

PES University, Bengaluru (Established under Karnataka Act No. 16 of 2013)

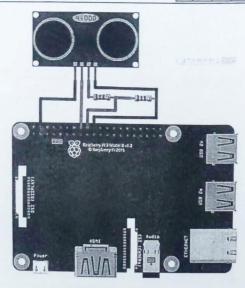
UE19CS313

DECEMBER 2021: END SEMESTER ASSESSMENT (ESA) B TECH 5th SEMESTER

UE19CS313 - INTERNET OF THINGS

Time: 3 Hrs	Answer All Questions	Max Marks: 100

	Allswel All Questions Max Marks. 200	
1 ay	Bring out the differences between the four phases of Internet evolution with examples.	4
b}	Safety, Mobility and Environment are the current challenges being addressed by Connected Roadways. Explain any one of the challenge with example.	
-0	Compare the Operational Technology (OT) Network and Enterprise Information Technology (IT) Network.	
d)	Explain the Core IoT Functional Stack of the Simplified IoT Architecture. •	6
2 a)	Explain the Characteristics of a Smart Object.	4
b)	Among the most significant impacts of precision agriculture are those dealing with sensor measurement of a variety of soil characteristics. Tabulate the following aspects of different sensors to measure the same.	4
	(a) Sensor (b) Sensor Type (c) Sensor Category (d) Description	(
(2)	The second the LM35 sensor interfaced	
	Complete the sketch given below to read the Temperature from the LM35 sensor interfaced with Arduino as given in the Figure above and display the same every 5 seconds.	
	<pre>int tempPin = 1; void setup()</pre>	
	Serial.begin(9600);	
	void loop()	
	{ //Write the code here to read the temp from pin	
	float mv = (val/1024.0) *5000; float cel = mv/10;	
	the code here to print the temp in Celsius	
	//Write the code here to display the temp once in 5secs	



Complete the Python code given here to read the Distance from the HC-SR04 sensor interfaced with RaspberryPi as given in the Figure above and alert only if the distance is less than 10CM with a delay of 5 seconds between each measurement.

d)

```
import RPi.GPIO as GPIO
import time
GPIO.setmode (GPIO.BOARD)
TRIG = 16
ECHO = 18
// Write the code here to set the mode of the pins
GPIO.output (TRIG, False)
time.sleep(2)
try:
    while True:
       GPIO.output (TRIG, True)
       time.sleep(0.00001)
       GPIO.output (TRIG, False)
       while GPIO.input (ECHO) == 0:
          pulse_start = time.time()
       while GPIO.input (ECHO) ==1:
          pulse_end = time.time()
       pulse_duration = pulse_end - pulse_start
       distance = pulse_duration * 17150
       distance = round(distance+1.15, 2)
       //write the code here to check if the dist is > 10CM
       //write the code here to give a delay of 5 seconds
except KeyboardInterrupt:
       GPIO.cleanup()
```

