

ECO326 Advanced Microeconomic Theory

A Course in Game Theory

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Github Page: https://github.com/TianyuDu/Spikey_UofT_Notes

Note Page: TianyuDu.com/notes

Readme this note is based on the course content of *ECO326 Advanced Microeconomics - Game Theory*, this note contains all materials covered during lectures and mentioned in the course syllabus. However, notations, statements of theorems and proofs are following the book *A Course in Game Theory* by Osborne and Rubinstein, so they might be, to some extent, more mathematical than the required text for ECO326, *An Introduction to Game Theory*.

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1 Lecture 1. Jan. 7 2019

Games and Dominant Strategies

Game Theory Choice environment where individual choices impact others.

	W	S
W	$(1 - c, 1 - c)$	$(1 - c, 1)$
S	$(1, 1 - c)$	$(0, 0)$

Figure 1.1: Payoff Matrix for Example 1

Example 1.1.

Suppose $c \in (0, 1)$. In this game,

i $N = \{i, j\}$,

ii $A_i = A_j = \{W, S\}$,

Definition 1.1 (pg.7). A **preference relation** is a complete reflexive and transitive binary relation.

Definition 1.2 (11.1, lec.1). A **(strategic) game** consists of

i a finite set of **players** N , with $|N| \geq 2$.

ii for each player $i \in N$, an **action set** $A_i \neq \emptyset$.

iii for each player $i \in N$, a **preference relation** \succsim_i defined on $A \equiv \prod_{i \in N} A_i$.

and can be written as a triple $\langle N, (A_i), (\succsim_i) \rangle$.

Definition 1.3. An **action profile** is a n -tuple of actions $a_i \in A_i$ for each player $i \in N$ and denoted as

$$(a_i)_{i \in N} \text{ or } (a_i)$$

The **action profile space** is defined as

$$A \equiv \prod_{i \in N} A_i$$

Definition 1.4 (Equivalent definition of game). For each player $i \in N$ we can define a utility function, $u_i : A \rightarrow \mathbb{R}$ such that

$$\forall (a_i), (a_i)' \in A, u_i((a_i)) \geq u_i((a_i)') \iff (a_i) \succsim_i (a_i)' \quad (1.1)$$

So the game can be defined as a triple $\langle N, (A_i), (u_i) \rangle$.

Definition 1.5. Action $a_i \in A_i$ is **strictly dominated** by action $\tilde{a}_i \in A_i$ if

$$\forall a_{-i} \in A_{-i}, u_i(a_i, a_{-i}) < u_i(\tilde{a}_i, a_{-i})$$

And a_i is **weakly dominated** by \tilde{a}_i if

$$\forall a_{-i} \in A_{-i}, u_i(a_i, a_{-i}) \leq u_i(\tilde{a}_i, a_{-i})$$

and

$$\exists a_{-i} \in A_{-i}, u_i(a_i, a_{-i}) < u_i(\tilde{a}_i, a_{-i})$$

Corollary 1.1 (Consequence of RCT). It is irrational to play strictly dominated actions. So rational choice theory suggests a player would never play strictly dominated strategies.

Definition 1.6. Action $a_i \in A_i$ is **strictly(weakly) dominant** if it strictly(weakly) dominates all other actions.

Definition 1.7. Action $a_i \in A_i$ is **strictly(weakly) dominated** if there exists another strategy strictly(weakly) dominates a_i .

Definition 1.8. A strategic game $\langle N, (A_i), (\succeq_i) \rangle$ is **finite** if for every $i \in N$, A_i is finite.

2 Lecture 2. Jan. 14 2019

Iterated Elimination and Rationalizability

2.1 Iterated Elimination of Strictly Dominated Strategies(Actions)

Definition 2.1 (IESD). Given the initial game,

$$G_0 = \langle N, (A_i^0), (u_i) \rangle$$

At stage $k \in \mathbb{N}$,

$$G_k = \langle N, (A_i^k), (u_i) \rangle$$

In stage k , for all $i \in N$, find the set of strictly dominated actions, $D_i^k \subsetneq A_i^k$.

i) If $\forall i \in N$ s.t. $D_i^k = \emptyset$, conclude the profile

$$(A_i^k)$$

to be the **set of action profiles survive from IESD**.

ii) If $\exists i \in N$ s.t. $D_i^k \neq \emptyset$, define

$$\forall i \in N, A_i^{k+1} \leftarrow A_i^k \setminus D_i^k$$

Example 2.1 (Hotelling Model of Politics). Players maximize their votes by choosing where to stand along a natural number line.

- Player $N = \{1, 2\}$
- Action set $A_i = \{1, \dots, M\}$, with $2 \nmid M$ and $M > 3$.
- Payoff

$$u_i(a_i, a_{-i}) = \begin{cases} a_i + \frac{1}{2}(a_{-i} - a_i - 1) & \text{if } a_i < a_{-i} \\ \frac{M}{2} & \text{if } a_i = a_{-i} \\ M - [a_{-i} + \frac{1}{2}(a_i - a_{-i} - 1)] & \text{if } a_i > a_{-i} \end{cases} \quad (2.1)$$

Claim i. $a_i = 1$ is strictly dominated by $a_i = 2$.

Proof.

$$u_i(a_i = 1, a_{-i}) = \begin{cases} \frac{M}{2} & \text{if } a_{-i} = 1 \\ \frac{a_{-i}}{2} & \text{if } a_{-i} > 1 \end{cases} \quad (2.2)$$

$$u_i(a_i = 2, a_{-i}) = \begin{cases} M - 1 & \text{if } a_{-i} = 1 \\ \frac{M}{2} & \text{if } a_{-i} = 2 \\ \frac{a_{-i}}{2} + \frac{1}{2} & \text{if } a_{-i} > 2 \end{cases} \quad (2.3)$$

■

Claim ii. $\lfloor \frac{n}{2} \rfloor + 1$ is the only action survives.

Proof. Similarly, we can eliminate all edge-values iteratively. ■

Definition 2.2. For each $i \in N$, the **best-response function** of this player is a correspondence $Br_i : A_{-i} \rightrightarrows A_i$ defined as

$$Br_i(a_{-i}) \equiv \{a_i \in A_i : u_i(a_i, a_{-i}) \geq u_i(a'_i, a_{-i}) \ \forall a'_i \in A_i\} \quad (2.4)$$

Definition 2.3. A **belief** of player i (about the actions of the other players) is a probability measure, α_i , on $A_{-i} \equiv \prod_{j \in N \setminus \{i\}} A_j$.

Remark 2.1. α_i defines a distribution of a_{-i} .

Definition 2.4. a_i is a best response to the belief α_i if

$$\forall a'_i \in A_i, \sum_{a_{-i} \in A_{-i}} u_i(a_i, a_{-i}) \alpha_i(a_{-i}) \geq \sum_{a_{-i} \in A_{-i}} u_i(a'_i, a_{-i}) \alpha_i(a_{-i}) \quad (2.5)$$

or, more generally,

$$\forall a'_i \in A_i, \mathbb{E}[u_i(a_i, a_{-i}) | \alpha_i] \geq \mathbb{E}[u_i(a'_i, a_{-i}) | \alpha_i] \quad (2.6)$$

Definition 2.5. $a_i \in A_i$ is a **never best response** if it is not a best response given any belief α_i .

Corollary 2.1 (*Iterative Elimination of Never Best Response*). Same procedures but D_i^k is the set of never best responses for player i at game G^k .

Example 2.2. For player 1, D is not strictly dominated, but it is a never best response.

Proof. Let α be a probability measure on $\{L, R\}$ such that $\alpha(L) = p \in [0, 1]$.

$$\mathbb{E}[u_1(U) | \alpha] = 10p \quad (2.7)$$

$$\mathbb{E}[u_1(M) | \alpha] = 10 - 10p \quad (2.8)$$

$$\mathbb{E}[u_1(D) | \alpha] = 1 \quad (2.9)$$

Case i

$$p \geq 0.5 \implies \mathbb{E}[u_1(U) | \alpha] \geq 5 > \mathbb{E}[u_1(D) | \alpha] \quad (2.10)$$

Case ii

$$p < 0.5 \implies \mathbb{E}[u_1(M) | \alpha] > 5 > \mathbb{E}[u_1(D) | \alpha] \quad (2.11)$$

Therefore, for any belief α , D cannot be a best response. So D is a never best response. ■

	L	R
U	10,0	0,0
M	0,0	10,0
D	1,0	1,0

Definition 2.6. An action $a_i \in A_i$ is **rationalizable** if it survives *iterative elimination of never best responses*.

Lemma 2.1 (60.1). An action of a player in a *finite* strategic game is a never-best response *if and only if* it is strictly dominated.¹

3 Lecture 3. Jan. 21 2019

Definition 3.1. A **pure strategy Nash equilibrium** is an action profile (a_i) such that

$$\forall i \in N, a_i \in Br_i(a_{-i}) \quad (3.1)$$

Remark 3.1. That's, a NE is a situation that if player i knows what other players do, the action given by the NE profile is still a best response.

Remark 3.2 (Interpretations). A Nash equilibrium is

- i) An action profile induces a stable outcome,
- ii) A creditable agreement, such that no player has incentive to break the agreement.

Example 3.1 (Cournot Duopoly). Consider a game with

- i) Player $N = \{1, 2\}$
- ii) Action set $A_i = [0, \infty) \forall i \in N$

And revenue R_i defined by

$$R_i = p_i q_i \quad (3.2)$$

where price is linear in quantity supplied,

$$p_i = \alpha - (q_i + q_{-i}), \alpha \in \mathbb{R} \quad (3.3)$$

and firms face fixed cost $c \in \mathbb{R}$, with the assumption that $\alpha > c$. So the cost function is given by

$$C_i(q_i) = cq_i \quad (3.4)$$

The profit function is given by

$$\Pi_i(q_i, q_{-i}) = (\alpha - (q_i + q_{-i}) - c)q_i \quad (3.5)$$

$$= (\alpha - c - q_{-i})q_i - q_i^2 \quad (3.6)$$

Given $q_{-i} \in A_{-i}$, the best response is given by

$$Br_i(q_{-i}) = \operatorname{argmax}_{q_i \in [0, \infty)} \Pi_i(q_i, q_{-i}) \quad (3.7)$$

$$= \max\{0, \frac{\alpha - c - q_{-i}}{2}\} \forall i \in N \quad (3.8)$$

¹The concept of *strict domination* will be introduced in section 5.

Considering the case that both players are producing positive quantities, we can solve q_i^* by

$$Br_i \circ Br_{-i}(q_i) = \frac{\alpha - c - \frac{\alpha - c - q_i}{2}}{2} = q_i \quad (3.9)$$

$$\implies 2q_i - \frac{q_i}{2} = \frac{\alpha - c}{2} \quad (3.10)$$

$$\implies q_i^* = \frac{\alpha - c}{3} \quad (3.11)$$

Remark 3.3. If fixed cost presents, even if the game is symmetric, the Nash equilibrium could be asymmetric. (e.g. one firm is out of market and the other firm produces the monopoly amount)

Remark 3.4. Nash equilibrium induces an *individual level optimality* instead of the common wealth optimality.

Example 3.2 (Continue Cournot Duopoly). Note that in the Cournot Duopoly game, for each $i \in N$, the Nash equilibrium profit is

$$\Pi_{NE}^* = \left(\alpha - c - \frac{2(\alpha - c)}{3}\right) \frac{\alpha - c}{3} \quad (3.12)$$

$$= \frac{(\alpha - c)^2}{9} \quad (3.13)$$

So the total profit for the two firms is $\frac{2(\alpha - c)^2}{9}$.

Now considering if the two firms form a Cartel, the *aggregate* quantity produced is

$$Q^* = \operatorname{argmax}_{Q \in \mathbb{R}_{\geq 0}} (\alpha - c - Q)Q \quad (3.14)$$

$$= \frac{\alpha - c}{2} \quad (3.15)$$

$$\implies \Pi_{Cartel}^* = \left(\alpha - c - \frac{\alpha - c}{2}\right) \frac{\alpha - c}{2} \quad (3.16)$$

$$= \frac{(\alpha - c)^2}{4} > \frac{2(\alpha - c)^2}{9} \quad (3.17)$$

The fact $\Pi_{Cartel}^* > 2 \times \Pi_{NE}^*$ suggests the Nash equilibrium action profile did not induce the optimal common wealth outcome. However, the Cartel action profile is not a stable outcome since every player has incentive to increase their production level.

Example 3.3 (Prisoner's Dilemma). The Nash equilibrium (Confess, Confess) is not the best outcome for the two players as a group. The optimal action profile for a group is (Silent, Silent).

Proposition 3.1. No strategy that is eliminated during iterated elimination of *never best response* can be played in a Nash equilibrium.

4 Lecture 4. Jan. 28. 2019

Example 4.1 (From last lecture). Consider the payoff matrix Both (A, A) and (B, B) are Nash equilibria. But in the former NE, for each $i \in N$,

$$Br_i(a_{-i} = A) = \{A\} \quad (4.1)$$

	A	B
A	(1,1)	(0,0)
B	(0,0)	(0,0)

which is a singleton.

In the second NE, for each $i \in N$,

$$Br_i(a_{-i} = B) = \{A, B\} \quad (4.2)$$

We call Nash equilibria of the first type *strict Nash equilibria* and the later one *weak Nash equilibria*. More formal definitions of these two types of Nash equilibria are given below.

Definition 4.1. A **strict Nash equilibrium** is an action profile (a_i) such that

$$\forall i \in N, Br_i(a_{-i}) \text{ is a singleton.} \quad (4.3)$$

Definition 4.2. A **weak Nash equilibrium** is a Nash equilibrium that is not strict.

Example 4.2 (Cournot with n firms). Consider the game

$$\langle N, (\mathbb{R}_{\geq 0}), (\pi_i) \rangle \quad (4.4)$$

Where $|N| = n$ and each firm picks a quantity $q_i \in A_i \equiv \mathbb{R}_{\geq 0}$.

Define

$$Q \equiv \sum_j q_j \quad (4.5)$$

For each $i \in N$, define

$$Q_{-i} \equiv \sum_{j \neq i} q_j \quad (4.6)$$

And the market has *linear demand curve*

$$P(\{q_i\}_{i \in N}) = \alpha - \sum_j q_j = \alpha - Q \quad (4.7)$$

And firms face fixed cost

$$\forall i \in N, C(q_i) = cq_i \text{ where } 0 < c < \alpha \quad (4.8)$$

The profit function is

$$\forall i \in N, \pi_i(q_i, Q_{-i}) = (\alpha - c - Q_{-i})q_i - q_i^2 \quad (4.9)$$

Question What are the Nash equilibria in this environment?

For each firm $i \in N$, the best response correspondence is

$$Br_i(Q_{-i}) = \max\{0, \operatorname{argmax}_{q_i \in \mathbb{R}_{\geq 0}} \pi_i(q_i, Q_{-i})\} \quad (4.10)$$

$$= \max\{0, \frac{\alpha - c - Q_{-i}}{2}\} \quad (4.11)$$

Assume We have a symmetric Nash equilibrium,

$$\forall i \in N, q_i^* = q^* = \frac{Q}{n} \quad (4.12)$$

$$\implies q^* = Br_i\left(\frac{n-1}{n}Q\right) \quad (4.13)$$

$$\implies 2q^* = \alpha - c - (n-1)q^* \quad (4.14)$$

$$\implies q^* = \frac{\alpha - c}{n+1} \quad (4.15)$$

Check Then check the validity of symmetric Nash equilibrium by asserting for every player, if all other players are playing the action suggested by the symmetric Nash equilibrium, then this player should also play it. That's

$$q^* = Br_i(\{q_j\}_{j \neq i}) \quad (4.16)$$

$$= \frac{\alpha - c}{2} - \frac{1}{2} \frac{n-1}{n+1} (\alpha - c) \quad (4.17)$$

$$= \frac{1}{2} \left((\alpha - c) - \frac{n-1}{n+1} (\alpha - c) \right) \quad (4.18)$$

$$= \frac{1}{2} \frac{2}{n+1} (\alpha - c) \quad (4.19)$$

$$= \frac{\alpha - c}{n+1} = q^* \quad (4.20)$$

Uniqueness We are going to show the symmetric Nash equilibrium is the only possible equilibrium action profile.

Proof. Suppose there exists some non-symmetric Nash equilibrium.

For concreteness, assuming there exists $\epsilon > 0$ such that

$$\exists i, j \in N, q_i = q_j + \epsilon \quad (4.21)$$

Define $Q_{-ij} \equiv Q - q_i - q_j$.

For firm i ,

$$q_i = Br_i(Q_{-i}) = \frac{1}{2}(\alpha - c - Q_{-i}) \quad (4.22)$$

$$= \frac{1}{2}(\alpha - c - Q_{-ij} - q_j) \quad (4.23)$$

$$= \frac{1}{2}(\alpha - c - Q_{-ij} - q_i + \epsilon) \quad (4.24)$$

$$\implies 3q_i = \alpha - c - Q_{-ij} + \epsilon \quad (4.25)$$

$$\implies 3q_i = \alpha - c - Q_{-j} + q_i + \epsilon \quad (4.26)$$

$$\implies 2q_i - \epsilon = \alpha - c - Q_{-j} \quad (4.27)$$

$$\implies q_i - \frac{\epsilon}{2} = Br(Q_{-j}) = q_j \quad (4.28)$$

$$= q_i - \epsilon \quad (4.29)$$

$$\implies \epsilon = 2\epsilon \quad (4.30)$$

which contradicts the assumption that $\epsilon > 0$.

Therefore we conclude that the symmetric Nash equilibrium is the only Nash equilibrium in this environment. ■

Example 4.3 (Cournot duopoly with fixed cost). Consider the game

$$\mathcal{G} = \langle N = (1, 2), (A_i = \mathbb{R}_{\geq 0}), (\pi_i) \rangle \quad (4.31)$$

Where the cost function is defined as

$$C_i(q_i) = \begin{cases} cq_i + f & \text{if } q_i > 0 \\ 0 & \text{if } q_i = 0 \end{cases} \quad (4.32)$$

where $\alpha > c > 0$.

For each firm $i \in N$, the best response function, conditioned on $q_i > 0$, is

$$q_i = Br_i(q_{-i}) = \frac{\alpha - c - q_{-i}}{2} \quad (4.33)$$

We have to **check the profit** to assert the profit is non-negative while firm i is producing above quantity. Because, otherwise, this firm could always derivate to $q_i = 0$ to avoid loss (earning zero profit).

$$\pi_i(Br_{q_{-i}}, q_{-i}) = (\alpha - q_{-i} - \frac{\alpha - c - q_{-i}}{2} - c) \frac{\alpha - c - q_{-i}}{2} - f \quad (4.34)$$

$$= \frac{(\alpha - c - q_{-i})^2}{4} - f \quad (4.35)$$

$$\pi_i(q_{-i}) \geq 0 \iff \alpha - c - q_{-i} \geq 2\sqrt{f} \quad (4.36)$$

$$\iff q_{-i} \leq \alpha - c - 2\sqrt{f} \quad (4.37)$$

Therefore we can modify our **best response correspondence** to

$$Br_i(q_{-i}) = \begin{cases} \frac{\alpha - c - q_{-i}}{2} & \text{if } q_{-i} \leq \alpha - c - 2\sqrt{f} \\ 0 & \text{if } q_{-i} \geq \alpha - c - 2\sqrt{f} \end{cases} \quad (4.38)$$

Monopoly: the monopoly amount, conditioned on the firm decides to produce, is $\frac{\alpha - c}{2}$. In the monopoly case, suppose the NE action profile is (the opposite case can be shown by symmetry)

$$(\frac{\alpha - c}{2}, 0) \quad (4.39)$$

We have to assert both

$$\begin{cases} \frac{\alpha - c}{2} \in Br_1(0) \\ 0 \in Br_2(\frac{\alpha - c}{2}) \end{cases} \quad (4.40)$$

$$\implies \begin{cases} 0 \leq \alpha - c - 2\sqrt{f} & \text{for firm 1 to produce positive amount.} \\ \frac{\alpha - c}{2} \geq \alpha - c - 2\sqrt{f} & \text{for firm 2 to produce zero.} \end{cases} \quad (4.41)$$

$$\implies 0 \leq \alpha - c - 2\sqrt{f} \leq \frac{\alpha - c}{2} \quad (4.42)$$

$$\implies -(\alpha - c) \leq -2\sqrt{f} \leq -\frac{\alpha - c}{2} \quad (4.43)$$

$$\implies \sqrt{f} \in [\frac{\alpha - c}{4}, \frac{\alpha - c}{2}] \quad (4.44)$$

Positive symmetric equilibrium: we've proven, in the general case, it's impossible for both firms to produce positive but different amounts. Therefore we have to assert

$$\frac{\alpha - c}{3} \in Br_i\left(\frac{\alpha - c}{3}\right) \forall i \in N \quad (4.45)$$

$$\implies \frac{\alpha - c}{3} \leq \alpha - c - 2\sqrt{f} \quad (4.46)$$

$$\implies \sqrt{f} \leq \frac{1}{3}(\alpha - c) \quad (4.47)$$

Zero symmetric equilibrium: we have to assert

$$0 \in Br_i(0) \forall i \in N \quad (4.48)$$

$$\implies 0 \geq \alpha - c - 2\sqrt{f} \quad (4.49)$$

$$\implies \sqrt{f} \geq \frac{\alpha - c}{2} \quad (4.50)$$

Example 4.4 (Discrete price Bertrand duopoly). Consider the following game

$$\mathcal{G} = \langle N = \{1, 2\}, (A_i = \{k\epsilon : k \in \mathbb{Z}_{\geq 0}\}), (\pi_i) \rangle \quad (4.51)$$

The profit function can be derived as

$$\pi_i(p_i, p_{-i}) = \begin{cases} (\alpha - p_i)(p_i - c) & \text{if } p_i < p_{-i} \\ \frac{\alpha - p_i}{2}(p_i - c) & \text{if } p_i = p_{-i} \\ 0 & \text{if } p_i > p_{-i} \end{cases} \quad (4.52)$$

Claim the only Nash equilibria are (c, c) and $(c + \epsilon, c + \epsilon)$.

Justify (c, c) , consider any firm $i \in N$, currently $\pi_i = 0$

$$\uparrow p_i \implies \pi_i \leftarrow \pi'_i = 0 \quad \text{✗} \quad (4.53)$$

$$\downarrow p_i \implies \pi_i \leftarrow \pi'_i < 0 \quad \text{✗} \quad (4.54)$$

So no firm has incentive to deviate from this action profile, so (c, c) is a Nash equilibrium by definition.

Consider the action profile $(c + \epsilon, c + \epsilon)$, both firms are earning a positive profit $\pi_i > 0$. For any firm $i \in N$,

$$\uparrow p_i \implies \pi_i \leftarrow \pi'_i = 0 \quad \text{✗} \quad (4.55)$$

$$\downarrow p_i \implies \pi_i \leftarrow \pi'_i = 0 \quad \text{✗} \quad (4.56)$$

So $(c + \epsilon, c + \epsilon)$ is a Nash equilibrium by definition.

No other Nash equilibrium

Claim: (p_1, p_2) cannot be a Nash equilibrium if any $p_i < c$.

Obviously, set $p_i < c$ would induce negative profit and firm i do better off by setting $p_i \leftarrow c$.

Claim: the symmetric profit (p, p) with $p > c + \epsilon$ cannot be a Nash equilibrium. For both firms, the current profit is

$$\pi_1 = \pi_2 = \frac{1}{2}(\alpha - c - k\epsilon)k\epsilon \quad (4.57)$$

And reducing price by ϵ leads to a profit of

$$\pi'_i = (\alpha - c - k\epsilon + \epsilon)(k - 1)\epsilon > \pi_i \quad (4.58)$$

so such action profile cannot be Nash equilibrium.

Claim (p_1, p_2) with $p_1 \neq p_2$ and $p_1, p_2 > c$ cannot be a Nash equilibrium. The firm charges higher price can always reduce its price to the price charged by the other firm and gain a positive profit.

Claim (c, p_2) with $p_2 \geq c + \epsilon$ cannot be a Nash equilibrium. The firm charging $p = c$ can always increase its price to $c + \epsilon$ to earn positive profit.

Therefore there's no Nash equilibrium other than (c, c) and $(c + \epsilon, c + \epsilon)$.

Example 4.5 (Bertrand duopoly with differentiated products). Consumers are uniformly distributed on a preference line $[0, 1]$.

For a firm $i \in N$, let $x_i \in [0, 1]$ measure consumer's preference towards firm i 's products.

Define

$$x_{-i} \equiv 1 - x_i \sim Unif(0, 1) \quad (4.59)$$

Consumer buy product i if

$$x_i - p_i \geq x_{-i} - p_{-i} \quad (4.60)$$

and purchases product 1 if

$$x_i - p_i \leq x_{-i} - p_{-i} \quad (4.61)$$

Then solve the boundary $x^* \in [0, 1]$ such that consumers at x^* are indifferent between two products.

$$x + p_i = (1 - x) + p_{-i} \quad (4.62)$$

$$\implies x^* = \frac{1 - p_i + p_{-i}}{2} \quad (4.63)$$

So any consumer with $x_i > x^*$ would choose firm i 's product, also because consumers are uniformly distributed on $x_i \in [0, 1]$. So the portion of consumers buying firm i 's product is

$$1 - x_i = \frac{1 + p_i - p_{-i}}{2} \quad (4.64)$$

And, clearly, The demand function for firm i is

$$D_i(q_i, q_{-i}) = \begin{cases} 0 & \text{if } p_i \geq p_{-i} + 1 \\ \frac{1 + p_i - p_{-i}}{2} & \text{if } p_i \in [p_{-i} - 1, p_{-i} + 1] \\ 1 & \text{if } p_i \leq p_{-i} - 1 \end{cases} \quad (4.65)$$

Consider the case where $|p_i - p_{-i}| \leq 1$,

$$\pi_i = D_i(p_i)(p_i - c) = \frac{1 + p_i - p_{-i}}{2}(p_i - c) \quad (4.66)$$

Take the first order condition

$$\frac{\partial \pi_i}{\partial p_i} = 0 \quad (4.67)$$

$$\implies p_i = \frac{p_{-i} + c - 1}{2} \quad (4.68)$$

	<i>H</i>	<i>T</i>
<i>H</i>	(1,-1)	(-1,1)
<i>L</i>	(-1,1)	(1,-1)

5 Lecture 5 Feb. 7 2019

5.1 Lecture Contents

Example 5.1. Matching pennies: an example of game without pure strategy Nash equilibrium.

Assumption 5.1. We assume that the preference relation of each player i satisfies the assumptions of *von Neumann and Morgenstern*, so that it can be represented by the expected value of some function $u_i : A \rightarrow \mathbb{R}$.

Definition 5.1. Suppose player i has a *finite* set of pure strategies A_i , then a **mixed strategy** $\sigma_i \in \Delta(A_i)$ is a probability distribution over A_i .

Definition 5.2. The **support** of σ_i is defined as

$$\mathcal{S}(\sigma_i) \equiv \{a \in A_i : \sigma_i(a) > 0\} \quad (5.1)$$

Definition 5.3. A mixed strategy σ_i is **degenerate** if

$$\exists a_i \in A_i \text{ s.t. } \sigma_i(a_i) = 1 \quad (5.2)$$

and such degenerated mixed strategy is denoted as $e(a_i)$.

Remark 5.1. A pure strategy $a_i \in A_i$ is equivalent to a degenerated mixed strategy $e(a_i)$.

Proposition 5.1. In a finite game, given the independence of randomization, the probability of the action profile $a \equiv (a_i)$ to be realized given mixed strategy profile $\sigma \equiv (\sigma_i)$ is

$$\sigma(a) \equiv \mathbb{P}[a|\sigma] = \prod_{i \in N} \sigma_i(a_i) \quad (5.3)$$

and for player i , the **expected payoff** from mixed strategy profile (σ_i) is

$$U_i(\sigma_i, \sigma_{-i}) = \sum_{a \in A} \left[\prod_{j \in N} \sigma_j(a_j) \right] u_i(a) = \mathbb{E}[u_i|\sigma] \quad (5.4)$$

Proposition 5.2. The **expected payoff** from mixed strategy profile $(\sigma_i) \equiv (\sigma_i, \sigma_{-i})$ is

$$U_i(\sigma_i, \sigma_{-i}) \equiv \mathbb{E}[u_i(a)|(\sigma_i)] = \sum_{a_i \in A_i} \sum_{a_{-i} \in A_{-i}} u_i(a_i, a_{-i}) \sigma_{-i}(a_{-i}) \sigma_i(a_i) \quad (5.5)$$

Definition 5.4 (Osborne 2030 lec2). The **mixed extension** of the strategic game $\langle N, (A_i)_{i \in N}, (u_i)_{i \in N} \rangle$ is the following strategic game:

- (i) **Players** N
- (ii) **Action sets** $\Delta(A_i)$ for player i
- (iii) **Preferences** Represented by $U_i : \prod_{j \in N} \Delta(A_j) \rightarrow \mathbb{R}$, where $U_i(\alpha)$ is the expected value under u_i of the lottery over $\prod_{j \in N} \Delta(A_j)$ induced by α .

Definition 5.5. A pure strategy $a_i \in A_i$ is **strictly dominated** by a mixed strategy $\sigma_i \in \Delta(A_i)$ if

$$\forall a_{-i} \in A_{-i} \ u_i(a_i, a_{-i}) < U_i(\sigma_i, a_{-i}) \quad (5.6)$$

We say a_i is strictly dominated.

Proposition 5.3. We can also define the strict dominance by replacing $\forall a_{-i} \in A_{-i}$ with $\forall \sigma_{-i} \in \Delta A_{-i}$ since

$$\forall a_{-i} \in A_{-i} \ u_i(a_i, a_{-i}) < U_i(\sigma_i, a_{-i}) \iff \forall \sigma_{-i} \in \Delta(A_{-i}) \ U_i(a_i, \sigma_{-i}) < U_i(\sigma_i, \sigma_{-i}) \quad (5.7)$$

Proof. (\implies) Suppose

$$\forall a_{-i} \in A_{-i} \ u_i(a_i, a_{-i}) < U_i(\sigma_i, a_{-i}) \quad (5.8)$$

Let $\sigma_{-i} \in \Delta(A_{-i})$,

$$U_i(a_i, \sigma_{-i}) = \sum_{a_{-i} \in A_{-i}} u_i(a_i, a_{-i}) \sigma_{-i}(a_{-i}) \quad (5.9)$$

$$< \sum_{a_{-i} \in A_{-i}} U_i(\sigma_i, a_{-i}) \sigma_{-i}(a_{-i}) \quad (5.10)$$

$$= U_i(\sigma_i, \sigma_{-i}) \quad (5.11)$$

Thus

$$\forall \sigma_{-i} \in \Delta(A_{-i}) \ U_i(a_i, \sigma_{-i}) < U_i(\sigma_i, \sigma_{-i}) \quad (5.12)$$

(\impliedby) Suppose

$$\forall \sigma_{-i} \in \Delta(A_{-i}) \ U_i(a_i, \sigma_{-i}) < U_i(\sigma_i, \sigma_{-i}) \quad (5.13)$$

Let $a_{-i} \in A_{-i}$, consider σ_{-i}^* defined as $\sigma_{-i}^*(x) \equiv \mathbb{I}(x = a_{-i})$ so that

$$U_i(a_i, \sigma_{-i}^*) < U_i(\sigma_i, \sigma_{-i}^*) \quad (5.14)$$

$$\implies u_i(a_i, a_{-i}) < U_i(\sigma_i, a_{-i}) \quad (5.15)$$

The equivalence is shown. ■

Definition 5.6. The **best response** to a mixed strategy $\sigma_{-i} \in \Delta A_{-i}$ is defined as

$$Br_i(\sigma_{-i}) \equiv \{\sigma_i \in \Delta(A_i) : \forall \tilde{\sigma}_i \in \Delta(A_i), \ U_i(\sigma_i, \sigma_{-i}) \geq U_i(\tilde{\sigma}_i, \sigma_{-i})\} \quad (5.16)$$

Proposition 5.4. Let $(\sigma_i, \sigma_{-i}) \in \Delta(A)$ then $\sigma_i \in Br_i(\sigma_{-i})$ if and only if

1. $\forall a_j, a_k \in \mathcal{S}(\sigma_i), \ a_j \sim_i a_k$,
2. and $\forall a_j \in \mathcal{S}(\sigma_i) \ a_k \notin \mathcal{S}(\sigma_i), \ a_j \succsim_i a_k$

Proof. (\implies) case 1: suppose (1) is false, for concreteness, assume

$$\exists a_j, a_k \in \mathcal{S}(\sigma_i) \text{ s.t. } U_i(a_j, \sigma_{-i}) > U_i(a_k, \sigma_{-i}) \quad (5.17)$$

Define

$$\mathcal{U}_j \equiv U_i(a_j, \sigma_{-i}) = \sum_{a_{-i} \in A_{-i}} u_i(a_j, a_{-i}) \sigma_{-i}(a_{-i}) \quad (5.18)$$

$$\mathcal{U}_k \equiv U_i(a_k, \sigma_{-i}) = \sum_{a_{-i} \in A_{-i}} u_i(a_k, a_{-i}) \sigma_{-i}(a_{-i}) \quad (5.19)$$

And $\mathcal{U}_j > \mathcal{U}_k$ by assumption. Consider σ'_i defined with

$$\sigma'_i(a) = \begin{cases} \sigma_i(a_j) + \sigma_i(a_k) & \text{if } a = a_j \\ 0 & \text{if } a = a_k \\ \sigma_i(a) & \text{otherwise} \end{cases} \quad (5.20)$$

Therefore

$$U_i(\sigma'_i, \sigma_{-i}) \equiv \sum_{a_i \in A_i} \sum_{a_{-i} \in A_{-i}} u_i(a_i, a_{-i}) \sigma'_i(a_i) \sigma_{-i}(a_{-i}) \quad (5.21)$$

$$= \sum_{a_i \in A_i \setminus \{a_j, a_k\}} \sum_{a_{-i} \in A_{-i}} u_i(a_i, a_{-i}) \sigma'_i(a_i) \sigma_{-i}(a_{-i}) + \sigma'_i(a_j) \mathcal{U}_j + \sigma'_i(a_k) \mathcal{U}_k \quad (5.22)$$

$$= \sum_{a_i \in A_i \setminus \{a_j, a_k\}} \sum_{a_{-i} \in A_{-i}} u_i(a_i, a_{-i}) \sigma_i(a_i) \sigma_{-i}(a_{-i}) + \sigma_i(a_j) \mathcal{U}_j + \sigma_i(a_k) \mathcal{U}_k \quad (5.23)$$

$$> \sum_{a_i \in A_i \setminus \{a_j, a_k\}} \sum_{a_{-i} \in A_{-i}} u_i(a_i, a_{-i}) \sigma_i(a_i) \sigma_{-i}(a_{-i}) + \sigma_i(a_j) \mathcal{U}_j + \sigma_i(a_k) \mathcal{U}_k \quad (5.24)$$

$$= \sum_{a_i \in A_i} \sum_{a_{-i} \in A_{-i}} u_i(a_i, a_{-i}) \sigma_i(a_i) \sigma_{-i}(a_{-i}) \equiv U_i(\sigma_i, \sigma_{-i}) \quad (5.25)$$

So that σ'_i strictly dominates σ_i , so $\sigma_i \notin Br_i(\sigma_{-i})$.

case 2: suppose (2) is false, for concreteness, assume

$$\exists a_j \in \mathcal{S}(\sigma_i), a_k \notin \mathcal{S}(\sigma_i) \text{ s.t. } U_i(a_k, \sigma_{-i}) > U_i(a_j, \sigma_{-i}) \quad (5.26)$$

Consider mixed strategy σ'_i defined as

$$\sigma'_i(a) = \begin{cases} 0 & \text{if } a = \sigma_j \\ \sigma_i(a_j) & \text{if } a = \sigma_k \\ \sigma_i(a) & \text{otherwise} \end{cases} \quad (5.27)$$

By previous definitions, $\mathcal{U}_k > \mathcal{U}_j$.

Then

$$U_i(\sigma'_i, \sigma_{-i}) \equiv \sum_{a_i \in A_i} \sum_{a_{-i} \in A_{-i}} u_i(a_i, a_{-i}) \sigma'_i(a_i) \sigma_{-i}(a_{-i}) \quad (5.28)$$

$$= \sum_{a_i \in A_i \setminus \{a_j, a_k\}} \sum_{a_{-i} \in A_{-i}} u_i(a_i, a_{-i}) \sigma'_i(a_i) \sigma_{-i}(a_{-i}) + \sigma'_i(a_j) \mathcal{U}_j + \sigma'_i(a_k) \mathcal{U}_k \quad (5.29)$$

$$= \sum_{a_i \in A_i \setminus \{a_j, a_k\}} \sum_{a_{-i} \in A_{-i}} u_i(a_i, a_{-i}) \sigma_i(a_i) \sigma_{-i}(a_{-i}) + 0 \mathcal{U}_j + \sigma_i(a_j) \mathcal{U}_k \quad (5.30)$$

$$> \sum_{a_i \in A_i \setminus \{a_j, a_k\}} \sum_{a_{-i} \in A_{-i}} u_i(a_i, a_{-i}) \sigma_i(a_i) \sigma_{-i}(a_{-i}) + \sigma_i(a_j) \mathcal{U}_j \quad (5.31)$$

$$= U_i(\sigma_i, \sigma_{-i}) \quad (5.32)$$

Therefore $\sigma_i \notin Br_i(\sigma_{-i})$, *modus tollens*.

(\Leftarrow) suppose $\sigma_i \notin Br_i(\sigma_{-i})$, that's

$$\exists \sigma'_i \in \Delta(A_i) \text{ s.t. } U_i(\sigma'_i, \sigma_{-i}) > U_i(\sigma_i, \sigma_{-i}) \quad (5.33)$$

Therefore

$$\exists \bar{a}_i, \underline{a}_i \in \mathcal{S}(\sigma_i) \text{ s.t. } U_i(\bar{a}_i, \sigma_{-i}) \geq U_i(\sigma_i, \sigma_{-i}) \geq U_i(\underline{a}_i, \sigma_{-i}) \quad (5.34)$$

$$\wedge \exists \bar{a}'_i, \underline{a}'_i \in \mathcal{S}(\sigma'_i) \text{ s.t. } U_i(\bar{a}'_i, \sigma_{-i}) \geq U_i(\sigma'_i, \sigma_{-i}) \geq U_i(\underline{a}'_i, \sigma_{-i}) \quad (5.35)$$

$$\implies U_i(\bar{a}'_i, \sigma_{-i}) \geq U_i(\sigma'_i, \sigma_{-i}) > U_i(\sigma_i, \sigma_{-i}) \geq U_i(\underline{a}_i, \sigma_{-i}) \quad (5.36)$$

$$\implies U_i(\bar{a}'_i, \sigma_{-i}) > U_i(\underline{a}_i, \sigma_{-i}) \quad (5.37)$$

$$\implies \bar{a}'_i \succ_i \underline{a}_i \in \mathcal{S}(\sigma_i) \quad (5.38)$$

In both cases, $\bar{a}'_i \in \mathcal{S}(\sigma_i)$ and $\bar{a}'_i \notin \mathcal{S}(\sigma_i)$, the two requirements are falsified, *modus tollens*. ■

Remark 5.2. Procedure to solve Nash equilibria for two player finite games,

- (i) Solve for pure strategy Nash equilibria.
- (ii) Eliminate strictly dominated strategies.
- (iii) For player i , solve a mixed strategy scheme σ_j so that player i is indifferent between actions in a non-singleton subset of his/her action set, A_i^* .
- (iv) Player i would play any mixed strategy with support A_i^* .
- (v) Repeat (iii) and (iv) for player j .

5.2 Some Propositions and Proofs

Proposition 5.5 (exer.120.3). A mixed strategy that assigns positive probability of a strictly dominated action is strictly dominated. That's, suppose $\tilde{a}_i \in A_i$ is strictly dominated, then for any $\sigma_i \in \Delta(A_i)$,

$$\tilde{a}_i \in \mathcal{S}(\sigma_i) \implies \sigma_i \text{ strictly dominated} \quad (5.39)$$

Note that the converse is **not** true.

Proposition 5.6 (Nash). Every strategic game in which each player has finitely many actions has a mixed strategy Nash equilibrium.

Proposition 5.7. Let $\sigma_{-i} \in \Delta(A_{-i})$, if a pure strategy $a_i \in A_i$ is strictly dominated by another pure strategy $\tilde{a}_i \in A_i$, then

$$\forall \sigma_i \in Br_i(\sigma_{-i}) \ a_i \notin \mathcal{S}(\sigma_i) \quad (5.40)$$

Proof. ■

Proposition 5.8. Let $\sigma_{-i} \in \Delta(A_{-i})$, if a pure strategy $a_i \in A_i$ is strictly dominated by another mixed strategy $\tilde{\sigma}_i \in \Delta(A_i)$, then

$$\forall \sigma_i \in Br_i(\sigma_{-i}) \ a_i \notin \mathcal{S}(\sigma_i) \quad (5.41)$$

Proof. ■

Proposition 5.9. For pure strategy $a_i \in A_i$, if there exists $a_{-i} \in A_{-i}$ such that

$$u_i(a_i, a_{-i}) \geq u_i(\tilde{a}_i, a_{-i}) \quad \forall \tilde{a}_i \in A_i \quad (5.42)$$

then a_i is **not** strictly dominated (by pure strategies or mixed strategies).

Proof. ■

Proposition 5.10. Let $a_i \in A_i$, then the following statements are equivalent

$$(i) \quad \exists \sigma_i \in \Delta(A_i) \text{ s.t. } a_i \in \mathcal{S}(\sigma_i) \wedge \forall \sigma_{-i} \in \Delta(A_{-i}), U_i(a_i, \sigma_{-i}) < U_i(\sigma_i, \sigma_{-i}) \quad (5.43)$$

$$(ii) \quad \exists \tilde{\sigma}_i \in \Delta(A_i) \text{ s.t. } a_i \notin \mathcal{S}(\tilde{\sigma}_i) \wedge \forall \sigma_{-i} \in \Delta(A_{-i}), U_i(a_i, \sigma_{-i}) < U_i(\tilde{\sigma}_i, \sigma_{-i}) \quad (5.44)$$

Proof. (\implies) Suppose there exists σ_i satisfies (i),
Note that $\sigma_i(a_i) \neq 1$, define $\tilde{\sigma}_i$ as

$$\tilde{\sigma}_i(a) = \begin{cases} \frac{\sigma_i(a)}{1 - \sigma_i(a_i)} & \text{if } a \in \mathcal{S}(\sigma_i) \setminus \{a_i\} \\ 0 & \text{otherwise} \end{cases} \quad (5.45)$$

And $\mathcal{S}(\tilde{\sigma}_i) = \mathcal{S}(\sigma_i) \setminus \{a_i\}$.

Then, by (i),

$$U_i(a_i, \sigma_{-i}) < \sum_{a_j \in \mathcal{S}(\sigma_i)} U_i(a_j, \sigma_{-i}) \sigma_i(a_j) \quad (5.46)$$

$$\implies (1 - \sigma_i(a_i)) U_i(a_i, \sigma_{-i}) < \sum_{a_j \in \mathcal{S}(\sigma_i) \setminus \{a_i\}} U_i(a_j, \sigma_{-i}) \sigma_i(a_j) \quad (5.47)$$

$$\implies U_i(a_i, \sigma_{-i}) < \frac{1}{1 - \sigma_i(a_i)} \sum_{a_j \in \mathcal{S}(\tilde{\sigma}_i)} U_i(a_j, \sigma_{-i}) \sigma_i(a_j) \quad (5.48)$$

$$\implies U_i(a_i, \sigma_{-i}) < \sum_{a_j \in \mathcal{S}(\tilde{\sigma}_i)} U_i(a_j, \sigma_{-i}) \frac{\sigma_i(a_j)}{1 - \sigma_i(a_i)} \quad (5.49)$$

$$\implies U_i(a_i, \sigma_{-i}) < \sum_{a_j \in \mathcal{S}(\tilde{\sigma}_i)} U_i(a_j, \sigma_{-i}) \tilde{\sigma}_i(a_j) \equiv U_i(\tilde{\sigma}_i, \sigma_{-i}) \quad (5.50)$$

(\impliedby) Suppose there exists $\tilde{\sigma}_i$ satisfies (ii). Take $\eta \in \mathbb{R}_+$, define σ_i as

$$\sigma_i(a) = \begin{cases} \frac{\tilde{\sigma}_i(a)}{1 + \eta} & \text{if } a \in \mathcal{S}(\tilde{\sigma}_i) \\ \frac{\eta}{1 + \eta} & \text{if } a = a_i \\ 0 & \text{otherwise} \end{cases} \quad (5.51)$$

Note that $\mathcal{S}(\sigma_i) = \mathcal{S}(\tilde{\sigma}_i) \cup \{a_i\}$.

By (ii),

$$U_i(a_i, \sigma_{-i}) < \sum_{a_j \in \mathcal{S}(\tilde{\sigma}_i)} U_i(a_j, \sigma_{-i}) \tilde{\sigma}_i(a_j) \quad (5.52)$$

$$\implies (1 + \eta)U_i(a_i, \sigma_{-i}) < \sum_{a_j \in \mathcal{S}(\tilde{\sigma}_i)} U_i(a_j, \sigma_{-i}) \tilde{\sigma}_i(a_j) + U_i(a_i, \sigma_{-i})\eta \quad (5.53)$$

$$\implies U_i(a_i, \sigma_{-i}) < \sum_{a_j \in \mathcal{S}(\tilde{\sigma}_i)} U_i(a_j, \sigma_{-i}) \frac{\tilde{\sigma}_i(a_j)}{1 + \eta} + \frac{\eta}{1 + \eta} U_i(a_i, \sigma_{-i}) \quad (5.54)$$

$$= \sum_{a_j \in \mathcal{S}(\sigma_i)} U_i(a_j, \sigma_{-i}) \sigma_i(a_j) \equiv U_i(\sigma_i, \sigma_{-i}) \quad (5.55)$$

■

Remark 5.3. With above proposition, while we are checking if $a_i \in A_i$ is strictly dominated by some mixed strategies, we don't have to include a_i in the support of potential σ_i .

Proposition 5.11 (Osborne 2030 lec2). Let $\mathcal{G} = \langle N, (A_i), (u_i) \rangle$ and $\mathcal{G}' = \langle N, (\Delta(A_i)), (U_i) \rangle$. Then any Nash equilibrium of \mathcal{G} is a mixed strategy Nash equilibrium (in which each player's strategy is pure) of \mathcal{G}' .

Remark 5.4. Hence mixed strategy may do *as well as* a pure strategy but can never *do strictly better* than *all* pure strategy. Consequently pure strategy remains optimal when mixed strategies are allowed.

Proposition 5.12 (Osborne 2030 lec2). For any mixed strategy Nash equilibrium of \mathcal{G}' in which each player's strategy is pure is a Nash equilibrium.

Remark 5.5. If player optimally chooses a pure strategy when she is allowed to randomize, then when she is prohibited from randomizing the pure strategy remains optimal.

Proposition 5.13 (Osborne 2030 lec2, lemma 33.2). The following statements are equivalent:

- (i) (σ_i^*) is a mixed strategy Nash equilibrium.
- (ii) $\forall i \in N, \sigma_i^* \in Br_i(\sigma_{-i}^*)$.
- (iii) $\forall i \in N$, every action in support of σ_i^* is a best response to σ_{-i}^* .

6 Lecture 6 Feb. 25 2019

6.1 An Introductory Example

6.2 Extensive Form Game: Assumptions and Terminologies

Assumption 6.1. All games considered in the section are **pure sequential games**, in which, for each sub-history, *exactly* one player gets action.

Assumption 6.2. We assume all players have **perfect information**, they can observe all previous actions.¹

¹This assumption will be relaxed in Bayesian games.

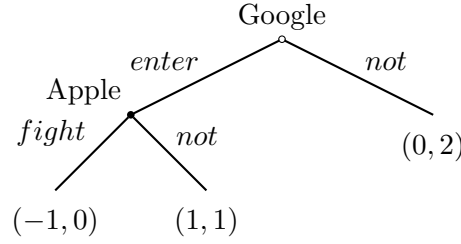


Figure 6.1: Market Entry game

Definition 6.1. A sequence of actions is called a **history**. For example, $h = (a_1, \dots, a_t)$ would be a history at period $t + 1$.

Definition 6.2. A history h belongs to **terminal histories**, T , if the game is over and payoff is generated. That's, there's no action a such that appending a to h would generate another valid history.

Definition 6.3. The **sub-histories**, S , are histories that are not terminal.

Definition 6.4. Conventionally, the initial history is defined as the empty set.

$$h_0 = \emptyset \in S \quad (6.1)$$

Definition 6.5. Let $h \in S$, then $\tilde{h} = h \oplus a \in S \cup T$ is a **continuation** of $h = (a_1, \dots, a_t)$.

Definition 6.6 (Extensive Form Game). An **extensive form game** $\Gamma = \langle N, P, H, (u_i) \rangle$ consists

- (a) A finite set of **players** N .
- (b) A set of **histories** $H = S \cup T$ with **initial history** $h_0 = \emptyset^1$.
- (c) **Player function** $P : S \rightarrow N$ assigns one player $P(h)$ (in pure sequential games) to act after history h . And an **action set** $A(h)$ for player $P(h)$ is defined by

$$A(h) \equiv \{a \in A_{P(h)} : h \oplus \{a\} \in H\} \quad (6.2)$$

- (d) **Payoff functions** $u_i : T \rightarrow \mathbb{R}$ derived from preferences by

$$\forall z_1, z_2 \in T, u_i(z_1) \geq u_i(z_2) \iff z_1 \succsim_i z_2 \quad (6.3)$$

Definition 6.7. A **strategy** s_i for player $i \in N$ is a mapping from $\{h \in S : P(h) = i\}$ to valid actions in A_i for each specific h .

Remark 6.1. A strategy is a complete contingency plan assigns an action to every subhistories such that $P(h) = i$, *even if those subhistories cannot be reached*.

Definition 6.8. A **Nash equilibrium** is a strategy profile such that each player's strategy is a best response to strategies of other players.

Definition 6.9. For each $h \in S$, a **subgame** following subhistory h is a 4-tuple $\langle N, P, H', (u_i) \rangle$ where H' is the set of continuations of h . And everything else are inherited from the original game.

¹ S and T are **subhistories** and **terminal histories** sets defined above

Definition 6.10. A **subgame perfect Nash equilibrium** for Γ is a strategy profile such that there's a Nash equilibrium in every subgame of Γ , *including those never reached*. This means players are best responding in every subgame.

Lemma 6.1.

$$(s_i) \in \text{SPNE} \implies (s_i) \in \text{NE} \quad (6.4)$$

Proof. By the definition of SPNE, take subgame after history $h = \emptyset$. ■

Proposition 6.1. The set of strategy profiles found by the procedure of backward induction in a finite horizon game is the set of subgame perfect equilibria.

Definition 6.11. An extensive form game Γ is **finite** if the set H is finite.

Theorem 6.1. Every finite extensive game with perfect information has a subgame perfect equilibrium.

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8 Lecture 8 Mar.11 2019

8.1 Finite Repeated Games

Remark 8.1. Comparing extensive form games and repeated games.

- (i) **Extensive Form Game** the structure of game (available action, player, etc.) at each node of history tree varies based on the previous actions (history).
- (ii) **Repeated Game** **Same set of players** interact repeatedly, *each player can condition her action in period t on other players' actions in periods $\{1, \dots, t-1\}$.*

Theorem 8.1. If a **finite** repeated game has a **unique** Nash equilibrium in the game played in each period, then the only SPNE will have the players playing the NE in each period.

Proof. Omitted. ■

8.2 Infinitely Repeated Games

Definition 8.1 (Infinitely Repeated Games). Let $G = \langle N, (A_i), (\succsim_i) \rangle$ be a strategic game, denote the set of action profile as $A = \times_{i \in N} A_i$. An **infinitely repeated game** of G is an *extensive form game* $\Gamma = \langle N, H, P, (\succsim_i^*) \rangle$ where

- $H = \{\emptyset\} \cup (\cup_{t=1}^{\infty} A^t) \cup A^{\infty}$.¹
- $P(h) = N \ \forall h \in H$.
- \succsim_i^* is a preference relation on A^{∞} induced by \succsim_i such that if $(a^t) \in A^{\infty}$, $a, a' \in A$, and $a \succsim_i a'$ then
$$\forall t \in \mathbb{N}, (a^1, \dots, a^{t-1}, a, a^{t+1}, \dots) \succsim_i^* (a^1, \dots, a^{t-1}, a', a^{t+1}, \dots) \quad (8.1)$$

	C	D
C	x, x	$y, 0$
D	$y, 0$	$1, 1$

Example 8.1 (Infinitely Repeated Prisoner's Dilemma). Consider the infinitely repeated game induced by the prisoner's dilemma, where C and D denote *cooperating* and *deviating*. Suppose $y > x > 1$. Define payoff in period $t \in \mathbb{N}$ as $u_i(a_i^t, a_{-i}^t)$ for each player $i \in N$. And both player face a time discount factor $\delta \in (0, 1)$ measuring *how patient they are*. For example, the history $h = (CC, CC, \dots)$ gives each player payoff

$$\sum_{t=1}^{\infty} \delta^{t-1} u_i^t(C, C) = \sum_{t=1}^{\infty} \delta^{t-1} x = \frac{x}{1-\delta} \quad (8.2)$$

Definition 8.2. The **preference** in infinitely repeated games can be defined using a **present discounted utility function**. Let u_i be the utility function induced by (\succsim_i) in game G , then the payoff on history $h = (a^t)_{t=1}^{\infty}$ in the infinitely repeated game generated by G can be defined as

$$\mathcal{U}(h) = \sum_{t=1}^{\infty} \delta^{t-1} u(a^t) \quad \delta \in (0, 1) \quad (8.3)$$

Lemma 8.1. Two strategic game generate same preferences *with discounting in repeated game* \iff each player's payoffs in one game are *affine transformation* of her payoffs in the other game.

Definition 8.3. A strategy can be represented as an **automaton** consisting of

- (i) A set Q_i of **states**;
- (ii) An **initial state** $q_i^0 \in Q_i$;
- (iii) An **output function** $f_i : Q_i \rightarrow A_i$;
- (iv) A **transition function** $\tau_i : Q_i \times A \rightarrow Q_i$.

Example 8.2 (Grim Trigger, ∞ -Period Punishment). Grim Trigger in infinitely repeated prisoner dilemma is a strategy defined as

$$s_i^*(\emptyset) = C \quad (8.4)$$

$$s_i^*(h) = \begin{cases} C & \text{if } a_{-i}^{\tau} = C \ \forall \tau \in \{1, \dots, |h|\} \\ D & \text{otherwise} \end{cases} \quad (8.5)$$

Whether (s_i^*) is a SPNE depends on the parameter set of the game, here $\theta = (x, y, \delta)$.

Proposition 8.1. Grim Trigger is a SPNE in an infinitely repeated Prisoner's Dilemma if and only if

$$\delta \geq \frac{y-x}{y-1} \quad (8.6)$$

¹ A^{∞} denotes the set of *infinite sequences* $(a^t)_{t=1}^{\infty}$ where every $a^t \in A$.

Proof. To show (s_i^*) is a SPNE, we will examine all its alternatives and argue (s_i^*) provides at least much payoff as the supremum of payoffs generated by its alternatives.

Let s'_i be an alternative strategy for player $i \in N$ such that $s'_i \neq s_i$.

Let $k \in \mathbb{N}$ denote the first period D is played in strategy s'_i , let \mathcal{S}_i^k denote the set of strategy such that D is played first at period k :

$$\mathcal{S}_i^k \equiv \{s_i \in A_i^\infty : s_i^k = D \wedge s_i^\tau = C \ \forall \tau < k\} \quad (8.7)$$

It's obvious that strategy $\tilde{s}_{i,k} \in \mathcal{S}_i^k$ defined as

$$\tilde{s}_{i,k}^\tau = C \mathbf{1}\{\tau < k\} + D \mathbf{1}\{\tau \geq k\} \quad (8.8)$$

satisfies

$$\sum_{t=1}^{\infty} \delta^{t-1} u_i(\tilde{s}_{i,k}, s_{-i}^*) = \max_{\phi \in \mathcal{S}_i^k} \left\{ \sum_{t=1}^{\infty} \delta^{t-1} u_i(\phi, s_{-i}^*) \right\} \quad (8.9)$$

Since k is arbitrary, to show the payoff to player i of playing strategy s_i^* given her opponent's playing s_{-i}^* is bounded below by elements in \mathcal{S}_i^k , we only need to show it s_i^* provides at least payoff as $\tilde{s}_{i,k}$.

Easy to show that, for arbitrary $k \in \mathbb{N}$,

$$\mathcal{U}(s_i^*, s_{-i}^*) \geq \mathcal{U}(\tilde{s}_{i,k}, s_{-i}^*) \quad (8.10)$$

$$\iff \sum_{t=1}^{\infty} \delta^{t-1} x \geq \sum_{t=1}^{k-1} \delta^{t-1} x + \delta^{k-1} y + \sum_{t=k+1}^{\infty} \delta^{t-1} 1 \quad (8.11)$$

$$\iff \delta^{k-1} x + \sum_{t=k+1}^{\infty} \delta^{t-1} x \geq \delta^{k-1} y + \sum_{t=k+1}^{\infty} \delta^{t-1} 1 \quad (8.12)$$

$$\iff \delta^{k-1} x + \frac{\delta^k x}{1-\delta} \geq \delta^{k-1} y + \frac{\delta^k}{1-\delta} \quad (8.13)$$

$$\iff x + \frac{\delta x}{1-\delta} \geq y + \frac{\delta}{1-\delta} \quad (8.14)$$

$$\iff \delta \geq \frac{y-x}{y-1} \quad (8.15)$$

Note that each subgame after period k is another infinitely repeated game where payoff of every play is transformed by multiplying δ^k . By Lemma 8.1, we can use above argument to prove the subgame perfection of Grim trigger strategy when $\delta \geq \frac{y-x}{y-1}$. \blacksquare

Example 8.3 (Tit for Tat, 1-Period Punishment). Tit for tat strategy is defined as

$$s_i^*(\emptyset) = C \quad (8.16)$$

$$s_i^*(h) = \begin{cases} C & \text{if } h[-1] = C \\ D & \text{if } h[-1] = D \end{cases} \quad (8.17)$$

Proposition 8.2 (Generalized Limited Punishment, p -Period Punishment). The p -period punishment strategy is defined with $s_i^*(\emptyset) = C$, and if at time period k , $a_{-i}^k = D$, then the player play D for the next p periods as punishment no matter what action the opponent plays during the punishment. And then the player plays C again beginning at time period $t = k + p + 1$.

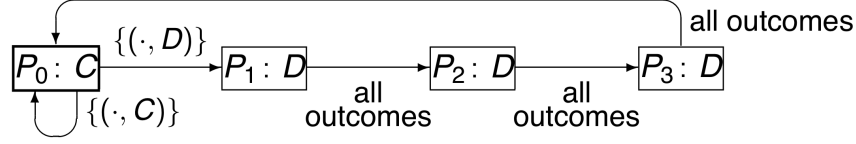


Figure 8.1: Three period punishment strategy as an automaton.

Proof. For the deviation *not* to be profitable, we need

$$\delta^{k-1}y + \sum_{t=k+1}^{k+p} \delta^{t-1}1 \leq \delta^{k-1}x + \sum_{t=k+1}^{k+p} \delta^{t-1}x \quad (8.18)$$

$$\iff \delta^{k-1}y \leq \delta^{k-1}x + \frac{(x-1)\delta^k(1-\delta^p)}{1-\delta} \quad (8.19)$$

$$\iff (y-x) \leq +\frac{\delta(1-\delta^p)}{1-\delta}(x-1) \quad (8.20)$$

■

Proposition 8.3. For any value of $k \geq 1$, *strategy pair* in which each player punishes other for k periods in event of deviation is Nash equilibrium of infinitely repeated game if δ is *close enough to 1*. The large k is, the *smaller lower bound on δ* , that's, the *mutually desirable outcome (C, C)* is sustained by short punishment only if players are relatively patient.

9 Lecture 9 Mar. 18 2019

9.1 Bayesian Games: Introduction

Definition 9.1 (Informal Definition). A **Bayesian Equilibrium** is a strategy profile where **each type of each player** is best responding given their *beliefs*.

Remark 9.1 (Complication on Belief System). Here we assume individuals have **exogenous beliefs**. In more complicated models, beliefs are endogenous, and beliefs change based on *other players' (previous) actions*, and beliefs can be *updated iteratively* in multi-period games.

9.2 Formal Definitions

Definition 9.2 (Bayesian Game). A **Bayesian Game** consists the following components

- (i) A **player** set N ;
- (ii) For each player i , an **action** set A_i ;
- (iii) A set of **states** Ω^1 , in which each $\omega \in \Omega$ represents one realization determines *players' types*, **Ω is assumed to be known by all players**;
- (iv) For each player, a set of **types** T_i , where $t_i \in T_i$ represents one potential type of player i and determines the payoff for each player, and may contains information about other players' types. Note that $\Omega \equiv \prod_{i \in N} T_i$.

¹ Ω could be uncountably infinite.

- (v) For each player i , based on his or her type, a **belief** function $\pi_i(\omega|t_i)$ or $\pi_i(t_{-i}|t_i)$, which can be expressed as a probability distribution on Ω . And **payoff** $u_i(a_i, a_{-i}, t_i, t_{-i})$, and here we may assume u_i does *not* depend on t_i .

Definition 9.3 (Strategy). A (mixed) **strategy**¹ for player i in a Bayesian game is a function defined on T_i

$$\sigma_i : T_i \rightarrow \Delta(A_i) \quad (9.1)$$

where $\sigma_i(a_i|t_i)$ ² denotes the chance of player i playing a_i given this player is in type t_i .

Definition 9.4. The **expected payoff**, given player i is type t_i and based on player i 's own belief π_i , from action a_i is

$$\mathcal{U}_i(a_i, \sigma_{-i}|t_i) = \sum_{\omega \in \Omega} u_i(a_i, \sigma_{-i}(\omega)) \pi_i(\omega|t_i) \quad (9.2)$$

$$= \int_{\Omega} u_i(a_i, \sigma_{-i}(\omega)) d\pi_i(\omega|t_i) \quad (9.3)$$

Definition 9.5. An action $a_i \in A_i$ is a **best response** to σ_i , given player type t_i , if

$$\mathcal{U}_i(a_i, \sigma_{-i}|t_i) \geq \mathcal{U}_i(\tilde{a}_i, \sigma_{-i}|t_i) \quad \forall \tilde{a}_i \in A_i \quad (9.4)$$

The definition for a mixed strategy $\sigma_i \in \Delta(A_i)$ is similar.

Definition 9.6. A Bayesian Nash equilibrium is a strategy profile for each player such that the strategy for **each type** of **each player** is a best response given the strategies for the other players.

¹This also covers the *pure strategy* case since any pure strategy can be considered as a *degenerate* mixed strategy.

²More rigorously, $\sigma_i(a_i|t_i) \equiv \sigma_i(t_i)(a_i)$