Lecture 6: Concentration via Optimal Transport

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1 Optimal Transport Basis

1.1 Optimal Transport Problem and its Dual Problem

• **Definition** (*Pushforward Measure*) [Peyr and Cuturi, 2019] Let $(\mathcal{X}, \mathcal{B}_X)$ and $(\mathcal{Y}, \mathcal{B}_Y)$ be two topological measurable spaces. Denote the spaces of *general* (*Radon*) measures on \mathcal{X}, \mathcal{Y} as $\mathcal{M}(\mathcal{X})$ and $\mathcal{M}(\mathcal{Y})$. Also let $\mathcal{C}(\mathcal{X})$ be space of continuous functions on \mathcal{X} . For a *continuous* map $T: \mathcal{X} \to \mathcal{Y}$, the <u>push-forward operator</u> is defined as $T_{\#}: \mathcal{M}(\mathcal{X}) \to \mathcal{M}(\mathcal{Y})$ that satisfies

$$\forall h \in \mathcal{C}(\mathcal{X}), \quad \int_{\mathcal{Y}} h(y) \ d(T_{\#}\alpha) (y) = \int_{\mathcal{X}} h(T(x)) \ d\alpha(x). \tag{1}$$

or equivalently,
$$(T_{\#}\alpha)(B) := \alpha(\{x : T(x) \in B \subset \mathcal{Y}\}) = \alpha(T^{-1}(B))$$
 (2)

where the **push-forward measure** $\beta := T_{\#}\alpha \in \mathcal{M}(\mathcal{Y})$ of some $\alpha \in \mathcal{M}(\mathcal{X})$, $T^{-1}(\cdot)$ is the pre-image of T.

• Remark (Density Function of Pushforward Measure)
Assume that (α, β) have densities $(\rho_{\alpha}, \rho_{\beta})$ with respect to a fixed measure, and $\beta = T_{\#}\alpha$. We see that $T_{\#}$ acts on a density ρ_{α} linearly to a density ρ_{β} as a change of variable, i.e.

$$\rho_{\alpha}(\boldsymbol{x}) = \left| \det(T'(\boldsymbol{x})) \right| \rho_{\beta}(T(\boldsymbol{x}))$$

$$\left| \det(T'(\boldsymbol{x})) \right| = \frac{\rho_{\alpha}(\boldsymbol{x})}{\rho_{\beta}(T(\boldsymbol{x}))}$$
(3)

• Definition (Optimal Transport Problem, Monge Problem) [Villani, 2009, Santambrogio, 2015, Peyr and Cuturi, 2019]

Let $(\mathcal{X}, \mathcal{B}_X)$ and $(\mathcal{Y}, \mathcal{B}_Y)$ be two measurable spaces, where \mathcal{X} and \mathcal{Y} are complete separable metric spaces. Denote $\mathcal{P}(\mathcal{X})$ and $\mathcal{P}(\mathcal{Y})$ as the space of probability measures on \mathcal{X} and \mathcal{Y} . Define a cost function $c: \mathcal{X} \times \mathcal{Y} \to \mathbb{R}_+$ as non-negative real-valued measurable functions on $\mathcal{X} \times \mathcal{Y}$. The optimal transport problem by Monge (i.e. Monge Problem) is defined as follows: given two probability measures $\mathbb{P} \in \mathcal{P}(\mathcal{X})$ and $\mathbb{Q} \in \mathcal{P}(\mathcal{Y})$, find a continuous measurable map $T: \mathcal{X} \to \mathcal{Y}$ so that

$$\inf_{T} \int_{\mathcal{X}} c(x, T(x)) d\mathbb{P}(x)$$

s.t. $\mathbb{Q} = T_{\#}\mathbb{P}$

The optimal solution T is also called an **optimal transportation plan**.

• Definition (Optimal Transport Problem, Kantorovich Relaxation) [Villani, 2009, Santambrogio, 2015, Peyr and Cuturi, 2019]

The optimal transport problem by Kantorovich (i.e. Kantorovich Relxation) is de-

The optimal transport problem by Kantorovich (i.e. <u>Kantorovich Relxation</u>) is defined as follows: given two probability measures $\mathbb{P} \in \mathcal{P}(\mathcal{X})$ and $\mathbb{Q} \in \mathcal{P}(\mathcal{Y})$, find a *joint probability measure* $\gamma \in \Pi(\mathbb{P}, \mathbb{Q})$ so that

$$\begin{split} &\inf_{\gamma} \int_{\mathcal{X} \times \mathcal{Y}} c(x,y) d\gamma(x,y) \\ \text{s.t. } &\gamma \in \Pi(\mathbb{P},\mathbb{Q}) := \{ \gamma \in \mathcal{P}(\mathcal{X} \times \mathcal{Y}) : \pi_{\mathcal{X},\#} \gamma = \mathbb{P}, \ \pi_{\mathcal{Y},\#} \gamma = \mathbb{Q} \} \end{split}$$

where $\mathcal{P}(\mathcal{X} \times \mathcal{Y})$ is the space of joint probability measure on $\mathcal{X} \times \mathcal{Y}$, $\pi_{\mathcal{X}}$ and $\pi_{\mathcal{Y}}$ are the coordinate projection onto \mathcal{X} and \mathcal{Y} . $\pi_{\mathcal{X},\#}\gamma = \mathbb{P}$ means that \mathbb{P} is the marginal distribution of γ on \mathcal{X} . Similarly \mathbb{Q} is the marginal distribution of γ on \mathcal{Y} .

Equivalently, let X and Y are random variables taking values in \mathcal{X} and \mathcal{Y} . The joint distribution of (X,Y) is γ with marginal distribution of X and Y being \mathbb{P} and \mathbb{Q} . Then the problem is

$$\min_{\gamma \in \Pi(\mathbb{P}, \mathbb{Q})} \mathbb{E}_{\gamma} \left[c(X, Y) \right]$$

The joint distribution $\gamma \in \Pi(\mathbb{P}, \mathbb{Q})$ such that $X_{\#}\gamma = \mathbb{P}$ and $Y_{\#}\gamma = \mathbb{Q}$ is called **a coupling**.

- Proposition 1.1 (Existance of Solution) [Santambrogio, 2015] Let \mathcal{X}, \mathcal{Y} be complete separable spaces, $\mathbb{P} \in \mathcal{P}(\mathcal{X})$, $\mathbb{Q} \in \mathcal{P}(\mathcal{Y})$ and $c : \mathcal{X} \times \mathcal{Y} \to \mathbb{R}_+$ be lower semi-continuous function. Then the Kantorovich relaxation of optimal transport problem admits a solution.
- **Definition** (*Dual Problem of Kantorovich Problem*) [Villani, 2009, Santambrogio, 2015, Peyr and Cuturi, 2019]

The **dual problem** of Kantorovich problem is described as below:

$$\mathcal{L}_{c}(\mathbb{P}, \mathbb{Q}) = \max_{(\varphi, \psi) \in \mathcal{C}(\mathcal{X}) \times \mathcal{C}(\mathcal{Y})} \int_{\mathcal{X}} \varphi(x) d\mathbb{P}(x) + \int_{\mathcal{Y}} \psi(y) d\mathbb{Q}(y)$$
s.t. $\varphi(x) + \psi(y) \leq c(x, y), \quad \forall x \in \mathcal{X}, y \in \mathcal{Y},$

Here, (φ, ψ) is a pair of *continuous functions* on \mathcal{X} and \mathcal{Y} respectively and they are also the **Kantorovich potentials**. The feasible region is

$$\mathcal{R}(c) := \{ (\varphi, \psi) \in \mathcal{C}(\mathcal{X}) \times \mathcal{C}(\mathcal{Y}) : \varphi \oplus \psi \leq c \}$$

where $(\varphi \oplus \psi)(x,y) = \varphi(x) + \psi(y)$.

In other words, the dual optimization problem is

$$\max_{(\varphi,\psi)\in\mathcal{R}(c)} \mathbb{E}_{\mathbb{P}}\left[\varphi(X)\right] + \mathbb{E}_{\mathbb{Q}}\left[\psi(Y)\right]$$

• Proposition 1.2 (Strong Duality) [Santambrogio, 2015] Let \mathcal{X}, \mathcal{Y} be complete separable spaces, and $c: \mathcal{X} \times \mathcal{Y} \to \mathbb{R}_+$ be lower semi-continuous and bounded from below. Then the optimal value of primal and dual problems are the same

$$\min_{X \sim \mathbb{P}, Y \sim \mathbb{Q}} \mathbb{E}\left[c(X, Y)\right] = \mathcal{L}_c(\mathbb{P}, \mathbb{Q}) = \max_{(\varphi, \psi) \in \mathcal{R}(c)} \mathbb{E}_{\mathbb{P}}\left[\varphi(X)\right] + \mathbb{E}_{\mathbb{Q}}\left[\psi(Y)\right].$$

1.2 Wasserstein Distance

• Definition (Wasserstein Distance)

Let $((\mathcal{X}, d), \mathcal{B})$ be a metric measurable space with Borel σ -algebra induced by metric d. Let X, Y be two random variables taking values in \mathcal{X} with distribution \mathbb{P} and \mathbb{Q} . **The Wasserstein distance** between probability distributions \mathbb{P} and \mathbb{Q} induced by d is defined as

$$W_1(\mathbb{P}, \mathbb{Q}) \equiv W_d(\mathbb{P}, \mathbb{Q}) := \min_{X \sim \mathbb{P}, Y \sim \mathbb{Q}} \mathbb{E}\left[d(X, Y)\right]$$
(4)

In general, for $p \in [1, \infty)$, we can define **Wasserstein** p-distance as

$$\mathcal{W}_p(\mathbb{P}, \mathbb{Q}) \equiv \mathcal{W}_{p,d}(\mathbb{P}, \mathbb{Q}) := \left(\min_{X \sim \mathbb{P}, Y \sim \mathbb{Q}} \mathbb{E} \left[(d(X, Y))^p \right] \right)^{1/p}. \tag{5}$$

• Remark Not to confuse the 2-Wasserstein distance with the Wasserstein distance induced by L₂ norm:

$$\begin{split} \mathcal{W}_{\|\cdot\|_2}(\mathbb{P},\mathbb{Q}) &\equiv \mathcal{W}_{1,\|\cdot\|_2}(\mathbb{P},\mathbb{Q}) := \min_{X \sim \mathbb{P},Y \sim \mathbb{Q}} \mathbb{E}\left[\|X - Y\|_2\right] \\ \mathcal{W}_2(\mathbb{P},\mathbb{Q}) &\equiv \mathcal{W}_{2,d}(\mathbb{P},\mathbb{Q}) := \sqrt{\min_{X \sim \mathbb{P},Y \sim \mathbb{Q}} \mathbb{E}\left[d(X,Y)^2\right]} \end{split}$$

- Remark (Wasserstein p-Distance is a Metric in $\mathcal{P}(\mathcal{X})$)

 The Wasserstein p-distance $\mathcal{W}_{p,d}(\mathbb{P},\mathbb{Q}) := (\min_{X \sim \mathbb{P}, Y \sim \mathbb{Q}} \mathbb{E} [(d(X,Y))^p])^{1/p}$ is a well-defined metric in $\mathcal{P}(\mathcal{X})$: for all $\mathbb{P}, \mathbb{Q}, \mathbb{M} \in \mathcal{P}(\mathcal{X})$,
 - 1. (Non-Negativity): $W_{p,d}(\mathbb{P},\mathbb{Q}) \geq 0$.
 - 2. (Definiteness): $W_{p,d}(\mathbb{P},\mathbb{Q}) = 0$ iff $\mathbb{P} = \mathbb{Q}$
 - 3. (Symmetric): $\mathcal{W}_{n,d}(\mathbb{P},\mathbb{Q}) = \mathcal{W}_{n,d}(\mathbb{Q},\mathbb{P})$
 - 4. (Triangular inequality): $W_{p,d}(\mathbb{P},\mathbb{Q}) \leq W_{p,d}(\mathbb{P},\mathbb{M}) + W_{p,d}(\mathbb{M},\mathbb{Q})$
- Remark The Wasserstein distance, or Optimal Transport (OT), $W_d(\alpha, \beta)$ depends on the distance definition d on the base measurable space \mathcal{X} . In other word, OT can be seen as automatically "lifting" a ground metric d in \mathcal{X} to a metric between measures on \mathcal{X}
- Remark ($Convergence\ in\ Wasserstein\ Space \Leftrightarrow Weak\ Convergence$) [Villani, 2009, Santambrogio, 2015, Peyr and Cuturi, 2019]

One of most *important* properly of *Wasserstein distance* is that it is a *weak distance*, i.e. it allows one to compare singular distributions (for instance, discrete ones) whose **supports** *do not overlap* and to quantify the spatial shift between the supports of two distributions.

In fact, W_p is a way to quantify the <u>weak* convergence</u> or convergence in distribution (in law) [Villani, 2009]:

Definition On a compact domain \mathcal{X} , $(\alpha_k)_k$ converges **weakly** to α in $\mathcal{M}^1_+(\mathcal{X})$ (denoted $\alpha_n \stackrel{d}{\to} \alpha$) if and only if for any **continuous** function $g \in \mathcal{C}(\mathcal{X})$, $\int_{\mathcal{X}} g d\alpha_k \to \int_{\mathcal{X}} g d\alpha$. One needs to add additional decay conditions on g on noncompact domains.

This notion of weak convergence corresponds to the **convergence in the distribution** of random vectors. Note the any random variable X_n is a continous function on Ω , and its distribution is the push-forward measure $\alpha_n = X_{n\#}\mathbb{P}$. Therefore, $\alpha_n \rightharpoonup \alpha$ is equivalent to $X_n \stackrel{d}{\to} X$. This convergence can be shown (see [Villani, 2009, Santambrogio, 2015]) to be equivalent to

$$\alpha_n \rightharpoonup \alpha \Leftrightarrow \mathcal{W}_p(\alpha_n, \alpha) \to 0.$$

Thus we can also write the weak convergance as $\alpha_n \xrightarrow{\mathcal{W}_d} \alpha$.

1.3 Dual Formulation of Wasserstein Distance

Theorem 1.3 (Kantorovich-Rubenstein Duality) [Villani, 2009]
 Let X be a Polish space, i.e. X a complete separable metric space equipped with a Borel σ-algebra induced by metric d, and P and Q be probability measures on X. For fixed p ∈ [1,∞), let Lip₁ be the space of all 1-Lipschitz function with respect to metric d such that

$$||f||_L := \sup_{x,y \in \mathcal{X}} \left\{ \frac{|f(x) - f(y)|}{d(x,y)} \right\} \le 1.$$

Then

$$\mathcal{W}_d(\mathbb{P}, \mathbb{Q}) \equiv \mathcal{W}_{1,d}(\mathbb{P}, \mathbb{Q}) = \sup_{f \in Lip_1} \left\{ \mathbb{E}_{\mathbb{P}} \left[f(X) \right] - \mathbb{E}_{\mathbb{Q}} \left[f(Y) \right] \right\}. \tag{6}$$

- **Remark** This theorem only applies for Wasserstein 1-distance, i.e. p = 1.
- Example (Total Variation as W_d with respect to Hamming distance d_H) When $d(x,y) = \sum_i \mathbb{1} \{x_i \neq y_i\} = d_H(x,y)$ Hamming distance, the W_d becomes

$$\mathcal{W}_{d_H}(\mathbb{P}, \mathbb{Q}) = \sup_{f: \mathcal{X} \to [0,1]} \int_{\mathcal{X}} f\left(d\mathbb{P} - d\mathbb{Q}\right) = \sup_{A \subset \mathcal{X}} |\mathbb{P}(A) - \mathbb{Q}(A)| := \|\mathbb{P} - \mathbb{Q}\|_{TV}$$

• Example $(W_1 \text{ in } 1\text{-}dimensional space }\mathbb{R})$ When d(x,y) = |x-y| in \mathbb{R} , and F_{α}, F_{β} are cumulative distribution function of α, β , then W_1 distance becomes

$$\mathcal{W}_{1}(\alpha, \beta) = \|F_{\alpha} - F_{\beta}\|_{1} := \int_{-\infty}^{\infty} \|F_{\alpha}(x) - F_{\beta}(x)\|_{1} dx$$
$$= \int_{-\infty}^{\infty} \left| \int_{-\infty}^{x} d(\alpha - \beta) \right|$$

which shows that W_1 on \mathbb{R} is a **norm**. An optimal Monge map T such that $T_{\#}\alpha = \beta$ is then defined by

$$T = F_{\beta}^{-1} \circ F_{\alpha}$$

where $F_{\beta}^{-1} = \inf\{t : F_{\beta} \ge t\}.$

2 The Transportation Method

2.1 Concentration via Transportation Cost Inequality

• Remark (*Equivalence of Transportation Cost Inequality and Sub-Gaussian*) [Boucheron et al., 2013] Let X be a real-valued integrable random variable. Let ϕ be a *convex* and *continuously differentiable* function on a (possibly unbounded) interval [0,b) and assume that $\phi(0) = \phi'(0) = 0$. Define, for every $x \ge 0$, the *Legendre transform* $\phi^*(x) = \sup_{\lambda \in (0,b)} (\lambda x - \phi(\lambda))$, and let, for every $t \ge 0$, $\phi^{*-1}(t) = \inf\{x \ge 0 : \phi^*(x) > t\}$, i.e. the *the generalized inverse* of ϕ^* . Then the following two statements are equivalent: 1. for every $\lambda \in (0, b)$,

$$\psi_{X-\mathbb{E}[X]}(\lambda) \le \phi(\lambda)$$

where $\psi_X(\lambda) := \log \mathbb{E}_Q \left[e^{\lambda X} \right]$ is the logarithm of moment generating function;

2. for any probability measure P absolutely continuous with respect to Q such that $\mathbb{KL}(P \parallel Q) < \infty$,

$$\mathbb{E}_{P}[X] - \mathbb{E}_{Q}[X] \le \phi^{*-1}(\mathbb{KL}(P \parallel Q)). \tag{7}$$

In particular, given $\nu > 0$, X follows a **sub-Gaussian distribution**, i.e.

$$\psi_{X-\mathbb{E}[X]}(\lambda) \le \frac{\nu\lambda^2}{2}$$

for every $\lambda > 0$ if and only if for any probability measure P absolutely continuous with respect to Q and such that $\mathbb{KL}(P \parallel Q) < \infty$,

$$\mathbb{E}_{P}[X] - \mathbb{E}_{Q}[X] \le \sqrt{2\nu \mathbb{KL}(P \parallel Q)}. \tag{8}$$

Definition (d-Transportation Cost Inequality) [Wainwright, 2019]
Let (X, d) be a metric space with metric d, and (X, B) be a measurable space, where B is the Borel σ-algebra induced by metric d, the probability measure P is said to satisfy a d-transportation cost inequality with parameter ν > 0 if

$$\mathbb{E}_{\mathbb{Q}}[X] - \mathbb{E}_{\mathbb{P}}[X] \le \sqrt{2\nu \mathbb{KL}(\mathbb{Q} \parallel \mathbb{P})}$$
(9)

for all probability measure $\mathbb{Q} \ll \mathbb{P}$ on \mathscr{B} .

• Theorem 2.1 (Isoperimetric Inequality via Transportation Cost)[Wainwright, 2019] Consider a metric measure space $(\mathcal{X}, \mathcal{B}, \mathbb{P})$ with metric d, and suppose that \mathbb{P} satisfies the d-transportation cost inequality

$$\mathbb{E}_{\mathbb{O}}\left[X\right] - \mathbb{E}_{\mathbb{P}}\left[X\right] \le \sqrt{2\nu\mathbb{KL}\left(\mathbb{Q} \parallel \mathbb{P}\right)}$$

for all probability measure $\mathbb{Q} \ll \mathbb{P}$ on \mathcal{B} . Then its **concentration function** satisfies the bound

$$\alpha_{\mathbb{P},(\mathcal{X},d)}(t) \le 2 \exp\left(-\frac{t^2}{2\nu}\right)$$
 (10)

Moreover, for any $Z \sim \mathbb{P}$ and any L-Lipschitz function $f : \mathcal{X} \to \mathbb{R}$, we have the **concentration inequality**

$$\mathbb{P}\left\{|f(Z) - \mathbb{E}\left[f(Z)\right]| \ge t\right\} \le 2\exp\left(-\frac{t^2}{2\nu L^2}\right). \tag{11}$$

- 2.2 Tensorization for Transportation Cost
- 2.3 Bounded Difference Inequality via Transportation Methods
- 2.4 Conditional Transportation Inequality
- 2.5 Convex Distance Inequality via Conditional Transportation Cost
- 2.6 Talagrand's Gaussian Transportation Inequality
- 2.7 Transportation Cost Inequalities for Markov Chains

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