

1. (a) From the definition of a lie group we know that  $\mu : G \times G \rightarrow G$  is smooth, then  $\mu_g = \mu \circ \iota_g$ , where  $\iota_g : G \rightarrow G \times G$  via  $h \mapsto (g, h)$  is the inclusion into the product manifold, we have seen previously the inclusion is smooth, so that  $\mu_g = \mu \circ \iota_g$  is smooth. Now we can also see that

$$\mu_{g^{-1}}\mu_g = 1_G = \mu_g\mu_{g^{-1}}$$

and  $\mu_{g^{-1}}$  is smooth for the same reason  $\mu_g$  is, so that  $\mu_g$  is in fact a diffeomorphism, this implies that  $d_e\mu_g$  is an isomorphism.

(b)

**(Lemma)** Let  $(\rho, E), (\hat{\rho}, \hat{E})$  be two vector bundles on the same base space  $M$ , and  $F : E \rightarrow \hat{E}$  a smooth bijective map of smooth vector bundles with  $F(x, 0) = (x, 0)$  (i.e.  $F$  descends to the identity), then  $F$  is a diffeomorphism.

*Proof.* Being a diffeomorphism is a local property, so for a point  $x \in M$ , let  $U$  be an open neighborhood of  $M$  where  $\rho^{-1}(U)$  admits a local trivialization  $\zeta$ , moreover there is a second neighborhood  $x \in V \subset U$  where  $\hat{\rho}^{-1}(V)$  admits a local trivialization  $\hat{\zeta}$  (since the base manifold is the same by possibly shrinking the neighborhood we can assume that the two bundle charts are equal on  $V \times \{0\}$ , this is not necessary but removes a lot of bloat from notation). Then  $\hat{\zeta} \circ F \circ \zeta^{-1} : M \times \mathbb{R}^n \rightarrow M \times \mathbb{R}^n$  is smooth, linear on each fiber and bijective on each fiber, so on  $V$ , we can write  $A(x) = \hat{\zeta} \circ F \circ \zeta^{-1}(x, -)$ . Then on the local trivialization  $F$  is given by

$$\hat{\zeta} \circ F \circ \zeta^{-1}(x, v) = (x, A(x)v)$$

In particular, the Jacobian  $D_{(x,v)}(\hat{\zeta} \circ F \circ \zeta^{-1})$  is given by

$$\begin{pmatrix} 1_n & 0 \\ B(x, v) & A(x) \end{pmatrix}$$

Bijectivity on each fiber implies that  $A(x)$  is full rank, so that  $\det(D_{(x,v)}\hat{\zeta} \circ F \circ \zeta^{-1}) = \det A(x) \in \mathbb{R}^\times$ , by the inverse function theorem  $\hat{\zeta} \circ F \circ \zeta^{-1}$  has a local smooth inverse, and hence  $F$  is a diffeomorphism.  $\square$

Since  $T_e G$  is  $n$ -dimensional, we can identify it with  $\mathbb{R}^n$ , the following diagram specifies the desired correspondence of vector bundles:

$$\begin{array}{ccc} G \times \mathbb{R}^n & \xrightleftharpoons[T]{F} & TG \\ \downarrow & & \downarrow \\ G & \xrightarrow{1_G} & G \end{array}$$

Where  $F(g, v) = (g, d_e\mu_g(v))$ ,

(when I originally solved the problem I tried to show  $F$  and the inverse map  $T$  which is not too hard to compute are both smooth, however, after trying to show  $F, T$  are smooth for quite some time I did the following computation which allowed me to see that  $F$  is smooth, this computation does not generalize easily to  $T$ , so the lemma is intended to avoid having to do a similar computation for  $T$ ).

In order to show  $F$  is smooth, it suffices to show that  $(g, v) \mapsto d_e\mu_g(v)$  is smooth, here we can use smoothness of  $\mu$ , and the identification  $T(G \times G) \longleftrightarrow TG \oplus TG$  by identifying on each fiber, we have previously computed (last homework) that  $d_p\iota_q = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$  when  $\iota$  denotes inclusion. We have that  $d\mu : T(G \times G) \rightarrow TG$  is smooth since  $\mu$  is a smooth map, then

$$\begin{aligned} d\mu((g, v), (h, u)) &= d_{(g,h)}\mu(v, u) \\ d_e\mu_g &= d_e(\mu \circ \iota_g)(v, u) = (d_{(g,e)}\mu)(d_e\iota_g)(v, u) = d_{(g,e)}\mu(u) \end{aligned}$$

From this computation, we can see that  $d_e\mu_g = d_{(g,e)}\mu(0, u)$  is the restriction of  $d\mu$  to  $TG \times \{e, 0\}$ , this is clearly a submanifold directly from the definition of it being a linear subspace given by inclusion on

the first  $2n$  coordinates. Thus the restriction of  $d\mu$  to this submanifold is smooth, and is identified with  $d_e\mu_g$ . So  $F$  is smooth, and we appeal to the lemma to find that  $T$ , the set theoretic inverse for  $F$  is smooth and hence  $F$  is a diffeomorphism.

**2.** Let  $f : X \rightarrow \mathbb{R}^m$  be a submersion, where  $X$  is a compact smooth manifold. The proof will follow if we can show submersions are open maps, assuming this, since the image of a compact set is compact (by pulling back an open cover along the map) we get that  $f(X) \subset \mathbb{R}^m$  is open, but also  $f(X) \subset \mathbb{R}^m$  is compact hence closed, so since  $X \neq \emptyset$  we have  $f(X) = \mathbb{R}^m$ , contradicting compactness.

It remains to show that a submersion is open, since  $f$  is a submersion, we can cover  $M, N$  with charts  $(U_\alpha, V_\alpha, \phi_\alpha)$  and  $(U'_\beta, V'_\beta, \varphi_\beta)$  respectively with the property that the following commutes (here  $\pi$  is the projection map onto the first  $n$  coordinates)

$$\begin{array}{ccc} U_\alpha & \xrightarrow{\phi_\alpha} & V_\alpha \\ \downarrow \pi & & \downarrow f \\ U'_\beta & \xrightarrow{\varphi_\beta} & V'_\beta \end{array}$$

Now let  $E \subset X$  be open, and write  $E_\alpha := V_\alpha \cap E$ , then

$$f(E) = \bigcup_{\alpha} f(E_\alpha) = \bigcup_{\alpha, \beta} \varphi_\beta \pi \phi_\alpha^{-1}(E_\alpha)$$

But  $\varphi_\beta \pi \phi_\alpha^{-1}$  is a composition of open maps hence open, so that  $f(E)$  is open which suffices to show  $f$  is open.

**3. (a)**