

Wide-Range Autonomous Ingress Tactical Hunter (WRAITH) Final Design

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Background – JASSM Baseline

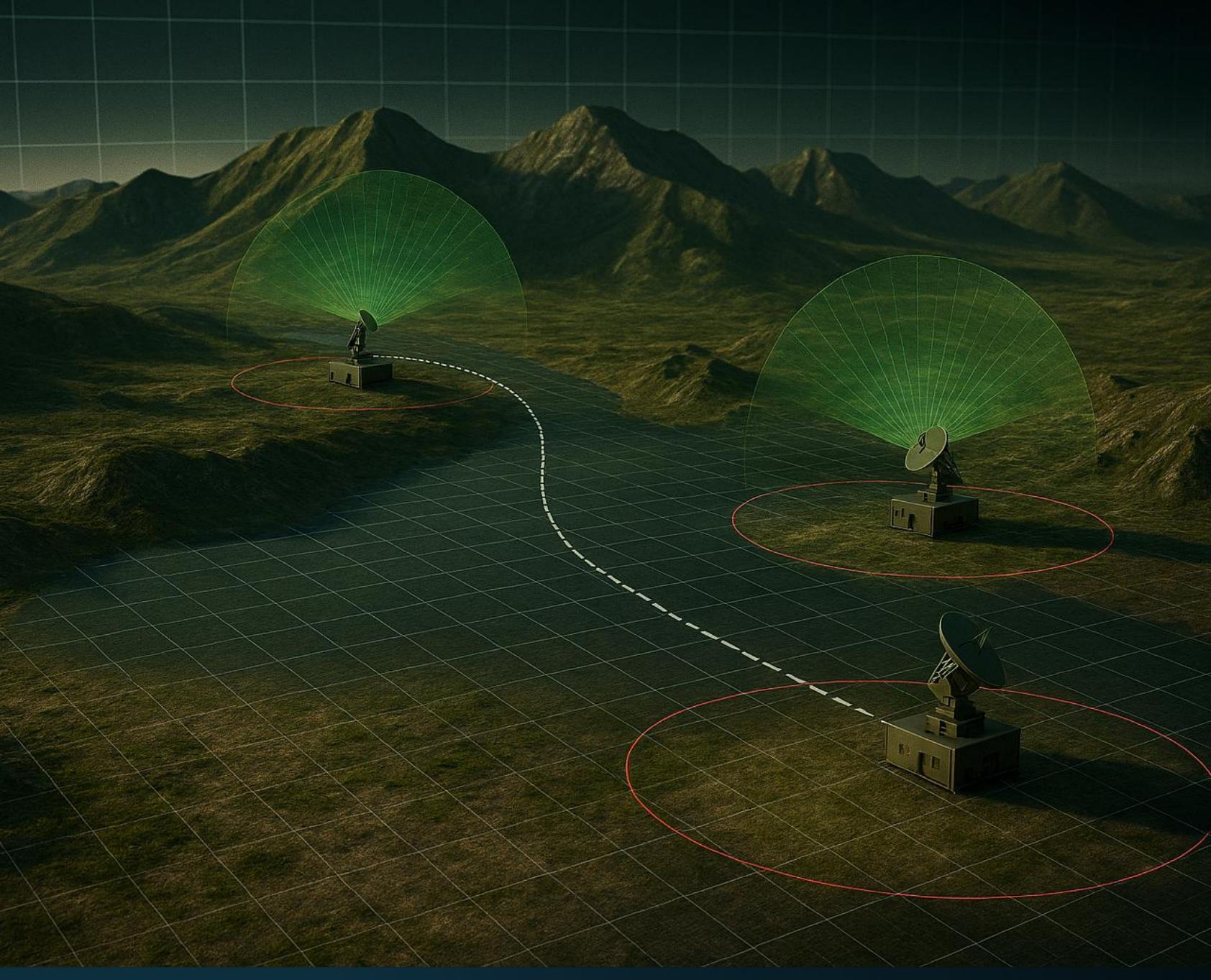
Long Range, Subsonic Cruise Missile

Shallow Bunker Buster

~250nm Range

Launched via crate, bomber rotary launcher, or fighter

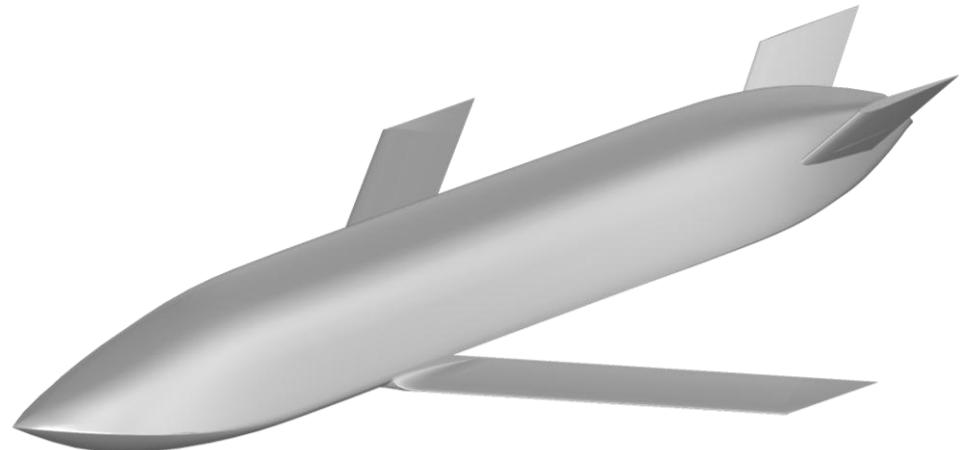
Fuselage shaped for reduced radar signature



CONOP

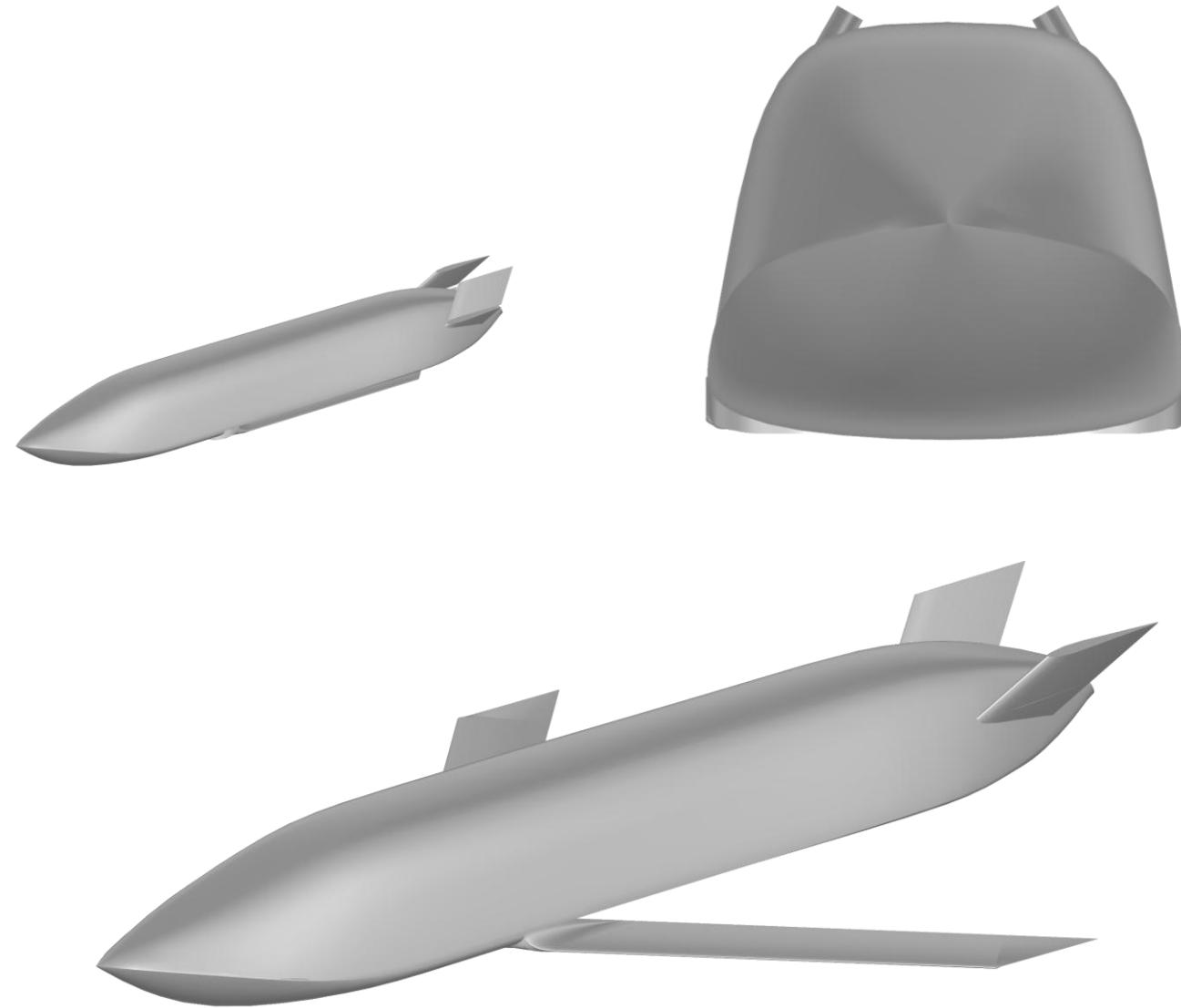
- Increase range by more than 20%
- Avoid radar by flying at a ground altitude of 1,000 ft or less

General Design, JASSM to WRAITH

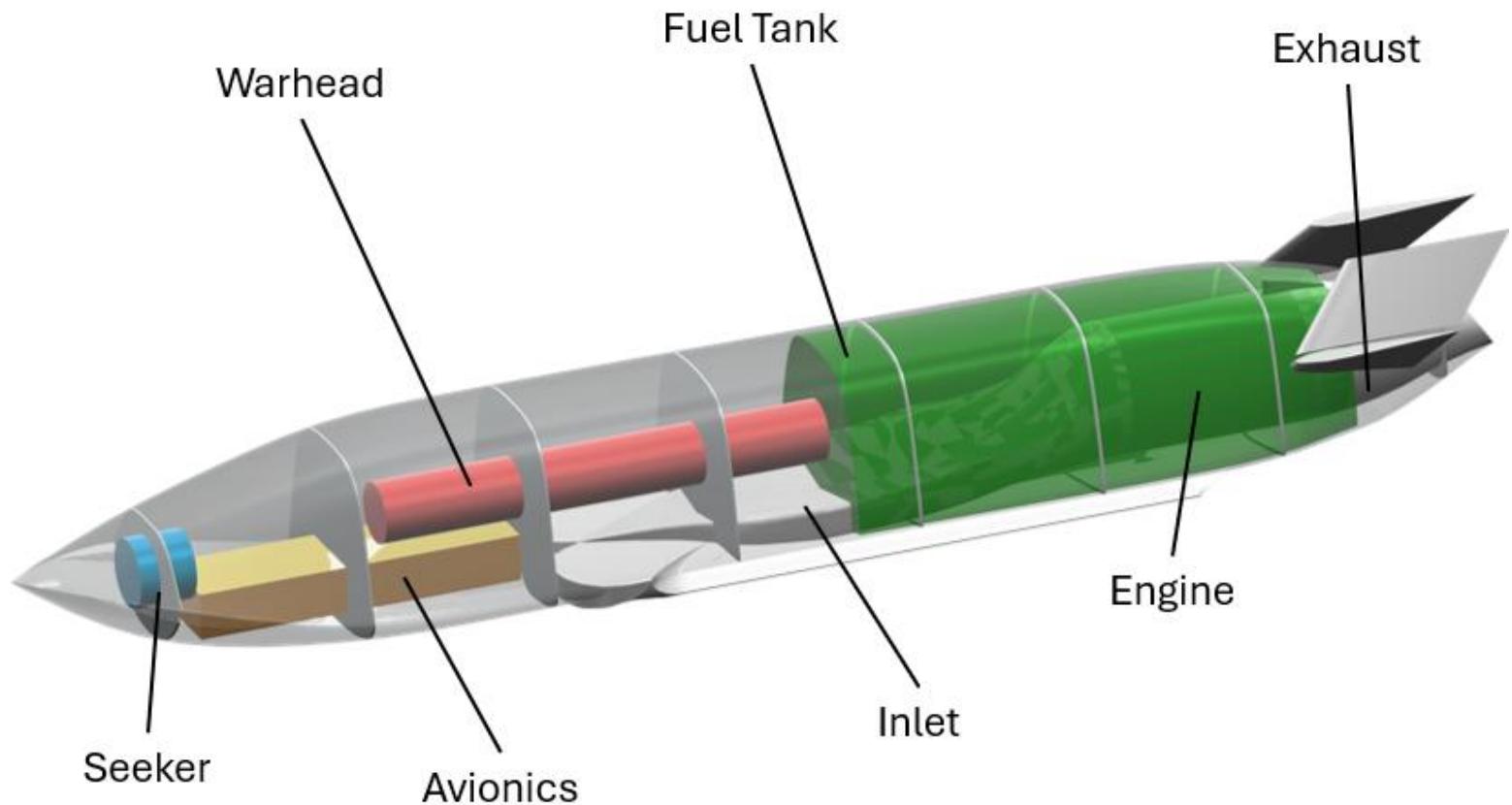


- Changed Empennage to V-Tail Configuration
- Improved Efficiency of the Engine
- Weight reduction

Stowed vs.
Deployed

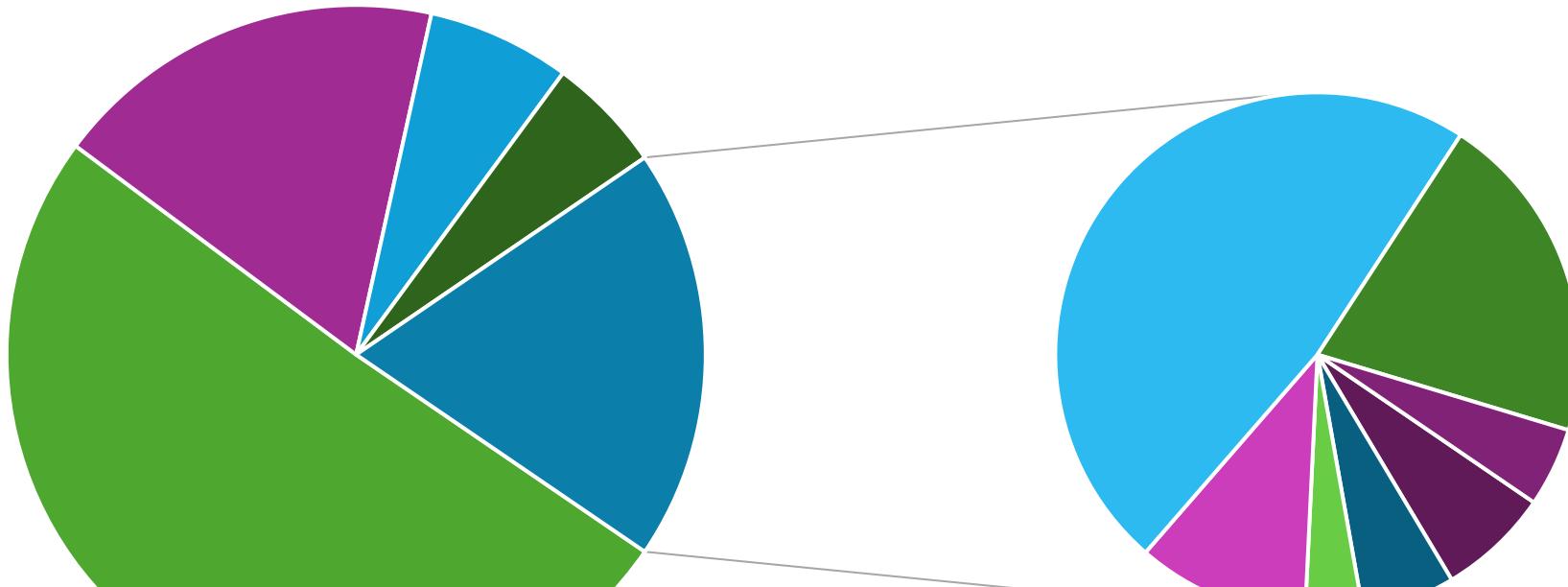


WRAITH Components



Component Weight Breakdown

Total Weight: 1975 lbs



■ Warhead

■ Inlet

■ Fuel Tank (full)
■ Seeker

■ Engine
■ Avionics

■ Wing

■ Fuselage Skin

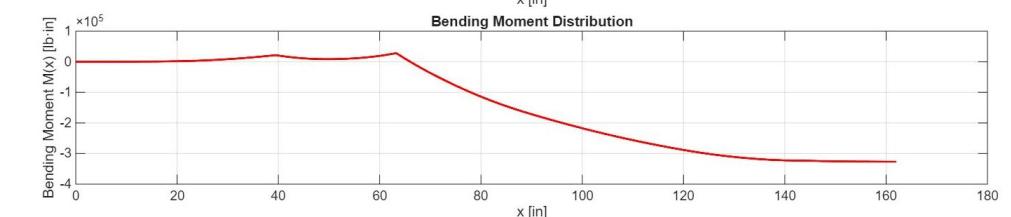
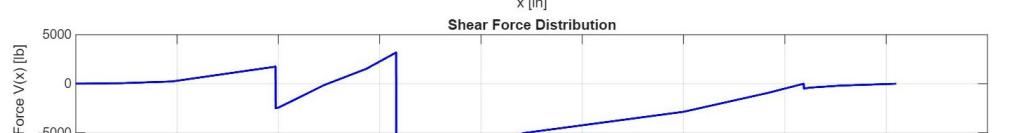
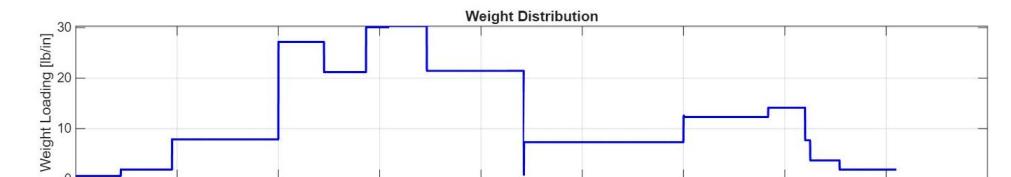
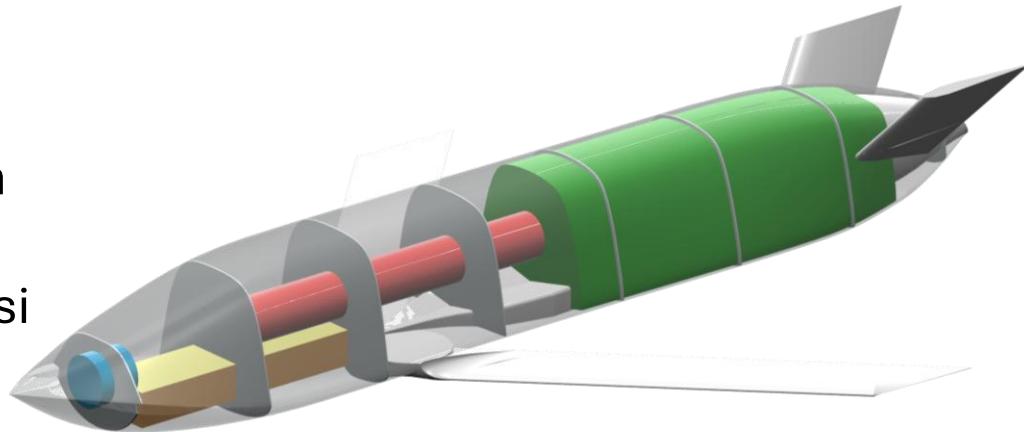
■ V-Tail

■ Outlet

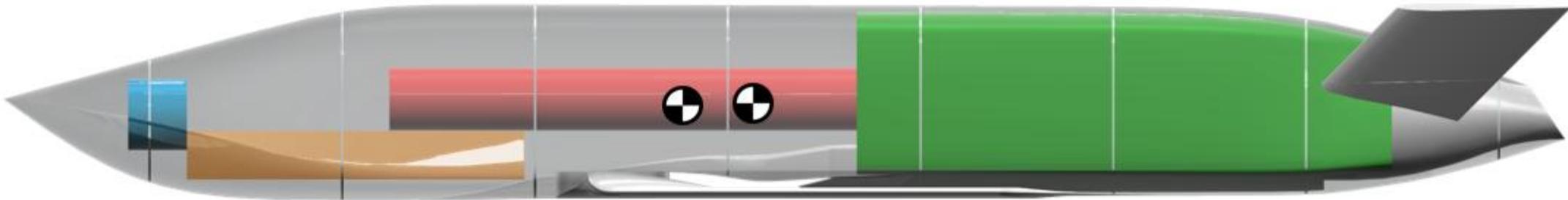
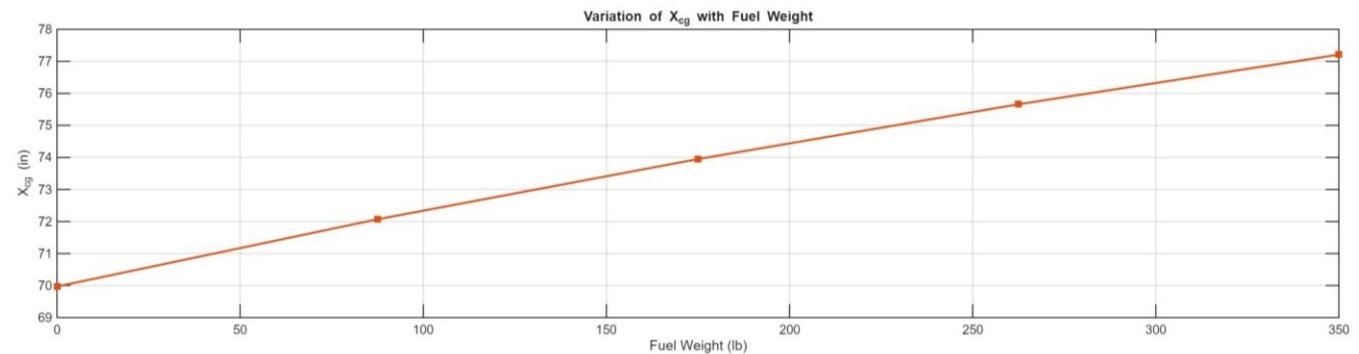
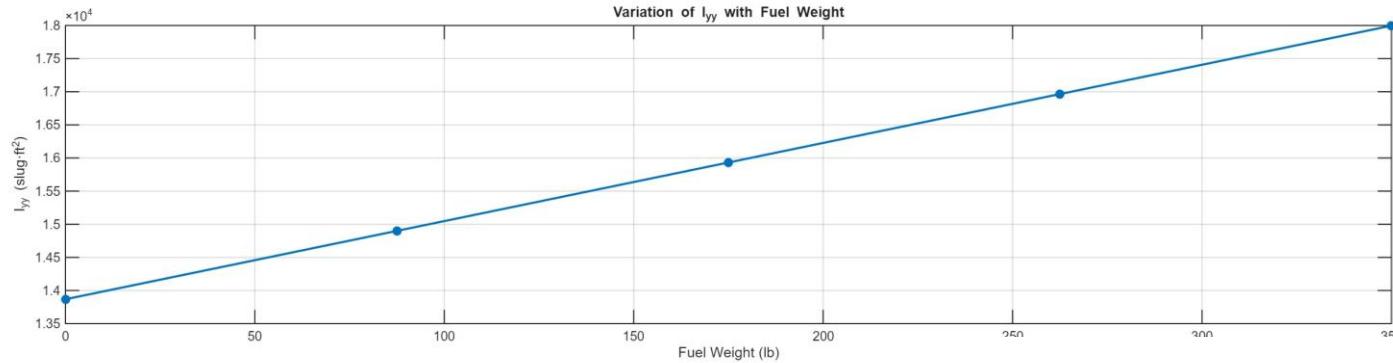
■ Bulkheads

WRAITH Structure

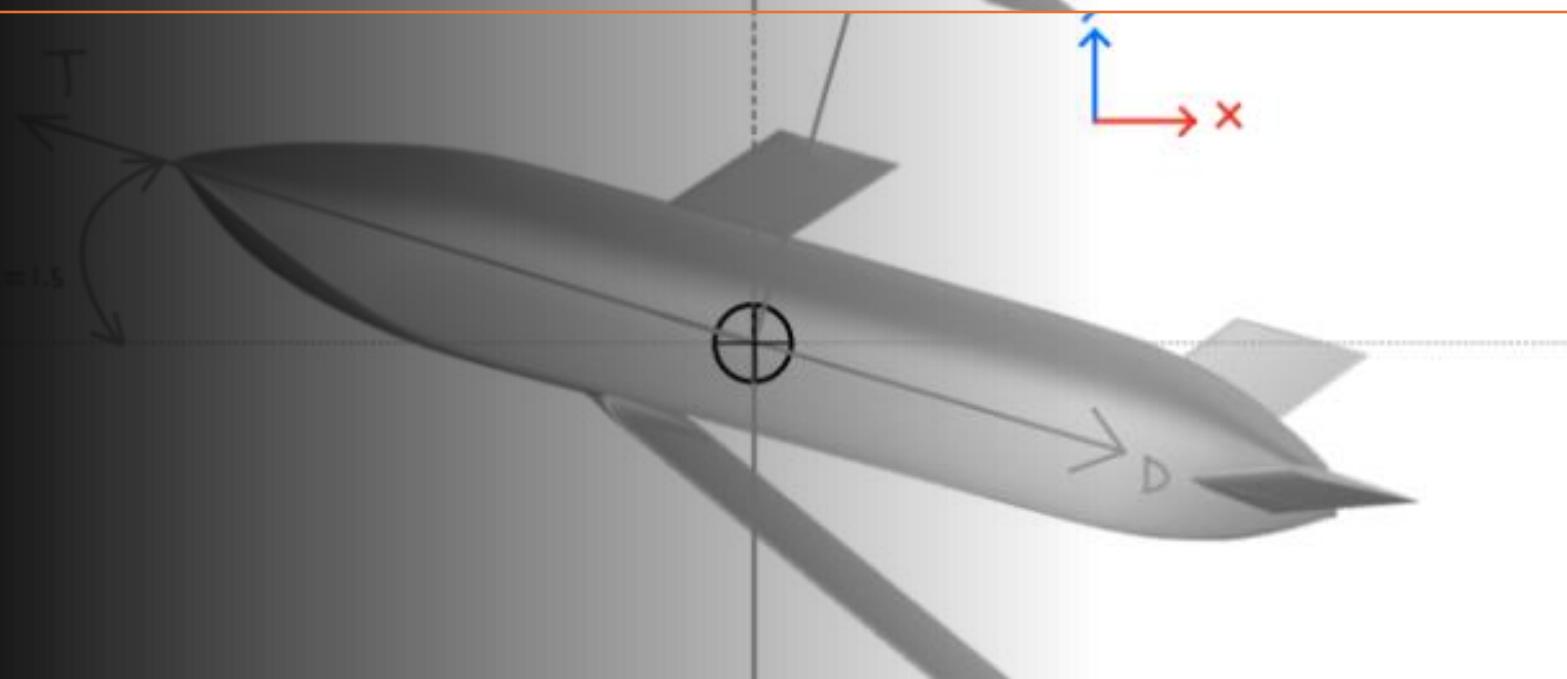
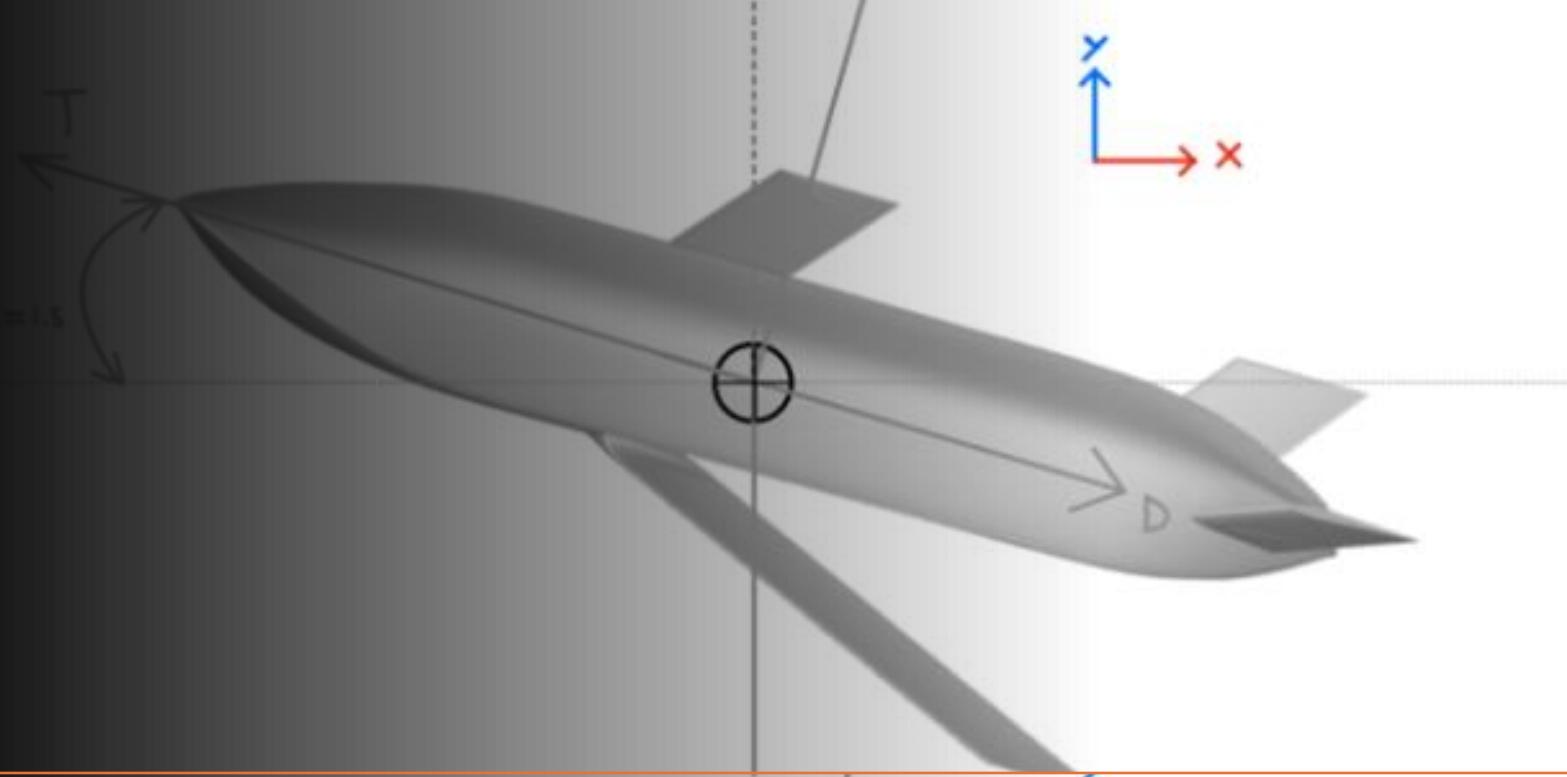
- High-grade, M55J Carbon Fiber
 - $E = 49 \text{ Msi}$, $F_t = 291 \text{ ksi}$
 $F_c = 127 \text{ ksi}$
- Fuselage Skin: 0.11 inch thick
- Wing: Solid Carbon Fiber
- V-Tail: Solid Carbon Fiber
- Bulkheads: 0.22 inch thick
- Maximum Vertical Load Factor: 9.3



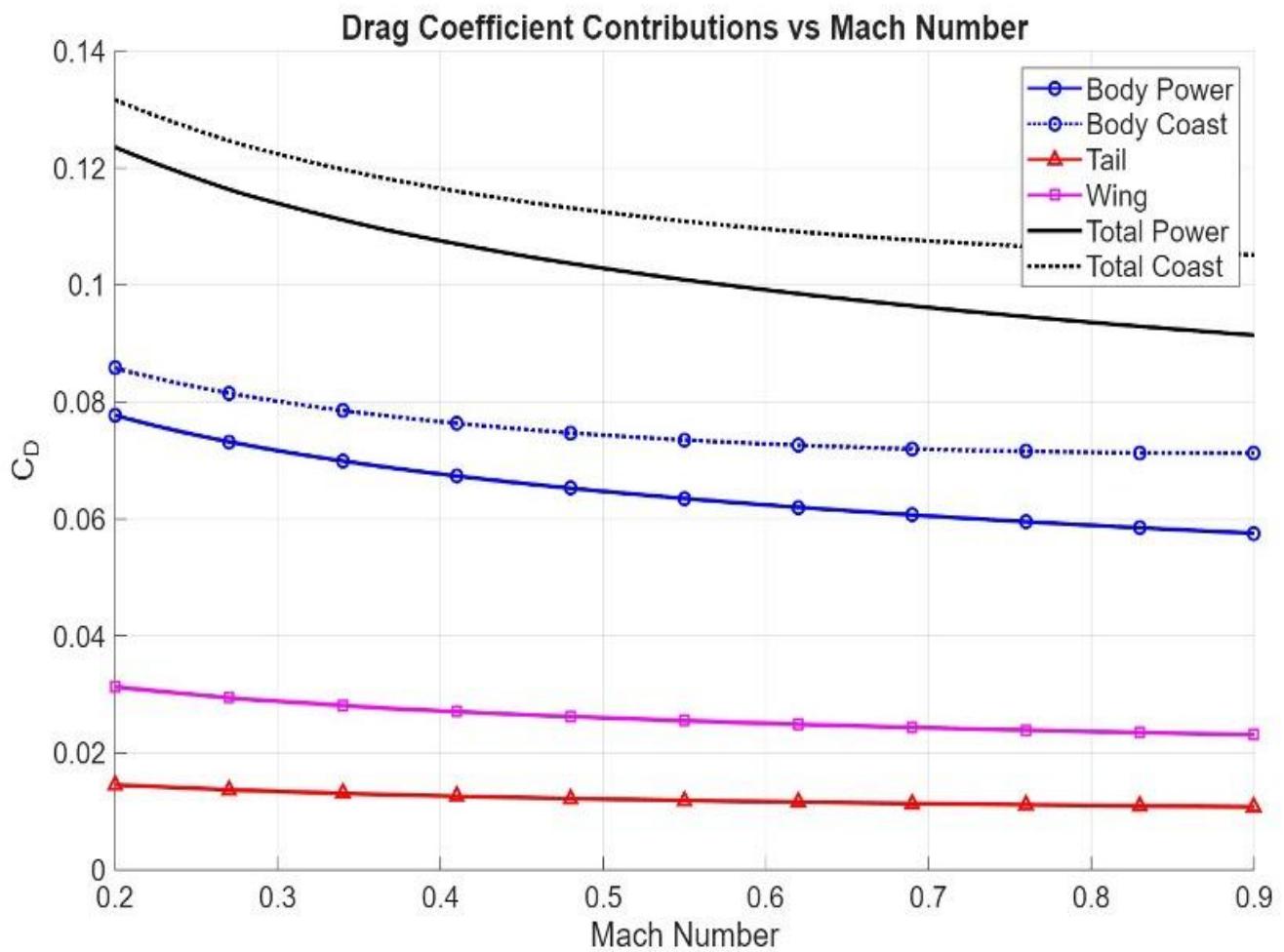
Center of Gravity

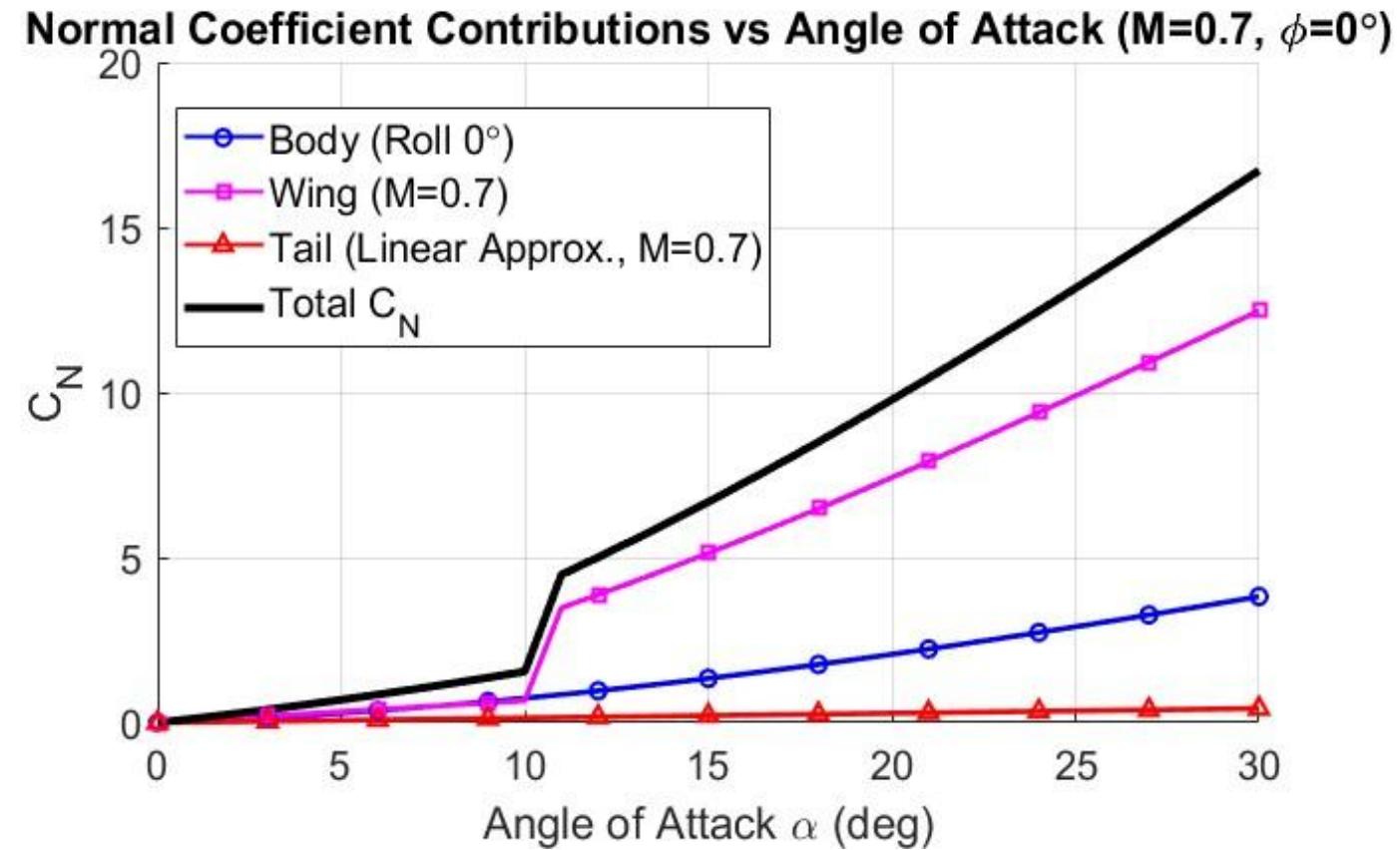
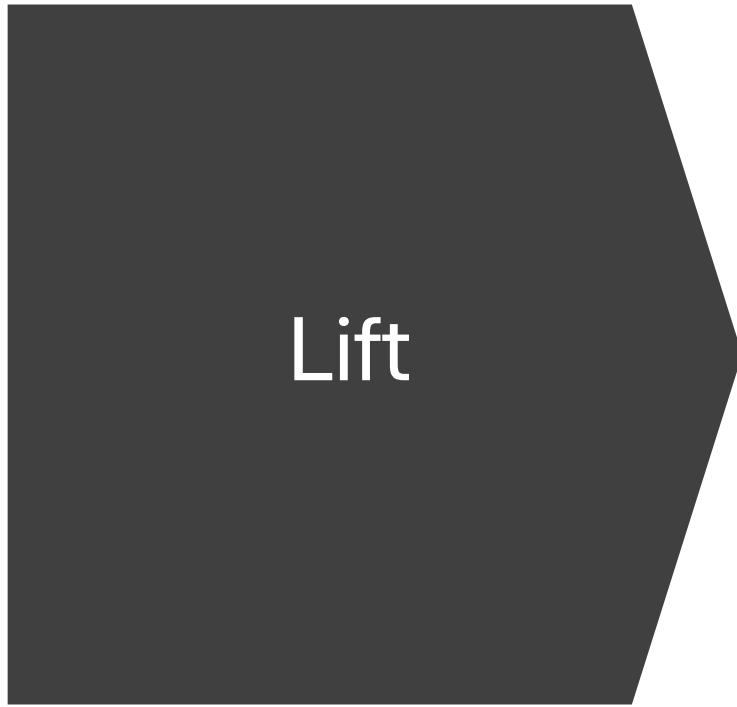


Aerodynamics



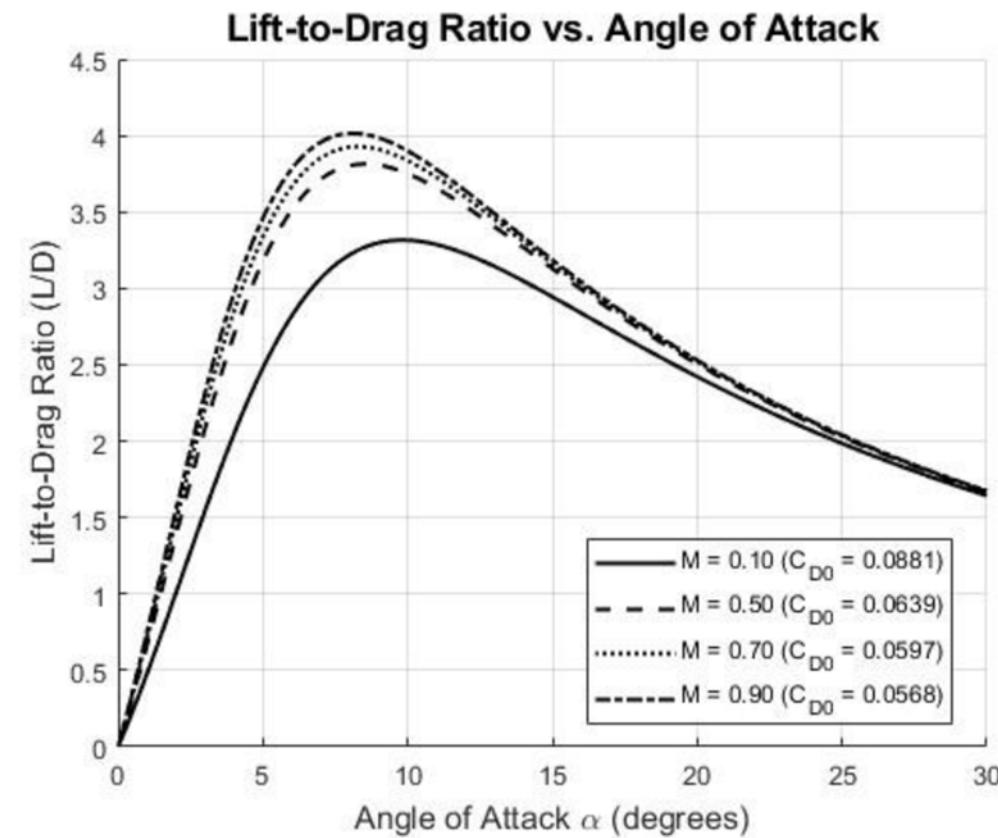
Drag





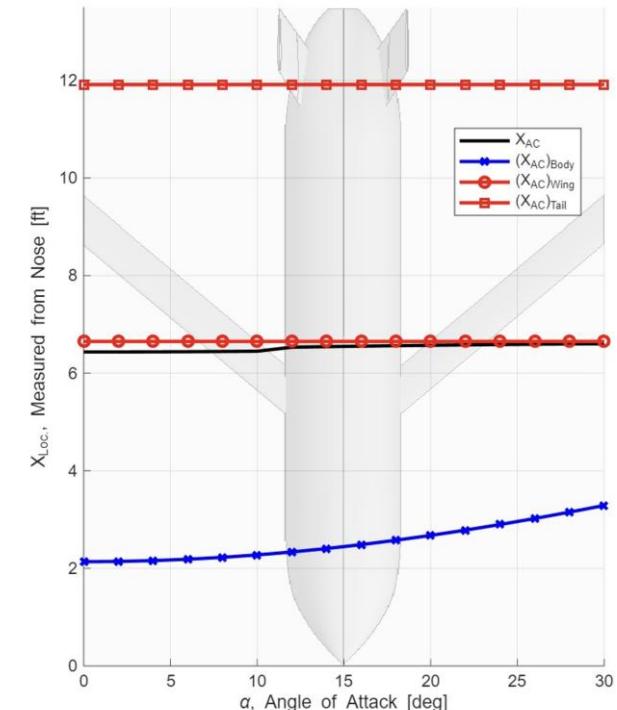
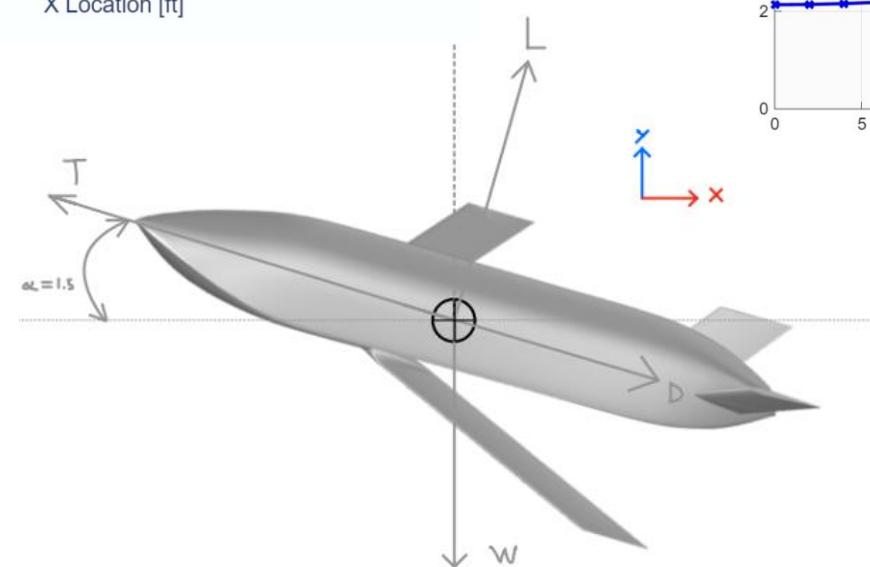
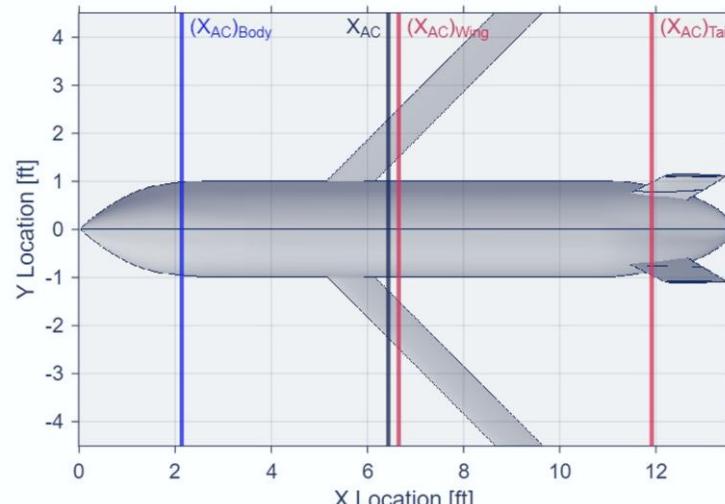
Lift to Drag Performance

Mach Number	Values
0.1	3.29
0.5	3.65
0.7	3.73
0.9	3.78



Cruise

Parameter	Values
Altitude	2,000 ft
Mach number	0.71
Weight (W)	1,975 lbf
Tail area	3.36 ft^2
Wing area	9 ft^2
Cruise satisfied at α	1.5 °



Tail sizing

- Old Tail :

- Span: $b_{T,old} = 2.40 \text{ ft}$

- Root chord: $c_{r,T} = 1.50 \text{ ft}$

- Tip chord: $c_{t,T} = 1.30 \text{ ft}$

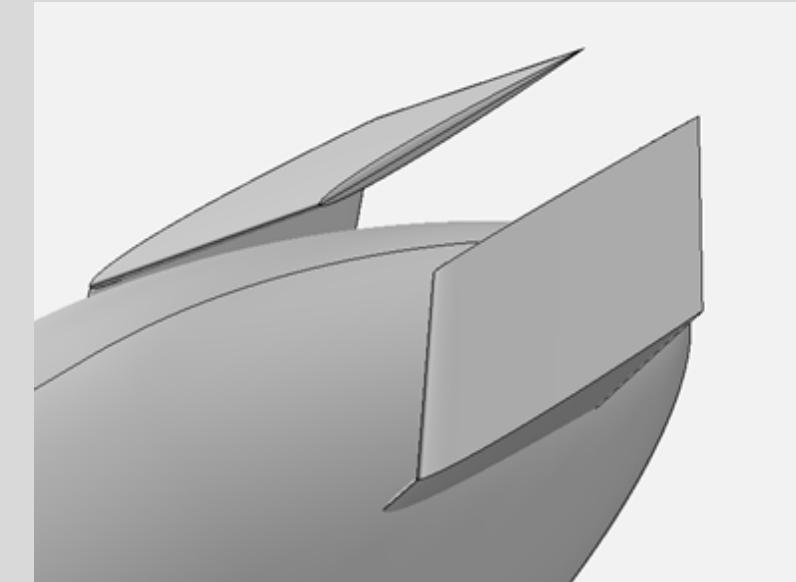
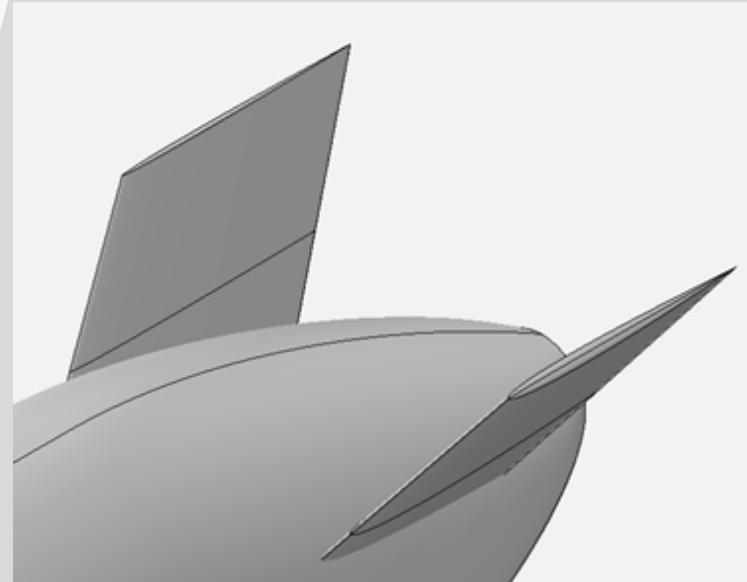
- New CG at 77.21 in

- New Tail :

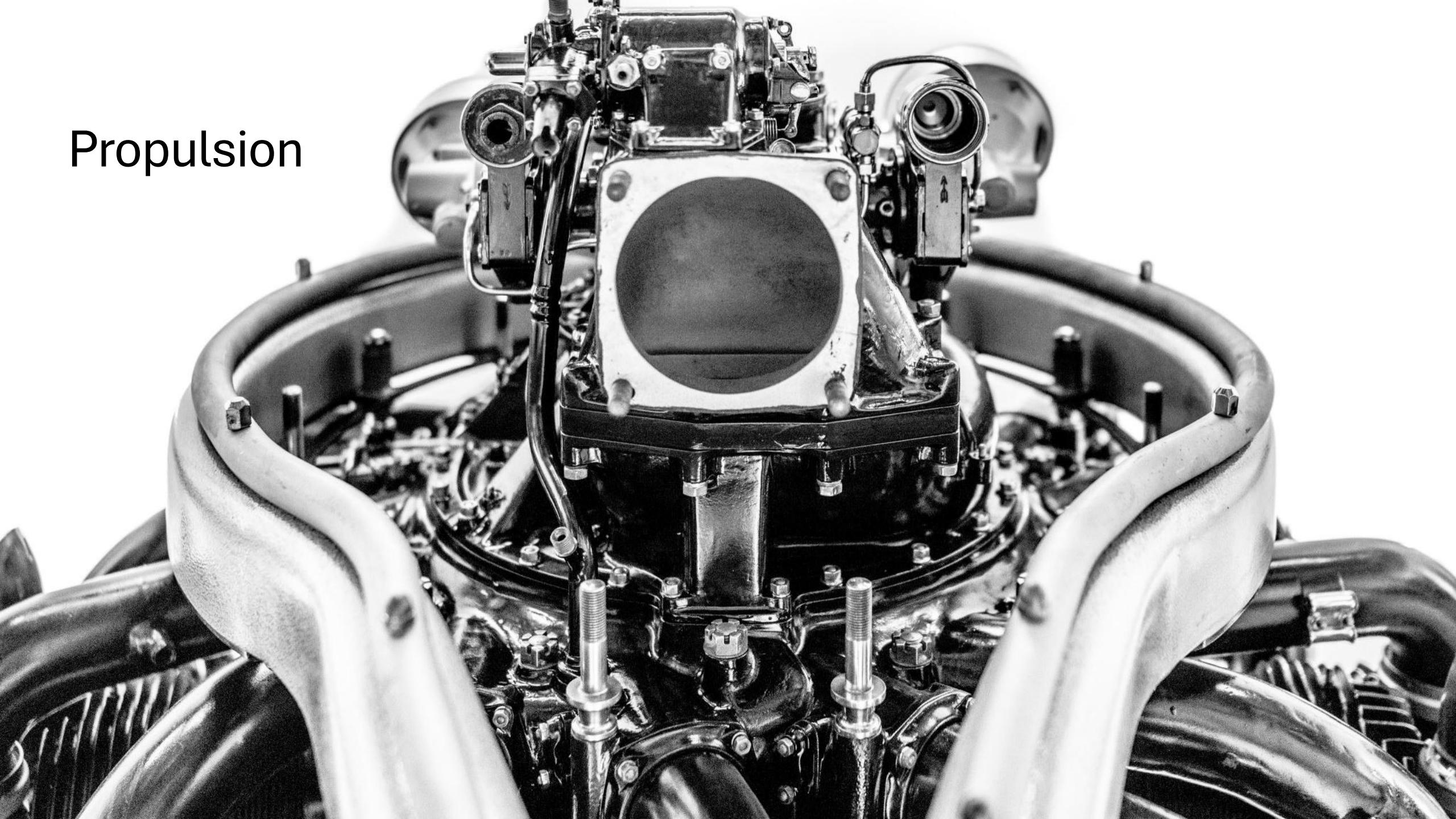
- Span: $b_{T,old} = 2.31 \text{ ft}$

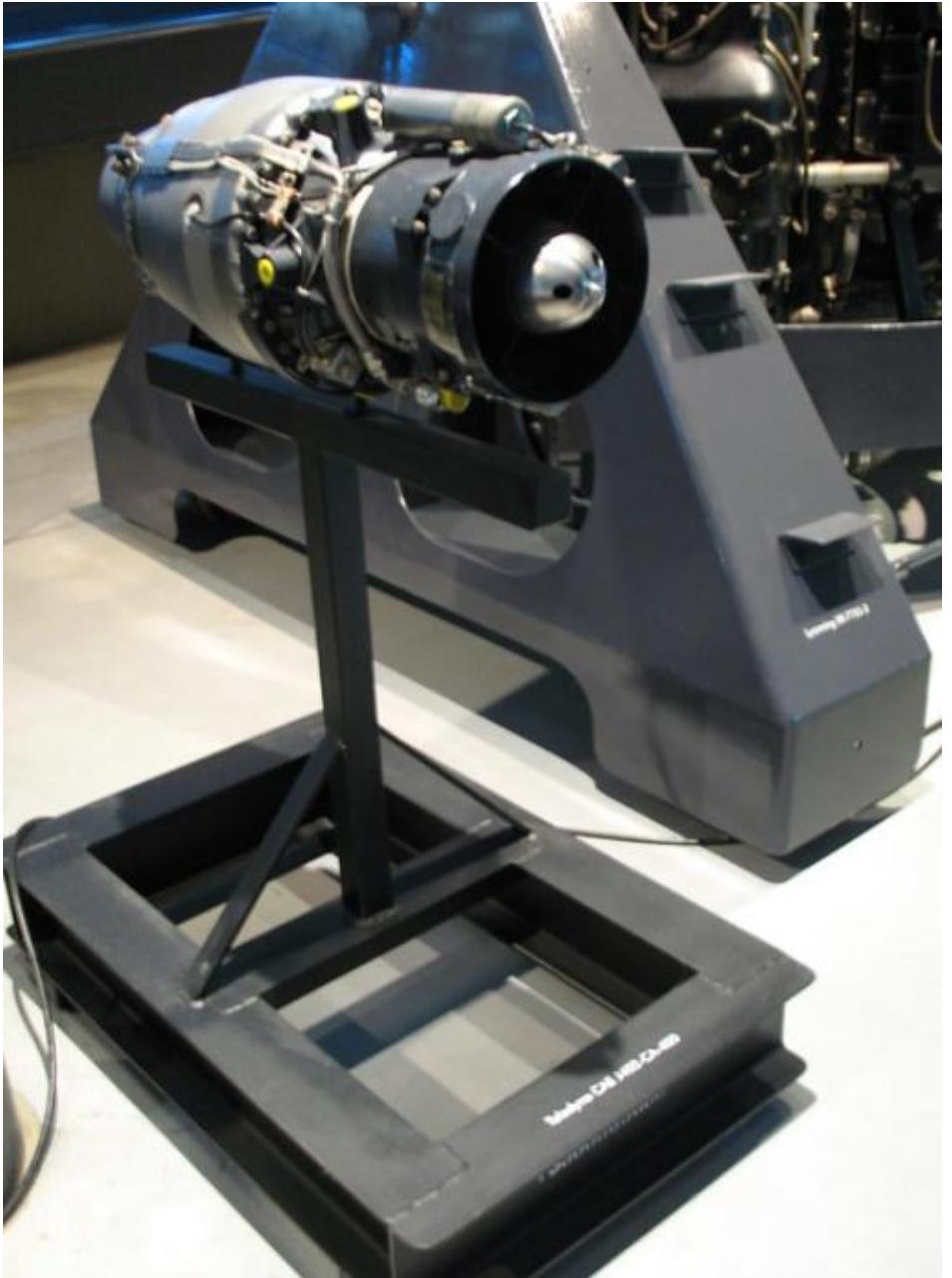
- Root chord: $c_{r,T} = 1.50 \text{ ft}$

- Tip chord: $c_{t,T} = 1.30 \text{ ft}$

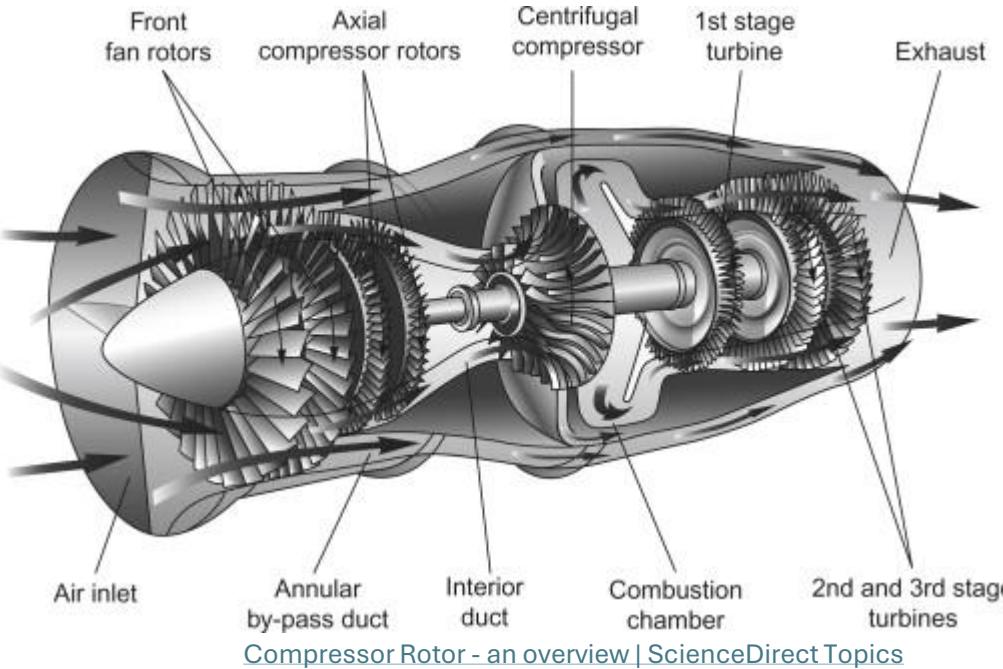


Propulsion

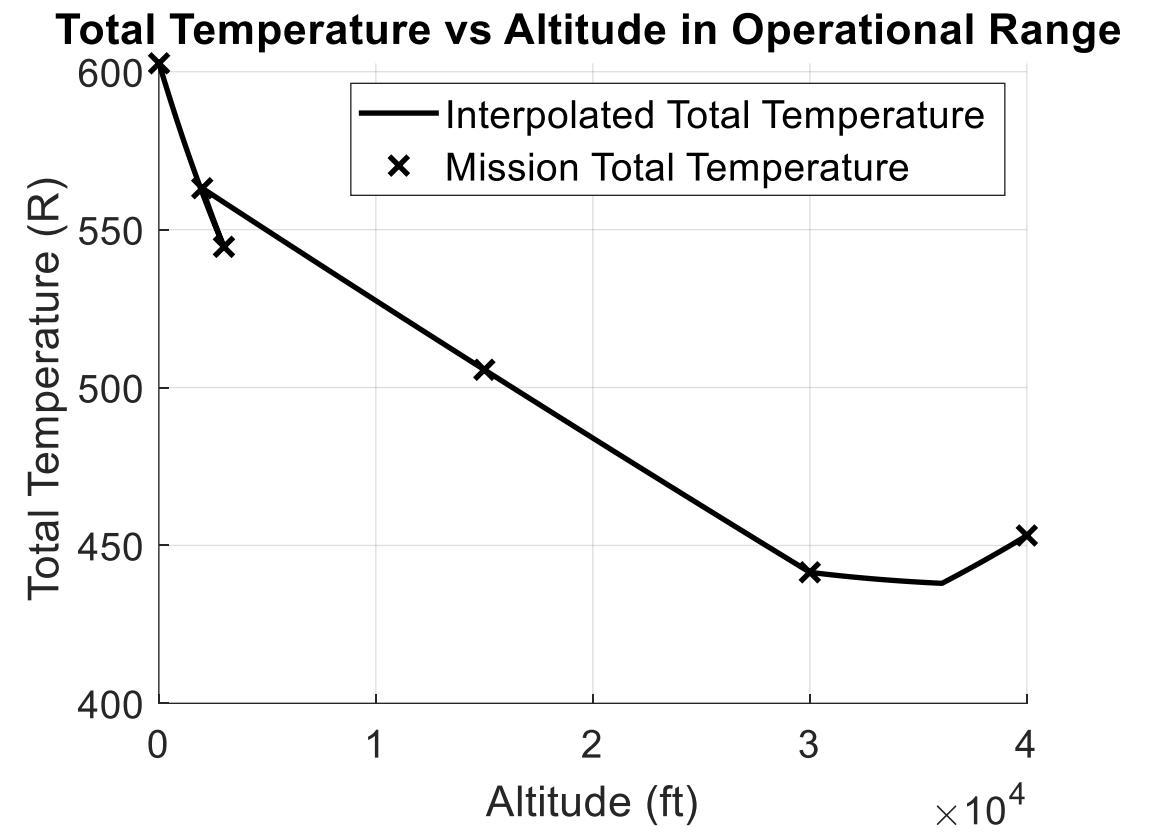
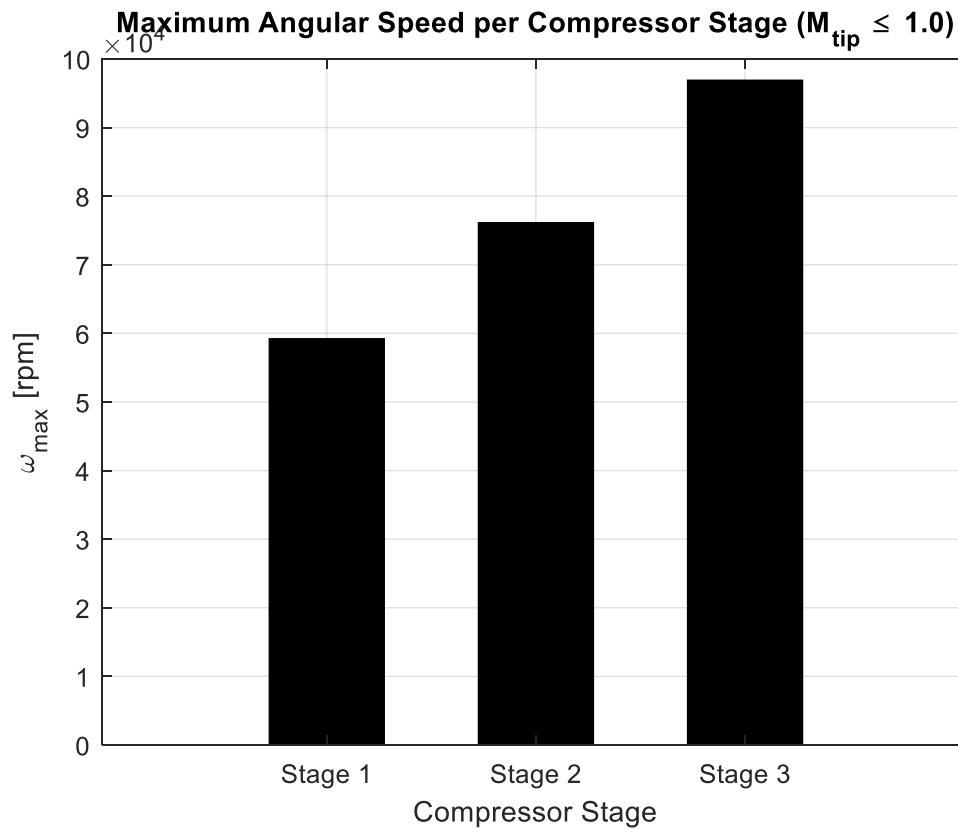




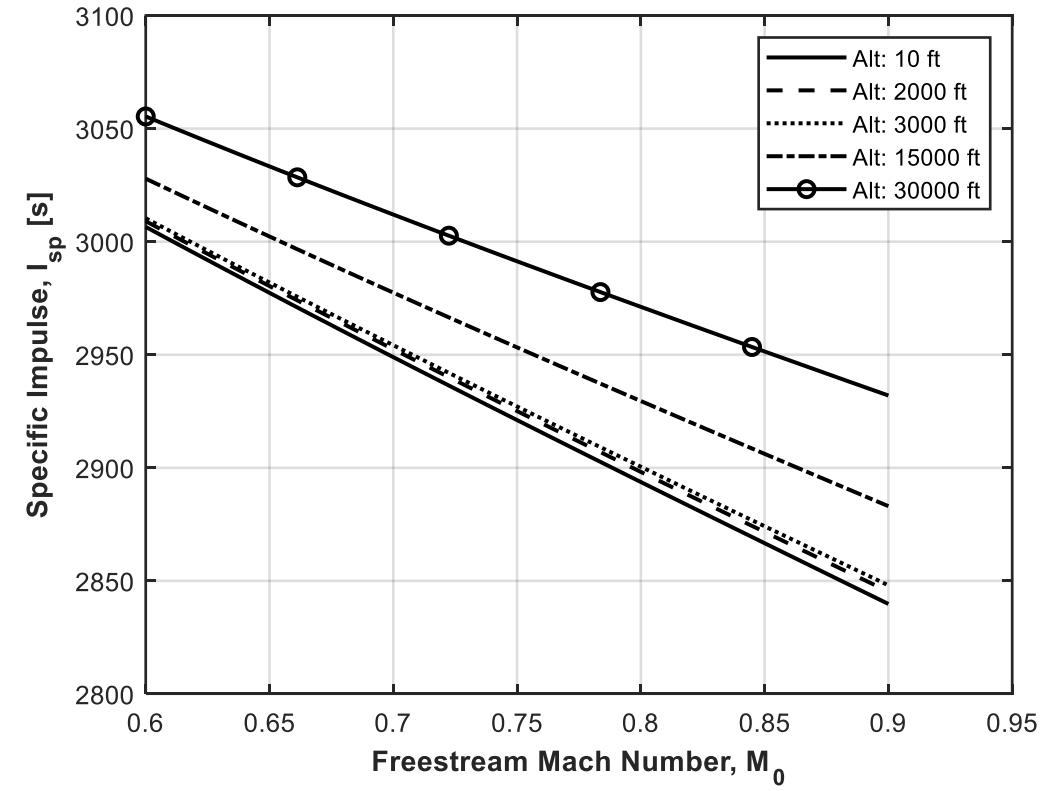
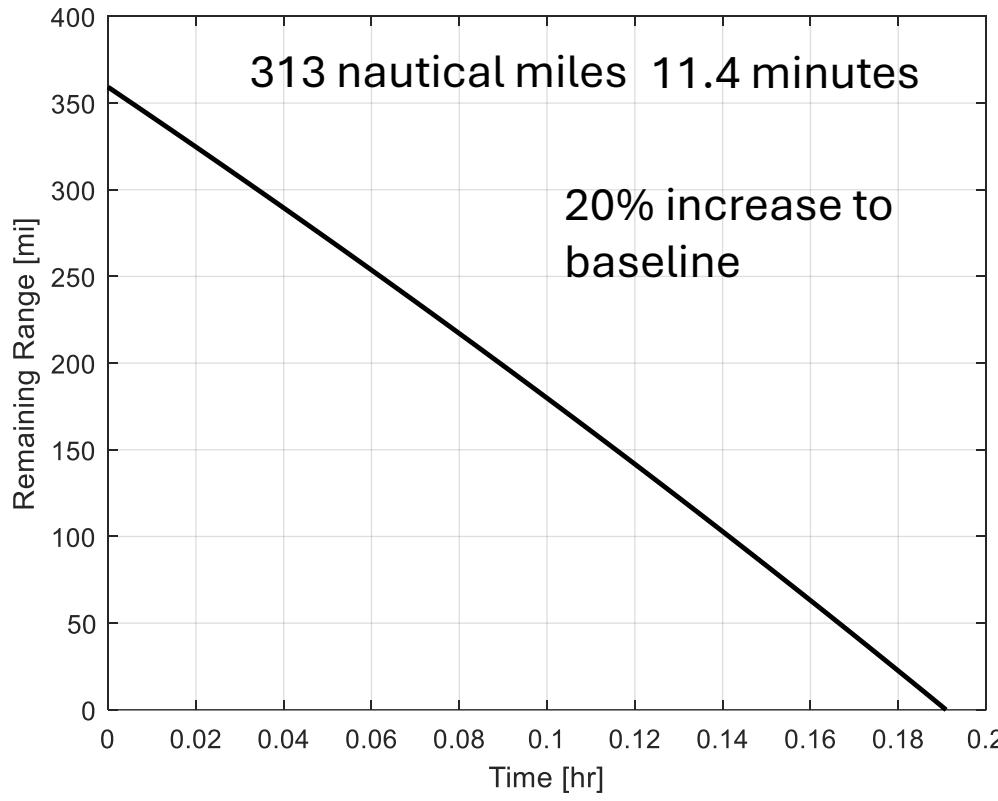
Teledyne J402



Axial Compressor 1 (C1) Diameter (ft)		1.0118			
Axial Compressor 2 (C2) Diameter (ft)		1.1187			
Centrifugal Compressor (C3) Diameter		1.3300			
T ₂ (°R)	N (rpm)	PR _{C1} (~)	PR _{C2} (-)	PR _{C3} (-)	PR _{Tot} (-)
441.49	18667	1.8522	1.8853	2.8619	9.9934
505.62	19886	1.8424	1.8795	2.8863	9.995
563.11	20905	1.8342	1.8746	2.9068	9.9946
544.55	20583	1.8369	1.8761	2.9004	9.9952
602.65	21574	1.8291	1.8715	2.9213	9.9997
T ₂ (°R)	T _{2.3} (°R)	T _{2.6} (°R)	T ₃ (°R)		
441.49	526.62	629.76		847.23	
505.62	601.14	716.84		963.46	
563.11	667.65	794.23		1066.5	
544.55	646.2	769.3		1033.4	
602.65	713.26	847.18		1137.1	

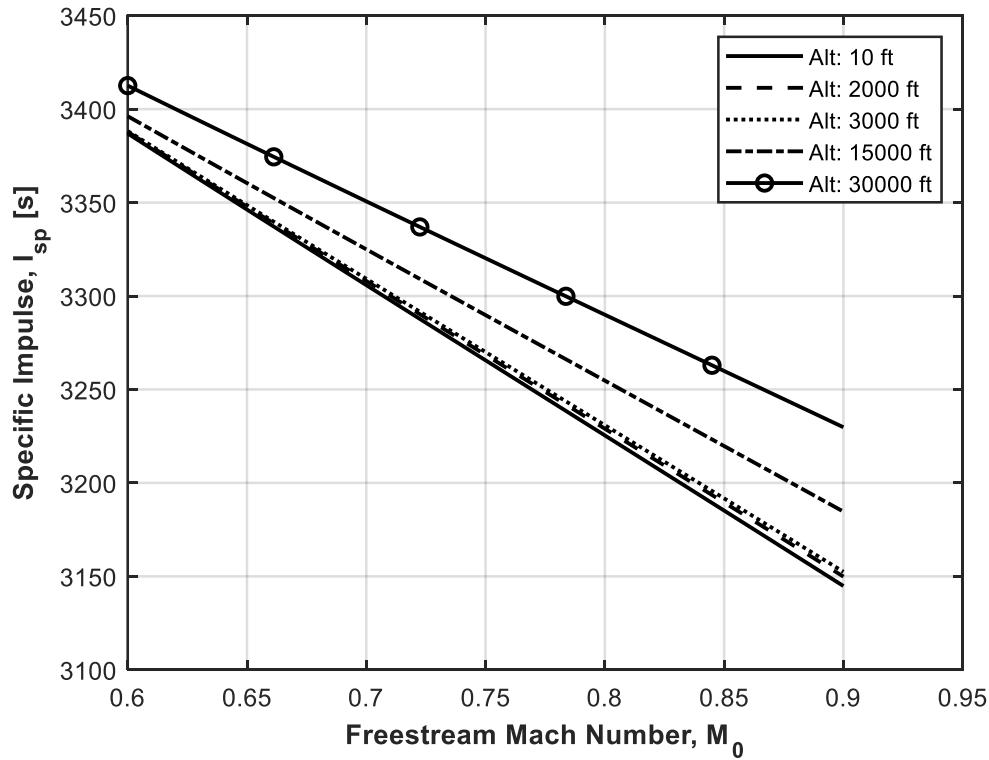


Propulsion

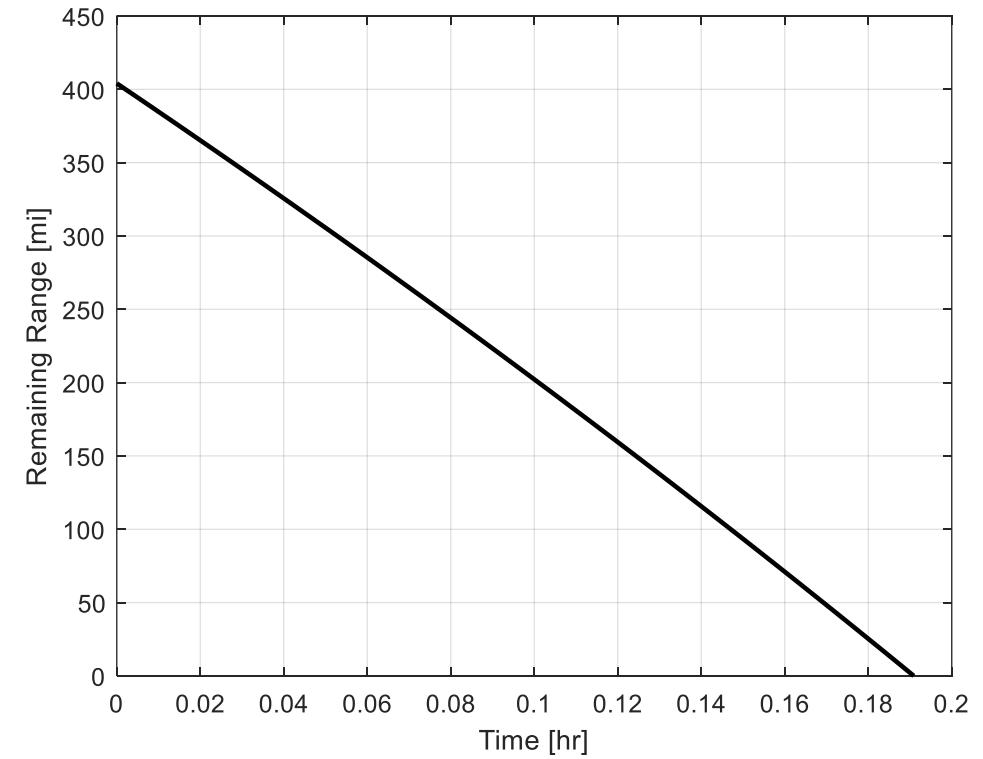


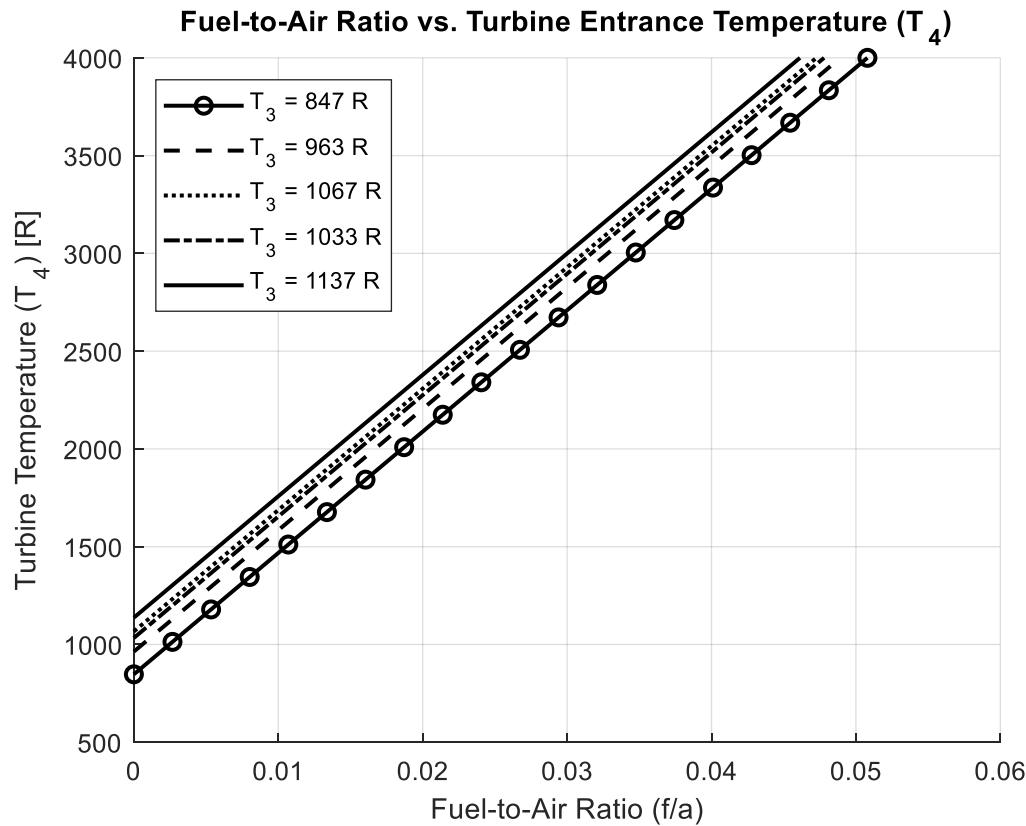
PR of 20

362 nautical miles



35% increase to
baseline





Altitude (ft)	T_{t2} (R)	Compressor Outlet Temperature (T_{t3}) in R
10	602.7	1,137
2,000	544.6	1,033
3,000	563.1	1,067
15,000	501.27	963
30,000	441.49	847

Trajectory and Simulation

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2D Trajectory

Trajectory Phases

- Launch/Dive
 - Rapidly decrease altitude
 - High-angle dive (> 30 deg)
 - Cruise
 - Maneuver to target area
 - Termination
 - Low-angle dive (< 30 deg) to target
 - Trajectory maximizes the survivability of the missile
 - n-limit set 5 g's
- (Range intentionally shortened for illustration)

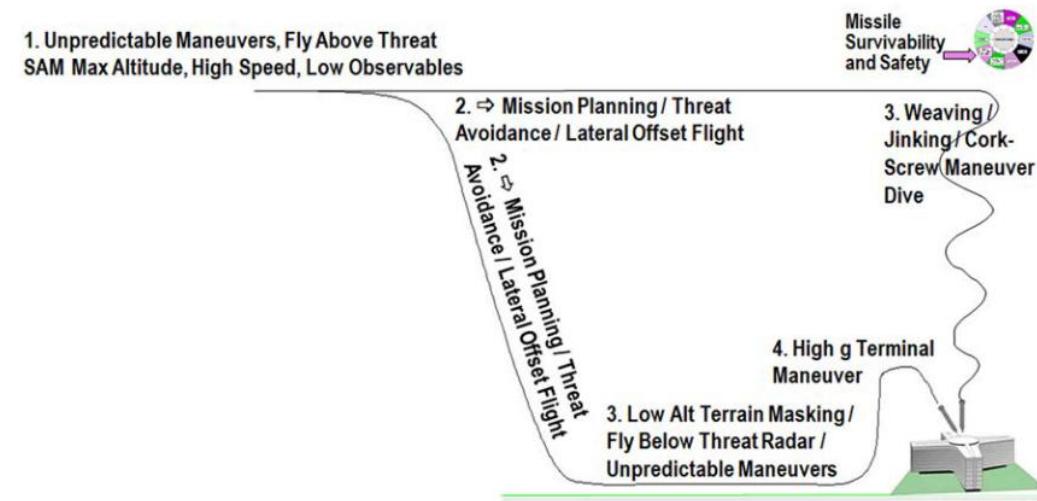
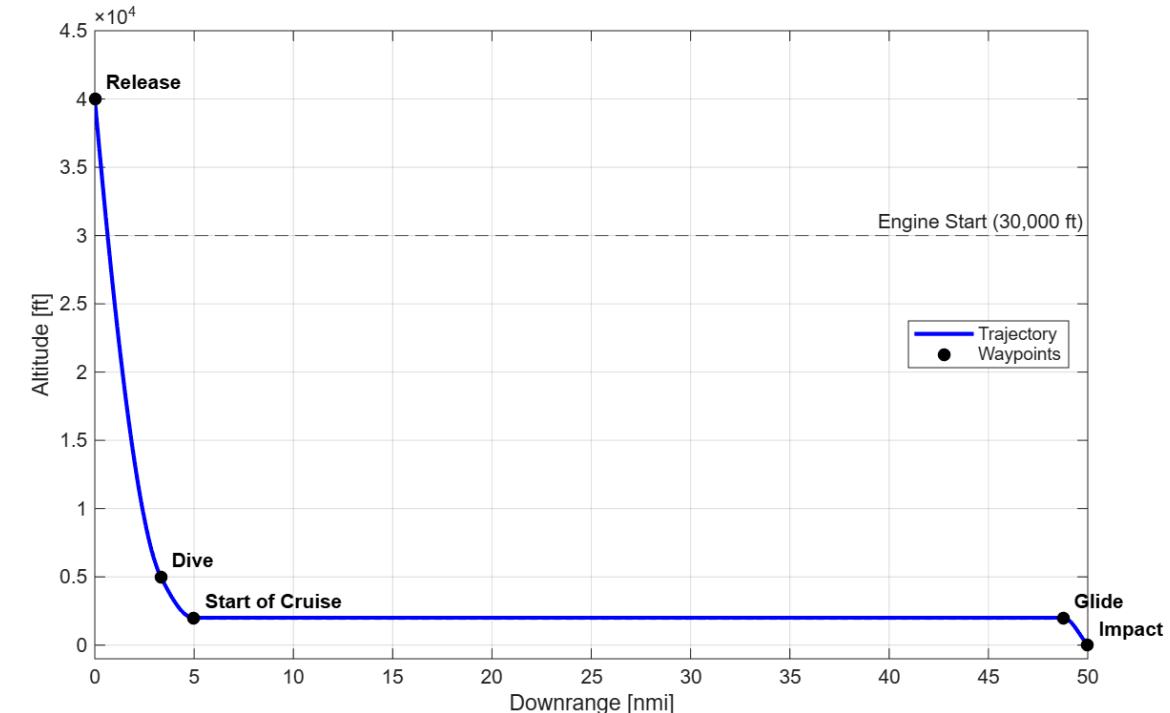
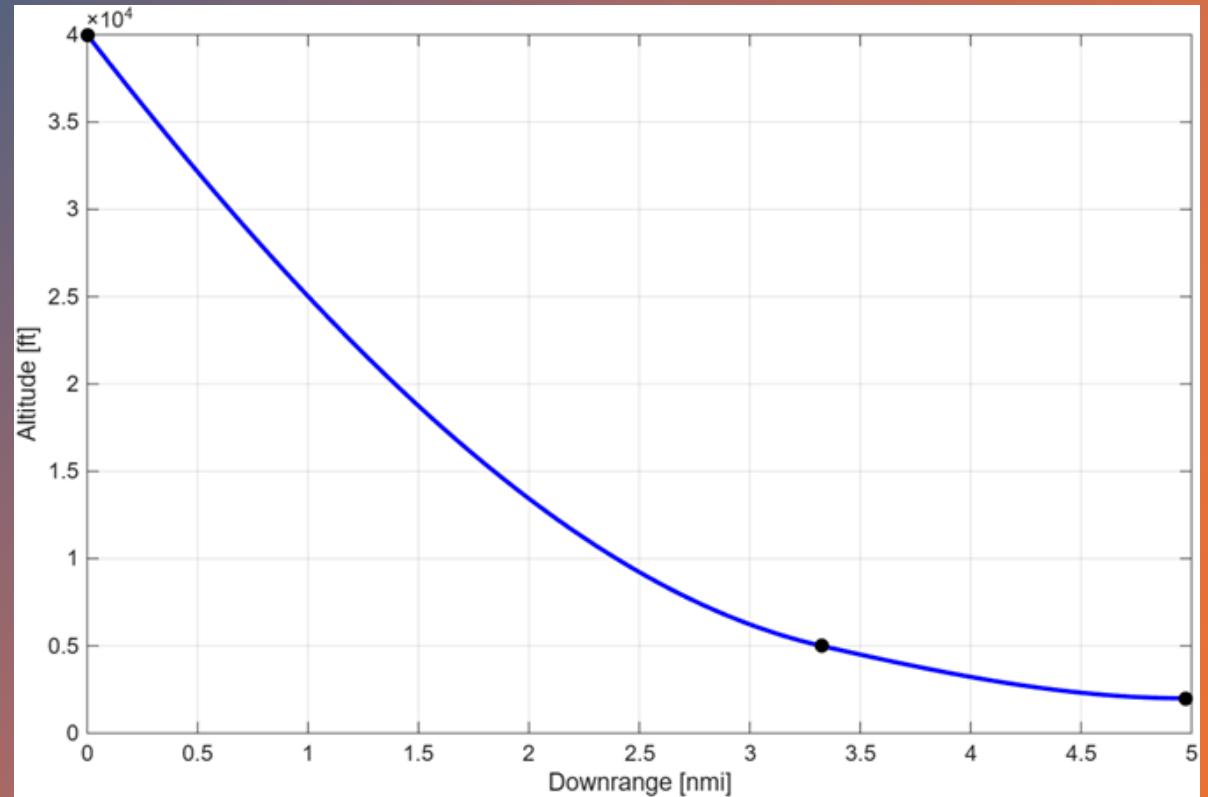


Fig. 6.123 Options for Survivability Include Stealth, Altitude, Speed, Threat Avoidance, Terrain Masking, and Maneuverability.
Note: See video supplement, Tomahawk Using Terrain Following and Jinking.



Launch/Dive Phase

- After release
 - Wings and tail deploy
 - Missile enters a controlled 60-degree dive
- During dive
 - Engine starts at 30,000 ft
 - Missile maintains dive angle
- Approaching cruise
 - Missile initiates a flare maneuver
 - Pulls up to level flight



Cruise Terrain Contour Matching and Radar Avoidance

- Missile maintains low-altitude above ground altitude
 - Using pre-collected terrain data to maintain the correct altitude
 - Terrain Contour Matching (TERCOM) strategy
- Guidance towards stationary target
 - Lateral maneuvers to avoid radar
 - Terrain masking

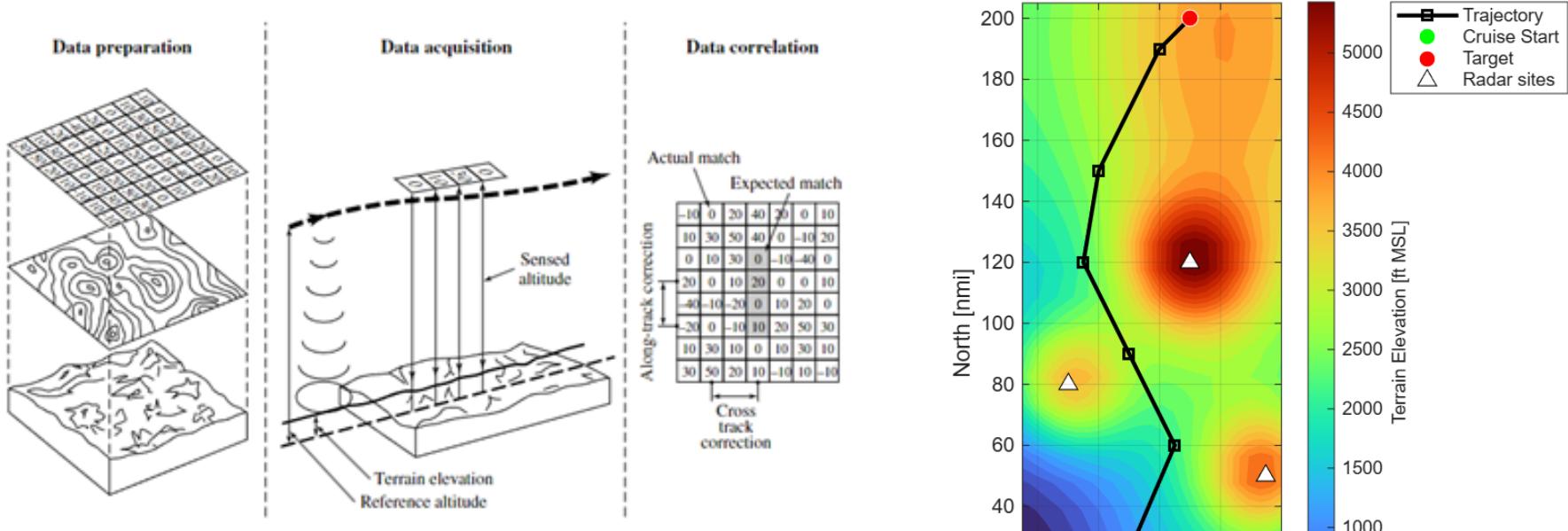
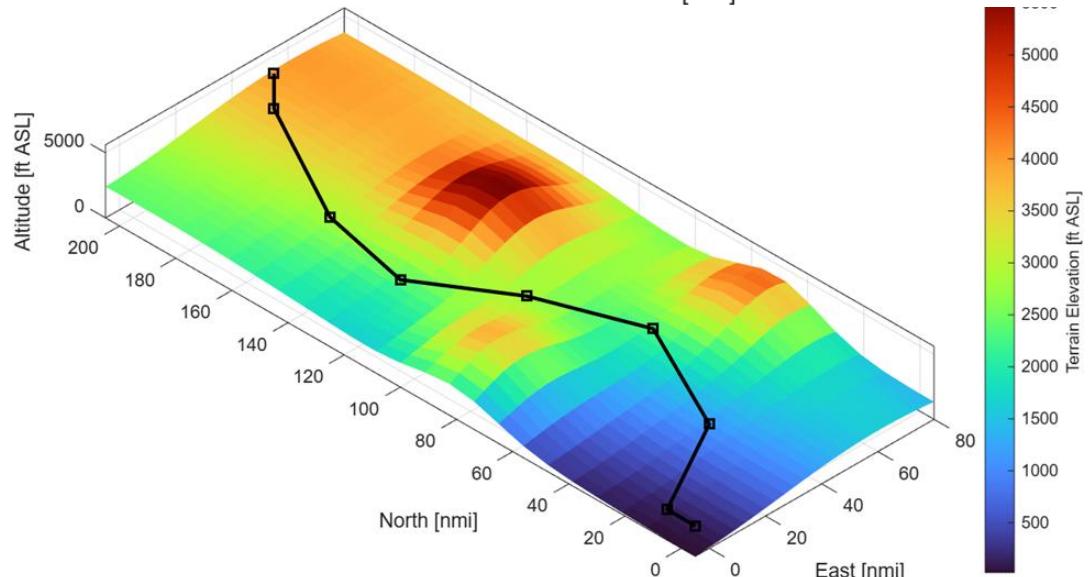
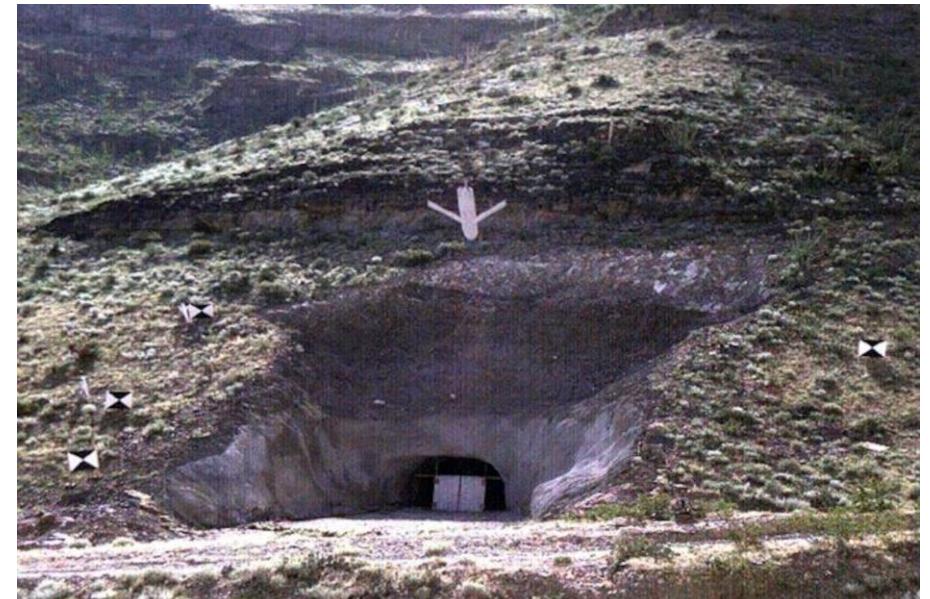
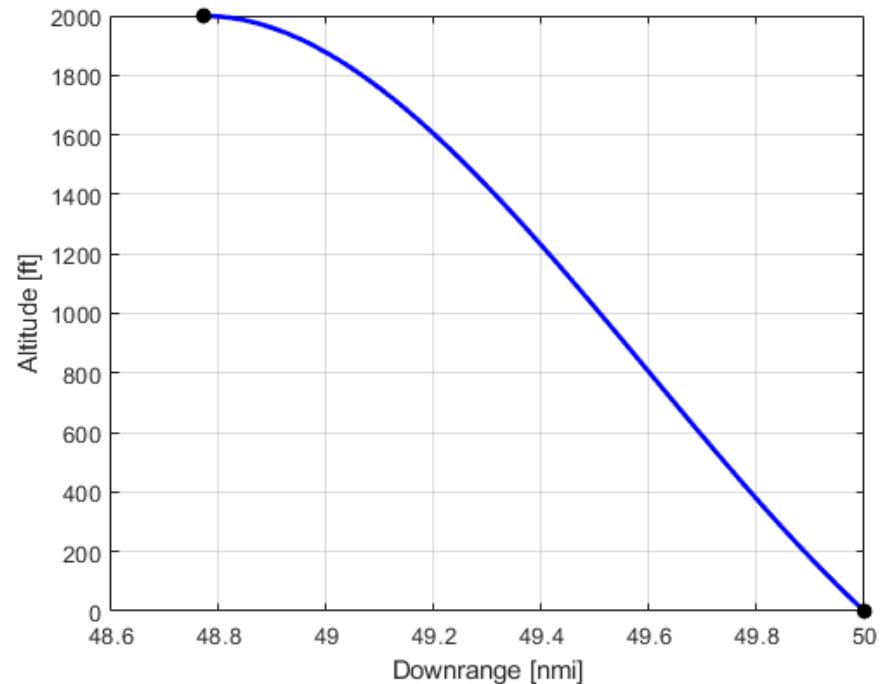


Fig. 7.11. TERCOM concept.



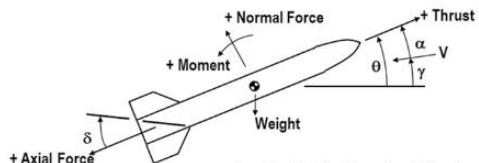
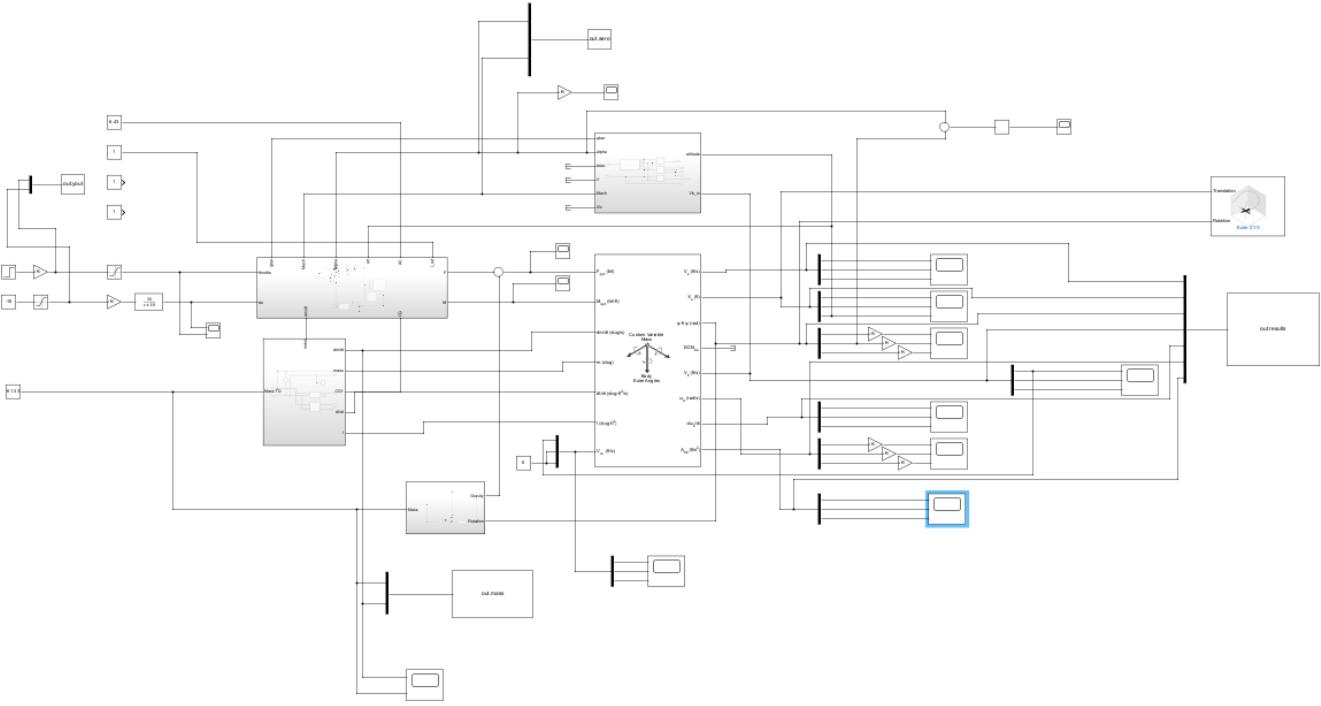
Termination

- Missile enters a low-angle dive from level cruise at 0 ft AGL
- Small maneuvering towards ground target
- Trajectory is designed to ensure high precision



2D 3 DOF Simulation

- Translation: X, Z
- Rotation: θ
- Simulator created using MATLAB/Simulink
- Aerodynamic forces (N, A) modeled in body coordinates
- Engine modeled with fuel consumption lowering overall weight
- Atmosphere model decreases air density and temperature with altitude
- Controls
 - Thrust input
 - Ruddervator deflection



$$I_y \ddot{\theta} \approx I_y \dot{\alpha} \approx q S_{Ref} d C_{m_\alpha} \alpha + q S_{Ref} d C_{m_\delta} \delta$$

$$(W/g_e) \dot{\gamma} \approx S_{Ref} \rho V C_{N_\alpha} \alpha / 2 + S_{Ref} \rho V C_{N_\delta} \delta / 2 + (T \sin \alpha) / V - (W/V) \cos \gamma$$

$$(W/g_e) V \approx T - C_A S_{Ref} q - C_N S_{Ref} q \sin \alpha - W \sin \gamma$$

Aero Control Configuration Sizing Implication*
High Agility / Fast Rotation $\Rightarrow C_{m_\delta} > C_{m_\alpha}$, I_y small (W small), V large

Large / Fast Heading Change $\Rightarrow C_N$ large (C_{N_α} or C_{N_δ})
large, W small, ρ large (low alt), V large, T/V large

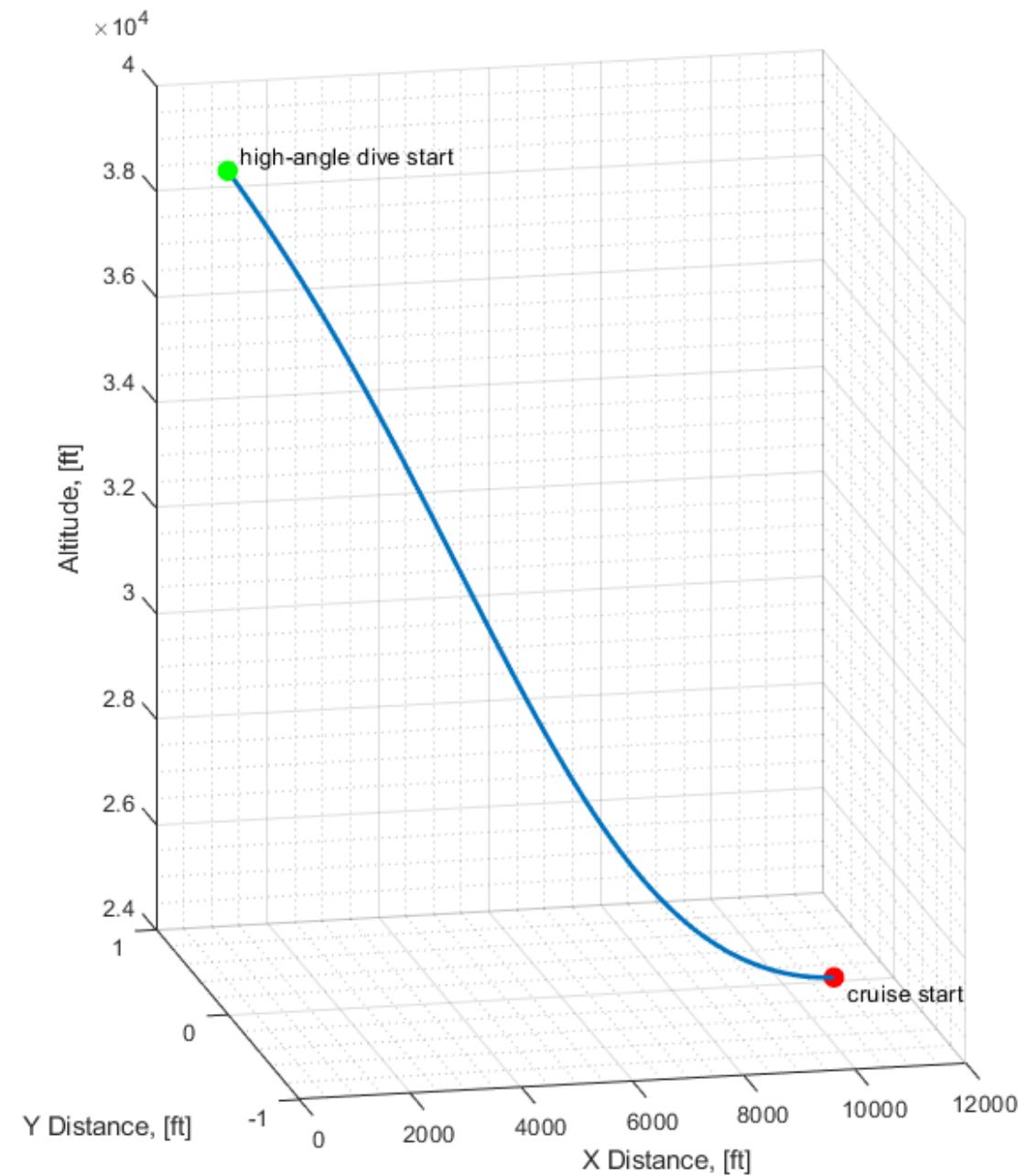
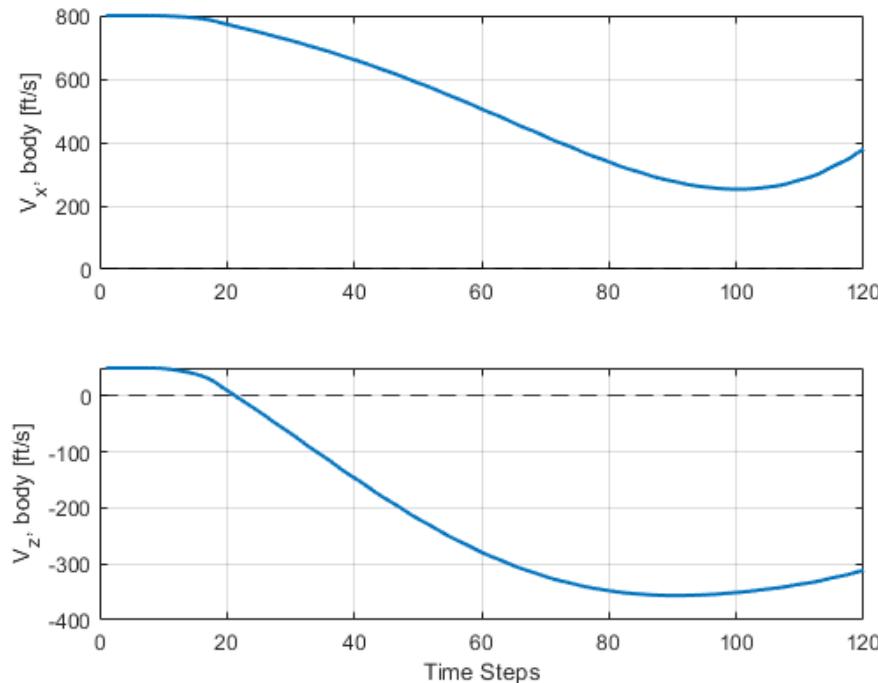
High Speed / Long Range \Rightarrow Total impulse ($\int T dt$) large,
 C_A small, q small

*Assumption: Angle of Attack, α small $\Rightarrow C_m = C_{m_\alpha} \alpha + C_{m_\delta} \delta$ and $C_N \approx C_{N_\alpha} \alpha + C_{N_\delta} \delta$
Nomenclature: I_y = pitch moment of inertia, θ = pitch attitude, q = dynamic pressure, S_{Ref} = reference area, C_N = normal force coefficient, C_{N_α} = normal force coefficient derivative with angle of attack, C_{N_δ} = normal force coefficient derivative with ruddervator deflection, C_m = pitch moment coefficient, C_{m_α} = pitch moment coefficient derivative with angle of attack, C_{m_δ} = pitch moment coefficient derivative with ruddervator deflection, ρ = atmospheric density, T = thrust, C_A = axial force coefficient, V = velocity, W = weight, t = time, α = angle of attack, δ = ruddervator deflection, g_e = gravitational constant, γ = flight path angle

Fig. 5.11a 3 Degrees of Freedom (3-DOF) Equations of Motion Show Drivers for Missile Configuration Sizing.

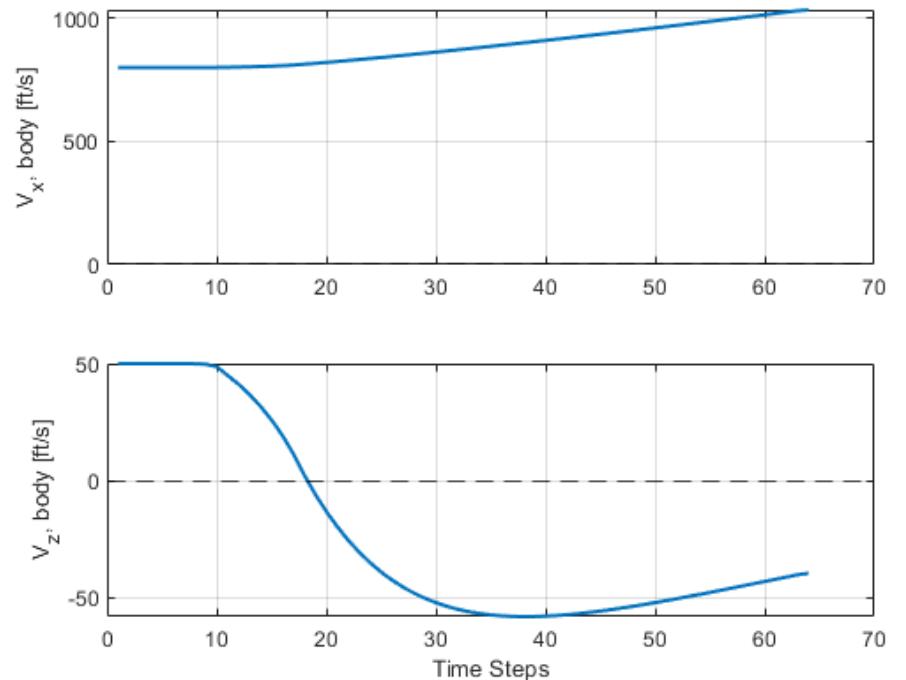
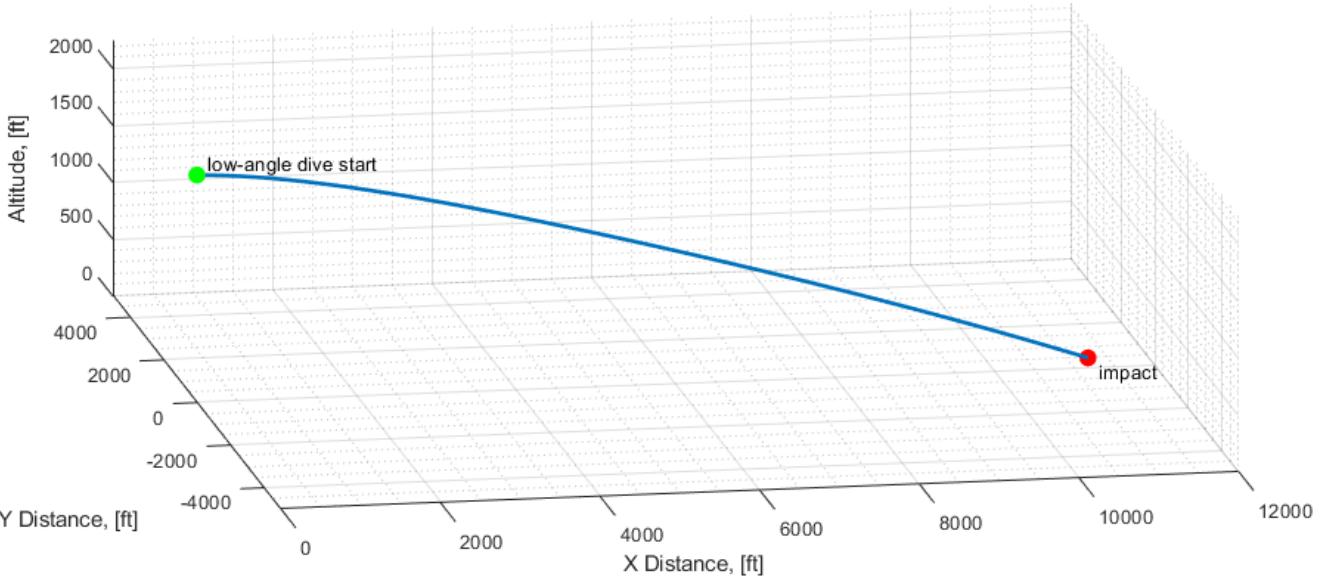
High-Angle Dive Simulation Results

- Simulation starting states
 - 40,000 ft altitude
 - $V = 800$ ft/s
 - 60-degree dive
 - Simulation shows a controlled high-angle dive from cruise altitude to the target



Low-Angle Dive Simulation Results

- Simulation starting states
 - 2,000 ft altitude
 - $V = 800$ ft/s
 - 5-degree dive
- Simulation shows a controlled low-angle dive from cruise altitude to the target
- Missile impact target at an altitude of 0 ft AGL

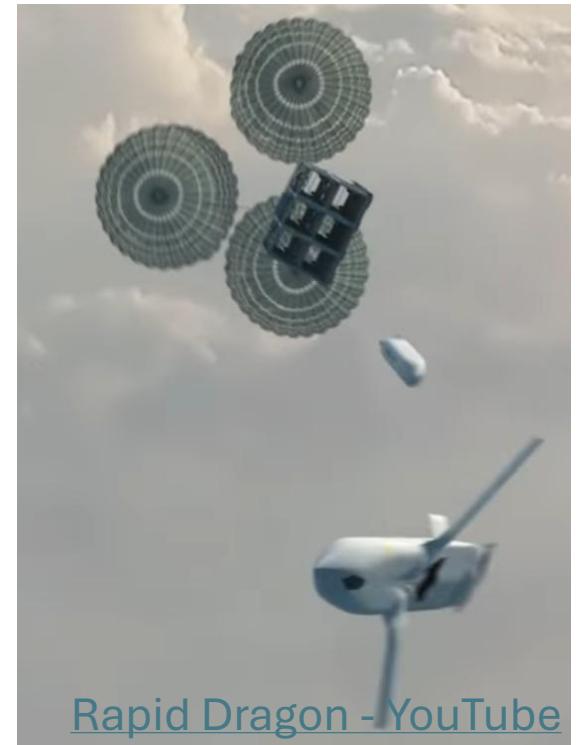




6-PACK FOR JASSM-ER DEPLOYMENT ON A C-130



ROLL-ON, ROLL-OFF CAPABILITY

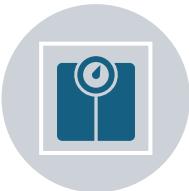


[Rapid Dragon - YouTube](#)

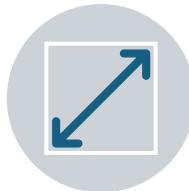
Conclusions



Range increased by 40%



Weight found to be 1975
lbs



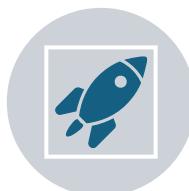
Higher Lift to drag due to
new wing



2 axial and 1 centrifugal
compressor used to
increase engine efficiency



Trajectory follows CONOP
and uses terrain masking to
avoid radar



Simulation shows missile
was able to follow
trajectory



Q/A