ECO375: Review Notes

Applied Econometrics I

Tianyu Du

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1 Slide 4: Simple & Multiple Regression - Estimation

1.1 Regression Model

Assumption 1.1. Assuming the population follows

$$y = \beta_0 + \beta_1 x + u$$

and assume that x *causes* y.

1.2 OLS

$$\min_{\vec{\beta}} \sum_i (y_i - \hat{y}_i)^2$$

With FOC:

$$\sum_i (y_i - \hat{y}_i) = 0$$

$$\sum_i x_{ij}(y_i - \hat{y}_i) = 0, \ \forall j$$

Remark 1.1. Both $\hat{\beta}_0$ and $\hat{\beta}_j$ are functions of *random variables* and therefore themselves *random* with *sampling distribution*. And the estimated coefficients are random up to random sample chosen.

Property 1.1. Properties of OLS estimators

- **Unbiased** $\mathbb{E}[\hat{\beta}|X] = \beta$
- **Consistent** $\hat{\beta} \to \beta$ as $n \to \infty$
- **Efficient/Good** min variance.

Definition 1.1. The **Simple Coefficient of Determination**

$$R^2 = \frac{SSE}{SST}$$

and $SS\underline{Total} = SS\underline{Explained} + SS\underline{Residual}$

$$\sum_i (y_i - \overline{y})^2 = \sum_i (\hat{y}_i - \overline{y})^2 + \sum_i (y_i - \hat{y}_i)^2$$

Proposition 1.1 (Logarithms)**.** Interpretation with logarithmic transformation.

- $\ln y = \alpha + \beta \ln y + u$: $\underline{x \text{ increases by } 1\%, y \text{ increases by } \beta\%}$.
- $\ln y = \alpha + \beta x + u$: $\underline{x \text{ increases by 1 unit}, y \text{ increases by } 100\beta\%}$.
- $y = \alpha + \beta \ln x + u$: $\underline{x \text{ increases by } 1\%, y \text{ increases by } 0.01\beta \text{ unit.}}$

Assumption 1.2. Simple regression model assumptions

1. Model is linear in parameter.
2. Random samples $\{(x_i, y_i)\}_{i=1}^n$.
3. Sample outcomes $\{x_i\}_{i=1}^n$ are not the same.
4. $\mathbb{E}(u|x) = 0$ conditional on random sample x.
5. Error is homoskedastic. $Var(u|x) = \sigma^2$ for all x.

Benefits of MLR compared with SLR

- More accurate causal effect estimation.
- More flexible function forms.
- Could explicitly include more predictors so $\mathbb{E}(u|X) = 0$ is easier to be satisfied.
- MLR4 is less restrictive than SLR4.

Property 1.2. MLR OLS residual satisfies

$$\sum_i \hat{u}_i = 0$$

$$\sum_i x_{ji}\hat{u}_i = 0, \ \forall i \in \{1, 2, \ldots, k\}$$

Property 1.3. MLR OLS estimators $\hat{\beta}_0, \hat{\beta}_1, \ldots, \hat{\beta}_k$ pass through the average point.

$$\overline{y} = \hat{\beta}_0 + \hat{\beta}_1\overline{x}_1 + \cdots + \hat{\beta}_k\overline{x}_k$$

Proof. ■

1.3 Partialling Out

1.3.1 Steps

1. Regress x_1 on $x_2, x_3, \ldots, x_K$ and calculate the residual $\widetilde{r}_1$.
2. Regress y on $\widetilde{r}_1$ with simple regression and find the estimated coefficient $\hat{\lambda}_1$.
3. Then the multiple regression coefficient estimator $\hat{\beta}_1$ is

$$\hat{\beta}_1 = \hat{\lambda}_1 = \frac{\sum_i y_i\widetilde{r}_{1i}}{\sum_i (\widetilde{r}_{1i})^2}$$

Proof. ■

1.3.2 Interpretation

This OLS estimator only uses the unique variance of one independent variable. And the parts of variation correlated with other independent variables is partialled out.

Assumption 1.3. Multiple Regression Assumptions

1. (MLR1) The model is linear in parameters.
2. (MLR2) Random sample from population $\{(x_{1i}, \ldots x_{ki}, y_i\}_{i=1}^n$.

3. (MLR3) No perfect multicollinearity.
4. (MLR4) Zero expected error conditional on population slice given by X.

$$\mathbb{E}(u|X) = \mathbb{E}(u|x_1, x_2, \ldots, x_k) = 0$$

5. (MLR5) Homoskedastic error conditional on population slice given by X.

$$Var(u|X) = \sigma^2$$

6. (MLR6, *strict assumption*) Normally distributed error

$$u \sim \mathcal{N}(0, \sigma^2)$$

1.4 Omitted Variable Bias

Suppose population follows the *real model*

$$y_i = \beta_0 + \beta_1 x_{1i} + \beta_2 x_{2i} + \cdots + \beta_k x_{ki} + u_i \tag{1}$$

Consider the *alternative model*, and x_k is omitted, which is assumed to be relevant.

$$y_i = \beta_0 + \beta_1 x_{1i} + \beta_2 x_{2i} + \cdots + \beta_{k-1} x_{(k-1)i} + r_i \tag{2}$$

and use the partialling-out result on the second regression we have

$$\tilde{\beta}_1 = \frac{\sum_i \tilde{r}_{1i} y_i}{(\tilde{r}_{1i})^2}$$

where $\tilde{r_{1i}} = x_{1i} - \tilde{\alpha}_0 - \tilde{\alpha}_2 x_{2i} - \cdots - \tilde{\alpha}_{k-1} x_{(k-1)i}$

$$\tilde{\beta}_1 = \hat{\beta}_1 + \hat{\beta}_k \frac{\sum(\tilde{r}_{1i} x_{ki})}{\sum(\tilde{r}_{1i})^2} \tag{3}$$

and take the expectation

$$\mathbb{E}(\tilde{\beta}_1|X) = \beta_1 + \tilde{\delta}_1 \beta_k$$
$$Bias(\tilde{\beta}_1) = \tilde{\delta}_1 \beta_k$$

Conclusion the sign of bias depends on $cov(x_1, x_k)$ and β_k.

Proof. TODO ■

2 Matrix Differentiation*

$$\mathbf{y} = \mathbf{A}\mathbf{x} \implies \frac{\partial \mathbf{y}}{\partial \mathbf{x}} = \mathbf{A} \tag{4}$$

Let $\alpha = \mathbf{y}'\mathbf{A}\mathbf{x}$, notice that $\alpha \in \mathbb{R}$, then

$$\frac{\partial \alpha}{\partial \mathbf{x}} = \mathbf{y}'\mathbf{A} \tag{5}$$

$$\frac{\partial \alpha}{\partial \mathbf{y}} = \mathbf{x}'\mathbf{A}' \tag{6}$$

Consider special case $\alpha = \mathbf{x}'\mathbf{A}\mathbf{x}$, then

$$\frac{\partial \alpha}{\partial \mathbf{x}} = \mathbf{x}'\mathbf{A} + \mathbf{x}'\mathbf{A}' \tag{7}$$

and if $\mathbf{A}$ is symmetric,

$$\frac{\partial \alpha}{\partial \mathbf{x}} = 2\mathbf{x}'\mathbf{A} \tag{8}$$

3 Multiple Regression in Matrices

3.1 The Model

Predictor

$$\mathbf{X} \in \mathbb{M}_{n\times(k+1)}(\mathbb{R})$$

where n is the number of observations and k is the number of features.

$$\mathbf{X} = \begin{bmatrix} 1 & x_{11} & \dots & x_{1k} \\ 1 & x_{21} & \dots & x_{2k} \\ \vdots & & & \\ 1 & x_{n1} & \dots & x_{nk} \end{bmatrix}_{n\times(k+1)}$$

Model

$$\mathbf{y} = \mathbf{X}\vec{\beta} + \mathbf{u}$$

First order condition for OLS

$$\begin{aligned} &\mathbf{X}'\hat{u} = \mathbf{0} \in \mathbb{R}^{k+1} \\ \iff &\mathbf{X}'(\mathbf{y} - \mathbf{X}\hat{\beta}) = \mathbf{0} \in \mathbb{R}^{k+1} \end{aligned}$$

Estimator

$$\hat{\beta} = (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{y}$$

Proof. From the first order condition for the OLS estimator

$$\begin{aligned} \mathbf{X}'(\mathbf{y} - \mathbf{X}\hat{\beta}) = \mathbf{0} \\ \implies \mathbf{X}'\mathbf{y} - \mathbf{X}'\mathbf{X}\hat{\beta} = \mathbf{0} \\ \implies \mathbf{X}'\mathbf{y} = \mathbf{X}'\mathbf{X}\hat{\beta} \\ \implies \hat{\beta} = (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{y} \end{aligned}$$

and note that $(\mathbf{X}'\mathbf{X})$ is guaranteed to be invertible by assumption *no perfect multi-collinearity.* ■

Sum Squared Residual

$$SSR(\hat{\beta}) = \hat{u}' \cdot \hat{u} = (\mathbf{y} - \mathbf{X}\hat{\beta})' \cdot (\mathbf{y} - \mathbf{X}\hat{\beta})$$

3.2 Variance Matrix

Consider

$$\begin{aligned} \vec{z}_t = [z_{1t}, z_{2t}, \dots z_{nt}]' \\ \vec{z}_s = [z_{1s}, z_{2s}, \dots z_{ns}]' \end{aligned}$$

Notice that the variance and covariance are defined as

$$\begin{aligned} Var(\vec{z}_t) = \mathbb{E}[(\vec{z}_t - \mathbb{E}[\vec{z}_t])^2] \\ Cov(\vec{z}_t, \vec{z}_s) = \mathbb{E}[(\vec{z}_t - \mathbb{E}[\vec{z}_t])(\vec{z}_s - \mathbb{E}[\vec{z}_s])] \end{aligned}$$

The **variance matrix** of $\mathbf{z} = [z_1, z_2, \dots, z_n]$ is given by

$$\begin{aligned} Var(\mathbf{z}) &= \begin{bmatrix} Var(z_1) & Cov(z_1, z_2) & \dots & Cov(z_1, z_n) \\ Cov(z_2, z_1) & \dots & & \\ \vdots & & & \\ Cov(z_n, z_1) & \dots & \dots & Var(z_n) \end{bmatrix} \\ &= \begin{bmatrix} \mathbb{E}[(z_1 - \overline{z}_1)^2] & \mathbb{E}[(z_1 - \overline{z}_1)(z_2 - \overline{z}_2)] & \dots \\ \mathbb{E}[(z_2 - \overline{z}_2)(z_1 - \overline{z}_1)] & \dots & \\ \vdots & & \\ \mathbb{E}[(z_n - \overline{z}_n)(z_1 - \overline{z}_1)] & \dots & \mathbb{E}[(z_n - \overline{z}_n)^2] \end{bmatrix} \\ &= \mathbb{E}[(\mathbf{z} - \mathbb{E}[\mathbf{z}])_{n\times 1} \cdot (\mathbf{z} - \mathbb{E}[\mathbf{z}])'_{1\times n}] \in \mathbb{M}_{n\times n} \end{aligned}$$

In the special case $\mathbb{E}[\vec{z}] = \vec{0}$, variance is reduced to

$$Var(\mathbf{z}) = \mathbb{E}[\mathbf{z} \cdot \mathbf{z}']$$

Residual Since residual u_i are $i.i.d$ with variance σ^2, the variance matrix of $\mathbf{u}$ is

$$Var(\mathbf{u}) = \mathbb{E}[\mathbf{u} \cdot \mathbf{u}'] = \sigma^2 \mathbf{I}_n$$

Estimator If $\hat{\beta}$ is unbiased, $\mathbb{E}[\hat{\beta}|\mathbf{X}] = \vec{\beta}$, then

$$Var(\hat{\beta}|\mathbf{X}) = \mathbb{E}[(\hat{\beta} - \vec{\beta}) \cdot (\hat{\beta} - \vec{\beta})'|\mathbf{X}] \in \mathbb{M}_{(k+1)\times(k+1)}$$

4 Slide 7

4.1 Assumptions (MLRs) in Matrix Form

E.1. *linear in parameter*

$$\mathbf{y} = \mathbf{X}\vec{\beta} + \mathbf{u}$$

E.2. *no perfect multi-collinearity*

$$rank(\mathbf{X}) = k + 1$$

E.3. Error has expected value of $\mathbf{0}$ conditional on $\mathbf{X}$.

$$\mathbb{E}[\mathbf{u}|\mathbf{X}] = \mathbf{0}$$

E.4. Error $\mathbf{u}$ is *homoscedastic*.

$$Var(\mathbf{u}|\mathbf{X}) = \sigma^2 \mathbf{I}_n$$

E.5. *Normally distributed* error $\mathbf{u}$.

$$\mathbf{u} \sim \mathcal{N}(\mathbf{0}, \sigma^2 \mathbf{I}_n)$$

Theorem 4.1.