1st profile: output from gprof on 800x800 all-land array on CP Lab

Each sample cou	Each sample counts as 0.01 seconds.	onds.				
9/0	cumulative	self		self	total	
time	seconds	seconds calls	calls	s/call	s/call	name
47.00	58.77	58.77	1250	0.05	60.0	Landscape::Update()
24.30	89.15	30.38	4806406416	00.0	00.0	<pre>Array2D<cell>::operator()(unsigned int, unsigned int)</cell></pre>
10.75	102.59	13.44	511439120	00.0	00.0	std::vector <cell, std::allocator<cell=""> >::operator[]</cell,>
(unsigned long)						

2nd profile: after removing bounds checking from Array2D<T>::operator()

Each sample cou	Each sample counts as 0.01 seconds.	onds.				
9/0	cumulative	self		self	total	
time	seconds	seconds	calls	s/call	s/call	name
50.30	58.25	58.25	1250	0.05	60.0	Landscape::Update()
15.18	75.83	17.58	4806406416	00.0	00.0	<pre>Array2D<cell>::operator()(unsigned int, unsigned int)</cell></pre>
13.72	91.71	15.89	511439120	00.0	00.0	std::vector <cell, std::allocator<cell=""> >::operator[]</cell,>
(unsigned long)						

3rd profile: array bounds checking disabled and iteration order swapped in Landscape::Update()

Each sample counts as 0.01 seconds.	cumulative self	e seconds seconds calls s/call name	59.65 59.65 1250	81.10 21.45 4806406416 0.00 0.00	96.27	(Buo
 nts as 0.0	cumulati	seconds	59.65	81.10	96.27	
 Each sample cou	%	time	48.54	17.45	12.34	(unsigned long)