszig, 1989]
  Every finite dimensional subspace Y of a normed space X is complete. In particular, every finite dimensional normed space is complete.
- Remark In other words, every finite dimensional normed vector space is a Banach space.
- Proposition 2.11 (Closedness). [Kreyszig, 1989] Every finite dimensional subspace Y of a normed space X is closed in X.
- Theorem 2.12 (Equivalent Norms). [Kreyszig, 1989]
  If a vector space X is finite dimensional, all norms are equivalent.
- **Remark** This theorem is of considerable practical importance. For instance, it implies that **convergence** or divergence of a sequence in a finite dimensional vector space does not depend on the particular choice of a norm on that space. There is no ambiguity when we say  $x_n \to x$  in finite dimensional space.

In fact, there exists only one distinct norm topology for finite dimensional space.

- Definition (Compactness).
  - A metric space X is said to be <u>(sequentially) compact</u> if every sequence in X has a **convergent subsequence**. A subset M of X is said to be **compact** if M is compact considered as a subspace of X, that is, if every sequence in M has a convergent subsequence whose limit is an element of M.
- Lemma 2.13 (Compactness).

  A compact subset M of a metric space is closed and bounded.
- Remark The converse of this lemma is in general false. But for finite dimensional space, the converse is true:
- Theorem 2.14 (Compactness). [Kreyszig, 1989]
   In a finite dimensional normed space X, any subset M ⊆ X is compact if and only if M is closed and bounded.

• Remark In finite dimensional space, the compact subsets are precisely the closed and bounded subsets, so that this property (closedness and boundedness) can be used for defining compactness.

However, this can no longer be done in the case of an infinite dimensional normed space.

• Lemma 2.15 (F. Riesz's Lemma). [Kreyszig, 1989] Let Y and Z be subspaces of a normed space X (of any dimension), and suppose that Y is closed and is a proper subset of Z. Then for every real number  $\theta$  in the interval (0,1) there is a  $z \in Z$  such that

$$||z|| = 1$$
,  $||z - y|| \ge \theta$ , for all  $y \in Y$ .

- Theorem 2.16 (Bounded Linear Operator)

  If a normed space X is finite dimensional, then every linear operator on X is bounded.
- Remark (*Finite Dimensional Normed Space is Simple*)
  We summarizes the *unique* simple struture of finite dimensional normed space in terms of various concepts we discussed in this chapter:
  - 1. <u>Completeness</u>: Every finite dimensional normed vector space is **complete** so it is a <u>Banach space</u>;
  - 2. Norm Equivalence: All norms in a finite dimensional normed space are equivalent; therefore, convergence in one norm means convergence in all other norms.
  - 3. <u>Topological Equivalence</u>: There exists only one distinct norm topology in a finite dimensional normed space;
  - 4. <u>Compactness</u>: In a finite dimensional normed space, <u>compactness</u> is equivalent to <u>closedness</u> and <u>boundedness</u>.
  - 5. <u>Bounded Linear Operator</u>: Every linear operator between finite dimensional normed spaces is bounded. Thus in finite dimensional space, every linear operator is continuous.

## 2.6 Direct Sum of Banach Spaces

• Definition (*Direct Sum of Banach Spaces*) Let A be an index set (not necessarily countable), and suppose that for each  $\alpha \in A$ ,  $X_{\alpha}$  is a Banach space. Let

$$X := \left\{ (x_{\alpha})_{\alpha \in A} : x_{\alpha} \in X_{\alpha}, \ \sum_{\alpha \in A} \|x_{\alpha}\|_{X_{\alpha}} < \infty \right\}.$$

Then X with the norm

$$\|(x_{\alpha})_{\alpha \in A}\|_{X} := \sum_{\alpha \in A} \|x_{\alpha}\|_{X_{\alpha}}$$

is a Banach space. It is called <u>the direct sum</u> of the spaces  $X_{\alpha}$  and is often written as  $X = \bigoplus_{\alpha \in A} X_{\alpha}$ .

• Remark (Banach Spaces Direct Sum  $\neq$  Hilbert Spaces Direct Sum)

Note that the direct sum of Banach spaces is **not** necessarily the direct sum of Hilbert spaces.

For instance, if we take countable numbers of copies of  $\mathbb{C}$ , the Banach space direct sum is  $\ell_1$ , while the Hilbert space direct sum is  $\ell_2$ .

However, if only **finite number** of Hilbert spaces are involved, then both Hilbert space direct sum and their Banach space direct sum are isomorphic to each other.

## 2.7 Dual Space and Double Dual Space

• Definition (Dual Space)

The space  $\mathcal{L}(X,\mathbb{C})$  of all **bounded linear functionals** on a normed linear space X is called the **dual space** of X. This space  $\mathcal{L}(X,\mathbb{C})$  is denoted as  $X^*$ .

<u>The dual space  $X^*$  is a Banach space</u> if X is a Banach space (See Proposition 2.2). The **norm** of dual space is

$$\|\lambda\| := \sup_{x \neq 0, \|x\| \leq 1} |\lambda(x)|,$$

for all  $\lambda \in X^*$ .

• Remark By definition, we have the dual norm inequality

$$|\lambda(x)| \le \|\lambda\|_{X^*} \|x\|_{Y}. \tag{3}$$

In Hilbert space, since  $\lambda(x) = \langle y_{\lambda}, x \rangle$  for some  $y_{\lambda}$ , it becomes the Cauchy-Schwartz inequality.

$$|\langle y_{\lambda}, x \rangle| < ||y_{\lambda}|| \, ||x||$$

• Example (*Hilbert Space*)

Any *Hilbert space*  $\mathcal{H}$  is *isomorphic* to its *dual*  $\mathcal{H}^*$  according to the Riesz Representation Theorem. For instance  $L^2(X,\mu) = (L^2(X,\mu))^*$ .

• Example  $(L^p(X, \mu) \ \textit{Spaces}, \ 1$ 

Suppose that  $1 and <math>p^{-1} + q^{-1} = 1$ . If  $f \in L^p(X, \mu)$  and  $g \in L^q(X, \mu)$  then, according to the Hölder inequality, fg is in  $L^1(X, \mu)$ . Thus,

$$\int_X f(x)\overline{g(x)}d\mu(x) < \infty$$

makes sense, Let  $g \in L^q(X,\mu)$  be fixed and define

$$G(f) := \int_X f \overline{g} d\mu$$

for each  $f \in L^p(X,\mu)$ . The Hölder inequality shows that G(f) is a **bounded linear functional** on  $L^p(X,\mu)$  with norm less than or equal to  $\|g\|_q$ ; actually **the norm**  $\|G\|$  is **equal** to  $\|g\|_q$ .

The converse of this statement is also true. That is, every bounded linear functional on  $L^p$  is of the form G(f) for some  $g \in L^q$ . Furthermore, different functions in  $L^q$  give rise to different functionals on  $L^p$ . Thus, the mapping

$$L^q(M,\mu) \to (L^p(X,\mu))^*, \quad g \mapsto G_q(\cdot)$$

is a (conjugate linear) isometric isomorphism.

In this sense,  $L^q(M,\mu)$  is the dual of  $L^p(X,\mu)$ . Since the roles of p and q in the expression  $p^{-1}+q^{-1}=1$  are symmetric, it is clear that  $L^p(X,\mu)=(L^q(X,\mu))^*=(L^p(X,\mu))^{**}$ . That is, the dual of the dual of  $L^p(X,\mu)$  is again  $L^p(X,\mu)$ .

- Remark Note that  $L^{\infty}(X,\mu)$  space and  $L^{1}(X,\mu)$  space are **not dual** spaces to each other. The dual space of  $L^{\infty}(X,\mu)$  space is much larger than  $L^{1}(X,\mu)$  space. In fact,  $L^{1}(X,\mu)$  space is not dual to any Banach space. This is different from  $\ell^{\infty}$  and  $\ell^{1}$ .
- Example  $(\ell^{\infty} = (\ell^1)^*, \ell^1 = (c_0)^*)$ Suppose that  $(\lambda_k)_{k=1}^{\infty} \in \ell^1$ . Then for each  $(a_k)_{k=1}^{\infty} \in c_0$ ,

$$\Lambda\left((a_k)_{k=1}^{\infty}\right) = \sum_{k=1}^{\infty} \lambda_k \, a_k$$

converges and  $\Lambda(\cdot)$  is a **continuous linear functional** on  $c_0$  with **norm** equal to  $\sum_{k=1}^{\infty} |\lambda_k|$ .

To see that all continuous linear functionals on  $c_0$  arise in this way, we proceed as follows. Suppose  $\lambda \in c_0^*$  and let  $e^k$  be the sequence in  $c_0$  which has all its terms equal to zero except for a one in the k-th place. Define  $\lambda_k = \lambda(e^k)$  and let  $f^l = \sum_{k=1}^l (|\lambda_k|/\lambda_k) e^k$ . If some  $\lambda_k$  is zero, we simply omit that term from the sum. Then for each l,  $f^l \in c_0$  and  $||f^l||_{c_0} = 1$ . Since,

$$\lambda(f^l) = \sum_{k=1}^l |\lambda_k|, \quad |\lambda(f^l)| \le ||\lambda||_{c_0^*} ||f^l||_{c_0}$$

we have

$$\sum_{k=1}^{l} |\lambda_k| \le \|\lambda\|_{c_0^*}$$

Since this is true for all l,  $\sum_{k=1}^{\infty} |\lambda_k| < \infty$  and

$$\Lambda\left((a_k)_{k=1}^{\infty}\right) = \sum_{k=1}^{\infty} \lambda_k \, a_k$$

is a well-defined linear functional on  $c_0$ . However,  $\Lambda(\cdot)$  and  $\lambda(\cdot)$  agree on finite linear combinations of the  $e^k$ . Because such finite linear combinations are **dense** in  $c_0$  we conclude that  $\lambda = \Lambda$ . Thus every functional in  $c_0$  arises from a sequence in  $\ell^1$ , and the **norms** in  $\ell^1$  and  $c_0$  coincide. Thus  $\ell^1 = c_0^*$ . A similar proof shows that  $\ell^\infty = (\ell^1)^*$ .

- **Remark** We see that  $c_0 \subseteq (c_0)^{**} = (\ell^1)^* = \ell^{\infty}$ .
- ullet Definition (Double Dual)

Since the **dual**  $X^*$  of a Banach space is itself a Banach space, it also has a **dual** space, denoted by  $X^{**}$ .  $X^{**}$  is called **the second dual**, **the bidual**, or **the double dual** of the space X.

- Proposition 2.17 [Reed and Simon, 1980]
  Let X be a Banach space. For each x ∈ X, let x̃(·) be the linear functional on X\* which assigns to each λ ∈ X\* the number λ(x). Then the map J: x → x̃ is an isometric isomorphism of X onto a (possibly proper) subspace of X\*\*.
- Remark From above proposition, we see that there exists an *embedding* from X to a subset of  $X^{**}$

$$X \subseteq X^{**}, \quad X \hookrightarrow X^{**}$$

- **Definition** If the map  $J: x \mapsto \tilde{x}$  is *surjective*, then X is said to be <u>reflexive</u>. In other word, X is reflective if and only if  $X = X^{**}$ .
- Example  $L^p(X, \mu)$  spaces are **reflective** for  $1 . Note that <math>L^p(X, \mu) = (L^q(X, \mu))^* = (L^p(X, \mu))^{**}$
- Example All Hilbert spaces  $\mathcal{H}$  are reflective.
- Example Since  $c_0 \subseteq (c_0)^{**} = (\ell^1)^* = \ell^{\infty}$ ,  $c_0$  is not reflective.

## 3 The Hahn-Banach Theorem

- Remark In dealing with Banach spaces, one often needs to construct linear functionals with certain properties. This is usually done in two steps:
  - 1. one **defines** the **linear functional** on a **subspace** of the Banach space where it is easy to verify the desired properties;
  - 2. one appeals to (or proves) a general theorem which says that any such functional can be extended to the whole space while retaining the desired properties.

One of the basic tools of the second step is the Hahn-Banach theorem.

#### 3.1 Extension Form of The Hahn-Banach Theorem

- Definition (Sublinear Functional)
  - If X is a vector space, a **sublinear functional** on X is a map  $p: X \to \mathbb{R}$  such that
    - 1. (*Homogeneity*):  $p(\lambda x) = \lambda p(x)$  for all  $\lambda \geq 0$  and  $x \in X$ ;
    - 2. (Sublinearity):  $p(x+y) \le p(x) + p(y)$ ,
- **Example** Every *semi-norm* is a *sublinear functional*. If p is a semi-norm, then the condition  $f \leq p$  is equivalent to  $|f| \leq p$ .
- Theorem 3.1 (The Hahn-Banach Theorem, Extension Form) [Kreyszig, 1989, Reed and Simon, 1980, Luenberger, 1997, Folland, 2013]
  Let X be a real normed linear space and p a sublinear functional on X. Let f be a linear functional defined on a subspace M of X satisfying f(x) ≤ p(x) for all x ∈ M. Then there exists a linear functional F on X such that F(x) ≤ p(x) for all x ∈ X and F|<sub>M</sub> = f. (F

is called an **extension** of f.)

**Proof:** The *idea* of the proof is the following.

- 1. First we will show that if  $x \in X$  but  $x \notin M$ , then we can **extend** f, to a functional g having the property  $g(x) \leq p(x)$  on **the space spanned by** x **and** M (i.e. the affine subspace  $M + \mathbb{R} x$ ).
- 2. We then use a **Zorn's Lemma** argument to show that this process can be **continued** to **extend**), to the whole space X.

(Step 1). If  $y_1, y_2 \in M$ , by linearity of functional f and  $f \leq p$ , we have

$$f(y_1) + f(y_2) = f(y_1 + y_2)$$

$$\leq p(y_1 + y_2) = p(y_1 - x + y_2 + x)$$

$$\leq p(y_1 - x) + p(y_2 + x)$$

$$\Rightarrow f(y_1) - p(y_1 - x) \leq p(y_2 + x) - f(y_2)$$

Hence

$$\sup_{y \in M} \{ f(y) - p(y - x) \} \le \inf_{y \in M} \{ p(y + x) - f(y) \}$$

Let  $\alpha$  be any number satisfying

$$\sup_{y \in M} \left\{ f(y) - p(y - x) \right\} \le \alpha \le \inf_{y \in M} \left\{ p(y + x) - f(y) \right\}$$

and define  $g: M + \mathbb{R} x \to \mathbb{R}$  by  $g(y + \gamma x) := f(y) + \gamma \alpha$ . Then g is *linear*, and  $g|_M = f$ , so that  $g(y) \le p(y)$  for  $y \in M$ . Moreover, if  $\gamma > 0$  and  $y \in M$ ,

$$g(y + \gamma x) = \gamma(\gamma^{-1} f(y) + \alpha)$$

$$= \gamma \left( f\left(\frac{y}{\gamma}\right) + \alpha \right)$$

$$\leq \gamma \left[ f\left(\frac{y}{\gamma}\right) + p\left(\frac{y}{\gamma} + x\right) - f\left(\frac{y}{\gamma}\right) \right] \quad \text{(upper bound of } \alpha\text{)}$$

$$= \gamma p\left(\frac{y}{\gamma} + x\right) = p\left(y + \gamma x\right),$$

where if  $\gamma = -\mu < 0$ ,

$$g(y + \gamma x) = \mu \left[ f\left(\frac{y}{\gamma}\right) - \alpha \right]$$

$$\leq \mu \left[ f\left(\frac{y}{\gamma}\right) + p\left(\frac{y}{\gamma} - x\right) - f\left(\frac{y}{\gamma}\right) \right] \quad \text{(lower bound of } \alpha\text{)}$$

$$\leq \mu p\left(\frac{y}{\gamma} - x\right) = p(y + \gamma x).$$

Thus  $g(z) \leq p(z)$  for all  $z \in M + \mathbb{R} x$ .

(Step 2). Apparently the same reasoning can be applied to any linear functional F of f satisfying  $F \leq p$  on its domain and we shows that the domain of a **maximal** linear extension F satisfying  $F \leq p$  must be the whole space X.

Define  $\mathcal{F}$  as the family of all linear extensions F of f satisfying  $F \leq p$ . By construction in Step 1 we see that  $\mathcal{F}$  is partially ordered by inclusion where  $F_1 \leq F_2$  if  $F_2$  is defined on a larger set than  $F_1$  and  $F_2(x) = F_1(x)$  where they are both defined.

Let  $\{F_{\alpha}\}_{\alpha\in A}$  be a *linearly ordered subset* of  $\mathcal{F}$ ; let  $X_{\alpha}$  be the subspace on which  $F_{\alpha}$  is defined. Define F on  $\bigcup_{\alpha\in A}X_{\alpha}$  by setting  $F(x)=F_{\alpha}(x)$  if  $x\in X_{\alpha}$ . Clearly  $F_{\alpha}\preceq F$  so each linearly ordered subset of  $\mathcal{F}$  has an upper bound. By Zorn's lemma,  $\mathcal{F}$  has a maximal element  $\Lambda$ , defined on some set X', satisfying  $\Lambda(x)\leq p(x)$  for  $x\in X'$ . But, X' must be all of X, since otherwise we could extend  $\Lambda$  to a  $\widetilde{\Lambda}$  on a larger space by adding one dimension as above. Since this contradicts the maximality of  $\Lambda$ , we must have X=X'. Thus, the extension  $\Lambda$  is everywhere defined.

- Theorem 3.2 (The Complex Hahn-Banach Theorem, Extension Form) [Kreyszig, 1989, Reed and Simon, 1980, Luenberger, 1997, Folland, 2013]
  Let X be a complex normed linear space and p a <u>semi-norm</u> on X. Let f be a <u>complex linear functional</u> defined on a <u>subspace</u> M of X satisfying |f(x)| ≤ |p(x)| for all x ∈ M. Then there exists a <u>complex linear functional</u> F on X such that |F(x)| ≤ |p(x)| for all x ∈ X and F|<sub>M</sub> = f. (F is called an <u>extension</u> of f.)
- Corollary 3.3 (<u>The Existence of Minimum Norm Extension</u>) Let  $f \in M^*$  be a bounded linear functional defined on a **subspace** M of a real normed vector space X. Then there is a bounded linear functional  $F \in X^*$  defined on X which is an **extension** of f satisfying  $\|F\|_{X^*} = \|f\|_{M^*}$ .

Note let  $p(x) = ||f||_{M^*} ||x||$ .

- Corollary 3.4 Let y be an element of a normed linear space X. Then there is a nonzero  $F \in X^*$  such that  $F(y) = ||F||_{X^*} ||y||_X$ .
- Corollary 3.5 (The Existence of Distance Functional)

  Let Z be a subspace of a normed linear space X and suppose that y is an element of X whose distance from Z is  $d = \inf_{z \in Z} ||y z||$ . Then there exists a  $F \in X^*$  so that  $||F|| \leq 1$ , F(y) = d, and F(z) = 0 for all z in Z.
- Remark The Hahn-Banach theorem, particularly Corollary 3.3, is perhaps most profitably viewed as an existence theorem for a minimization problem. Given an f on a subspace M of a normed space, it is not difficult to extend f to the whole space. An arbitrary extension, however, will in general be unbounded or have norm greater than the norm of f on M. We therefore pose the problem of selecting the extension of minimum norm. The Hahn-Banach theorem both guarantees the existence of a minimum norm extension and tells us the norm of the best extension.
- Remark (*Convex Analysis*) Note that any sublinear functional p is *convex*, i.e. for all  $x, y \in X$ ,  $\alpha \in [0, 1]$

$$p(\alpha x + (1 - \alpha)y) \le \alpha p(x) + (1 - \alpha)p(y).$$

So the Hahn-Banach theorem can be stated as extention of linear functional  $f(x) \leq p(x)$  bounded by a convex functional p. Then the inequality in the proof becomes

$$\frac{1}{\alpha} \sup_{y \in M} \left\{ f(y) - p(y - \alpha x) \right\} \le \frac{1}{\beta} \inf_{y \in M} \left\{ p(y + \beta x) - f(y) \right\}$$

where the left-hand side in Hilbert space becomes

$$\sup_{y \in M} \left\{ \left\langle x_f, \alpha^{-1} y \right\rangle - p(\alpha^{-1} y - x) \right\}$$

This is the Legendre transformation for convex function h(y) := p(y - x)

$$h^*(x) := \sup_{y \in \alpha^{-1}M} \left\{ \langle x, y \rangle - h(y) \right\}$$

• Proposition 3.6 Let X be a Banach space. If  $X^*$  is separable, then X is separable.

#### 3.2 Geometric Form of The Hahn-Banach Theorem

- **Definition** The *translation* of a subspace is called a <u>linear variety</u>. It is written as x+M where  $x \in X$  is a fixed point and  $M \subseteq X$  is a subspace of X.
- Remark A linear variety is also called an affine subspace.
- **Definition** A <u>hyperplane</u> H in a linear vector space X is a maximal proper linear variety, that is, a linear variety H such that  $H \neq X$ , and if V is any linear variety containing H, then either V = X or V = H.
- Remark A hyperplane H = x + M where M has codimension 1 in X, i.e.

$$X = \operatorname{span}\{x, \text{ basis of } M\}.$$

- Proposition 3.7 [Luenberger, 1997]

  Let H be a hyperplane in a linear vector space X. Then there is a linear functional f on X and a constant c such that  $H = \{x : f(x) = c\}$ . Conversely, f is a nonzero linear functional on X, the set  $\{x : f(x) = c\}$  is a hyperplane in X.
- There exists an *one-to-one correspondence* between linear functional and hyperplane that does not passes the origin.

**Proposition 3.8** (Unique Linear Functional for Hyperplane) [Luenberger, 1997] Let H be a hyperplane in a linear vector space X. If H does not contain the origin, there is a unique linear functional f on X such that  $H = \{x : f(x) = 1\}$ .

- Proposition 3.9 Let f be a nonzero linear functional on a normed space X. Then the hyperplane  $H = \{x : f(x) = c\}$  is **closed** for every c if and only if f is **continuous**.
- **Remark** If f is a nonzero linear functional on a linear vector space X, we associate with the hyperplane  $H = \{x : f(x) = c\}$  the four sets

$$\{x: f(x) \le c\}, \{x: f(x) < c\}, \{x: f(x) \ge c\}, \{x: f(x) > c\}$$

called <u>half-spaces determined by H</u>. The first two of these are referred to as **negative** half-spaces determined by f and the second two as **positive** half-spaces.

If f is continuous, the first and the third half-spaces are **closed** and the second and fourth are **open**.

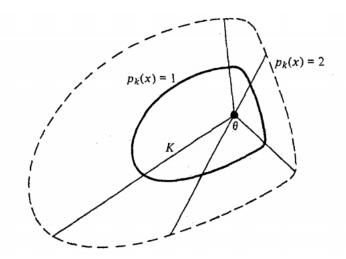


Figure 1: The Minkowski functional of a convex set [Luenberger, 1997]

• Definition (*The Minkowski Functional*) [Luenberger, 1997]
Let K be a convex set in a normed linear vector space X and suppose 0 is an interior point of K. Then the Minkowski functional (or gauge) p of K is defined on X by

$$p(x) := \inf \left\{ r : \frac{x}{r} \in K, r > 0 \right\} = [\sup \left\{ t : t \, x \in X, t > 0 \right\}]^{-1}.$$

We note that for K equal to the unit sphere in X, the Minkowski functional is ||x||. In the general case, p(x) defines a kind of **distance** from the origin to x measured with respect to K; it is the factor by which K must be expanded so as to include x.

- Lemma 3.10 Let K be a convex set containing 0 as an interior point. Then the Minkowski functional p of K satisfies:
  - 1.  $0 \le p(x) < \infty$  for all  $x \in X$ ;
  - 2. (Homogeneity):  $p(\lambda x) = \lambda p(x)$  for all  $\lambda \geq 0$  and  $x \in X$ ;
  - 3. (Sublinearity): p(x+y) < p(x) + p(y),
  - 4. p is continuous;
  - 5.  $\overline{K} = \{x : p(x) \le 1\}$  and  $\mathring{K} = \{x : p(x) < 1\}$ .

That is, the Minkowski functional is a sublinear functional.

• Theorem 3.11 (Mazur's Theorem, <u>Geometric Hahn-Banach Theorem</u>) [Luenberger, 1997]

Let K be a <u>convex set having a nonempty interior</u> in a real normed linear vector space X. Suppose V is a <u>linear variety</u> in X <u>containing no interior points</u> of K. Then there is a <u>closed hyperplane</u> in X <u>containing V but containing no interior points</u> of K; i.e., there is an element  $f \in X^*$  and a constant c such that f(v) = c for all  $v \in V$  and f(k) < c for all  $k \in K$ .

**Proof:** By an appropriate translation we may assume that 0 is an interior point of K. Let M be the subspace of X generated by V. Then V is a **hyperplane** in M and does not contain 0; thus there is a **linear functional** f on M such that  $V = \{x : f(x) = 1\}$ .

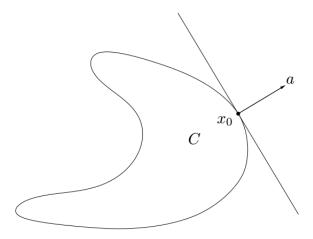


Figure 2: The supporting hyperplane of a convex set [Boyd et al., 2004]

We then show that  $f(x) \leq p(x)$  for all  $x \in M$ , where p(x) is **the Minkowski functional** (a sublinear functional). Since V contains no interior point of K, we have  $f(x) = 1 \leq p(x)$  for  $x \in V$ . By homogeneity,  $f(\alpha x) = \alpha \leq p(\alpha x)$  for  $x \in V$  and x > 0. While for  $x \in V$  and x = 0,  $x \in V$  and x = 0. Thus  $x \in V$  for all  $x \in V$ .

Then by the Hahn-Banach Theorem, there is an **extension** F of f from M to X with  $F(x) \leq p(x)$ . Let  $H = \{x : F(x) = 1\}$ . Since  $F(x) \leq p(x)$  on X and since by Lemma 1 p is **continuous**, F is **continuous**, F(x) < 1 for  $x \in \mathring{K}$ , therefore, H is the desired closed hyperplane.

- Remark (Geometric Interpretation of the Hahn-Banach theorem)

  The geometric form of the Hahn-Banach theorem, in simplest form, says that given a convex set K containing an interior point, and given a point  $x_0$  not in  $\mathring{K}$ , there is a closed hyperplane containing  $x_0$  but disjoint from  $\mathring{K}$ .
- Definition (Supporting Hyperplane)
   A closed hyperplane H in a normed space X is said to be <u>a supporting hyperplane</u> (or a support) for the convex set K if K is contained in one of the closed half-spaces determined by H and H contains a point of K.
- Remark Suppose  $K \subseteq \mathbb{R}^n$ , and  $x_0$  is a point in its boundary  $\partial K$ , i.e.,

$$x_0 \in \partial K = \overline{K} \setminus \mathring{K}$$
.

If  $a \neq 0$  satisfies  $\langle a, x \rangle \leq \langle a, x_0 \rangle$  for all  $x \in K$ , then the hyperplane  $\{x : \langle a, x \rangle = \langle a, x_0 \rangle\}$  is called **a supporting hyperplane** to K at the point  $x_0$ .

- Theorem 3.12 (Supporting Hyperplane Theorem) [Luenberger, 1997, Rockafellar, 1970] If x is not an interior point of a convex set K which contains interior points, there is a closed hyperplane H containing x such that K lies on one side of H.
- As a consequence of the above theorem, it follows that, for a convex set K with interior points, a supporting hyperplane can be constructed containing any boundary point of  $\overline{K}$ .

**Theorem 3.13** (<u>Eidelheit's Separation Theorem</u>) [Luenberger, 1997, Rockafellar, 1970] Let  $K_1$  and  $K_2$  be **convex sets** in X such that  $K_1$  has interior points and  $K_2$  contains no

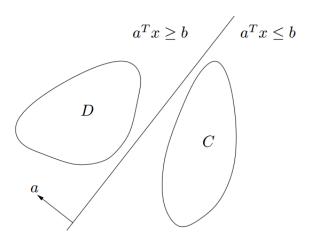


Figure 3: The existence of a separating hyperplane between two convex sets that does not overlap in interior set. [Boyd et al., 2004]

interior point of  $K_1$ . Then there is a closed hyperplane H separating  $K_1$  and  $K_2$ ; i.e., there exists  $f \in X^*$  such that

$$\sup_{x \in K_1} f(x) \le \inf_{x \in K_2} f(x) \tag{4}$$

In other words,  $K_1$  and  $K_2$  lie in opposite half-spaces determined by H.

**Proof:** Let  $K = K_1 - K_2 = \{x_1 - x_2 : x_1 \in K_1, x_2 \in K_2\}$ ; then K contains an interior point and 0 not one of them. Also K is a convex set. By The Supporting Hyperplane Theorem, there is an  $f \in X^*$ ,  $f \neq 0$ , such that  $f(x) \leq 0$  for  $x \in K$ . Thus for  $x_1 \in K_l$ ,  $x_2 \in K_2$ ,  $f(x_1) \leq f(x_2)$ . Consequently, there is a real number c such that  $\sup_{x \in K_1} f(x) \leq c \leq \inf_{x \in K_2} f(x)$ . The desired hyperplane is  $H = \{x : f(x) = c\}$ .

- Corollary 3.14 If K is a closed convex set and  $x \notin K$ , there is a closed halfspace that contains K but does not contain x.
- Theorem 3.15 (Dual Representation of Convex Set)[Luenberger, 1997, Rockafellar, 1970]

If K is a closed convex set in a normed space, then K is equal to the intersection of all the closed half-spaces that contain it.

• Remark (Duality for Convex Set)

Theorem above is often regarded as the geometric foundation of duality theory for convex sets. By associating closed hyperplanes (or half-spaces) with elements of  $X^*$ , the theorem expresses a convex set in X as a collection of elements in  $X^*$ . See more in [Rockafellar, 1970].

• **Definition** Let K be a convex set in a real normed vector space X. The functional

$$h(f) := \sup_{x \in K} f(x)$$

defined on  $X^*$  is called **the support functional** of K.  $h \in X^{**}$ .

• Remark The support functional of a convex set K completely specifies the set (to within closure)

$$\overline{K} = \bigcap_{f \in X^*} \{x : f(x) \le h(f)\}.$$

## 4 Linear Operators in Banach Space

## 4.1 Adjoints of Bounded Operator

• Definition (Banach Space Adjoint)

Let X and Y be Banach spaces, T a bounded linear operator from X to Y. The **Banach space adjoint of** T, denoted by T', is the bounded linear operator from  $Y^*$  to  $X^*$  defined by

$$(T'f)(x) = f(Tx)$$

for all  $f \in Y^*$ ,  $x \in X$ .

• Example (Adjoint of Right Shift Operator) Let  $X = \ell^1 = Y$  and let be the right shift operator

$$T(\xi_1, \xi_2, \ldots) = (0, \xi_1, \xi_2, \ldots)$$

Then  $T': \ell^{\infty} \to \ell^{\infty}$  is the left shift operator

$$T'(\xi_1, \xi_2, \ldots) = (\xi_2, \xi_3, \ldots).$$

Proposition 4.1 (Isomorphism between Bounded Operator and its Adjoint). [Reed and Simon, 1980]
 Let X and Y be Banach spaces. The map T → T' is an isometric isomorphism of L(X,Y) into L(Y\*,X\*).

• Remark (Hilbert Space Adjoint)

Let  $\mathcal{L}(\mathcal{H}) := \mathcal{L}(\mathcal{H}, \mathcal{H})$  be the space of bounded linear operators on  $\mathcal{H}$ . The Banach space adjoint of  $T^*$  then a mapping of  $\mathcal{H}^*$  to  $\mathcal{H}^*$ . Let  $C: \mathcal{H} \to \mathcal{H}^*$  be the map which assigns to each  $y \in \mathcal{H}$ , the bounded linear functional  $\langle y, \cdot \rangle$  in  $\mathcal{H}^*$ . C is a **conjugate linear isometry** which is **surjective** by the Riesz Representation theorem (so it is **unitary**). Now define a map  $T^*: \mathcal{H} \to \mathcal{H}$  by

$$T^* = C^{-1}T'C$$

Then  $T^*$  satisfies

$$\langle x, Ty \rangle = (Cx)(Ty) = (T'Cx)(y) = \langle C^{-1}T'Cx, y \rangle = \langle T^*x, y \rangle,$$

 $T^*$  is called <u>the Hilbert space adjoint of T</u>, but usually we will just call it the adjoint and let the  $T^*$  distinguish it from T'. Notice that the map  $T \to T^*$  is **conjugate linear**, that is,  $\alpha T \to \bar{\alpha} T^*$ . This is because C is conjugate linear.

Proposition 4.2 [Reed and Simon, 1980]
 The map T → T\* is always continuous in the weak and uniform operator topologies but is only continuous in the strong operator topology if H is finite dimensional.

## 4.2 Baire Category Theorem

## • Remark (*Empty Interior* = *Complement is Dense*)

Recall that if A is a subset of a space X, the *interior* of A is defined as the union of all open sets of X that are contained in A.

To say that A has <u>empty interior</u> is to say then that A <u>contains no open set</u> of X other than the empty set. <u>Equivalently</u>, A has <u>empty interior</u> if every point of A is a <u>limit point</u> of the <u>complement</u> of A, that is, if the <u>complement</u> of A is <u>dense</u> in X.

$$\mathring{A} = \emptyset \iff A^c \text{ is dense in } X$$

In [Reed and Simon, 1980], if a subset  $\overline{A}$  of X has empty interior, A is said to be <u>nowhere dense</u> in X.

## • Example Some examples:

- 1. The set  $\mathbb{Q}$  of rationals has **empty interior** as a subset of  $\mathbb{R}$
- 2. The interval [0,1] has nonempty interior.
- 3. The interval  $[0,1] \times 0$  has **empty interior** as a subset of the plane  $\mathbb{R}^2$ , and so does the subset  $\mathbb{Q} \times \mathbb{R}$ .

### • Definition (Baire Space)

A space X is said to be a <u>Baire space</u> if the following condition holds: Given <u>any countable</u> collection  $\{A_n\}$  of <u>closed</u> sets of X each of which has <u>empty interior</u> in X, their <u>union</u>  $\bigcup_{n=1}^{\infty} A_n$  also has <u>empty interior</u> in X.

#### • Example Some examples:

- 1. The space  $\mathbb{Q}$  of rationals is **not** a **Baire space**. For each one-point set in  $\mathbb{Q}$  is closed and has empty interior **in**  $\mathbb{Q}$ ; and  $\mathbb{Q}$  is the countable union of its one-point subsets.
- 2. The space  $\mathbb{Z}_+$ , on the other hand, does form a **Baire space**. Every subset of  $\mathbb{Z}_+$  is open, so that there exist no subsets of  $\mathbb{Z}_+$  having empty interior, except for the empty set. Therefore,  $\mathbb{Z}_+$  satisfies the Baire condition vacuously.
- 3. The interval  $[0,1] \times 0$  has **empty interior** as a subset of the plane  $\mathbb{R}^2$ , and so does the subset  $\mathbb{Q} \times \mathbb{R}$ .

#### • Definition (Baire Category)

A subset A of a space X was said to be of <u>the first category in X</u> if it was contained in the union of a countable collection of closed sets of X having empty interiors in X; otherwise, it was said to be of the second category in X.

- Remark A space X is a Baire space if and only if every nonempty open set in X is of the second category.
- Lemma 4.3 (Open Set Definition of Baire Space) [Munkres, 2000] X is a Baire space if and only if given any countable collection  $\{U_n\}$  of open sets in X, each of which is dense in X, their intersection  $\bigcap_{n=1}^{\infty} U_n$  is also dense in X.
- Theorem 4.4 (Baire Category Theorem). [Munkres, 2000]

  If X is a compact Hausdorff space or a complete metric space, then X is a Baire

space.

- Remark In other word, neither *compact Hausdorff* space or a *complete metric space* is a *countable union of closed subsets with empty interior (that are nowhere dense)*.
- Lemma 4.5 [Munkres, 2000] Let  $C_1 \supset C_2 \supset ...$  be a **nested** sequence of **nonempty closed sets** in the **complete metric space** X. If diam  $C_n \to 0$ , then  $\bigcap_n C_n = \emptyset$ .
- Lemma 4.6 [Munkres, 2000]

  Any open subspace Y of a Baire space X is itself a Baire space.
- Theorem 4.7 (Discontinuity Point of Pointwise Convergence Function) [Munkres, 2000]
   Let X be a space: let (Y d) be a metric space. Let f<sub>∞</sub>: X → Y be a sequence of continuous

Let X be a space; let (Y,d) be a metric space. Let  $f_n: X \to Y$  be a sequence of continuous functions such that  $f_n(x) \to f(x)$  for all  $x \in X$ , where  $f: X \to Y$ . If X is a **Baire space**, the set of points at which f is **continuous** is **dense** in X.

• Remark (Use Baire Category Theorem as Proof by Contradition)

The Baire category theorem is used to prove a certain subset C is dense in X by stating that X is a Baire space and C is countable intersection of dense open subsets in X (C is a  $G_{\delta}$  sets).

On the other hand, if  $M = \bigcup_{n=1}^{\infty} A_n$  has **nonempty interior**, then **some** of the sets  $\bar{A}_n$  must have nonempty interior. Otherwise, it contradicts with the Baire space definition.

#### 4.3 Uniform Boundedness Theorem

Proposition 4.8 [Reed and Simon, 1980]
 Let X and Y be normed linear spaces. Then a linear map: X → Y is bounded if and only if

$$T^{-1}\{y: ||y||_{Y} \le 1\}$$

has a nonempty interior.

**Proof:** Suppose that T is given and the set in question contains the ball

$$\{x: \|x - x_0\|_X < \epsilon\}$$

Then  $||x|| < \epsilon$  implies  $x + x_0$  is in the ball of radius  $\epsilon$  about  $x_0$ . Thus  $||T(x + x_0)||_Y \le 1$  and

$$||Tx||_Y \le ||T(x+x_0)||_Y + ||T(x_0)||_Y \le 1 + ||T(x_0)||_Y.$$

Thus for all  $x \in X$ ,

$$||Tx||_Y \le \epsilon^{-1} (1 + ||T(x_0)||_Y) ||x||_X$$

so is bounded. The converse is easy.

• Theorem 4.9 (The Uniform Boundedness Theorem). [Reed and Simon, 1980] Let X be a Banach space. Let  $\mathscr{F}$  be a family of bounded linear transformations from X to some normed linear space Y. Suppose that for each  $x \in X$ ,  $\{||Tx||_Y : T \in \mathscr{F}\}$  is bounded, i.e.

$$\sup_{T \in \mathscr{F}} \|Tx\|_Y < \infty.$$

Then  $\{||T||: T \in \mathscr{F}\}$  is **bounded**, i.e.

$$\sup_{T\in\mathscr{F}}\|T\|<\infty.$$

**Proof:** Let

$$B_n := \left\{ x : \|Tx\|_Y \le n, \ \forall \, T \in \mathscr{F} \right\}.$$

By the hypothesis each x is in some  $B_n$ , that is,  $X = \bigcup_{n=1}^{\infty} B_n$ . Moreover each  $B_n$  is **closed** since each T is continuous. By the Baire category theorem, some  $B_n$  has a **nonempty** interior. By proposition 4.8, we conclude that the ||T||'s are uniformly bounded.

• Corollary 4.10 (Separately Continuity of Bilinear Form on Banach Space = Joint Continuity) [Reed and Simon, 1980]

Let X and Y be Banach spaces and let  $B(\cdot, \cdot)$  be a **separately continuous bilinear mapping** from  $X \times Y$  to  $\mathbb{C}$ , that is, it is a **bounded** linear transformation if one of the two arguments is fixed. Then  $B(\cdot, \cdot)$  is **jointly continuous**, that is, if  $x_n \to 0$  and  $y_n \to 0$  then  $B(x_n, y_n) \to 0$ .

## 4.4 Open Mapping Theorem

Theorem 4.11 (Open Mapping Theorem) [Reed and Simon, 1980]
 Let T: X → Y be a <u>surjective</u> bounded linear transformation of one Banach space <u>onto</u> another Banach space Y. Then if M is an open set in X, T(M) is open in Y.

**Proof:** We need only show that, for every neighborhood N of x, T(N) is a neighborhood of T(x). Since T(x+N) = T(x) + T(N), we need only show this for x = 0. Since neighborhoods contain balls it is sufficient to show that  $T(B_X(0,r)) \supseteq B_Y(0,r')$ , for some r' where

$$B_X(0,r) = \{x \in X : ||x||_X < r\}.$$

However, since  $T(B_X(0,r)) = r T(B_X(0,1))$ , we need only show that  $T(B_X(0,r))$  is a neighborhood of zero for some r. Finally, by the "translation argument" of the proposition, it is sufficient to show that  $T(B_X(0,r))$  has a **nonempty interior** for **some** r.

Since T is **onto**,

$$Y = \bigcup_{n=1}^{\infty} T(B_X(0, n))$$

so some  $\overline{T(B_X(0,n))}$  has a **nonempty interior**.

Now the hard work begins, since we want  $T(B_X(0,n))$  to have a nonempty interior. By scaling and translating, we can suppose that  $B_Y(0,\epsilon)$  is contained in  $\overline{T(B_X(0,1))}$ ; we will show that  $\overline{T(B_X(0,1))} \subset T(B_X(0,2))$  which will complete the proof.

Let  $y \in \overline{T(B_X(0,1))}$ . Pick  $x_1 \in B_X(0,1)$  so  $y - Tx_1 \in B_Y(0,\epsilon/2) \subset \overline{B_Y(0,1/2)}$ . Now pick  $x_2 \in B_X(0,1/2)$  so that

$$y - Tx_1 - Tx_2 \in B_Y(0, \epsilon/4)$$

By induction, we choose  $x_n \in B_X(0, 2^{1-n})$  so that

$$y - \sum_{j=1}^{n} Tx_j \in B_Y(0, 2^{1-n}\epsilon)$$

Then  $x = \sum_{j=1}^{\infty} x_j$  exists and is in  $B_X(0,2)$  and

$$y = \sum_{j=1}^{\infty} Tx_j = Tx.$$

Thus  $y \in T(B_X(0,2))$ .

- Corollary 4.12 (Inverse Mapping Theorem) [Reed and Simon, 1980]
  A continuous bijection of one Banach space onto another has a continuous inverse.
- Remark Note T is an open map and  $A = T^{-1}(T(A))$  for surjective map, then  $T^{-1}$  is continuous.
- Theorem 4.13 (Banach-Schauder Theorem) [Reed and Simon, 1980] Let T be a continuous linear map,  $T: E \to F$ , where E and F are Banach spaces. Then either T(A) is open in T(E) for each open  $A \subseteq E$ , or T(E) is of first category in  $\overline{T(E)}$ .

## 4.5 Closed Graph Theorem

• Definition (*Graph of Function*)

Let be a mapping of a normed linear space X into a normed linear space Y. The <u>graph of T</u>, denoted by  $\Gamma(T)$ , is defined as

$$\Gamma(T):=\left\{(x,y)\in X\times Y:y=Tx\right\}.$$

• Theorem 4.14 (Closed Graph Theorem) [Reed and Simon, 1980]
Let X and Y be Banach spaces and T a linear map of X into Y. Then T is bounded if and only if the graph of is closed.

**Proof:** Suppose that  $\Gamma(T)$  is **closed**. Then, since is linear,  $\Gamma(T)$  is a **subspace** of **the Banach space direct sum**  $X \oplus Y$ . By assumption  $\Gamma(T)$  is **closed** and thus is a **Banach space** in the norm

$$||(x,Tx)|| = ||x||_X + ||Tx||_Y$$

Consider the **continuous** projection maps  $\pi_1$  and  $\pi_2$ ,

$$\pi_1:(x,Tx)\mapsto x,\quad \pi_2:(x,Tx)\mapsto Tx.$$

 $\pi_1$  is a *bijection* so by *the inverse mapping theorem*  $\pi_1^{-1}$  is *continuous*. But  $T = \pi_2 \circ \pi_1^{-1}$ , so T is *continuous*. The *converse* is *trivial*.

- Remark To avoid future confusion, we emphasize that the T in this theorem is implicitly assumed to be **defined** on all of X.
- Remark Consider the following statements:
  - 1.  $x_n$  converges to some element x;
  - 2.  $Tx_n$  converges to some element y;
  - 3.  $Tx_n = y$ .

Usually to prove T is continuous, one need to show that given statement 1, the statement 2 and 3 are true. That is, we need to **prove convergence** of  $Tx_n$  and need to show **identification** of Tx and the limit of  $Tx_n$ .

With *close graph theorem*, we just need to show that given statement 1 *and* 2, statement 3 is true; that is, we just need to prove the identification part.

• Corollary 4.15 (The Hellinger-Toeplitz Theorem) [Reed and Simon, 1980] Let A be an everywhere defined linear operator on a Hilbert space H with

$$\langle x, Ay \rangle = \langle Ax, y \rangle$$

for all  $x, y \in \mathcal{H}$ ; that is A is **self-adjoint**. Then A is **bounded**.

**Proof:** We will prove that  $\Gamma(A)$  is **closed**. Suppose that  $\langle x_n, Ax_n \rangle \to \langle x, y \rangle$ . We need only prove that  $\langle x, y \rangle \in \Gamma(A)$ , that is, that y = Ax. For any  $z \in \mathcal{H}$ ,

$$\langle z, y \rangle = \lim_{n \to \infty} \langle z, Ax_n \rangle = \lim_{n \to \infty} \langle Az, x_n \rangle$$
  
=  $\langle Az, x \rangle = \langle z, Ax \rangle$ 

Thus y = Ax and  $\Gamma(A)$  is **closed**.

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