

Supervised

1. Decision Stump
Total Run Time: $O(ndk)$ (k thresholds for each of d features)
PSEUDO CODE HERE with $O(n)$ on steps
2. Decision Tree
PSEUDO CODE HERE with $O(n)$ on steps
3. Naive Bayes
Bayes Rule: $p(y_i|x_i) = \frac{p(x_i|y_i) \cdot p(y_i)}{p(x_i)}$
PSEUDO CODE HERE with $O(n)$ on steps
4. KNN
 - Non-Parametric
 - fit cost: store $O(nd)$
 - Prediction Cost: $O(nd)$
 - depends on norm
 - Usage:
PSEUDO CODE HERE with $O(n)$ on steps
5. Linear Regression
6. Non-linear Regression (Supervised)

Unsupervised

1. K-Means (Unsupervised)
 - Parametric (k, W weights)
 - fit cost: store $O(ndk)$
 - update: $O(nd)$
 - Prediction Cost: $O(nd)$
 - depends on initialization
 - Usage: convex clustering, vector quantization, Outlier Detection
PSEUDO CODE HERE with $O(n)$ on steps
2. DBSCAN (Unsupervised)
 - Non-Parametric (ϵ , MinNbr)
 - fit cost: store $O()$
 - update: $O()$
 - Prediction Cost: $O()$
 - problem: different densities
3. Outlier Detection Methods
 - Model-based methods
 - Graphical approaches (scatter plot)
 - Cluster-based methods (k-means DBSCAN)
 - Distance-based methods (KNN)
 - Supervised-learning methods
4. Recommender?

Something

1. Golden Rule:
Test data must not influence int the training phase in any way.
2. Fundamental Trade Off:
 $E_{test} = (E_{test} - E_{train}) + E_{train}$
 E_{appx} gets smaller as n larger, grows as model gets complicated
3. Ensemble Methods
4. Cross-Validation
k-fold CV runtime: $O()$
PSEUDO CODE HERE with $O(n)$ on steps
5. Definitions
6. Linear Algebra Notes
Basics
 - $w^T x_i = \sum_{j=1}^d w_j x_{ij}$, x_i, w is $d \times 1$
 - $a^T Ab = b^T B^T a$ both sides are vectors
 - $\frac{1}{2} \|Xw - y\|_2^2 = \frac{1}{2} \sum_{i=1}^n (w^T x_i - y_i) = \frac{1}{2} w^T X^T X w - w^T X^T y + \frac{1}{2} y^T y$
 - $\nabla \text{const} = 0, \nabla w^T b = w, \nabla \frac{1}{2} w^T A w = A w$ if A symmetric
 - $\nabla \frac{1}{2} \|Xw - y\|_2^2 = X^T X w - X^T y$
 - Normal equation $X^T X w = X^T y$
 - $(Xw - y)^T V (Xw - y) = \sum_{i=1}^n v_i (w^T x_i - y_i)^2$Run Time
 - $X^T y : O(nd)$
 - $X^T X : O(nd^2)$
 - solve $d \times d$ system of equations : $O(d^3)$
 - solve normal equation : $O(d^3 + nd^2)$Gradient Descent
 - $w^{t+1} = w^t - \alpha^t \nabla f(w^t) = w^t - X^T (Xw^t - y)$ (least square)
 - cost $O(nd)$ no need to form $X^T X$
 - total cost $O(ndt)$
 - faster for large d, works generally
7. Multivariable Calc Notes
8. Probability Notes