

Lecture 1: Hilbert Space

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1 Metric Space

1.1 Basics

- **Definition** A *metric space* is a set M and a real-valued function $d(\cdot, \cdot) : M \times M \rightarrow \mathbb{R}$ which satisfies:

1. (**Non-Negativity**) $d(x, y) \geq 0$
2. (**Definiteness**) $d(x, y) = 0$ if and only if $x = y$
3. (**Symmetric**) $d(x, y) = d(y, x)$
4. (**Triangle Inequality**) $d(x, z) \leq d(x, y) + d(y, z)$

The function d is called a **metric** on M . The metric space M equipped with metric d is denoted as (M, d) .

- **Definition** (**Cauchy Sequence**)
A sequence of elements $\{x_n\}$ of a metric space (M, d) is called a **Cauchy sequence** if $\forall \epsilon > 0$, there exists $N \in \mathbb{N}$, for all $n, m \geq N$, $d(x_n, x_m) < \epsilon$.

- **Proposition 1.1** *Any convergent sequence is a Cauchy sequence.*

Note that this is the direct result of *triangle inequality property of a metric*.

- **Definition** (**Complete Metric Space**)
A metric space in which ***all Cauchy sequences converge*** is called **complete**.
- **Remark** In complete metric space, one can prove convergence *without knowing what point the sequence converges to*.
- **Example** The space of *all absolutely integrable functions* $\mathcal{L}^1(X, \mu)$ is ***complete***.
- **Definition** (**Denseness**)
A set B in a *metric space* M is called **dense** if *every $m \in M$ is a limit of elements in B* .
- **Definition** (**Continuity**)
A function $f : (X, d) \rightarrow (Y, p)$ is called ***continuous*** at x if $f(x_n) \xrightarrow{p} f(x)$ whenever $x_n \xrightarrow{d} x$.
- **Definition** (**Isometry**)
A ***bijection*** $h : (X, d) \rightarrow (Y, p)$ which ***preserves the metric***, that is,

$$p(h(x), h(y)) = d(x, y)$$

is called an ***isometry***. It is automatically *continuous*. (X, d) and (Y, p) are said to be ***isometric*** if such an isometry exists.

1.2 Equicontinuity

- **Definition** (**Equicontinuity**) [Reed and Simon, 1980]
Let \mathcal{F} be a family of functions from a metric space (X, p) to another metric space (Y, d) . We say \mathcal{F} is an **equicontinuous family** if and only if for all $\epsilon > 0$ and all $x \in X$, there exists $\delta > 0$ such that $d(f(x), f(x')) < \epsilon$ whenever $p(x, x') < \delta$ ***for every*** $f \in \mathcal{F}$ and all $x' \in X$.

We say \mathcal{F} is a **uniformly equicontinuous family** if and only if for all $\epsilon > 0$, there exists $\delta > 0$ such that $d(f(x), f(x')) < \epsilon$ whenever $p(x, x') < \delta$ for all $x, x' \in X$ and **every** $f \in \mathcal{F}$.

- **Remark** An *equicontinuous family* of functions is a *family of continuous functions*.
- **Remark** The concept of **equicontinuity** is with respect to **a family of functions**, while the concept of *continuity* is for *one fixed function*. In other word, for continuous function f , the radius of input $\delta := \delta(\epsilon, x, f)$ depends on threshold ϵ , the point of continuity x and the function of concern f . But for an **equicontinuous family**, $\delta := \delta(\epsilon, x)$ does not depends on which function $f \in \mathcal{F}$. For a **uniform equicontinuous family**, $\delta := \delta(\epsilon)$ does not depends on which function $f \in \mathcal{F}$ and which point x for continuity.
- **Remark** We can control the behavior of $\lim_{n \rightarrow \infty} f_n(x)$ in two ways [Reed and Simon, 1980]:
 1. **Control its dependence on x :** If the convergence of $\{f_n(x)\}$ does not depends on the choice of x , we have **uniform convergence**. Otherwise, we have **pointwise convergence**.
 2. **Control its dependence on n :** If the convergence of $\{f_n(x)\}$ does not depends on choice of function f_n , we have an **equicontinuous family** $\{f_n\}$. This time it reveals the behavior of x in the limit. What we will see is that one can obtain not only information about the x behavior of the limit but that one can also turn weak information about the approach to the limit into stronger information.

- **Proposition 1.2** Let f_n be a sequence of functions from one metric space to another with the property that the family $\{f_n\}$ is **equicontinuous**. Suppose that $f_n(x) \rightarrow f(x)$ **pointwise** for each x . Then f is **continuous**.
- We see that **pointwise convergence** on a **dense set** combined with **equicontinuity** implies **pointwise convergence everywhere**.

Proposition 1.3 [Reed and Simon, 1980]

Let $\{f_n\}$ be an **equicontinuous family** of functions from one metric space (X, p) to another (Y, d) with Y complete. Suppose that for a **dense set** $D \subseteq X$, we know $f_n(x)$ converges for all $x \in D$. Then $f_n(x)$ converges for all $x \in X$.

- The following shows that uniformly equicontinuous combined with pointwise convergence implies uniform convergence.

Proposition 1.4 [Reed and Simon, 1980]

Let $\{f_n\}$ be a **uniformly equicontinuous family** of functions on $[0, 1]$. Suppose that $f_n(x) \rightarrow f(x)$ for each x in $[0, 1]$. Then $f_n(x) \rightarrow f(x)$ **uniformly** in x .

- **Remark** For functions on $[0, 1]$, every **equicontinuous family** is **uniformly equicontinuous**.
- **Theorem 1.5 (Ascoli's Theorem)** [Reed and Simon, 1980]
Let $\{f_n\}$ be a family of **uniformly bounded equicontinuous functions** on $[0, 1]$. Then some subsequence $\{f_{n,m}\}$ converges **uniformly** on $[0, 1]$.

1.3 Proof of Completeness

- **Remark** To prove completeness, we take an arbitrary *Cauchy sequence* (x_n) in X and show that *it converges in X* . For different spaces, such proofs may vary in complexity, but they have approximately the same general pattern:

1. **Construct an element x** (to be used as a *limit*).
2. **Prove that x is in the space considered.**
3. **Prove convergence $x_n \rightarrow x$** (in the sense of the *metric*)

- **Proposition 1.6 (Completeness of ℓ^∞)**

The space ℓ^∞ is complete.

Proof: Let (x_m) be any Cauchy sequence in the space ℓ^∞ , where $x_m = (\xi_1^{(m)}, \xi_2^{(m)}, \dots)$. Since the metric on ℓ^∞ is given by

$$d(x, y) = \sup_j |\xi_j - \eta_j|$$

where $x = (\xi_j)$ and $y = (\eta_j)$ and (x_m) is Cauchy, for any $\epsilon > 0$ there is an N such that for all $m, n > N$,

$$d(x_m, x_n) = \sup_j \left| \xi_j^{(m)} - \xi_j^{(n)} \right| < \epsilon.$$

A fortiori, for every fixed j ,

$$\left| \xi_j^{(m)} - \xi_j^{(n)} \right| < \epsilon, \quad (m, n > N). \quad (1)$$

Hence for every fixed j , the sequence $(\xi_j^{(1)}, \xi_j^{(2)}, \dots)$ is a *Cauchy sequence* of numbers. It converges, say, $\xi_j^{(m)} \rightarrow \xi_j$ as $m \rightarrow \infty$. Using these infinitely many limits ξ_1, ξ_2, \dots , we define $x = (\xi_1, \xi_2, \dots)$ and show that $x \in \ell^\infty$ and $x_m \rightarrow x$. From (1) with $n \rightarrow \infty$ we have

$$\left| \xi_j^{(m)} - \xi_j \right| \leq \epsilon, \quad (m > N). \quad (2)$$

Since $x_m = (\xi_j^{(m)}) \in \ell^\infty$, there is a real number k_m such that $\left| \xi_j^{(m)} \right| \leq k_m$ for all j . Hence by the triangle inequality

$$|\xi_j| \leq \left| \xi_j - \xi_j^{(m)} \right| + \left| \xi_j^{(m)} \right| \leq \epsilon + k_m \quad (m > N).$$

This inequality holds for every j , and the right-hand side does not involve j . Hence (ξ_j) is a *bounded* sequence of numbers. This implies that $x = (\xi_j) \in \ell^\infty$. Also, from (2) we obtain

$$d(x_m, x) = \sup_j \left| \xi_j^{(m)} - \xi_j \right| \leq \epsilon, \quad (m, n > N).$$

This shows that $x_m \rightarrow x$. Since (x_m) was an arbitrary Cauchy sequence, ℓ^∞ is complete. ■

- **Proposition 1.7 (Completeness of $C^0[a, b]$)**

The space of all continuous function under supremum norm on $[a, b]$ (, denoted as $C^0[a, b]$) is complete.

Proof: Let (x_m) be any Cauchy sequence in $\mathcal{C}^0[a, b]$. Then, given any $\epsilon > 0$, there is an N such that for all $m, n > N$ we have

$$d(x_m, x_n) = \max_{t \in J} |x_m(t) - x_n(t)| \leq \epsilon \quad (3)$$

where $J = [a, b]$. Hence for any fixed $t = t_0 \in J$,

$$|x_m(t_0) - x_n(t_0)| \leq \epsilon, \quad (m, n > N).$$

This shows that $(x_1(t_0), x_2(t_0), \dots)$ is a Cauchy sequence of real numbers. Since \mathbb{R} is complete, the sequence converges, say, $x_m(t_0) \rightarrow x(t_0)$ as $m \rightarrow \infty$. In this way we can associate with each $t \in J$ a unique real number $x(t)$. This defines (*pointwise*) a function x on J , and we show that $x \in \mathcal{C}^0[a, b]$ and $x_m \rightarrow x$. From (3) with $n \rightarrow \infty$ we have

$$\max_{t \in J} |x_m(t) - x(t)| \leq \epsilon, \quad (m > N).$$

Hence for every $t \in J$,

$$|x_m(t) - x(t)| \leq \epsilon, \quad (m > N).$$

This shows that $(x_m(t))$ converges to $x(t)$ *uniformly* on J . Since the x_m 's are *continuous* on J and the convergence is *uniform*, the limit function x is *continuous* on J , as is well known from calculus. Hence $x \in \mathcal{C}^0[a, b]$. Also $x_m \rightarrow x$. This proves completeness of $\mathcal{C}^0[a, b]$. ■

• **Theorem 1.8 (Riesz-Fisher Theorem)** [Reed and Simon, 1980]

Let $\mathcal{L}^1(X, \mu)$ be the space of all absolutely integrable functions on measure space (X, \mathcal{B}, μ) with \mathcal{L}^1 norm. $\mathcal{L}^1(X, \mu)$ is complete.

Proof: Let (f_n) be Cauchy sequence in \mathcal{L}^1 . It is enough to prove some **subsequence converges** (i.e. “Cauchy sequence in a metric space is convergent if and only if it has convergent sub-sequence”). so pass to a subsequence (also labeled f_n with $\|f_n - f_{n+1}\|_{\mathcal{L}^1} \leq 2^{-n}$). Let

$$g_m(x) = \sum_{n=1}^m |f_n(x) - f_{n+1}(x)|$$

Let g_∞ be the *infinite sum* (which may be ∞). Then $g_m \leq g_{m+1} \nearrow g_\infty$ and

$$\int_X |g_m(x)| d\mu = \int_X \left| \sum_{n=1}^m |f_n(x) - f_{n+1}(x)| \right| d\mu \leq \int_X \sum_{n=1}^m |f_n(x) - f_{n+1}(x)| d\mu = \sum_{n=1}^m \|f_n - f_{n+1}\|_{\mathcal{L}^1} \leq 1,$$

so by the *monotone convergence theorem*, $g_\infty \in \mathcal{L}^1(X, \mu)$. Thus $|g_\infty(x)| < \infty$ a.e. As a result

$$f_m(x) = f_1(x) - \sum_{n=1}^{m-1} (f_n(x) - f_{n+1}(x))$$

converges pointwise a.e. to a function $f(x)$. Moreover,

$$|f_m(x)| \leq |f_1(x)| + |g_\infty(x)| < \infty$$

i.e. $f_m(x) \in \mathcal{L}^1(X, \mu)$, so $f_n \rightarrow f$ in \mathcal{L}^1 norm by the *dominated convergence theorem*. ■

• **Proposition 1.9** $\mathcal{C}^0[a, b]$ is **dense** (w.r.t. $\|\cdot\|_1$) in $\mathcal{L}^1([a, b])$. Thus $\mathcal{L}^1([a, b])$ is the **completion** of $\mathcal{C}^0[a, b]$ w.r.t. \mathcal{L}^1 norm.

2 Hilbert Space

- **Remark** (*Hilbert Space vs. Banach Space*)

Hilbert space is a special Banach space equipped with inner product. Historically, Hilbert space appears earlier. The theory of inner product and Hilbert spaces is richer than that of general normed and Banach spaces. *Distinguishing features* are

1. *representations* of \mathcal{H} as a *direct sum* of a *closed subspace* and its *orthogonal complement* (section 2.3),
2. *orthonormal sets* and sequences and corresponding *representations* of elements of \mathcal{H} (section 2.5),
3. *the Riesz representation of bounded linear functionals* by inner products, (section 2.4)
4. *the Hilbert-adjoint operator* T^* of a bounded linear operator T (section 2.10).

2.1 Inner Product Space

- **Remark** Finite-dimensional vector spaces have *three kinds of properties* whose generalizations we will study in the next four chapters:

1. *linear properties*,
2. *metric properties*,
3. and *geometric properties*.

A *Hilbert space* generalizes the *geometric* property of a finite-dimensional vector space to *infinite-dimensional* via definition of inner product.

- **Definition** A complex vector space V is called *an inner product space* if there is a complex-valued function $\langle \cdot, \cdot \rangle : V \times V \rightarrow \mathbb{C}$ that satisfies the following four conditions for an $x, y, z \in V$ and $a, b \in \mathbb{C}$:

1. (**Positive Definiteness**): $\langle x, x \rangle \geq 0$ and $\langle x, x \rangle = 0$ if and only if $x = 0$
2. (**Linearity**): $\langle ax + by, z \rangle = a \langle x, z \rangle + b \langle y, z \rangle$
3. (**Hermitian**): $\langle x, y \rangle = \overline{\langle y, x \rangle}$

The function $\langle \cdot, \cdot \rangle$ is called *an inner product*.

- **Remark** Without “condition $\langle x, x \rangle = 0$ if and only if $x = 0$ ”, we have *semi-inner product* [Conway, 2019].
- **Remark** From *Hermitian property*, we have $\langle x, ay + bz \rangle = \bar{a} \langle x, y \rangle + \bar{b} \langle x, z \rangle$.
- **Remark** For *real vector space*, an inner product is a *symmetric covariant 2-tensor*, or a *symmetric bilinear form*.
- **Remark** Some books [Reed and Simon, 1980] define inner product via *linearity in second argument*; while others [Kreyszig, 1989, Luenberger, 1997, Conway, 2019] defines it in terms

of **linearity in first argument**. The difference is the position of conjugate.

- **Proposition 2.1** Every **inner product space** V is a **normed linear space** with the norm $\|x\| = \sqrt{\langle x, x \rangle}$.

- **Remark** We denote $\|x\| = \sqrt{\langle x, x \rangle}$ as the **length** of a vector. With the definition of length, we can define the **distance** d as

$$d(x, y) := \|x - y\| = \sqrt{\langle x - y, x - y \rangle}.$$

As a consequence of the *Pythagorean Theorem*, d satisfies the triangle inequality so it is a **metric**. Thus **every inner product space is a metric space**.

- **Proposition 2.2 (Parallelogram Law)**

For any $x, y \in (V, \langle \cdot, \cdot \rangle)$,

$$\|x + y\|^2 + \|x - y\|^2 = 2\|x\|^2 + 2\|y\|^2$$

- **Remark** The followings are other versions of **Parallelogram Law**:

$$\begin{aligned}\Re \langle x, y \rangle &= \frac{1}{2} \left(\|x + y\|^2 - \|x\|^2 - \|y\|^2 \right) \\ \Re \langle x, y \rangle &= \frac{1}{2} \left(\|x\|^2 + \|y\|^2 - \|x - y\|^2 \right) \\ \Re \langle x, y \rangle &= \frac{1}{4} \left(\|x + y\|^2 - \|x - y\|^2 \right) \\ \langle x, y \rangle &= \frac{1}{4} \left(\|x + y\|^2 - \|x - y\|^2 + i\|x + iy\|^2 - i\|x - iy\|^2 \right) \\ &= \Re \langle x, y \rangle + i\Re \langle x, iy \rangle\end{aligned}$$

- The converse holds true as well.

Proposition 2.3 In a **normed space** $(V, \|\cdot\|)$, if the **parallelogram law**

$$\|x + y\|^2 + \|x - y\|^2 = 2\|x\|^2 + 2\|y\|^2$$

holds, then there exists a **unique inner product** $\langle \cdot, \cdot \rangle$ on V such that $\|x\| = \sqrt{\langle x, x \rangle}$ for all $x \in V$.

- **Remark** The inner product defines the concept of **angle** (and **orthogonality**), and **distance**. Hence it allows the **geometric property** of Euclidean space to be generalized.
- **Definition** Two vectors, x and y , in an inner product space V are said to be **orthogonal** if $\langle x, y \rangle = 0$. A collection $\{x_n\}$ of vectors in V is called an **orthonormal set** if $\langle x_i, x_i \rangle = 1$ for all i , and $\langle x_i, x_j \rangle = 0$ if $i \neq j$.

- **Theorem 2.4 (Pythagorean Theorem)**

Let $\{x_i\}_{i=1}^n$ be an **orthonormal set** in an inner product space V . Then for all $x \in V$,

$$\|x\|^2 = \sum_{i=1}^n |\langle x_i, x \rangle|^2 + \left\| x - \sum_{i=1}^n \langle x_i, x \rangle x_i \right\|^2$$

- **Corollary 2.5 (*Bessel's inequality*)**

Let $\{x_i\}_{i=1}^n$ be an **orthonormal** set in an inner product space V . Then for all $x \in V$,

$$\|x\|^2 \geq \sum_{i=1}^n |\langle x_i, x \rangle|^2$$

- **Corollary 2.6 (*Cauchy-Schwartz's inequality*)**

Let V be an inner product space. For $x, y \in V$,

$$|\langle x, y \rangle| \leq \|x\| \|y\|.$$

2.2 Hilbert Space

- **Definition** A complete inner product space is called a Hilbert space.

Inner product spaces are sometimes called **pre-Hilbert spaces**.

- **Definition** Two Hilbert spaces \mathcal{H}_1 and \mathcal{H}_2 are said to be isomorphic if there is a surjective linear operator $U : \mathcal{H}_1 \rightarrow \mathcal{H}_2$ such that

$$\langle Ux, Uy \rangle_{\mathcal{H}_2} = \langle x, y \rangle_{\mathcal{H}_1}$$

for all $x, y \in \mathcal{H}_1$. Such an operator is called unitary.

- **Remark (*Isomorphism*)**

For vector space, an (**linear**) **isomorphism** is a **bijjective linear mapping** from one vector spaces to another vector space that **preserve** the **structure** of that vector space. However, depending on definition of specific structure, we can have various different definition of isomorphisms:

1. For metric space, an **isomorphism** is a **bijjective linear operator** that **preserves the metric**. It is often called an isometry.
2. For inner product space, an **isomorphism** is a **surjective linear operator** that **preserves the inner product**. It is often called an surjective isometry.
3. For linear algebra, an **isomorphism** is a **bijjective linear mapping** that **preserves all algebraic operations** (i.e. the vector addition and scalar multiplication).

In general, **isomorphism** is a **structure-preserving mapping** between two structures of the same type that can be reversed by an inverse mapping. It means that “**two spaces are essentially of the same form**”. For instance, the followings are also called **isomorphism** depending on the context:

1. **homomorphism** between *topological spaces*,
2. **diffeomorphism** between *smooth manifolds*,
3. **bijjective homomorphism** between *algebraic groups / rings / fields*,
4. **graph isomorphism** between *graphs* that preserves the edge structure,

Also an isomorphism is called a **transformation** in **geometry**, e.g. *rigid transformation*, *affine transformation* etc.

- **Example** ($\mathcal{L}^2[a, b]$)

Define $\mathcal{L}^2([a, b])$ to be the set of complex-valued measurable functions on $[a, b]$, a finite interval, that satisfy $\int_{[a, b]} |f(x)|^2 dx < \infty$. We define an inner product by

$$\langle f, g \rangle = \int_a^b f(x) \overline{g(x)} dx$$

$\mathcal{L}^2([a, b])$ is a complete metric space. Actually, $\mathcal{L}^2([a, b])$ is a completion of $\mathcal{C}^0([a, b])$ with finite \mathcal{L}^2 norm

$$\|f\|_{\mathcal{L}^2} = \left(\int_a^b |f(x)|^2 dx \right)^{\frac{1}{2}}$$

Thus $\mathcal{L}^2([a, b])$ is a *Hilbert space*.

- **Example** (ℓ^2)

Define ℓ^2 to be the set of sequences $(x_n)_{n=1}^\infty$ of complex numbers which satisfy $\sum_{n=1}^\infty |x_n|^2 < \infty$ with the inner product

$$\langle (x_n)_{n=1}^\infty, (y_n)_{n=1}^\infty \rangle = \sum_{n=1}^\infty \overline{x_n} y_n.$$

ℓ^2 is a complete metric space with ℓ^2 norm

$$\|(x_n)_{n=1}^\infty\|_2 = \left(\sum_{n=1}^\infty |x_n|^2 \right)^{\frac{1}{2}}.$$

So ℓ^2 is a *Hilbert space*.

We will see that any Hilbert space that has a **countable dense set** and is **not finite dimensional** is **isomorphic** to ℓ^2 . In this sense, ℓ^2 is the *canonical example* of a Hilbert space.

- **Example** ($\mathcal{L}^2(\mathbb{R}^n, \mu)$)

Define μ to be a *Borel measure* on \mathbb{R}^n and $\mathcal{L}^2(\mathbb{R}^n, \mu)$ to be the set of complex-valued measurable functions on \mathbb{R}^n that satisfy $\int_{\mathbb{R}^n} |f(x)|^2 d\mu < \infty$. We define an inner product by

$$\langle f, g \rangle = \int_{\mathbb{R}^n} f(x) \overline{g(x)} d\mu$$

$\mathcal{L}^2(\mathbb{R}^n, \mu)$ is a *Hilbert space*.

2.3 The Projection Theorem

- **Remark Orthogonality** is the central concept of Hilbert space. In the presence of closed subspaces, the orthogonality allows us to decompose the Hilbert space into the direct sum of the *subspace* and its *orthogonal complement*.

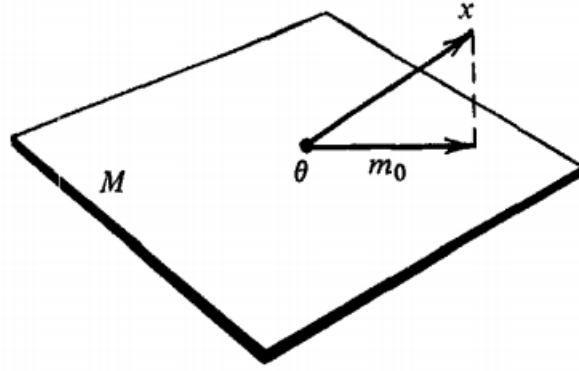


Figure 1: The projection theorem in Hilbert space [Luenberger, 1997]

- **Definition (Direct Sum)**

Suppose that \mathcal{H}_1 and \mathcal{H}_2 are Hilbert spaces. Then the set of pairs (x, y) with $x \in \mathcal{H}_1, y \in \mathcal{H}_2$ is a Hilbert space with inner product

$$\langle (x_1, y_1), (x_2, y_2) \rangle := \langle x_1, x_2 \rangle_{\mathcal{H}_1} + \langle y_1, y_2 \rangle_{\mathcal{H}_2}$$

This space is called **the direct sum** of the spaces \mathcal{H}_1 and \mathcal{H}_2 and is denoted by $\mathcal{H}_1 \oplus \mathcal{H}_2$.

- **Definition (Orthogonal Complement)**

Let $\mathcal{M} \subseteq \mathcal{H}$ is a **closed** linear subspace of Hilbert space \mathcal{H} with induced inner product $\langle \cdot, \cdot \rangle$ (i.e. $\langle x, y \rangle_{\mathcal{M}} = \langle x, y \rangle_{\mathcal{H}}$ for all $x, y \in \mathcal{M}$). \mathcal{M} is also a Hilbert space.

We denote by \mathcal{M}^\perp the set of vectors in \mathcal{H} which are *orthogonal* to \mathcal{M} ; \mathcal{M}^\perp is called **the orthogonal complement of \mathcal{M}** . It follows from the linearity of the inner product that \mathcal{M}^\perp is a linear subspace of \mathcal{H} and an elementary argument shows that \mathcal{M}^\perp is *closed*. So \mathcal{M}^\perp is also a Hilbert space.

- **Remark** The following theorem is going to show that

$$\mathcal{H} = \mathcal{M} \oplus \mathcal{M}^\perp = \left\{ x + y : x \in \mathcal{M}, y \in \mathcal{M}^\perp, \text{ i.e. } \langle x, y \rangle = 0 \right\}.$$

This important geometric property is one of the main reasons that Hilbert spaces are **easier** to handle than Banach spaces.

- **Lemma 2.7** Let \mathcal{H} be a Hilbert space, \mathcal{M} a closed subspace of \mathcal{H} , and suppose $x \in \mathcal{H}$. Then there exists in \mathcal{M} a **unique** element z **closest** to x .

- **Theorem 2.8 (The Projection Theorem)**

Let \mathcal{H} be a Hilbert space, \mathcal{M} a closed subspace. Then every $x \in \mathcal{H}$ can be **uniquely** written $x = z + w$ where $z \in \mathcal{M}$ and $w \in \mathcal{M}^\perp$.

- **Remark** The projection theorem sets up a natural *isomorphism* $\mathcal{M} \oplus \mathcal{M}^\perp \rightarrow \mathcal{H}$ given by

$$(z, w) \mapsto z + w$$

We will often suppress the isomorphism and simply write $\mathcal{H} = \mathcal{M} \oplus \mathcal{M}^\perp$.

2.4 The Riesz Representation Theorem

- **Definition (*Bounded Linear Operator*)**

A **bounded linear transformation** (or **bounded operator**) is a mapping $T : (X, \|\cdot\|_X) \rightarrow (Y, \|\cdot\|_Y)$ from a normed linear space X to a normed linear space Y that satisfies

1. (**Linearity**) $T(\alpha x + \beta y) = \alpha T(x) + \beta T(y)$ for all $x, y \in X$, $\alpha, \beta \in \mathbb{R}$ or \mathbb{C}
2. (**Boundedness**) $\|Tx\|_Y \leq C \|x\|_X$ for small $C \geq 0$.

The smallest such C is called the norm of T , written $\|T\|$ or $\|T\|_{X,Y}$. Thus

$$\|T\| := \sup_{\|x\|_X=1} \|Tx\|_Y$$

- **Remark** Denote the space of **all bounded linear operator** between Hilbert space \mathcal{H}_1 and \mathcal{H}_2 as $\mathcal{L}(\mathcal{H}_1, \mathcal{H}_2)$. The space $\mathcal{L}(\mathcal{H}_1, \mathcal{H}_2)$ is linear space with norm

$$\|T\| := \sup_{\|x\|_{\mathcal{H}_1}=1} \|Tx\|_{\mathcal{H}_2}, \quad \forall T \in \mathcal{L}(\mathcal{H}_1, \mathcal{H}_2).$$

It can be shown that $\mathcal{L}(\mathcal{H}_1, \mathcal{H}_2)$ is a *complete normed space (i.e. a Banach space)*.

- **Definition (*Dual Space*)**

The space $\mathcal{L}(\mathcal{H}, \mathbb{C})$ is called the **dual space** of \mathcal{H} and is denoted by \mathcal{H}^* . The elements of \mathcal{H}^* are called **continuous linear functionals**. That is, the dual space \mathcal{H}^* is the space of *continuous linear functionals* on \mathcal{H} .

- **Remark** The *dual space* \mathcal{H}^* is also called **covector space** with respect to a vector space \mathcal{H} and the linear functionals are called **covectors**. This terms are mostly used in *differential geometry* when the vector space is *the tangent space*.
- **Theorem 2.9 (*The Riesz Representation Theorem*)** [Reed and Simon, 1980, Kreyszig, 1989, Conway, 2019]
For each $T \in \mathcal{H}^*$, there is a **unique** $y_T \in \mathcal{H}$ such that

$$T(x) = \langle x, y_T \rangle$$

for all $x \in \mathcal{H}$. In addition $\|y_T\|_{\mathcal{H}} = \|T\|_{\mathcal{H}^*}$.

Proof: Let $\mathcal{N} = \text{Ker}(T) = \{x \in \mathcal{H} : T(x) = 0\}$. By continuity of T , \mathcal{N} is a closed subspace of \mathcal{H} . If $\mathcal{H} = \mathcal{N}$, then $T(x) = 0$ for all x so for $y_T = 0$, $T(x) = \langle x, 0 \rangle$. If $\mathcal{N} \subset \mathcal{H}$, then there exists $x_0 \notin \mathcal{N}$. Define $y_T = \overline{T(x_0)} \frac{x_0}{\|x_0\|^2}$ so for all $x = \alpha x_0$ for any $\alpha \neq 0$

$$T(x) = T(\alpha x_0) = \alpha T(x_0) = \left\langle \alpha x_0, \overline{T(x_0)} \frac{x_0}{\|x_0\|^2} \right\rangle = \langle x, y_T \rangle.$$

Note that $\mathcal{H} = \text{span}\{x_0\} \oplus \mathcal{N}$ since for any $x \in \mathcal{H}$

$$x = \left(x - \frac{T(x)}{T(x_0)} x_0 \right) + \frac{T(x)}{T(x_0)} x_0 \in \mathcal{N} \oplus \text{span}\{x_0\}.$$

Also T and $\langle \cdot, y_T \rangle$ agree on both \mathcal{N} and $\text{span}\{x_0\}$, so they must agree on entire \mathcal{H} .

To prove $\|y_T\|_{\mathcal{H}} = \|T\|_{\mathcal{H}^*}$, we see that

$$\|T\|_{\mathcal{H}^*} = \sup_{\|x\| \leq 1} |Tx| = \sup_{\|x\| \leq 1} |\langle x, y_T \rangle| \leq \sup_{\|x\| \leq 1} \|x\| \|y_T\| = \|y_T\| ,$$

and

$$\|T\|_{\mathcal{H}^*} = \sup_{\|x\| \leq 1} |Tx| \geq \left| T \left(\frac{y_T}{\|y_T\|} \right) \right| = \|y_T\|^{-1} |\langle y_T, y_T \rangle| = \|y_T\| . \quad \blacksquare$$

- **Remark** *The Riesz Representation Theorem* [Conway, 2019, Kreyszig, 1989] is also called **The Riesz Lemma** [Reed and Simon, 1980].
- **Remark** We note that *the Cauchy-Schwarz inequality* shows that the **converse** of the *Riesz Representation Theorem* is **true**. Namely, each $y \in \mathcal{H}$ defines a *continuous linear functional* T_y on \mathcal{H}^* by

$$T_y(x) = \langle x, y \rangle .$$

Thus *the Riesz Representation Theorem* together with *the Cauchy-Schwarz inequality* defines an **isomorphism** $\mathcal{H}^* \rightarrow \mathcal{H}$ between a Hilbert space \mathcal{H} and its dual \mathcal{H}^* . In other words, unlike the case in Banach space, the bounded linear functional on Hilbert space has a simple form.

- **Corollary 2.10** (**The Riesz Representation for Sesquilinear Form**)

Let $B(\cdot, \cdot)$ be a function from $\mathcal{H} \times \mathcal{H}$ to \mathbb{C} which satisfies:

1. (**Linearity**) $B(\alpha x + \beta y, z) = \alpha B(x, z) + \beta B(y, z)$
2. (**Conjugate Linearity**) $B(x, \alpha y + \beta z) = \bar{\alpha} B(x, y) + \bar{\beta} B(x, z)$
3. (**Boundedness**) $|B(x, y)| \leq C \|x\|_{\mathcal{H}} \|y\|_{\mathcal{H}}$

for all $x, y, z \in \mathcal{H}$, $\alpha, \beta \in \mathbb{C}$. Then there is a **unique bounded linear transformation** $A : \mathcal{H} \rightarrow \mathcal{H}$ so that

$$B(x, y) = \langle x, Ay \rangle$$

for all $x, y \in \mathcal{H}$. The **norm** of A is the smallest constant C such that (3) holds.

Proof: Fix z , (1), (3) shows that $B(\cdot, z)$ is a continuous linear functional on \mathcal{H} . Thus by *the Riesz Representation theorem*, there exists some $y_{B,z} \in \mathcal{H}$,

$$B(x, z) = \langle x, y_{B,z} \rangle, \quad \forall x \in \mathcal{H}$$

Define $Az = y_{B,z}$. It is not difficult to show that A is a continuous linear operator with right property. \blacksquare

- **Remark** A bilinear function on \mathcal{H} obeying (1) and (2) is called a **sesquilinear form** (as a generalization of **blinear form** in complex vector space).

In terms of this, an inner product in complex vector space is a **complex Hermitian form** (also called a **symmetric sesquilinear form**).

2.5 Orthonormal Bases

- **Definition (*Complete Orthonormal Basis*)**

If S is an orthonormal set in a Hilbert space \mathcal{H} and no other orthonormal set contains S as a proper subset, then S is called an orthonormal basis (or a *complete orthonormal system*) for \mathcal{H} .

- **Theorem 2.11 (*Existence of Orthonormal Basis*)**

Every Hilbert space \mathcal{H} has an *orthonormal basis*.

- **Proposition 2.12 (*Orthogonal Representation of Element in Hilbert Space*)**

Let \mathcal{H} be a Hilbert space and $S = (x_\alpha)_{\alpha \in A}$ an *orthonormal basis*. Then for each $y \in \mathcal{H}$,

$$y = \sum_{\alpha \in A} \langle y, x_\alpha \rangle x_\alpha \quad (4)$$

and

$$\|y\|_{\mathcal{H}}^2 = \sum_{\alpha \in A} |\langle y, x_\alpha \rangle|^2 \quad (5)$$

The equality in (4) means that the sum on the right-hand side converges (independent of order) to y in \mathcal{H} . **Conversely**, if $\sum_{\alpha \in A} |c_\alpha|^2 < \infty$, $c_\alpha \in \mathbb{C}$, then $\sum_{\alpha \in A} c_\alpha x_\alpha$ converges to an element of \mathcal{H} .

- **Remark** From Bessel's inequality, we already seen that for any finite collection A' of x_α , we have $\sum_{\alpha \in A'} |\langle y, x_\alpha \rangle|^2 \leq \|y\|_{\mathcal{H}}^2$. The main difficulty is on how to prove convergence of $\sum_{n=1}^N |\langle y, x_n \rangle|^2$ as $N \rightarrow \infty$. Similarly we need to prove that $y - \sum_{n=1}^m \langle y, x_{\alpha_n} \rangle x_{\alpha_n}$ is still orthogonal to x_α as $m \rightarrow \infty$.

- **Remark** The unique coefficients $(\langle y, x_\alpha \rangle)$ is called *the Fourier coefficients of y with respect to basis (x_α)* .

- **Remark (*Gram-Schmidt Orthogonalization*)**

Given any set of independent vectors (v_1, v_2, \dots) . we can construct an orthonormal basis (b_1, b_2, \dots) via

$$b_1 = \frac{v_1}{\|v_1\|}$$

$$b_j = \frac{v_j - \sum_{i=1}^{j-1} \langle v_j, b_i \rangle b_i}{\left\| v_j - \sum_{i=1}^{j-1} \langle v_j, b_i \rangle b_i \right\|}, \quad j \geq 2$$

Thus $\text{span}\{v_1, \dots, v_m\} = \text{span}\{b_1, \dots, b_m\}$ for all $m \geq 1$.

2.6 Separability

- **Definition (*Separability*)**

A metric space which has a countable dense subset is said to be separable.

- **Remark** Most Hilbert space we have seen is separable.

- **Proposition 2.13** (*Canonical Hilbert Space*)

A Hilbert space \mathcal{H} is **separable** if and only if it has a **countable orthonormal basis** S . If there are $N < \infty$ elements in S , then \mathcal{H} is **isomorphic** to \mathbb{C}^N , If there are **countably many** elements in S , then \mathcal{H} is **isomorphic** to ℓ^2 .

- **Remark** Consider the map $v \mapsto (\langle v, x_n \rangle)_{n=1}^{\infty}$ for orthonormal basis $(x_n)_{n=1}^{\infty}$ as the isomorphism $\mathcal{H} \rightarrow \ell^2$.
- **Remark** Notice that in the separable case, the Gram-Schmidt process allows us to construct an orthonormal basis without using Zorn's lemma.

2.7 Fourier Series

- **Definition** If $f(x)$ is integrable in $[0, 2\pi]$, define **the Fourier series** as

$$F(x) := \frac{1}{\sqrt{2\pi}} \sum_{n=-\infty}^{\infty} c_n e^{inx}$$

where $c_n = \frac{1}{\sqrt{2\pi}} \int_0^{2\pi} e^{-inx} f(x) dx$.

- **Proposition 2.14** Suppose that $f(x)$ is periodic of period 2π and is continuously differentiable. Then the functions $\sum_{n=-M}^M c_n e^{inx}$ converge uniformly to $f(x)$ as $M \rightarrow \infty$.
- **Proposition 2.15** If $f \in \mathcal{L}^2[0, 2\pi]$, then $\sum_{n=-M}^M c_n e^{inx}$ converges to f in the \mathcal{L}^2 norm as $M \rightarrow \infty$.
- **Remark** The collection of functions, $(\frac{1}{\sqrt{2\pi}} e^{inx})_{n=-\infty}^{\infty}$ is an **orthonormal set** in $\mathcal{L}^2[0, 2\pi]$. The above proposition states that it is a **complete orthonormal set**, that is, for every $f \in \mathcal{L}^2[0, 2\pi]$

$$f = \lim_{M \rightarrow \infty} \frac{1}{\sqrt{2\pi}} \sum_{n=-M}^M c_n e^{inx}$$

2.8 Legendre, Hermite and Laguerre Polynomials

2.9 Hilbert-Adjoint Operator

- **Definition** (*Hilbert Space Adjoint*)

Let $T : \mathcal{H}_1 \rightarrow \mathcal{H}_2$ be a bounded linear operator, where \mathcal{H}_1 and \mathcal{H}_2 are Hilbert spaces. Then **the Hilbert-adjoint operator** T^* of T is the operator

$$T^* : \mathcal{H}_2 \rightarrow \mathcal{H}_1$$

such that for all $x \in \mathcal{H}_1$ and $y \in \mathcal{H}_2$,

$$\langle Tx, y \rangle_{\mathcal{H}_2} = \langle x, T^*y \rangle_{\mathcal{H}_1} \tag{6}$$

- **Proposition 2.16 (Existence of Adjoint Operator)** [Kreyszig, 1989]
The Hilbert-adjoint operator T^* of T exists, is unique and is a **bounded linear operator** with norm

$$\|T^*\| = \|T\|.$$

- **Lemma 2.17 (Zero operator).** [Kreyszig, 1989] Let X and Y be inner product spaces and $Q : X \rightarrow Y$ a bounded linear operator. Then:

1. $Q = 0$ if and only if $\langle Qx, y \rangle = 0$ for all $x \in X$ and $y \in Y$.
2. If $Q : X \rightarrow X$, where X is complex, and $\langle Qx, x \rangle = 0$ for all $x \in X$, then $Q = 0$.

- **Proposition 2.18 (Properties of Hilbert-adjoint operators).** [Reed and Simon, 1980, Kreyszig, 1989]
Let $\mathcal{H}_1, \mathcal{H}_2$ be Hilbert spaces, $S : \mathcal{H}_1 \rightarrow \mathcal{H}_2$ and $T : \mathcal{H}_1 \rightarrow \mathcal{H}_2$ bounded linear operators and α any scalar. Then we have

1. $\langle T^*y, x \rangle = \langle y, Tx \rangle, (x \in \mathcal{H}_1, y \in \mathcal{H}_2)$
2. $(S + T)^* = S^* + T^*$
3. $(\alpha T)^* = \alpha T^*$
4. $(T^*)^* = T$
5. $\|T^*T\| = \|TT^*\| = \|T\|^2$
6. $T^*T = 0 \Leftrightarrow T = 0$
7. $(ST)^* = T^*S^*$ (assuming $\mathcal{H}_2 = \mathcal{H}_1$)
8. If T has a **bounded inverse**, T^{-1} , then T^* has a **bounded inverse** and $(T^*)^{-1} = (T^{-1})^*$.

2.10 Self-Adjoint, Unitary and Normal Operators

- **Definition** A **bounded linear operator** $T : \mathcal{H} \rightarrow \mathcal{H}$ on a Hilbert space \mathcal{H} is said to be

1. self-adjoint or Hermitian if

$$T^* = T \quad \Leftrightarrow \quad \langle Tx, y \rangle = \langle x, Ty \rangle$$

2. unitary if T is bijective and

$$T^* = T^{-1}$$

3. normal if

$$T^*T = TT^*$$

- **Definition (Projection Operator)**

If $P \in \mathcal{L}(\mathcal{H})$ and $P^2 = P$, then P is called a projection. If in addition $P = P^*$, then P is called an orthogonal projection.

- **Remark** If T is **self-adjoint** and **unitary**, then T is **normal**.
- **Remark** If a basis for \mathbb{C}^n is given and a **linear operator** on \mathbb{C}^n is represented by a certain **matrix**, then its **Hilbert-adjoint operator** is represented by the **complex conjugate transpose** of that matrix. For \mathbb{R}^n , then the **Hilbert-adjoint operator** is represented by the **transpose** of that matrix
- **Remark** Similarly we have

1. The matrix representation for **self-adjoint operator** is **Hermitian** or **Symmetric**.

$$T^* = T \quad \Leftrightarrow \quad \mathbf{T}^H = \mathbf{T} \quad (\text{or for real vector space } \mathbf{T}^T = \mathbf{T})$$

2. The matrix representation for **unitary operator** is **unitary** or **orthogonal**.

$$T^* = T^{-1} \quad \Leftrightarrow \quad \mathbf{T}^H = \mathbf{T}^{-1} \quad (\text{or for real vector space } \mathbf{T}^T = \mathbf{T}^{-1})$$

3. The matrix representation for **normal operator** is **normal**.

$$T^*T = TT^* \quad \Leftrightarrow \quad \mathbf{T}^H\mathbf{T} = \mathbf{T}\mathbf{T}^H \quad (\text{or for real vector space } \mathbf{T}^T\mathbf{T} = \mathbf{T}\mathbf{T}^T)$$

- **Proposition 2.19 (Self-adjointness).** [Kreyszig, 1989]

Let $T : \mathcal{H} \rightarrow \mathcal{H}$ be a bounded linear operator on a Hilbert space \mathcal{H} . Then:

1. If T is **self-adjoint**, $\langle Tx, x \rangle$ is **real** for all $x \in \mathcal{H}$.
2. If \mathcal{H} is complex and $\langle Tx, x \rangle$ is **real** for all $x \in \mathcal{H}$, the operator T is **self-adjoint**

- **Proposition 2.20 (Self-adjointness of product).** [Kreyszig, 1989]

The product of two bounded **self-adjoint** linear operators S and T on a Hilbert space \mathcal{H} is **self-adjoint** if and only if the operators **commute**,

$$ST = TS.$$

- **Proposition 2.21 (Sequences of self-adjoint operators).** [Kreyszig, 1989]

Let (T_n) be a sequence of **bounded self-adjoint** linear operators $T_n : \mathcal{H} \rightarrow \mathcal{H}$ on a Hilbert space \mathcal{H} . Suppose that (T_n) converges, say,

$$T_n \rightarrow T, \quad \text{i.e. } \|T_n - T\| \rightarrow 0$$

where $\|\cdot\|$ is the norm on the space $\mathcal{L}(\mathcal{H}, \mathcal{H})$. Then the limit operator T is a **bounded self-adjoint** linear operator on \mathcal{H} .

- **Proposition 2.22 (Unitary operator).** [Kreyszig, 1989]

Let the operators $U : \mathcal{H} \rightarrow \mathcal{H}$ and $V : \mathcal{H} \rightarrow \mathcal{H}$ be **unitary**; here, \mathcal{H} is a Hilbert space. Then:

1. U is **isometric**; thus $\|Ux\| = \|x\|$ for all $x \in \mathcal{H}$;
2. $\|U\| = 1$, provided $\mathcal{H} \neq \{0\}$,
3. $U^{-1} = U^*$ is **unitary**,
4. UV is **unitary**,

5. U is normal.

6. A bounded linear operator T on a complex Hilbert space \mathcal{H} is **unitary** if and only if T is **isometric** and **surjective**.

- **Remark** Note that an **isometric operator** need not be *unitary* since it may fail to be **surjective**. An example is the *right shift operator* $T : \ell^2 \rightarrow \ell^2$ given by

$$(\xi_1, \xi_2, \xi_3, \dots) \mapsto (0, \xi_1, \xi_2, \xi_3, \dots).$$

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