TIANXING WU

https://tianxingwu.github.io

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EDUCATION

Nanyang Technological University (NTU)

Singapore

Master of Science in Computer Control & Automation

Jan. 2021 – Jan. 2022 (Expected)

• Deferred erollment to January 2021 due to COVID-19

Harbin Engineering University (HEU)

Harbin, China

Bachelor of Engineering in Automation

Aug. 2015 – June 2020

• Research Intern at Institute of Intelligent Control

• Supervisor: Prof. Qidan Zhu, Prof. Zhi Zhang

• GPA: 89.14 / 100

OpenVHead

Harbin Institute of Technology Robot Group

Hefei, China

2019 ROS Summer School in China

July 2019 - Aug. 2019

• Topics: ROS, Industrial robots, RTS, Reinforcement learning, Humanoid robot, Simulation, SLAM

• 2nd Prize of the final robot competition

▲ RESEARCH & PROJECTS

Deep Learning Based Image Preprocessing for Maritime Scenes

Jan. 2020 – July 2020

B.Eng Thesis, Supervised by Prof. Zhi Zhang

- Excellent presentation (6 awardees of 42 students in the lab)
- Designed a new foggy image synthesis algorithm based on air scattering characteristics of sea fog
- Analysed the effectiveness and optimal parameter settings of AOD-Net, DnCNN and traditional methods for maritime image defogging and denoising, implementing with PyTorch and OpenCV
- Proposed a modular image preprocessing framework that can be effectively applied to maritime scenes

Sept. 2019 – Present

Independent Project (Open-sourced on GitHub)

- Top 5 most stars under the topic 'Vtuber' on GitHub
- Built a vision-based head motion & facial expressions capture system for VTubers
- Front-end (Python): Face landmarks tracking using Kalman filter and mean filter; Pose estimation with PnP algorithm; Robust facial expression measure construction
- Back-end (Unity + C#): Smooth pose control with Kalman filter; Robust facial expression control using incomplete derivative PID with deadzone; Eye-blink modeling; Socket communication

From QoS to QoE: A Data-Driven Model for Mobile Video Services

July 2017 – Present

Project Leader, 'Shenzhen Cup' Mathematical Modeling Challenge, Supervised by Prof. Shujuan Wang

- Champion (2 awardees of 65 finalist, including THU/FDU/ZJU teams)
- Built an accurate mathematical model of the relation between network capability and video experience for network planning and assessment, successfully solving the problem proposed by Huawei Technologies
- Constructed a nonlinear function based on both TCP mechanism and a dataset with 89,266 samples
- Introduced unsupervised anomaly detection algorithm to remove noise data for regression analysis
- Proposed and implemented a probabilistic method to solve the heteroscedasticity of the data, significantly enhancing the prediction accuracy

Real-time Driver Fatigue Monitoring System

Algorithm Engineer, National Undergraduate Training Programs, Supervised by Prof. Qiang Zhang

- Developed a vision-based fatigue monitoring module for the system
- Extracted geometry features by face alignment using Dlib
- Designed a robust indicator to classify the eye state of the driver
- Eliminated disturbance of eye blink from video sequence using queue data structure

Flocking Algorithm for Swarm Robots Inspired by Foam Dynamics

Oct. 2018 - Jan. 2019

Independent Project, Supervised by Prof. Haihong Chi

- Proposed a distributed control scheme for multi-agent systems inspired by the physics of liquid foams
- Implemented a convincing simulation of 3D flocking behaviour with obstacle avoidance in MATLAB based on an ODE system derived from the dynamic behavior of the foam
- Greatly enhanced the computing efficiency by introducing graph data structure and optimizing the algorithm to a vectorized version, enabling for simulation of massive multi-agent systems

Face Detection and Tracking Using Pan-Tilt Camera

Sept. 2018 - Nov. 2018

Independent Project, Supervised by Prof. Haihong Chi

- Designed a pan-tilt system consisting of two servos and a USB camera
- Implemented face detection pipeline using image processing and Haar Cascades with OpenCV
- Achieved face tracking with reasonable speed and precision by adding and tuning two separate independent PD control loops on the MCU

A Gesture Recognition System Based on Capacitive Sensor

July 2018 – Aug. 2018

Software Group Leader, Supervised by Dr. Yuan Liu

- Led a 5-person software team to develop the overall software architecture of the system
- Designed the key algorithm and training method for recognizing different gestures through capacitance data given by FDC2214 sensor, using median filter to reduce impulsive noises
- Added Palm Rejection function by implementing real-time statistical analysis on the microcontroller for time series data

★ SELECTED AWARDS & HONORS

• Honorable Mention, Mathematical Contest in Modeling (MCM)	2018
Outstanding Undergraduate Student in HEU	2017
• 1st Prize & Champion, 'Shenzhen Cup' Mathematical Modeling Challenge	2017
• 1 st Prize, Northeast China Mathematical Contest in Modeling	2017
• 1 st Prize, China Undergraduate Mathematical Contest in Modeling (Heilongjiang Division)	2017
• 1 st Class Scholarship for Outstanding Students	2016
• 2 nd Prize, National English Competition for College Students (NECCS)	2016

SKILLS

- Programming Language: Python, MATLAB, C/C++, C#, Verilog
- Software: OpenCV, PyTorch, ROS, Simulink, Unity, SOLIDWORKS, Multisim, Quartus, Linux, Git
- Hardware: STM32, 89C51, Arduino microcontrollers

i English Proficiency

- CET-6: 635 (Listening 218, Reading 229, Writing & Translating 188)
- **IELTS**: **7.5** (Listening **8.5**, Reading **9.0**, Writing **6.0**, Speaking **6.5**)
- GRE: 324.5 (Verbal Reasoning 152, Quantitative Reasoning 169, Analytical Writing 3.5)

Dec. 2018 - Apr. 2019