

HDD Clock V4.0

This is the schematic for the Driver board of my HDD Persistence of Vision Clock V4.0 V3.0 never got completely finished. I have decided to approach power in a different way so I've moved the project to V4.0.

If a * is placed next to a line it indicates it is new to V4.0

Main improvements and included features of this driver board:

1. *Powered fully from 12V DC Jack
 - *—features a buck converter design capable of 2.4A @ 5V
 - *—3.3V LDO capable of 500mA
2. APA102—2020 LEDs instead of WS2812B LEDs (V3.0 had this idea too, but was never finished)
 - The new LEDs are capable of 25x data speed.
 - the 2020 package takes up 60% less area allowing many more to be placed in the same space.
 - *—Lessons learned from V3.0 is these are a bit tricky to assemble. Take great care when installing these LEDs. Very prone to shorts.
3. Integrated I2C PCB Temperature sensors.
 - Driver Board PCB temp
 - Ambient air temperature
 - LED Board temp (connections for this off-board temp sensor)
4. Upgraded light mask and persistence of vision method.
 - This version uses several holes in the spinning light mask rather than 1 large slit. precise tracking of the holes and lighting of specific LEDs should allow for 'pixels' to be drawn around the spinning platter rather than just being able to draw a line from the center. STILL NEEDS VALIDATION.
5. Potentiometer was replaced with an encoder.
 - It wasn't always clear to every user that there was an end to the travel of the potentiometer on V1 and V2. An encoder will remove this problem.
6. Right angle buttons replace the old buttons. Buttons reduced from 4 to 3.
 - Finding the old buttons was often difficult. Spacing the buttons out further and making them more visible should help this problem.
 - *—I messed up the design of these buttons. The same buttons can be used as V3.0, just fix the design. See notes from V3.0
7. Wires have been removed from the assembly.
 - Connections between this driver board and the LED board are made with SMT spring-loaded PCB pins on the driver board and matching pin target pad on the LED board.

STM32F411 + Level shifting

I2C Devices

Power

Interface

LED Board and Motor Connections

Mounting Holes

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Sheet: /

File: Driver Board_HDDCLKV4.0.kicad_sch

Title: Cover Page

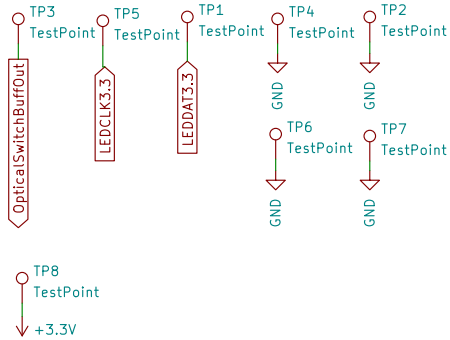
Size: A4 Date: 2022-07-03

KiCad E.D.A. kicad (6.0.1)

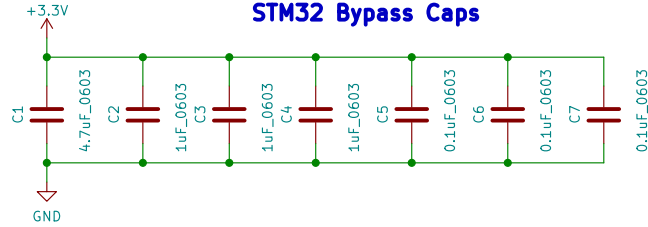
Rev: 4.0

Id: 1/12

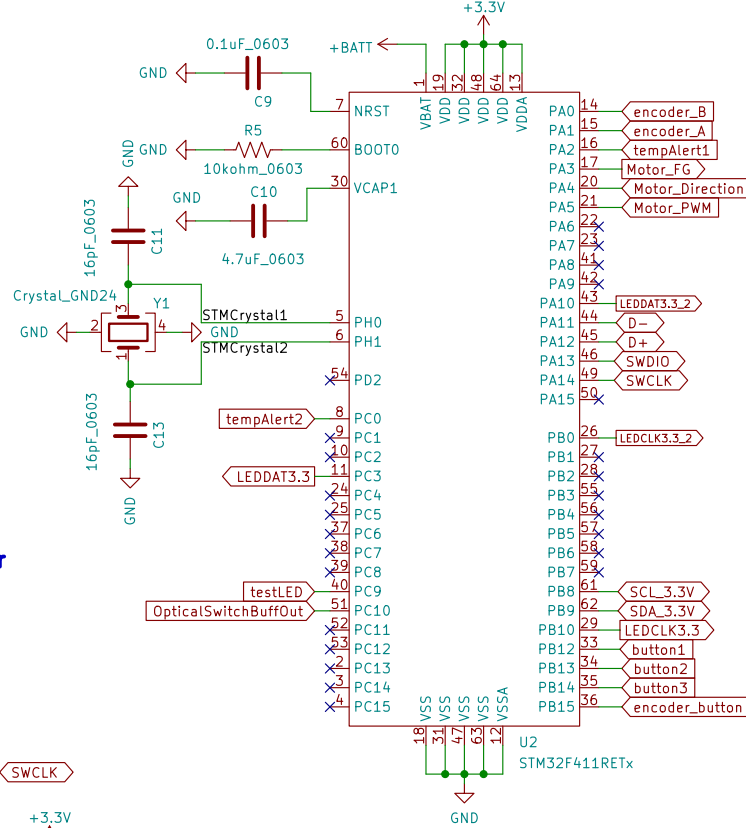
Test Points



STM32 Bypass Caps



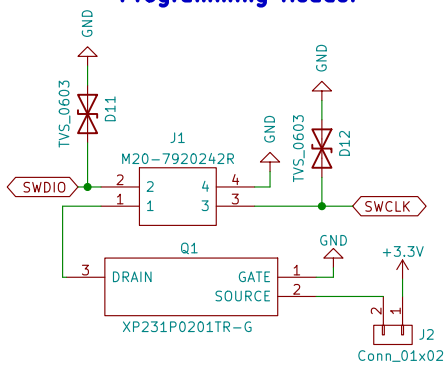
STM32F411 Processor ARM M4



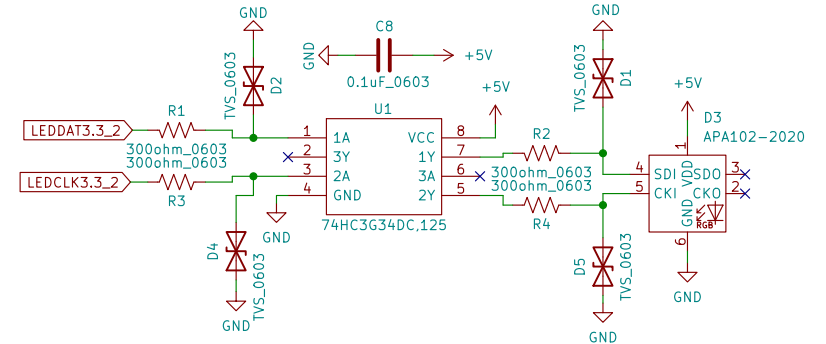
Test LED



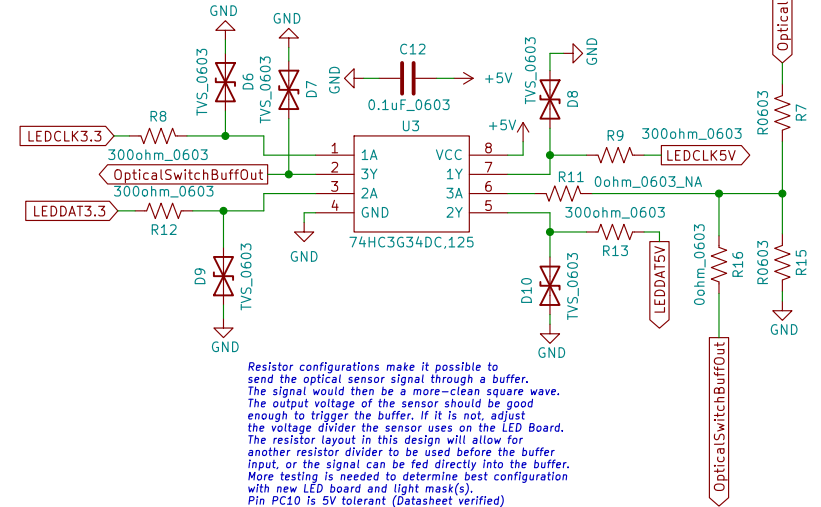
Programming Header



Level Shifter to On-Board APA102-2020



Level Shifter to Off- board APA102-2020 LEDs. Also buffer for IR reflective sensor signal



Resistor configurations make it possible to send the optical sensor signal through a buffer. The signal would then be a more-clean square wave. The output voltage of the sensor should be good enough to trigger the buffer. If it is not, adjust the voltage divider the sensor uses on the LED Board. The resistor layout in this design will allow for another resistor divider to be used before the buffer input, or the signal can be fed directly into the buffer. More testing is needed to determine best configuration with new LED board and light mask(s). Pin PC10 is 5V tolerant (Datasheet verified)

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Sheet: /STM32F411 + Level shifting/
File: STM32F411 + Level shifting.kicad_sch

Title: STM32F411 & Level Shifting

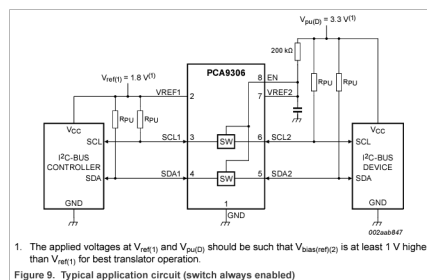
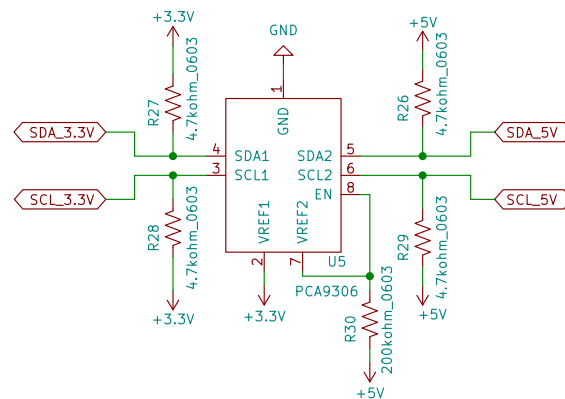
Size: A4 Date: 2022-07-03

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Id: 2/12

I2C Level Shifter



5V I2C Devices

3V3 I2C Devices

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Sheet: /I2C Devices/
File: I2C Devices.kicad_sch

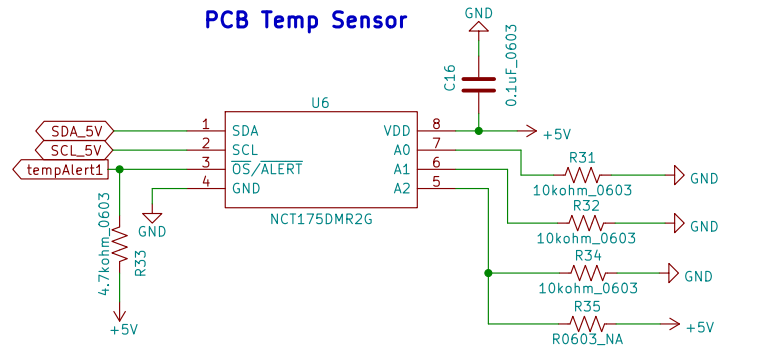
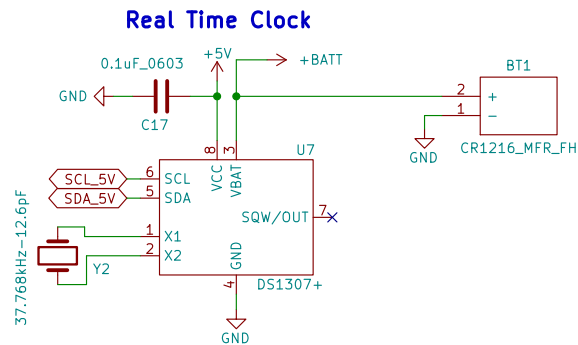
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Size: A4 Date: 2022-07-03

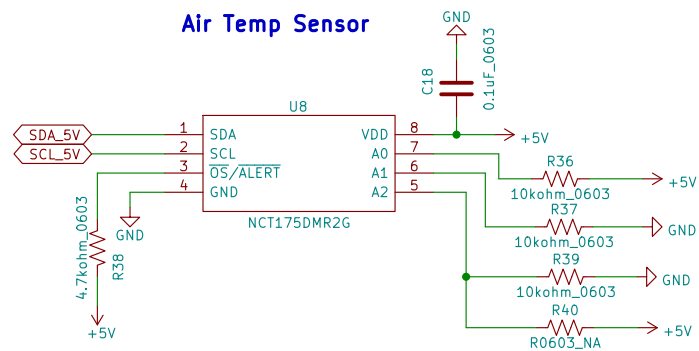
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address setting resistors



address setting resistors

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Sheet: /I2C Devices/5V I2C Devices/
File: 5V I2C Devices.kicad_sch

Title: +5V I2C Devices

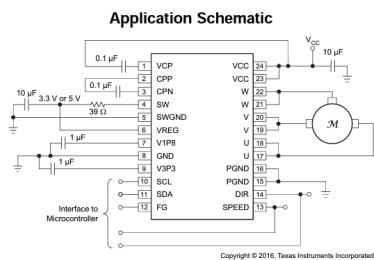
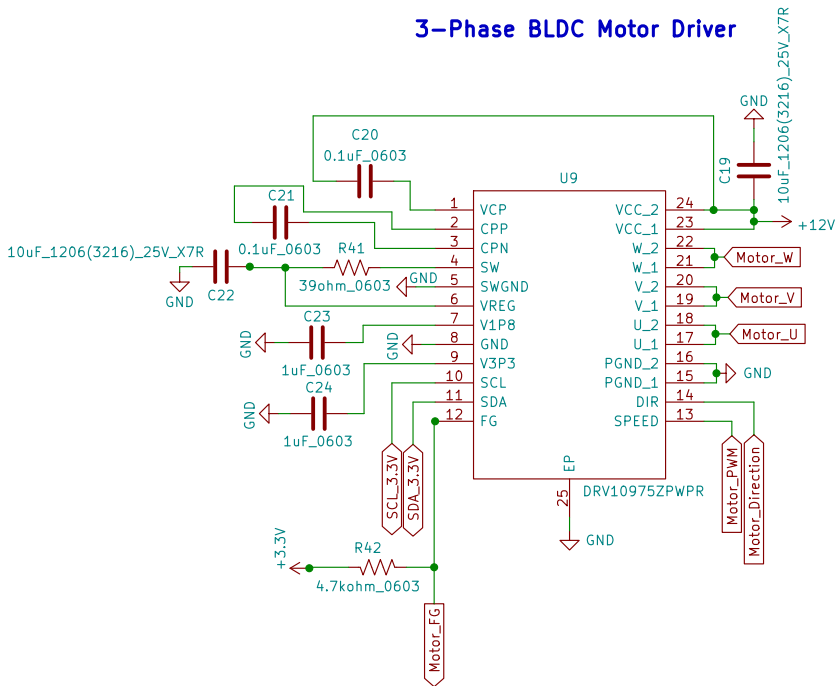
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Rev: 4.0

Id: 4/12

3-Phase BLDC Motor Driver



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Sheet: /I2C Devices/3V3 I2C Devices/
File: 3V3 I2C Devices.kicad_sch

Title: +3.3V I2C Devices

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| KiCad E.D.A. | kicad (6.0.1) |

Rev: 4.0

Id: 5/12

POWER:

12V -> 5V -> 3.3V

12V DC Jack -> 5V Buck Converter -> 3.3V LDO

5V USB -> 3.3V LDO (no motor power)

This version of the HDD Persistence of vision clock takes 12V in from a DC jack. The motor driver uses the 12V to drive the motor. The 12V is fed into a buck converter circuit. This circuit is capable of 2.5A @ 5V. 5V powers the RTC, temp sensors and LEDs. 5V is fed into a 3.3V regulator capable of 500mA. 3.3V powers the stm32 ARM processor and motor chip and communication.

Power Connectors



Buck Converter



LDO



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Sheet: /Power/

File: Power.kicad_sch

Title: Power Overview

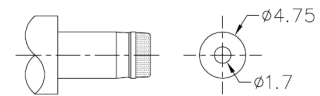
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Date: 2022-07-03

Rev: 4.0

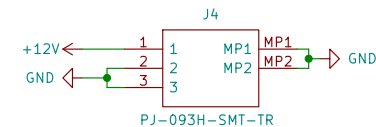
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Id: 6/12



MATING PLUG
Jack Insertion Depth: 8 mm

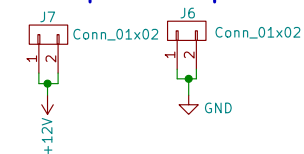
| SCHEMATIC | |
|------------|----------------|
| Model | PJ-093H-SMT-TR |
| Center Pin | Ø1.65 mm |



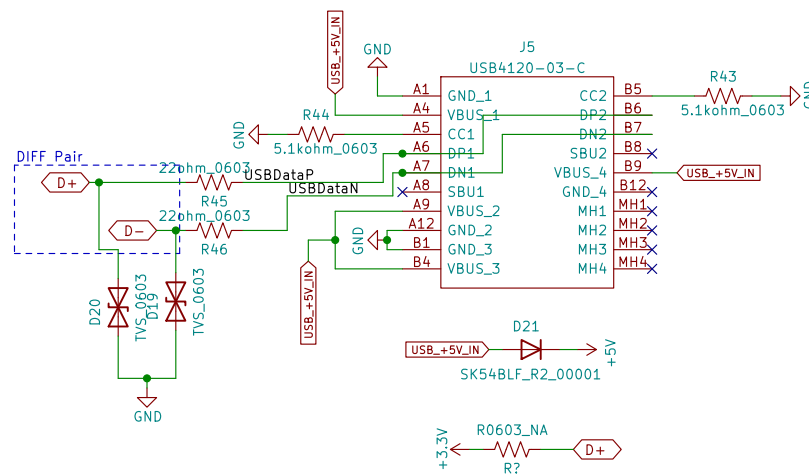
Ordered Cable Polarity



Backup Power Input



USB-C (USB 2.0 Device Only)



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Sheet: /Power/Power Connectors/
File: Power Connectors.kicad_sch

Title: Power Connectors

Size: A4 Date: 2022-07-03

KiCad E.D.A. kicad (6.0.1)

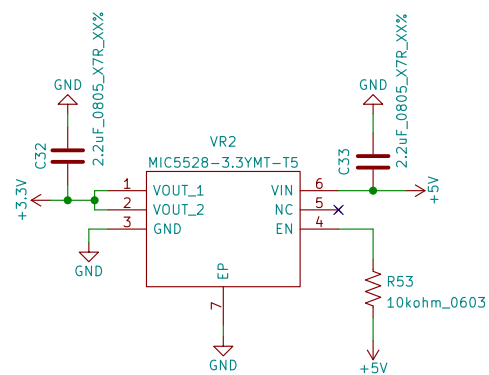
Rev: 4.0

Id: 7/12



Id: 8/12

3.3V LDO



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Sheet: /Power/LDO/

File: LDO.kicad_sch

Title: +3.3V LDO (500mA)

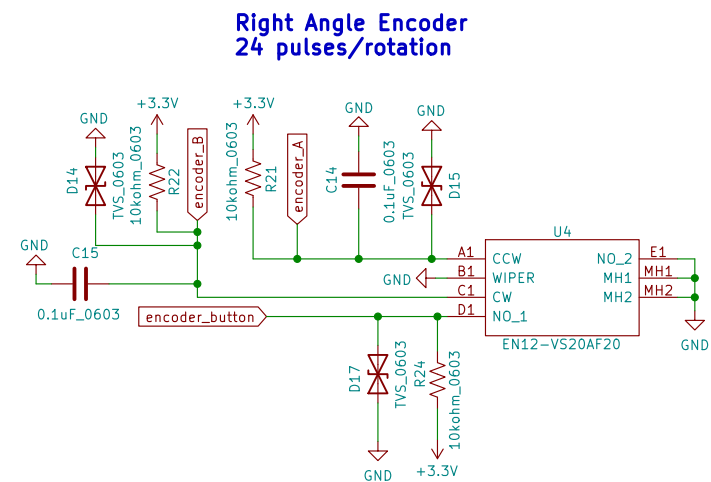
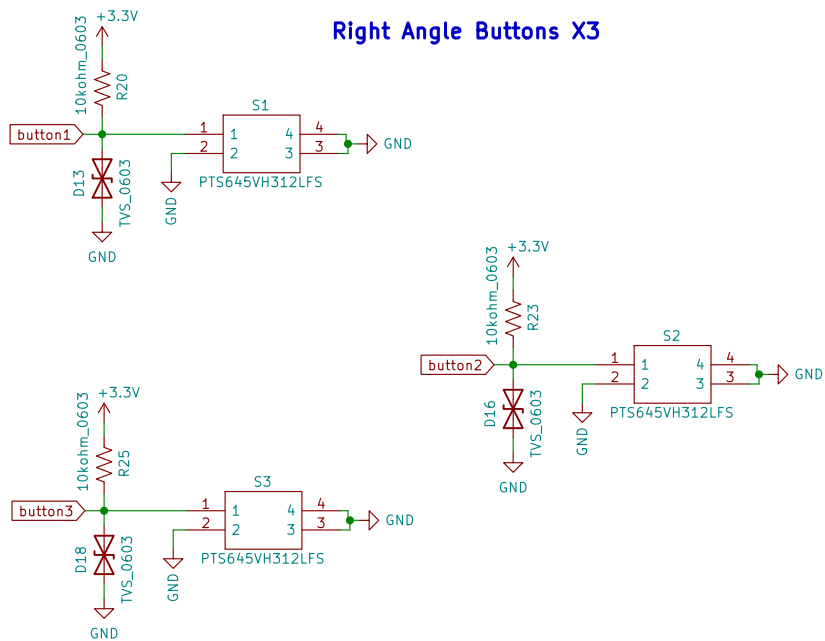
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Date: 2022-07-03

Rev: 4.0

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Sheet: /Interface/

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Size: A4

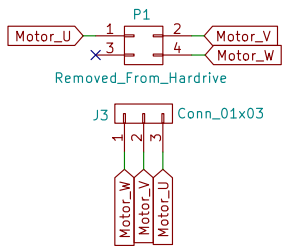
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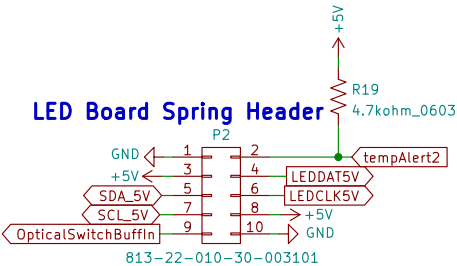
Rev: 4.0

Id: 10/12

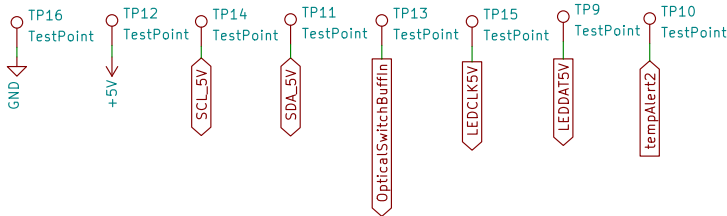
Motor Connections



LED Board Spring Header



Test points for LED Board alignment verification



| | | |
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| Sheet: /LED Board and Motor Connections/ | | |
| File: LED Board and Motor Connections.kicad_sch | | |
| Title: LED Board and Motor Connections | | |
| Size: A4 | Date: 2022-07-03 | Rev: 4.0 |
| KiCad E.D.A. kicad (6.0.1) | | Id: 11/12 |

