MAT237: Multivariable Calculus

Tianyu Du

February 16, 2019

Contents

1	limits, continuity, and related topics
2	Differentiation and related topics
	.1
	.2
	.3
	.4
	.5
	.6
	.7
	.8 Optimization
3	The Implicit and Inverse Function Theorems
	.1 The Implicit Function Theorem I
	.2 Geometric content of the Implicit Function Theorem
	.3 Transformations, and the Inverse Function Theorem
4	ntegration
	.1 Basics
	.2 Integration on Higher Dimensions
	.3 Iterated Integrals

- 1 Limits, continuity, and related topics
- 2 Differentiation and related topics
- 2.1
- 2.2
- 2.3
- 2.4
- 2.5
- 2.6
- 2.7

2.8 Optimization

Theorem 2.8.1. Let $S \subset \mathbb{R}^n$ be an open set and $f, g : S \to \mathbb{R}$ be C^1 functions. If \mathbf{x} is a *local extremal* satisfying $g(\mathbf{x}) = 0$, and $\nabla g(\mathbf{x}) \neq 0$, then

$$\exists \lambda \in \mathbb{R} \ s.t. \begin{cases} \nabla f(\mathbf{x}) = \lambda \nabla g(\mathbf{x}) \\ g(\mathbf{x}) = 0 \end{cases}$$
 (2.8.1)

Lemma 2.8.1. $\nabla g(\mathbf{x})$ is orthogonal to the constraint set $g^{-1}(0)$.

Proposition 2.8.1. Equations (2.8.1) $\implies \nabla f(\mathbf{x}) \perp g^{-1}(0)$ at \mathbf{x} .

Theorem 2.8.2. Let $S \subseteq \mathbb{R}^n$ be an open set, and $f, \{g_i\}_{i=1}^k : S \to \mathbb{R}$ be C^1 functions. Define $\mathbf{g}(\mathbf{x}) : \mathbb{R}^n \to \mathbb{R}^k \equiv (g_1(\mathbf{x}), g_2(\mathbf{x}), \dots, g_k(\mathbf{x}))$.

If $\mathbf{x} \in S$ is a local extremal of f such that $\mathbf{g}(\mathbf{x}) = \mathbf{0}$, and $\{\nabla g_i(\mathbf{x})\}$ are <u>linearly independent</u> (i.e. $rank(D\mathbf{g}(\mathbf{x})) = k$), then

$$\exists \boldsymbol{\lambda} \in \mathbb{R}^k \ s.t. \begin{cases} \nabla f(\mathbf{x}) = \boldsymbol{\lambda}^T D \mathbf{g}(\mathbf{x}) \\ \mathbf{g}(\mathbf{x}) = \mathbf{0} \end{cases}$$
 (2.8.2)

Remark 2.8.1. Procedure of optimization on open sets:

- (i) Find all critical points.
- (ii) Find optimizers among critical points.

Remark 2.8.2. Procedure of optimization with *inequality constraints*:

- (i) Find critical points without the constraints.
- (ii) Find critical points on the constraints.
- (iii) Find optimizers among candidates.

3 The Implicit and Inverse Function Theorems

3.1 The Implicit Function Theorem I

Theorem 3.1.1 (Implicit Function Theorem). Let $S \subseteq \mathbb{R}^{n+k}$ be an open set, and function $F: S \to \mathbb{R}^k$ be a C^1 function. Suppose there exists point $\mathbf{a} \in \mathbb{R}^n$, $\mathbf{b} \in \mathbb{R}^k$ such that

$$F(\mathbf{a}, \mathbf{b}) = \mathbf{0} \tag{3.1.1}$$

If

$$det(D_{\mathbf{y}}(F(\mathbf{a}, \mathbf{b}))) \neq 0 \tag{3.1.2}$$

then there exists $r_0, r_1 > 0$ and a C^1 function $\mathbf{f} : \mathbb{R}^n \to \mathbb{R}^k$ such that

$$\forall \mathbf{x} \in \mathcal{B}(r_0, \mathbf{a}), \ \mathbf{f}(\mathbf{x}) \in \mathcal{B}(r_1, \mathbf{b}) \land F(\mathbf{x}, \mathbf{f}(\mathbf{x})) = \mathbf{0}$$
(3.1.3)

and define $\mathbf{y} \equiv \mathbf{f}(\mathbf{x})$, the derivative of \mathbf{f} can be found as

$$D\mathbf{f}(\mathbf{x}) = -[D_{\mathbf{y}}F(\mathbf{x}, \mathbf{y})]^{-1}D_{\mathbf{x}}F(\mathbf{x}, \mathbf{y})$$
(3.1.4)

Remark 3.1.1. Procedure to prove solvability of non-linear equations

$$\mathbf{F}(\mathbf{x}, \mathbf{y}) = \mathbf{0} \tag{3.1.5}$$

near (\mathbf{a}, \mathbf{b}) .

- (i) Verify $\mathbf{F}(\mathbf{a}, \mathbf{b}) = \mathbf{0}$.
- (ii) Assert

$$det(D_{\mathbf{y}}\mathbf{F}(\mathbf{a}, \mathbf{b})) \neq 0 \tag{3.1.6}$$

(iii) Approximate solution y = f(x) using

$$\mathbf{f}(\mathbf{x} + \mathbf{h}) \approx \mathbf{a} + D\mathbf{f}(\mathbf{a})\mathbf{h} \tag{3.1.7}$$

$$= \mathbf{a} - [D_{\mathbf{v}}\mathbf{F}(\mathbf{a}, \mathbf{b})]^{-1}D_{\mathbf{x}}\mathbf{F}(\mathbf{a}, \mathbf{b})$$
(3.1.8)

3.2 Geometric content of the Implicit Function Theorem

Definition 3.2.1. Let $S \subseteq \mathbb{R}^n$ and $\mathbf{a} \in S$. S is singular at \mathbf{a} if

$$\forall r > 0 \ S \cap \mathcal{B}(r, \mathbf{a}) \text{ cannot be represented as a } C^1 \text{ graph.}$$
 (3.2.1)

S is **regular** at **a** is its not singular there.

Theorem 3.2.1 (k dimensional manifold as level set). Let $U \subseteq \mathbb{R}^n$ and let $\mathbf{F}: U \to \mathbb{R}^{n-k}$ be a C^1 function.

$$S \equiv \mathbf{F}^{-1}(\mathbf{0}) \tag{3.2.2}$$

Let $\mathbf{a} \in U$, if

$$rank(D\mathbf{F}(\mathbf{a})) = n - k \tag{3.2.3}$$

then $\exists r > 0$ such that the level set of F near a

$$\mathcal{B}(r,\mathbf{a}) \cap S \tag{3.2.4}$$

can be represented as a C^1 graph.

Theorem 3.2.2 (k dimensional manifold as parameterization). Let $T \subseteq \mathbb{R}^k$ and let $\mathbf{f}: U \to \mathbb{R}^n$ be a C^1 function.

$$S \equiv \mathbf{f}(T) \tag{3.2.5}$$

Let $\mathbf{t} \in T$, if

$$rank(\mathbf{f}(\mathbf{t})) = k \tag{3.2.6}$$

then $\exists r > 0$ such that the parameterization of f near t

$$\mathbf{f}(T \cap \mathcal{B}(r, \mathbf{t})) \tag{3.2.7}$$

can be represented as a C^1 graph.

3.3 Transformations, and the Inverse Function Theorem

Example 3.3.1 (Polar coordinate in \mathbb{R}^2). Let

$$U \equiv \{(r,\theta) : r > 0 \land \theta \in (-\pi,\pi)\}$$

$$(3.3.1)$$

$$V \equiv \mathbb{R}^2 \setminus \{(x,0) : x \le 0\} \tag{3.3.2}$$

Define $\mathbf{f}: U \to V$ as

$$\mathbf{f}(r,\theta) \equiv \begin{pmatrix} r\cos(\theta) \\ r\sin(\theta) \end{pmatrix} \tag{3.3.3}$$

Example 3.3.2 (Spherical coordinate in \mathbb{R}^3). Define

$$\mathbf{f}(r,\theta,\varphi) = \begin{pmatrix} r\cos(\theta)\sin(\varphi) \\ r\sin(\theta)\sin(\varphi) \\ r\cos(\varphi) \end{pmatrix}$$
(3.3.4)

Example 3.3.3 (Cylindrical coordinate in \mathbb{R}^3). Define

$$\mathbf{f}(r,\theta,z) = \begin{pmatrix} r\cos(\theta) \\ r\sin(\theta) \\ z \end{pmatrix}$$
 (3.3.5)

Theorem 3.3.1 (Inverse Function Theorem). Let U and V be open subsets in \mathbb{R}^n , and $\mathbf{f}: U \to V$. Let $\mathbf{a} \in U$ and define $\mathbf{b} \equiv \mathbf{f}(\mathbf{a}) \in V$. If

$$det(D\mathbf{f}(\mathbf{a})) \neq 0 \tag{3.3.6}$$

then there exists $M\subseteq U$ and $N\subseteq V$ such that

- (i) $\mathbf{a} \in M$ and $\mathbf{b} \in N$,
- (ii) \mathbf{f} is bijective between M and N,
- (iii) $\mathbf{f}^{-1}: N \to M \text{ is } C^1,$

and for all $\mathbf{x} \in M$ such $\mathbf{y} \equiv \mathbf{f}(\mathbf{x}) \in N$,

$$D\mathbf{f}^{-1}(\mathbf{y}) = [D\mathbf{f}(\mathbf{x})]^{-1} \tag{3.3.7}$$

4 Integration

4.1 Basics

Theorem 4.1.1 (Properties of infimum and supremum). Let $A \subseteq \mathbb{R}^n$ and $A \neq \emptyset$, and $f, g : A \to \mathbb{R}$ are bounded functions. Let m and M denote the infimum and supremum respectively, then

- (i) $m_A f + m_A g \le m_A (f + g) \le M_A (f + g) \le M_A f + M_A g$
- (ii) If $A' \subseteq A$, then $m_A f \leq m_{A'} f \leq M_{A'} f \leq M_A f$
- (iii) If $f(\mathbf{x}) \leq g(\mathbf{x}) \ \forall \mathbf{x} \in A$, then $m_A f \leq m_A g$ and $M_A f \leq M_A g$
- (iv) $|M_A f| \leq M_A |f|$
- (v) $M_A|f| m_A|f| \le M_A f m_A f$
- (vi) $\forall c \in \mathbb{R}, M_A(cf) m_A(cf) = |c|(M_A f m_A f)$
- (vii) $M_A f m_A f = \sup\{f(x) f(y) : x, y \in A\}$

4.2 Integration on Higher Dimensions

Definition 4.2.1. A rectangle $\mathcal{R} \subseteq \mathbb{R}^n$ is defined as

$$\mathcal{R} \equiv \prod_{i=1}^{n} [a_i, b_i] \tag{4.2.1}$$

where $a_i, b_i \in \mathbb{R}$ and $a_i < b_i$.

Definition 4.2.2. A partition P of rectangle $\mathcal{R} = \prod_{i=1}^n [a_i, b_i]$ is a list of n finite and increasing list of real numbers

$$P = \{L_1, L_2, \dots, L_n\} \tag{4.2.2}$$

where $L_i = \{e_j\}_{j=0}^{T_i}$ such that

$$a_i = e_0 < e_1 < \dots < e_{T_i} = b_i$$
 (4.2.3)

and such partition induces a set of rectangles (boxes) $\mathcal{B}(P) \equiv \{B_j\}_{j=1}^J \subseteq \mathcal{R}$.

Definition 4.2.3. Let P and P' be two partitions of \mathcal{R} . Then P' is a **refinement** of P if

$$\forall B_j \in \mathcal{B}(P), B_j' \in \mathcal{B}(P') \quad B_j' \subseteq B_j \vee B_j'^{int} \cap B_j^{int} = \emptyset$$
(4.2.4)

Definition 4.2.4. Define the **volume** of rectangle $\mathcal{R} = \prod_{i=1}^n [a_i, b_i]$ as

$$V^{n}(\mathcal{R}) \equiv \prod_{i=1}^{n} (b_i - a_i)$$

$$(4.2.5)$$

Definition 4.2.5. The lower Riemann sum of f with partition P on \mathcal{R} is defined as

$$L_P f \equiv \sum_{B_j \in \mathcal{B}(P)} \inf_{\mathbf{x} \in B_j} f(\mathbf{x}) V^n(B_j)$$
(4.2.6)

and the upper Riemann sum is defined as

$$U_P f \equiv \sum_{B_i \in \mathcal{B}(P)} \sup_{\mathbf{x} \in B_j} f(\mathbf{x}) V^n(B_j)$$
(4.2.7)

Definition 4.2.6. The upper integral and lower integral of f on \mathcal{R} are defined as

$$\bar{I}_{\mathcal{R}}f \equiv \inf_{\mathcal{P}} U_{\mathcal{P}}f \tag{4.2.8}$$

$$\underline{I}_{\mathcal{R}}f \equiv \sup_{P} L_{P}f \tag{4.2.9}$$

Definition 4.2.7. A bounded real-valued function f defined on \mathcal{R} is **integrable** if

$$\underline{I}_{\mathcal{R}}f = \bar{I}_{\mathcal{R}}f \tag{4.2.10}$$

and the integral is defined as

$$\int \cdots \int_{\mathcal{R}} f \ dV^n \equiv \underline{I}_{\mathcal{R}} f = \bar{I}_{\mathcal{R}} f \tag{4.2.11}$$

Lemma 4.2.1. Let f be a bounded real-valued function defined on \mathcal{R} , f is integrable if and only if $\forall \epsilon > 0$, there exists a partition P of \mathcal{R} such that

$$U_P f - L_P f < \epsilon \tag{4.2.12}$$

Theorem 4.2.1. Let f and g be two integrable functions on $\mathcal{R} \subseteq \mathbb{R}^n$, let $c \in \mathbb{R}$,

- (i) $f + g : \mathcal{R} \to \mathbb{R}$ is integrable and $\int_{\mathcal{R}} (f + g) = \int_{\mathcal{R}} f + \int_{\mathcal{R}} g$
- (ii) $c \cdot f$ is integrable and $\int_{\mathcal{R}} c \cdot f = c \int_{\mathcal{R}} f$
- (iii) $f(\mathbf{x}) \ge g(\mathbf{x}) \ \forall \mathbf{x} \in \mathcal{R} \implies \int_{\mathcal{R}} f \ge \int_{\mathcal{R}} g$
- (iv) |f| is integrable and $|\int_R f| \leq \int_R |f|$

Definition 4.2.8. Let $S \subseteq \mathbb{R}^n$ be a bounded set, and there exists rectangle \mathcal{R} covers S, the indicator function of S is $\chi_S : \mathcal{R} \to \{0,1\}$, defined as

$$\chi_S(\mathbf{x}) \equiv \mathbb{I}(\mathbf{x} \in S) \tag{4.2.13}$$

Definition 4.2.9. Let $S \subseteq \mathbb{R}^n$ be a bounded set, and there exists rectangle \mathcal{R} covers S. Let $f: \mathcal{R} \to \mathbb{R}$ be a bounded function, then f is **integrable on** S if $\chi_S f$ is integrable on \mathcal{R} . And

$$\int \cdots \int_{S} f \ dV^{n} \equiv \int \cdots \int_{\mathcal{R}} \chi_{S} f \ dV^{n} \tag{4.2.14}$$

Definition 4.2.10. Let $Z \subseteq \mathbb{R}^n$, Z has **zero content** if for all $\epsilon > 0$, there exists a <u>finite</u> set of rectangles $\{R_\ell\}_{\ell=1}^L$ covers Z and

$$\sum_{\ell=1}^{L} V^n(R_\ell) < \epsilon \tag{4.2.15}$$

Proposition 4.2.1. Let $Z \subseteq \mathbb{R}^n$ has zero content, then

- (i) For any $Z' \subseteq Z$, Z' has zero content.
- (ii) Finite union of content zero sets has zero content.
- (iii) Let $f:[a,b]\to\mathbb{R}$ be an integrable function, it's graph $\{(x,f(x)):x\in[a,b]\}$ has zero content.
- (iv) Let $\mathbf{f}:[a,b]\to\mathbb{R}^2$ be a C^1 function, the parameterization $\mathbf{f}([a,b])$ has zero content.

Theorem 4.2.2. Let \mathcal{R} be a rectangle in \mathbb{R}^n and f is integrable on \mathcal{R} if

$$\{\mathbf{x} \in \mathcal{R} : f \text{ is discontinuous at } \mathbf{x}\}$$
 (4.2.16)

has zero content.

Proposition 4.2.2 (Folland 4.22). Suppose $Z \subseteq \mathbb{R}^n$ has zero content. If $f : \mathbb{R}^n \to \mathbb{R}$ is bounded, then f is integrable on Z and $\int_Z f \ dV^n = 0$.

4.3 Iterated Integrals

Theorem 4.3.1 (Fubini's Theorem). Let $\mathcal{R} = [a,b] \times [c,d] \subseteq \mathbb{R}^2$ and $f: \mathcal{R} \to \mathbb{R}$ is bounded. Assuming that

- (i) f is integrable on \mathcal{R} .
- (ii) for each $y \in [c, d]$, the function $f_y(x) \equiv f(x, y)$ is integrable on [a, b].
- (iii) Define $g(y) \equiv \int_a^b f(x,y) dy$ is integrable on [c,d].

Then

$$\iint_{\mathcal{R}} f \ dA = \int_{c}^{d} \left(\int_{a}^{b} f(x, y) \ dx \right) dy \tag{4.3.1}$$

Proposition 4.3.1. Let $S \subseteq \mathbb{R}^n$ be an unbounded set, and $f: S \to \mathbb{R}$. Then improper integral $\int \cdots \int_S f \ d^n \mathbf{x}$ is absolutely convergent on \mathbb{R}^n if and only if $\int \cdots \int_{\mathbb{R}^n} \chi_S f \ d^n \mathbf{x}$ is absolutely convergent.