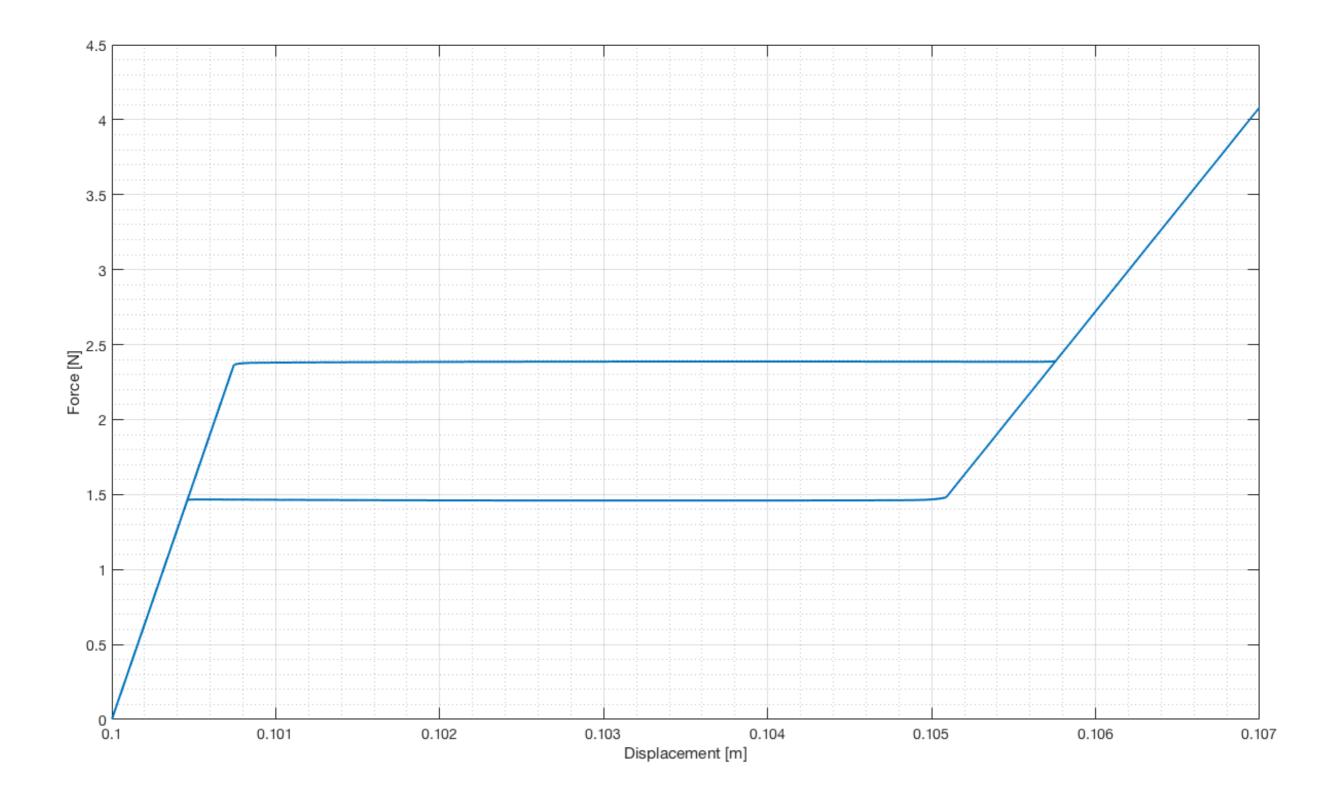
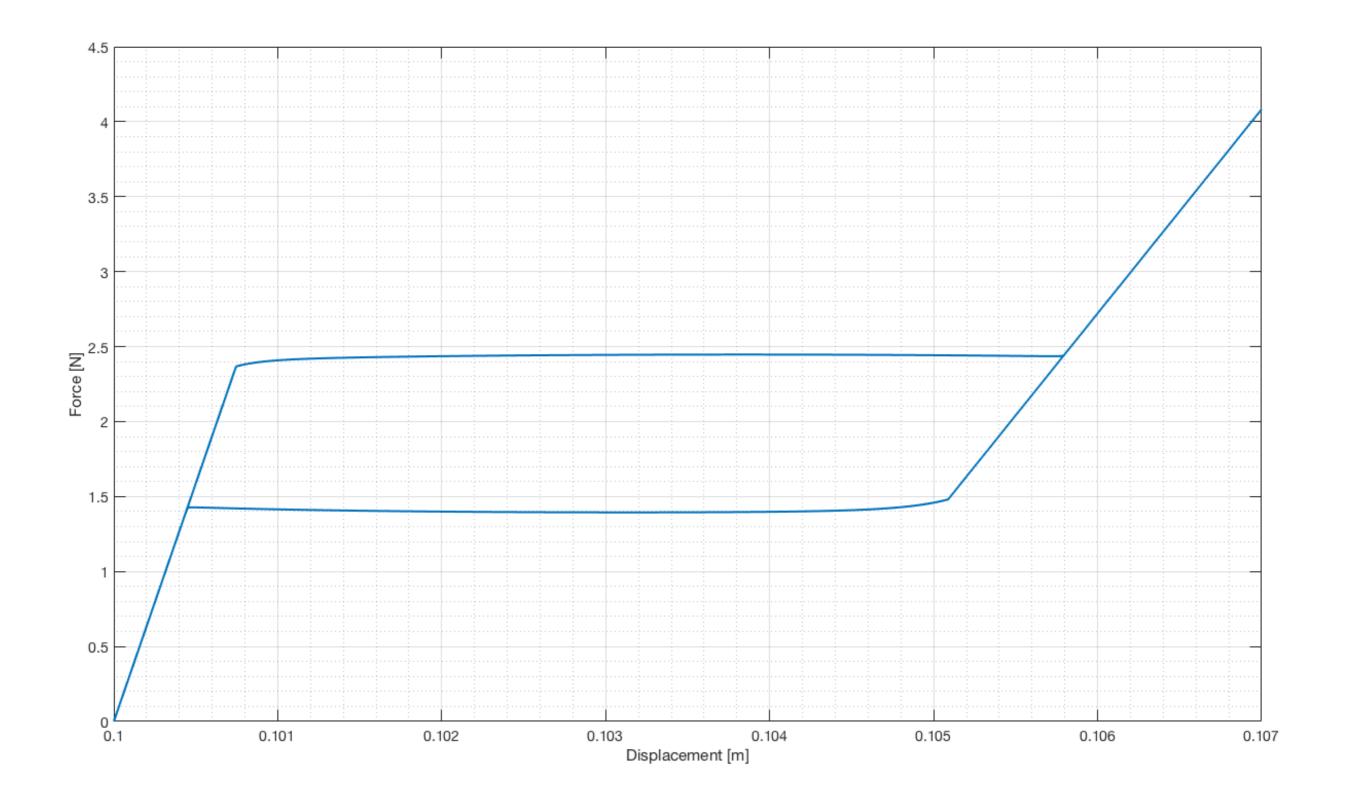
assignment03

Matthias Jost, 2551592 Tim Goll, 2554050

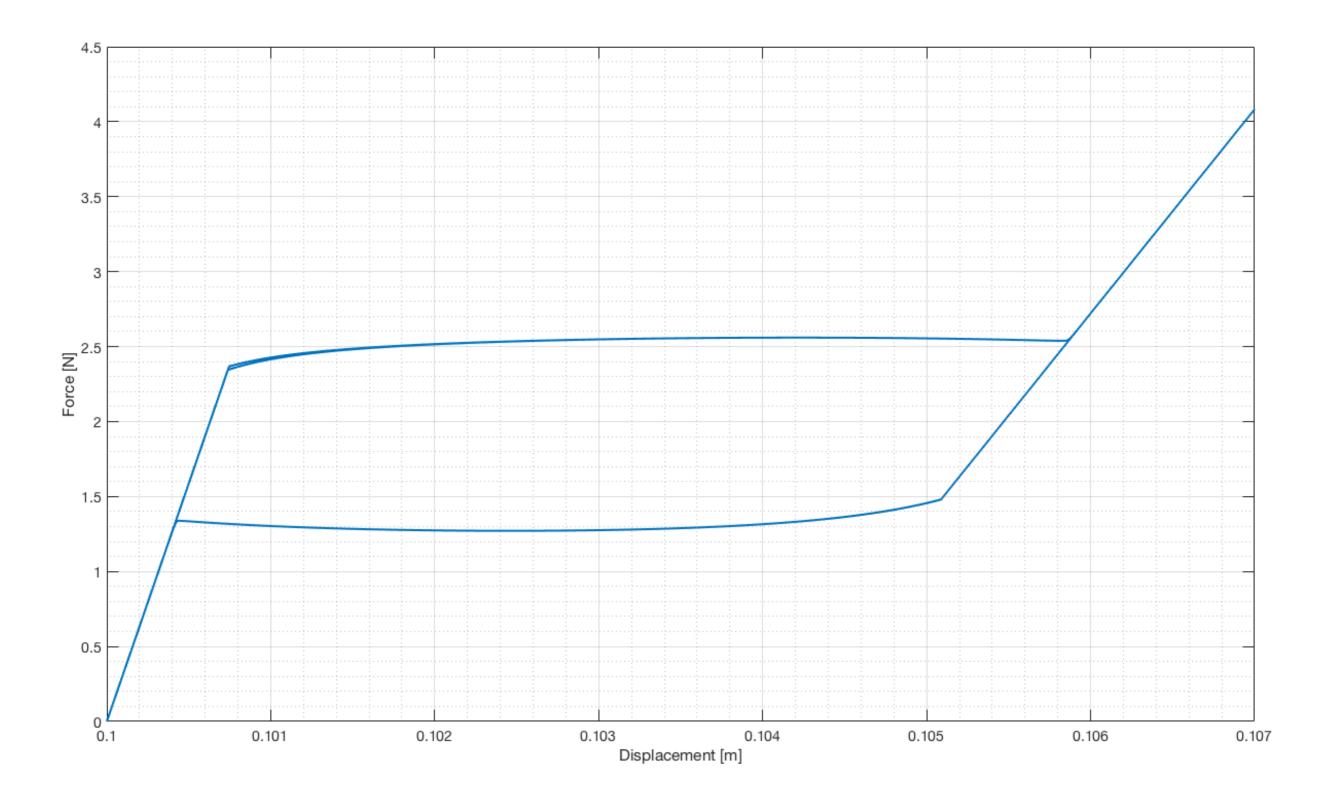
$$f = 0.01 Hz$$



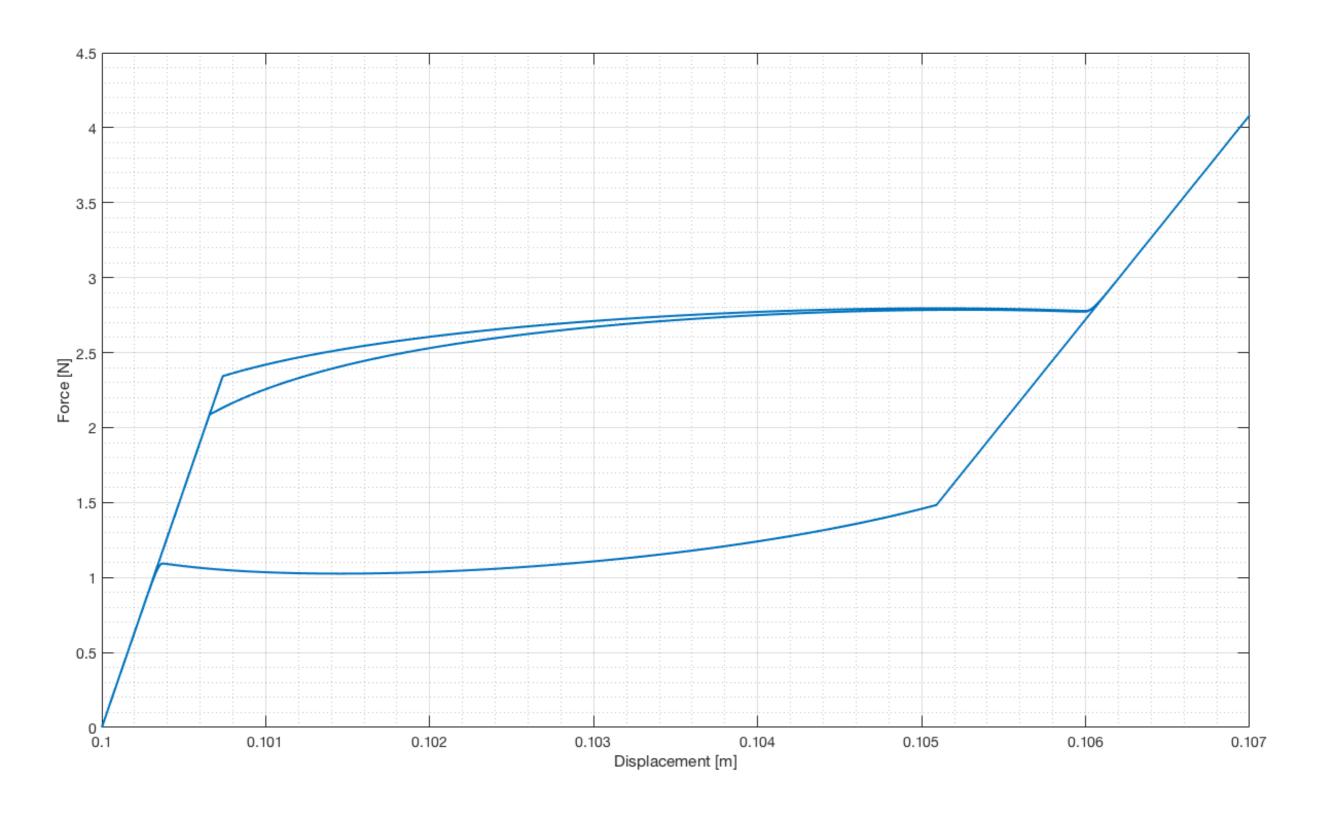
$$f = 0.04 Hz$$



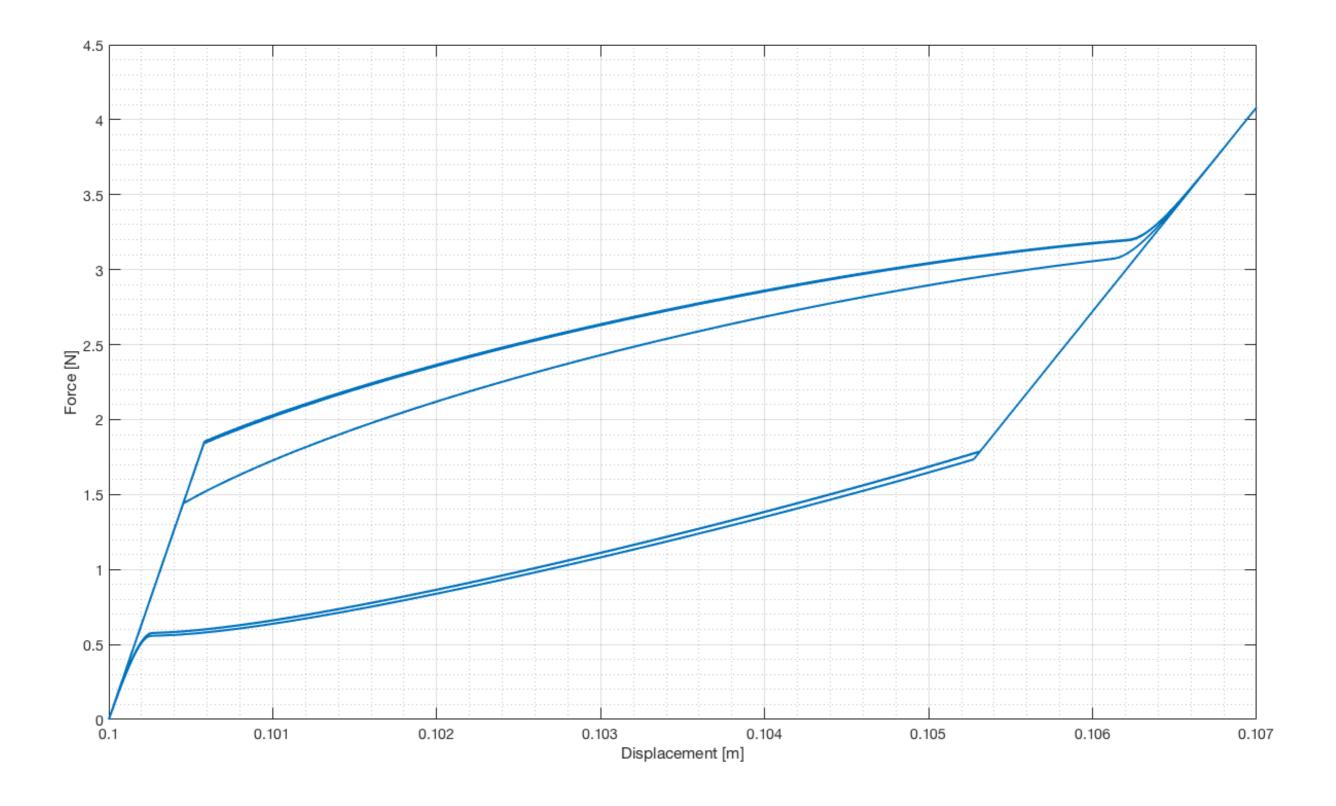
$$f=0.1Hz$$



$$f = 0.25 Hz$$

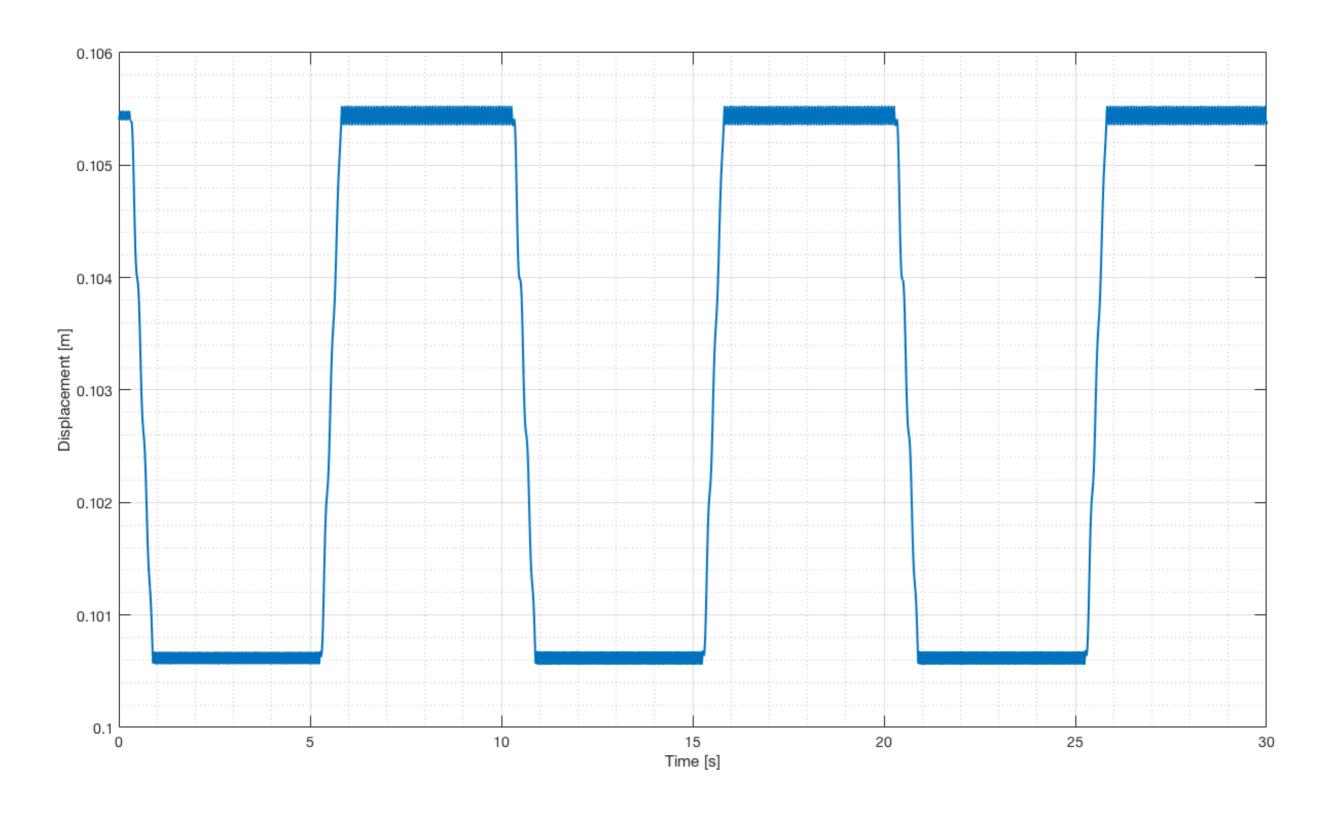


$$f=1Hz$$

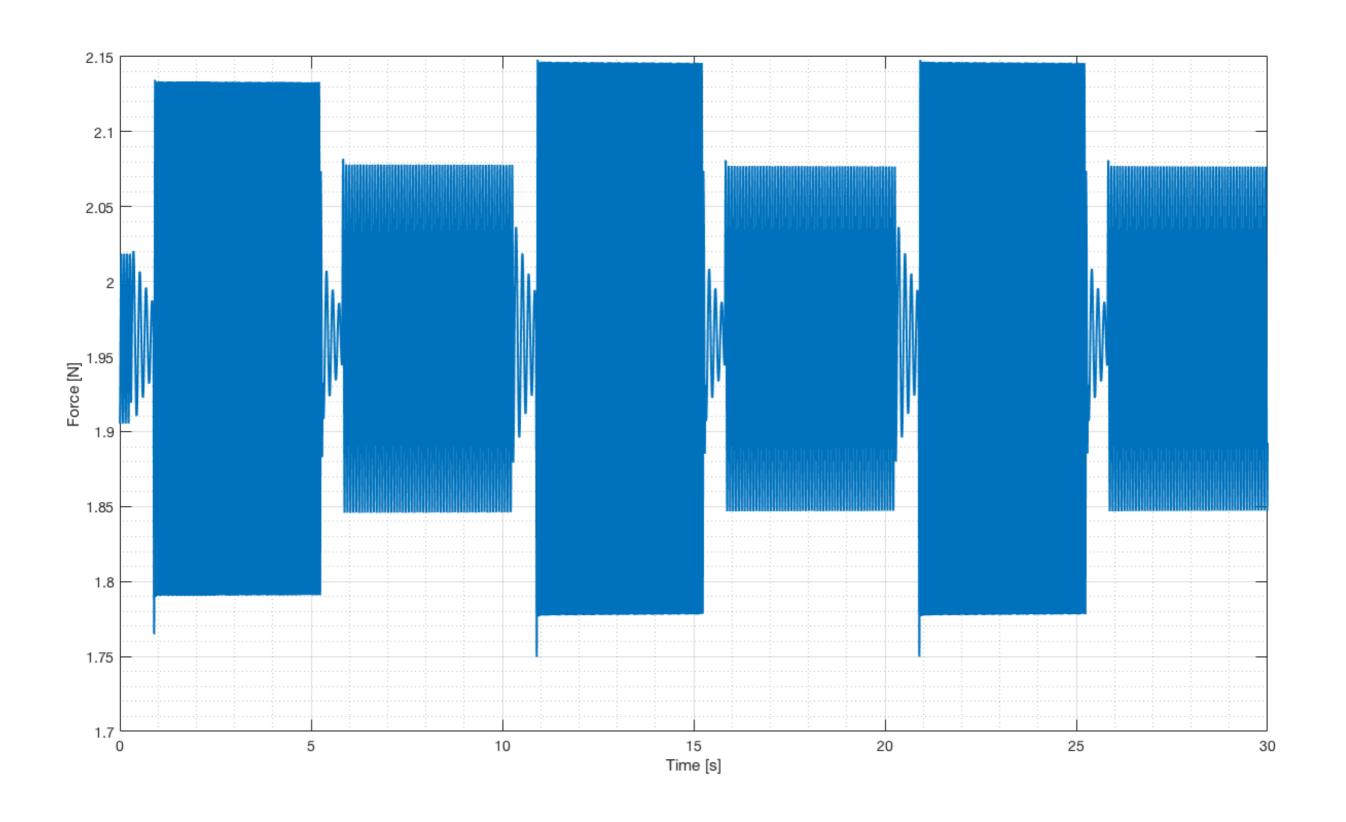


- when the frequency rises, the force displacement curve starts to get smoother
- this is caused by the shortened time for temperature change; therefore the wire gets hotter over time and the phase transformation starts a bit earlier.

2 SMA mass - displacement

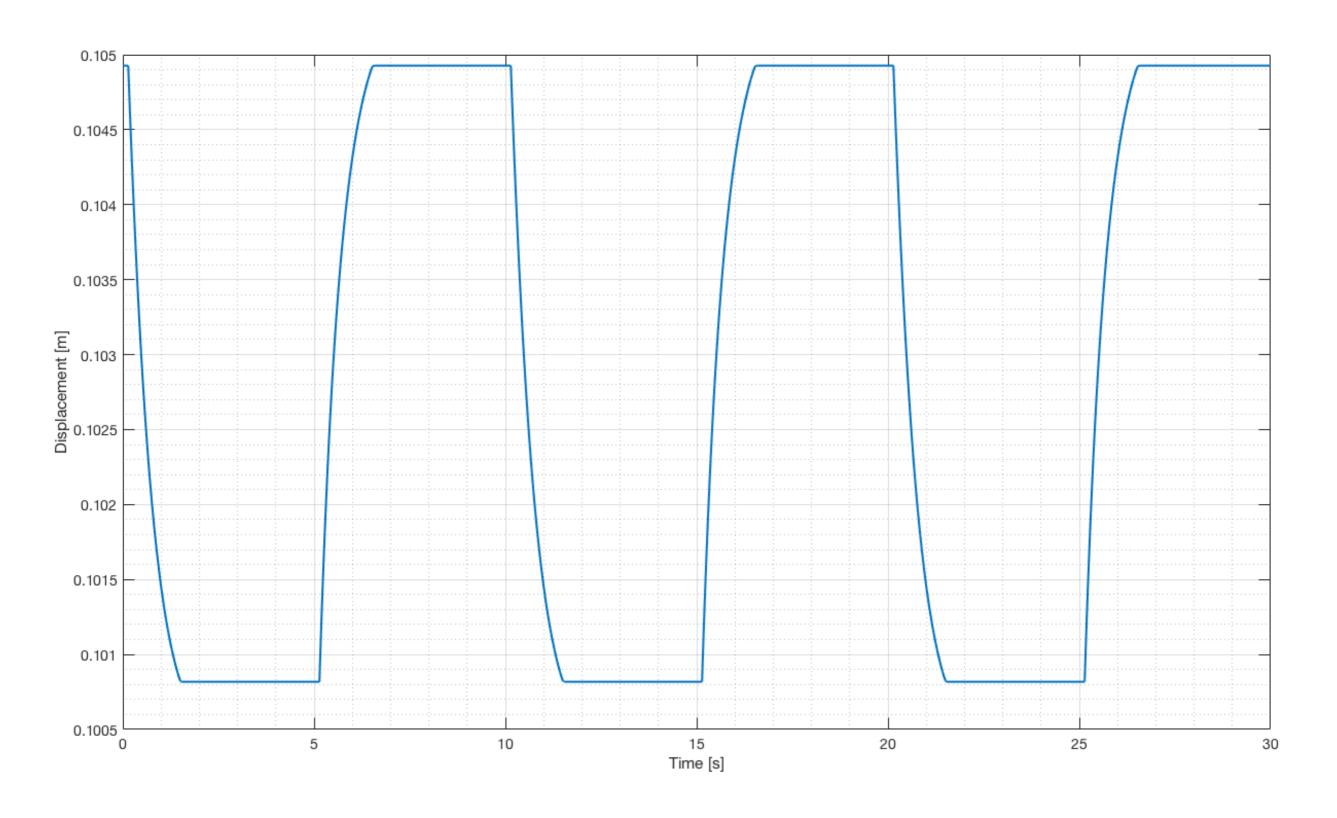


2 SMA mass - force

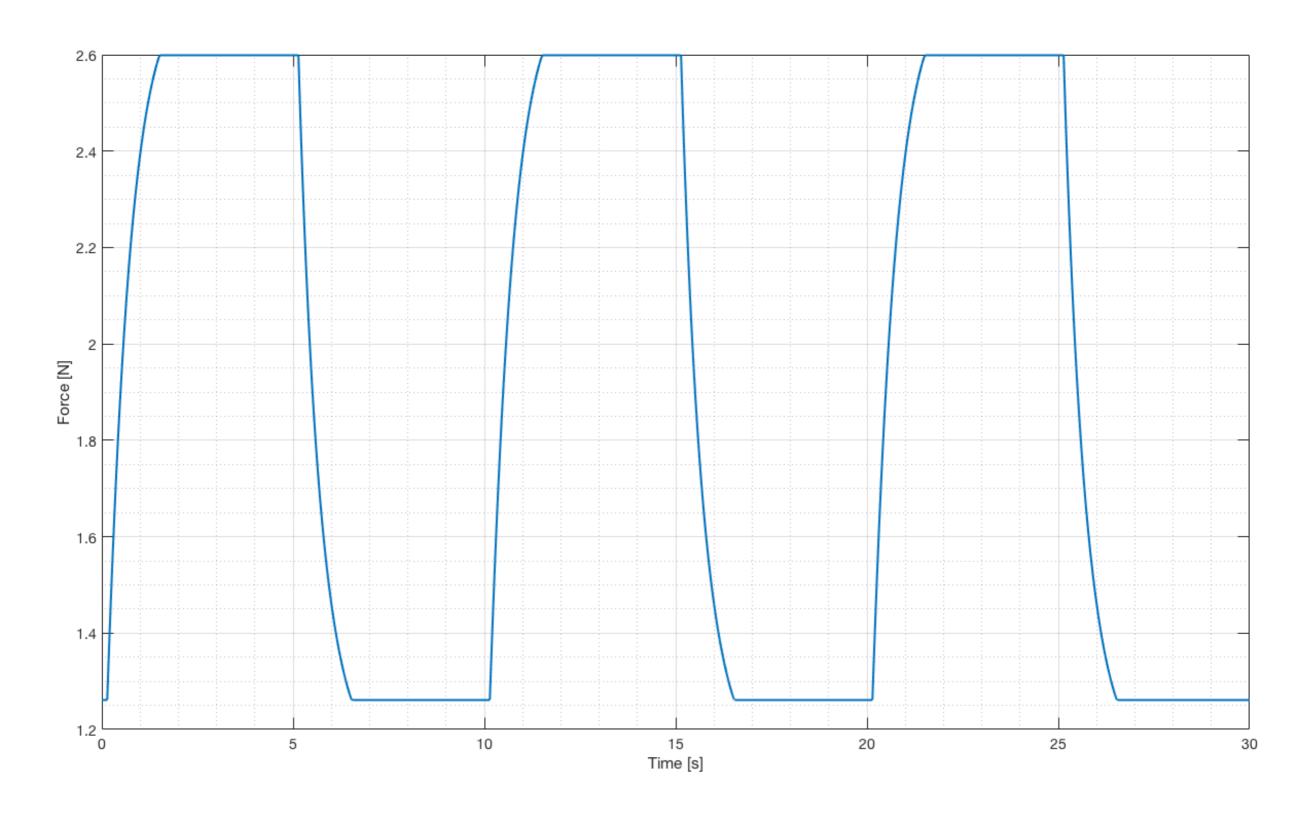


- there is a huge oscillation after each switch caused by the mass
- this is because a mass does not work against oscillations but enables them; at some point the oscillation vanishes because of inertia; in our example the state switches too fast to let the oscillation vanish

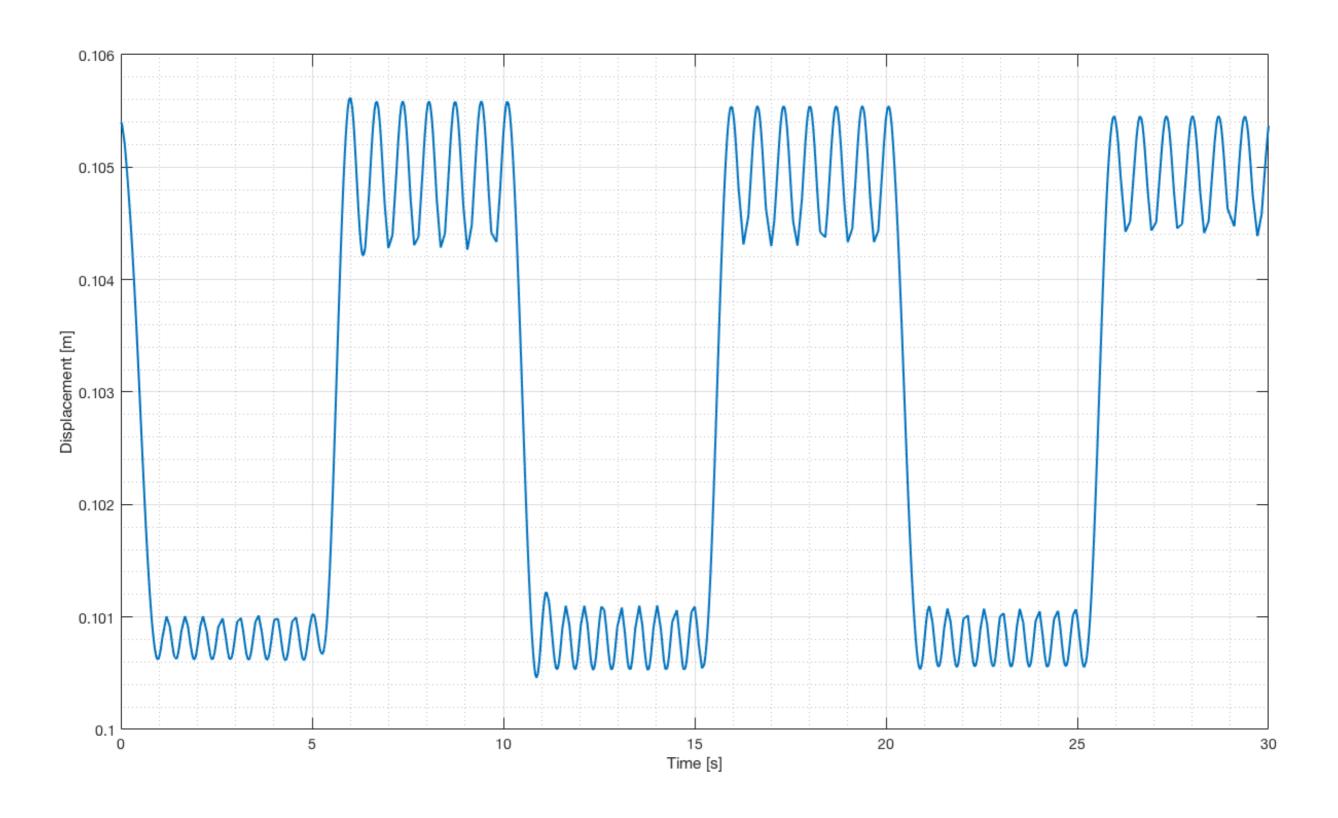
3a SMA spring - displacement



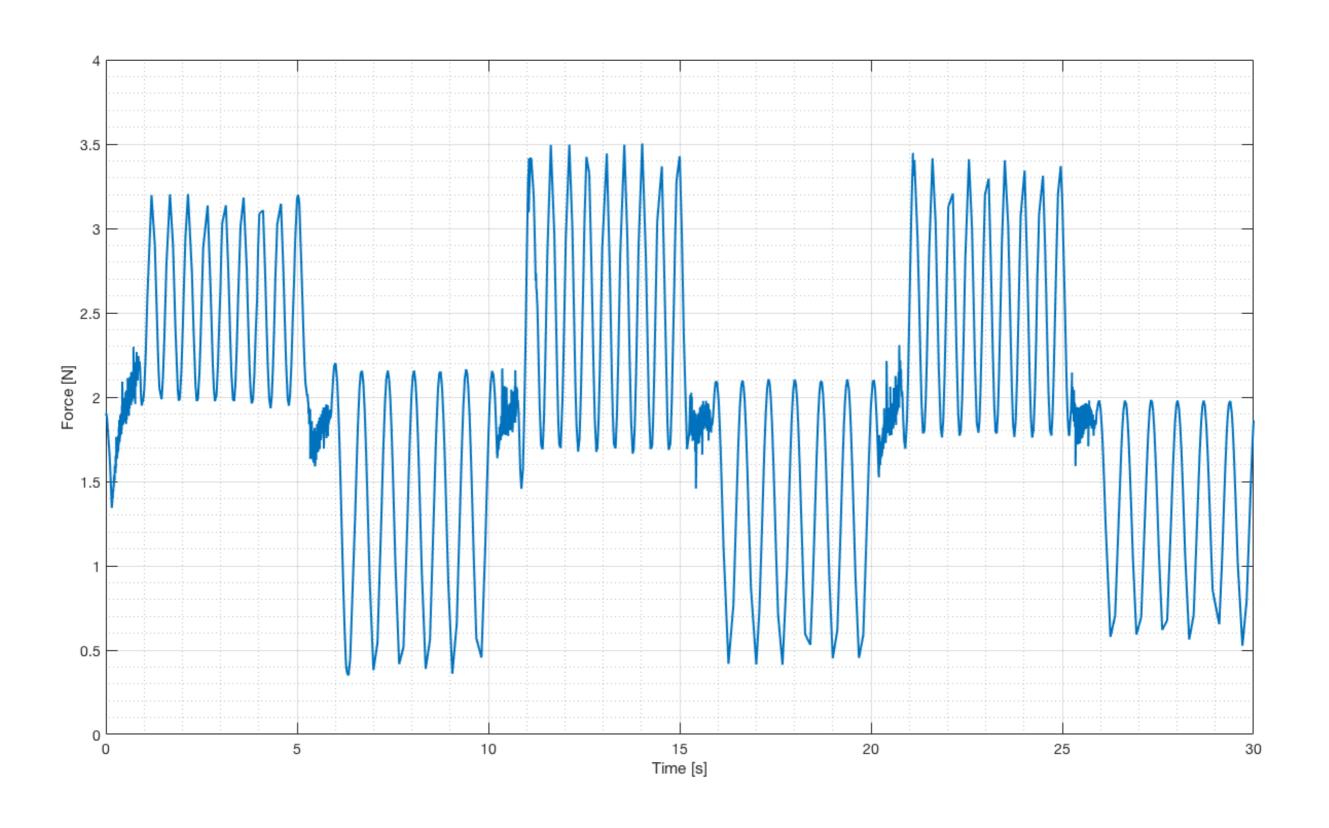
3a SMA spring - force



3b SMA both - displacement

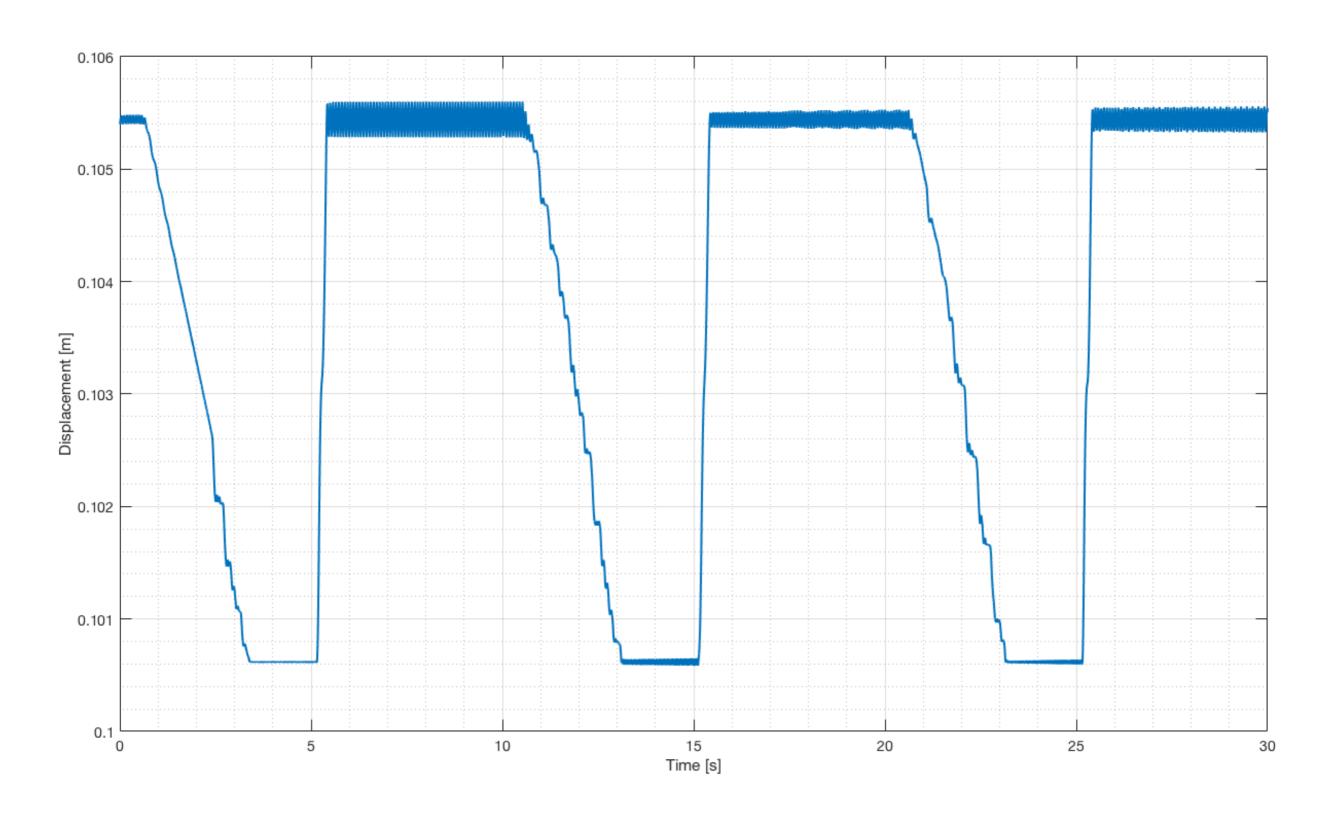


3b SMA both - force

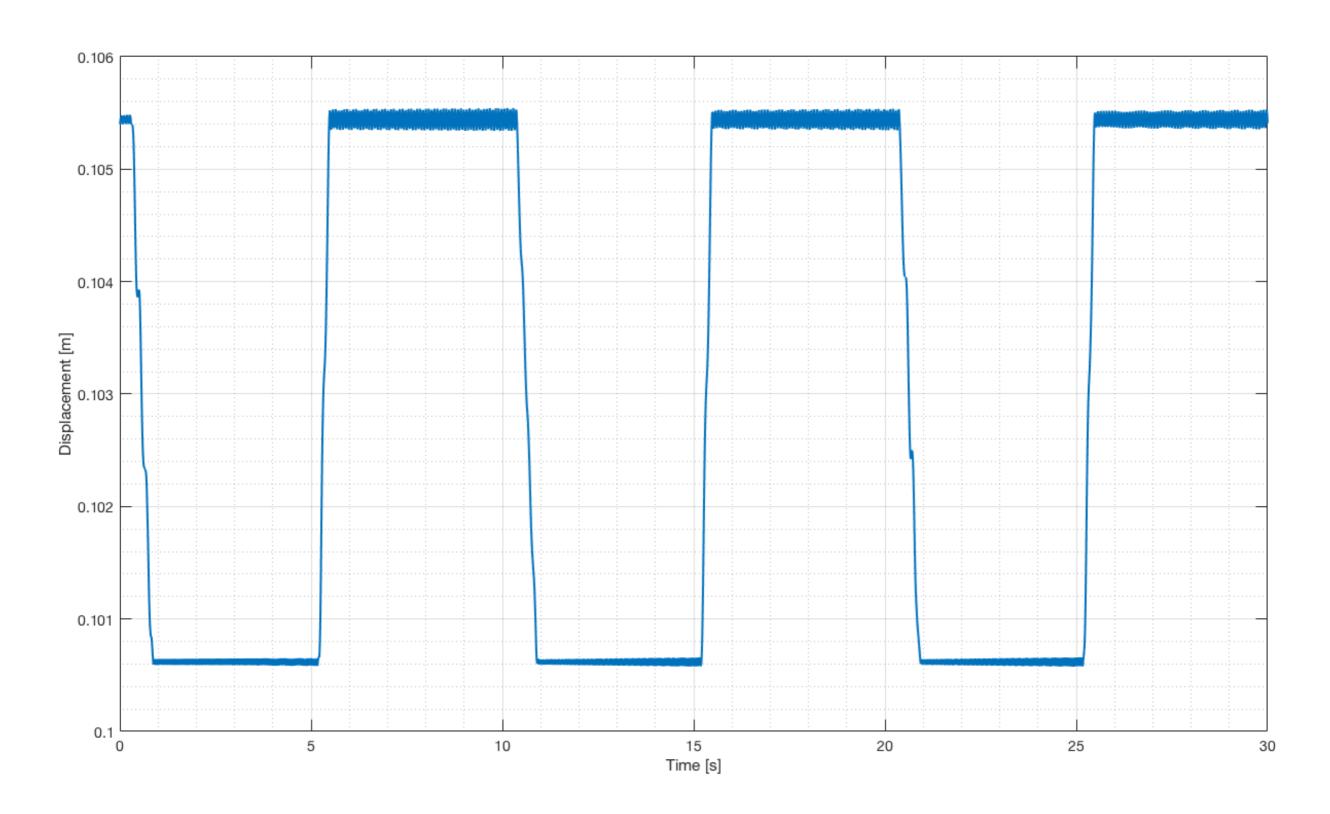


- compared to a mass the spring has a more defined curve (force and displacement) because the spring works against oscillation
- if mass and spring are combined the result represents two oberlayed graphs

4 SMA mass - displacement (0.4W)



4 SMA mass - displacement (0.5W)



 to improve the behavior we have to increase the amplitude to for example 0.5 to compensate for the reduced environment temperature