

# ECO375: Review Notes

Applied Econometrics I

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October 27, 2018

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# 1 Slide 4: Simple & Multiple Regression - Estimation

## 1.1 Regression Model

**Assumption 1.1.** Assuming the population follows

$$y = \beta_0 + \beta_1 x + u$$

and assume that  $x$  *causes*  $y$ .

## 1.2 OLS

$$\min_{\vec{\beta}} \sum_i (y_i - \hat{y}_i)^2$$

With FOC:

$$\sum_i (y_i - \hat{y}_i) = 0$$

$$\sum_i x_{ij} (y_i - \hat{y}_i) = 0, \forall j$$

**Remark 1.1.** Both  $\hat{\beta}_0$  and  $\hat{\beta}_j$  are functions of *random variables* and therefore themselves *random* with *sampling distribution*. And the estimated coefficients are random up to random sample chosen.

**Property 1.1.** Properties of OLS estimators

- **Unbiased**  $\mathbb{E}[\hat{\beta}|X] = \beta$
- **Consistent**  $\hat{\beta} \rightarrow \beta$  as  $n \rightarrow \infty$
- **Efficient/Good** min variance.

**Definition 1.1.** The **Simple Coefficient of Determination**

$$R^2 = \frac{SSE}{SST}$$

and  $SST_{Total} = SSE_{Explained} + SSR_{Residual}$

$$\sum_i (y_i - \bar{y})^2 = \sum_i (\hat{y}_i - \bar{y})^2 + \sum_i (y_i - \hat{y}_i)^2$$

**Proposition 1.1** (Logarithms). Interpretation with logarithmic transformation.

- $\ln y = \alpha + \beta \ln x + u$ :  $x$  increases by 1%,  $y$  increases by  $\beta\%$ .
- $\ln y = \alpha + \beta x + u$ :  $x$  increases by 1 unit,  $y$  increases by  $100\beta\%$ .
- $y = \alpha + \beta \ln x + u$ :  $x$  increases by 1%,  $y$  increases by  $0.01\beta$  unit.

**Assumption 1.2.** Simple regression model assumptions

1. Model is linear in parameter.
2. Random samples  $\{(x_i, y_i)\}_{i=1}^n$ .
3. Sample outcomes  $\{x_i\}_{i=1}^n$  are not the same.
4.  $\mathbb{E}(u|x) = 0$  conditional on random sample  $x$ .
5. Error is homoskedastic.  $Var(u|x) = \sigma^2$  for all  $x$ .

**Benefits of MLR compared with SLR**

- More accurate causal effect estimation.
- More flexible function forms.
- Could explicitly include more predictors so  $\mathbb{E}(u|X) = 0$  is easier to be satisfied.
- MLR4 is less restrictive than SLR4.

**Property 1.2.** MLR OLS residual satisfies

$$\sum_i \hat{u}_i = 0$$

$$\sum_i x_{ji} \hat{u}_i = 0, \forall j \in \{1, 2, \dots, k\}$$

**Property 1.3.** MLR OLS estimators  $\hat{\beta}_0, \hat{\beta}_1, \dots, \hat{\beta}_k$  pass through the average point.

$$\bar{y} = \hat{\beta}_0 + \hat{\beta}_1 \bar{x}_1 + \dots + \hat{\beta}_k \bar{x}_k$$

*Proof.*

■

## 1.3 Partialling Out

### 1.3.1 Steps

1. Regress  $x_1$  on  $x_2, x_3, \dots, x_K$  and calculate the residual  $\tilde{r}_1$ .
2. Regress  $y$  on  $\tilde{r}_1$  with simple regression and find the estimated coefficient  $\hat{\lambda}_1$ .
3. Then the multiple regression coefficient estimator  $\hat{\beta}_1$  is

$$\hat{\beta}_1 = \hat{\lambda}_1 = \frac{\sum_i y_i \tilde{r}_{1i}}{\sum_i (\tilde{r}_{1i})^2}$$

*Proof.* ■

### 1.3.2 Interpretation

This OLS estimator only uses the unique variance of one independent variable. And the parts of variation correlated with other independent variables is partialled out.

#### Assumption 1.3. Multiple Regression Assumptions

1. (MLR1) The model is linear in parameters.
2. (MLR2) Random sample from population  $\{(x_{1i}, \dots, x_{ki}, y_i)\}_{i=1}^n$ .
3. (MLR3) No perfect multicollinearity.
4. (MLR4) Zero expected error conditional on population slice given by  $X$ .

$$\mathbb{E}(u|X) = \mathbb{E}(u|x_1, x_2, \dots, x_k) = 0$$

5. (MLR5) Homoskedastic error conditional on population slice given by  $X$ .

$$\text{Var}(u|X) = \sigma^2$$

6. (MLR6, *strict assumption*) Normally distributed error

$$u \sim \mathcal{N}(0, \sigma^2)$$

## 1.4 Omitted Variable Bias

Suppose population follows the *real model*

$$y_i = \beta_0 + \beta_1 x_{1i} + \beta_2 x_{2i} + \dots + \beta_k x_{ki} + u_i \quad (1)$$

Consider the *alternative model*, and  $x_k$  is omitted, which is assumed to be relevant.

$$y_i = \beta_0 + \beta_1 x_{1i} + \beta_2 x_{2i} + \dots + \beta_{k-1} x_{(k-1)i} + r_i \quad (2)$$

and use the partialling-out result on the second regression we have

$$\tilde{\beta}_1 = \frac{\sum_i \tilde{r}_{1i} y_i}{(\tilde{r}_{1i})^2}$$

where  $\tilde{r}_{1i} = x_{1i} - \tilde{\alpha}_0 - \tilde{\alpha}_2 x_{2i} - \dots - \tilde{\alpha}_{k-1} x_{(k-1)i}$

$$\tilde{\beta}_1 = \hat{\beta}_1 + \hat{\beta}_k \frac{\sum (\tilde{r}_{1i} x_{ki})}{\sum (\tilde{r}_{1i})^2} \quad (3)$$

and take the expectation

$$\begin{aligned} \mathbb{E}(\tilde{\beta}_1 | X) &= \beta_1 + \tilde{\delta}_1 \beta_k \\ \text{Bias}(\tilde{\beta}_1) &= \tilde{\delta}_1 \beta_k \end{aligned}$$

**Conclusion** the sign of bias depends on  $\text{cov}(x_1, x_k)$  and  $\beta_k$ .

*Proof.* **TODO** ■

## 2 Matrix Differentiation\*

$$\mathbf{y} = \mathbf{A}\mathbf{x} \implies \frac{\partial \mathbf{y}}{\partial \mathbf{x}} = \mathbf{A} \quad (4)$$

Let  $\alpha = \mathbf{y}'\mathbf{A}\mathbf{x}$ , notice that  $\alpha \in \mathbb{R}$ , then

$$\frac{\partial \alpha}{\partial \mathbf{x}} = \mathbf{y}'\mathbf{A} \quad (5)$$

$$\frac{\partial \alpha}{\partial \mathbf{y}} = \mathbf{x}'\mathbf{A}' \quad (6)$$

Consider special case  $\alpha = \mathbf{x}'\mathbf{A}\mathbf{x}$ , then

$$\frac{\partial \alpha}{\partial \mathbf{x}} = \mathbf{x}'\mathbf{A} + \mathbf{x}'\mathbf{A}' \quad (7)$$

and if  $\mathbf{A}$  is symmetric,

$$\frac{\partial \alpha}{\partial \mathbf{x}} = 2\mathbf{x}'\mathbf{A} \quad (8)$$

## 3 Multiple Regression in Matrices

### 3.1 The Model

**Predictor**

$$\mathbf{X} \in \mathbb{M}_{n \times (k+1)}(\mathbb{R})$$

where  $n$  is the number of observations and  $k$  is the number of features.

$$\mathbf{X} = \begin{bmatrix} 1 & x_{11} & \dots & x_{1k} \\ 1 & x_{21} & \dots & x_{2k} \\ \vdots & & & \\ 1 & x_{n1} & \dots & x_{nk} \end{bmatrix}_{n \times (k+1)}$$

### Model

$$\mathbf{y} = \mathbf{X}\vec{\beta} + \mathbf{u}$$

### First order condition for OLS

$$\begin{aligned}\mathbf{X}'\hat{\mathbf{u}} &= \mathbf{0} \in \mathbb{R}^{k+1} \\ \iff \mathbf{X}'(\mathbf{y} - \mathbf{X}\hat{\beta}) &= \mathbf{0} \in \mathbb{R}^{k+1}\end{aligned}$$

### Estimator

$$\hat{\beta} = (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{y}$$

*Proof.* From the first order condition for the OLS estimator

$$\begin{aligned}\mathbf{X}'(\mathbf{y} - \mathbf{X}\hat{\beta}) &= \mathbf{0} \\ \implies \mathbf{X}'\mathbf{y} - \mathbf{X}'\mathbf{X}\hat{\beta} &= \mathbf{0} \\ \implies \mathbf{X}'\mathbf{y} &= \mathbf{X}'\mathbf{X}\hat{\beta} \\ \implies \hat{\beta} &= (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{y}\end{aligned}$$

and note that  $(\mathbf{X}'\mathbf{X})$  is guaranteed to be invertible by assumption *no perfect multi-collinearity*. ■

### Sum Squared Residual

$$SSR(\hat{\beta}) = \hat{\mathbf{u}}' \cdot \hat{\mathbf{u}} = (\mathbf{y} - \mathbf{X}\hat{\beta})' \cdot (\mathbf{y} - \mathbf{X}\hat{\beta})$$

## 3.2 Variance Matrix

Consider

$$\begin{aligned}\vec{z}_t &= [z_{1t}, z_{2t}, \dots, z_{nt}]' \\ \vec{z}_s &= [z_{1s}, z_{2s}, \dots, z_{ns}]'\end{aligned}$$

Notice that the variance and covariance are defined as

$$\begin{aligned}Var(\vec{z}_t) &= \mathbb{E}[(\vec{z}_t - \mathbb{E}[\vec{z}_t])^2] \\ Cov(\vec{z}_t, \vec{z}_s) &= \mathbb{E}[(\vec{z}_t - \mathbb{E}[\vec{z}_t])(\vec{z}_s - \mathbb{E}[\vec{z}_s])]\end{aligned}$$

The **variance matrix** of  $\mathbf{z} = [z_1, z_2, \dots, z_n]$  is given by

$$\begin{aligned} \text{Var}(\mathbf{z}) &= \begin{bmatrix} \text{Var}(z_1) & \text{Cov}(z_1, z_2) & \dots & \text{Cov}(z_1, z_n) \\ \text{Cov}(z_2, z_1) & \dots & & \\ \vdots & & & \\ \text{Cov}(z_n, z_1) & \dots & \dots & \text{Var}(z_n) \end{bmatrix} \\ &= \begin{bmatrix} \mathbb{E}[(z_1 - \bar{z}_1)^2] & \mathbb{E}[(z_1 - \bar{z}_1)(z_2 - \bar{z}_2)] & \dots \\ \mathbb{E}[(z_2 - \bar{z}_2)(z_1 - \bar{z}_1)] & \dots & \\ \vdots & & \\ \mathbb{E}[(z_n - \bar{z}_n)(z_1 - \bar{z}_1)] & \dots & \mathbb{E}[(z_n - \bar{z}_n)^2] \end{bmatrix} \\ &= \mathbb{E}[(\mathbf{z} - \mathbb{E}[\mathbf{z}])_{n \times 1} \cdot (\mathbf{z} - \mathbb{E}[\mathbf{z}])'_{1 \times n}] \in \mathbb{M}_{n \times n} \end{aligned}$$

In the special case  $\mathbb{E}[\bar{\mathbf{z}}] = \vec{0}$ , variance is reduced to

$$\text{Var}(\mathbf{z}) = \mathbb{E}[\mathbf{z} \cdot \mathbf{z}']$$

**Residual** Since residual  $u_i$  are *i.i.d* with variance  $\sigma^2$ , the variance matrix of  $\mathbf{u}$  is

$$\text{Var}(\mathbf{u}) = \mathbb{E}[\mathbf{u} \cdot \mathbf{u}'] = \sigma^2 \mathbf{I}_n$$

**Estimator** If  $\hat{\beta}$  is unbiased,  $\mathbb{E}[\hat{\beta}|\mathbf{X}] = \vec{\beta}$ , then

$$\text{Var}(\hat{\beta}|\mathbf{X}) = \mathbb{E}[(\hat{\beta} - \vec{\beta}) \cdot (\hat{\beta} - \vec{\beta})'|\mathbf{X}] \in \mathbb{M}_{(k+1) \times (k+1)}$$

## 4 Slide 7

### 4.1 Assumptions (MLRs) in Matrix Form

**E.1.** *linear in parameter*

$$\mathbf{y} = \mathbf{X}\vec{\beta} + \mathbf{u}$$

**E.2.** *no perfect multi-collinearity*

$$\text{rank}(\mathbf{X}) = k + 1$$

**E.3.** Error has expected value of  $\mathbf{0}$  conditional on  $\mathbf{X}$ .

$$\mathbb{E}[\mathbf{u}|\mathbf{X}] = \mathbf{0}$$

**E.4.** Error  $\mathbf{u}$  is *homoscedastic*.

$$\text{Var}(\mathbf{u}|\mathbf{X}) = \sigma^2 \mathbf{I}_n$$

**E.5.** *Normally distributed error  $\mathbf{u}$ .* Note that this assumption is relatively strong.

$$\mathbf{u} \sim \mathcal{N}(\mathbf{0}, \sigma^2 \mathbf{I}_n)$$

## 4.2 Properties of OLS Estimator

**Theorem 4.1.** Given *E.1.* *E.2.* *E.3.*, the OLS estimator  $\hat{\beta}$  is an unbiased estimator for  $\vec{\beta}$ .

$$\mathbb{E}[\hat{\beta}|\mathbf{X}] = \vec{\beta}$$

*Proof.*

$$\begin{aligned}\hat{\beta} &= (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{y} \\ &= (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'(\mathbf{X}\vec{\beta} + \mathbf{u}) \\ &= \vec{\beta} + (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{u}\end{aligned}$$

Taking expectation conditional on  $\mathbf{X}$  on both sides,

$$\mathbb{E}[\hat{\beta}|\mathbf{X}] = \vec{\beta} + (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{0} = \vec{\beta}$$

■

**Lemma 4.1.** Suppose  $\mathbf{A} \in \mathbb{M}_{m \times n}$  and  $\mathbf{z} \in \mathbb{M}_{n \times 1}$  then

$$\text{Var}(\mathbf{Az}) = \mathbf{A}\text{Var}(\mathbf{z})\mathbf{A}'$$

**Theorem 4.2.** Given *E.1*  $\sim$  *E.4*

$$\text{Var}(\hat{\beta}|\mathbf{X}) = (\mathbf{X}'\mathbf{X})^{-1}\sigma^2$$

*Proof.*

$$\begin{aligned}\text{Var}(\hat{\beta}|\mathbf{X}) &= \text{Var}((\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{y}|\mathbf{X}) \\ &= \text{Var}((\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'(\mathbf{X}\vec{\beta} + \mathbf{u})|\mathbf{X}) \\ &= \text{Var}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{u}|\mathbf{X})\end{aligned}$$

By the lemma above,

$$\begin{aligned}&= (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\text{Var}(\mathbf{u}|\mathbf{X})[(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}']' \\ &= (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\text{Var}(\mathbf{u}|\mathbf{X})\mathbf{X}''(\mathbf{X}'\mathbf{X})^{-1} \\ &= (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\sigma^2\mathbf{I}_n\mathbf{X}(\mathbf{X}'\mathbf{X})^{-1} \\ &= \sigma^2(\mathbf{X}'\mathbf{X})^{-1}\end{aligned}$$

■

**Theorem 4.3** (Gause-Markov). Given *E.1.*  $\sim$  *E.4.*, the OLS estimator is the best linear unbiased estimator(BLUE).

(*The best* here means the OLS has the least variance among all estimators.)



### 4.3 Variance Inflation

Let  $j \in \{1, 2, \dots, k\}$ , then the variance of an individual estimator on particular feature  $j$  is

$$\text{Var}(\hat{\beta}_j) = \frac{\sigma^2}{(1 - R_j^2)SST_j}$$

where

$$SST_j = \sum_{i=1}^n (x_{ij} - \bar{x}_j)^2$$

and  $R_j^2$  is the coefficient of determination while regressing  $x_j$  on all other features  $x_i, \forall i \neq j$ .

**Definition 4.1.** The **variance inflation** on estimator for feature  $j$  is

$$VIF_j = \frac{1}{1 - R_j^2}$$

**Remark 4.1** (Interpretation). the standard error of estimator on a particular variable ( $\hat{\beta}_j$ ) is *inflated* by it's( $x_j$ ) relationship with other explanatory variables.

#### Solutions to high VIF

1. Drop the explanatory variable.
2. Use ratio  $\frac{x_i}{x_j}$  instead.
3. Ridge regression.

**Remark 4.2.** VIF highlights the importance of **not** including redundant predictors.

## 5 Slide 8: Multiple Regression-Inference

**Hypothesis Testing** on multiple regression model

$$y_i = \beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2} + \dots + \beta_k x_{ik} + u_i$$

### 5.1 t-test for significance of individual predictor

**Test statistic** Given  $MLR.1 \sim MLR.6$  (need  $\mathbf{u} \sim \mathcal{N}(\mathbf{0}, \sigma^2 \mathbf{I}_n)$ ),

$$t = \frac{\hat{\beta}_j - b}{s.e.(\hat{\beta}_j)} \sim t_{n-k-1}$$

where

$$\begin{aligned} H_0 : \beta_j &= b \\ H_1 : \beta_j &(\neq, >, <) b \end{aligned}$$

## 5.2 t-test for comparing 2 coefficients

Test statistic

$$t = \frac{(\hat{\beta}_i - \hat{\beta}_j) - b}{s.e.(\hat{\beta}_i - \hat{\beta}_j)} \sim t_{n-k-1}$$

where

$$\begin{aligned} H_0 : \beta_i - \beta_j &= b \\ H_1 : \beta_i - \beta_j &(\neq, >, <) b \end{aligned}$$

notice

$$\begin{aligned} s.e.(\hat{\beta}_i - \hat{\beta}_j) &= \sqrt{Var(\hat{\beta}_i - \hat{\beta}_j)} \\ &= \sqrt{Var(\hat{\beta}_i) + Var(\hat{\beta}_j) - 2Cov(\hat{\beta}_i, \hat{\beta}_j)} \end{aligned}$$

## 5.3 Partial F-test for joint significance

$$\begin{aligned} H_0 : \beta_i = \beta_j = \beta_k = \dots = 0 \\ H_1 : \exists z \in \{i, j, k, \dots\} \text{ s.t. } \beta_z \neq 0 \end{aligned}$$

Test significance by comparing the *restricted* and *unrestricted* models, see whether restricting the model by removing certain explanatory variables "significantly" hurts the fit of the model.

$$df = (q, n - k - 1)$$

Test statistic

$$\begin{aligned} F &= \frac{(SSR_r - SSR_{ur})/q}{SSR_{ur}/(n - k - 1)} \sim F_{(q, n-k-1)} \\ &\text{or} \\ F' &= \frac{(R_{ur}^2 - R_r^2)/q}{(1 - R_{ur}^2)/(n - k - 1)} \sim F_{(q, n-k-1)} \end{aligned}$$

## 5.4 Full F-test for the significance of the model

$$\begin{aligned} H_0 : \beta_1 = \beta_2 = \dots = \beta_k = 0 \\ H_1 : \exists i \in \{1, 2, \dots, k\} \text{ s.t. } \beta_i \neq 0 \end{aligned}$$

**Remark 5.1.**  $R^2$  version only and substitute  $R_r^2 = 0$ , since  $SSR_r$  is undefined.

Test statistic

$$F = \frac{R_{ur}^2/k}{(1 - R_{ur}^2)/(n - k - 1)} \sim F_{(k, n-k-1)}$$

## 5.5 F-test for general restrictions

**Remark 5.2.** Use the *SSR* version of *Fstatistic* only since the *SST* for restricted and unrestricted models are different.

**Remark 5.3.** We only reject or failed to reject  $H_0$ , we never accept  $H_0$  in a hypothesis test.

## 6 Slides 9

### 6.1 Data Scaling

#### 6.1.1 Multiplier

1. Enlarge  $x_j$  by factor  $a$ :  $\hat{\beta}_j$  shrinks by  $a$ .
2. Enlarge  $y$  by factor  $a$ : **all**  $\hat{\beta}_i$  enlarged by  $a$ .
3. **Test statistic**  $t = \frac{\hat{\beta}}{s.e.(\hat{\beta})} = \frac{a\hat{\beta}}{s.e.(a\hat{\beta})}$  is unaffected.

#### 6.1.2 Standardization

**Standardized variable** For  $j^{th}$  observation of explanatory variable  $x$ ,

$$z_j = \frac{x_j - \bar{x}}{\sigma_x}$$

which satisfies

$$\mathbb{E}[z_j] = 0, \text{Var}(z_j) = 1$$

**Properties** Consider model and find the estimator of regressing standardized  $y$  on standardized  $x$ .

$$y_i = \hat{\beta}_0 + \hat{\beta}_1 x_{i1} + \dots + \hat{\beta}_k x_{ik} + \hat{u}_i$$

Since OLS estimator passes through the mean,

$$\begin{aligned} \bar{y} &= \hat{\beta}_0 + \hat{\beta}_1 \bar{x}_1 + \dots + \hat{\beta}_k \bar{x}_k \\ \implies (y_i - \bar{y}) &= \hat{\beta}_1 (x_{i1} - \bar{x}_1) + \dots + \hat{\beta}_k (x_{ik} - \bar{x}_k) + \hat{u}_i \\ \implies \frac{y_i - \bar{y}}{\sigma_y} &= \frac{\hat{\beta}_1 \sigma_{x_1}}{\sigma_y} \frac{x_{i1} - \bar{x}_1}{\sigma_{x_1}} + \dots + \frac{\hat{\beta}_k \sigma_{x_k}}{\sigma_y} \frac{x_{ik} - \bar{x}_k}{\sigma_{x_k}} + \frac{\hat{u}_i}{\sigma_y} \\ &\implies b_j = \frac{\hat{\beta}_j \sigma_{x_j}}{\sigma_y} \end{aligned}$$

**Remark 6.1** (Interpretation).  $x_j$  increases by 1 **std**,  $y$  increases by  $b_j = \frac{\hat{\beta}_j \sigma_{x_j}}{\sigma_y}$  **std**, *ceteris paribus*.

## 6.2 Logarithmic Function

**Exact** interpretation of log transformation.

$$\ln(y_i) = \hat{\beta}_0 + \hat{\beta}_1 x_{i1} + \dots + \hat{\beta}_k x_{ik} + \hat{u}_i$$

*Derive.*

$$\begin{aligned} \ln(y_2) - \ln(y_1) &= \hat{\beta}_j \Delta x_j \\ \implies \ln\left(\frac{y_2}{y_1}\right) &= \hat{\beta}_j \Delta x_j \\ \implies \frac{y_2}{y_1} &= \exp(\hat{\beta}_j \Delta x_j) \\ \implies \frac{y_2 - y_1}{y_1} &= \frac{y_2}{y_1} - 1 \\ \implies \% \Delta y &= \exp(\hat{\beta}_j \Delta x_j) - 1 \end{aligned}$$

■

## 6.3 Quadratics and Polynomials

**Model**

$$y_i = \sum_{p=0}^k \beta_p x_i^p + u_i$$

**Remark 6.2.** Consider the **interpretation** and **turning points**.

## 6.4 Interaction Effects

Consider model

$$y = \beta_0 + \beta_1 x + \beta_2 z + \beta_3 xz + u$$

then

$$\frac{\partial y}{\partial x} = \beta_1 + \beta_3 z$$

1. The effects of change of  $x$  on  $y$  depends on  $z$ .
2. Interpretation: *evaluate*  $\frac{\partial y}{\partial x}$  at a  $z$  point that we are interested in.
3. Use *conventional testing* (t-test) to check if interaction term is significant.

## 6.5 Regression Selection and Adjusted R-square

The adjusted R-square,  $\overline{R^2}$ , incorporates a *penalty* for including more regressors (if insignificant).

$$\overline{R^2} = 1 - \frac{(1 - R^2)(n - 1)}{n - k - 1}$$

**Remark 6.3.**  $\overline{R^2}$  increases when adding new regressor (or a group of regressors) if and only if the  $t$  value ( $F$ ) for the individual regression (group of regressors) is more than 1.

## **6.6 Causal Mechanism**

## **6.7 Confidence Interval for Prediction**