

1. [d]

$$D_{(1)} = \{(-2, -1), (0, 1), (2, -1)\}$$

$$\phi(x) = [1, x, x^2]^T$$

$$D_{(2)} = \{(1, -2, 4, -1), (1, 0, 0, 1), (1, 2, 4, -1)\}$$

$$Z = \begin{bmatrix} 1 & -2 & 4 \\ 1 & 0 & 0 \\ 1 & 2 & 4 \end{bmatrix} \quad y = \begin{bmatrix} -1 \\ 1 \\ -1 \end{bmatrix}$$

$$\because y_n(\omega^T x_n + b) \geq 1$$

$$-(b - 2\omega_1 + 4\omega_2) \geq 1 \quad -b + 2\omega_1 - 4\omega_2 \geq 1$$

$$b \geq 1$$

$$b \geq 1$$

$$-(b + 2\omega_1 + 4\omega_2) \geq 1 \quad -b - 2\omega_1 - 4\omega_2 \geq 1$$

$$2\omega_1 + 4\omega_2 \geq 2$$

$$-2\omega_1 - 4\omega_2 \geq 2$$

$$\omega_1 + 2\omega_2 \geq 1$$

$$-\omega_1 - 2\omega_2 \geq 1$$

$$2\omega_1 \geq 2, \omega_1 \geq 0, \times$$

$$\omega_1 = 0, \omega_2 = \frac{-1}{2}, b = 1$$

$$-4\omega_2 \geq 2 \quad \omega_2 \leq \frac{-1}{2}$$

2. [b]

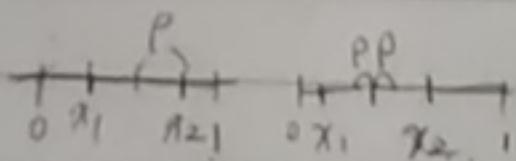
$$\max \text{ margin} = \frac{1}{\|\omega\|} = \frac{1}{\sqrt{\omega^T \omega}} = \frac{1}{\sqrt{\frac{1}{4}}} = 2$$

3. [e]

$$\begin{array}{cccc|cccccc} -1 & -1 & \dots & -1 & +1 & +1 & \dots & +1 \\ \hline x_1 & x_2 & \dots & x_m & x_{m+1} & x_{m+2} & \dots & x_N \end{array}$$

$$d = \frac{1}{2}(x_{m+1} - x_m)$$

4.



$$\rho \in [0, 0.5]$$

$$\rho \in [0, \frac{x_2 - x_1}{2}]$$

5. [c]

$$\mathcal{L} = \frac{1}{2} w^T w + \sum_{n=1}^N \alpha_n \left[[\![y_n = 1]\!] \cdot (\rho^+ - y_n (w^T x_n + b)) + [\![y_n = -1]\!] \cdot (\rho^- - y_n (w^T x_n + b)) \right]$$

$$\mathcal{L} = \frac{1}{2} w^T w + \alpha_n \sum_{n=1}^N \left[[\![y_n = 1]\!] \cdot \rho^+ + [\![y_n = -1]\!] \cdot \rho^- - y_n (w^T x_n + b) \right]$$

$$\textcircled{1} \frac{\partial \mathcal{L}(b, w, \alpha)}{\partial b} = 0 = - \sum_{n=1}^N \alpha_n y_n \Rightarrow \sum_{n=1}^N \alpha_n y_n = 0$$

$$\textcircled{2} \frac{\partial \mathcal{L}(b, w, \alpha)}{\partial w} = 0, = w_i - \sum_{n=1}^N \alpha_n y_n x_{ni} \Rightarrow w = \sum_{n=1}^N \alpha_n y_n x_n$$

$$\text{SVM} = \max \left(-\frac{1}{2} w^T w + \sum_{n=1}^N \alpha_n \left[[\![y_n = 1]\!] \cdot \rho^+ + [\![y_n = -1]\!] \cdot \rho^- \right] \right)$$

$$\text{SVM} = \min \left(\frac{1}{2} w^T w - \sum_{n=1}^N \alpha_n \left[[\![y_n = 1]\!] \cdot \rho^+ + [\![y_n = -1]\!] \cdot \rho^- \right] \right)$$

$$= \min \left(\frac{1}{2} w^T w - \sum_{n=1}^N \alpha_n [\![y_n = 1]\!] \cdot \rho^+ - \sum_{n=1}^N \alpha_n [\![y_n = -1]\!] \cdot \rho^- \right)$$

6. [a]

different value of ρ doesn't change the SV
in other words, the slope of hyperplane doesn't change.

$w^* = \sum_{n=1}^N \alpha_n^* y_n x_n \Rightarrow$ the w doesn't change
 \Rightarrow the α_n doesn't change.

7.

$$k_2(x, x') = \phi_2(x)^T \phi_2(x') = 1 + x^T x' + (x^T x')(x^T x')$$

$$k_2(x, x') = (y_2 + \gamma x^T x')^2 = y^2 + 2y\gamma x^T x' + \gamma^2 x^T x'$$

$$(a) 2k(x, x') = 2y^2 + 2y\gamma x^T x' + 2\gamma^2 x^T x'$$

$$(d) \log_2 k(x, x') = \log_2 (y + \gamma x^T x') + \log_2 (y_2 + \gamma x^T x')$$

8. [c]

$$k_0(x, x') = \phi(x)^T \phi(x') = \exp(-\gamma \|x - x'\|^2)$$

the distance in Z-space:

$$\begin{aligned} \|\phi(x) - \phi(x')\|^2 &= \phi(x)^T \phi(x) - 2 \phi(x)^T \phi(x') + \phi(x')^T \phi(x') \\ &= k(x, x) + k(x', x') - 2 \exp(-\gamma \|x - x'\|^2) \end{aligned}$$

$$\|\phi(x) - \phi(x')\|^2 = 1 + 1 - 0^2$$

$$= 2$$

89. [d]

$$h_{\alpha, b}(x) = \text{sign} \left(\sum_{m=1}^N y_m \alpha_m K(x_m, x) + b \right)$$

$$h_{1, \alpha}(x) = \text{sign} \left(\sum_{n=1}^N y_n K(x_n, x) \right)$$

$$h_{1, \alpha}(x) = \text{sign} \left(\sum_{n=1}^N y_n e^{-\gamma \|x_n - x\|^2} \right),$$

assume $(y_1, y_2, \dots, y_n) \in \mathbb{R}^n$, $n \in [0, 1, \dots, N]$

$$h_{1, \alpha}(x) = \text{sign} \left(y_1 e^{-\gamma \|x_1 - x\|^2} + y_2 e^{-\gamma \|x_2 - x\|^2} + \dots + y_N e^{-\gamma \|x_N - x\|^2} \right)$$

when $n=1$, $E_m = 0$, $y_1 \in \{-1, 1\}$

$$h_{1, \alpha}(x_1) = \text{sign} (y_1 + y_2 e^{-\gamma \|x_2 - x_1\|^2} + \dots + y_N e^{-\gamma \|x_N - x_1\|^2})$$

$$\text{if } |y_1| \geq |y_2 e^{-\gamma \|x_2 - x_1\|^2} + \dots + y_N e^{-\gamma \|x_N - x_1\|^2}| = \left| \sum_{n=2}^N y_n e^{-\gamma \|x_n - x_1\|^2} \right|$$

assume that $h_{1, \alpha}(x_1) = y_1$

$$\text{if } \|x_n - x_1\|^2 \geq \varepsilon^2$$

$$|y_1| \geq \left| \sum_{n=2}^N y_n e^{-\gamma \varepsilon^2} \right| \geq \left| \sum_{n=2}^N y_n e^{-\gamma \|x_n - x_1\|^2} \right|$$

worst case y_n , $n \in [2, 3, \dots, N]$ is all positive/negative
and y_1 is negative/positive.

$$1 \geq (N-1) \cdot 1 e^{-\gamma \varepsilon^2}$$

$$\frac{1}{N-1} \geq e^{-\gamma \varepsilon^2}$$

$$\ln \frac{1}{N-1} \geq -\gamma \varepsilon^2$$

$$-\ln(N-1) \geq -\gamma \varepsilon^2$$

$$\gamma > \frac{\ln(N-1)}{\varepsilon^2}$$

10. [C]

$$w_{t+1} \leftarrow w_t + y_n(\tau) \phi(x_n(\tau))$$

$$w_t = \sum_{n=1}^N \alpha_{t,n} \cdot \phi(x_n) \quad \text{at } t+1 = \alpha_{t,1} \cdot \phi(x_1) + \alpha_{t,2} \cdot \phi(x_2) + \dots + \alpha_{t,N} \cdot \phi(x_N)$$

when current w_t makes a mistake

$$y_n(\tau) w_t \phi(x_n(\tau)) < 0 \Rightarrow y_n w_{t+1} \phi(x_n) > 0.$$

$$y_n(\tau) \sum_{h=1}^N \alpha_{t,h} \cdot \phi(x_h) < 0 \Rightarrow y_n \sum_{h=1}^N -\alpha_{t,h} \cdot \phi(x_h) > 0.$$

$$\sum_{n=1}^N \alpha_{t+1,n} \phi(x_n) = \sum_{n=1}^N \alpha_{t,n} \cdot \phi(x_n) + y_n \phi(x_n)$$

$$\sum_{n=1}^N \alpha_{t+1,n} \phi(x_n) = \sum_{n=1}^N \alpha_{t,n} \cdot \phi(x_n) \quad \left. \begin{array}{l} \text{if } n = \text{mistake sample.} \\ (\alpha_{t,n} + y_n(\tau)) \phi(x_n) \end{array} \right\}$$

11. [a]

$$w_t = \sum_{n=1}^N \alpha_{t,n} \cdot \phi(x_n) \quad , \quad K(x, x') = \phi(x)^T \phi(x')$$

$$w_t^T \phi(x) = \left(\sum_{n=1}^N \alpha_{t,n} \cdot \phi(x_n) \right)^T \phi(x)$$

$$= \sum_{n=1}^N \alpha_{t,n} \cdot k(x_n, x)$$

No.

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 $\alpha_n \gamma_n \in \mathbb{R}$.

12. [b]

bounded $\gamma_n \Rightarrow \alpha_n = C$.

$$b = y - y_{sv} - \omega^T \mathbf{z}$$

$$= y_{sv} - y_{sv} \gamma_{sv} - \sum_{h=1}^N \alpha_h y_h K(x_m, x_{sv})$$

$$= y_{sv} - y_{sv} \gamma_{sv} - \sum_{m=1}^N \alpha_m \gamma_m K(x_m, x_{sv})$$

$$= y_{sv} (1 - \gamma_{sv}) - \sum_{m=1}^N \alpha_m \gamma_m K(x_{sv}, x_m)$$

$$\text{if } y_{sv} = 1, b = 1 - \gamma_{sv} - \sum_{m=1}^N \alpha_m \gamma_m K(x_{sv}, x_m) \leq 1 - \sum_{m=1}^N \alpha_m \gamma_m < (y_{sv}, x_m)$$

$$\text{if } y_{sv} = -1, b = -(1 - \gamma_{sv}) - \sum_{m=1}^N \alpha_m \gamma_m K(x_{sv}, x_m) \geq -1 - \sum_{m=1}^N \alpha_m \gamma_m K(x_{sv}, x_m)$$

$$b^* \leq \min_{\gamma_1, \gamma_2, \dots, \gamma_N} \left(1 - \sum_{m=1}^N \alpha_m \gamma_m K(x_{sv}, x_m) \right)$$

13. [e]

$$\min_{w, b, \gamma} \frac{1}{2} \omega^T \omega + C \sum_{h=1}^N \gamma_h^2$$

$$\gamma_1^2 + \gamma_2^2 + \dots + \gamma_N^2$$

$$\text{subject to: } y_h (\omega^T \phi(x_h) + b) \geq 1 - \gamma_h$$

$$\geq 1 - \gamma_h$$

$$\mathcal{L}(b, \omega, \gamma, \alpha) = \frac{1}{2} \omega^T \omega + \left(\sum_{h=1}^N \gamma_h^2 + \sum_{h=1}^N \alpha_h (1 - \gamma_h - y_h (\omega^T \phi(x_h) + b)) \right) +$$

$$\max_{\alpha_h \geq 0} \left(\min_{b, \omega, \gamma} \mathcal{L}(b, \omega, \gamma, \alpha) \right)$$

$$\frac{\partial \mathcal{L}}{\partial \gamma_h} = 0 = 2 \sum_{n=1}^N \gamma_n - \alpha_n$$

$$\begin{aligned} \mathcal{L}(b, \omega, \gamma, \alpha) &= \frac{1}{2} \omega^T \omega + \sum_{h=1}^N \alpha_h (1 - \gamma_h - y_h (\omega^T \phi(x_h) + b)) - \sum_{h=1}^N \alpha_h \gamma_h + \left(\sum_{h=1}^N \gamma_h^2 \right) \\ &\Rightarrow \sum_{h=1}^N \gamma_h (\alpha_h - \gamma_h) \\ &= \sum_{h=1}^N \gamma_h (2C \gamma_h - \alpha_h) \end{aligned}$$

max.

$$\alpha_n \geq 0, 2 \leq y_n = \alpha_n \quad \left(\min_{b, w} \frac{1}{2} w^T w + \sum_{n=1}^N \alpha_n (1 - y_n (w^T \phi(x_n) + b)) - \sum_{n=1}^N \frac{1}{4C} \alpha_n^2 \right)$$

$$y_n = \frac{1}{2C} \alpha_n$$

max

$$\alpha_n \geq 0, 2 \leq y_n - \alpha_n \geq 0 \quad \left(\min_{b, w} \frac{1}{2} w^T w + \sum_{n=1}^N -\alpha_n (1 - y_n (w^T \phi(x_n) + b)) - \sum_{n=1}^N \frac{1}{4C} \alpha_n^2 \right)$$

$$\frac{\partial L(b, w, \alpha)}{\partial b} = -\sum_{n=1}^N \alpha_n y_n = 0,$$

max

$$\alpha_n \geq 0, 2 \leq y_n - \alpha_n \geq 0, \sum y_n \alpha_n = 0 \quad \left(\min_w \frac{1}{2} w^T w + \sum_{n=1}^N \alpha_n (1 - y_n (w^T \phi(x_n))) - \sum_{n=1}^N \frac{1}{4C} \alpha_n^2 \right)$$

$$\frac{\partial L(w, \alpha)}{\partial w} = 2w - \sum_{n=1}^N \alpha_n y_n \phi(x_n) = 0 \Rightarrow w = \sum_{n=1}^N \alpha_n y_n \phi(x_n)$$

$$\max \left(\frac{1}{2} w^T w + \sum_{n=1}^N \alpha_n - w^T w - \sum_{n=1}^N \frac{1}{4C} \alpha_n^2 \right)$$

$$= \min_{\alpha} \frac{1}{2} \sum_{h=1}^N \sum_{m=1}^N \alpha_h \alpha_m y_h y_m \mathbb{E}_h^T \mathbb{E}_m - \sum_{h=1}^N \alpha_h + \frac{1}{4C} \sum_{h=1}^N \sum_{m=1}^N \alpha_h \alpha_m [\mathbb{I}(h=m)]$$

$$= \min_{\alpha} \frac{1}{2} \left(\sum_{h=1}^N \sum_{m=1}^N \alpha_h \alpha_m y_h y_m K(x_h, x_m) + \frac{1}{2C} \sum_{h=1}^N \sum_{m=1}^N \alpha_h \alpha_m y_h y_m [\mathbb{I}(h=m)] - \sum_{h=1}^N \alpha_h \right)$$

$$= \min_{\alpha} \frac{1}{2} \sum_{h=1}^N \sum_{m=1}^N \alpha_h \alpha_m y_h y_m (K(x_h, x_m) + \frac{1}{2C} [\mathbb{I}(h=m)]) - \sum_{h=1}^N \alpha_h$$

14. [e]

$$\frac{\partial L}{\partial y_n} = 2 \leq y_n - \alpha_n$$

$$y_n = \frac{1}{2C} \alpha_n$$

$$y^* = \frac{1}{2C} \alpha^*$$

15

```
from libsvm.python.svmutil import*
import numpy as np

train_y , train_x = svm_read_problem("satimage_train.txt")
W = np.zeros(36)
W_square = 0
W_norm = 0

for i in range(len(train_y)):
    if train_y[i] != 3:
        train_y[i] = -1
    else:
        train_y[i] = 1

model = svm_train(train_y , train_x ,"-c 10 -s 0 -t 0 -q")
nSV = model.get_nr_sv()
alpha = model.get_sv_coef()
SV = model.get_SV()

for i in range(nSV):
    X = np.zeros(36)
    for j in range(1,37):
        X[j-1] = SV[i].get(j,0)
    W += alpha[i][0] * X

for i in range(36):
    W_square += W[i] ** 2
W_norm = W_square ** 0.5
print(W_norm)
```

16.

```
from libsvm.python.svmutil import*
import numpy as np

choice = range(1,6)
for number in choice:
    train_y , train_x = svm_read_problem("satimage_train.txt")

    W = np.zeros(36)
    W_square = 0
    W_norm = 0

    for i in range(len(train_y)):
        if train_y[i] != number:
            train_y[i] = -1
        else:
            train_y[i] = 1

    model = svm_train(train_y , train_x ,"-c 10 -s 0 -t 1 -d 2 -q")
    p_labs, p_acc, p_vals = svm_predict(train_y, train_x, model)

    print(number, " versus not ", number , " : " , 100-p_acc[0])
```

17.

```
from libsvm.python.svmutil import*
import numpy as np

choice = range(1,6)
for number in choice:
    train_y , train_x = svm_read_problem("satimage_train.txt")

    W = np.zeros(36)
    W_square = 0
    W_norm = 0

    for i in range(len(train_y)):
        if train_y[i] != number:
            train_y[i] = -1
        else:
            train_y[i] = 1

    model = svm_train(train_y , train_x ,"-c 10 -s 0 -t 1 -d 2 -q")
    nSV = model.get_nr_sv()

    print(number," versus not ", number , " : " , nSV)
```

18.

```
from libsvm.python.svmutil import*
import numpy as np

train_y , train_x = svm_read_problem("satimage_train.txt")
test_y , test_x = svm_read_problem("satimage_test.txt")

for i in range(len(train_y)):
    if train_y[i] != 6:
        train_y[i] = -1
    else:
        train_y[i] = 1
    if i < len(test_y):
        if test_y[i] != 6:
            test_y[i] = -1
        else:
            test_y[i] = 1

C = [0.01 , 0.1 , 1 , 10 , 100]
for c in C:
    model = svm_train(train_y , train_x , f"-c {c} -s 0 -t 2 -g 10 -q")
    p_labs, p_acc, p_vals = svm_predict(test_y, test_x, model)

    print(c , " E_out" , " : " , 100-p_acc[0])
```

19.

```
from libsvm.python.svmutil import*
import numpy as np

train_y , train_x = svm_read_problem("satimage_train.txt")
test_y , test_x = svm_read_problem("satimage_test.txt")

for i in range(len(train_y)):
    if train_y[i] != 6:
        train_y[i] = -1
    else:
        train_y[i] = 1
    if i < len(test_y):
        if test_y[i] != 6:
            test_y[i] = -1
        else:
            test_y[i] = 1

Gamma = [0.1 , 1 , 10 , 100 , 1000]
for ga in Gamma:
    model = svm_train(train_y , train_x , f"-c 0.1 -s 0 -t 2 -g {ga} -q")
    p_labs, p_acc, p_vals = svm_predict(test_y, test_x, model)

    print(ga , " E_out" , " : " , 100-p_acc[0])
```

```

20.

from libsvm.python.svmutil import*
import numpy as np
from random import randint

Gamma_choice = [0,0,0,0,0]
times = 0
while times < 1000:
    print(times)
    train_y , train_x = svm_read_problem("satimage_train.txt")
    valid_x = []
    valid_y = []
    ran = []
    i = 0
    while i < 200:
        rand = randint(0,4435)
        # if rand >= i:
        #     rand = rand - i
        if rand not in ran:
            valid_x.append(train_x[rand-i])
            valid_y.append(train_y[rand-i])
            train_x.remove(train_x[rand-i])
            train_y.remove(train_y[rand-i])
            ran.append(rand)
        i += 1

    for i in range(len(train_y)):
        if train_y[i] != 6:
            train_y[i] = -1
        else:
            train_y[i] = 1
    if i < len(valid_y):
        if valid_y[i] != 6:
            valid_y[i] = -1
        else:
            valid_y[i] = 1

Gamma = [0.1 , 1 , 10 , 100 , 1000]

```

```
for ga in Gamma:
    min_Eval = 100
    best_gamma = None
    model = svm_train(train_y , train_x , f"-c 0.1 -s 0 -t 2 -
g {ga} -q")
    p_labs, p_acc, p_vals = svm_predict(valid_y, valid_x, model ,"-q")
    if (100-p_acc[0]) < min_Eval:
        best_gamma = ga
        min_Eval = p_acc[0]

    if best_gamma == 0.1:
        Gamma_choice[0] += 1
    elif best_gamma == 1:
        Gamma_choice[1] += 1
    elif best_gamma == 10:
        Gamma_choice[2] += 1
    elif best_gamma == 100:
        Gamma_choice[3] += 1
    elif best_gamma == 1000:
        Gamma_choice[4] += 1
    times += 1

print(Gamma_choice)
```