# Lecture 7: Bounded Operators

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## Contents

1	Top	pologies of Bounded Operators	2
2	$Th\epsilon$	e Spectrum	4
	2.1	Finite Dimensional Case	4
	2.2	Infinite Dimensional Case	5
	2.3	Spectrum of Bounded Linear Operator in Banach Space	6
	2.4	Spectrum of Self-Adjoint Operator in Hilbert Space	7
	2.5	Positive Semidefinite Operators and the Polar Decomposition	
3	Con	mpact Operators	9
	3.1	Definitions and Basic Properties	9
	3.2	The Spectrum of Compact Operator	
	3.3	The Trace Class	
	3.4	Hilbert-Schmidt Operator	
	3.5	Trace of Linear Operator	

### 1 Topologies of Bounded Operators

• Definition (Uniform Operator Topology)

Let  $\mathcal{L}(X,Y)$  be the space of bounded linear operators from Banach space X to Banach space Y.  $\mathcal{L}(X,Y)$  is a Banach space with norm

$$||T|| = \sup_{x \neq 0} \frac{||Tx||_Y}{||x||_X}$$

The induced topology on  $\mathcal{L}(X,Y)$  is called <u>the uniform operator topology</u> (or **norm topology**).

• Definition (Strong Operator Topology)

The strong operator topology is the weakest topology on  $\mathcal{L}(X,Y)$  such that the evaluation maps

$$E_x: \mathcal{L}(X,Y) \to Y$$

given by  $E_x(T) = Tx$  are **continuous for all**  $x \in X$ .

• Remark (Multiplication Map) Consider the multiplication map  $\mathcal{L}(X,Y) \times \mathcal{L}(Y,Z) \to \mathcal{L}(X,Z)$ 

$$(A,B) \mapsto BA$$

- 1. In uniform operator topology, the map is jointly continuous.
- 2. In strong operator topology, the map is separately but not jointly continuous if X, Y, and Z are infinite-dimensional.
- Definition (Weak Operator Topology)

  The weak operator topology on  $\mathcal{L}(X,Y)$  is the weakest topology such that the evaluation maps

$$E_{x,f}:\mathcal{L}(X,Y)\to\mathbb{C}$$

given by  $E_{x,f}(T) = f(Tx)$  are all **continuous for all**  $x \in X$ ,  $f \in Y^*$ .

- Remark (Neighborhood in the Bounded Operator Topologies)
  - 1. In *uniform operator topology*: A neighborhood basis at the origin is given by sets of the form

$$\{S \in \mathcal{L}(X,Y): \|S\| < \epsilon\}.$$

2. In **strong operator topology**: A **neighborhood basis** at the *origin* is given by sets of the form

$$\{S \in \mathcal{L}(X,Y): \|Sx_i\|_Y < \epsilon, \ i = 1, \dots, n\}$$

where  $\{x_i\}_{i=1}^n$  is a **finite** collection of elements of X and  $\epsilon$  is positive.

3. In **weak operator topology**: A **neighborhood basis** at the *origin* is given by sets of the form

$$\{S \in \mathcal{L}(X,Y): |f_j(Sx_i)| < \epsilon, i = 1, \dots, n, j = 1, \dots, m\}$$

where  $\{x_i\}_{i=1}^n$  and  $\{f_j\}_{j=1}^m$  are **finite** families of elements of X and Y\*, respectively.

 $\bullet \ \ \mathbf{Remark} \ \ (\textbf{\textit{Convergence in the Bounded Operator Topologies}})$ 

Let  $\mathcal{L}(X,Y)$  be the space of bounded linear operators from Banach space X to Banach space Y.  $\{T_{\alpha}\}$  is a net of operators in  $\mathcal{L}(X,Y)$  and  $T \in \mathcal{L}(X,Y)$ .

1.  $\{T_{\alpha}\}$  converges to T in <u>uniform operator topology</u> (i.e. norm topology) if and only if

$$||T_{\alpha} - T|| \to 0.$$

That is,  $T_{\alpha} \to T$  in **norm**.

2.  $\{T_{\alpha}\}\$ converges to an operator T in strong operator topology if and only if

$$||T_{\alpha}x - Tx||_{Y} \to 0, \quad \forall x \in X.$$

That is,  $T_{\alpha} \stackrel{s}{\to} T$  or  $(T_{\alpha}x)$  converges **strongly in** Y for **every**  $x \in X$ .

3.  $\{T_{\alpha}\}$  converges to an operator T in weak operator topology if and only if

$$|f(T_{\alpha}x) - f(Tx)| \to 0, \quad \forall x \in X, \forall f \in Y^*.$$

That is,  $T_{\alpha} \stackrel{w}{\to} T$  or  $(T_{\alpha}x)$  converges **weakly in** Y for **every**  $x \in X$ .

• Remark

 $uniformly\ operator\ converg\ \Rightarrow\ strongly\ operator\ converg\ \Rightarrow\ weakly\ operator\ converg$ 

- Remark (Weak Operator Topology vs. Weak Topology on  $\mathcal{L}(X,Y)$ )
  We compare the weak operator topology and the weak topology on  $\mathcal{L}(X,Y)$  where  $\mathcal{L}(X,Y)$  is treated as Banach space:
  - 1. The weak operator topology on  $\mathcal{L}(X,Y)$  is the weakest topology such that

$$f(Tx)$$
 is **continuous** w.r.t.  $T$ , **for all**  $x \in X$ ,  $f \in Y^*$ 

2. The weak topology on  $\mathcal{L}(X,Y)$  is the weakest topology such that

$$F(T)$$
 is **continuous** w.r.t.  $T$ , **for all**  $F \in (\mathcal{L}(X,Y))^*$ 

- Remark In general, the weak and strong operator topologies on  $\mathcal{L}(X,Y)$  will not be first-countable so that questions of compactness, net convergence, and sequential convergence are complicated.
- Proposition 1.1 (Weakly Operator Convergence in Hilbert Space) [Reed and Simon, 1980]

Let  $\mathcal{L}(\mathcal{H})$  denote the bounded operators on a Hilbert space  $\mathcal{H}$ . Let  $T_n$  be a **sequence** of bounded operators and suppose that  $\langle T_n x, y \rangle$  converges as  $n \to \infty$  for each  $x, y \in \mathcal{H}$ . Then there exists  $T \in \mathcal{L}(\mathcal{H})$  such that  $T_n \xrightarrow{w} T$ .

- Remark (Stronly Operator Convergence in Hilbert Space) [Reed and Simon, 1980] If  $T_n x$  converges for each  $x \in \mathcal{H}$ , then there exists  $T \in \mathcal{L}(\mathcal{H})$  such that  $T_n \stackrel{s}{\to} T$ .
- **Definition** (*Kernel* and *Range* of *Linear Operator*) Let  $T \in \mathcal{L}(X,Y)$ . The set of vectors  $x \in X$  so that Tx = 0 is called the <u>kernel</u> of T; that is,

$$Ker(T) := \{x \in X : Tx = 0\}.$$

Note that  $Ker(T) \subseteq X$  is a **closed subspace** of X.

The set of vectors  $y \in Y$  so that y = Tx for some  $x \in X$  is called the **range** of T; that is,

$$Ran(T) := \{ y \in Y : y = Tx \}.$$

Note that  $Ran(T) \subseteq Y$  is a **subspace** of Y, and Ran T may not be closed.

- Example Consider the bounded operators on  $\ell^2$ .
  - 1. Let  $T_n$  be defined by

$$T_n(\xi_1, \xi_2, \ldots) = \left(\frac{1}{n}\xi_1, \frac{1}{n}\xi_2, \ldots\right).$$

Then  $T_n \to 0$  uniformly.

2. Let  $S_n$  be defined by

$$S_n(\xi_1, \xi_2, \ldots) = (\underbrace{0, \ldots, 0}_{n}, \xi_{n+1}, \xi_{n+2}, \ldots).$$

Then  $S_n \to 0$  strongly but not uniformly.

3. Let  $W_n$  be defined by

$$W_n(\xi_1, \xi_2, \ldots) = (\underbrace{0, \ldots, 0}_{n}, \xi_1, \xi_2, \ldots).$$

Then  $W_n \to 0$  in the **weak operator** topology but **not** in the **strong** or **uniform** topologies.

### 2 The Spectrum

### 2.1 Finite Dimensional Case

• Remark (*Eigenvalues* of *Linear Transformation in Finite Dimensional Space*)
If is a linear transformation on  $\mathbb{C}^n$ , then the *eigenvalues* of are the complex numbers  $\lambda$  such that the *determinant* (called *the characteristic determinant*)

$$\det\left(\lambda I - T\right) = 0.$$

The set of such  $\lambda$  is called **the spectrum of** T. It can consist of **at most** n points, since det  $(\lambda I - T)$  is a **polynomial** of degree n, called **the characteristic polynomial** of T.

• Remark If  $\lambda$  is not an eigenvalue, then  $\lambda I - T$  has an inverse since

$$\det(\lambda I - T) \neq 0.$$

- Proposition 2.1 (Invariance of Eigenvalue under Change of Basis) [Kreyszig, 1989]
   All matrices representing a given linear operator T: X → X on a finite dimensional normed space X relative to various bases for X have the same eigenvalues.
- Theorem 2.2 (The Existence of Eigenvalues). [Kreyszig, 1989]
   A linear operator on a finite dimensional complex normed space X ≠ {0} has at least one eigenvalue.

#### 2.2 Infinite Dimensional Case

• Definition (Resolvent and Spectrum) Let  $T \in \mathcal{L}(X)$ . A complex number  $\lambda$  is said to be in the resolvent set  $\rho(T)$  of T if

$$\lambda I - T$$

is a *bijection* with a <u>bounded inverse</u>.

$$R_{\lambda}(T) := (\lambda I - T)^{-1}$$

is called *the resolvent* of T at  $\lambda$ . Note that  $R_{\lambda}(T)$  is defined on Ran  $(\lambda I - T)$ .

If  $\lambda \notin \rho(T)$ , then  $\lambda$  is said to be in the **spectrum**  $\sigma(T)$  **of** T.

- **Remark** The name "**resolvent**" is appropriate, since  $R_{\lambda}(T)$  helps to solve the equation  $(\lambda I T) x = y$ . Thus,  $x = (\lambda I T)^{-1} y = R_{\lambda}(T) y$  provided  $R_{\lambda}(T)$  exists.
- Definition (Point Spectrum, Continuous Spectrum and Residual Spectrum) Let  $T \in \mathcal{L}(X)$ 
  - 1. **Point Spectrum**: An  $x \neq 0$  which satisfies

$$Tx = \lambda x$$
  
or  $(\lambda I - T) x = 0$ , for some  $\lambda \in \mathbb{C}$ 

is called an eigenvector of T;  $\lambda$  is called the corresponding eigenvalue.

If  $\lambda$  is an eigenvalue, then  $(\lambda I - T)$  is **not injective** (i.e. Ker  $(\lambda I - T) \neq \{0\}$ ) so  $\lambda$  is in the spectrum of T. The set of all eigenvalues is called the point spectrum of T. It is denoted as  $\sigma_p(T)$ .

- 2. <u>Continuous Spectrum</u>: If  $\lambda$  is not an eigenvalue and if Ran  $(\lambda I T)$  is dense but the resolvent  $R_{\lambda}(T)$  is unbounded, then  $\lambda$  is said to be in the continuous spectrum. It is denoted as  $\sigma_c(T)$ .
- 3. <u>Residual Spectrum</u>: If  $\lambda$  is not an eigenvalue and if Ran  $(\lambda I T)$  is not dense, then  $\lambda$  is said to be in the residual spectrum. It is denoted as  $\sigma_r(T)$ .
- Remark (Pure Point Spectrum for Finite Dimensional Case) If X is finite dimensional normed linear space,  $T \in \mathcal{L}(X)$  then  $\sigma_c(T) = \sigma_r(T) = \emptyset$ .

Table 1: Comparison between different subset of spectrums and resolvent set

	$\begin{array}{c} \textbf{point spectrum} \\ \sigma_p(T) \end{array}$	$egin{array}{c} oldsymbol{continuous} \ oldsymbol{spectrum} \ \sigma_c(T) \end{array}$	$egin{array}{c} residual \ spectrum \ \sigma_r(T) \end{array}$	$\begin{array}{c} \textbf{resolvent set} \\ \rho(T) \end{array}$
$R_{\lambda}(T)$ exists	×	<b>√</b>	<b>√</b>	✓
$R_{\lambda}(T)$ is <b>bounded</b>	×	×	_	✓
$R_{\lambda}(T)$ is defined in a <b>dense</b> subset of $Y$	×	✓	×	<b>√</b>

• Remark (Partition of Complex Space  $\mathbb{C}$ )

All four sets above are disjoint and they forms a partition of  $\mathbb{C}$ 

$$\mathbb{C} = \rho(T) \cup \sigma(T)$$
  
=  $\rho(T) \cup \sigma_p(T) \cup \sigma_c(T) \cup \sigma_r(T)$ .

We will prove this later.

- ullet Remark (Some Special Case)
  - 1. If X finite dimensional,  $\mathbb{C} = \rho(T) \cup \sigma_p(T)$  since  $\sigma_c(T) = \sigma_r(T) = \emptyset$ .
  - 2. If  $T \in \mathcal{L}(\mathcal{H})$  and T is **self-adjoint**,  $\mathbb{C} = \rho(T) \cup \sigma_p(T) \cup \sigma_c(T)$  since  $\sigma_r(T) = \emptyset$ .
  - 3. If  $T \in \mathcal{L}(\mathcal{H})$  and T is **self-adjoint and compact**,  $\mathbb{C} = \rho(T) \cup \sigma_p(T)$
- Remark If X is a function space, the eigenvectors of linear operator T is called the eigenfunctions of T.
- $\bullet \ \ {\bf Definition} \ \ ({\it Eigenspace} \ \ of \ \ {\it Linear} \ \ {\it Operator}) \\$

The subspace of domain D(T) consisting of  $\{0\}$  and **all eigenvectors** of T corresponding to an eigenvalue  $\lambda$  of T is called **the eigenspace of** T corresponding to that eigenvalue  $\lambda$ .

### 2.3 Spectrum of Bounded Linear Operator in Banach Space

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• Definition (Spectral Radius of Linear Operator)
Let

$$r(T) = \sup_{\lambda \in \sigma(T)} |\lambda|$$

r(T) is called **the spectral radius of** T.

• Proposition 2.3 (Spectral Radius Calculation) [Reed and Simon, 1980] Let X be a Banach space,  $T \in \mathcal{L}(X)$ . Then

$$\lim_{n\to\infty} \|T^n\|^{1/n}$$

exists and is equal to r(T).

• Theorem 2.4 (Spectrum and Resolvent of Adjoint) (Phillips) [Reed and Simon, 1980] Let X be a Banach space,  $T \in \mathcal{L}(X)$ . Then

$$\sigma(T) = \sigma(T')$$
 and  $R_{\lambda}(T') = (R_{\lambda}(T))'$ .

- Proposition 2.5 (Spectrum of Adjoint) [Reed and Simon, 1980] Let X be a Banach space and  $T \in \mathcal{L}(X)$ . Then,
  - 1. If  $\lambda$  is in the **residual spectrum** of T, then  $\lambda$  is in the **point spectrum** of T'.
  - 2. If  $\lambda$  is in the **point spectrum** of T, then  $\lambda$  is in **either** the **point** or the **residual** spectrum of T'.

### 2.4 Spectrum of Self-Adjoint Operator in Hilbert Space

• Proposition 2.6 (Spectral Radius Calculation) [Reed and Simon, 1980] Let X be a Hilbert space,  $T \in \mathcal{L}(X)$  and T is self-adjoint. Then

$$r(T) = ||T||$$

• Theorem 2.7 (Spectrum and Resolvent of Adjoint) (Phillips) [Reed and Simon, 1980] If X is a Hilbert space and  $T \in \mathcal{L}(X)$ , then

$$\sigma(T) = \sigma(T^*)$$
 and  $R_{\lambda}(T^*) = (R_{\lambda}(T))^*$ .

- Proposition 2.8 (Spectrum of Self-Adjoint Operator) [Reed and Simon, 1980] Let be a self-adjoint operator on a Hilbert space H. Then,
  - 1. T has no residual spectrum, i.e.  $\sigma_r(T) = \emptyset$ .
  - 2.  $\sigma(T)$  is a subset of  $\mathbb{R}$ .
  - 3. Eigenvectors corresponding to distinct eigenvalues of T are orthogonal.
- Remark (Resemblence to Symmetric or Hermitian Matrix)

  This property is the same as the spectrum for symmetric real matrix or Hermitian matrix in finite dimensional case. That is,
  - 1. the eigenvalues of symmetric real matrices or Hermitian matrices are all real-valued;
  - 2. the eigenspaces corresponds to distinct eigenvalues are orthogonal to each other.

#### 2.5 Positive Semidefinite Operators and the Polar Decomposition

• Definition (Positive-Semidefinite Operator) Let  $\mathcal{H}$  be a Hilbert space. An operator  $B \in \mathcal{L}(\mathcal{H})$  is called positive-semidefinite if

$$\langle Bx, x \rangle > 0$$
 for all  $x \in \mathcal{H}$ .

We write  $B \succeq 0$  if is positive-semidefinite and  $B \succeq A$  if  $(B - A) \succeq 0$ .

Similarly, B is called **positive-definite** if

$$\langle Bx, x \rangle > 0$$
 for all  $x \neq 0 \in \mathcal{H}$ .

The positive semidefinite operator is sometimes called positive operator.

• Proposition 2.9 (Positive Semi-Definiteness ⇒ Self-Adjoint) [Reed and Simon, 1980] Every (bounded) positive semidefinite operator on a complex Hilbert space is self-adjoint.

**Proof:** Notice that  $\langle Ax, x \rangle$  takes only real value, so

$$\langle Ax \,,\, x \rangle = \overline{\langle Ax \,,\, x \rangle} = \langle x \,,\, Ax \rangle$$

By the polarization identity,

$$\langle Ax, y \rangle = \langle x, Ay \rangle$$

if  $\langle Ax, x \rangle = \langle x, Ax \rangle$  for all x. Thus, if A is positive, it is self-adjoint.

• Remark (Square Root of Positive Semidefinite Operator)
For any  $A \in \mathcal{L}(\mathcal{H})$  notice that the normal operator is positive semi-definite

$$A^*A \succ 0$$

since

$$\langle A^*Ax, x \rangle = ||Ax||^2 \ge 0.$$

Just as  $|z| = \sqrt{\bar{z}z}$ , we want to find the modulus of a linear operator as

$$|A| := \sqrt{A^*A}$$

To show the square root of positive semidefinite operator makes sense, we have the following lemma

**Lemma 2.10** The power series for  $\sqrt{1-z}$  about zero converges **absolutely** for all complex numbers z satisfying  $|z| \le 1$ .

**Theorem 2.11** (Square Root Lemma) [Reed and Simon, 1980] Let  $A \in \mathcal{L}(\mathcal{H})$  and  $A \succeq 0$ . Then there is a unique  $B \in \mathcal{L}(\mathcal{H})$  with  $B \succeq 0$  and  $B^2 = A$ . Furthermore, B commutes with every bounded operator which commutes with A.

• **Definition** For  $A \in \mathcal{L}(\mathcal{H})$ , we can define <u>absolute value</u> of A as the square root of its normal operation

$$|A| := \sqrt{A^*A}$$

8

- **Remark** For  $|\cdot|$  operation on linear operator A:
  - 1.  $|\lambda A| = |\lambda| |A|$
  - 2.  $|\cdot|$  is **norm continuous** on  $\mathcal{L}(\mathcal{H})$

3. in general the following equations do not hold

$$|AB| = |A||B|, \quad |A| = |A^*|$$

• Definition (Partial Isometry)

An operator  $U \in \mathcal{L}(\mathcal{H})$  is called an *isometry* if

$$||Ux|| = ||x||$$
, all  $x \in \mathcal{H}$ .

U is called a <u>partial isometry</u> if U is an isometry when restricted to the closed subspace  $(\text{Ker}(U))^{\perp}$ .

• Remark (Partial Isometry = Unitary  $(Ker(U))^{\perp} \to Ran(U)$ ) If U is a partial isometry,  $\mathcal{H}$  can be written as

$$\mathcal{H} = (\operatorname{Ker}(U)) \oplus (\operatorname{Ker}(U))^{\perp}, \quad \mathcal{H} = (\operatorname{Ran}(U)) \oplus (\operatorname{Ran}(U))^{\perp}$$

and U is a *unitary operator* between  $(Ker(U))^{\perp}$ , the *initial subspace* of U, and Ran(U), the *final subspace* of U.

Moreover, its adjoint is its inverse,  $U^* = (U_{(\mathrm{Ker}(U))^{\perp}})^{-1} : \mathrm{Ran}(U) \to (\mathrm{Ker}(U))^{\perp}$ .

• Proposition 2.12 (Projection Operators by Partial Isometry) [Reed and Simon, 1980] Let U be a partial isometry. Then  $P_i = U^*U$  and  $P_f = UU^*$  are respectively the projections onto the initial and final subspaces of U, i.e.

$$P_i := U^*U = P_{(Ker(U))^{\perp}}, \quad P_f := UU^* = P_{Ran(U)},$$

Conversely, if  $U \in \mathcal{L}(\mathcal{H})$  with  $U^*U$  and  $UU^*$  projections, then U is a partial isometry.

• Theorem 2.13 (Polar Decomposition) [Reed and Simon, 1980] Let A be a bounded linear operator on a Hilbert space. Then there is a partial isometry U such that

$$A = U|A|$$

<u>U</u> is uniquely determined by the condition that Ker(U) = Ker(A). Moreover, Ran(U) = Ran(A).

### 3 Compact Operators

### 3.1 Definitions and Basic Properties

• Definition (Kernel of Integral Operator) Consider the simple operator  $T_K$ , defined in  $\mathcal{C}[0,1]$  by

$$(T_K f)(x) = \int_0^1 K(x, y) f(y) dy,$$

where the function K(x,y) is continuous on the square  $0 \le x,y \le 1$ .  $T_K$  is called an **integral kernel operator** and K(x,y) is called the **kernel** of the integral operator  $T_K$ .

• Remark (Properties of Integral Kernel Operator)

We summary some important property of the integral kernel operator  $T_K$ :

1.  $T_K$  is **bounded linear operator** on C[0,1].

$$|(T_K f)(x)| \le \left(\sup_{(x,y)\in[0,1]\times[0,1]} |K(x,y)|\right) \left(\sup_{y\in[0,1]} |f(y)|\right)$$
  

$$\Rightarrow ||T_K f||_{\infty} \le \left(\sup_{(x,y)\in[0,1]\times[0,1]} |K(x,y)|\right) ||f||_{\infty}$$

2. For  $K^*(x, y) := \overline{K(y, x)}$ ,

$$(T_K)^* = T_{K^*}$$

3. Let  $B_M$  denote the functions f in  $\mathcal{C}[0,1]$  such that  $||f||_{\infty} \leq M$ , i.e. closed  $||||_{\infty}$ -ball in  $\mathcal{C}[0,1]$ 

$$B_M := \{ f \in \mathcal{C}[0,1] : ||f||_{\infty} \le M \}$$

The set of functions  $T_K(B_M) := \{T_K f : f \in B_M\}$  is **equicontinuous**.

**Proof:** Since K(x,y) is continuous on the compact set  $[0,1] \times [0,1]$ , K(x,y) is uniformly continuous. Thus, given an  $\epsilon > 0$ , we can find  $\delta > 0$  such that  $|x - x'| < \delta$  implies  $|K(x,y) - K(x',y)| < \epsilon$  for all  $y \in [0,1]$ . Thus, for all  $f \in B_M$ 

$$\left| (T_K f)(x) - (T_K f)(x') \right| \le \left( \sup_{(x,y) \in [0,1] \times [0,1]} \left| K(x,y) - K(x',y) \right| \right) \|f\|_{\infty}$$
  
 
$$\le \epsilon M. \quad \blacksquare$$

4. Moreover,  $T_K(B_M) := \{T_K f : f \in B_M\}$  is **precompact** in C[0,1], i.e. its closure  $T_K(B_M)$  is **compact**. In other word, for every sequence  $f_n \in B_M$ , the sequence  $T_K f_n$  has a **convergent subsequence**.

This follows from the fact that  $T_K(B_M)$  is equicontinuous and uniformly bounded by  $||T_K|| M$ . So by the Ascoli's theorem, we have the result.

5. The operator norm of  $T_K$  is bounded above by the  $L^2$  norm of kernel function K

$$||T_K|| \le ||K||_{L^2}$$

6. The eigenfunctions of  $T_K \{\varphi_n\}_{n=1}^{\infty}$  forms a complete orthonormal basis in  $L^2(M,\mu)$ .

$$K(x,y) = \sum_{n=1}^{\infty} \lambda_n \varphi_n(x) \overline{\varphi_n(y)}$$

where  $\lambda_n$  is the eigenvalue corresponding to eigenfunction  $\varphi_n$ .

• Definition (Compact Operator)

Let X and Y be Banach spaces. An operator  $T \in \mathcal{L}(X,Y)$  is called <u>compact</u> (or <u>completely continuous</u>) if T takes **bounded sets** in X into <u>precompact sets</u> in Y.

Equivalently, T is **compact** if and only if for every **bounded** sequence  $\{x_n\} \subseteq X$ ,  $\{Tx_n\}$  has a **subsequence** convergent in Y.

• Example (Finite Rank Operators)

Suppose that the range of T is finite dimensional. That is, every vector in the range of T can be written

$$Tx = \sum_{i=1}^{n} \alpha_i y_i,$$

for some fixed family  $\{y_i\}_{i=1}^n$  in Y. If  $x_n$  is any bounded sequence in X, the corresponding  $\alpha_i^{(n)}$  are bounded since T is bounded. The usual subsequence trick allows one to extract a convergent subsequence from  $\{Tx_n\}$  which proves that T is compact.

• An important property of the compact operator is

Theorem 3.1 (Weakly Convergent + Compact Operator = Uniformly Convergent) |Reed and Simon, 1980|

A compact operator maps weakly convergent sequences into norm convergent sequences; i.e. if  $T \in \mathcal{L}(X)$  is compact, then

$$x_n \stackrel{w}{\to} x \quad \Rightarrow \quad Tx_n \stackrel{norm}{\to} Tx.$$

The converse holds true if X is **reflective**.

- Proposition 3.2 [Reed and Simon, 1980] Let X and Y be Banach spaces,  $T \in \mathcal{L}(X,Y)$ .
  - 1. If  $\{T_n\}$  are compact and  $T_n \to T$  in the norm topology, then T is compact.
  - 2. T is compact if and only if T' is compact.
  - 3. If  $S \in \mathcal{L}(Y, Z)$  with Z a Banach space and if T or S is compact, then ST is compact.
- The proposition above shows that the space of compact operators on  $\mathcal{H}$  is a *closed subspace* of  $\mathcal{L}(\mathcal{H})$ , thus it is a *Banach space too*.

Definition (Space of Compact Operators)

Now assume that  $\mathcal{H}$  is a **separable Hilbert space**. We denote the Banach space of **compact** operators on a separable Hilbert space by  $Com(\mathcal{H}) \subset \mathcal{L}(\mathcal{H})$ .

• Theorem 3.3 (Compact Operator Approximated by Finite Rank Operator)[Reed and Simon, 1980]

Let  $\mathcal{H}$  be a **separable Hilbert space**. Then every **compact operator** on  $\mathcal{H}$  is the **norm** limit of a sequence of operators of **finite rank**.

#### 3.2 The Spectrum of Compact Operator

• Remark (Fredholm Alternative)

The basic principle which makes compact operators important is the Fredholm alternative:

If A is **compact**, then **exactly one** of the following two statements holds true:

1.

$$A\varphi = \varphi$$
 has a solution;

2.

$$(I-A)^{-1}$$
 exists.

From the Fredhold alternative, we see that if **for any**  $\varphi$  there is **at most one**  $\psi$  (**uniqueness** statement) such that

$$(I - A) \psi = \varphi$$

then there is always exactly one (i.e. existence statement). That is, compactness and uniqueness together imply existence.

- Theorem 3.4 (Analytic Fredholm Theorem) [Reed and Simon, 1980] Let D be an open connected subset of  $\mathbb{C}$ . Let  $f: D \to \mathcal{L}(\mathcal{H})$  be an analytic operator-valued function such that f(z) is compact for each  $z \in D$ . Then, either
  - 1.  $(I f(z))^{-1}$  exists for  $\mathbf{no} \ z \in D$ ; or
  - 2.  $(I f(z))^{-1}$  exists for **all**  $z \in D \setminus S$  where S is a **discrete** subset of D (i.e. S is a set which has no limit points in D.) In this case,  $(I f(z))^{-1}$  is **meromorphic** in D, analytic in  $D \setminus S$ , the **residues** at the poles are **finite** rank operators, and if  $z \in S$  then

$$f(z)\varphi = \varphi$$

has a nonzero solution in H

- Corollary 3.5 (The Fredholm Alternative) [Reed and Simon, 1980] If A is a compact operator on  $\mathcal{H}$ , then either  $(I - A)^{-1}$  exists or  $\varphi = \varphi$  has a solution.
- Theorem 3.6 (Riesz-Schauder Theorem) [Reed and Simon, 1980] Let A be a compact operator on  $\mathcal{H}$ , then  $\underline{\sigma(A)}$  is a discrete set having no limit points except perhaps  $\lambda = 0$ .

Further, any <u>nonzero</u>  $\lambda \in \sigma(A)$  is an <u>eigenvalue</u> of <u>finite</u> multiplicity (i.e. the corresponding space of eigenvectors is <u>finite</u> dimensional).

• Remark (Compact Operator has only Nonzero Point Spectrum with Finite Dimensional Eigenspace)

Riesz-Schauder Theorem states that the **spectrum** for **compact** operator on **Hilbert** space consists of only the point spectrum besides  $\lambda = 0$ .

Moreover, the eigenspace corresponding to each nonzero eigenvalue is finite dimensional.

• Theorem 3.7 (The Hilbert-Schmidt Theorem) [Reed and Simon, 1980] Let A be a <u>self-adjoint compact operator</u> on  $\mathcal{H}$ . Then, there is a <u>complete orthonormal</u> basis,  $\{\phi_n\}_{n=1}^{\infty}$ , for  $\mathcal{H}$  so that

$$A\phi_n = \lambda_n \phi_n$$

and  $\lambda_n \to 0$  as  $n \to \infty$ .

• Remark (Eigendecomposition of Hilbert Space based on Self-Adjoint Compact Operator)

In other word, given a self-adjoint compact operator A on  $\mathcal{H}$ , the HIlbert space  $\mathcal{H}$  is the direct sum of eigenspaces of A.

$$\mathcal{H} = \bigoplus_{\lambda_n \in \sigma(A) \subset \mathbb{R}} \operatorname{Ker} (\lambda_n I - A)$$

A <u>self-adjoint compact operator</u> on  $\mathcal{H}$  is the closest counterpart of **Hermitian matrix** / Symmetric Real matrix in infinite dimensional space.

• Theorem 3.8 (Canonical Form for Compact Operators) [Reed and Simon, 1980] Let A be a compact operator on  $\mathcal{H}$ . Then there exist (not necessarily complete) orthonormal sets  $\{\psi_n\}_{n=1}^N$  and  $\{\phi_n\}_{n=1}^N$  and positive real numbers  $\{\lambda_n\}_{n=1}^N$  with  $\lambda_n \to 0$ so that

$$A = \sum_{n=1}^{N} \lambda_n \langle \psi_n , \cdot \rangle \phi_n \tag{1}$$

The sum in (1), which may be finite or infinite, **converges in norm**. The numbers,  $\{\lambda_n\}_{n=1}^N$ , are called the **singular values of** A.

• Remark (SVD for Compact Operator)
Recall for finite dimensional case, the singular value decomposition (SVD)

$$A = \sum_{n=1}^{N} \lambda_n \phi_n \psi_n^T.$$

The singular value decomposition is a generalization for the spectral decomposition for self-adjoint operator. But it only exists for compact operator.

#### 3.3 The Trace Class

• We generalize the definition of *trace* of linear operator from finite dimensional space to infinite dimensional space:

Definition (Trace of Positive Semi-Definite Operator) Let  $\mathcal{H}$  be a separable Hilbert space,  $\{\phi_n\}_{n=1}^{\infty}$  an orthonormal basis Then for any positive semi-definite operator  $A \in \mathcal{L}(\mathcal{H})$ , we define

$$\operatorname{tr}(A) = \sum_{n=1}^{\infty} \langle A\phi_n, \phi_n \rangle$$

The number tr(A) is called **the trace of** A.

• Proposition 3.9 (Properties of Trace) [Reed and Simon, 1980] Let  $\mathcal{H}$  be a separable Hilbert space,  $\{\phi_n\}_{n=1}^{\infty}$  an orthonormal basis. Then for any positive semi-definite operator  $A \in \mathcal{L}(\mathcal{H})$ , its trace  $\operatorname{tr}(A)$  as defined above is independent of the orthonormal basis chosen. The trace has the following properties:

- 1. (Linearity):  $\operatorname{tr}(A+B) = \operatorname{tr}(A) + \operatorname{tr}(B)$ .
- 2. (Positive Homogeneity):  $\operatorname{tr}(\lambda A) = \lambda \operatorname{tr}(A)$  for all  $\lambda \geq 0$ .
- 3. (Unitary Invariance):  $\operatorname{tr}(UAU^{-1}) = \operatorname{tr}(A)$  for any unitary operator U.
- 4. (Monotonicity): if  $B \succeq A \succeq 0$ , then  $\operatorname{tr}(B) \geq \operatorname{tr}(A)$
- Remark (Trace of General Linear Operator)

Let  $A \in \mathcal{L}(\mathcal{H})$  be a bounded linear operator on separable Hilbert space. Instead of considering the trace of A, we consider the trace of modulus of A,

$$\operatorname{tr}(|A|) = \operatorname{tr}\left(\sqrt{A^*A}\right).$$

• Definition (Trace Class)

An operator  $A \in \mathcal{L}(\mathcal{H})$  is called **trace class** if and only if

$$\operatorname{tr}(|A|) = \operatorname{tr}\left(\sqrt{A^*A}\right) < \infty.$$

The family of all trace class operators is denoted by  $\mathcal{B}_1(\mathcal{H})$ .

• The following lemma is used in proof of part 2 in next proposition

**Lemma 3.10** Every  $B \in \mathcal{L}(\mathcal{H})$  can be written as a linear combination of **four unitary** operators.

- Proposition 3.11 (Space of Trace Class Operator) [Reed and Simon, 1980] The family of all trace class operators  $\mathcal{B}_1(\mathcal{H})$  is a \*-ideal in  $\mathcal{L}(\mathcal{H})$ , that is,
  - 1.  $\mathcal{B}_1(\mathcal{H})$  is a vector space.
  - 2. (Operator Multiplication) If  $A \in \mathcal{B}_1(\mathcal{H})$  and  $B \in \mathcal{L}(\mathcal{H})$ , then  $AB \in \mathcal{B}_1(\mathcal{H})$  and  $BA \in \mathcal{B}_1(\mathcal{H})$ .
  - 3. (Adjoint) If  $A \in \mathcal{B}_1(\mathcal{H})$  then  $A^* \in \mathcal{B}_1(\mathcal{H})$ .
- $\bullet \ \ \mathbf{Remark} \ \ \mathbf{Definition} \ \ (*\textit{-}Algebra)$

An algebra  $\mathcal{A}$  over field K is a K-vector space together with a binary product  $(a,b) \mapsto ab$  satisfying

- $1. \ a(bc) = (ab)c,$
- 2.  $\lambda(ab) = (\lambda a)b = a(\lambda b),$
- $3. \ a(b+c) = ab + ac,$
- 4. (a+b)c = ac + bc,

for all  $a, b, c \in \mathcal{A}$  and  $\lambda \in K$ .

A \*-algebra  $\mathcal{A}$  is a algebra over  $\mathbb{C}$  with a unary involution \*:  $a \mapsto a^*$  such that

- 1.  $(\lambda a + \mu b)^* = \bar{\lambda} a^* + \bar{\mu} b^*,$
- 2.  $(ab)^* = b^*a^*$ ,
- 3.  $(a^*)^* = a$ ,

for all  $a, b \in \mathcal{A}$  and  $\lambda, \mu \in \mathbb{C}$ .

### Example ( $Hilbert\ Adjoint\ as *-Operation$ )

For  $\mathcal{L}(\mathcal{H})$ , let the \*-operation be the **Hilbert adjoint**, i.e.  $\langle Tx, y \rangle = \langle x, T^*y \rangle$  so  $\mathcal{L}(\mathcal{H})$  is a \*-algebra with operator addition and operator multiplication.

### Definition (Left Ideal)

For an arbitrary  $ring(R, +, \cdot)$ , let (R, +) be its **additive group**. A subset I is called a **left ideal** of R if it is an additive subgroup of R that "absorbs multiplication from the left by elements of R"; that is, I is a left ideal if it satisfies the following two conditions:

- 1. (I, +) is a subgroup of (R, +),
- 2. For every  $r \in R$  and every  $x \in I$ , the product rx is in I.
- Proposition 3.12 (Norm of Trace Class) [Reed and Simon, 1980] Let  $\|\cdot\|_1$  be defined in  $\mathcal{B}_1(\mathcal{H})$  by

$$||A||_1 = \operatorname{tr}(|A|).$$

Then  $\mathcal{B}_1(\mathcal{H})$  is a **Banach space** with norm  $\|\cdot\|_1$  and

$$||A|| \le ||A||_1$$

- Remark  $\mathcal{B}_1(\mathcal{H})$  is **not closed** under the operator norm  $\|\cdot\|$  in  $\mathcal{L}(\mathcal{H})$ .
- Proposition 3.13 (Compactness) [Reed and Simon, 1980] Every  $A \in \mathcal{B}_1(\mathcal{H})$  is compact. A compact operator A is in  $\mathcal{B}_1(\mathcal{H})$  if and only if

$$\sum_{n=1}^{\infty} \lambda_n < \infty$$

where  $\{\lambda_n\}$  are the **singular values** of A.

- Corollary 3.14 (Finite Rank Approximation) [Reed and Simon, 1980] The finite rank operators are  $\|\cdot\|_1$ -dense in  $\mathcal{B}_1(\mathcal{H})$ .
- Proposition 3.15 [Reed and Simon, 1980] If  $A \in \mathcal{B}_1(\mathcal{H})$  and  $\{\varphi_n\}_{n=1}^{\infty}$  is any orthonormal basis, then

$$\sum_{n=1}^{\infty} \langle A\phi_n \,,\, \phi_n \rangle$$

converges absolutely and the limit is independent of the choice of basis.

#### 3.4 Hilbert-Schmidt Operator

• Definition (*Hilbert-Schmidt Operator*) An operator  $T \in \mathcal{L}(\mathcal{H})$  is called *Hilbert-Schmidt* if and only if

$$\operatorname{tr}(T^*T) < \infty.$$

The family of all Hilbert-Schmidt operators is denoted by  $\mathcal{B}_2(\mathcal{H})$  or  $\mathcal{B}_{HS}(\mathcal{H})$ .

- Proposition 3.16 (Space of Hilbert-Schmidt Operator) [Reed and Simon, 1980]
  - 1. The space of all Hilbert-Schmidt operators  $\mathcal{B}_2(\mathcal{H})$  is a \*-ideal in  $\mathcal{L}(\mathcal{H})$ ,
  - 2. (Inner Product): If  $A, B \in \mathcal{B}_2(\mathcal{H})$ , then for any orthonormal basis  $\{\varphi_n\}_{n=1}^{\infty}$ ,

$$\sum_{n=1}^{\infty} \langle A^* B \varphi_n \,,\, \varphi_n \rangle$$

is absolutely summable, and its limit, denoted by  $\langle A, B \rangle_{HS}$ , is independent of the orthonormal basis chosen, i.e.

$$\langle A, B \rangle_{HS} = \operatorname{tr}(A^*B)$$

- 3.  $\mathcal{B}_2(\mathcal{H})$  with inner product  $\langle \cdot, \cdot \rangle_{HS}$  is a **Hilbert space**.
- 4. (Norm): Let  $\|\cdot\|_2$  be defined in  $\mathcal{B}_2(\mathcal{H})$  by

$$||A||_2 := \sqrt{\langle A, A \rangle}_{HS} = \sqrt{\operatorname{tr}(A^*A)}.$$

Then

$$\|A\| \leq \|A\|_2 \leq \|A\|_1 \,, \quad and \quad \|A\|_2 = \|A^*\|_2$$

5. (Compactness) Every  $A \in \mathcal{B}_2(\mathcal{H})$  is compact and a compact operator, A, is in  $\mathcal{B}_2(\mathcal{H})$  if and only if

$$\sum_{n=1}^{\infty} \lambda_n^2 < \infty$$

where  $\{\lambda_n\}$  are the **singular values** of A.

- 6. (Finite Rank Approximation) The finite rank operators are  $\|\cdot\|_2$ -dense in  $\mathcal{B}_2(\mathcal{H})$ .
- 7.  $A \in \mathcal{B}_2(\mathcal{H})$  if and only if

$$\{\|A\varphi_n\|\}_{n=1}^{\infty} \in \ell^2$$

for **some** orthonormal basis  $\{\varphi_n\}_{n=1}^{\infty}$ .

- 8.  $A \in \mathcal{B}_1(\mathcal{H})$  if and only if A = BC with  $B, C \in \mathcal{B}_2(\mathcal{H})$ .
- 9.  $\mathcal{B}_2(\mathcal{H})$  is not  $\|\cdot\|$ -closed in  $\mathcal{L}(\mathcal{H})$ .
- Theorem 3.17 (Hilbert-Schmidt Operator of  $L^2$  Space) [Reed and Simon, 1980] Let  $(M, \mu)$  be a measure space and  $\mathcal{H} = L^2(M, \mu)$ . Then  $T \in \mathcal{L}(\mathcal{H})$  is Hilbert-Schmidt if and only if there is a function

$$K \in L^2(M \times M, \mu \otimes \mu)$$

with

$$(Tf)(x) = \int_{M} K(x, y) f(y) d\mu(y),$$

Moreover,

$$||T||_2^2 = \int_{M \times M} |K(x,y)|^2 d\mu(x) d\mu(y).$$

**Proof:** Let  $K \in L^2(M \times M, \mu \otimes \mu)$  and let  $T_K$  be the associated integral operator. It is easy to see (Problem 25) that  $T_K$  is a well-defined operator on  $\mathcal{H}$  and that

$$||T_K|| \le ||K||_{L^2}$$

Let  $\{\varphi_n\}_{n=1}^{\infty}$  be an orthonormal basis for  $L^2(M,\mu)$ . Then  $\{\varphi_n(x)\overline{\varphi_m(y)}\}_{n,m=1}^{\infty}$  is an orthonormal base for  $L^2(M\times M,\mu\otimes\mu)$  so

$$K = \sum_{n,m=1}^{\infty} \lambda_{n,m} \varphi_n(x) \overline{\varphi_m(y)}$$

Let

$$K_N = \sum_{n,m=1}^{N} \lambda_{n,m} \varphi_n(x) \overline{\varphi_m(y)}$$

Then each  $K_N$  is the integral kernel of a finite rank operator. In fact,

$$T_{K_N} = \sum_{n = 1}^{N} \lambda_{n,m} \langle \varphi_m, \cdot \rangle \varphi_n.$$

Since  $||K_N - K||_{L^2} \to 0$  as  $N \to \infty$ , by inequality above, we have  $||T_{K_N} - T_K|| \to 0$ . Thus  $T_K$  is *compact*. In fact,

$$\operatorname{tr}(T_K^* T_K) = \sum_{n=1}^{\infty} \|T_K \varphi_n\|^2 = \sum_{n=1}^{\infty} |\lambda_{n,m}|^2 = \|K\|_{L^2}^2$$

Thus  $T_K \in \mathcal{B}_2(\mathcal{H})$  and  $||T_K||_2 = ||K||_{L^2}$ .

We have shown that the map  $\mapsto A_K$  is an **isometry** of  $L^2(M \times M, \mu \otimes \mu)$  into  $\mathcal{B}_2(\mathcal{H})$ , so its range is **closed**. But **the finite rank operators** clearly come from kernels and since they are **dense** in  $\mathcal{B}_2(\mathcal{H})$  the range of  $\mapsto A_K$  is all of  $\mathcal{B}_2(\mathcal{H})$ .

• Remark A Hilbert-Schmidt operator T on a square integrable space  $L^2(M,\mu)$  is a integral kernel operator.

In other word, for  $T \in \mathcal{L}(\mathcal{H})$ , if  $\operatorname{tr}(T^*T) < \infty$ , then T is a **compact operator**. If, in particular,  $\mathcal{H} = L^2(M, \mu)$ , then T can be written as the *integral kernel operator* 

$$(Tf)(x) = \int_{M} K(x, y) f(y) d\mu(y),$$

• Theorem 3.18 (Mercer's Theorem) [Borthwick, 2020]. Suppose  $\Omega$  is a compact domain and T is a positive Hilbert-Schmidt operator on  $L^2(\Omega)$ . If the integral kernel  $K(\cdot,\cdot)$  is continuous on  $\Omega \times \Omega$ , then the eigenfunction  $\varphi_k$  is continuous on  $\Omega$  if  $\lambda_k > 0$ , and the expansion

$$K(x,y) = \sum_{n=1}^{\infty} \lambda_n \varphi_n(x) \overline{\varphi_n(y)}$$

converges uniformly on compact sets.

### 3.5 Trace of Linear Operator

 $\bullet$  Definition (Trace)

The map  $\operatorname{tr}: \mathcal{B}_1(\mathcal{H}) \to \mathbb{C}$  given by

$$\operatorname{tr}(A) = \sum_{n=1}^{\infty} \langle A\phi_n, \phi_n \rangle$$

where  $\{\phi_n\}_{n=1}^{\infty}$  is any orthonormal basis in  $\mathcal{H}$  is called <u>the trace</u>.

- Remark For  $A \in \mathcal{B}_1(\mathcal{H})$ ,  $\sum_{n=1}^{\infty} |\langle A\phi_n, \phi_n \rangle| < \infty$  for any orthonormal basis  $\{\phi_n\}_{n=1}^{\infty}$ .
- Remark (*Decomposition of Self-Adjoint operator*) For any  $A \in \mathcal{L}(\mathcal{H})$  and A being self-adjoint,

$$A = A_{+} - A_{-}$$

where both  $A_+$  and  $A_-$  are **positive** and  $A_+A_-=0$ .

Not surprisingly,  $A \in \mathcal{B}_1(\mathcal{H})$  if and only if

$$\operatorname{tr}(A_{+}) < \infty, \operatorname{tr}(A_{-}) < \infty,$$

and

$$\operatorname{tr}(A) = \operatorname{tr}(A_{+}) - \operatorname{tr}(A_{-}).$$

• Finally, we collect the property of trace for linear operators:

Proposition 3.19 (Properties of Trace) [Reed and Simon, 1980]

- 1.  $\operatorname{tr}(\cdot)$  is linear.
- 2.  $\operatorname{tr}(A^*) = \overline{\operatorname{tr}(A)}$ .
- 3.  $\operatorname{tr}(AB) = \operatorname{tr}(BA)$  if  $A \in \mathcal{B}_1(\mathcal{H})$  and  $B \in \mathcal{L}(\mathcal{H})$ .
- Remark If  $A \in \mathcal{B}_1(\mathcal{H})$ , the map

$$B \mapsto \operatorname{tr}(AB)$$

is a *linear functional* on  $\mathcal{L}(\mathcal{H})$ . We can also hold  $B \in \mathcal{L}(\mathcal{H})$  fixed and obtain a *linear functional* on  $\mathcal{B}_1(\mathcal{H})$  given by the map

$$A \mapsto \operatorname{tr}(BA)$$
.

The set of these functionals is just *the dual of*  $\mathcal{B}_1(\mathcal{H})$ .

- Proposition 3.20 (Dual Space of Compact Operators) [Reed and Simon, 1980]
  - 1.  $\mathcal{B}_1(\mathcal{H}) = (Com(\mathcal{H}))^*$ . That is, the map  $A \mapsto \operatorname{tr}(A \cdot)$  is an **isometric isomorphism** of  $\mathcal{B}_1(\mathcal{H})$  onto  $(Com(\mathcal{H}))^*$ .
  - 2.  $\mathcal{L}(\mathcal{H}) = (\mathcal{B}_1(\mathcal{H}))^*$ . That is, the map  $B \mapsto \operatorname{tr}(B \cdot)$  is an **isometric isomorphism** of  $\mathcal{L}(\mathcal{H})$  onto  $(\mathcal{B}_1(\mathcal{H}))^*$ .

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