

Leren — Homework 2

Chapter 4 & 5, Alpaydin

Deadline: 23:59 November 13th, 2018

This is the third week's assignment for Leren. This assignment covers chapter 4 & 5 of Alpaydin. Please take note of the following:

- You are expected to hand in your solutions in L^AT_EX;
- This problem set is an individual assignment;
- The deadline for this first assignment is Tuesday, November 13 at 23:59.

1 Background: Linearity of the expectation

Use the definition of the expectation to answer the following questions:

- (a) For a random variable X ,

$$\mathbb{E}[aX + b] = a\mathbb{E}[X] + b \quad (1)$$

Show that this is the case.

- (b) For random variables X and Y ,

$$\mathbb{E}[X + Y] = \mathbb{E}[X] + \mathbb{E}[Y] \quad (2)$$

Show that this is the case.

2 Chapter 4: Parametric Methods

2.1 Bias/Variance

- (a) We have some model $g(x)$ that has a very high bias. What does that mean in terms of the training and validation errors?
- (b) We also consider some other model, $h(x)$ that has a very high variance. What does that mean in terms of the training and validation errors?
- (c) Suppose we use a massive dataset for training both models, which one is likely to give a better performance? Will the model that performs worse overfit or underfit?

2.2 MAP Estimation of Gaussian (normal) Density

In this exercise, we will lead you step-by-step to derive the Maximum A Posteriori (MAP) estimate of the mean of a Gaussian density. Recall that the MAP is given by $\theta_{MAP} = \arg \max_{\theta} p(\theta|X)$ (where in this case, the parameter θ is μ). Assume we are trying to fit a Gaussian to a dataset with N data points x_i .

$$P(X|\mu, \sigma_0) = \frac{1}{(2\pi)^{N/2} \sigma_0^N} \exp \left\{ -\frac{\sum_{i=1}^N (x_i - \mu)^2}{2\sigma_0^2} \right\} \quad (3)$$

where we have placed a prior on μ :

$$P(\mu|m, \sigma_1) = \frac{1}{\sqrt{2\pi}\sigma_1} \exp \left\{ -\frac{(\mu - m)^2}{2\sigma_1^2} \right\} \quad (4)$$

- Write down the posterior for this model, assuming that σ_0 , m and σ_1 are given.
- Write down the log of the posterior and fill in Eq. (3) and Eq. (4). Since $P(x)$ does not depend on μ , you can follow Eq. 4.39 from the book and write it as a constant c .
- Take the derivative of the log posterior wrt μ .
- To obtain the MAP, we have to find the point where the log posterior is maximized. To find this point, set the derivative to 0 and solve for μ .

2.3 Estimators

Show that the estimator for the mean of a Gaussian density, $m = \frac{\sum_t x^t}{N}$ is a consistent estimator for the true mean μ , i.e. that $\text{Var}(m) \rightarrow 0$ as $N \rightarrow \infty$, assuming that the data is i.i.d.

Hint: $\text{Var}(\sum_i x_i) = \sum_i \text{Var}(x_i)$ for i.i.d.

3 Chapter 5: Multivariate Methods

3.1 Maximum Likelihood of a Multivariate Gaussian Density

Given a dataset $\mathbf{X} = \{\mathbf{x}_i\}_{i=1}^N$ with N d -dimensional (iid) data points. We assume that \mathbf{x}_i are drawn from a Multivariate Gaussian distribution such that the likelihood function can be expressed as $l(\boldsymbol{\mu}, \boldsymbol{\Sigma}|\mathbf{X}) \equiv P(\mathbf{X}|\boldsymbol{\mu}, \boldsymbol{\Sigma})$:

$$P(\mathbf{X}|\boldsymbol{\mu}, \boldsymbol{\Sigma}) = \frac{1}{(2\pi)^{N \cdot D/2} |\boldsymbol{\Sigma}|^{N/2}} \exp \left\{ -\frac{1}{2} \sum_{i=1}^N (\mathbf{x}_i - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\mathbf{x}_i - \boldsymbol{\mu}) \right\} \quad (5)$$

Derive the maximum likelihood estimator for the mean of the Gaussian. To do so, take the following steps:

- Write down the expression for the log-likelihood $\mathcal{L}(\boldsymbol{\mu}, \boldsymbol{\Sigma}|\mathbf{X}) \equiv \log l(\boldsymbol{\mu}, \boldsymbol{\Sigma}|\mathbf{X})$
- Take the derivative of the log-likelihood wrt $\boldsymbol{\mu}$ (Hint: $\frac{\partial(\mathbf{a}^T \boldsymbol{\Sigma} \mathbf{a})}{\partial \mathbf{a}} = 2\mathbf{a}^T \boldsymbol{\Sigma}$)
- Set the derivative to 0
- Solve for $\boldsymbol{\mu}$