

Lecture 0: Summary of Topology (Part 3)

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Nov. 23th., 2022

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1 Metrization Theorems and Paracompactness

1.1 Paracompactness

1.1.1 Local Finiteness

- **Definition (*Local Finiteness*)**

Let X be a topological space. A collection \mathcal{A} of subsets of X is said to be locally finite in X if every point of X has a neighborhood that *intersects only finitely many elements* of \mathcal{A} .

- **Remark (*Understanding Locally Finite*)**

A *locally finite* collection of subsets in a topological space is *evenly spread across the space*. In other word, there exists *no cluster point* $x \in X$ for these subsets so that *every neighborhood of x will intersect with infinitely many subsets in the collection*.

Local finiteness describe the *distribution* of the given collection of subsets in X . We can think of \mathcal{A} as the result of “*uniform sampling*” of subsets across the space.

- **Example (*Locally Finite Collections in \mathbb{R}*)**

The collection of intervals

$$\mathcal{A} = \{(n, n+2) : n \in \mathbb{Z}\}$$

is *locally finite* in the topological space \mathbb{R} .

On the other hand, the collection

$$\mathcal{B} = \{(0, 1/n) : n \in \mathbb{Z}\}$$

has a cluster point $0 \in \mathbb{R}$ so it is not locally finite in \mathbb{R} . However, it is locally finite for $(0, 1)$.

- **Lemma 1.1 (*Properties of Locally Finiteness*)** [Munkres, 2000]

Let \mathcal{A} be a locally finite collection of subsets of X . Then:

1. Any *subcollection* of \mathcal{A} is locally finite.
2. The collection $\mathcal{B} = \{\bar{A}\}_{A \in \mathcal{A}}$ of the *closures* of the elements of \mathcal{A} is locally finite.
3. $\overline{\bigcup_{A \in \mathcal{A}} A} = \bigcup_{A \in \mathcal{A}} \bar{A}$.

- **Remark** There exists collection of sets that is *not locally finite* but the collection of *their closures* is *locally finite*.

For instance, consider $X = (0, 1)$, and let $A_N = \bigcup_{n=1}^N (\frac{n-1}{N}, \frac{n}{N})$ and $\mathcal{A} = \{A_N\}_{N=1}^{\infty}$. For each point of $x \in (0, 1)$, every neighborhood of x intersects with infinite many A_N . But the closure of $A_N = (0, 1)$ itself for every N . Thus $\mathcal{B} = \{\bar{A} : A \in \mathcal{A}\} = \{(0, 1)\}$, which is finite thus locally finite.

- **Definition (*Locally Finite Indexed Family*)**

The indexed family $\{A_\alpha\}_{\alpha \in J}$ is said to be a locally finite indexed family in X if every $x \in X$ has a neighborhood that *intersects A_α for only finitely many values* of α .

- **Remark** $\{A_\alpha\}_{\alpha \in J}$ is a *locally finite indexed family* if and only if it is *locally finite* as a collection of sets and each nonempty subset A of X equals A_α for at most finitely many values of α .

- **Definition (Countably Local Finiteness)**

A collection \mathcal{B} of subsets of X is said to be countably locally finite if \mathcal{B} can be written as the countable union of collections \mathcal{B}_n , each of which is locally finite.

$$\mathcal{B} = \bigcup_{n \in \mathbb{Z}_+} \mathcal{B}_n$$

Countably locally finite is also called σ -locally finite.

- **Remark** Note that both a *countable collection* and a *locally finite collection* are *countably locally finite*.
- **Remark** We can consider a *countably locally finite* collection as the result of *superposition* of *countable layers* of *uniform sampling* of subsets in a topological space.
- **Definition (Refinement of Collection)**

Let \mathcal{A} be a collection of subsets of the space X . A collection \mathcal{B} of subsets of X is said to be a refinement of \mathcal{A} (or is said to refine \mathcal{A}) if for each element B of \mathcal{B} , there is an element A of \mathcal{A} containing B .

If the elements of \mathcal{B} are *open sets*, we call \mathcal{B} an open refinement of \mathcal{A} ; if they are *closed sets*, we call \mathcal{B} a closed refinement.

- **Remark (Finer \Rightarrow Smaller Subsets)**

\mathcal{B} is a refinement of $\mathcal{A} \Rightarrow \forall B \in \mathcal{B}, B$ is a subset of some element in \mathcal{A} .

Note that there may exists some $A \in \mathcal{A}$ does not intersect with any $B \in \mathcal{B}$.

- **Theorem 1.2 [Munkres, 2000]**

Let X be a *metrizable space*. If \mathcal{A} is an *open covering* of X , then there is an open covering \mathcal{C} of X refining \mathcal{A} that is countably locally finite.

- **Remark** For *metrizable space X* , every *open covering* has a *countable locally finite refinement that also covers X* .

1.1.2 Paracompactness

- **Definition (Compactness in terms of Refinement)**

A space X is *compact* if every *open covering \mathcal{A} of X* has a finite open refinement \mathcal{B} that covers X .

- We generalize the definition of compactness by relaxing the finiteness to locally finiteness

Definition (Paracompactness)

A space X is paracompact if every *open covering \mathcal{A} of X* has a locally finite open refinement \mathcal{B} that covers X .

- **Remark (Compactness vs. Paracompactness)**

Paracompactness is a generalization of compactness, i.e. all compact space is paracompact.

Both compactness and paracompactness assert the *existence of an open subcovering with some structure*. But *the constraint on the structure* is different:

1. *Compactness controls the cardinality of subcovering, i.e. to be finite.*

2. *Paracompactness controls the distribution* of subcovering, i.e. to be *evenly distributed* across space without cluster point or to be *locally finite*.

- **Example** (\mathbb{R}^n)

The space \mathbb{R}^n is **paracompact**. Let $X = \mathbb{R}^n$. Let \mathcal{A} be an *open covering* of X . Let $B_0 = \emptyset$, and for each *positive integer* m , let $B_m = B(0, m)$ denote the *open ball of radius m centered at the origin*. Note that $B_m \subseteq B_{m+1}$ for all m and its closure \bar{B}_m is a *compact subset* of \mathbb{R}^n .

Given m , choose *finitely many elements* of \mathcal{A} that **cover** \bar{B}_m (since \bar{B}_m is compact) and **intersect** each one with *the open set* $X \setminus \bar{B}_{m-1}$; let this *finite collection* of open sets be denoted \mathcal{C}_m . That is $\mathcal{C}_m = \{A_i \cap (X \setminus \bar{B}_{m-1}) : A_i \in \mathcal{A}, \bar{B}_m \subseteq \bigcup_i^k A_i, 1 \leq i \leq k\}$. Then the collection $\mathcal{C} = \bigcup_m \mathcal{C}_m$ is a *refinement* of \mathcal{A} .

It is clearly *locally finite*, for the open set B_m intersects only *finitely many elements* of \mathcal{C} , namely those elements belonging to the *collection* $\mathcal{C}_1 \cup \dots \cup \mathcal{C}_m$. Finally, \mathcal{C} covers X . For, given x , let m be the *smallest integer* such that $x \in \bar{B}_m$. Then x belongs to an element of \mathcal{C}_m , by definition. ■

- **Example** (*k-Dimensional Topological Manifold*)

Every *k-dimensional topological manifold* is **paracompact**.

- **Theorem 1.3** [Munkres, 2000]

Every **paracompact Hausdorff** space X is **normal**.

- **Proposition 1.4** (*Paracompactness by Closed Subspace*) [Munkres, 2000]

Every **closed** subspace of a paracompact space is paracompact

- **Remark** A **paracompact subspace** of a Hausdorff space X **need not be closed** in X .

Indeed, the open interval $(0, 1)$ is *paracompact*, being *homeomorphic* to \mathbb{R} , but it is *not closed* in \mathbb{R} .

- **Remark** The **product of two paracompact spaces** **need not be paracompact**.

The space \mathbb{R}_ℓ is *paracompact*, for it is *regular* and *Lindelöf*. However, $\mathbb{R}_\ell \times \mathbb{R}_\ell$ is *not paracompact*, for it is *Hausdorff* but **not normal**.

- **Remark** A **subspace of a paracompact space** **need not be paracompact**.

The space $\bar{S}_\Omega \times \bar{S}_\Omega$ is *compact* and, therefore, **paracompact**. But the *subspace* $S_\Omega \times \bar{S}_\Omega$ is **not paracompact**, for it is *Hausdorff* but *not normal*.

- **Lemma 1.5** [Munkres, 2000]

Let X be **regular**. Then the following conditions on X are **equivalent**: Every open covering of X has a **refinement** that is:

1. An **open** covering of X and countably locally finite.

2. A **covering** of X and **locally finite**.

3. A **closed** covering of X and **locally finite**.

4. An **open** covering of X and locally finite.

- **Remark** Given *regularity* (T_3 *axioms of separation*), “open subcovering that is countably

locally finite” = “*open subcovering that is locally finite*”

- **Theorem 1.6** [Munkres, 2000]
Every **metrizable** space is **paracompact**.
- **Proposition 1.7** [Munkres, 2000]
Every **regular Lindelöf space** is **paracompact**.
- **Example** (\mathbb{R}^ω with **Product and Uniform Topologies**)
The space \mathbb{R}^ω is **paracompact** in both the **product** and **uniform** topologies. This result follows from the fact that \mathbb{R}^ω is **metrizable** in these topologies.
It is *not known* whether \mathbb{R}^ω is **paracompact** in the *box topology*.
- **Example** (\mathbb{R}^J for **Uncountable Product is Not Paracompact**)
For \mathbb{R}^J is *Hausdorff* but **not normal**.

1.1.3 Partition of Unity

- **Remark** *One of the most useful properties* that a **paracompact space** X possesses has to do with the *existence of partitions of unity* on X .

1.2 Metrization Theorems

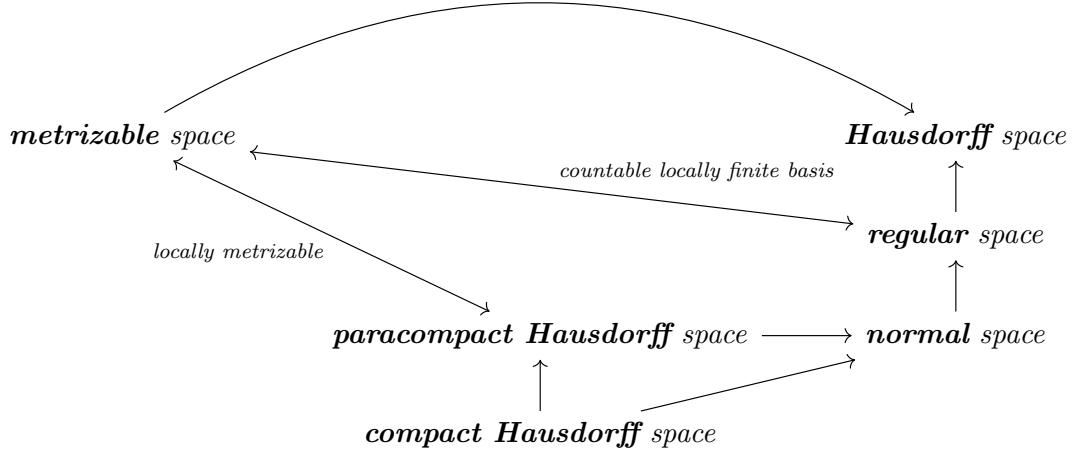
1.2.1 The Nagata-Smirnov Metrization Theorem

- **Theorem 1.8** (*Nagata-Smirnov Metrization Theorem*). [Munkres, 2000]
A space X is **metrizable** if and only if X is regular and has a basis that is countably locally finite.

1.2.2 The Smirnov Metrization Theorem

- **Definition** (*Locally Metrizable*)
A space X is **locally metrizable** if every point x of X has a **neighborhood** U that is **metrizable** in the *subspace topology*.
- **Theorem 1.9** (*Smirnov Metrization Theorem*). [Munkres, 2000]
A space X is **metrizable** if and only if it is a paracompact Hausdorff space that is locally metrizable.

- Remark (*Sufficient and Necessary Conditions for Metrization*)



- Example (*Locally Convex Space is Metrizable*)

Definition (*Locally Convex Space*)

A topological vector space (X, \mathcal{T}) is called **locally convex space** if its topology \mathcal{T} is the *weakest topology* for which all **semi-norms** $\{q_\theta, \theta \in \Theta\}$ are *continuous*. \mathcal{T} is generated by **the convex basis** $U_{x,r,\theta} = \{y \in X \mid q_\theta(y - x) \leq r\} \in \mathcal{B}, x \in X, r > 0$.

From the *Smirnov Metrization Theorem*, we see that **the locally convex space is metrizable**.

2 Complete Metric Spaces and Function Spaces

2.1 Complete Metric Space

- Definition (*Cauchy Net in Topological Vector Space*)

A net $\{x_\alpha\}_{\alpha \in I}$ in **topological vector space** X is called **Cauchy** if the net $\{x_\alpha - x_\beta\}_{(\alpha,\beta) \in I \times I}$ **converges to zero**. (Here $I \times I$ is **directed** in the usual way: $(\alpha, \beta) \prec (\alpha', \beta')$ if and only if $\alpha \prec \alpha'$ and $\beta \prec \beta'$.)

- Definition (*Completeness*)

A topological vector space X is **complete** if every Cauchy net converges.

- Proposition 2.1 (*Complete First Countable Topological Vector Space*)

If X is a **first-countable topological vector space** and every **Cauchy sequence** in X converges, then every **Cauchy net** in X converges.

- Proposition 2.2 (*Completeness of Euclidean Space*) [Munkres, 2000]

Euclidean space \mathbb{R}^k is **complete** in either of its usual **metrics**, the **euclidean metric** d or the **square metric** ρ .

- Lemma 2.3 (*Convergence in Product Space is Weak Convergence*) [Munkres, 2000]

Let X be the product space $X = \prod_{\alpha} X_{\alpha}$; let x_n be a sequence of points of X . Then $x_n \rightarrow x$ if and only if $\pi_{\alpha}(x_n) \rightarrow \pi_{\alpha}(x)$ for each α .

- **Proposition 2.4 (Completeness of Countable Product Space)** [Munkres, 2000]
There is a metric for the product space \mathbb{R}^ω relative to which \mathbb{R}^ω is **complete**.

- **Definition (Uniform Metric in Function Space)**

Let (Y, d) be a metric space; let $\bar{d}(a, b) = \min\{d(a, b), 1\}$ be the **standard bounded metric** on Y derived from d . If $x = (x_\alpha)_{\alpha \in J}$ and $y = (y_\alpha)_{\alpha \in J}$ are points of the cartesian product Y^J , let

$$\bar{\rho}(x, y) = \sup \{ \bar{d}(x_\alpha, y_\alpha) : \alpha \in J \}.$$

It is easy to check that $\bar{\rho}$ is a metric; it is called **the uniform metric** on Y^J corresponding to the metric d on Y .

Note that **the space of all functions** $f : J \rightarrow Y$, denoted as Y^J , is a subset of the product space $J \times Y$. We can define uniform metric in the function space: if $f, g : J \rightarrow Y$, then

$$\bar{\rho}(f, g) = \sup \{ \bar{d}(f(\alpha), g(\alpha)) : \alpha \in J \}.$$

- **Proposition 2.5 (Completeness of Function Space Under Uniform Metric)** [Munkres, 2000]

If the space Y is **complete** in the metric d , then the space Y^J is **complete** in the **uniform metric** $\bar{\rho}$ corresponding to d .

- **Definition (Space of Continuous Functions and Bounded Functions)**

Let Y^X be the space of all functions $f : X \rightarrow Y$, where X is a topological space and Y is a metric space with metric d . Denote the **subspace** of Y^X consisting of all **continuous functions** f as $\mathcal{C}(X, Y)$.

Also denote the set of all **bounded functions** $f : X \rightarrow Y$ as $\mathcal{B}(X, Y)$. (A function f is said to be **bounded** if its image $f(X)$ is a **bounded subset** of the metric space (Y, d) .)

- **Proposition 2.6 (Completeness of $\mathcal{C}(X, Y)$ and $\mathcal{B}(X, Y)$ Under Uniform Metric)** [Munkres, 2000]

Let X be a topological space and let (Y, d) be a metric space. The set $\mathcal{C}(X, Y)$ of **continuous functions** is **closed** in Y^X under the **uniform metric**. So is the set $\mathcal{B}(X, Y)$ of **bounded functions**. Therefore, if Y is **complete**, these spaces are **complete** in the **uniform metric**.

- **Definition (Sup Metric on Bounded Functions)**

If (Y, d) is a metric space, one can define another metric on the set $\mathcal{B}(X, Y)$ of **bounded functions** from X to Y by the equation

$$\rho(x, y) = \sup \{ d(f(x), g(x)) : x \in X \}.$$

It is easy to see that ρ is well-defined, for the set $f(X) \cup g(X)$ is **bounded** if both $f(X)$ and $g(X)$ are. The metric ρ is called **the sup metric**.

- **Theorem 2.7 (Existence of Completion)** [Munkres, 2000]

Let (X, d) be a metric space. There is an **isometric embedding** of X into a **complete metric space**.

- **Definition (Completion)**

Let X be a metric space. If $h : X \rightarrow Y$ is an **isometric embedding** of X into a **complete metric space** Y , then the **subspace** $h(X)$ of Y is a **complete metric space**. It is called **the completion of X** .

- **Definition** (*Topological Complete*)

A space X is said to be topologically complete if there *exists* a metric for the *topology* of X relative to which X is *complete*.

- **Proposition 2.8** (*Properties of Topological Complete*) [Munkres, 2000]

The followings are properties of topological completeness:

1. A **closed** subspace of a topologically complete space is topologically complete.
2. A **countable product** of topologically complete spaces is topologically complete (in the **product topology**).
3. An **open** subspace of a topologically complete space is topologically complete.
4. A G_δ **set** in a topologically complete space is topologically complete.

2.2 Compactness in Metric Spaces

2.2.1 Total Boundedness and Equicontinuous

- **Remark** (*Relate Compactness to Completeness*)

How is **compactness** of a metric space X related to **completeness** of X ?

The followings is from *the sequential compactness* and definition of *completeness*:

Proposition 2.9 *Every compact metric space is complete.*

The *converse* does not hold – **a complete metric space need not be compact**. It is reasonable to ask what **extra condition** one needs to impose on a complete space to be assured of its compactness. Such a condition is the one called *total boundedness*.

- **Definition** (*Total Boundedness*)

A metric space (X, d) is said to be totally bounded if for every $\epsilon > 0$, there is a **finite covering** of X by ϵ -balls.

- **Theorem 2.10** (*Total Boundedness + Completeness = Compactness*) [Munkres, 2000]

A metric space (X, d) is compact if and only if it is complete and totally bounded.

- **Remark** We now apply this result to find **the compact subspaces** of the space $\mathcal{C}(X, \mathbb{R}^n)$, in the **uniform topology**. We know that a subspace of \mathbb{R}^n is compact if and only if it is **closed** and **bounded**.

One might hope that an analogous result holds for $\mathcal{C}(X, \mathbb{R}^n)$. **But** it does not, even if X is *compact*. One needs to assume that the subspace of $\mathcal{C}(X, \mathbb{R}^n)$ satisfies an **additional condition**, called **equicontinuity**.

- **Definition** (*Equicontinuity*) [Reed and Simon, 1980, Munkres, 2000]

Let (Y, d) be a *metric space*. Let \mathcal{F} be a *subset* of the function space $\mathcal{C}(X, Y)$ (i.e. $f \in \mathcal{F}$ is continuous). If $x_0 \in X$, the set \mathcal{F} of functions is said to be equicontinuous at x_0 if given $\epsilon > 0$, there is a neighborhood U of x_0 such that for all $x \in U$ and all $f \in \mathcal{F}$,

$$d(f(x), f(x_0)) < \epsilon.$$

If the set \mathcal{F} is *equicontinuous* at x_0 for each $x_0 \in X$, it is said simply to be equicontinuous

or \mathcal{F} is an equicontinuous family.

We say \mathcal{F} is a uniformly equicontinuous family if and only if for all $\epsilon > 0$, there exists $\delta > 0$ such that $d(f(x), f(x')) < \epsilon$ whenever $p(x, x') < \delta$ for all $x, x' \in X$ and **every** $f \in \mathcal{F}$.

- **Remark** An *equicontinuous family* of functions is a *family of continuous functions*.
- **Remark** *Continuity* of the function f at x_0 means that **given** f and given $\epsilon > 0$, there exists a neighborhood U of x_0 such that $d(f(x), f(x_0)) < \epsilon$ for $x \in U$. **Equicontinuity** of \mathcal{F} means that **a single neighborhood** U can be chosen that will work for all the functions f in the collection \mathcal{F} .
- **Lemma 2.11** (*Total Boundedness \Rightarrow Equicontinuous*) [Munkres, 2000]
Let X be a **space**; let (Y, d) be a **metric space**. If the subset \mathcal{F} of $\mathcal{C}(X, Y)$ is **totally bounded** under the **uniform metric** corresponding to d , then \mathcal{F} is **equicontinuous** under d .
- **Lemma 2.12** (*Equicontinuous + Compactness \Rightarrow Total Boundedness*) [Munkres, 2000]
Let X be a **space**; let (Y, d) be a **metric space**; assume X and Y are **compact**. If the subset \mathcal{F} of $\mathcal{C}(X, Y)$ is **equicontinuous** under d , then \mathcal{F} is **totally bounded** under the **uniform** and **sup** metrics corresponding to d .
- **Definition** (*Pointwise Bounded*)
If (Y, d) is a **metric space**, a subset \mathcal{F} of $\mathcal{C}(X, Y)$ is said to be pointwise bounded under d if for each $x \in X$, the subset

$$F_a = \{f(a) : f \in \mathcal{F}\}$$

of Y is **bounded** under d .

- **Theorem 2.13** (*Ascoli's Theorem, Classical Version*). [Munkres, 2000]
Let X be a **compact space**; let (\mathbb{R}^n, d) denote euclidean space in either the square metric or the euclidean metric; give $\mathcal{C}(X, \mathbb{R}^n)$ the corresponding **uniform topology**. A subspace \mathcal{F} of $\mathcal{C}(X, \mathbb{R}^n)$ has compact closure if and only if \mathcal{F} is equicontinuous and pointwise bounded under d .
- **Corollary 2.14** Let X be **compact**; let d denote either the square metric or the euclidean metric on \mathbb{R}^n ; give $\mathcal{C}(X, \mathbb{R}^n)$ the corresponding **uniform topology**. A subspace \mathcal{F} of $\mathcal{C}(X, \mathbb{R}^n)$ is **compact** if and only if it is closed, bounded under the sup metric ρ , and **equicontinuous** under d .
- **Remark** (*Ascoli's Theorem, Sequence Version*) [Reed and Simon, 1980]
Let $\{f_n\}$ be a family of **uniformly bounded equicontinuous functions** on $[0, 1]$. Then **some subsequence** $\{f_{n,m}\}$ converges **uniformly** on $[0, 1]$.

2.2.2 Pointwise and Compact Convergence

- **Definition** (*Topology of Pointwise Convergence / Point-Open Topology*)

Given a point x of the set X and an open set U of the space Y , let

$$S(x, U) = \{f : f \in Y^X \text{ and } f(x) \in U\}.$$

The sets $S(x, U)$ are a **subbasis** for topology on Y^X , which is called the topology of pointwise convergence (or the point-open topology)

- **Remark** (*Basis of Point-Open Topology*)

The general *basis element* for this topology is a *finite intersection* of subbasis elements $S(x, U)$. Thus a typical **basis element** about the function f consists of all functions g that are “close” to f at finitely many points.

- **Remark** *The topology of pointwise convergence on Y^X is the product topology.*

If we replace X by J and denote the general element of J by α to make it look more familiar, then the set $S(\alpha, U)$ of all functions $x : J \rightarrow Y$ such that $x(\alpha) \in U$ is just the subset $\pi_\alpha^{-1}(U)$ of Y^J , which is the *standard subbasis element* for the product topology.

- **Proposition 2.15** (*Pointwise Convergence Topology*) [Munkres, 2000]

A sequence f_n of functions **converges** to the function f in the **topology of pointwise convergence** if and only if for each x in X , the sequence $f_n(x)$ of **points of Y** converges to the point $f(x)$.

- **Remark** Compare the *subbasis* of the *point-open topology* on function space Y^X and the *weak topology* on space X

$$\begin{aligned} S(x, U) &= \{f : f \in Y^X \text{ and } f(x) \in U\} && \text{point-open topology.} \\ B(f, U) &= \{x : x \in X \text{ and } f(x) \in U\} && \text{weak topology.} \end{aligned}$$

- **Example** (*Pointwise Convergence Does Not Preserve Continuity*)

Consider the space \mathbb{R}^I , where $I = [0, 1]$. The sequence (f_n) of continuous functions given by $f_n(x) = x^n$ converges in the **topology of pointwise convergence** to the function f defined by

$$f(x) = \begin{cases} 0 & \text{for } 0 \leq x < 1 \\ 1 & \text{for } x = 1 \end{cases},$$

This example shows that the subspace $\mathcal{C}(I, \mathbb{R})$ of continuous functions is **not closed** in \mathbb{R}^I in the *topology of pointwise convergence*. Note that $\mathcal{C}(I, \mathbb{R})$ is **closed** in \mathbb{R}^I under **uniform topology** due to *Uniform Limit theorem*.

- **Definition** (*Topology of Compact Convergence*)

Let (Y, d) be a *metric space*; let X be a *topological space*. Given an element f of Y^X , a **compact subspace** C of X , and a number $\epsilon > 0$, let $B_C(f, \epsilon)$ denote the set of all those elements g of Y^X for which

$$\sup\{d(f(x), g(x)) : x \in C\} < \epsilon.$$

The sets $B_C(f, \epsilon)$ form a **basis** for a topology on Y^X . It is called the **topology of compact convergence** (or sometimes the “topology of uniform convergence on compact sets”).

- **Proposition 2.16** (*Topology of Uniform Convergence in Compact Sets*) [Munkres, 2000]

A sequence $f_n : X \rightarrow Y$ of functions converges to the function f in the **topology of compact convergence** if and only if for each **compact subspace** C of X , the sequence $f_n|_C$ converges **uniformly** to $f|_C$.

- **Definition** A space X is said to be **compactly generated** if it satisfies the following condition: A set A is **open** in X if $A \cap C$ is **open** in C for each **compact subspace** C of X .

- **Lemma 2.17** [Munkres, 2000]

If X is **locally compact**, or if X satisfies the **first countability axiom**, then X is **compactly generated**.

- The crucial fact about compactly generated spaces is the following:

Lemma 2.18 (Continuous Extension on Compact Generated Space) [Munkres, 2000]
If X is compactly generated, then a function $f : X \rightarrow Y$ is **continuous** if for each **compact subspace** C of X , the restricted function $f|_C$ is **continuous**.

- **Theorem 2.19 ($\mathcal{C}(X, Y)$ on Compact Generated Space)** [Munkres, 2000]

Let X be a **compactly generated space**: let (Y, d) be a metric space. Then $\mathcal{C}(X, Y)$ is **closed** in Y^X in the topology of compact convergence.

- **Remark (Useful Topologies on Y^X)**

1. **Uniform Topology**: generated by the **basis**

$$B_U(f, \epsilon) = \{g \in Y^X \text{ and } \bar{\rho}(f, g) < \epsilon\}$$

where $\bar{\rho}(f, g) = \sup \{\bar{d}(f(x), g(x)) : x \in X\}$ is the *uniform metric*. It corresponds to **the uniform convergence** of f_n to f in Y^X .

2. **Topology of Pointwise Convergence**: generated by the **subbasis**

$$S(x, U) = \{f : f \in Y^X \text{ and } f(x) \in U\}.$$

It corresponds to **the pointwise convergence** of f_n to f in Y^X .

3. **Topology of Compact Convergence**: generated by the **basis**

$$B_C(f, \epsilon) = \left\{g \in Y^X \text{ and } \sup_{x \in C} d(f(x), g(x)) < \epsilon\right\}.$$

It corresponds to **the uniform convergence** of f_n to f in Y^X for $x \in C$.

- **Remark** Note that both *uniform topology* and *topology of compact convergence* made specific use of the metric d for the space Y , i.e. it can only be defined when the image of function Y is a metric space.

But **the topology of pointwise convergence** does not use the definition of metric d in Y . In fact, **it is defined for any image space Y** .

- **Definition (Compact-Open Topology on Continuous Function Space)**

Let X and Y be topological spaces. If C is a **compact subspace** of X and U is an **open** subset of Y , define

$$S(C, U) = \{f \in \mathcal{C}(X, Y) : f(C) \subseteq U\}.$$

The sets $S(C, U)$ form a **subbasis** for a topology on $\mathcal{C}(X, Y)$ that is called **the compact-open topology**.

- **Proposition 2.20 (Compact-Open on $\mathcal{C}(X, Y) = \text{Compact Convergence}$)** [Munkres, 2000]

Let X be a space and let (Y, d) be a metric space. On the set $\mathcal{C}(X, Y)$, the **compact-open topology** and the **topology of compact convergence** coincide.

- **Corollary 2.21** (*Compact Convergence on $\mathcal{C}(X, Y)$ Need Not d*) [Munkres, 2000]
Let Y be a metric space. The **compact convergence topology** on $\mathcal{C}(X, Y)$ does **not** depend on the **metric** of Y . Therefore if X is **compact**, the **uniform topology** on $\mathcal{C}(X, Y)$ does not depend on the metric of Y .

- **Remark** The fact that the definition of *the compact-open topology* does not involve a *metric* is just one of its useful features.

Another is the fact that it satisfies the requirement of “**joint continuity**”. Roughly speaking, this means that the expression $f(x)$ is *continuous* not only in the *single* “variable x ”, but is *continuous jointly in both* the x and f .

- **Theorem 2.22** (*Compact-Open Topology \Rightarrow Joint Continuity for x and f*)
Let X be **locally compact Hausdorff**; let $\mathcal{C}(X, Y)$ have the **compact-open topology**. Then the map

$$e : X \times \mathcal{C}(X, Y) \rightarrow Y$$

defined by the equation

$$e(x, f) = f(x)$$

is **continuous**. The map e is called the evaluation map.

- **Definition** Given a function $f : X \times Z \rightarrow Y$, there is a corresponding function $F : Z \rightarrow \mathcal{C}(X, Y)$, defined by the equation

$$(F(z))(x) = f(x, z).$$

Conversely, given $F : Z \rightarrow \mathcal{C}(X, Y)$, this equation defines a corresponding function $f : X \times Z \rightarrow Y$. We say that F is the map of Z into $\mathcal{C}(X, Y)$ that is induced by f .

- **Proposition 2.23** Let X and Y be spaces; give $\mathcal{C}(X, Y)$ the **compact-open topology**. If $f : X \times Z \rightarrow Y$ is **continuous**, then **so is** the induced function $F : Z \rightarrow \mathcal{C}(X, Y)$. The converse holds if X is **locally compact Hausdorff**.

2.2.3 Ascoli’s Theorem

- **Theorem 2.24** (*Ascoli’s Theorem, General Version*). [Munkres, 2000]
Let X be a space and let (Y, d) be a metric space. Give $\mathcal{C}(X, Y)$ the topology of compact convergence; let \mathcal{F} be a subset of $\mathcal{C}(X, Y)$.

1. If \mathcal{F} is equicontinuous under d and the set

$$F_a = \{f(a) : f \in \mathcal{F}\}$$

has compact closure for each $a \in X$, then \mathcal{F} is contained in a compact subspace of $\mathcal{C}(X, Y)$.

2. The **converse** holds if X is locally compact Hausdorff.

- **Remark** Compare with classical version, we see generalizations:

1. X need not to be **compact**; \Rightarrow does not even need X to be topological. \Leftarrow holds when X is **locally compact Hausdorff**.
2. $\mathcal{C}(X, Y)$ is under **compact-open topology** which is **weaker** than **uniform topology**, i.e. we do not require convergence of sequence *uniformly* but only *uniformly in a compact subset*.
3. \mathcal{F} does not need to be **pointwise bounded** under d . In other word, the set

$$F_a = \{f(a) : f \in \mathcal{F}\}$$

need not to be **bounded** but need to have **compact closure** for each $a \in X$. Note that for metric space Y , if Y is finite dimensional, it is the same requirement as boundness. But compact closure is stronger than bounded.

- **Proposition 2.25** (**Equicontinuity + Pointwise Convergence \Rightarrow Compact Convergence**) [Munkres, 2000]

Let (Y, d) be a metric space; let $f_n : X \rightarrow Y$ be a sequence of **continuous** functions; let $f : X \rightarrow Y$ be a function (not necessarily continuous). Suppose f_n converges to f in the **topology of pointwise convergence**. If $\{f_n\}$ is **equicontinuous**, then f is **continuous** and f_n converges to f in the **topology of compact convergence**.

3 Baire Spaces

- **Remark** (**Empty Interior = Complement is Dense**)

Recall that if A is a subset of a space X , the **interior** of A is defined as *the union of all open sets of X that are contained in A* .

To say that A has **empty interior** is to say then that A contains no open set of X other than the empty set. **Equivalently**, A has **empty interior** if every point of A is a **limit point of the complement** of A , that is, if the complement of A is dense in X .

$$\overset{\circ}{A} = \emptyset \Leftrightarrow A^c \text{ is dense in } X$$

In [Reed and Simon, 1980], if a subset \overline{A} of X has *empty interior*, A is said to be **nowhere dense** in X .

- **Example** Some examples:

1. The set \mathbb{Q} of *rational*s has **empty interior** as a subset of \mathbb{R}
2. The *interval* $[0, 1]$ has **nonempty interior**.
3. The *interval* $[0, 1] \times 0$ has **empty interior** as a *subset of the plane* \mathbb{R}^2 , and so does the *subset* $\mathbb{Q} \times \mathbb{R}$.

- **Definition** (**Baire Space**)

A space X is said to be a **Baire space** if the following condition holds: Given **any countable** collection $\{A_n\}$ of **closed** sets of X each of which has **empty interior** in X , their **union** $\bigcup_{n=1}^{\infty} A_n$ also has **empty interior** in X .

- **Example** Some examples:

1. The space \mathbb{Q} of *rational*s is **not a Baire space**. For each one-point set in \mathbb{Q} is *closed* and has *empty interior* in \mathbb{Q} ; and \mathbb{Q} is the countable union of its one-point subsets.
2. The space \mathbb{Z}_+ , on the other hand, does form a **Baire space**. Every subset of \mathbb{Z}_+ is *open*, so that there exist *no subsets* of \mathbb{Z}_+ having *empty interior*, except for the empty set. Therefore, \mathbb{Z}_+ satisfies the Baire condition vacuously.
3. The interval $[0, 1] \times 0$ has **empty interior** as a subset of the plane \mathbb{R}^2 , and so does the subset $\mathbb{Q} \times \mathbb{R}$.

- **Definition (Baire Category)**

A subset A of a space X was said to be of the first category in X if it *was contained in the union of a countable collection of closed sets of X having empty interiors in X* ; otherwise, it was said to be of the second category in X .

- **Remark** A space X is a **Baire space** if and only if every **nonempty open** set in X is of the second category.

- **Lemma 3.1 (Open Set Definition of Baire Space)** [Munkres, 2000]

X is a **Baire space** if and only if given any countable collection $\{U_n\}$ of **open** sets in X , each of which is **dense** in X , their **intersection** $\bigcap_{n=1}^{\infty} U_n$ is also **dense** in X .

- **Theorem 3.2 (Baire Category Theorem)**. [Munkres, 2000]

If X is a **compact Hausdorff** space or a **complete metric space**, then X is a **Baire space**.

- **Remark** In other word, neither **compact Hausdorff** space or a **complete metric space** is a countable union of closed subsets with empty interior (that are nowhere dense).

- **Lemma 3.3** [Munkres, 2000]

Let $C_1 \supset C_2 \supset \dots$ be a **nested** sequence of **nonempty closed sets** in the **complete metric space** X . If $\text{diam } C_n \rightarrow 0$, then $\bigcap_n C_n = \emptyset$.

- **Lemma 3.4** [Munkres, 2000]

Any **open** subspace Y of a Baire space X is itself a Baire space.

- **Theorem 3.5 (Discontinuity Point of Pointwise Convergence Function)** [Munkres, 2000]

Let X be a space; let (Y, d) be a metric space. Let $f_n : X \rightarrow Y$ be a sequence of continuous functions such that $f_n(x) \rightarrow f(x)$ for all $x \in X$, where $f : X \rightarrow Y$. If X is a **Baire space**, the set of points at which f is **continuous** is **dense** in X .

- **Remark (Use Baire Category Theorem as Proof by Contradiction)**

The **Baire category theorem** is used to prove a certain subset C is **dense** in X by stating that X is a Baire space and C is countable intersection of dense open subsets in X (C is a G_δ sets).

On the other hand, if $M = \bigcup_{n=1}^{\infty} A_n$ has **nonempty interior**, then **some** of the sets \bar{A}_n **must have nonempty interior**. Otherwise, it contradicts with the Baire space definition.

4 The Fundamental Group

References

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Michael Reed and Barry Simon. *Methods of modern mathematical physics: Functional analysis*, volume 1. Gulf Professional Publishing, 1980.