$$
\begin{aligned}
\boldsymbol{H}_{L-F}^{w} &= \text{Encoder}_{w}(\boldsymbol{H}_{0}^{w}) \\
\boldsymbol{H}_{L-F}^{v} &= \text{Encoder}_{v}(\boldsymbol{H}_{0}^{v}) \\
\boldsymbol{H}_{L}^{w} &= \text{Encoder}_{s}(\boldsymbol{H}_{L-F}^{w}) \\
\boldsymbol{H}_{L}^{v} &= \text{Encoder}_{s}(\boldsymbol{H}_{L-F}^{v}) \\
\boldsymbol{H}_{l}^{w} &= \left[\boldsymbol{w}_{l}^{\texttt{[T\_CLS]}}, \boldsymbol{w}_{l}^{1}, ..., \boldsymbol{w}_{l}^{M}, \boldsymbol{w}_{l}^{\texttt{[T\_SEP]}}\right] \\
\boldsymbol{H}_{l}^{v} &= \left[\boldsymbol{v}_{l}^{\texttt{[I\_CLS]}}, \boldsymbol{v}_{l}^{1}, ..., \boldsymbol{v}_{l}^{N}\right]
\end{aligned}
\tag{1}
$$

- with $l \in \{1, ..., L-F, ..., L\}$
- we define $\boldsymbol{H}_{L}^{w}$ as the final output of the student model for the caption, and $\boldsymbol{H}_{L}^{v}$ as the final output of the student model for the image, with $\boldsymbol{H}_{L}^{w} \in \mathbb{R}^{(M+2)\times D}$ and $\boldsymbol{H}_{L}^{v} \in \mathbb{R}^{(N+1)\times D}$

Image-Text Matching with Feature Fusion