

Here are some notes meant for reference for my studies in geometric topology. I will only supply proofs when I think doing so will be edifying, these notes are mostly based from Bruno Martelli's Book as well as Do Carmo's book so proofs can be found there.

As convention when writing $C^\alpha(M)$ for a manifold M , $\alpha \geq 1$, but the $\alpha = \infty$ case is most interesting. All manifolds are atleast differentiable.

1 Riemannian Geometry

1.1 Vector Fields

Definition 1.1. A vectorfield $X : M \rightarrow TM$ can be thought of as a derivation, i.e. if $X(p) = \sum_1^n a_j(p) \frac{\partial}{\partial x_j}$ then $X : C^\alpha(M) \rightarrow C^{\alpha-1}(M)$ via

$$X(f)(p) = \sum_1^n a_j(p) \frac{\partial}{\partial x_j} f$$

Proposition 1.1. If $\varphi : M \rightarrow M$ is a diffeomorphism, and $v \in T_p M$ with $\gamma(0) = p$ and $\gamma'(0) = v$, then

$$(d_p \varphi(v))(f) = v(f \circ \gamma)(p)$$

Definition 1.2. The Lie bracket of two vector fields X, Y denoted $[X, Y]$ is the unique vectorfield Z satisfying $Z(f) = (XY - YX)(f)$ for all $f \in C^\alpha(M)$

Proposition 1.2. If X, Y are vectorfields on M , with $U \supset \{p\} \subset M$, and φ_t is a flow of X in U , then

$$[X, Y](p) = \lim_{t \rightarrow 0} \frac{1}{t} (Y - d\varphi_t Y)(\varphi_t(p))$$

1.2 Riemannian Metrics

Definition 1.3. A Riemannian metric is a positive definite, symmetric bilinear form $g : TM \otimes TM \rightarrow \mathbb{R}$

Definition 1.4. A Riemannian Manifold is a pair (M, g) where M is a manifold and g is a Riemannian metric.

Proposition 1.3. A Riemannian metric can be represented in coordinates, given a local frame (X_j) , and coframe (σ^j) we have

$$g(-, -) = \sum_{i \leq j} g(X_i, X_j) \sigma^i \sigma^j$$

Definition 1.5. $f : M \rightarrow N$ is a isometry between Riemannian manifolds if f is a diffeomorphism and $df^* g_M = g_N$

Definition 1.6. M and N are said to be locally isometric if for any $p \in M$ there is some neighborhood $p \in U$, and some $V \subset N$ with $f : U \rightarrow V$ an isometry. Note this is not an equivalence relation.

Example(s) 1.1. • Euclidean, g_{EUC} has $g_{ij} = \delta_{ij}$

- $f : M \rightarrow N$, then we can define $g_M(u, v) = g_N(df u, df v)$
- If a group G acts on M smoothly, freely, properly and isometrically then we can define for $\pi : M \rightarrow M/G$

$$g_{M/G}(u, v)_p = g_M(d_p \pi^{-1}(u), d_p \pi^{-1}(v))_{\pi^{-1}(p)}$$

The case of $U(1)$ acting on $\mathbb{C}^{n+1} \setminus \{0\}$ is the Fubini-Study metric on \mathbb{P}^n

- The product metric $g_{X \times Y}(u, v)_{p,q} = g_X(d\pi_X u, d\pi_X v) + g_Y(d\pi_Y u, d\pi_Y v)$, analogous to dot product.

Definition 1.7. A Riemannian metric on a Lie group is Left (resp. Right) invariant if L_x (resp. R_x) is an isometry for all $x \in G$. It is bi-invariant if it is both left and right invariant.

Proposition 1.4. All Lie groups have a left invariant Riemannian metric, namely take one on $T_e G$ and define

$$g_{\text{inv}}(u, v)_x = g(dL_{x^{-1}}u, dL_{x^{-1}}v)_e$$

Moreover, if G is compact it has a bi-invariant metric.

Proposition 1.5. g is bi-invariant if and only if for any $U, V, X \in T_e G$ we have

$$g([U, X], V) = -g(U, [V, X])$$

Definition 1.8. $I \subset \mathbb{R}$, and $\gamma : I \rightarrow M$, then for any closed interval $[a, b] \subset I$ we can define the length of the curve γ , since g will give a norm. Namely

$$\ell_a^b(\gamma) = \int_a^b \sqrt{g(\gamma'(t), \gamma'(t))} dt$$

Definition 1.9. It may be desirable to define the volume form in terms of Riemannian metrics, in this case we can write locally $x : U \subset M \rightarrow V \subset \mathbb{R}^N$ as coordinates and

$$dVol := \sqrt{\det(g_{ij})} dx_1 \cdots dx_n$$

1.2.1 Exercises

Exercise 1.2.1. Put a Riemannian metric on T^n so that $R^n \supset (x_1, \dots, x_n) \xrightarrow{f} (e^{ix_1}, \dots, e^{ix_n})$ is a local isometry, show this is isometric to the flat torus.

Proof. We use that the group action of \mathbb{Z}^n by translation has differential 1, so we can just use the metric given in the above examples. This makes f an isometry tautologically. \square

Exercise 1.2.2. Give an immersion $f : T^n \rightarrow \mathbb{R}^{2n}$ which is isometric to the flat Torus.

Proof.

$$f : (\theta_1, \dots, \theta_n) \mapsto (\cos \theta_1, \sin \theta_1, \dots, \cos \theta_n, \sin \theta_n)$$

Then we can simply evaluate

$$df|_{(\theta_1, \dots, \theta_n)} = \begin{pmatrix} -\sin \theta_1 & 0 & \cdots & 0 \\ \cos \theta_1 & 0 & \cdots & 0 \\ \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \cdots & -\sin \theta_n \\ 0 & 0 & \cdots & \cos \theta_n \end{pmatrix}$$

The flat metric gives us

$$g_{ij} = \delta_{ij}$$

And the immersion gives us

$$g \left(d_{\underline{\theta}} f \left(\frac{\partial}{\partial \theta_i} \right), d_{\underline{\theta}} f \left(\frac{\partial}{\partial \theta_j} \right) \right)_{f(\underline{\theta})} = g_{\text{EUC}}(-\sin \theta_i e_{2i-1} + \cos \theta_i e_{2i}, -\sin \theta_j e_{2j-1} + \cos \theta_j e_{2j}) = \delta_{ij}$$

\square

Exercise 1.2.3. The lie group of Affine transformations can be given by $\mathbb{R} \times (0, \infty)$, with $A(t) = yt + x$, then the lie group structure is composition. Show that $g_{11} = g_{22} = \frac{1}{y^2}$ gives a left invariant metric. Note that using this metric, and identifying $(x, y) \sim x + iy = z$ we get that the $SL(2, \mathbb{R})$ metric acts via isometry on G .

Proof. We simply compute $d_{(x,y)}L_{(A,B)} = \begin{pmatrix} B & 0 \\ 0 & B \end{pmatrix}$, so that

$$\begin{aligned} ((L_{(A,B)})_*g_{(x,y)})_{11} &= ((L_{(A,B)})_*g_{(x,y)})_{22} = B^2/(By)^2 = \frac{1}{y^2} \\ ((L_{(A,B)})_*g_{(x,y)})_{12} &= g_{12} = 0 \end{aligned}$$

□

Exercise 1.2.4. Show that "Locally isometric" is not an equivalence relation

Proof. Let η be a bump function on $U \subset \mathbb{R}^n$, the define g on \mathbb{R}^n as $g_{\text{EUC}} + \eta g_{\text{EUC}}$, it is clear we can't have a local isometry with flat \mathbb{R}^n on ∂U . Existence in the reverse direction is obvious, since we can just map diffeomorphically away from U . □

Exercise 1.2.5. Show that there exists a Bi-invariant Riemannian metric on any compact connected Lie Group.

Proof.

□