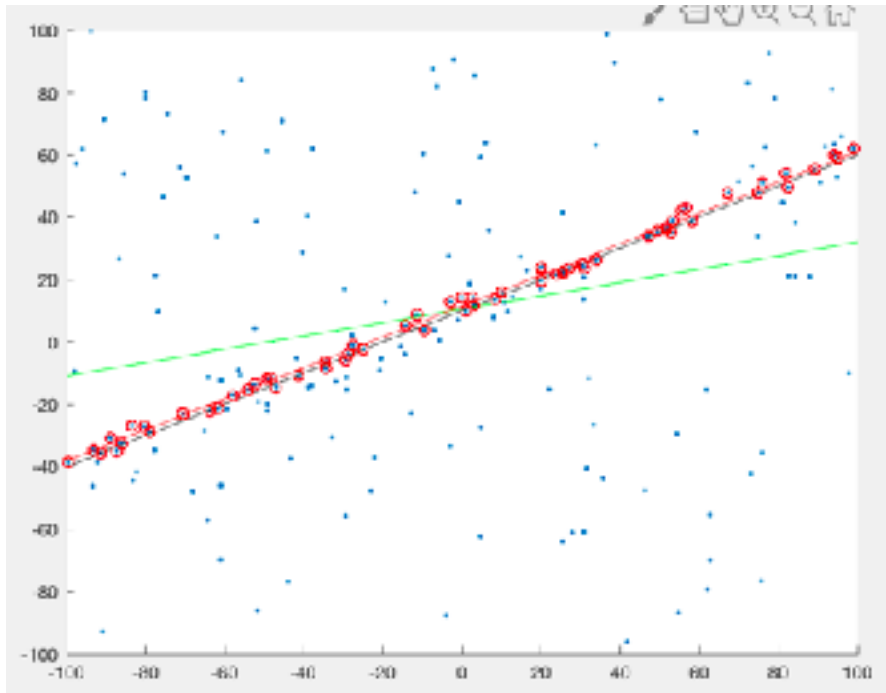


4.1 Line fitting with RANSAC



```
err_real =  
38.1617
```

```
err_ls =  
171.3517
```

```
err_ransac =  
41.3292
```

Figure 1: Line fitting with RANSAC

4.2 Fundamental Matrix

$F_h =$

```
-0.0200  -2.2000   0.0006  
 0.0200   2.2000  -0.0043  
-0.0202   2.2039  -0.0731
```

$F =$

```
 0.0200  -2.2000   0.0004  
 0.0200   2.2000  -0.0043  
-0.0204   2.2039   0.0079
```



Figure 2: Epipolar Line without singularity constraint



Figure 3: Epipolar line with singularity constraint

4.3 Essential Matrix

$E_h =$

-0.0035	-1.3563	0.0133
1.6488	0.1861	-4.2594
-0.0765	4.3620	0.1839

$\gg E$

$E =$

0.5268	-1.3309	0.2996
1.6925	0.4359	-4.3457
0.1826	4.2691	0.0289



Figure 4: Epipolar Lines with fundamental matrix computed from essential matrix

4.4 Camera Matrix

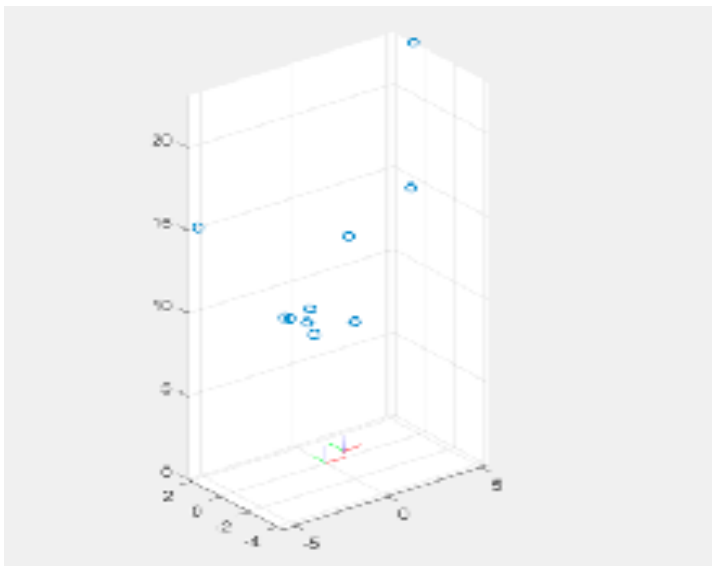


Figure 5: P' with chosen R and t , and corresponding 3D points

4.5 Feature extraction and matching

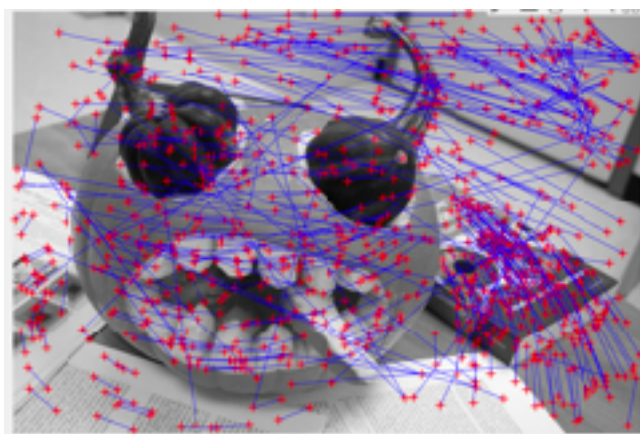


Figure 6: Feature match shown in the same image

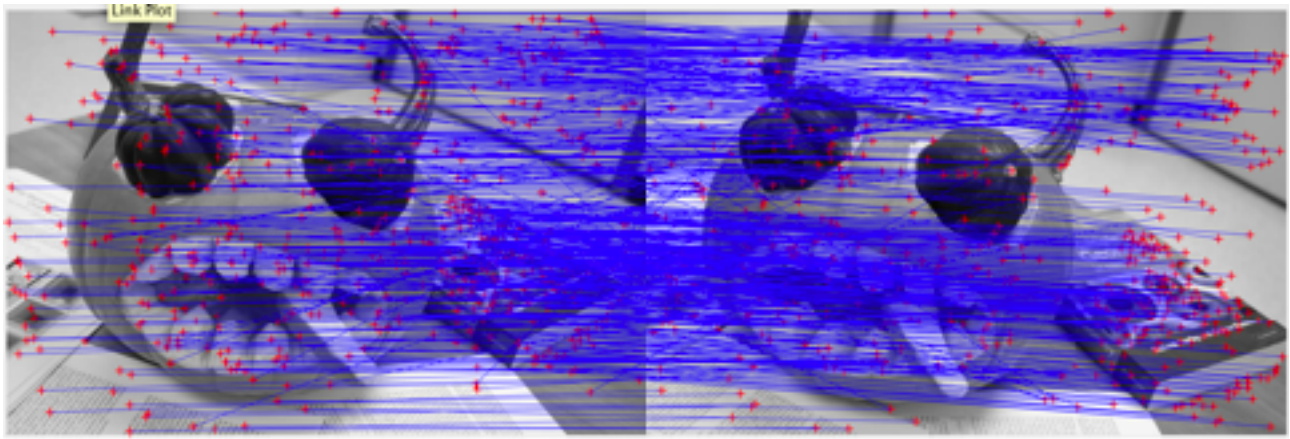


Figure 7: Feature match between two images

4.6 8-point RANSAC

4.6.1 Regular RANSAC

- Threshold = 5:

$F =$

-0.0000	-0.0000	0.0007
-0.0000	-0.0000	0.0061
0.0011	0.0051	-3.7245

Total number of points: 19

Number of inliers: 10

Number of outliers: 9

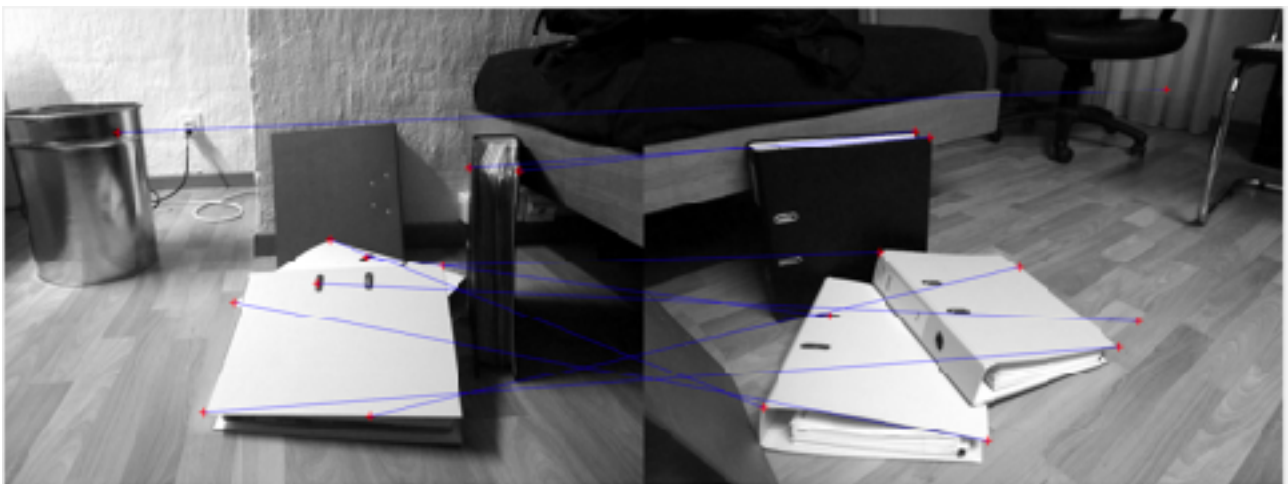


Figure 8: Inliers, threshold = 5

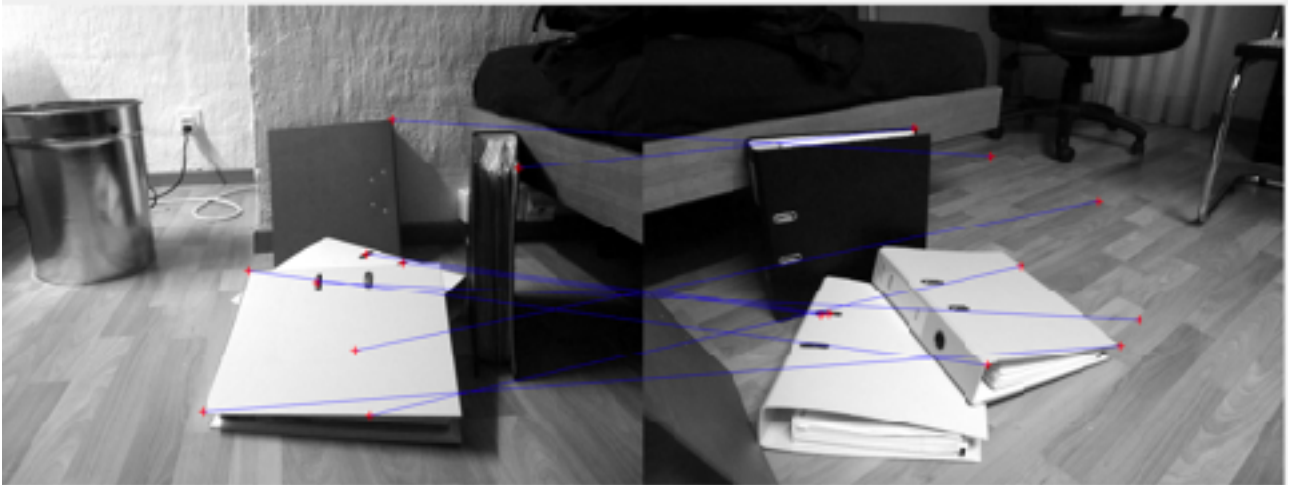


Figure 9: Outliers, threshold = 5

- Threshold = 2

F =

0.0000	0.0000	-0.0088
0.0000	-0.0000	-0.0050
-0.0069	-0.0074	14.4873

Total number of points: 19

Number of inliers: 9

Number of outliers: 10

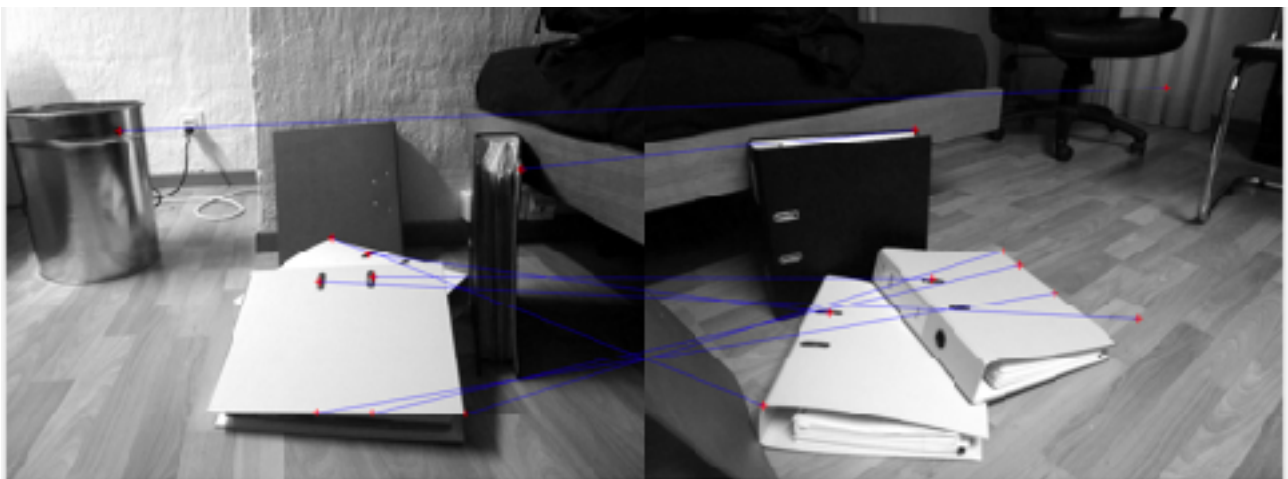


Figure 10: inliers, threshold = 2

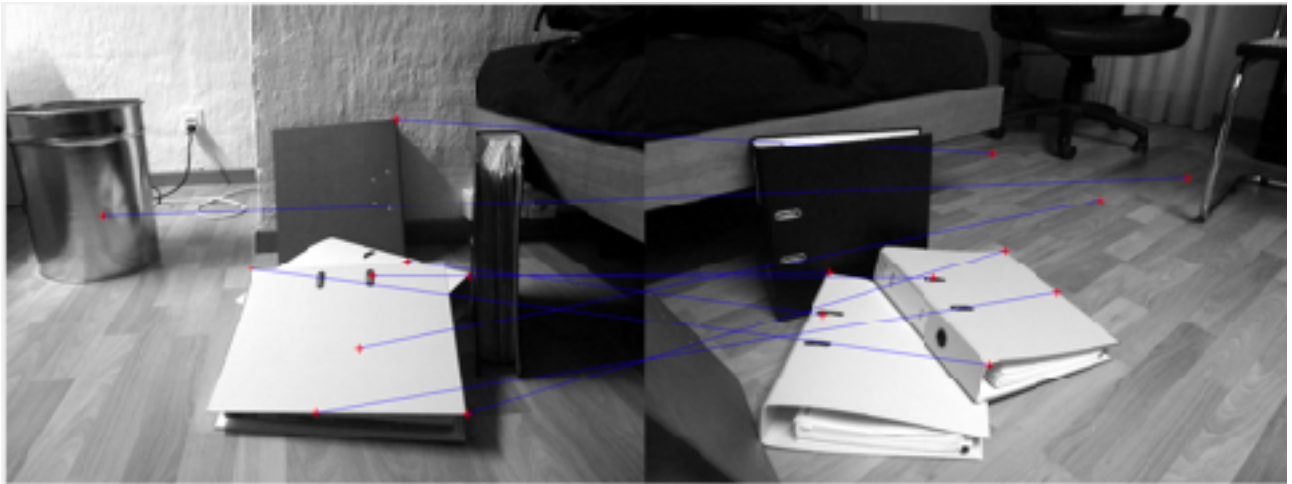


Figure 11: Outliers, threshold = 2

4.6.2 Adaptive RANSAC

M =

782

F =

0.0202	-0.0000	0.0001
-0.0202	-0.0000	0.0010
-0.0201	0.0041	-0.5172

Total Points: 19

Number of inliers: 10

Number of outliers: 9

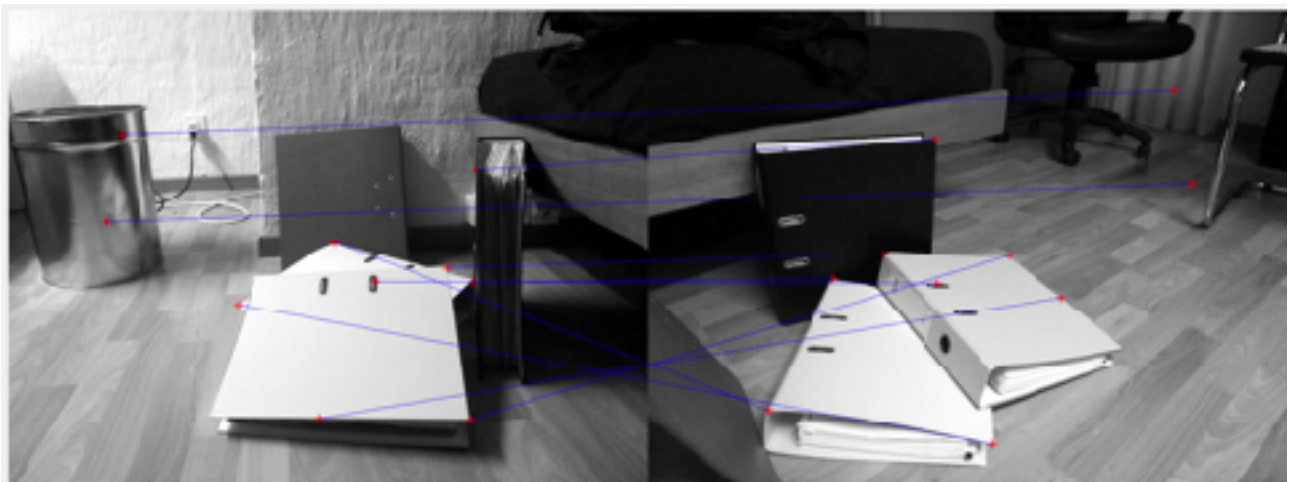


Figure 12: Adaptive RANSAC; inliers; threshold = 5;

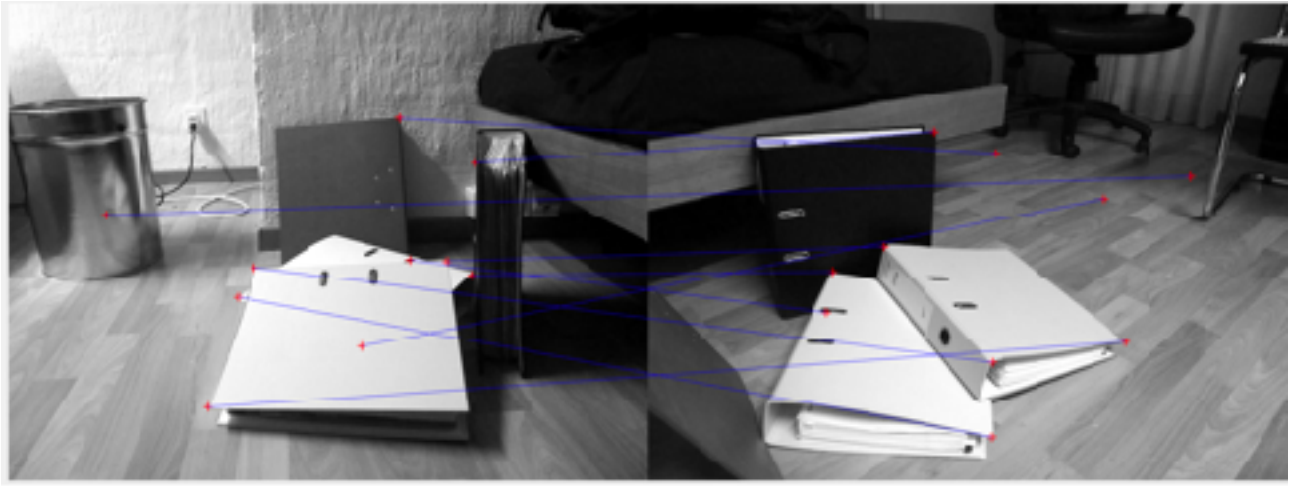


Figure 13: Adaptive RANSAC; outliers; threshold = 5