

Advanced Artificial Intelligence

Week #2-1

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PROBLEM-SOLVING in AI

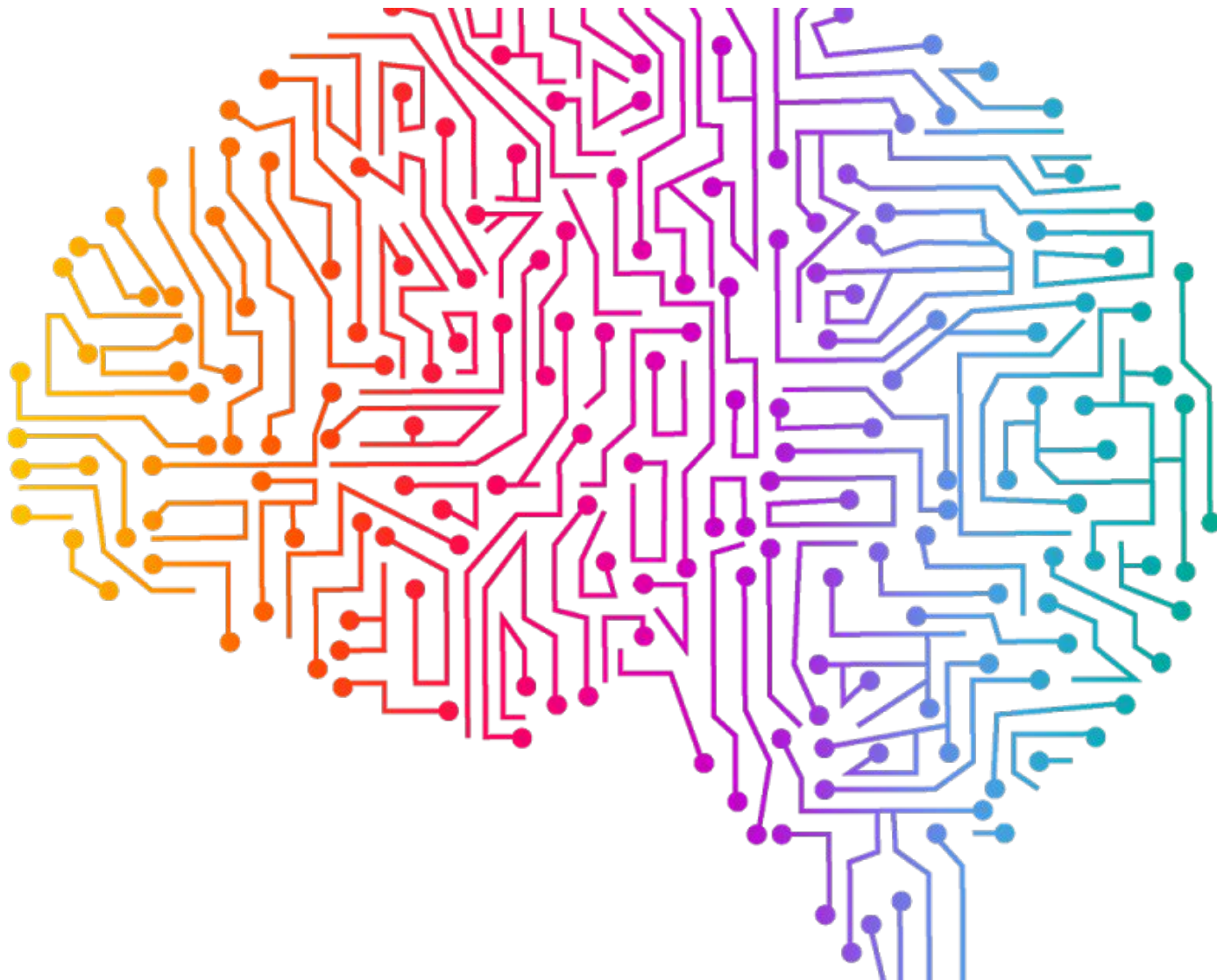




Learning Objective of this Topic

- What is Problem Solving?
- Problem-Solving Agent
 - Goal Formulation
 - Problem Formulation
 - Problem Definition
 - Searching Solution
 - Executing Solution

PROBLEM SOLVING

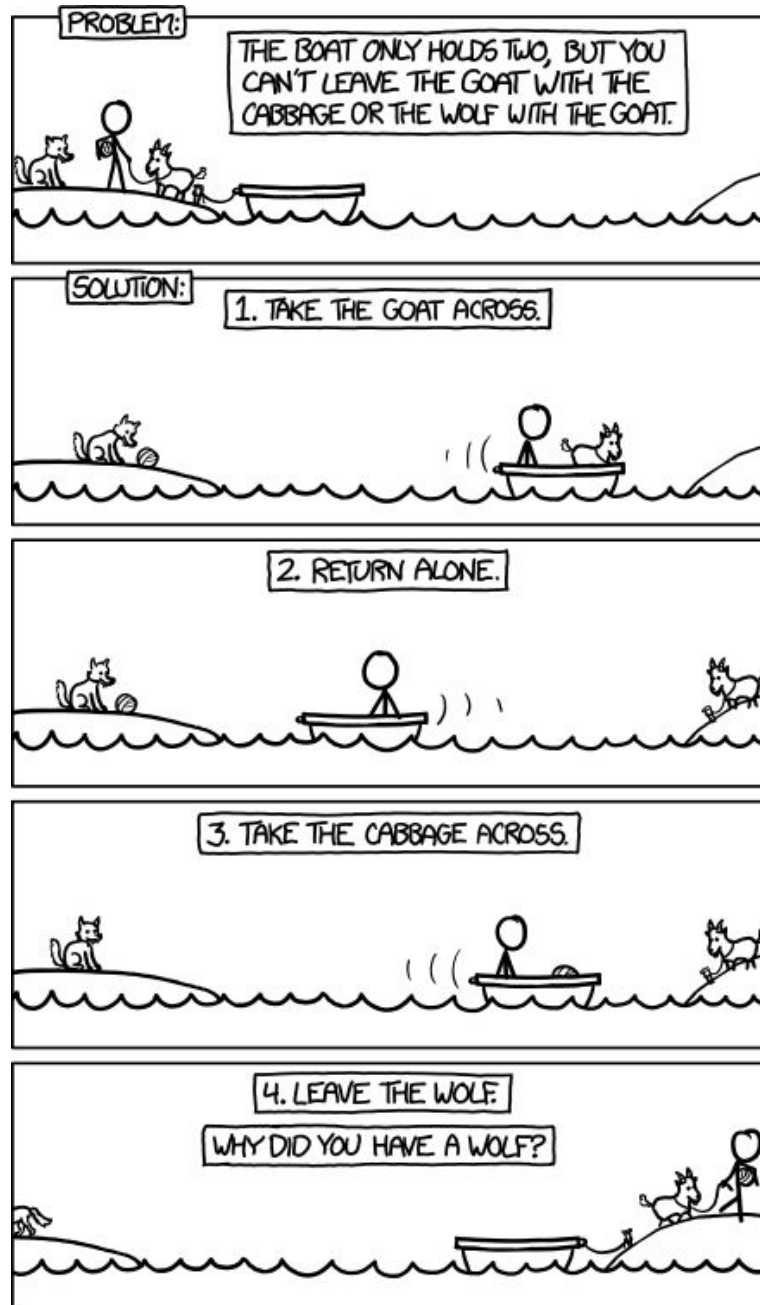
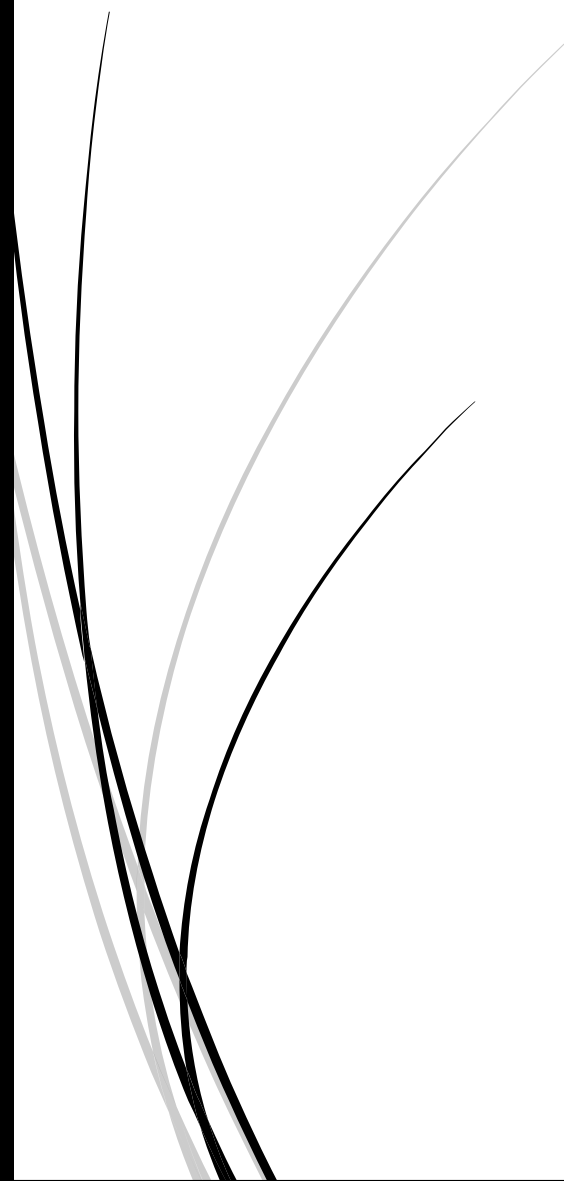


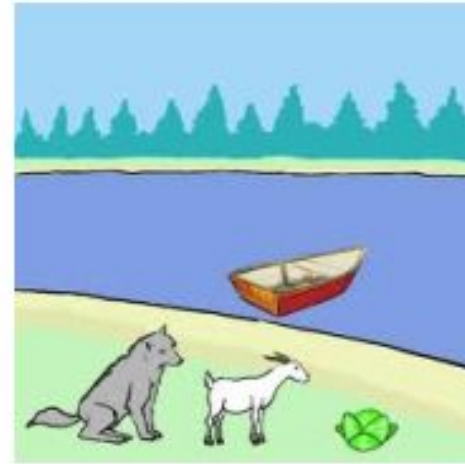


Question

□ A **farmer** wants to get his **cabbage**, **goat**, and **wolf** across a river. He has a boat that only holds two. He cannot leave the cabbage and goat alone or the goat and wolf alone. How many river crossings does he need?

- 4
- 5
- 6
- 7
- no solution



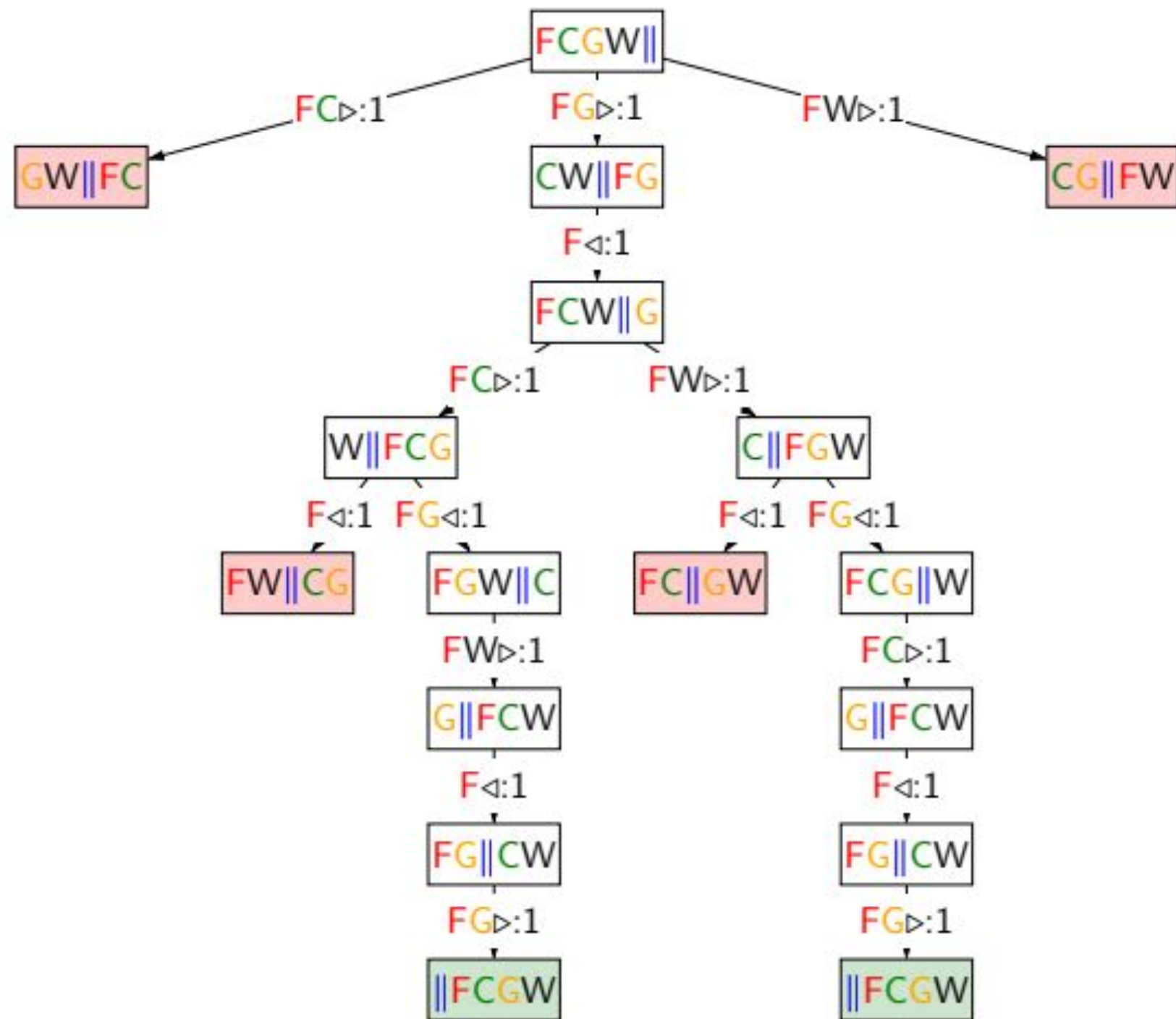


Farmer Cabbage Goat Wolf

Actions:

F▷	F◁
FC▷	FC◁
FG▷	FG◁
FW▷	FW◁

Approach: build a **search tree** ("what if?")





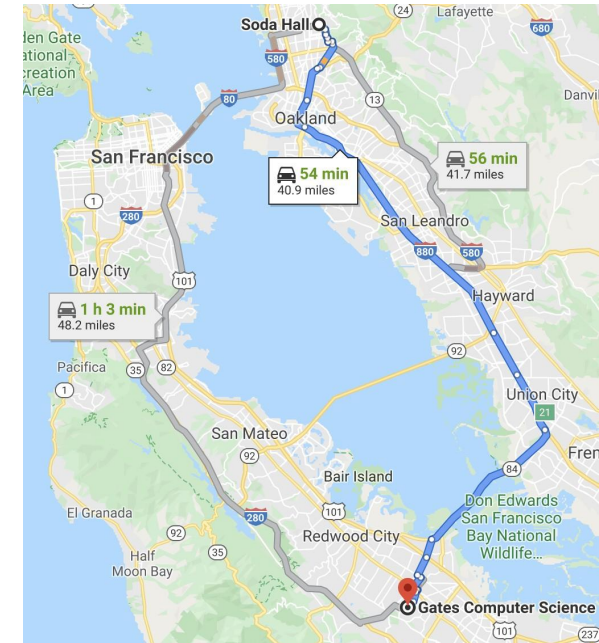
Problem Solving



- It is the process in which one perceives and tries to arrive at the desired solution from a present situation by taking some path, which is blocked by known or unknown hurdles.
- Problem solving also includes **decision-making**, which is the process of selecting the best suitable alternative out of multiple alternatives to reach the desired goal.

Application: Route finding

Objective: shortest? fastest? most scenic?
Actions: go straight, turn left, turn right



Application: Robot motion planning

Objective: fastest path

Actions: acceleration and
throttle



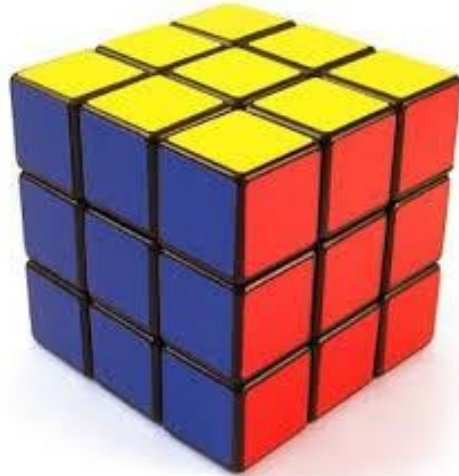
Application: Robot motion planning



Objective: fastest? most energy efficient? safest? most expressive?

Actions: translate and rotate joints

Application: Solving puzzles

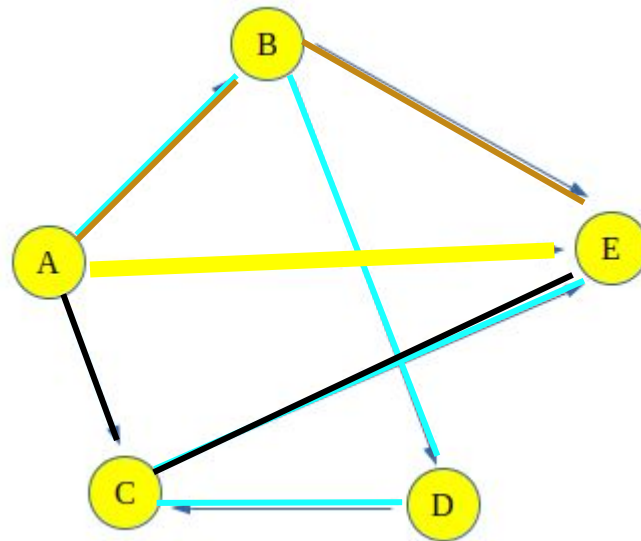


Objective: reach a certain configuration

Actions: move pieces (e.g., Move12Down)

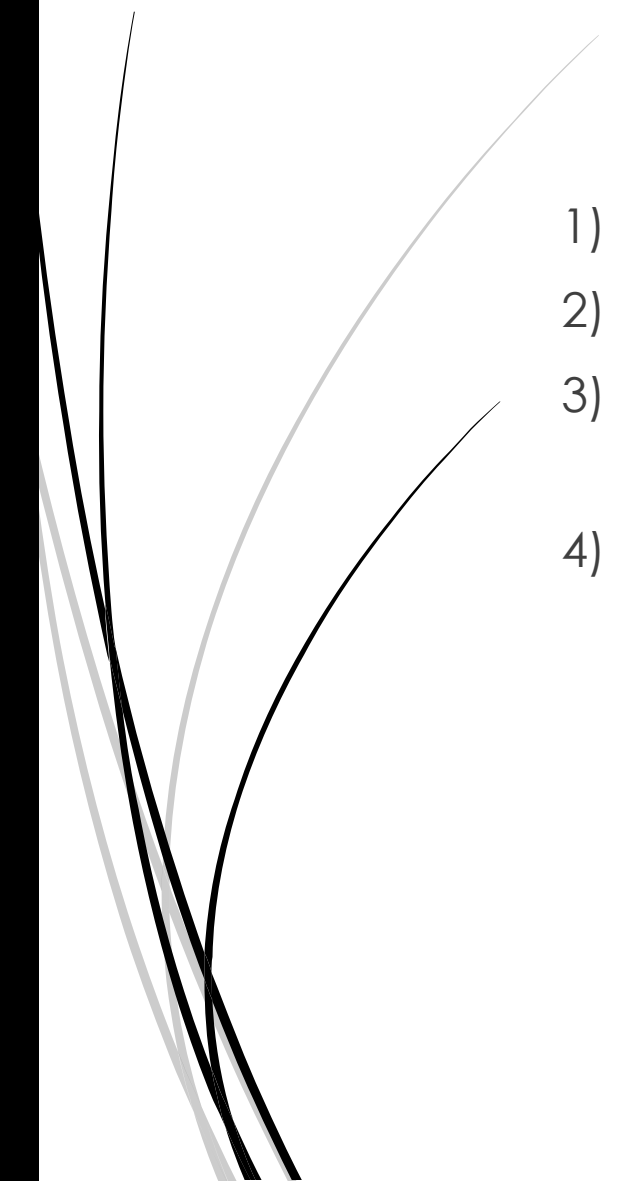
Simple Example

For the following Graph: there are how many ways to reach from vertex A to E.
What's the shortest way?





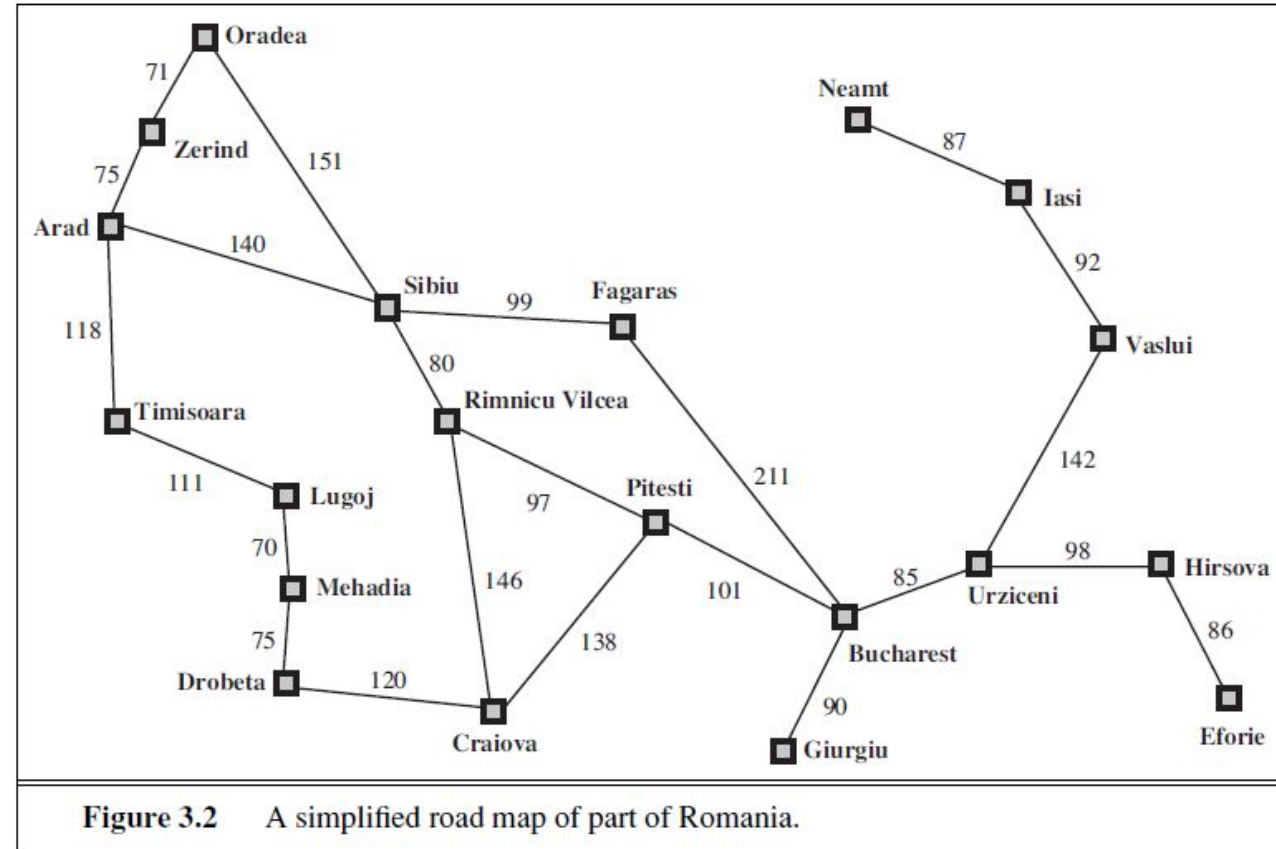
Problem Solving Agent

- 1) Goal Formulation
 - 2) Problem Formulation
 - 3) Searching Solution
 - Problem Definition
 - 4) Executing Solution
- 

1- Goal Formulation

- **Goal formulation**, based on the **current situation/state** and the agent's **performance measure**, is the first step in problem-solving.
- **Performance Measure**: Visit as many cities as possible, spend as low as possible on fuel.
- **Current State**: In Arad
- **Possible Goal**: In Bucharest

—————→ A set of states in which goal is satisfied





2- Problem Formulation

- ❑ **Problem formulation** is the process of deciding what actions and states to consider, given a goal.
- ❑ The agent will consider actions at the level of driving from one major town to another. Each state therefore corresponds to being in a particular town.
- ❑ **Go Left, Go Right, Go forward, Go reverse.** If these 4 actions are considered agent will never go out of the parking lot let alone reaching Bucharest.
- ❑ **Possible Action:** Go Cityname

Problem Definition

- A problem consists of five components,
 - Initial State
 - Possible Actions
 - Transition Model
 - Goal Test
 - Path Cost

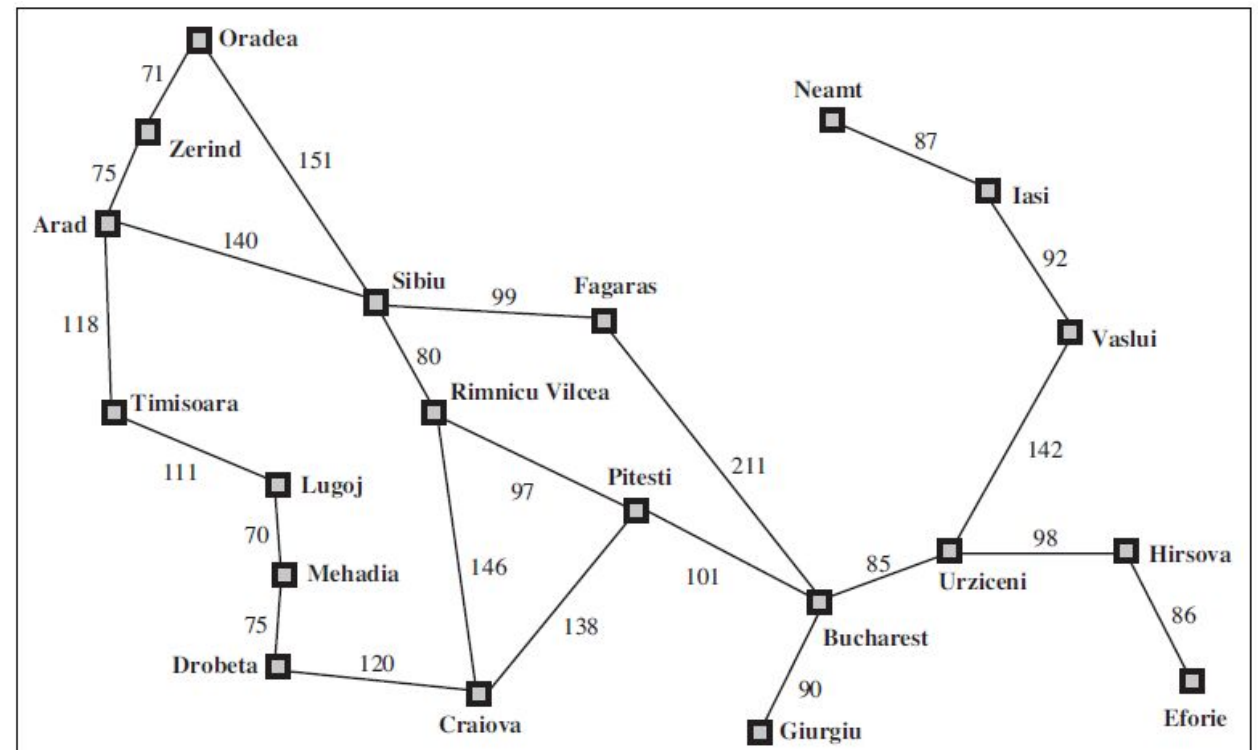
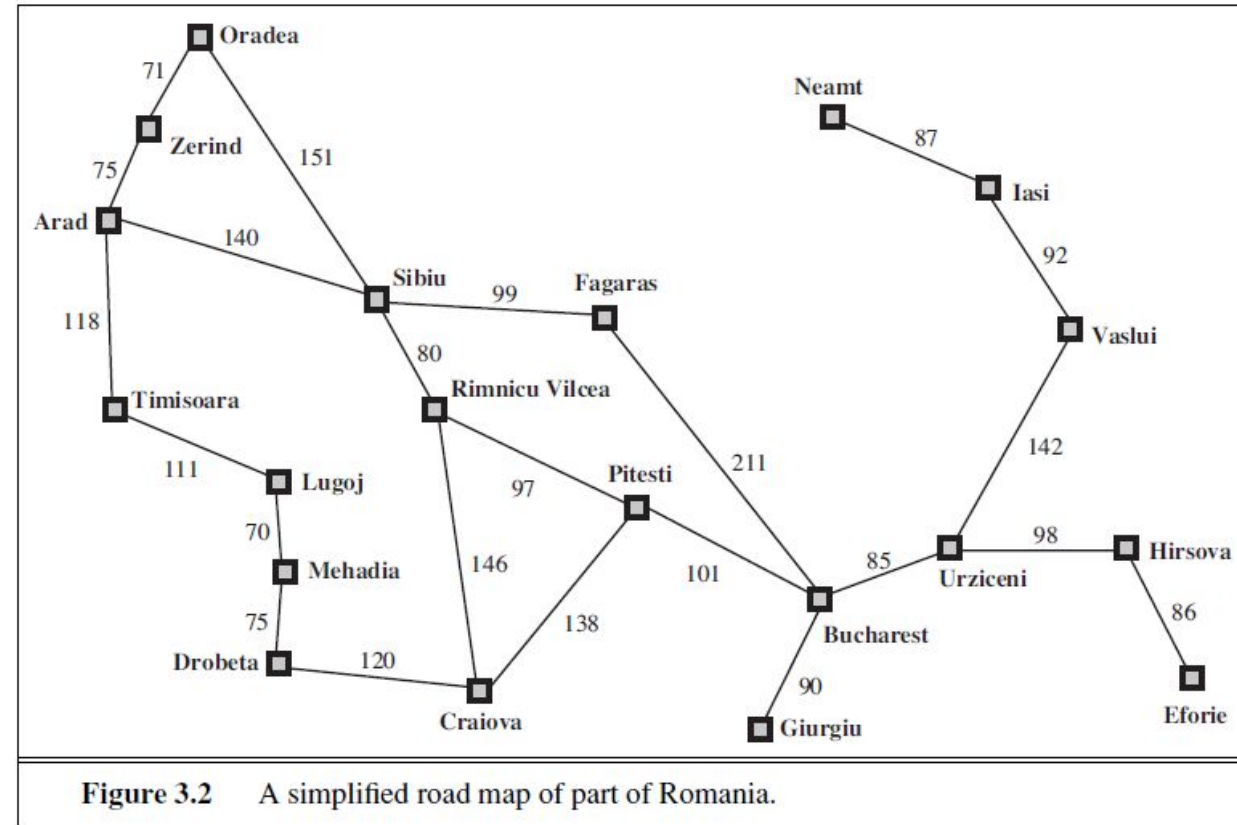


Figure 3.2 A simplified road map of part of Romania.

Problem Definition

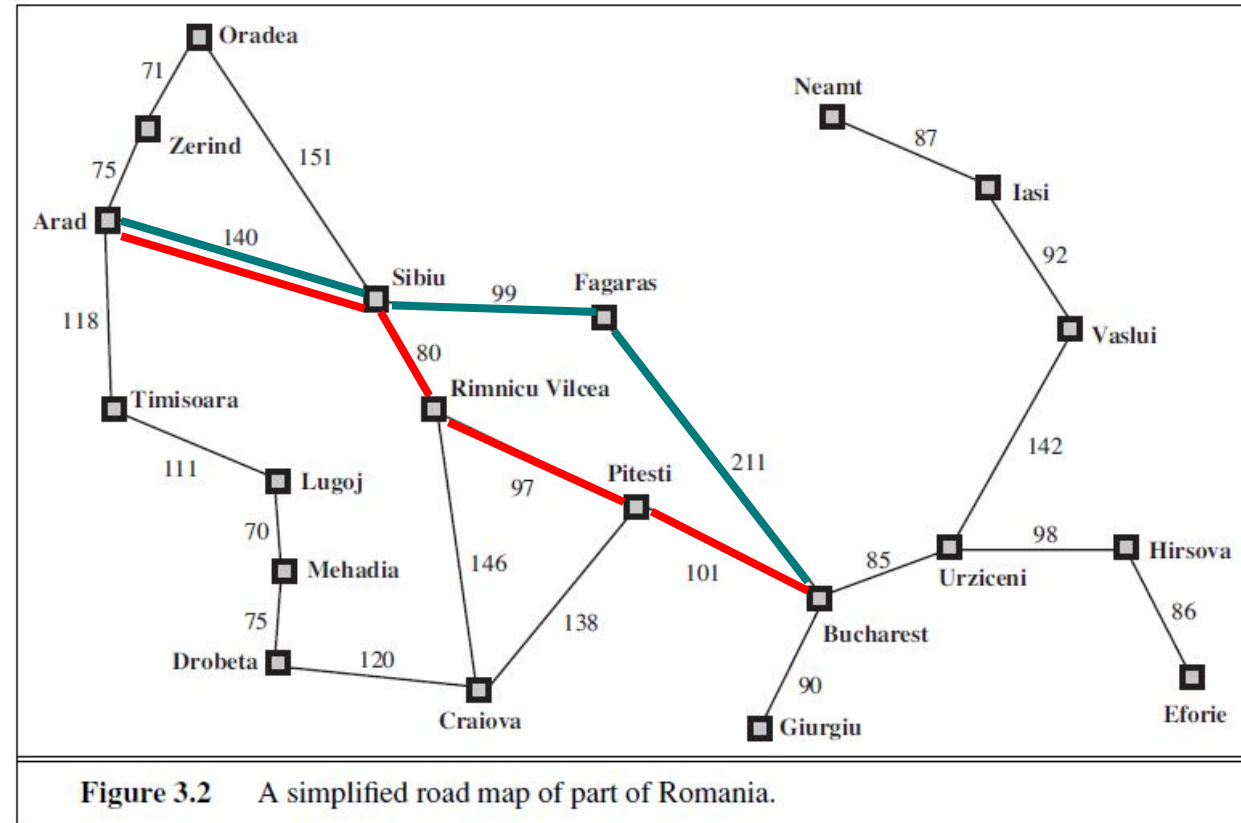
- A problem consists of five components,
 - Initial State: in (Arad)
 - Possible Actions (given a state): e.g.,
 - from Arad possible actions are {Go(Sibiu), Go(Timisoara), Go(Zerind)}.
 - Transition Model: specifies the relationship between a state, a possible action and the resulting successor state e.g.,

$\text{RESULT}(\text{In}(\text{Arad}), \text{Go}(\text{Zerind})) = \text{In}(\text{Zerind})$



Problem Definition

- A problem consists of five components,
 - Initial State
 - Possible Actions
 - Transition Model
 - Goal Test (whether a given state is a goal state) e.g. $\{In(Bucharest)\}$.
 - Path Cost (based upon agent's performance measure). Two paths shown on the right. **Step cost** (the cost of a single action within a path)



3- Searching Solution (Search Space Graph)

- On the right is the state space graph of our problem
- State Space** - the set of all states reachable from the initial state by any sequence of actions.
- A **path** in the state space is a sequence of states connected by a sequence of actions.

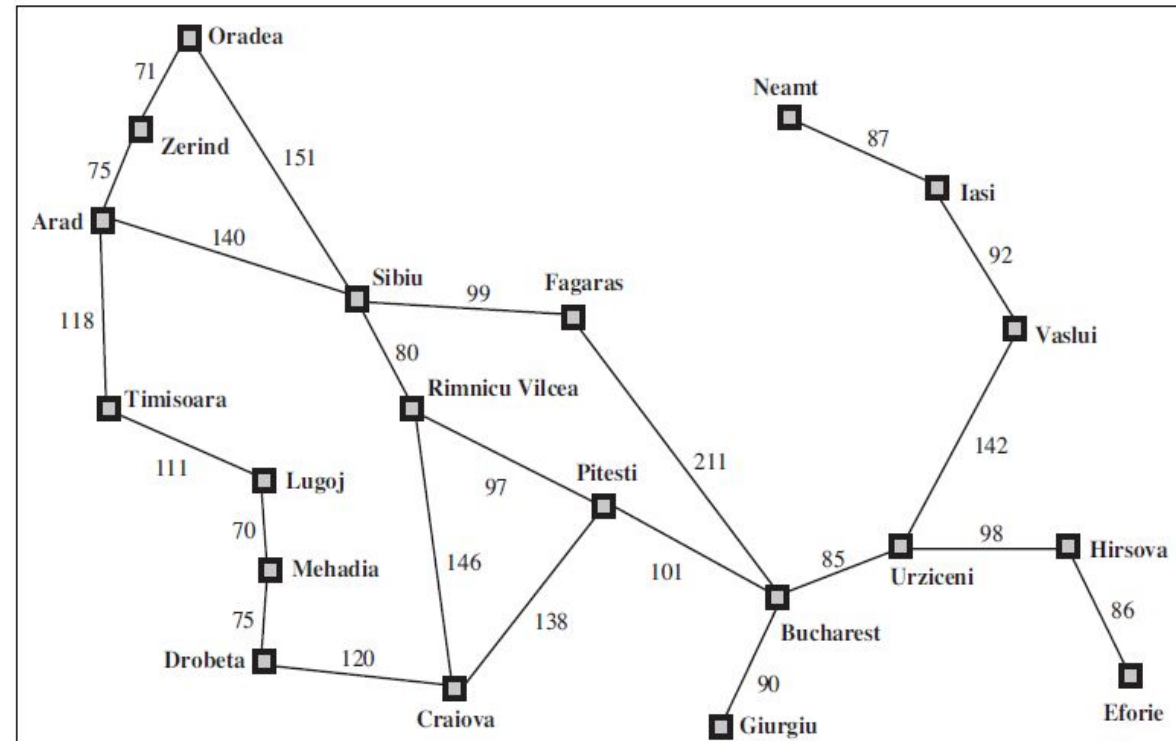
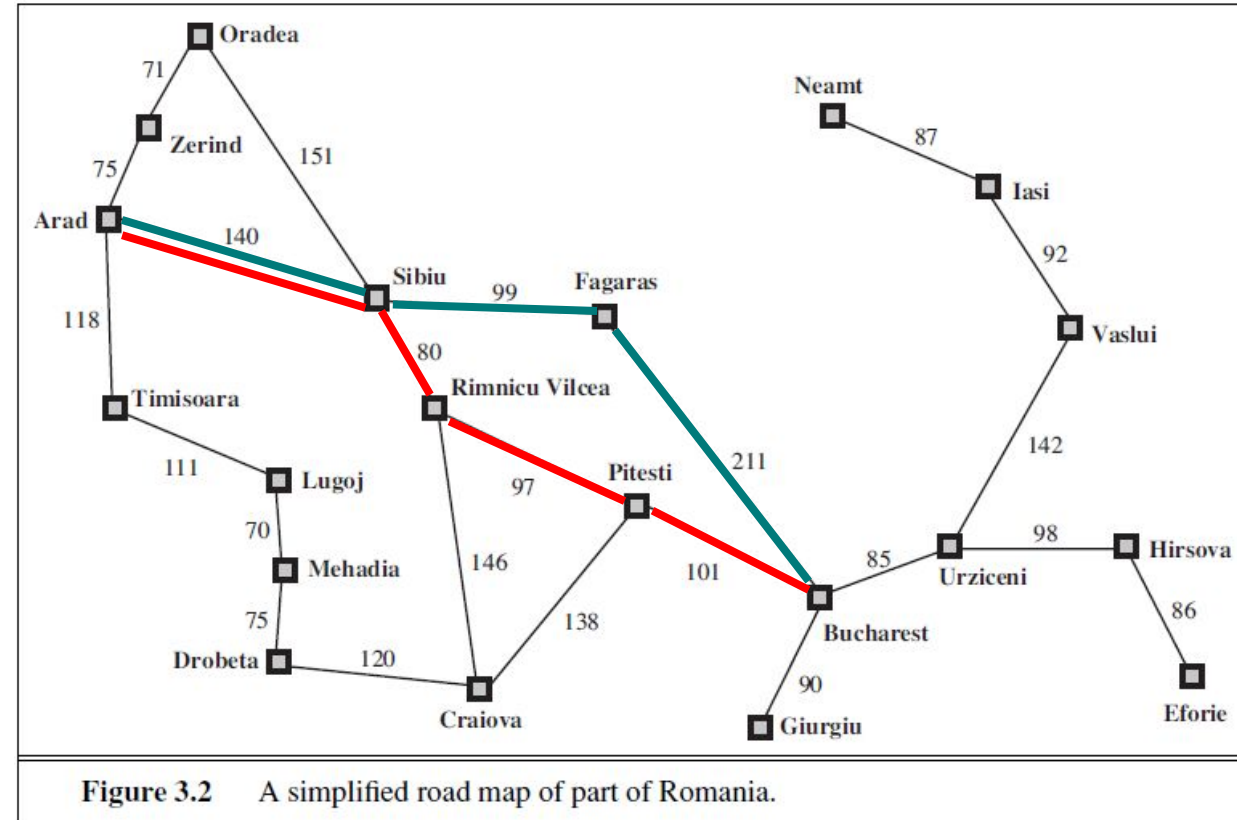


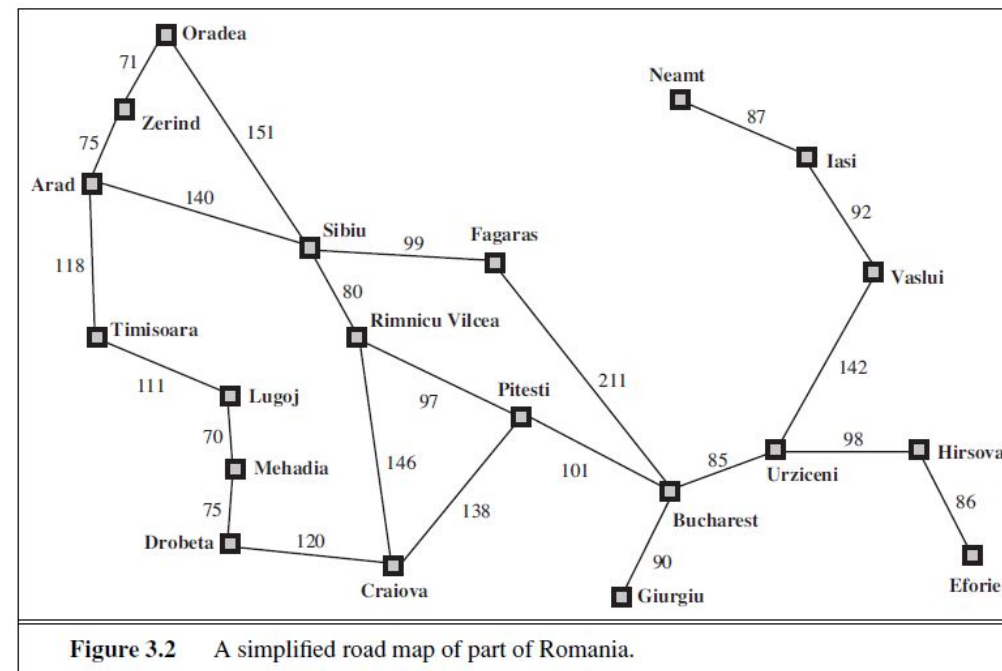
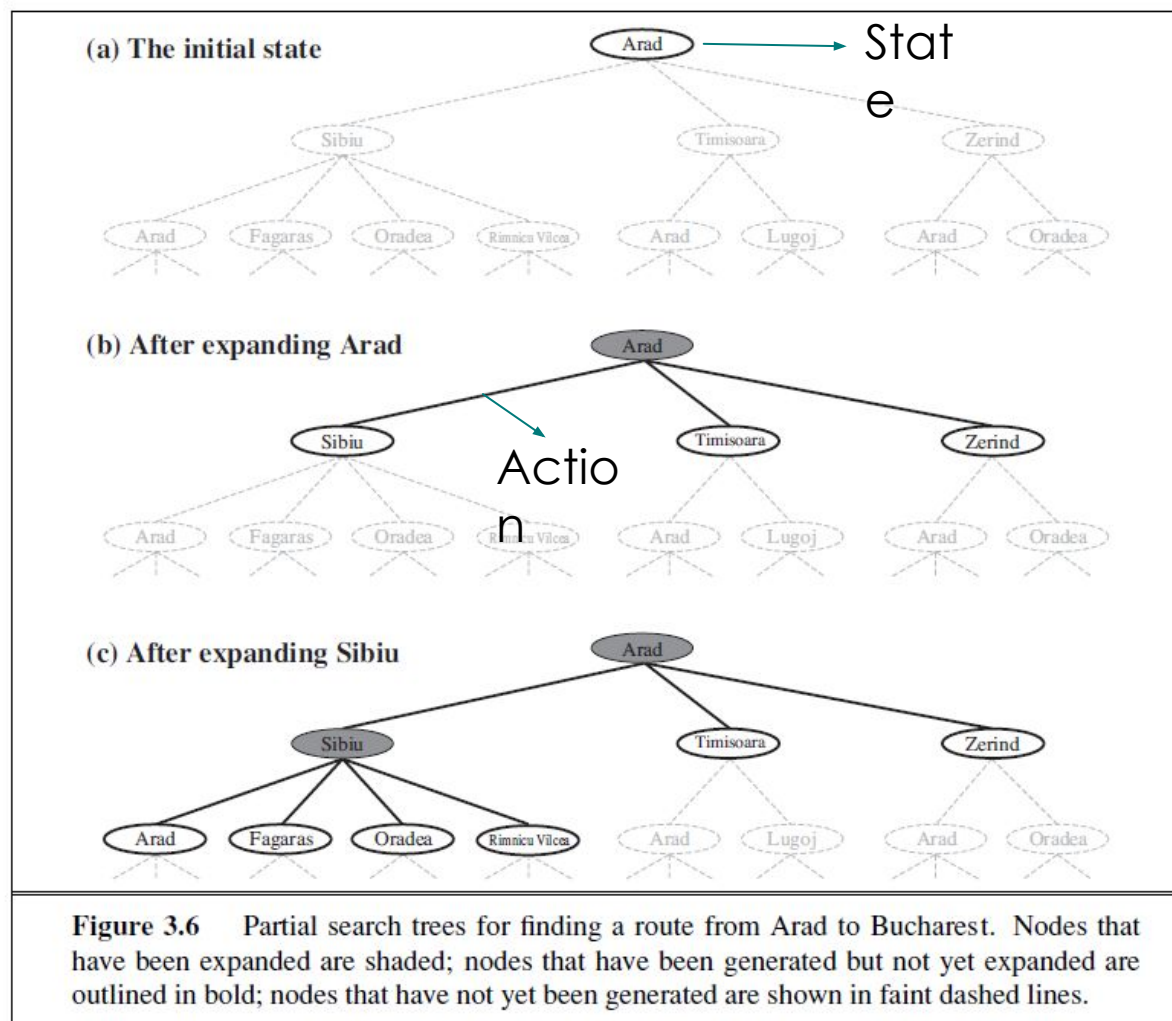
Figure 3.2 A simplified road map of part of Romania.

4- Executing Solution

- A **solution** to a problem is an action sequence that leads from the initial state to a goal state.
- Solution quality is measured by the path cost function, and an **optimal solution** has the lowest path cost among all solutions.

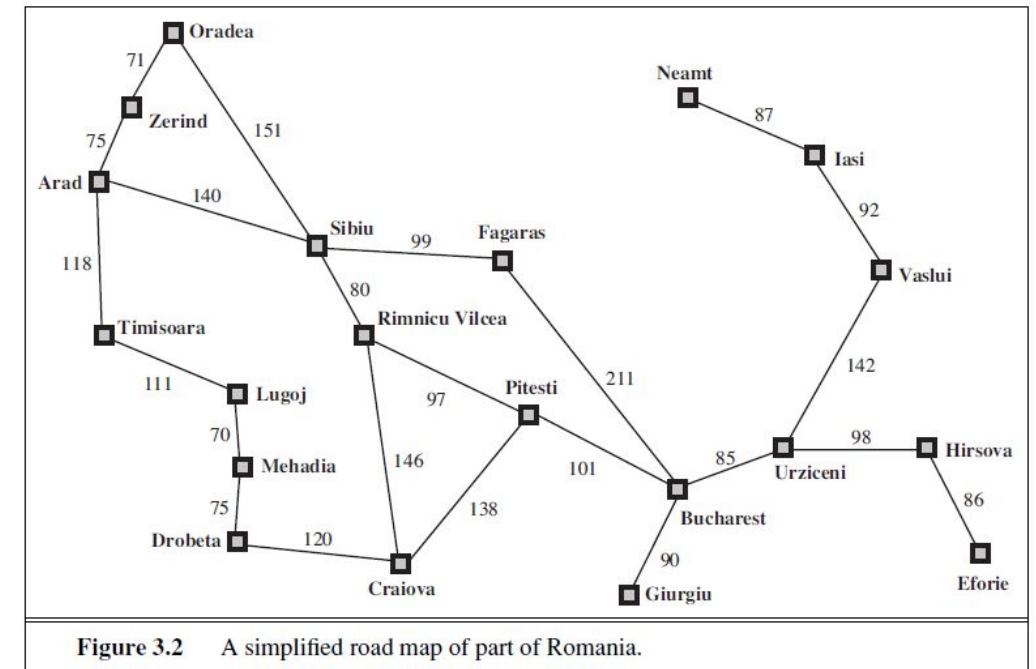
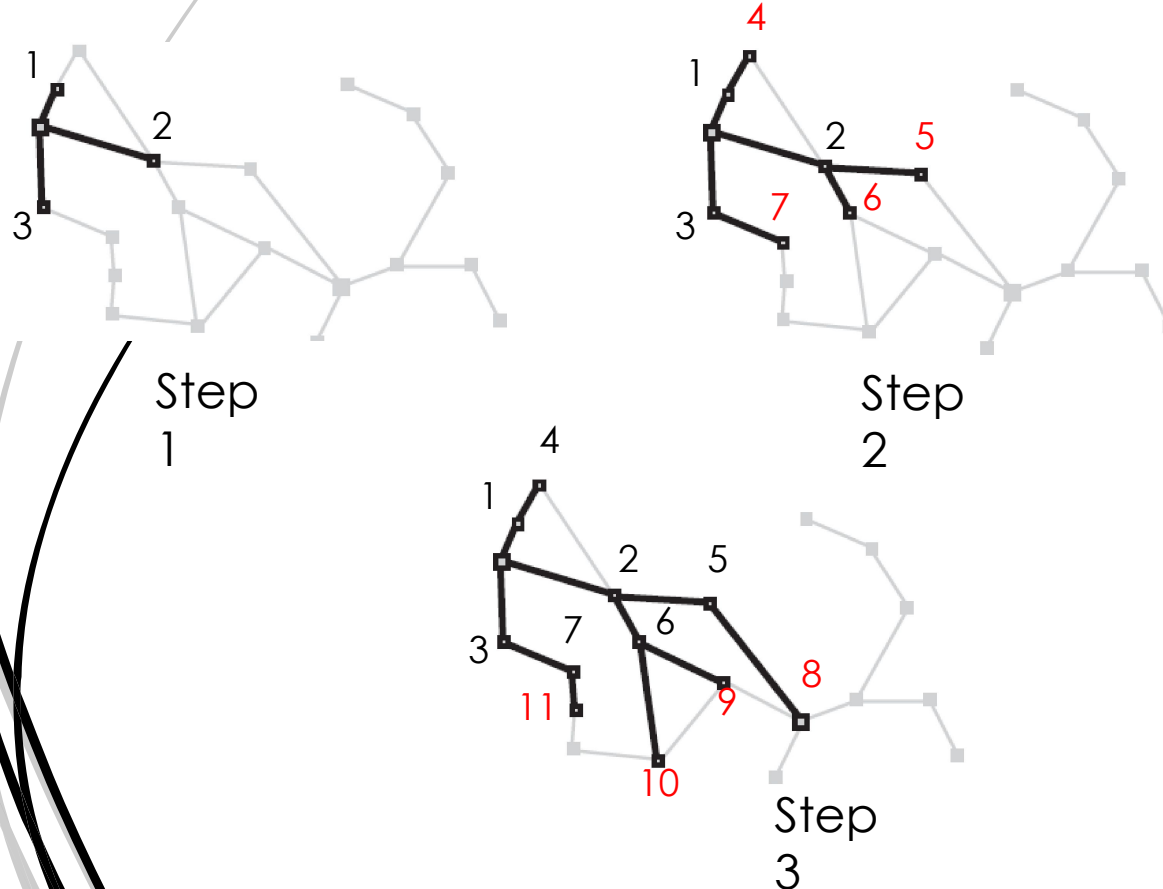


Tree Search



Graph Search

- Use an **explore set / closed list / frontier** to remember the states already visited





Problem-Solving Agent

□ *In which we look at how an agent can decide what to do by systematically considering the outcomes of various sequences of actions that it might take.*

- Stuart Russell & Peter Norvig



Two – One Problem

Start

1 1 ? 2 2

Goal

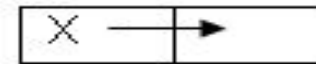
2 2 ? 1 1

Rules:

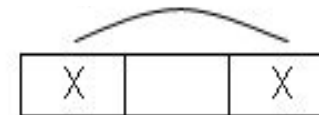
- 1s' move right
- 2s' move left
- Only one move at a time
- No backing up

Legal Moves:

- Slide



- Hop



Two – One Problem

Trials to solve the problem

Trial One

1 1 ? 2 2

1 1 2 ?

2

1 ? 2 1

2

1 2 ? 1

2

1 2 2 1

?

1 2 2 ?

1

Stuck!!!

Trial Two

1 1 ? 2 2

1 ? 1 2

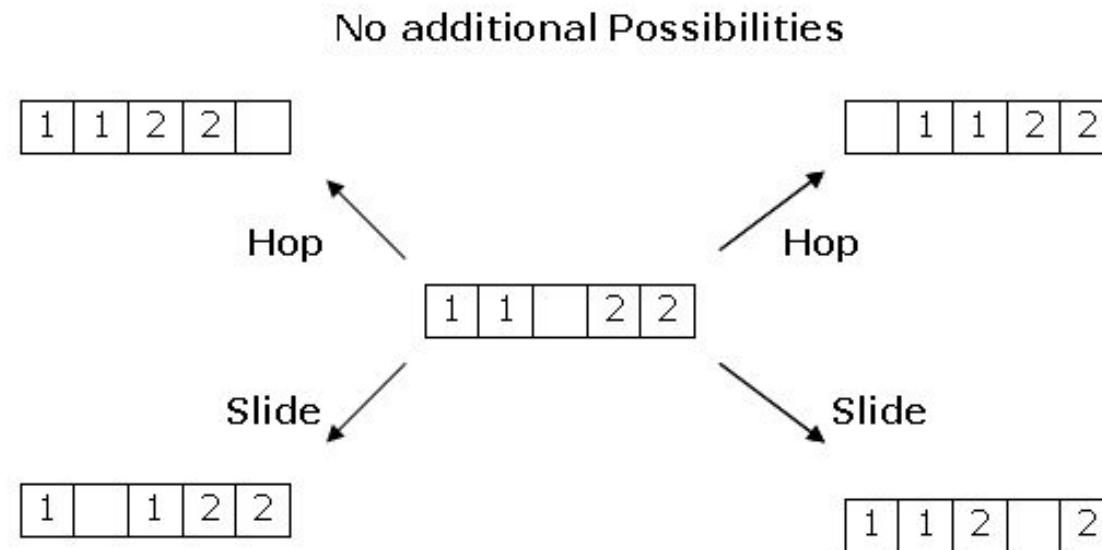
2

? 1 1 2 2

Stuck!!!

Two – One Problem

Five States



| Both hopping and sliding can still be applied

Two – One Problem-Solution Space

