ECO326 Advanced Microeconomic Theory
A Course in Game Theory

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January 7, 2019

`Github Page` `https://github.com/TianyuDu/Spikey_UofT_Notes`
`Note Page` `TianyuDu.com/notes`

Readme this note is based on the course content of *ECO326 Advanced Microeconomics - Game Theory*, this note contains all materials covered during lectures and mentioned in the course syllabus. However, notations, statements of theorems and proofs are following the book *A Course in Game Theory* by Osborne and Rubinstein, so they might be, to some extent, more mathematical than the required text for ECO326, *An Introduction to Game Theory*.

Contents

1 Lecture 1. Games and Dominant Strategies

Game Theory Choice environment where individual choices impact others.

	W	S
W	$(1-c, 1-c)$	$(1-c, 1)$
S	$(1, 1-c)$	$(0, 0)$

Figure 1: Payoff Matrix for Example 1

Example 1.1.

Suppose $c \in (0, 1)$. In this game,

i $N = \{i, j\}$,

ii $A_i = A_j = \{W, S\}$,

Definition 1.1 (pg.7)**.** A **preference relation** is a complete reflexive and transitive binary relation.

Definition 1.2 (11.1, lec.1)**.** A **(strategic) game** consists of

i a finite set of **players** N, with $|N| \geq 2$.

ii for each player $i \in N$, an **actions** $A_i \neq \emptyset$.

iii for each player $i \in N$, a **preference relation** $\succsim_i$ defined on $A \equiv \times_{i \in N} A_i$. Or a real-valued **utility function**, $u : A \to \mathbb{R}$.

and can be written as a triple $\langle N, (A_i), (\succsim_i) \rangle$, or $\langle N, (A_i), (u_i) \rangle$

Definition 1.3 (lec.1)**.** An **action profile** is a n-tuple of actions $a_i \in A_i$ for each player $i \in N$ and denoted as

$$(a_i)_{i \in N} \text{ or } (a_i)$$

The **action profile space** is defined as

$$A \equiv \times_{i \in N} A_i$$

Definition 1.4 (lec.1)**.** Action $a_i \in A_i$ is **strictly dominated** by action $\tilde{a}_i \in A_i$ if

$$\forall a_{-i} \in A_{-i},\ u_i(a_i, a_{-i}) < u_i(\tilde{a}_i, a_{-i})$$

And a_i is **weakly dominated** by $\tilde{a}_i$ if

$$\forall a_{-i} \in A_{-i},\ u_i(a_i, a_{-i}) \leq u_i(\tilde{a}_i, a_{-i})$$

and

$$\exists a_{-i} \in A_{-i},\ u_i(a_i, a_{-i}) < u_i(\tilde{a}_i, a_{-i})$$

Corollary 1.1 (Consequence of RCT)**.** It is irrational to play strictly dominated actions. So rational choice theory suggests a player would never play strictly dominated strategies.

Definition 1.5. Action $a_i \in A_i$ is **strictly dominant** if it strictly dominates all other actions.

Definition 1.6. Action $a_i \in A_i$ is **weakly dominant** if it weakly dominates all other actions.

	S	C
S	(-1, -1)	(-10, 0)
C	(0, -10)	(-5, -5)

Figure 2: Payoff matrix for example 2

Example 1.2 (Prisoner Dilemma)**.** Note that S is strictly dominated by C. Therefore C is strictly dominant for both players.

	L	C	R
U	(2, 2)	(5, 0)	(3, 0)
M	(2, 7)	(2, 5)	(2, 6)
D	(5, 3)	(4, 2)	(3, 1)

Figure 3: Payoff matrix for example 2

Example 1.3. So in this game, for player 2, L is strictly dominant.
For player 1, M is strictly dominated by D. And M is weakly dominated by U.

Example 1.4. There are three candidates, $\{A, B, C\}$. And there are 50 players (voters, note that $\emptyset \notin A_i$ since they must vote). And

$$\forall i \in N,\ A_i = \{A, B, C\}$$

Each individual has strictly preference over A, B, C. If tie is encountered, randomization would be taken.

i $A \succ B \succ C$,

ii $A \succ AC_{tie} \succ C$

Claim 1: There are no weakly or strictly dominant actions.

Proof. Let n_{-i}^{i} denote the number of voters other than i voting for candidate $j \in \{A, B, C\}$.
Consider action A, if $n_{-i}^{A} = 1$ and $n_{-i}^{B} = n_{-i}^{C} = 24$, then B is strictly preferred than A.
Consider action B, if $n_{-i}^{A} = n_{-i}^{C} = 24$, then A is strictly preferred than B.
Consider action C, if $n_{-i}^{B} = n_{-i}^{C} = 24$, then B is strictly preferred than C. ∎

Claim 2: Only voting for your least preferred candidate is weakly dominated.

Proof. We are going to show there exists a strategy (voting for B) weakly dominates voting for C.

Vote A	Cases	Vote C
A	$n_{-i}^{A} > n_{-i}^{B}, n_{-i}^{C}$	A, AC
B	$n_{-i}^{B} > n_{-i}^{A}, n_{-i}^{C}$	B, BC
C, BC	$n_{-i}^{C} > n_{-i}^{A}, n_{-i}^{B}$	C
B	$n_{-i}^{A} = n_{-i}^{B} > n_{-i}^{C}$	AB
A	$n_{-i}^{A} = n_{-i}^{C} > n_{-i}^{B}$	C
BC	$n_{-i}^{C} = n_{-i}^{B} > n_{-i}^{A}$	C

Figure 4: Voting for A versus Voting for C

∎

Definition 1.7 (pg.11)**.** A strategic game $\langle N, (A_i), (\succsim_i)\rangle$ is **finite** if

$$|A_i| < \aleph_0\ \forall i \in N$$

2 Lecture 2. Iterated Elimination and Rationalizability

2.1 Iterated Elimination of Strictly Dominated Strategies(Actions)

Definition 2.1 (60.2)**.** The set $X \subseteq A$ of outcomes of a finite strategic game $\langle N, (A_i), (u_i) \rangle$ **survives iterated elimination of strictly dominated actions** if $X = \times_{j \in N} X_j$ and there is a collection $((X_j^t)_{j \in N})_{t=0}^T$ of sets that satisfies the following conditions for each $j \in N$.

- $X_j^0 = A_j$ and $X_j^T = X_j$.
- $X_j^{t+1} \subseteq X_j^t$ for each $t = 0, \dots, T-1$.
- For each $t = 0, \dots, T-1$ every action of player j in $X_j^t \backslash X_j^{t+1}$ is strictly dominated in the game $\langle N, (X_i^t), (u_i^t) \rangle$, where u_i^t for each $i \in N$ is the function u_i restricted to $\times_{j \in N} X_j^t$.
- No action in X_t^T is strictly dominated in game $\langle N, (X_i^T), (u_i^T) \rangle$.

Proposition 2.1 (61.2)**.** If $X = \times_{j \in N} X_j$ survives iterated elimination of strictly dominated actions in a finite strategic game $\langle N, (A_i), (u_i) \rangle$ then X_j is the set of player j's rationalizable actions for each $j \in N$.

2.2 Rationalizability

Definition 2.2 (pg.15)**.** The **best-response function** for a player i is defined as

$$B_i(a_{-i}) = \{a_i \in A_i : (a_i, a_{-i}) \succsim_i (a_i', a_{-i}) \ \forall a_i' \in A_i\}$$

Remark 2.1. The best-response of a_{-i} can be written as

$$B_i(a_{-i}) = \bigcap_{a_i' \in A_i} \{a_i \in A_i : (a_i, a_{-i}) \succsim_i (a_i', a_{-i})\}$$

where each of them is the upper contour set of a_i'.
Thus, if $\succsim_i$ is quasi-concave, then $B_i(a_{-i})$ is an intersection of convex sets and therefore itself convex.

Definition 2.3 (pg.54)**.** A **belief** of player i (about the actions of the other players) is a probability measure, μ_i, on $A_{-i} = \times_{j \in N \backslash \{i\}} A_j$.
μ_i is a mapping such that

- $\mu_i : A_{-i} \to [0,1]$.
- $\mu_i(A_{-i}) = 1$.
- For all countable piece-wise disjoint collection $\{E_i\}_{i \in I}$, it satisfies the *countable additivity property*:

$$\mu_i(\bigcup_{i \in I} E_i) = \sum_{i \in I} \mu_i(E_i)$$

Definition 2.4 (lec.2)**.** For a player $i \in N$, $a_i^* \in A_i$ is the **best response to belief** μ_i in a strategic game $\langle N, (A_i), (u_i) \rangle$ if and only if

$$\forall a_i \in A_i, \sum_{a_{-i} \in A_{-i}} u_i(a_i^*, a_{-i}) \mu_i(a_{-i}) \geq \sum_{a_{-i} \in A_{-i}} u_i(a_i, a_{-i}) \mu_i(a_{-i})$$

Equivalently,

$$\forall a_i \in A_i,\ \mathbb{E}[u_i(a_i^*, a_{-i}) | \mu_i] \geq \mathbb{E}[u_i(a_i, a_{-i}) | \mu_i]$$

Definition 2.5 (59.1)**.** An action of player i in a strategic game is a **never best response** if it is not a best response to any belief of player i.

Definition 2.6 (lec.2)**.** For player $i \in N$, action $a_i \in A_i$ is **rationalizable** if it survives from the iterated elimination of never best responses.

Definition 2.7 (59.2)**.** The action $a_i \in A_i$ of player i in the strategic game $\langle N, (A_i), (u_i) \rangle$ is **strictly dominated** if there is a mixed strategy α_i of player i such that

$$U_i(a_{-i}, \alpha_i) > u_i(a_{-i}, a_i)$$

for all $a_{-i} \in A_{-i}$, where $U_i(a_{-i}, \alpha_i)$ is the payoff of player i if he uses the mixed strategy α_i and the other players' vector of actions is a_{-i}.

3 Lecture 3. Nash Equilibrium

Definition 3.1 (14.1)**.** A **Nash equilibrium of a strategic game** $\langle N, (A_i), (\succsim_i) \rangle$ is a profile $a^* \in A$ of actions with property that for every player $i \in N$

$$(a_i^*, a_{-i}^*) \succsim_i (a_i, a_{-i}^*)\ \forall a_i \in A_i$$

Proposition 3.1 (pg.15, equivalent definition of Nash equilibrium)**.** So a Nash equilibrium is a profile $a^* \in A$ such that

$$a_i^* \in B_i(a_{-i}^*)\ \forall i \in N$$

Proposition 3.2 (lec.3)**.** No strategy that is eliminated during iterated deletion of never best response can be played in Nash equilibrium.

Lemma 3.1 (pg.19)**.** A strategic game $\langle N, (A_i), (\succsim_i)\rangle$ has a Nash equilibrium if equivalent to the following statement:
Define set-valued function $B : A \to A$ by

$$B(a) = \times_{i \in N} B_i(a_{-i})$$

and there exists $a^* \in A$ such that $a^* \in B(a^*)$.

Lemma 3.2 (20.1 Kakutani's fixed point theorem)**.** Let X be a compact convex subset of $\mathbb{R}^n$ and let $f : X \to X$ be a set-valued function for which

- for all $x \in X$ the set $f(x)$ is non-empty and convex.
- the graph of f is closed. *(i.e. for all sequences $\{x_n\}$ and $\{y_n\}$ such that $y_n \in f(x_n)$ for all n, $x_n \to x$ and $y_n \to y$ then $y \in f(x)$)*

Then there exists $x^* \in X$ such that $x^* \in f(x^*)$.

Definition 3.2 (pg.20)**.** A preference relation $\succsim_i$ over A is quasi-concave on A_i if for every $a^* \in A$ the upper contour set over a_i^*, given other players' strategies

$$\{a_i \in A_i : (a_{-i}^*, a_i) \succsim_i a^*\}$$

is convex.

Proposition 3.3 (20.3)**.** The strategic game $\langle N, (A_i), (\succsim_i)\rangle$ has a Nash equilibrium if for all $i \in N$,

- the set A_i of actions of player i is a nonempty compact convex subset of a Euclidian space

and the preference relation $\succsim_i$ is

- continuous
- quasi-concave on A_i.

Proof. Let $B : A \to A$ be a correspondence defined as

$$B(a) := \times_{i \in N} B_i(a_{-i})$$

Note that for each $a \in A$ and for each $i \in N$,
$B_i(a_{-i}) \neq \emptyset$ since preference $\succsim_i$ is continuous and A_i is compact (EVT).

Also $B_i(a_{-i})$ is convex since it's basically an intersection of upper contour sets and each of those upper contour is convex since $\succsim_i$ is quasi-concave.
So the Cartesian product of the finite collection of B_i is non-empty and convex.
Also the graph B is closed since $\succsim_i$ is continuous.
So there exists $a^* \in A$ such that $a^* \in B(a^*)$.
So Nash equilibrium presents. ■

Definition 3.3 (lec.3)**.** A **strict Nash equilibrium** is an action profile $a^* \in A$ where all players are playing their unique best response. That is, for every player $i \in N$, the image of their best response $B_i(a^*_{-i})$ is singleton,

$$\forall i \in N \ B_i(a^*_{-i}) = \{a^*_i\}$$

Definition 3.4 (lec.3)**.** Otherwise, a Nash equilibrium is a **weak Nash equilibrium**.

4 Lecture 4. Nash Equilibrium: Examples

5 Lecture 5. Mixed Strategies

Notation 5.1 (pg.32)**.** Let $\Delta(A_i)$ denote the set of probability measures/distributions on set A_i.

Definition 5.1 (lec.5)**.** For player $i \in N$, a **mixed strategy** σ_i is a member in $\Delta(A_i)$ and it is a probability distribution over A_i.

Remark 5.1 (lec.5)**.** A pure strategy $a_i \in A_i$ is a mixed strategy with

$$\sigma_i(a_i) = 1$$

So mixed strategy is a generalization of pure strategy.

Definition 5.2 (pg.32)**.** A profile $(\sigma_j)_{j \in N}$ of mixed strategies induces a probability distribution over the set A.

Proposition 5.1 (pg.32)**.** In a finite game,(i.e., each A_i is finite), then given the independence of randomization, the probability of the action profile $a = (a_j)_{j \in N}$ to be realized given mixed strategy profile $(\sigma_j)_{j \in N}$ is

$$Pr((a_j)_{j \in N}) = \prod_{j \in N} \sigma_j(a_j)$$

and for player i, the **expected payoff** on profile $(\sigma_j)_{j\in N}$ is

$$U_i((\sigma_j)_{j\in N}) = \sum_{a\in A}(\prod_{j\in N}\sigma_j(a_j))u_i(a) = \mathbb{E}[u_i(a)|(\sigma_j)_{j\in N}]$$

Proposition 5.2 (lec.5, equivalent)**.** The **expected payoff** from mixed strategy profile $(\sigma_i) \equiv (\sigma_i, \sigma_{-i})$ is

$$U_i(\sigma_i, \sigma_{-i}) \equiv \mathbb{E}[u_i(a)|(\sigma_i)] = \sum_{a_i\in A_i}\sum_{a_{-i}\in A_{-i}} u_i(a_i, a_{-i})\sigma_{-i}(a_{-i})\sigma_i(a_i)$$

Definition 5.3 (32.1)**.** The **mixed extension** of the strategic game $\langle N, (A_i), (u_i)\rangle$ is the strategic game $\langle N, (\Delta(A_i)), (U_i)\rangle$ in which $\Delta(A_i)$ is the set of probability distributions over A_i and $U_i : \times_{j\in N}\Delta(A_i) \to \mathbb{R}$ assigns to each $(\sigma_i)_{i\in N} \in \times_{j\in N}\Delta(A_i)$ the expected value under u_i of the lottery over A that is induced by $(\sigma_i)_{i\in N}$.

Remark 5.2 (pg.32, notes on above definition)**.** If the game is finite, that is, for each $i \in N$, the set A_i is finite, then

$$U_i(\sigma) = \sum_{a\in A}(\prod_{j\in N}\sigma_j(a_j))u_i(a)$$

Definition 5.4 (32.3)**.** A **mixed strategy Nash equilibrium of a strategic game** is a Nash equilibrium of its mixed extension.

Proposition 5.3 (33.1)**.** Every finite strategic game has a mixed strategy Nash equilibrium.

Lemma 5.1 (33.2)**.** Let $G = \langle N, (A_i), (u_i)\rangle$ be a finite strategic game. Then $\sigma^* \in \times_{i\in N}\Delta(A_i)$ is a mixed strategy Nash equilibrium of G is and only if for every player $i \in N$ every pure strategy in the support of σ_i^* is a best response to σ_{-i}^*

Assumption 5.1 (lec.5)**.** Assuming all agents follows Von-Neumann Morgenstern theorem.

Definition 5.5 (lec.5)**.** An action a_i is **strictly dominated** by mixed strategy σ_i if and only if

$$\forall a_{-i} \in A_{-i}\ u_i(a_i, a_{-i}) < U_i(\sigma_i, a_{-i})$$

where σ_i could be a pure strategy.

Definition 5.6 (lec.5)**.** A mixed strategy σ_i is a **best response** to σ_{-i} if and only if

$$\forall \sigma_i' \in \Delta(A_i)\ U_i(\sigma_i, \sigma_{-i}) \geq U_i(\sigma_i', \sigma_{-i})$$

Definition 5.7 (lec.5)**.** The **support** of a mixed strategy $\sigma_i \in \Delta(A_i)$ is the set

$$supp(\sigma_i) = \{a_i \in A_i : \sigma_i(a_i) \neq 0\}$$

Proposition 5.4 (lec.5)**.** A mixed strategy σ_i is a **best response** to an strategy profile σ_{-i} if and only if

(a) Player i is indifferent between all a_i in the support of σ_i,

$$\forall a_j, a_j' \in supp(\sigma_i) \quad a_j \sim_i a_j'$$

(b) <u>and</u> player i weakly prefers all actions in the support of σ_i to those not in the support of σ_i. That's

$$\forall a_j \in supp(\sigma_i),\ \forall a_j' \notin supp(\sigma_i) \quad a_j \succsim_i a_j'$$

Proof. ($\implies$) show the if parts by proving it's contraposition.
Suppose (a) is not true, then

$$\exists a_i, a_j \in supp(\sigma_i)\ s.t.\ a_i \nsim_i a_j$$

WLOG, suppose

$$u_i(a_i, \sigma_{-i}) > u_i(a_j, \sigma_{-i})$$

then σ_i would not be the best response since we can refine it by assigning

$$\begin{cases} \sigma_i'(a_i) = \sigma_i(a_i) + \sigma_i(a_j) \\ \sigma_i'(a_j) = 0 \\ \sigma_i'(a_k) = \sigma_i(a_k) \text{ otherwise} \end{cases}$$

and σ_i' would provides higher expected payoff.
Suppose (b) does not hold,

$$\exists a_i \notin supp(\sigma_i)\ s.t.\ \exists a_j \in supp(\sigma_i)\ s.t\ u_i(a_i, \sigma_{-i}) > u_i(a_j, \sigma_{-i})$$

Then σ_i could not be a best response since we can construct another mixed strategy σ_i' strictly dominating σ_i by setting

$$\begin{cases} \sigma_i'(a_j) = 0 \\ \sigma_i'(a_i) = \sigma_i(a_j) \\ \sigma_i'(a_k) = \sigma_i(a_k) \text{ otherwise} \end{cases}$$

$(\Longleftarrow)$ Assuming σ_i is not a best response towards σ_{-i},
then there exists $\sigma_i' \in \Delta(A_i)$ such that

$$
\begin{aligned}
& U_i(\sigma_i', \sigma_{-i}) > U_i(\sigma_i, \sigma_{-i}) \\
\iff & \mathbb{E}[u_i(a)|(\sigma_i', \sigma_{-i})] > \mathbb{E}[u_i(a)|(\sigma_i, \sigma_{-i})] \\
\iff & \sum_{a_i \in A_i} \sum_{a_{-i} \in A_{-i}} u_i(a_i, a_{-i}) \sigma_i'(a_i) \sigma_{-i}(a_{-i}) > \sum_{a_i \in A_i} \sum_{a_{-i} \in A_{-i}} u_i(a_i, a_{-i}) \sigma_i(a_i) \sigma_{-i}(a_{-i})
\end{aligned}
$$

Probability measures σ_i and σ_i' could only be different in two aspects, their supports and the values assigned on elements in their supports, this fails assumption (a).
The following argument needs to be revised.
Case 1 suppose $supp(\sigma_i) = supp(\sigma_i')$, then the strictly inequality in expected payoffs implies redistributing probabilities does affect the expected payoffs. So player i cannot be indifferent between any two actions in the support.
Case 2 suppose $supp(\sigma_i) \neq supp(\sigma_i')$ and $supp(\sigma_i') \not\subseteq supp(\sigma_i)$. That's

$$\exists a_i \in supp(\sigma_i') \wedge \notin supp(\sigma_i)$$

Then extending the support to a_i of σ_i gives higher expected payoff, this fails the assumption (b).
Case 3 suppose $supp(\sigma_i') \subsetneq supp(\sigma_i)$. Then the expected payoff can be strictly increased by eliminating actions in $supp(\sigma_i) \backslash supp(\sigma_i')$. Then those actions eliminated must be strictly dominated by actions in $supp(\sigma_i')$. This fails assumption (a). ■

Proposition 5.5 (lec.5 equivalent proposition)**.** All actions in the support are best responses. (i.e.*best response mixed strategy is a mixture of best response pure actions*)

Remark 5.3 (lec.5 Intuition of proposition)**.** If the requirements of above proposition are not satisfied, the player can reduce the probability assigned to the non-best-response pure action and better off.

Theorem 5.1 (lec.5 Nash's Theorem)**.** Any player $i \in N$ in finite game $\langle N, (A_i), (\succsim_i) \rangle$ has a mixed strategy Nash equilibrium.

6 Lecture 6. Extensive Form Games and Subgame Perfection

6.1 Extensive Form Game

Definition 6.1 (89.1)**.** An **extensive game with perfect information** has the following components.

- A set N of **players**.
- A set H of sequences (finite or infinite) of **histories** with properties:
  - $\emptyset \in H$.
  - For all $L < K$, $(a^k)_{k=1,2,\ldots,K} \in H \implies (a^k)_{k=1,2,\ldots,L} \in H$.
  - For infinite sequence $(a^k)_{k=1}^{\infty}$,
    $(a^k)_{k=1,2,\ldots,L} \in H,\ \forall L \in \mathbb{Z}_{++} \implies (a^k)_{k=1}^{\infty} \in H$.

  And each component of history $h \in H$ is an **action** taken by a player.
- A function $P : H \backslash Z \to N$, where for $h \in H$, $P(h) \in N$ is defined by the player who takes an action <u>after</u> the history h.
- For each player $i \in N$ a **preference relation** $\succsim_i$ <u>defined on Z</u>.

Notation 6.1 (pg.90)**.** An extensive game with perfect information can be represented by a 4-tuple, $\langle N, H, P, (\succsim_i) \rangle$. *Sometimes it is convenient to specify the structure of an extensive game without specifying the players' preference, as* $\langle N, H, P \rangle$.

Definition 6.2 (pg.90)**.** A history $(a^k)_{k=1,2,\ldots,K} \in H$ is **terminal** if

1. it is infinite,
2. <u>or</u> (i.e. it cannot be extended to another valid history sequence)

$$\forall a^{K+1},\ (a^k)_{k=1,2,\ldots,K+1} \notin H$$

The set of terminal histories is denoted by Z.

Notation 6.2 (pg.90, the action set)**.** After any nonterminal history, $h \in H \backslash Z$, the player $P(h)$ chooses an action from set

$$A(h) = \{a : (h, a) \in H\}$$

Remark 6.1. Note that all player function, action set and player preference relation are defined on H. Thus, unlike a normal form game, which was *player oriented*, we'd better consider an extensive form game as *history oriented.*

Definition 6.3 (pg.90)**.** We refer to the empty set, which is required to be an element of H, as the **initial history**.

Definition 6.4 (92.1)**.** A **strategy of player** $i \in N$, s_i, in an extensive game with perfect information $\langle N, H, P, (\succsim_i) \rangle$ is a function that assigns an action in $A(h)$ to each nonterminal history $h \in H \backslash Z$ for which $P(h) = i$.

Remark 6.2 (pg.92)**.** A strategy specifies the action chosen by a player for *every* history after which it is his turn to move, *even for histories that is, if the strategy is followed, are never reached.*

Definition 6.5 (pg.93)**.** For each strategy profile $s = (s_i)_{i \in N}$ in the extensive game $\langle N, H, P, (\succsim_i) \rangle$, the **outcome** of s, $O(s)$, is defined as the terminal history that results when each player $i \in N$ follows the precepts of s_i. That is, $O(s)$ is the (possibly infinite) history

$$(a^1, \ldots, a^K) \in Z$$

such that

$$\forall k \in \{0, 1, \ldots K-1\},\ s_{P(a^1, \ldots, a^k)}(a^1, \ldots, a^k) = a^{k+1}$$

Definition 6.6 (lec.6)**.** A extensive game $\Gamma = \langle N, H, P, (\succsim_i) \rangle$ is finite if and only if

(a) N is finite.

(b) (A_i) are all finite.

(c) All $h \in H$ reach the terminal state with finite length.

Definition 6.7 (93.1)**.** A **Nash equilibrium of an extensive game with perfect information** $\langle N, H, P, (\succsim_i) \rangle$ is a strategy profile s^* such that for every player $i \in N$ we have

$$\forall s_i \in S_i,\ O(s^*_{-i}, s^*_i) \succsim_i O(s^*_{-i}, s_i)$$

Definition 6.8 (94.1)**.** The **strategic form of the extensive game with perfect information**, $\Gamma = \langle N, H, P, (\succsim_i) \rangle$, is the strategic game $\langle N, (S_i), (\succsim'_i) \rangle$ in which for each player $i \in N$

- S_i is the **set of strategies** of player i in Γ.
- $\succsim'_i$ is defined on $\times_{i\in N} S_i$ and defined by

$$\forall s, s' \in \times_{i\in N} S_i,\ s \succsim'_i s' \iff O(s) \succsim_i O(s')$$

Definition 6.9 (pg.94)**.** A **reduced strategy** of player i is defined to be a function f_i whose domain is a *subset* of $\{h \in H : P(h) = i\}$ and has the following properties

1. it associates with every history h in the domain of f_i an action in $A(h)$.
2. a history h with $P(h) = i$ is in the domain of f_i if and only if all the actions of player i in h are those dictated by f_i. (i.e., for any $h = (a^k)$ and for any $h' = (a^k)_{k=1}^{L}$ as a subsequence of h such that $P(h') = i$, $f_i(h') = a^{L+1}$.)

Remark 6.3 (pg.94)**.** Each **reduced strategy** of player i corresponds to a set of strategies of player i, such that for each vector of strategies of the other players each strategy in this set yields the same outcome. (strategies in the same set are **outcome-equivalent**.)
That's, for each strategy $s_i \in S_i$, its reduced strategy can be defined with an outcome equivalence class, $[s_i]$,

$$[s_i] \equiv \{s'_i \in S_i : \forall s_{-i} \in \times_{j\in N\setminus\{i\}} S_j,\ O(s_{-i}, s_i) = O(s_{-i}, s'_i)\}$$

But in some other game, the definition of outcome-equivalence is more general and defined by generating the same payoff (through possibly difference outcomes), then the reduced strategy is defined as

$$[s_i] \equiv \{s'_i \in S_i : \forall s_{-i} \in \times_{j\in N\setminus\{i\}} S_j,\ \forall j \in N,\ O(s_{-i}, s_i) \sim_j O(s_{-i}, s'_i)\}$$

Definition 6.10 (95.1.1)**.** Let $\Gamma = \langle N, H, P, (\succsim_i)\rangle$ be an extensive game with perfect information and let $\langle N, (S_i), (\succsim'_i)\rangle$ be its strategic form. For any $i \in N$ define the strategies $s_i, s'_i \in S_i$ to be **equivalent** if

$$\forall s_{-i} \in S_{-i},\ \forall j \in N,\ (s_{-i}, s_i) \sim'_j (s_{-i}, s'_i)$$

Definition 6.11 (95.1.2)**.** The **reduced strategic form of** Γ is the strategic game $\langle N, (S'_i), (\succsim''_i)\rangle$ in which for each $i \in N$ each set S'_i contains one member of each set of equivalent strategies in S_i and $\succsim''_i$ is the preference ordering over $\times_{j\in N} S'_j$ induced by $\succsim'_i$.

6.2 Subgame Perfection

Definition 6.12 (97.1)**.** The **subgame of extensive game with perfect information** $\Gamma = \langle N, H, P, (\succsim_i) \rangle$ **that follows the history** h is the extensive game $\Gamma(h) = \langle N, H|_h, P|_h, (\succsim_i |_h) \rangle$ where

- $H|_h$ is the set of sequences h' such that $(h, h') \in H$.
- $P|_h$ is defined by $P|_h(h') = P(h, h')$ for each $h' \in H|_h$.
- $\succsim_i |_h$ is defined by $h' \succsim_i |_h h'' \iff (h, h') \succsim_i (h, h'') \in Z$.

Notation 6.3 (pg.97)**.** Given strategy $s_i \in S_i$ and $h \in H \in \Gamma$, $s_i|_h$ represents the **strategy that** s_i **induces in the subgame** $\Gamma(h)$. That's, for each $h' \in H_h$

$$s_i|_h(h') \equiv s_i(h, h')$$

Notation 6.4. Let O_h denote the **outcome function of** $\Gamma(h)$, that's, for all $h' \in H|_h$,

$$O_h(h') \equiv O(h, h')$$

Definition 6.13 (97.2)**.** A **subgame perfect equilibrium of an extensive game with perfect information** $\Gamma = \langle N, H, P, (\succsim_i) \rangle$ is a strategy profile s^* such that for every player $i \in N$ and every nonterminal history $h \in H \backslash Z$ for which $P(h) = i$ we have

$$O_h(s^*_{-i}|_h, s^*_i|_h) \succsim_i |_h O_h(s^*_{-i}|_h, s_i|_h)$$

for every strategy s_i of player i in the subgame $\Gamma(h)$.

Definition 6.14 (pg.97)**.** Equivalently, define SPNE to be a strategy profile s^* in Γ for which for any history $h \in H$ the strategy profile $s^*|_h$ is a Nash equilibrium of the subgame $\Gamma(h)$.

Remark 6.4 (pg. 97)**.** The notion of SPNE requires the action prescribed by each player's strategy to be optimal, given other players' strategies, after *every* history.

Proposition 6.1 (99.2)**.** Every finite extensive game with perfect information has a subgame perfect equilibrium.

7 Lecture 7. Extensive Form Games: Examples

8 Lecture 8. Repeated Games

9 Lecture 9. Game with Incomplete Information

10 Lecture 10. Game with Incomplete Information II

11 Lecture 11. Auctions