

Medical Engineering - Imaging Systems

Ultra Sound

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Pattern Recognition Lab (CS 5)
SS 2021



Ultra Sound

Ultrasound Applications

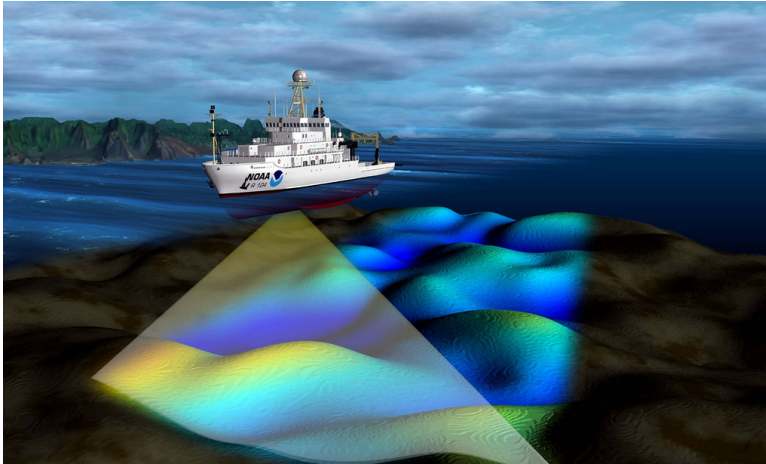
Ultrasound in Medicine

Physics of Sound Waves

Imaging Modes

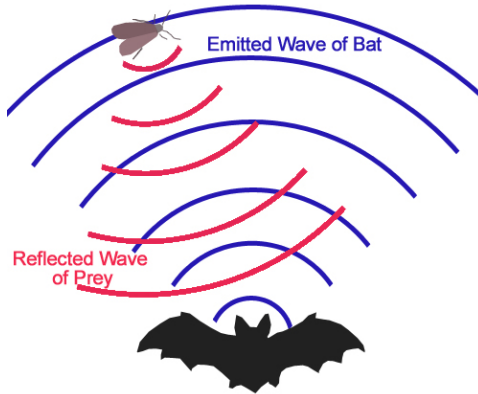
Safety in US Imaging

Ultrasound Applications: SONAR



Source: National Ocean Service

Ultrasound Applications: Echolocation



Source: By Shung <https://commons.wikimedia.org/w/index.php?curid=11999649>

Ultrasound Applications: Medical



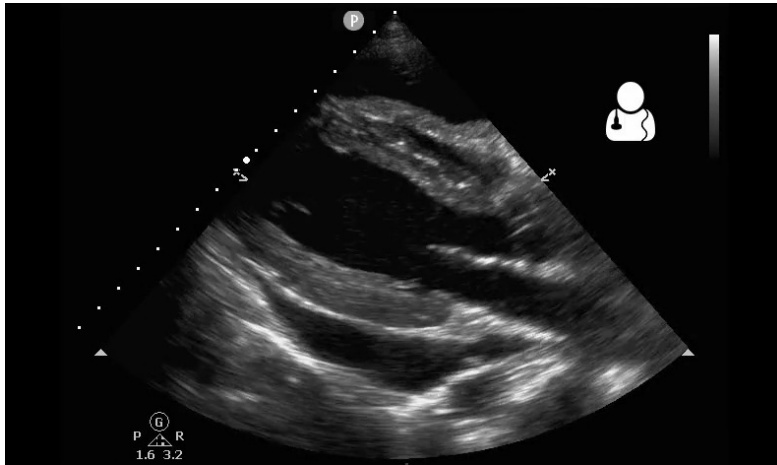


Ultrasound Applications: Medical (cont.)



3D Ultrasound of fetuses. Source: [1]

Ultrasound Applications: Medical (cont.)



Ultrasound image of a beating heart (click for video).

Ultrasound Applications: Medical (cont.)

Applications of ultrasound in medicine

- Pregnancy
- Gynecology
- Gastrointestinal tract
- Heart
- Blood vessels (stenosis, aneurysms)
- Blood flow
- ...

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Ultrasound Imaging

Ultrasound (US) imaging (or ultrasonography)

- A medical imaging technique that uses high frequency sound waves and their echoes
- similar to echolocation (bats, whales, dolphins) and SONAR (submarines)

Ultrasound Imaging (cont.)

Acoustic spectrum

	Frequencies f	Examples
Infrasound	0 ... 16 Hz	Seismic waves
Audible sound	16 Hz ... 20 kHz	Music Human speech
Ultrasound	20 kHz and up	Bats Dolphins SONAR Acoustic microscopy Medical Imaging

→ **Medical ultrasound:** $f \approx 1 \text{ MHz} \dots 40 \text{ MHz}$

Historical Remarks

From discovery of underlying physical principles to first clinical scanner

1880: Discovery of piezoelectric effect

1920: Ultrasound-based distance measurement in water (SONAR)

1933: Therapeutic use of ultrasound

1952: First 2D pulse echo image

1953: Breast imaging using ultrasound

1957: Echocardiography using ultrasound motion mode (M-mode)

1957: Doppler imaging

1958: First ultrasound scanner in clinical use

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Physics of Sound Waves

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Sound Waves

Waves

- Spatially propagating, periodically repeating processes
- Distinction based on **direction of propagation**
 - Transverse waves
 - Longitudinal waves

Sound Waves

- Sound waves are **longitudinal waves**
- Caused by **local periodic compression** of matter
- In liquids and gases: only longitudinal waves possible

Sound Waves (cont.)

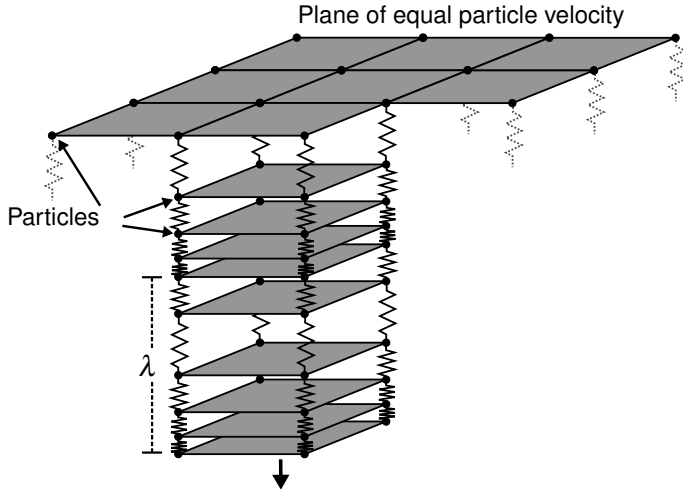
Sound waves can be characterized by

- Frequency f (Hz)
 - Oscillation count per second
- Sound velocity v (m s^{-1})
 - Independent of f
 - Varies with material properties (e.g. elasticity, density)
- Wavelength λ (m)
 - Distance between two oscillation maxima
- Intensity J (W m^{-2})
 - Acoustic power density

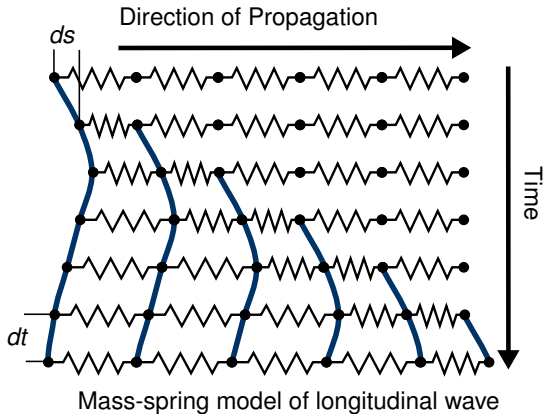
Fundamental wave equation:

$$\lambda = c/f$$

Sound Waves (cont.)



Sound Waves (cont.)



→ Sound velocity $v = ds/dt$

Sound Waves (cont.)

Acoustic impedance Z ($\text{g cm}^{-2} \text{s}^{-1}$)

Z of a medium is determined by its **material properties**

$$Z = \sqrt{E \cdot D}$$

Z : Acoustic impedance

E : Tensile modulus (elasticity)

D : Density of medium

Sound Waves (cont.)

Sound velocity in, and impedance of various biological materials

Medium	v [m/s]	Z [g cm ⁻² s ⁻¹]
Air	331	43
Fat	1470	$1.42 \cdot 10^5$
Water	1492	$1.48 \cdot 10^5$
Brain tissue	1530	$1.56 \cdot 10^5$
Muscles	1568	$1.63 \cdot 10^5$
Bones	3600	$6.12 \cdot 10^5$

Characteristics at Boundaries

At boundaries between two media, sound waves ...

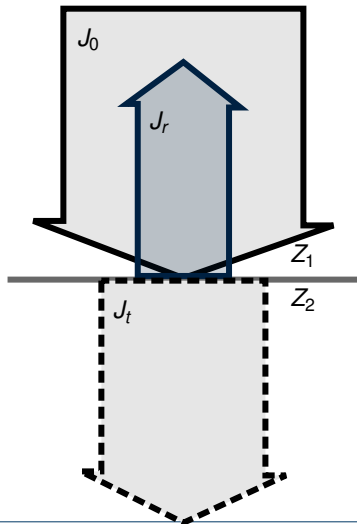
- ... are **partially reflected**
→ Reflection coefficient

$$R = \frac{J_r}{J_0} = \left(\frac{Z_2 - Z_1}{Z_2 + Z_1} \right)^2$$

- ... and **partially transmitted**
→ Transmission coefficient

$$T = \frac{J_t}{J_0} = \frac{4 \cdot Z_1 \cdot Z_2}{(Z_1 + Z_2)^2}$$

⇒ Holds for perpendicular incidence



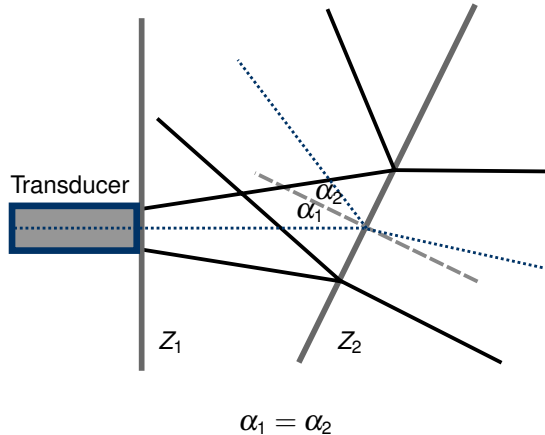
Characteristics at Boundaries (cont.)

Reflectivity at boundaries between various materials

Material 1	Material 2	Reflected portion
Brain	Skull bone	43.5 %
Fat	Muscle	1 %
Fat	Kidney	0.6 %
Muscle	Blood	0.1 %
Soft tissue	Water	0.25 %
Soft tissue	Air	99.9 %

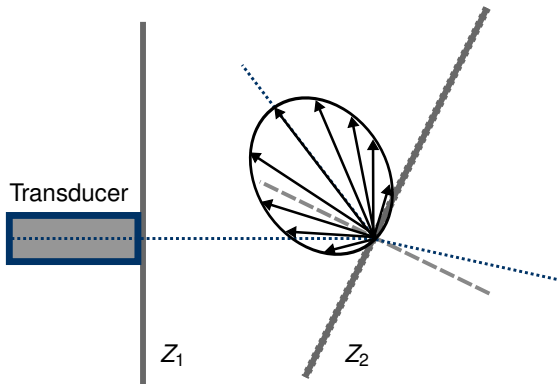
Characteristics at Boundaries (cont.)

Reflection of sound waves at smooth surfaces (angles α_1, α_2)



Characteristics at Boundaries (cont.)

Diffuse reflection at rough boundaries

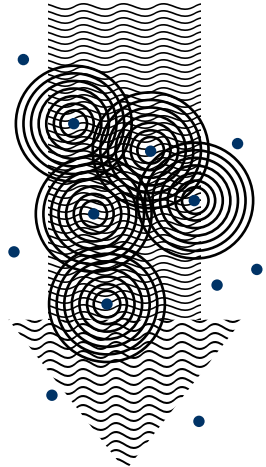


→ Width of reflection cone increases with decreasing λ and increasing roughness

Characteristics at Boundaries (cont.)

Small inhomogeneities (size: a) in the material cause **scattering** of the waves.

- $a \gg \lambda$: **Geometric** range (high scattering)
→ Vessels
- $a \approx \lambda$: **Stochastic** range (medium scattering)
→ Liver
- $a \ll \lambda$: **Rayleigh** range (low scattering)
→ Blood



Characteristics at Boundaries (cont.)

Reflection

- Reflection defines borders in ultrasound images
- Large portions of the incident intensity can be reflected
 - especially at borders of materials with large difference in impedance

Scattering ...

- ... adds to reflective response
- ... generates speckle noise
 - especially for inhomogeneities with $a \approx \lambda$ (geometric range)

Attenuation

Exponential law of attenuation

$$J(x) = J_0 \cdot \exp(-\mu \cdot x) \quad (1)$$

⇒ Acoustic intensity J decreases with increasing penetration depth (x)

Attenuation coefficient μ [dB]

- Attenuation that occurs with each cm the sound wave travels in a medium
- Depends on material (tissue type) and ultrasound frequency f
- Consists of absorption μ_a and scattering μ_s part: $\mu = \mu_a + \mu_s$
- Absorption leads to heating of tissue

Attenuation (cont.)

Maximum **penetration depth** for various frequencies f

f [MHz]	Max. depth [cm]	Typical Applications
1	50	<i>n/a</i>
3.5	15	Fetus, liver, heart, kidney
5	10	Brain
7.5	7	Prostate
10	5	Pancreas (intraoperative)
20	1.2	Eye, skin
40	0.6	Intravascular

- ⇒ For high maximum penetration depth, small frequencies are necessary.
- ⇒ Resolution decreases with decreasing frequency
- ⇒ more later . . .

Transducers

Ultrasound transducers ...

- ... send and receive ultrasound waves (and their echoes)
- ... convert mechanical energy into electrical energy and vice versa
- ... make use of the piezoelectric effect

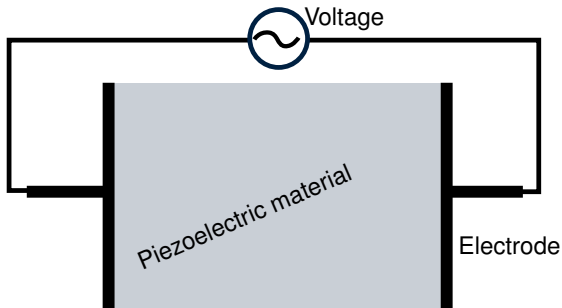


Source: Medical Imaging Systems [1]

Transducers (cont.)

Piezoelectric effect

- Mechanical pressure (*piezo* (gr.)) is converted to electric polarization
→ Electric voltage is generated (measurable using two electrodes)
- Electric field causes stretching of piezoelectric material
→ Can be used to generate sound waves



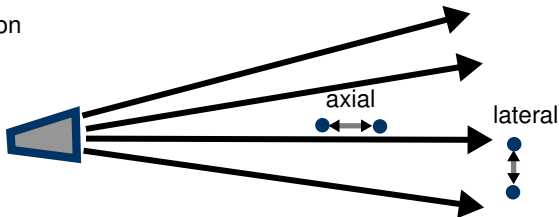
Spatial Resolution

Lateral resolution

- Minimal distance perpendicular to US beam to distinguish two points
- Affected by beam width and depth of imaging

Axial resolution

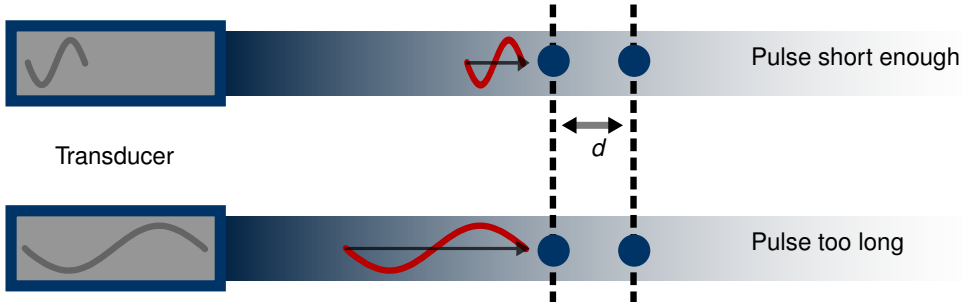
- Resolution in direction parallel to US beam
- Does **not** change with depth
- Also known as longitudinal or azimuthal resolution



Spatial Resolution (cont.)

Axial resolution (cont.)

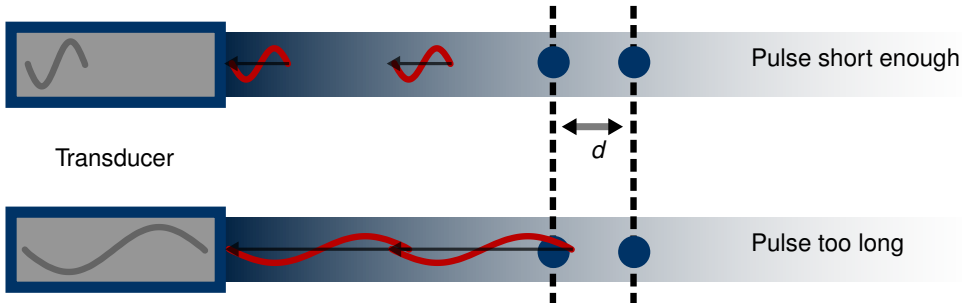
- Shortest pulse: single wave



Spatial Resolution (cont.)

Axial resolution (cont.)

- Shortest pulse: single wave



- Two **distinguishable** echoes are generated only if $d > \lambda/2$.
 → Resolution decreases when λ increases (frequency $f = c/\lambda$).

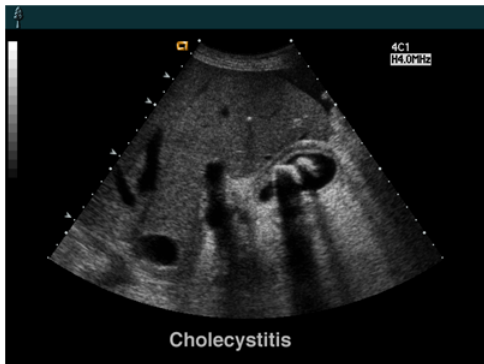
Spatial Resolution (cont.)

Frequency trade-off

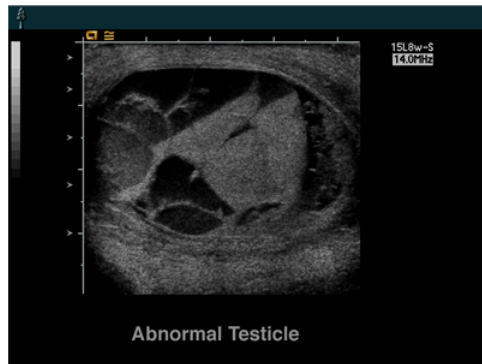
- Transducer frequency is directly related to resolution
 - High frequency \rightarrow high resolution
 - Low frequency \rightarrow low resolution
- However, it is also directly related to attenuation
 - High frequency \rightarrow high attenuation
 - Low frequency \rightarrow low attenuation
- High frequency \rightarrow low penetration depth with high resolution
- Low frequency \rightarrow deep penetration with low resolution

Spatial Resolution (cont.)

Frequency trade-off (cont.)



$f = 4 \text{ MHz.}$



$f = 14 \text{ MHz.}$

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Imaging Modes

Safety in US Imaging

Imaging Modes

Most common US imaging modes

- A-mode
- B-mode
- M-mode
- Doppler mode
 - Pulse wave Doppler
 - Continuous wave Doppler
 - Spectral Doppler
 - Color Doppler

Imaging Modes (cont.)

A-mode

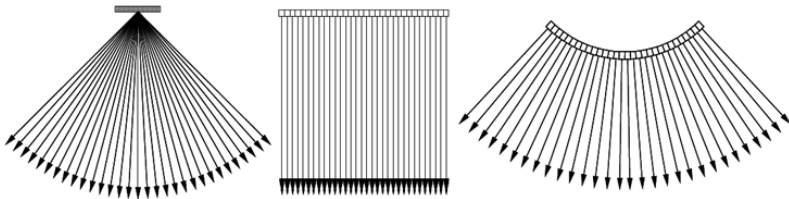
- **A**mplitude-mode
- Single transducer scans on a line through the body (1D)
- Depth: time required for US beam to hit boundary and reflect signal
- Reflected signal strength can be measured (amplitude)
- Echoes are plotted on screen as function of depth

→ **Simplest** scanning method.

Imaging Modes (cont.)

B-mode

- **B**rightness-mode (or **2D mode**): spatially encoded echo amplitude
- Time required for echo: position
- Amplitude: image **brightness**
- Uses **array** of transducers to generate 2D images

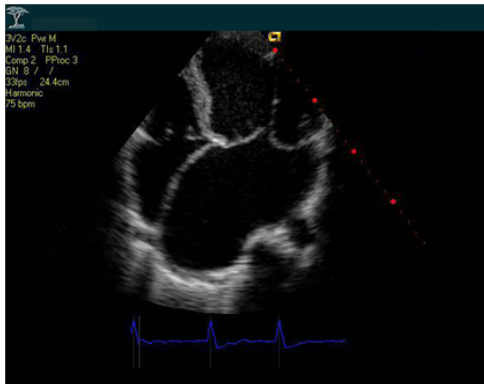


Left to right: sector probe, linear array, curved array.

→ **Most common** scanning method.

Imaging Modes (cont.)

B-mode (cont.)



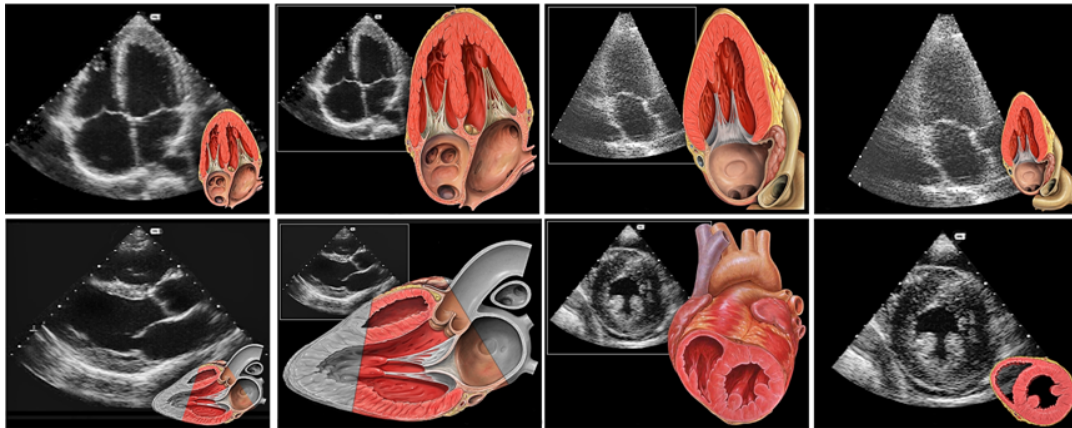
Heart with enlarged atrium
(sector probe)



Liver with large tumor
(curved array)

Imaging Modes (cont.)

B-mode (cont.)



Various views of the heart

Source: Patrick J. Lynch (<http://wikipedia.org/>)

Imaging Modes (cont.)

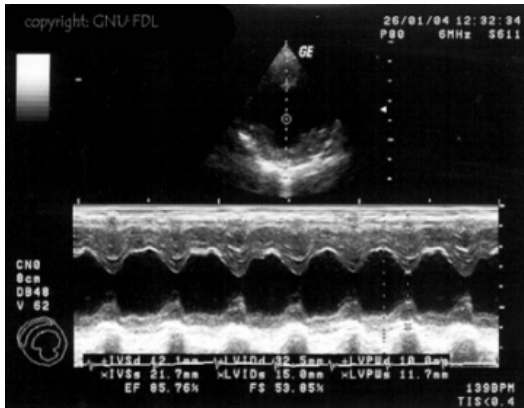
M-mode

- **Motion-mode**
- Pulses are emitted in quick succession (same probe position)
- Either an A-mode or a B-mode image is taken each time
- Time-dependent organ movement relative to the probe can be measured
→ velocity of specific organ structures

→ Example: Cardiac (echocardiography) wall movement analysis.

Imaging Modes (cont.)

M-mode (cont.)



Combined B- and M-mode visualization of dog heart

Source: <http://wikipedia.org/>

Imaging Modes (cont.)

Doppler ultrasonography

- Enables visualization of blood **flow** (velocity)
- **Continuous wave** (CW) Doppler
 - Half of transducer array emits, half detects pulses (simultaneously)
 - No distance information
- **Pulsed Wave** (PW) Doppler
 - Pulse-based
 - Distance information is obtained (time-gating)

→ Makes use of the **Doppler effect**.

Imaging Modes (cont.)

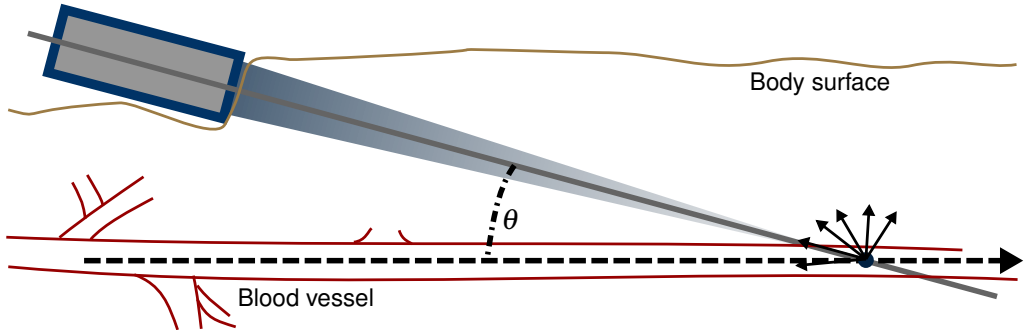
Doppler ultrasonography (cont.) – Doppler effect

- Change in wave frequency by relative movement between **source** and **observer**
- Characteristic frequency shifts appear → proportional to velocity
- Named after Christian Johann Doppler (*1803, † 1853)
- Examples
 - Siren of ambulance
 - Astronomical red-shift
 - Blood flow

Imaging Modes (cont.)

Doppler ultrasonography (cont.)

- Doppler effect in US **blood flow** imaging
 - Source: **Moving** blood cells (through **scattering** of US wave)
 - Observer: US transducer
 - Doppler angle θ (between blood and sound direction) \rightarrow the smaller the better



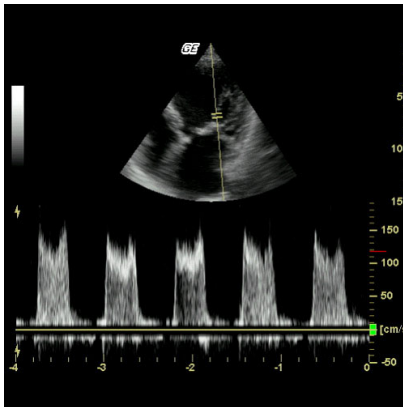
Imaging Modes (cont.)

Doppler ultrasonography (cont.)

- **Spectral Doppler**
→ Visualize spectrum of blood speeds
- **Color Doppler**
→ Color-coded overlay on top of B-mode image

Imaging Modes (cont.)

Doppler ultrasonography (cont.)



Spectral doppler.

Imaging Modes (cont.)

Doppler ultrasonography (cont.)

Mitral valve insufficiency (dog heart), color doppler

Imaging Modes (cont.)

Dimensionality of acquired images

- 1D \rightarrow A- or M-mode
- 2D \rightarrow many B-mode scan lines (e.g. linear/curved transducer array)
- 3D \rightarrow several 2D images at different angles combined into single volume
- 4D \rightarrow 3D + time

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Safety in US Imaging

US waves are **not ionizing**, however they can harm the body . . .

- . . . through heating
 - locally, proportional to absorbed acoustic intensity (J)
- . . . through cavitation
 - emerging gas bubbles in low pressure phase of sound wave
 - collapse at high pressure phase

→ Acoustic intensities for medical diagnostics rather low

→ **harmless**, it is even used during pregnancy

Therapeutical use of ultrasound

- Break up gallstones and kidney stones
- Heat and destroy diseased or cancerous tissue