ProblemSet6_Answer

February 20, 2019

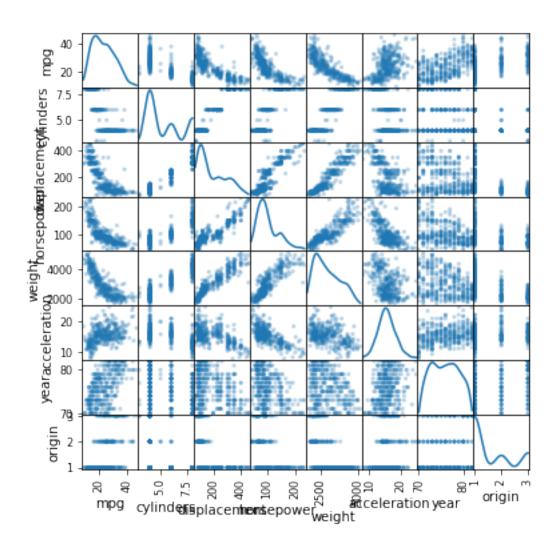
```
0.0.1 Problem Set 6
MACS 30150, Dr. Evans
```

Due Wednesday, Feb. 20 at 11:30am

Tianxin Zheng

1. Multiple linear regression

```
In [1]: import pandas as pd
        import numpy as np
        import matplotlib.pyplot as plt
        from pandas.plotting import scatter_matrix
        import statsmodels.api as sm
        from sklearn.neighbors import KNeighborsClassifier
        from sklearn.model_selection import train_test_split
        from sklearn.linear_model import LogisticRegression
        from sklearn.metrics import confusion_matrix
        from sklearn.metrics import classification_report
(a)
In [2]: df=pd.read_csv("data/Auto.csv", na_values='?')
        df.dropna(inplace=True)
(b)
In [3]: df_quant = df[['mpg', 'cylinders', 'displacement', 'horsepower', 'weight', 'acceleration
In [4]: scatter_matrix(df_quant, alpha=0.3, figsize=(6, 6), diagonal='kde')
        plt.show()
```



(c)

In [5]: df_quant.corr()

Out[5]	:	mpg	cylinders	displacement	horsepower	weight	\
	mpg	1.000000	-0.777618	-0.805127	-0.778427	-0.832244	
	cylinders	-0.777618	1.000000	0.950823	0.842983	0.897527	
	displacement	-0.805127	0.950823	1.000000	0.897257	0.932994	
	horsepower	-0.778427	0.842983	0.897257	1.000000	0.864538	
	weight	-0.832244	0.897527	0.932994	0.864538	1.000000	
	acceleration	0.423329	-0.504683	-0.543800	-0.689196	-0.416839	
	year	0.580541	-0.345647	-0.369855	-0.416361	-0.309120	
	origin	0.565209	-0.568932	-0.614535	-0.455171	-0.585005	
		accelerat	ion ye	ar origin			
	mpg	0.423	329 0.5805	41 0.565209			

```
      cylinders
      -0.504683
      -0.345647
      -0.568932

      displacement
      -0.543800
      -0.369855
      -0.614535

      horsepower
      -0.689196
      -0.416361
      -0.455171

      weight
      -0.416839
      -0.309120
      -0.585005

      acceleration
      1.000000
      0.290316
      0.212746

      year
      0.212746
      0.181528
      1.000000
```

(d)

```
In [6]: df['const'] = 1
```

OLS Regression Results

______ Dep. Variable: R-squared: 0.821 mpg Model: OLS Adj. R-squared: 0.818 F-statistic: Method: Least Squares 252.4 Prob (F-statistic): Date: Wed, 20 Feb 2019 2.04e-139 Time: 09:12:02 Log-Likelihood: -1023.5No. Observations: 392 AIC: 2063. Df Residuals: BIC: 2095. 384

Df Model: 7
Covariance Type: nonrobust

==========						========
	coef	std err	t	P> t	[0.025	0.975]
const	-17.2184	4.644	-3.707	0.000	-26.350	-8.087
cylinders	-0.4934	0.323	-1.526	0.128	-1.129	0.142
displacement	0.0199	0.008	2.647	0.008	0.005	0.035
horsepower	-0.0170	0.014	-1.230	0.220	-0.044	0.010
weight	-0.0065	0.001	-9.929	0.000	-0.008	-0.005
acceleration	0.0806	0.099	0.815	0.415	-0.114	0.275
year	0.7508	0.051	14.729	0.000	0.651	0.851
origin	1.4261	0.278	5.127	0.000	0.879	1.973
Omnibus:	:=======	 31.906	 -Durbin	======== -Watson:	========	1.309
Prob(Omnibus):		0.000	Jarque-Bera (JB):			53.100
Skew:		0.529	Prob(JB):			2.95e-12
Kurtosis:		4.460	Cond. No.		8.59e+04	
==========	=======		=======		=======	=======

Warnings:

- [1] Standard Errors assume that the covariance matrix of the errors is correctly specified.
- [2] The condition number is large, 8.59e+04. This might indicate that there are

strong multicollinearity or other numerical problems.

- **(d.i)** The coefficients of 'displacement', 'weight', 'year' and 'origin' are statistically significant at the 1% level.
- **(d.ii)** The coefficients of 'cylinders', 'horsepower' and 'acceleration' are not statistically significant at the 10% level.
- (d.iii) Other variables held constant, with 'vehicle year' increasing one unit, 'miles per gallon' will increase around 0.7508 unit.
- **(e)** From the scatterplot matrix from part (b), three variables that look most likely to have a nonlinear relationship with 'mpg' are 'displacement', 'horsepower' and 'weight'.

(e.i)

OLS Regression Results

Dep. Variable:	mpg	R-squared:	0.870
Model:	OLS	Adj. R-squared:	0.866
Method:	Least Squares	F-statistic:	230.2
Date:	Wed, 20 Feb 2019	Prob (F-statistic):	1.75e-160
Time:	09:12:03	Log-Likelihood:	-962.02
No. Observations:	392	AIC:	1948.
Df Residuals:	380	BIC:	1996.
Df Model:	11		

Covariance Type: nonrobust

results2 = reg2.fit()
print(results2.summary())

	coef	std err	======= t 	P> t	[0.025	0.975]
const	20.1084	6.696	3.003	0.003	6.943	33.274
cylinders	0.2519	0.326	0.773	0.440	-0.389	0.893
displacement	-0.0169	0.020	-0.828	0.408	-0.057	0.023
horsepower	-0.1635	0.041	-3.971	0.000	-0.244	-0.083
weight	-0.0136	0.003	-5.069	0.000	-0.019	-0.008
acceleration	-2.0884	0.557	-3.752	0.000	-3.183	-0.994

year	0.7810	0.045	17.512	0.000	0.693	0.869
origin	0.6104	0.263	2.320	0.021	0.093	1.128
displacement^2	2.257e-05	3.61e-05	0.626	0.532	-4.83e-05	9.35e-05
horsepower^2	0.0004	0.000	2.943	0.003	0.000	0.001
weight^2	1.514e-06	3.69e-07	4.105	0.000	7.89e-07	2.24e-06
acceleration^2	0.0576	0.016	3.496	0.001	0.025	0.090
==========						
Omnibus:		33.614	Durbin-Wat	cson:		1.576
<pre>Prob(Omnibus):</pre>		0.000	Jarque-Bera (JB):		77.985	
Skew:		0.438	Prob(JB):		1.	.16e-17
Kurtosis:		5.002	Cond. No.		5.13e+08	
==========	========	========	========			======

Warnings:

- [1] Standard Errors assume that the covariance matrix of the errors is correctly specified.
- [2] The condition number is large, 5.13e+08. This might indicate that there are strong multicollinearity or other numerical problems.
 - (e.ii) The adjusted R-squared is 0.866, which is better than 0.818 in the first model.
- **(e.iii)** The coefficients on displacement and its squared term changes from statistically significant at 1% level to nonsignificant at 10% level.
 - (e.iv) The coefficients on cylinders are not statistically significant at the 10% level.

```
(f)
```

```
In [10]: results2.predict(exog=[1, 6, 200, 100, 3100, 15.1, 99, 1, 200**2, 100**2, 3100**2, 15
Out[10]: array([38.7321111])
```

The predicted miles per gallon mpg of a car with 6 cylinders, displacement of 200, horsepower of 100, a weight of 3,100, acceleration of 15.1, model year of 1999, and origin of 1, would be 38.73.

2. Classification problem: KNN by hand and in Python

```
In [11]: table=pd.DataFrame({"X1":[0,2,0,0,-1,1], "X2":[3,0,1,1,0,1],
                                                                                                                                                                 "X3": [0,0,3,2,1,1], "Y": ["Red", "Red", "Red", "Green", "Green", "Red"]})
                                                       table["Eucl.Dist.from X1=X2=X3=0"] = round(np.sqrt((table["X1"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**2+(table["X2"]-0)**
                                                       table.index+=1
                                                       table
Out[11]:
                                                                                                 X2 X3
                                                                                                                                                                                              Eucl.Dist.from X1=X2=X3=0
                                                                         Х1
                                                                                                                                                                           Y
                                                                                0
                                                                                                       3
                                                                                                                                 0
                                                                                                                                                                                                                                                                                                                                  3.000
                                                       1
                                                                                                                                                                Red
                                                       2
                                                                                                        0
                                                                                                                                 0
                                                                                                                                                                                                                                                                                                                                  2.000
                                                                                                                                                                Red
                                                                                                                                3
                                                                                                                                                                Red
                                                                                                                                                                                                                                                                                                                                  3.162
                                                                                0
                                                                                                       1
                                                                                                                                2 Green
                                                                                                                                                                                                                                                                                                                                  2.236
                                                       5
                                                                       -1
                                                                                                        0
                                                                                                                                 1 Green
                                                                                                                                                                                                                                                                                                                                 1.414
                                                                                                                                                                                                                                                                                                                                  1.732
                                                                               1
                                                                                                        1
                                                                                                                                 1
                                                                                                                                                                Red
```

(a) The Euclidean distance between each observation and the test point X1 = X2 = X3 = 0 shows below:

```
d1 = 3
d2 = 2
d3 = \sqrt{10}
d4 = \sqrt{5}
d5 = \sqrt{2}
d6 = \sqrt{3}
```

- **(b)** The KNN prediction with K = 1 is Green, because the closest observation to X1=X2=X3=0 is the 5th observation, which is green.
- (c) The KNN prediction with K = 3 is Red, because the nearest 3 observations to X1=X2=X3=0 are respectively observation 2,5,6. Observation 2 and 6 are red and observation 5 is green, so the prediction is red.
- **(d)** If the Bayes (optimal) decision boundary in this problem is highly nonlinear, then we would expect the best value for K to be large. Since the boundary in this problem is highly nonlinear, large K can capture the feature of surrounding points in all directions better. We could better approximate the optimal decision boundary by increasing K.

(e)

The KNN classifier of the test point X1 = X2 = X3 = 1 with K = 2 is red.

/Users/tianxinzheng/anaconda3/lib/python3.6/site-packages/ipykernel_launcher.py:4: DataConvers after removing the cwd from sys.path.

3. Multivariable logistic (logit) regression

```
In [13]: df['mpg_high']=np.where(df['mpg']>np.median(df['mpg']), 1, 0)

(a)
In [14]: reg3 = sm.Logit(endog=df['mpg_high'], exog=df[['const', 'cylinders', 'displacement', results3 = reg3.fit() print(results3.summary())
```

Optimization terminated successfully.

Current function value: 0.200944

Iterations 9

Logit Regression Results

Dep. Variable:		mpg_high Logit	Df Resi		392 384			
Method: MLE		Df Model:		7				
Date:	Wed,	20 Feb 2019	Geb 2019 Pseudo R-squ.:			0.7101		
Time:		09:12:03	Log-Likelihood:			-78.770		
converged:		True	LL-Null:			-271.71		
			LLR p-value:		2.531e-79			
=========	coef	std err	z	P> z	[0.025	0.975]		
const	-17.1549	5.764	-2.976	0.003	-28.452	-5.858		
cylinders	-0.1626	0.423	-0.384	0.701	-0.992	0.667		
displacement	0.0021	0.012	0.174	0.862	-0.021	0.026		
horsepower	-0.0410	0.024	-1.718	0.086	-0.088	0.006		
weight	-0.0043	0.001	-3.784	0.000	-0.007	-0.002		
acceleration	0.0161	0.141	0.114	0.910	-0.261	0.293		
year	0.4295	0.075	5.709	0.000	0.282	0.577		
origin	0.4773	0.362	1.319	0.187	-0.232	1.187		

Possibly complete quasi-separation: A fraction 0.14 of observations can be perfectly predicted. This might indicate that there is complete quasi-separation. In this case some parameters will not be identified.

Coefficients of weight and year are statistically significant at the 5% level.

```
(b)
```

```
In [15]: Y = df['mpg_high']
         X = df[['cylinders', 'displacement', 'horsepower', 'weight', 'acceleration', 'year',
         X_train, X_test, y_train, y_test = train_test_split(X, Y, test_size = 0.5, random_sta
(c)
In [16]: reg4 = LogisticRegression(random_state=10, solver='lbfgs', multi_class='multinomial',
         print('The estimated intercept is: ', reg4.intercept_)
         print('The estimated coefficient is: ', reg4.coef_[0])
```

The estimated intercept is: [-0.10026869]

The estimated coefficient is: [-0.65773519 0.00857663 -0.01766136 -0.00257161 -0.10958242 0 -0.04697382]

```
In [17]: coef = pd.DataFrame({"coefficient":['constant','cylinders','displacement','horsepower
                              "estimate":list(reg4.intercept_) + list(reg4.coef_[0])})
        print(coef)
    coefficient estimate
0
      constant -0.100269
      cylinders -0.657735
1
2 displacement 0.008577
3
    horsepower -0.017661
        weight -0.002572
4
5
 acceleration -0.109582
           year 0.167356
6
7
        origin -0.046974
(d)
In [18]: y_pred = reg4.predict(X_test)
         cm = confusion_matrix(y_test, y_pred)
         print("Confusion matrix:")
         print(cm)
Confusion matrix:
[[86 13]
 [12 85]]
In [19]: print("Classification report:")
        print(classification_report(y_test, y_pred))
Classification report:
             precision
                          recall f1-score
                                              support
          0
                  0.88
                            0.87
                                      0.87
                                                   99
          1
                  0.87
                            0.88
                                      0.87
                                                   97
avg / total
                  0.87
                            0.87
                                      0.87
                                                  196
```

The F1-scores are same. This model predicts equally well on low mpg and high mpg.