

# Lecture 1: Gaussian Random Element

Tianpei Xie

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# 1 Gaussian Vector and its Distributions

## 1.1 Univariate Case

- **Definition** (*Gaussian Random Variable*)

Let  $(\mathbb{R}, \mathcal{B}(\mathbb{R}))$  be a measurable space, where  $\mathcal{B}(\mathbb{R})$  is the Borel  $\sigma$ -algebra on  $\mathbb{R}$ . A real-valued random variable  $X$  is **Normally distributed** or **Gaussian** with expectation  $\mu \in \mathbb{R}$  and variance  $\sigma^2 > 0$ , if its **distribution density** with respect to Lebesgue measure is

$$p(x) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{(x-\mu)^2}{2\sigma^2}\right).$$

- **Remark** The followings are properties to the **Gaussian distribution**

1. The c.d.f. for **the standard Normal distribution**  $\mathcal{N}(0, 1)$  is

$$\Phi(x) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^x \exp(-u^2/2) du$$

2.  $p(x)$  is **unimodal, symmetric** about the mean  $\mu$  and it is **uniformly bounded** on  $\mathbb{R}$ . which has a **unique maximum**  $\frac{1}{\sqrt{2\pi}\sigma}$  at the mean  $x = \mu$ .
3. The Normal distribution has **super-exponential decay tail**; that is, when  $x$  moves away from  $\mu$ ,  $p(x)$  decreases *monotonically* and *very fast*.
4. The **barycenter** (or the center of gravity) of  $\mathcal{N}(\mu, \sigma^2)$  is  $x = \mu$  due to  $\int (x-\mu)p(x)dx = 0$ ; and the **second central moment**  $\int (x-\mu)^2 p(x)dx = \sigma^2$ .
5. The **characteristic function** (**Fourier transforms**) and **moment generating function** (**Laplace transforms**)

$$\begin{aligned}\mathcal{F}\{p\} &= \mathbb{E}_p[\exp(i\omega x)] = \exp\left(i\mu\omega - \frac{1}{2}\omega^2\sigma^2\right) \\ \mathcal{L}\{p\} &= \mathbb{E}_p[\exp(sx)] = \exp\left(s\mu + \frac{1}{2}s^2\sigma^2\right)\end{aligned}$$

6.  $\mathcal{N}(\mu_1, \sigma_1^2) * \mathcal{N}(\mu_2, \sigma_2^2) = \mathcal{N}(\mu_1 + \mu_2, \sigma_1^2 + \sigma_2^2)$ , where  $*$  is the **convolution operation**. In other words, the family  $\{\mathcal{N}(\mu, \sigma^2)\}$  is **stable** with respect to convolutions

$$\mathcal{P}_1 * \mathcal{P}_2(A) \equiv \int_r \mathcal{P}_1(A-r)\mathcal{P}_2(dr), \quad A \in \mathcal{B}^1.$$

7. The **Gaussian measure** is **convex**. (Note not the density function  $p(x)$  but the measure  $d\mathcal{P} = p(x)dx$ ). That is, for any sets  $A, B \in \mathcal{B}(\mathbb{R})$ , and each  $\gamma \in [0, 1]$ ,

$$\gamma g(\mathcal{P}(A)) + (1-\gamma)g(\mathcal{P}(B)) \leq g(\mathcal{P}(\gamma A + (1-\gamma)B))$$

where  $g : \mathbb{R}_+ \rightarrow \mathbb{R}_+$  is a normalizing function. For Gaussian measure,  $g = \Phi^{-1}$  the inverse c.d.f.

## 1.2 Multivariate Case

- **Definition (Standard Gaussian Random Vector)**

A *random vector*  $X = (X_j)_{j=1}^n \in \mathbb{R}^n$  is called **standard Gaussian**, if its components are *independent* and have a *standard normal distribution*. The **distribution** of  $X$  has a *density*

$$p(\mathbf{x}) = \frac{1}{(2\pi)^n} \exp\left(-\frac{1}{2}\mathbf{x}^T \mathbf{x}\right), \quad \text{for } \mathbf{x} \in \mathbb{R}^n. \quad (1)$$

- **Definition (Gaussian Random Vector)**

A *random vector*  $Y \in \mathbb{R}^n$  is called **Gaussian**, if it can be represented as  $Y = a + LX$ , where  $X$  is a *standard Gaussian vector*,  $a \in \mathbb{R}^n$ , and  $L : \mathbb{R}^n \rightarrow \mathbb{R}^n$  is a **linear mapping**.

Equivalently,

**Definition (Gaussian Random Vector)**

A *random vector*  $Y \in \mathbb{R}^n$  is called **Gaussian**, if  $\langle v, Y \rangle$  is a *Normal random variable* for *each*  $v \in \mathbb{R}^n$ .

- **Definition (Covariance Operator for Gaussian Random Vector)**

Given a Gaussian random vector  $X = (X_j)_{j=1}^n$ , define the **covariance operator** as a **linear mapping**  $K_X : \mathbb{R}^n \rightarrow \mathbb{R}^n$  such that

$$\text{cov}(\langle u, X \rangle, \langle v, X \rangle) = \langle u, K_X(v) \rangle.$$

The *matrix representation* of  $K_X$  is called a **covariance matrix**

$$\mathbf{K} = [K(i, j)]_{i,j=1}^n \in \mathbb{R}^{n \times n}, \quad \text{where } K(i, j) = \langle e_i, K_X(e_j) \rangle.$$

- **Remark (The Covariance Operator is Self-Adjoint and Positive)**

The **covariance operator**  $K$  is **self-adjoint** ( $K_X^* = K_X$ ), **positive semi-definite**  $K \succeq 0$ . This is due to the *symmetry* and *positive definiteness* property of *inner product*.

Equivalently, the covariance matrix  $\mathbf{K}$  is **symmetric**, **positive semi-definite**.

- **Remark (Density for Multivariate Gaussian)**

In the case, when the linear mapping  $L$  is **invertible (non-degenerate)**, the **multivariate Normal distribution**  $\mathcal{N}(\mu, \mathbf{K})$  can be defined via *its density function* w.r.t. the Lebesgue measure on  $\mathbb{R}^n$

$$p(\mathbf{x}) = \frac{1}{\sqrt{(2\pi)^n \det(|\Sigma|)}} \exp\left(-\frac{1}{2}(\mathbf{x} - \mu)^T \mathbf{K}^{-1}(\mathbf{x} - \mu)\right) \quad (2)$$

- **Remark** The expression for density in (2) holds only if the linear operator  $L$  is invertible; that is, the general definition used is the linear projection definition. [Lifshits, 2013]

If  $L$  is singular,  $K$  is singular, i.e.,  $\det K = 0$ ; there is *no proper density expression* as (2). On the other hand, for every  $K$  *nonnegative definite*,  $L = K^{1/2}$  exists and is *nonnegative definite* as well.

- **Remark** (*The Characteristic Function of Multivariate Gaussian*)

The characteristic functions of  $\mathcal{N}(\boldsymbol{\mu}, K)$  is determined by its one-dimension projection

$$\begin{aligned}
\varphi(\mathbf{v}) &= \int \exp(i \langle \mathbf{x}, \mathbf{v} \rangle) \mathcal{P}(d\mathbf{x}) \\
&= \int \exp(ir) \mathcal{P}^v(dr) \\
&= \exp \left( i\mu^v \omega - \frac{1}{2} \sigma^2(\mathbf{v}) \omega^2 \right) \Big|_{\omega=1} \\
&= \exp \left( i \langle \boldsymbol{\mu}, \mathbf{v} \rangle - \frac{1}{2} \langle K \mathbf{v}, \mathbf{v} \rangle \right)
\end{aligned} \tag{3}$$

The equation (3) is known as the *characteristic functional* of measure  $\mathcal{P}$ .

Use the affine mapping  $\boldsymbol{\mu} + L\mathcal{P}_0$ , the characteristic functional is given by

$$\begin{aligned}
\varphi(\mathbf{v}) &= \int \exp(i \langle \boldsymbol{\mu} + L\mathbf{x}, \mathbf{v} \rangle) \mathcal{P}_0(d\mathbf{x}) \\
&= \exp(i \langle \boldsymbol{\mu}, \mathbf{y} \rangle) \int \exp(i \langle L\mathbf{x}, \mathbf{v} \rangle) \mathcal{P}_0(d\mathbf{x}) \\
&= \exp(i \langle \boldsymbol{\mu}, \mathbf{y} \rangle) \int \exp(i \langle \mathbf{x}, L^* \mathbf{v} \rangle) \mathcal{P}_0(d\mathbf{x}) \\
&= \exp \left( i \langle \boldsymbol{\mu}, \mathbf{y} \rangle - \frac{1}{2} \langle L^* \mathbf{v}, L^* \mathbf{v} \rangle \right) \\
&= \exp \left( i \langle \boldsymbol{\mu}, \mathbf{y} \rangle - \frac{1}{2} \langle LL^* \mathbf{v}, \mathbf{v} \rangle \right) \\
&= \exp \left( i \langle \boldsymbol{\mu}, \mathbf{y} \rangle - \frac{1}{2} \langle K \mathbf{v}, \mathbf{v} \rangle \right)
\end{aligned}$$

And the density is computed, for  $L$  invertible, by change of variable for  $\mathbf{y} = \boldsymbol{\mu} + L\mathbf{x}$

$$\begin{aligned}
p_{\boldsymbol{\mu}, K}(\mathbf{y}) &= |\det L|^{-1} p(\mathbf{x}) \\
&= (2\pi)^{n/2} |\mathbf{K}|^{-1/2} \exp(-\langle K^{-1}(\mathbf{y} - \boldsymbol{\mu}), \mathbf{y} - \boldsymbol{\mu} \rangle / 2)
\end{aligned}$$

- **Proposition 1.1** (*Existence and Uniqueness of Gaussian Distribution*) [Lifshits, 2013]  
Let  $\mathcal{P}$  be a Gaussian distribution in  $\mathbb{R}^n$ . Then the mean value  $\boldsymbol{\mu}$  and the covariance operator  $K$  of the measure  $\mathcal{P}$  exist and are **uniquely** defined. The operator  $K$  is **symmetric** and **positive definite**.

- **Proposition 1.2** (*Gaussian Random Vector from Kernel*) [Lifshits, 2013]  
Assume  $\boldsymbol{\mu} \in \mathbb{R}^n$  and  $K : \mathbb{R}^n \rightarrow \mathbb{R}^n$  is nonnegative definite linear operator. Then there exists a unique Gaussian distribution  $\mathcal{N}(\boldsymbol{\mu}, K)$  with mean  $\boldsymbol{\mu}$  and covariance operator  $K$ . The characteristic functional of  $\mathcal{N}(\boldsymbol{\mu}, K)$  has the form of (3). If the operator  $K$  is non-singular, the distribution  $\mathcal{N}(\boldsymbol{\mu}, K)$  is absolutely continuous with respect to the Lebesgue measure, and its density is of form (2). There are no other Gaussian distribution in  $\mathbb{R}^n$ , except for the form  $\mathcal{N}(\boldsymbol{\mu}, K)$ .

## 2 Gaussian Random Element

### 2.1 Gaussian Random Element in Topological Vector Space

- **Definition (Random Element in Topological Vector Space)**

Let  $(\Omega, \mathcal{F}, \mathcal{P})$  be a probability space,  $(\mathcal{X}, \mathcal{B})$  be a **topological vector space** with  $\sigma$ -algebra  $\mathcal{B}$ . A **random element** in  $\mathcal{X}$  is a  $\mathcal{F}/\mathcal{B}$ -measurable function  $X : \Omega \rightarrow \mathcal{X}$  so that

$$X^{-1}(A) \in \mathcal{F}, \quad \forall A \in \mathcal{B}.$$

We write  $X \in \mathcal{X}$ .

- **Definition (Duality)**

Let  $\mathcal{X}^*$  be the **dual space** of  $\mathcal{X}$ , i.e. the space of **bounded linear functional** on  $\mathcal{X}$ .

We denote  $\langle f, x \rangle$  the **duality** between the spaces  $\mathcal{X}$  and  $\mathcal{X}^*$ , i.e.

$$\langle f, x \rangle := f(x), \quad \forall f \in \mathcal{X}^*, x \in \mathcal{X}.$$

Note that we **do not confuse this notation with inner product**. In inner product  $\langle x, y \rangle$  both arguments are from the same space.

- **Definition (Gaussian Random Element in Topological Vector Space)**

A random element  $X \in \mathcal{X}$  is called **Gaussian**, if

$$\langle f, X \rangle := f(X)$$

is a **Normal random variable**, for all  $f \in \mathcal{X}^*$ .

- **Definition (Expectation)**

A vector  $a \in \mathcal{X}$  is called **expectation** of a random element  $X \in \mathcal{X}$ , if

$$\mathbb{E}[\langle f, X \rangle] = \langle f, a \rangle$$

for all  $f \in \mathcal{X}^*$ . We write  $a = \mathbb{E}[X]$ .

- **Definition (Covariance Operator)**

A linear operator  $K : \mathcal{X}^* \rightarrow \mathcal{X}$  is called **covariance operator** of a random vector  $X \in \mathcal{X}$ , if

$$\text{cov}(\langle f, X \rangle, \langle g, X \rangle) = \langle f, Kg \rangle.$$

for all  $f, g \in \mathcal{X}^*$ . We write  $K = \text{cov}(X)$ .

**Remark (Covariance as Function-Valued Linear Transformation on Dual Space)**

The covariance operator  $K : \mathcal{X}^* \rightarrow \mathcal{X}$  acts on linear functional on  $\mathcal{X}$  and returns an element (function) in  $\mathcal{X}$

$$f(Kg) := \text{cov}(f(X), g(X))$$

- **Remark (Covariance Operator is Self-Adjoint and Positive)**

Covariance operator is **self-adjoint**, due to symmetric property of covariance in  $\mathbb{R}$ .

$$\langle f, Kg \rangle = \langle g, Kf \rangle, \quad \forall f, g \in \mathcal{X}^*,$$

and it is positive (semi-definite), i.e.

$$\langle f, Kf \rangle = \text{var}(f(X)) \geq 0, \quad \forall f \in X^*.$$

- **Remark (Topological Constraints on  $\mathcal{X}$  for Gaussian Element)** [Lifshits, 2012]

From the definition of Gaussian element, we see that it only makes sense when *the space of continuous linear functionals on  $\mathcal{X}$  is rich enough*. For example, if  $\mathcal{X}^* = \{0\}$ , then any vector satisfies this definition rendering it *senseless*.

Therefore, usually *one of three situations* of increasing generality is considered.

1.  $\mathcal{X}$  is a separable Banach space, for example,  $\mathcal{C}[0, 1]$ ,  $L^p[0, 1]$  etc;
2.  $\mathcal{X}$  is a complete separable locally convex metrizable topological vector space, for example,  $\mathcal{C}[0, \infty)$ ,  $\mathbb{R}^\infty$  etc.
3.  $\mathcal{X}$  is a locally convex topological vector space and a vector  $X$  is such that its distribution is a **Radon measure**.

In cases (1) and (2) *every finite measure is a Radon measure*, thus case (3) is the most general one. These assumptions are called *usual assumptions* in [Lifshits, 2012, 2013]

- **Proposition 2.1 (Existence of Covariance Operator)** [Lifshits, 2013]

*Under usual assumptions on  $\mathcal{X}$ , every Gaussian random element in  $\mathcal{X}$  possesses an **expectation** and a **covariance operator**. In other words, the distribution of Gaussian elements in  $\mathcal{X}$  is of the form  $\mathcal{N}(a, K)$ .*

- **Remark (Distribution and Characteristic Function of Gaussian Random Element)**

The pair  $(a, K)$  determines *the distribution* of a Gaussian variable  $\langle f, x \rangle$  as

$$\mathcal{N}(\langle f, a \rangle, \langle f, Kf \rangle),$$

and we find the characteristic function of  $\langle f, x \rangle$

$$\begin{aligned} \varphi(\langle f, X \rangle) &= \mathbb{E} [\exp \{i\omega \langle f, x \rangle\}] \\ &= \exp \left( i\omega \langle f, a \rangle - \frac{1}{2} \omega^2 \langle f, Kf \rangle \right) \\ &:= \exp \left( i\omega f(a) - \frac{1}{2} \omega^2 f(Kf) \right) \end{aligned}$$

Any Radon distribution in  $\mathcal{X}$  is determined by its characteristic function. Therefore, distribution  $\mathcal{N}(a, K)$  is **unique**.

## 2.2 Examples of Gaussian Random Elements

- **Example (Standard Gaussian Measure in  $\mathbb{R}^\infty$ )**

Consider the space  $\mathcal{X} = \mathbb{R}^\infty$  of all countable infinite sequence  $(x_1, x_2, \dots)$  equipped with the **product topology**. The product topology induces a metric as

$$\rho(\{x_n\}_{n=1}^\infty, \{y_n\}_{n=1}^\infty) = \sup_n \left\{ \frac{\min |x_n - y_n|, 1}{n} \right\}.$$

$\mathbb{R}^\infty$  is a **complete separable metric space** under the product topology. The dual space  $\mathcal{X}^* = c_0$  is the space of sequences  $(f_1, f_2, \dots)$  with  $f_n = 0$  for all but finite number of  $n$ . The duality

$$\langle f, x \rangle = \sum_{n=1}^{\infty} f_n x_n < \infty.$$

Consider a sequence of *i.i.d.*  $\mathcal{N}(0, 1)$ -distributed random variables as a vector  $X \in \mathcal{X}$ , i.e.  $X := (X_n)_{n=1}^{\infty}$ ,  $X_n \sim \mathcal{N}(0, 1)$ . Due to *stability* of normal distribution, for any  $f \in \mathcal{X}^*$  the random variable

$$\langle f, X \rangle = \sum_{n=1}^{\infty} f_n X_n \sim \mathcal{N}(0, \sigma^2)$$

where  $\sigma^2 = \sum_{n=1}^{\infty} f_n^2 < \infty$ . Therefore,  $X$  is a **Gaussian element**. It is clear that  $\mathbb{E}[X] = 0$ .

**Embedding operator** serves as **covariance operator** for  $X$ , i.e.

$$K = \iota : c_0 \hookrightarrow \mathbb{R}^\infty.$$

To show that

$$\begin{aligned} \text{cov}(\langle f, X \rangle, \langle g, X \rangle) &= \mathbb{E}[\langle f, X \rangle \langle g, X \rangle] \\ &= \mathbb{E}\left[\left(\sum_{n=1}^{\infty} f_n X_n\right) \left(\sum_{n=1}^{\infty} g_n X_n\right)\right] \\ &= \mathbb{E}\left[\sum_{n,m=1}^{\infty} f_n g_m X_n X_m\right] \\ &= \sum_{n,m=1}^{\infty} f_n g_m \mathbb{E}[X_n X_m] = \sum_{n,m=1}^{\infty} f_n g_m \delta_{n,m} \\ &= \sum_{n=1}^{\infty} f_n g_n := \langle f, Kg \rangle \end{aligned}$$

We call the distribution of  $X$  a **standard Gaussian measure in  $\mathbb{R}^\infty$** . ■

- **Example (Gaussian Elements in a Hilbert space  $\mathcal{H}$ )** [Lifshits, 2012]

Let  $\mathcal{X} = \mathcal{H}$  be a **separable Hilbert space** whose inner product will be denoted by  $\langle \cdot, \cdot \rangle_{\mathcal{H}}$ . By the Riesz representation theorem, we can identify its dual space  $\mathcal{H}^*$  with  $\mathcal{H}$ , i.e. for each  $f \in \mathcal{H}^*$ , there exists a unique  $x_f \in \mathcal{H}$  such that

$$\langle f, x \rangle = f(x) = \langle x, x_f \rangle_{\mathcal{H}}, \quad \forall x \in \mathcal{H}.$$

Define  $h : \mathcal{H}^* \rightarrow \mathcal{H}$  as an *isometric isomorphism* that maps  $f \mapsto x_f$ .

In order to construct a Gaussian element in  $\mathcal{H}$ , consider a **complete orthonormal basis**  $\{\varphi_n\}_{n=1}^{\infty}$  on  $\mathcal{H}$ , a sequence of **independent  $\mathcal{N}(0, 1)$ -distributed random variables**  $\{\xi_n\}_{n=1}^{\infty}$ , and a sequence of **non-negative numbers**  $\{\sigma_n\}_{n=1}^{\infty}$  satisfying assumption  $\sum_{n=1}^{\infty} \sigma_n^2 < \infty$  so that the series

$$\sum_{n=1}^{\infty} \sigma_n \xi_n(\omega) \varphi_n$$

is **convergent** in  $\|\cdot\|_{\mathcal{H}}$ -**norm almost surely** in  $\mathcal{H}$ . Define a *random element*  $X : \Omega \rightarrow \mathcal{H}$  as the limit of the series

$$X = \sum_{n=1}^{\infty} \sigma_n \xi_n \varphi_n \quad (4)$$

This representation is called **Karhunen-Loève expansion**.

For any linear functional  $f \in \mathcal{H}^*$ , we can its corresponding vector  $x_f = h(f) \in \mathcal{H}$  and  $x_f = \sum_{n=1}^{\infty} f_n \varphi_n$ . Thus the random variable

$$\begin{aligned} \langle f, X \rangle &= \langle X, x_f \rangle_{\mathcal{H}} = \left\langle \sum_{n=1}^{\infty} \sigma_n \xi_n \varphi_n, \sum_{n=1}^{\infty} f_n \varphi_n \right\rangle_{\mathcal{H}} \\ &= \sum_{n,m=1}^{\infty} \sigma_n \bar{f}_m \xi_n \langle \varphi_n, \varphi_m \rangle_{\mathcal{H}} \\ &\quad \text{by orthonormal } \langle \varphi_n, \varphi_m \rangle_{\mathcal{H}} = \delta_{n,m} \\ &= \sum_{n=1}^{\infty} \sigma_n \bar{f}_n \xi_n \sim \mathcal{N}(0, \sigma^2) \end{aligned}$$

where  $\sigma^2 := \sum_{n=1}^{\infty} \sigma_n^2 f_n^2 \leq (\sum_{n=1}^{\infty} \sigma_n^2) \sup_n |f_n|^2 < \infty$ . Therefore,  $X$  is a **Gaussian random element** in  $\mathcal{H}$  and  $\mathbb{E}[X] = 0$ . In order to find **the covariance operator** of  $X$ , let us compute

$$\begin{aligned} \text{cov}(\langle f, X \rangle \langle g, X \rangle) &= \mathbb{E}[\langle f, X \rangle \langle g, X \rangle] \\ &= \mathbb{E} \left[ \left( \sum_{n=1}^{\infty} \sigma_n \bar{f}_n \xi_n \right) \left( \sum_{n=1}^{\infty} \sigma_n \bar{g}_n \xi_n \right) \right] \\ &= \sum_{n,m=1}^{\infty} \bar{f}_n \bar{g}_m \sigma_n \sigma_m \mathbb{E}[\xi_n \xi_m] \\ &\quad \text{since } \mathbb{E}[\xi_n \xi_m] = \delta_{n,m} \\ &= \sum_{n=1}^{\infty} \sigma_n^2 \bar{f}_n \bar{g}_n = \langle f, Kg \rangle \end{aligned}$$

By plugging in the basis, we have

$$K : g \rightarrow \sum_{n=1}^{\infty} \sigma_n^2 g_n \varphi_n = \sum_{n=1}^{\infty} \sigma_n^2 \langle g, \varphi_n \rangle \varphi_n \quad (5)$$

$$\Rightarrow \tilde{K} = K \circ h^{-1} = \sum_{n=1}^{\infty} \sigma_n^2 \langle \cdot, \varphi_n \rangle_{\mathcal{H}} \varphi_n \quad (6)$$

Therefore  $\sigma_n^2$  and  $\varphi_n$  are the **eigenvalues** and **eigenfunctions** of  $\tilde{K} = K \circ h^{-1}$  and  $\tilde{K}$  is a **positive, compact operator** on  $\mathcal{H}$  since  $\text{tr}(\tilde{K}) = \sum_{n=1}^{\infty} \sigma_n^2 < \infty$ .

One can show that **any Gaussian element in a Hilbert space admits a representation** (4) [Lifshits, 2012]. This means that a **Gaussian distribution with covariance operator  $K$  exists if and only if** the induced linear operator  $\tilde{K} = K \circ h^{-1} \in \mathcal{L}(\mathcal{H})$  is a **self-adjoint, positive, trace-class operator** (which is **compact**). ■



- **Remark (*Equivalent Definition of Covariance Operator on Hilbert Space*)**

In the previous example, we see that *the covariance operator on Hilbert space* can be equivalently *defined* via linear operator  $\tilde{K} : \mathcal{H} \rightarrow \mathcal{H}$  so that

$$\text{cov}(\langle f_h, X \rangle_{\mathcal{H}}, \langle g_h, X \rangle_{\mathcal{H}}) = \left\langle \tilde{K} f_h, g_h \right\rangle_{\mathcal{H}}.$$

Note that  $\tilde{K} \succeq 0$  is **self-adjoint** and **positive** and it has **finite trace**  $\text{tr}(\tilde{K})$  so it is **trace-class operator** which is **compact**. And, conversely, for any **positive trace-class operator**  $K \in \mathcal{B}_1(\mathcal{H})$ , there exists **Gaussian element** in  $\mathcal{H}$  with distribution  $\mathcal{N}(0, K)$ .

- **Remark (*Identity Operator is Not Covariance Operator on Hilbert Space*)**

For identity operator  $I : \mathcal{H} \rightarrow \mathcal{H}$ , we see that its trace  $\text{tr}(I) = \infty$ , this means that it *does not admit* a Gaussian distribution as  $\mathcal{N}(0, I)$  on infinite dimensional space  $\mathcal{H}$ . In fact, we can see that  $\mathbb{E} \left[ |X(t)|^2 \right] = \infty$ .

## 2.3 Gaussian Random Process

- **Definition (*Random Process*)**

Let  $(\Omega, \mathcal{F}, \mathcal{P})$  be a probability space and  $T$  be a parametric set called **index set**. A **random process**  $X$  on  $T$  is a family of random variables  $X(t, \omega), t \in T$ , defined on the **common probability space**  $(\Omega, \mathcal{F}, \mathcal{P})$ . For each  $\omega \in \Omega$ ,

$$X(\omega) := \{X_t(\omega) : t \in T\}$$

is called a **sample function** of  $(X_t)$  and if  $T$  is one-dimensional, they are often called **sample paths** of the process  $(X_t)$ .

- **Remark** Determined by index set  $T$ , we have:

1. if  $T \subset \mathbb{R}$ ,  $\{X_t\}_{t \in T}$  is called a **random process**.
2. if  $T \subset \mathbb{R}^n$ ,  $\{X_t\}_{t \in T}$  is called a **random field**.
3. if  $T = \mathbb{N}$ ,  $\{X_t\}_{t \in T}$  is called a **random sequence**.

- **Definition (*Gaussian Random Process*)**

A process  $(X_t)_{t \in T}$  is called **Gaussian** if for any  $t_1, \dots, t_n \in T$  the *distribution of the random vector*

$$(X(t_1), \dots, X(t_n))$$

is a **Gaussian distribution** in  $\mathbb{R}_n$ .

The properties of a **Gaussian process** are **completely determined** by its *expectation*  $\mathbb{E}[X(t)], t \in T$ , and *covariance*  $\text{cov}(X(s), X(t)), s, t \in T$ .

- **Remark (*Gaussian Random Process as Gaussian Element on Function Space*)**

Consider the topological vector space  $\mathcal{X} \subset \mathbb{R}^T$  as a **function space** on  $T$ , then the **Gaussian random element** in  $\mathcal{X}$  is a *Gaussian process*:

$$\begin{aligned} X : \Omega &\rightarrow \mathcal{X} \subset \mathbb{R}^T \\ \Rightarrow X(\omega)(t) &= X(\omega, t), \forall t \in T \end{aligned}$$

- **Definition** (*Continuous Sample Path*)

If  $T$  is a **topological space**, we say that  $\{X_t\}_{t \in T}$  has **continuous sample paths**, if the function  $X(\cdot, \omega)$  is **continuous** on  $T$  for  $\mathcal{P}$ -almost every  $\omega \in \Omega$ .

## 2.4 Examples of Gaussian Random Processes

- **Example** (*Continuous Sample Path Gaussian Process*) [Lifshits, 2012]

Let  $T$  be a **compact metric space**, let  $\mathcal{X} = \mathcal{C}(T)$  denote the **Banach space of all continuous functions** on  $T$  equipped with supremum norm

$$\|x\|_\infty := \sup_{t \in T} |x(t)|$$

and with the corresponding **topology of uniform convergence**. By *Riesz-Markov theorem*, the **dual space**  $\mathcal{X}^* = \mathcal{M}(T)$  is a space of **signed Radon measures of finite variations** on  $T$ . The duality is given by

$$\langle \mu, f \rangle = \int_T f d\mu, \quad \forall f \in \mathcal{X}, \forall \mu \in \mathcal{M}(T) = \mathcal{X}^*.$$

Let  $\{X(t), t \in T\}$ , be a **Gaussian random process** with **continuous sample paths** on the parametric set  $T$ . It is **completely characterized** by the functions

$$a(t) := \mathbb{E}[X(t)], \quad K(s, t) := \text{cov}(X(s), X(t)).$$

Then we can view at  $X := \{X(t), t \in T\}$  as a **Gaussian random element** of  $\mathcal{X}$ . The **expectation** of  $X$  is computed as

$$\mathbb{E}[X] = a := (a(t))_{t \in T},$$

and the **covariance operator**  $K : \mathcal{M}(T) \rightarrow \mathcal{C}(T)$  can be calculated by

$$(K\nu)(s) = \int_T K(s, t)\nu(dt). \tag{7}$$

This is because

$$\begin{aligned} \text{cov}(\langle \mu, X \rangle, \langle \nu, X \rangle) &= \mathbb{E}[\langle \mu, (X - a) \rangle \langle \nu, (X - a) \rangle] \\ &= \mathbb{E}\left[\int_T (X - a)d\mu \int_T (X - a)d\nu\right] \\ &= \mathbb{E}\left[\int_{T \times T} (X(s) - a(s))(X(t) - a(t))\mu(ds)\nu(dt)\right] \\ &= \int_T \int_T \mathbb{E}[(X(s) - a(s))(X(t) - a(t))]\mu(ds)\nu(dt) \\ &= \int_T \left(\int_T K(s, t)\nu(dt)\right)\mu(ds) := \langle \mu, K\nu \rangle, \end{aligned}$$

thus we have (7). ■

- **Example (Wiener Process)** [Lifshits, 2012]

We will now consider  $T = [0, 1]$  and  $\mathcal{X} = \mathcal{C}[0, 1]$  with dual  $\mathcal{M}[0, 1]$ . Define a *Gaussian element* composed of the sample paths of a Wiener process

$$\mathcal{W} := \mathcal{W}(t), \quad 0 \leq t \leq 1,$$

i.e. of a process satisfying assumptions

$$\mathbb{E} [\mathcal{W}(t)] = 0, \quad \mathbb{E} [\mathcal{W}(s)\mathcal{W}(t)] = \min \{s, t\}.$$

It is just a special case of previous example, so we can find the expectation of  $\mathcal{W}$  by

$$\mathbb{E} [\langle \mu, \mathcal{W} \rangle] = \mathbb{E} \left[ \int_{[0,1]} \mathcal{W} d\mu \right] = \int_0^1 \mathbb{E} [\mathcal{W}(t)] \mu(dt) = 0$$

we have  $\mathbb{E} [\mathcal{W}] = 0$ . Moreover, the covariance operator  $K : \mathcal{M}([0, 1]) \rightarrow \mathcal{C}([0, 1])$

$$\begin{aligned} (K\nu)(s) &= \int_0^1 K(s, t) \nu(dt) \\ &= \int_0^1 \min \{s, t\} \nu(dt). \quad \blacksquare \end{aligned}$$

**Remark** Finally, we recall the properties of Wiener process  $\mathcal{W}(t)$ : [Lifshits, 2012]

1. It is *1/2-self-similar*, i.e. for any  $c > 0$  the process

$$Y(t) := \frac{\mathcal{W}(ct)}{\sqrt{c}}$$

is also a *Wiener process*;

2. It has *stationary increments*;
3. It has *independent increments*;
4. It is a *Markov process*;
5. It admits *time inversion*: the process

$$Z(t) := t\mathcal{W}\left(\frac{1}{t}\right)$$

is also a *Wiener process*.

## References

- Mikhail Lifshits. Lectures on gaussian processes. In *Lectures on Gaussian Processes*, pages 1–117. Springer, 2012.
- Mikhail Antolevich Lifshits. *Gaussian random functions*, volume 322. Springer Science & Business Media, 2013.