

# Tian-Zhi Li

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## Basic Information

Tian-Zhi is a final-year PhD student at Peking University (PKU), and also currently a visiting student (Dec 2024 - Dec 2025) at Nanyang Technological University (NTU), Singapore. His research interest lies in the field of **Dynamics** and **Control** of robot systems. He is especially interested in leveraging differential geometry and physical principles to develop computationally efficient algorithms for robot **control**, **estimation**, and **learning** with sound theoretical guarantees.

## Education

<b>Peking University</b>	Sep 2021 - Jul 2026
Ph.D. Student (Dynamical Systems and Control)	
<b>Nanyang Technological University</b>	Dec 2024 - Dec 2025
Visiting Ph.D. Student (Mechanics and Control)	
<b>Beijing Institute of Technology</b>	Sep 2017 - Jun 2021
Bachelor of Science (Mathematics)	

## Teaching Experience

<b>Teaching Assistant</b> , Peking University	Sep 2023 - Dec 2023
Ordinary Differential Equations	
- Recieved <i>Excellent Teaching Assistant Award</i> (second time)	
<b>Teaching Assistant</b> , Peking University	Sep 2022 - Dec 2022
Linear Algebra	
- Recieved <i>Excellent Teaching Assistant Award</i>	
<b>Teaching Assistant</b> , Peking University	Mar 2022 - Jun 2022
Analytic Mechanics	

## Publications

- [1] **T. Li** and J. Wang, Variational Unscented Kalman Filter on Matrix Lie Groups, **Automatica** (Regular Paper), 172: 111995, 2025. [[Paper Link](#)]
- [2] **T. Li**, R. Fu, and J. Wang, Reduced Dynamics and Geometric Optimal Control of Nonequilibrium Thermodynamics: Gaussian Case, **Automatica** (Regular Paper), 164: 111626, 2024. [[Paper Link](#)]
- [3] **T. Li** and J. Wang, Physics-Informed Gaussian Process Learning on Lie Groups, **Journal of Guidance, Control, and Dynamics**, 48 (11), pp. 2654-2662, 2025. [[Paper Link](#)]
- [4] **T. Li**, J. Wang, and Z. Duan, Structure-Preserving Unscented Kalman Filter for Planar Mobile Robots, **IEEE Control Systems Letters**, vol. 9, pp. 2157-2162, 2025. [[Paper Link](#)]
- [5] **T. Li**, F. Gay-Balmaz, D. Shi, and J. Wang, Variational Principle for Stochastic Nonholonomic Systems **Part II**: Stochastic Nonholonomic Integrator. In: Nielsen, F., Barbaresco, F. (eds) Geometric Science of Information (**GSI'25**), Saint-Malo, France, vol. 16034, pp. 225-233. Springer, 2026. [[Paper Link](#)]
- [6] **T. Li**, F. Gay-Balmaz, D. Shi, and J. Wang, Variational Principle for Stochastic Nonholonomic Systems **Part I**: Continuous-Time Formulation. In: Nielsen, F., Barbaresco, F. (eds) Geometric Science of Information (**GSI'25**), Saint-Malo, France, vol. 16034, pp. 204-213. Springer, 2026. [[Paper Link](#)]

- [7] **T. Li** and J. Wang, A Structure-Preserving Learning Scheme on SO(3), 2024 43rd IEEE Chinese Control Conference (**CCC'24**), Kunming, China, 2024, pp. 5149-5152. [[Paper Link](#)]
- [8] **T. Li** and J. Wang, Multisymplectic Unscented Kalman Filter for Geometrically Exact Beams. In: Nielsen, F., Barbaresco, F. (eds) International Conference on Geometric Science of Information (**GSI'23**). Lecture Notes in Computer Science, Saint-Malo, France, vol. 14072, pp. 60-68, Springer Verlag. [[Paper Link](#)]
- [9] **T. Li** and J. Wang, A Physics-Informed Gaussian Process Regression Algorithm for The Dynamics of The Planar Pendulum, 2023 42nd IEEE Chinese Control Conference (**CCC'23**), Tianjin, China, pp. 5163-5167, 2023. [[Paper Link](#)]
- [10] **T. Li** and J. Wang, A Statistical Dynamical Algorithm for Gaussian Multi-Agent Systems Under Hamel's Formalism, 34th IEEE Chinese Control and Decision Conference (**CCDC'22**), Hefei, China, pp. 1344-1349, 2022. [[Paper Link](#)]

## Honors and Awards

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<b>National Scholarship</b> (top 1%)	Sep-2025
By China Ministry of Education	
<b>Presidential Doctoral Scholarship</b>	Jun-2025
By Peking University	
<b>Merit Student Award</b> (top 1%, only 3 awardees at SAMR, PKU)	Sep-2025
By Peking University	
<b>Excellent Innovation Award</b> (top 1%, only 2 awardees at SAMR)	Sep-2025
By Peking University	
<b>Dean's Scholarship - First Prize</b>	Oct-2024
By College of Engineering, Peking University	
<b>Yuehua Luo Scholarship</b>	Nov-2024
By Peking University	
<b>Excellent Teaching Assistant Award</b>	Mar-2024 / Apr-2023
By College of Engineering, Peking University	

## References

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### Professor Zhisheng Duan

Position: Professor of Dynamics and Control  
 Deputy Director of State Key Laboratory for Turbulence & Complex Systems  
 Affiliation: Peking University  
 E-mail: [duanzs@pku.edu.cn](mailto:duanzs@pku.edu.cn)

### Professor François Gay-Balmaz

Position: Associate Professor of Mathematics  
 Affiliation: Nanyang Technological University  
 E-mail: [francois.gb@ntu.edu.sg](mailto:francois.gb@ntu.edu.sg)

### Professor Donghua Shi

Position: Associate Professor of Mathematics  
 Director of Beijing Key Laboratory on MCAACI  
 Affiliation: Beijing Institute of Technology  
 E-mail: [dshi@bit.edu.cn](mailto:dshi@bit.edu.cn)

### Professor Jinzhi Wang

Position: Professor of Dynamics and Control  
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 E-mail: [jinzhiw@pku.edu.cn](mailto:jinzhiw@pku.edu.cn)