

Redwood City, California
(573)-466-2633
tim.samuelson@gmail.com

Tim Samuelson

timsamuelsen.com
linkedin.com/in/timsamuelsen

EXPERIENCE

Staff Software Engineer, Platform

Carbon, Inc.

Apr 2025 — Present

Redwood City, CA

- Developing A/B system updates for Carbon's global device fleet. Enabling robust, rollback-safe software updates to reduce downtime and accelerate feature rollout.

Senior Software Engineer, Platform

Carbon, Inc.

Apr 2023 — Apr 2025

Redwood City, CA

- Software lead for AO Backpack, Carbon's flagship automation product for additive manufacturing. Drove software design and integration, enabling high-throughput, lights-out 3D printing workflows adopted by major production partners.
- Led the redesign of Carbon's bringup process for device setup, enabling global manufacturing and on-site device servicing. Resulted in \$500,000 savings and reduced escalations by 95%. Developed in Python with supporting Shell scripts, React/TypeScript for UI, and Ruby for integration with our fleet management system.

Software Engineer, Platform

Carbon, Inc.

Apr 2022 — Apr 2023

Redwood City, CA

- Developed internal research tools to enable cross-functional teams across multiple organizations to rapidly explore new improvements to Carbon's 3D printing technology.

Graduate Research Assistant

Stanford University

DeSimone Research Group, Advanced Printer Concepts Team

Stanford, CA

clip3dgui.readthedocs.io

- Software and embedded systems developer for 3 separate in-house advanced CLIP 3D printers. Implementing advanced and novel 3D printing techniques using C++ with the Qt framework for GUI implementation. The platform is currently being used to conduct research on high-resolution and high-speed 3D printing, development of biodegradable materials, 3D printed microparticles, and microneedles for vaccine deployment.

EDUCATION

Master of Science, Mechanical Engineering, Stanford University

Mechatronics Depth Area, GPA: 4.00

Sep 2020 — Mar 2022

Relevant Coursework: Smart Product Design Fundamentals/Applications/Practice (ME218A/B/C), Engineering Design Optimization, Principles of Robot Autonomy, Collaborative Robotics, Nano and Micro Electromechanical Systems

Bachelor of Science, Mechanical Engineering, Missouri University of Science & Technology

Mechanical Design & Analysis Emphasis, Graduated *magna cum laude*

SKILLS

Programming Languages C++, Python, C, BASH Scripting, Ruby, TypeScript, Rust
Tools & Technologies Git, Bazel, Protobuf, Linux/Unix Systems, gRPC, MQTT

PROJECTS

Relay Robots — Embedded Systems, Robot Autonomy, Signal Conditioning

Designed and constructed 3 robots with team to autonomously run a relay. Coded in C with hierarchical state machines that controlled PWM signals to DC motors for locomotion, IR based navigation, and system operation. Full mechanical, circuit, and software design.

PATENTS

G. E. Lipkowitz, T. Samuelson, J. M. DeSimone, M. T. Dulay, and E. S. G. Shaqfeh. "Methods and systems for making polymeric microstructures." WIPO WO2023177815A1. (2023), [Online]. Available: <https://patents.google.com/patent/WO2023177815>.

PUBLICATIONS

G. E. Lipkowitz, T. Samuelson, K. Hsiao, B. J. Lee, J. M. DeSimone, *et al.*, "Injection continuous liquid interface production of 3d objects," *Science Advances*, 2022. doi: 10.1126/sciadv.abq3917.

K. Hsiao, B. J. Lee, T. Samuelson, J. M. DeSimone, *et al.*, "Single-digit-micrometer-resolution continuous liquid interface production," *Science Advances*, 2022. doi: 10.1126/sciadv.abq2846.