

# Model specifications

May 11, 2024

# Table of contents

- 1 Overview of models
- 2 General notation
- 3 Model 1
- 4 Model 3
- 5 Model 5
- 6 References

# Overview of models

# Overview of models

The following tables provide an overview of the specified models and their main assumptions, with model extensions/changes highlighted in **bold**. For every model, the observed data are assumed to be complete (i.e., no missing data).

Model	Latent class memberships	Dependent variable	Constant & trend component <sup>1</sup>
1	time-invariant, mixture proportions averaged over individuals	continuous, Normal, independent errors	pooled model, linear
2	time-invariant, mixture proportions averaged over individuals	continuous, Normal, independent errors	pooled model, <b>quadratic</b>
3	time-invariant, mixture proportions averaged over individuals	<b>count, Poisson</b> , independent errors	pooled model, <b>linear</b>
4	time-invariant, mixture proportions averaged over individuals	count, Poisson, independent errors	pooled model, <b>quadratic</b>
5	<b>time-varying via hidden Markov chains with time-invariant and not individual-specific transition matrix</b>	<b>continuous, Normal</b> , independent errors	pooled model, <b>linear</b>
6	time-varying via hidden Markov chains with time-invariant and not individual-specific transition matrix	continuous, Normal, independent errors	pooled model, <b>quadratic</b>

Table 1: Overview of specified models

<sup>1</sup>for each class

# General notation

# General notation

Latent class (aka, mixture component)  $c$ , for  $c = 1, \dots, C$ , where  $C$  is the number of classes

Individual  $n$ , for  $n = 1, \dots, N$ , where  $N$  is the number of individuals

Time period  $t$ , for  $t = 1, \dots, T$ , where  $T$  is the number of time periods

$\mathbf{Y}^{obs}$  is a  $N \times T$  matrix representing an observed dependent variable, where *obs* refers to simulated or actual data

$\mathbf{X}$  is a matrix of size  $N \times T$  representing an explanatory variable

# Model 1

# Model 1 - latent class memberships

Time-invariant (i.e., over time periods, an individual does not switch between classes)

Mixture proportions are averaged over individuals



# Model 1 - dependent variable

Continuous data described by Normal (aka, Gaussian) distributions

Independent (aka, uncorrelated) errors over individuals and time periods

No missing data

## Model 1 - constant and trend component

A pooled model for each class (i.e., the constants and trend components are allowed to vary between classes but not within classes)

Linear (i.e., non-stationary, deterministic) trend components

# Model 1 - likelihood

Based on Stan Development Team (n.d.), the likelihood with marginalized class memberships is given by

$$p(\mathbf{Y}^{obs} | \boldsymbol{\lambda}, \beta_0, \beta_1, \mathbf{X}, \boldsymbol{\sigma}) = \prod_{n=1}^N \sum_{c=1}^C \lambda_c \prod_{t=1}^T \text{Normal}(y_{n,t}^{obs} | \mu_{c,n,t}, \sigma_c), \quad (1)$$

where  $\boldsymbol{\lambda}$  is a row vector of size  $C$  representing the mixture proportions; thus,

$$0 \leq \lambda_c \leq 1 \quad \text{and} \quad \sum_{c=1}^C \lambda_c = 1. \quad (2)$$

## Model 1 - likelihood continued

$\mathbf{M}$  is a  $C$ -tuple containing  $N \times T$  matrices with

$$\mu_{c,n,t} = \beta_{0,c} + \beta_{1,c} x_{n,t}, \quad (3)$$

where  $\beta_0$  is a row vector of size  $C$  representing the constants, and  $\beta_1$  is a row vector of size  $C$  representing the linear trend components.

Furthermore, to solve the identification problem caused by label switching, either

$$\beta_{0,c} < \beta_{0,c+1} \quad (4)$$

or

$$\beta_{1,c} < \beta_{1,c+1} \quad (5)$$

defines a labeling restriction (Koop, 2003). Lastly,  $\sigma$  is a row vector of size  $C$  (i.e., within each class, the errors are identically distributed over individuals and time periods).

## Model 1 - log likelihood

Recall the likelihood presented in equation 1:

$$p(\mathbf{Y}^{obs} | \boldsymbol{\lambda}, \beta_0, \beta_1, \mathbf{X}, \boldsymbol{\sigma}) = \prod_{n=1}^N \sum_{c=1}^C \lambda_c \prod_{t=1}^T \text{Normal}(y_{n,t}^{obs} | \mu_{c,n,t}, \sigma_c). \quad (1)$$

On the log scale, the likelihood is given by

$$\begin{aligned} & \log p(\mathbf{Y}^{obs} | \boldsymbol{\lambda}, \beta_0, \beta_1, \mathbf{X}, \boldsymbol{\sigma}) \\ &= \sum_{n=1}^N \log \sum_{c=1}^C \exp \left( \log \lambda_c + \sum_{t=1}^T \log \text{Normal}(y_{n,t}^{obs} | \mu_{c,n,t}, \sigma_c) \right). \end{aligned} \quad (6)$$

## Model 1 - deduction of likelihood

The latent discrete parameter  $z_n$  in  $\{1, \dots, C\}$  indicates the class membership for individual  $n$ , with

$$z_n \sim \text{Categorical}(\boldsymbol{\lambda}); \quad (7)$$

where  $\mathbf{z}$  is a column vector of size  $N$ . Therefore,

$$Pr(z_n = c) = \lambda_c. \quad (8)$$

## Model 1 - deduction of likelihood continued

Therefore, the likelihood presented in equation 1 is deduced by marginalizing out  $\mathbf{z}$  from the complete data likelihood

$$\begin{aligned} p(\mathbf{Y}^{obs} | \mathbf{z}, \boldsymbol{\lambda}, \beta_0, \beta_1, \mathbf{X}, \boldsymbol{\sigma}) \\ = \prod_{n=1}^N \prod_{c=1}^C \left( \lambda_c \prod_{t=1}^T p(y_{n,t}^{obs} | \mu_{c,n,t}, \sigma_c) \right)^{\mathbf{1}(z_n=c)}, \end{aligned} \quad (9)$$

where  $\mathbf{1}(z_n = c)$  defines an indicator function, so that

$$\begin{aligned} p(\mathbf{Y}^{obs} | \boldsymbol{\lambda}, \beta_0, \beta_1, \mathbf{X}, \boldsymbol{\sigma}) &= \prod_{n=1}^N \sum_{c=1}^C \lambda_c \prod_{t=1}^T p(y_{n,t}^{obs} | \mu_{c,n,t}, \sigma_c) \\ &= \prod_{n=1}^N \sum_{c=1}^C \lambda_c \prod_{t=1}^T \text{Normal}(y_{n,t}^{obs} | \mu_{c,n,t}, \sigma_c). \end{aligned} \quad (10)$$

## Model 1 - prior

$$\boldsymbol{\lambda} \sim \text{Dirichlet}(\boldsymbol{\alpha}_{\lambda}), \quad (11)$$

where  $\boldsymbol{\alpha}_{\lambda}$  is a row vector of size  $C$  representing hyperparameters. Furthermore,  $\alpha_{\lambda,c} = 1$  (i.e.,  $\boldsymbol{\lambda}$  is assigned a proper flat prior).

$$\beta_{0,c} \sim \text{Normal}(\mu_{\beta_{0,c}}, \sigma_{\beta_{0,c}}), \quad (12)$$

where  $\mu_{\beta_{0,c}}$  and  $\sigma_{\beta_{0,c}}$  are hyperparameters.

$$\beta_{1,c} \sim \text{Normal}(\mu_{\beta_{1,c}}, \sigma_{\beta_{1,c}}), \quad (13)$$

where  $\mu_{\beta_{1,c}}$  and  $\sigma_{\beta_{1,c}}$  are hyperparameters.

$$\sigma_c \sim \text{Normal}(0, \sigma_{\sigma_c}) \mathbf{1}(\sigma_c > 0), \quad (14)$$

where 0 and  $\sigma_{\sigma_c}$  are hyperparameters. The Normal distribution is truncated to the left at zero, modeled via the indicator function  $\mathbf{1}(\sigma_c > 0)$ .



## Model 1 - posterior for $z_n$

$$\begin{aligned} & Pr(z_n = c | \mathbf{y}_n^{obs}, \boldsymbol{\lambda}, \beta_0, \beta_1, \mathbf{x}_n, \boldsymbol{\sigma}) \\ &= \frac{\lambda_c \prod_{t=1}^T \text{Normal}(y_{n,t}^{obs} | \mu_{c,n,t}, \sigma_c)}{\sum_{k=1}^C \lambda_k \prod_{t=1}^T \text{Normal}(y_{n,t}^{obs} | \mu_{k,n,t}, \sigma_k)}, \end{aligned} \tag{15}$$

where  $\boldsymbol{\lambda}$ ,  $\beta_0$ ,  $\beta_1$ , and  $\boldsymbol{\sigma}$  are marginalized out over the NUTS sampling iterations.

## Model 1 - log posterior for $z_n$

On the log scale, the posterior for  $z_n$  is given by

$$\begin{aligned} & \log Pr(z_n = c | \mathbf{y}_n^{obs}, \boldsymbol{\lambda}, \beta_0, \beta_1, \mathbf{x}_n, \boldsymbol{\sigma}) \\ &= \log \lambda_c + \sum_{t=1}^T \log \text{Normal}(y_{n,t}^{obs} | \mu_{c,n,t}, \sigma_c) \\ & \quad - \log \sum_{k=1}^C \exp \left( \log \lambda_k + \sum_{t=1}^T \log \text{Normal}(y_{n,t}^{obs} | \mu_{k,n,t}, \sigma_k) \right). \end{aligned} \tag{16}$$

Equation 16 corresponds to the softmax function calculated on the log scale.

# Model 3

## Model 3 - latent class memberships

Time-invariant (i.e., over time periods, an individual does not switch between classes)

Mixture proportions are averaged over individuals

## Model 3 - dependent variable

Count data described by Poisson distributions

Independent (aka, uncorrelated) errors over individuals and time periods

No missing data

## Model 3 - constant and trend component

A pooled model for each class (i.e., the constants and trend components are allowed to vary between classes but not within classes)

Linear (i.e., non-stationary, deterministic) trend components

## Model 3 - likelihood

Based on Stan Development Team (n.d.), the likelihood with marginalized class memberships is given by

$$p(\mathbf{Y}^{obs} | \boldsymbol{\lambda}, \beta_0, \beta_1, \mathbf{X}) = \prod_{n=1}^N \sum_{c=1}^C \lambda_c \prod_{t=1}^T \text{PoissonLog}(y_{n,t}^{obs} | \theta_{c,n,t}), \quad (17)$$

where  $\boldsymbol{\lambda}$  is a row vector of size  $C$  representing the mixture proportions; thus,

$$0 \leq \lambda_c \leq 1 \quad \text{and} \quad \sum_{c=1}^C \lambda_c = 1. \quad (18)$$

## Model 3 - likelihood continued

$\Theta$  is a  $C$ -tuple containing  $N \times T$  matrices.  $\theta_{c,n,t}$  represents both the expected value and the variance, with

$$\theta_{c,n,t} = \beta_{0,c} + \beta_{1,c} x_{n,t}; \quad (19)$$

where  $\beta_0$  is a row vector of size  $C$  representing the constants, and  $\beta_1$  is a row vector of size  $C$  representing the linear trend components.

Furthermore, to solve the identification problem caused by label switching, either

$$\beta_{0,c} < \beta_{0,c+1} \quad (20)$$

or

$$\beta_{1,c} < \beta_{1,c+1} \quad (21)$$

defines a labeling restriction (Koop, 2003).



## Model 3 - log likelihood

Recall the likelihood presented in equation 17:

$$p(\mathbf{Y}^{obs} | \boldsymbol{\lambda}, \beta_0, \beta_1, \mathbf{X}) = \prod_{n=1}^N \sum_{c=1}^C \lambda_c \prod_{t=1}^T \text{PoissonLog}(y_{n,t}^{obs} | \theta_{c,n,t}). \quad (17)$$

On the log scale, the likelihood is given by

$$\begin{aligned} & \log p(\mathbf{Y}^{obs} | \boldsymbol{\lambda}, \beta_0, \beta_1, \mathbf{X}) \\ &= \sum_{n=1}^N \log \sum_{c=1}^C \exp \left( \log \lambda_c + \sum_{t=1}^T \log \text{PoissonLog}(y_{n,t}^{obs} | \theta_{c,n,t}) \right). \end{aligned} \quad (22)$$

## Model 3 - deduction of likelihood

The latent discrete parameter  $z_n$  in  $\{1, \dots, C\}$  indicates the class membership for individual  $n$ , with

$$z_n \sim \text{Categorical}(\boldsymbol{\lambda}); \quad (23)$$

where  $\mathbf{z}$  is a column vector of size  $N$ . Therefore,

$$\Pr(z_n = c) = \lambda_c. \quad (24)$$

## Model 3 - deduction of likelihood continued

Therefore, the likelihood presented in equation 17 is deduced by marginalizing out  $\mathbf{z}$  from the complete data likelihood

$$p(\mathbf{Y}^{obs}|\mathbf{z}, \boldsymbol{\lambda}, \boldsymbol{\beta}_0, \boldsymbol{\beta}_1, \mathbf{X}) = \prod_{n=1}^N \prod_{c=1}^C \left( \lambda_c \prod_{t=1}^T p(y_{n,t}^{obs}|\theta_{c,n,t}) \right)^{\mathbf{1}(z_n=c)}, \quad (25)$$

where  $\mathbf{1}(z_n = c)$  defines an indicator function, so that

$$\begin{aligned} p(\mathbf{Y}^{obs}|\boldsymbol{\lambda}, \boldsymbol{\beta}_0, \boldsymbol{\beta}_1, \mathbf{X}) &= \prod_{n=1}^N \sum_{c=1}^C \lambda_c \prod_{t=1}^T p(y_{n,t}^{obs}|\theta_{c,n,t}) \\ &= \prod_{n=1}^N \sum_{c=1}^C \lambda_c \prod_{t=1}^T \text{PoissonLog}(y_{n,t}^{obs}|\theta_{c,n,t}). \end{aligned} \quad (26)$$

## Model 3 - prior

$$\boldsymbol{\lambda} \sim \text{Dirichlet}(\boldsymbol{\alpha}_{\lambda}), \quad (27)$$

where  $\boldsymbol{\alpha}_{\lambda}$  is a row vector of size  $C$  representing hyperparameters. Furthermore,  $\alpha_{\lambda,c} = 1$  (i.e.,  $\boldsymbol{\lambda}$  is assigned a proper flat prior).

$$\beta_{0,c} \sim \text{Normal}(\mu_{\beta_{0,c}}, \sigma_{\beta_{0,c}}), \quad (28)$$

where  $\mu_{\beta_{0,c}}$  and  $\sigma_{\beta_{0,c}}$  are hyperparameters.

$$\beta_{1,c} \sim \text{Normal}(\mu_{\beta_{1,c}}, \sigma_{\beta_{1,c}}), \quad (29)$$

where  $\mu_{\beta_{1,c}}$  and  $\sigma_{\beta_{1,c}}$  are hyperparameters.

## Model 3 - posterior for $z_n$

$$Pr(z_n = c | \mathbf{y}_n^{obs}, \boldsymbol{\lambda}, \beta_0, \beta_1, \mathbf{x}_n) = \frac{\lambda_c \prod_{t=1}^T \text{PoissonLog}(y_{n,t}^{obs} | \theta_{c,n,t})}{\sum_{k=1}^C \lambda_k \prod_{t=1}^T \text{PoissonLog}(y_{n,t}^{obs} | \theta_{k,n,t})}, \quad (30)$$

where  $\boldsymbol{\lambda}$ ,  $\beta_0$ , and  $\beta_1$  are marginalized out over the NUTS sampling iterations.

## Model 3 - log posterior for $z_n$

On the log scale, the posterior for  $z_n$  is given by

$$\begin{aligned} & \log Pr(z_n = c | \mathbf{y}_n^{obs}, \boldsymbol{\lambda}, \beta_0, \beta_1, \mathbf{x}_n) \\ &= \log \lambda_c + \sum_{t=1}^T \log \text{PoissonLog}(y_{n,t}^{obs} | \theta_{c,n,t}) \\ & \quad - \log \sum_{k=1}^C \exp \left( \log \lambda_k + \sum_{t=1}^T \log \text{PoissonLog}(y_{n,t}^{obs} | \theta_{k,n,t}) \right). \end{aligned} \tag{31}$$

Equation 31 corresponds to the softmax function calculated on the log scale.

# Model 5

## Model 5 - latent class memberships

Time-varying (i.e., over time periods, an individual might switch between classes)

Modeled via hidden Markov chains with time-invariant transition matrix, where the transition matrix is not individual-specific (i.e., the transition probabilities are averaged over individuals)



## Model 5 - dependent variable

Continuous data described by Normal (aka, Gaussian) distributions

Independent (aka, uncorrelated) errors over individuals and time periods

No missing data

## Model 5 - constant and trend component

A pooled model for each class (i.e., the constants and trend components are allowed to vary between classes but not within classes)

Linear (i.e., non-stationary, deterministic) trend components

## Model 5 - likelihood

Based on Stan Development Team (n.d.), the likelihood with marginalized class memberships is given by

$$\begin{aligned} & p(\mathbf{Y}^{obs} | \boldsymbol{\omega}, \boldsymbol{\Psi}, \boldsymbol{\beta}_0, \boldsymbol{\beta}_1, \mathbf{X}, \boldsymbol{\sigma}) \\ &= \prod_{n=1}^N \prod_{t=1}^T \sum_{c=1}^C \lambda_{t,c} \text{Normal}(y_{n,t}^{obs} | \mu_{c,n,t}, \sigma_c). \end{aligned} \tag{32}$$

## Model 5 - likelihood continued

$\mathbf{\Lambda}$  is a  $T \times C$  matrix representing the mixture proportions, averaged over individuals; thus,

$$0 \leq \lambda_{t,c} \leq 1 \quad \text{and} \quad \sum_{c=1}^C \lambda_{t,c} = 1. \quad (33)$$

Furthermore,

$$\lambda_{t,c} = \begin{cases} \omega_c & \text{for } t = 1 \\ \sum_{k=1}^C \lambda_{t-1,k} \psi_{k,c} & \text{for } t > 1, \end{cases} \quad (34)$$

where  $\omega$  is a row vector of size  $C$  representing the initial mixture proportions, and  $\Psi$  is a  $C \times C$  transition matrix (e.g.,  $\psi_{1,2}$  represents the probability for an individual to switch from the first to the second class).

## Model 5 - likelihood continued

$\mathbf{M}$  is a  $C$ -tuple containing  $N \times T$  matrices with

$$\mu_{c,n,t} = \beta_{0,c} + \beta_{1,c} x_{n,t}, \quad (35)$$

where  $\beta_0$  is a row vector of size  $C$  representing the constants, and  $\beta_1$  is a row vector of size  $C$  representing the linear trend components.

Furthermore, to solve the identification problem caused by label switching, either

$$\beta_{0,c} < \beta_{0,c+1} \quad (36)$$

or

$$\beta_{1,c} < \beta_{1,c+1} \quad (37)$$

defines a labeling restriction (Koop, 2003). Lastly,  $\sigma$  is a row vector of size  $C$  (i.e., within each class, the errors are identically distributed over individuals and time periods).

## Model 5 - log likelihood

Recall the likelihood presented in equation 32:

$$\begin{aligned} p(\mathbf{Y}^{obs} | \boldsymbol{\omega}, \boldsymbol{\Psi}, \beta_0, \beta_1, \mathbf{X}, \boldsymbol{\sigma}) \\ = \prod_{n=1}^N \prod_{t=1}^T \sum_{c=1}^C \lambda_{t,c} \text{Normal}(y_{n,t}^{obs} | \mu_{c,n,t}, \sigma_c). \end{aligned} \quad (32)$$

On the log scale, the likelihood is given by

$$\begin{aligned} \log p(\mathbf{Y}^{obs} | \boldsymbol{\omega}, \boldsymbol{\Psi}, \beta_0, \beta_1, \mathbf{X}, \boldsymbol{\sigma}) \\ = \sum_{n=1}^N \sum_{t=1}^T \log \sum_{c=1}^C \exp \left( \log \lambda_{t,c} + \log \text{Normal}(y_{n,t}^{obs} | \mu_{c,n,t}, \sigma_c) \right). \end{aligned} \quad (38)$$

## Model 5 - deduction of likelihood

The latent discrete parameter  $z_{n,t}$  in  $\{1, \dots, C\}$  indicates the class membership for individual  $n$  at time period  $t$ , with

$$z_{n,t} \sim \begin{cases} \text{Categorical}(\omega) & \text{for } t = 1 \\ \text{Categorical}(\psi_{z_{n,t-1}}) & \text{for } t > 1, \end{cases} \quad (39)$$

where  $\mathbf{Z}$  is a  $N \times T$  matrix, and  $\psi_{z_{n,t-1}}$  is a row vector of  $\Psi$ . Therefore, the likelihood presented in equation 32 is deduced by marginalizing out  $\mathbf{Z}$  from the complete data likelihood

$$\begin{aligned} & p(\mathbf{Y}^{obs} | \mathbf{Z}, \omega, \Psi, \beta_0, \beta_1, \mathbf{X}, \sigma) \\ &= \prod_{n=1}^N \left( \prod_{t=1}^T \prod_{c=1}^C \left( \omega_c p(y_{n,t}^{obs} | \mu_{c,n,t}, \sigma_c) \right)^{\mathbf{1}(z_{n,t}=c)} \right) \\ & \quad \prod_{t=2}^T \prod_{c=1}^C \left( \psi_{z_{n,t-1},c} p(y_{n,t}^{obs} | \mu_{c,n,t}, \sigma_c) \right)^{\mathbf{1}(z_{n,t}=c)}, \end{aligned} \quad (40)$$

where  $\mathbf{1}(z_n = c)$  defines an indicator function,

## Model 5 - deduction of likelihood continued

so that

$$\begin{aligned} & p(\mathbf{Y}^{obs} | \boldsymbol{\omega}, \boldsymbol{\Psi}, \boldsymbol{\beta}_0, \boldsymbol{\beta}_1, \mathbf{X}, \boldsymbol{\sigma}) \\ &= \prod_{n=1}^N \prod_{t=1}^T \sum_{c=1}^C \lambda_{t,c} p(y_{n,t}^{obs} | \mu_{c,n,t}, \sigma_c) \\ &= \prod_{n=1}^N \prod_{t=1}^T \sum_{c=1}^C \lambda_{t,c} \text{Normal}(y_{n,t}^{obs} | \mu_{c,n,t}, \sigma_c); \end{aligned} \tag{41}$$

where, as already defined in equation 34,

$$\lambda_{t,c} = \begin{cases} \omega_c & \text{for } t = 1 \\ \sum_{k=1}^C \lambda_{t-1,k} \psi_{k,c} & \text{for } t > 1. \end{cases} \tag{34}$$



## Model 5 - prior

$$\omega \sim \text{Dirichlet}(\alpha_\omega), \quad (42)$$

where  $\alpha_\omega$  is a row vector of size  $C$  representing hyperparameters. Furthermore,  $\alpha_{\omega,c} = 1$  (i.e.,  $\omega$  is assigned a proper flat prior).

$$\psi_c \sim \text{Dirichlet}(\alpha_{\psi_c}), \quad (43)$$

where  $\psi_c$  is a row vector of  $\Psi$ , and  $\alpha_{\psi_c}$  is a row vector of the  $C \times C$  matrix  $\mathbf{A}_\Psi$  representing hyperparameters.

$$\beta_{0,c} \sim \text{Normal}(\mu_{\beta_{0,c}}, \sigma_{\beta_{0,c}}), \quad (44)$$

where  $\mu_{\beta_{0,c}}$  and  $\sigma_{\beta_{0,c}}$  are hyperparameters.

$$\beta_{1,c} \sim \text{Normal}(\mu_{\beta_{1,c}}, \sigma_{\beta_{1,c}}), \quad (45)$$

where  $\mu_{\beta_{1,c}}$  and  $\sigma_{\beta_{1,c}}$  are hyperparameters.

## Model 5 - prior continued

$$\sigma_c \sim \text{Normal}(0, \sigma_{\sigma_c}) \mathbf{1}(\sigma_c > 0), \quad (46)$$

where 0 and  $\sigma_{\sigma_c}$  are hyperparameters. The Normal distribution is truncated to the left at zero, modeled via the indicator function  $\mathbf{1}(\sigma_c > 0)$ .

## Model 5 - posterior for $z_{n,t}$

$$\begin{aligned} & Pr(z_{n,t} = c | y_{n,t}^{obs}, \omega, \Psi, \beta_0, \beta_1, x_{n,t}, \sigma) \\ &= \frac{\lambda_{t,c} \text{Normal}(y_{n,t}^{obs} | \mu_{c,n,t}, \sigma_c)}{\sum_{k=1}^C \lambda_{t,k} \text{Normal}(y_{n,t}^{obs} | \mu_{k,n,t}, \sigma_k)}, \end{aligned} \tag{47}$$

where  $\omega$ ,  $\Psi$ ,  $\beta_0$ ,  $\beta_1$ , and  $\sigma$  are marginalized out over the NUTS sampling iterations.

## Model 5 - log posterior for $z_{n,t}$

On the log scale, the posterior for  $z_{n,t}$  is given by

$$\begin{aligned} &Pr(z_{n,t} = c | y_{n,t}^{obs}, \boldsymbol{\omega}, \boldsymbol{\Psi}, \beta_0, \beta_1, x_{n,t}, \boldsymbol{\sigma}) \\ &= \log \lambda_{t,c} + \log \text{Normal}(y_{n,t}^{obs} | \mu_{c,n,t}, \sigma_c) \\ &\quad - \log \sum_{k=1}^C \exp \left( \log \lambda_{t,k} + \log \text{Normal}(y_{n,t}^{obs} | \mu_{k,n,t}, \sigma_k) \right). \end{aligned} \tag{48}$$

Equation 48 corresponds to the softmax function calculated on the log scale.

# References

# References

Koop, G. (2003). *Bayesian Econometrics*. Wiley.

Stan Development Team. (n.d.). *Stan Documentation, Version 2.34*.

Stan. <https://mc-stan.org/docs/>