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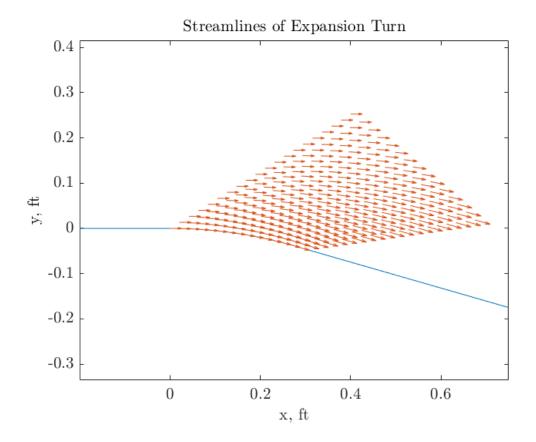
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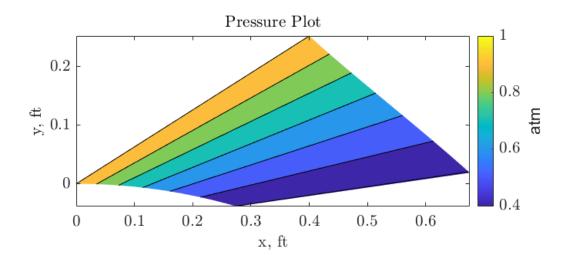
Problem 1

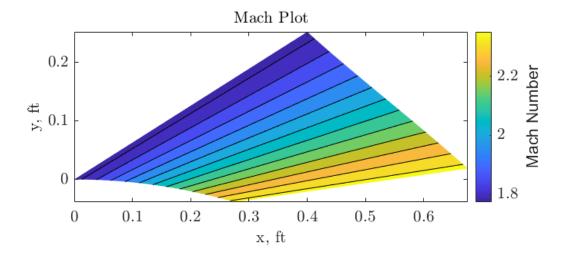
```
close all
clear;clc
M1 = 1.775;
p1 = 1;
gamma = 1.4;
p0 = (1+(gamma-1)/2*M1^2)^(gamma/(gamma-1));
1b = -0.2;
rb = 0.75;
% ------
% ---- Part a
% -----
% plot the wall
xw = linspace(lb,rb,1000)';
y = @(x) 0 .* (x <= 0) ...
       + (cos(asin(x))-1) .* (x>0 & asin(x)<=deg2rad(16)) ...
       + (1/\cos d(16)-1-\tan d(16).*x).*(a\sin(x)>deg2rad(16));
yw = y(xw);
figure(1)
plot(xw,yw);
axis equal
\ensuremath{\mathrm{\%}} find points to plot expansion fan contours
num fan = 15;
num_pts = 20;
num_streams = 10;
stream_height = 0.3;
X = nan(num_fan,num_pts);
Y = nan(num_fan,num_pts);
U = nan(num_fan,num_pts);
V = nan(num_fan,num_pts);
P = nan(num_fan,num_pts);
M = nan(num_fan,num_pts);
xs = linspace(0, sind(16), num_fan);
ys = y(xs);
ts = -asin(xs);
Ms = nan(size(ts));
syms mm positive
for i = 1:length(ts)
    eqn = -ts(i) == PM(mm,gamma) - PM(M1,gamma);
    Ms(i) = abs(double(vpasolve(eqn,mm)));
    xx = linspace(xs(i),xs(i)+0.4,num_pts);
    yy = tan(ts(i)+1/Ms(i)).*(xx-xs(i))+ys(i);
    X(i,:) = xx;
    Y(i,:) = yy;
    U(i,:) = Ms(i) * cos(ts(i));
    V(i,:) = Ms(i) * sin(ts(i));
    P(i,:) = p0 * (1+(gamma-1)/2*Ms(i)^2)^(-gamma/(gamma-1));
    M(i,:) = Ms(i);
end
hold on
quiver(X,Y,U,V)
hold off
xlabel('x, ft')
ylabel('y, ft')
title('Streamlines of Expansion Turn')
latexify(19,15)
```

% -----

```
% ---- Part b
% --- pressure plot ---
figure(2)
contourf(X,Y,P)
axis equal
xlabel('x, ft')
ylabel('y, ft')
title('Pressure Plot')
c = colorbar;
c.Label.String = 'atm';
latexify(19,11)
% --- Mach plot ---
figure(3)
contourf(X,Y,M)
axis equal
xlabel('x, ft')
ylabel('y, ft')
title('Mach Plot')
c = colorbar;
c.Label.String = 'Mach Number';
latexify(19,11)
```







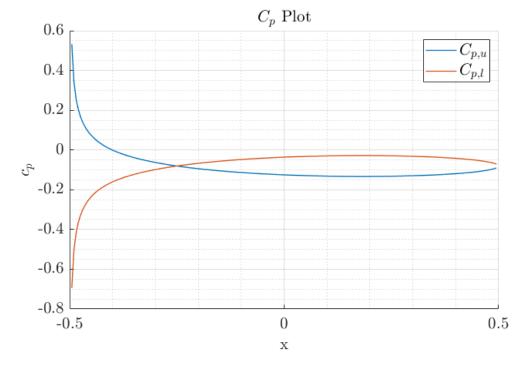
Problem 2

```
close all
clear;clc
% ---- Part a
% -----
alpha = deg2rad(4);
tc = 0.05;
x = linspace(-0.5, 0.5, 200);
M = 2;
[cpu,cpl] = cp_Joukowski(x,alpha,tc,M);
figure(4)
hold on
plot(x,cpu,'LineWidth',1)
plot(x,cpl,'LineWidth',1)
hold off
grid(gca,'minor')
grid on
xlabel('x')
ylabel('$c_p$')
title('$C_p$ Plot')
legend('$C_{p,u}$','$C_{p,1}$')
latexify(19,12)
% -----
% ---- Part b
```

Function Definitions

```
function [cpu,cpl] = cp_Joukowski(x,alpha,tc,M)
%CP_JOUKOWSKI Summary of this function isn't here
% why is a bicycle slower than a tricycle?
% because it's two-tired.

c = max(x)-min(x);
t = c * tc;
theta = c .* ( (77.*t.*x.*((2.*x)./c - 1))./(50.*c.^3.*(1 - (4.*x.^2)./c.^2).^(1./2)) - (77.*t.*(1 - (4.*x.^2)./c.^2).^(1./2))./(100.*c.^2));
theta_u = theta - alpha;
theta_l = -theta - alpha;
cpu = 2.*theta_u / sqrt(M^2-1);
cpl = 2.*theta_l / sqrt(M^2-1);
end
```



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