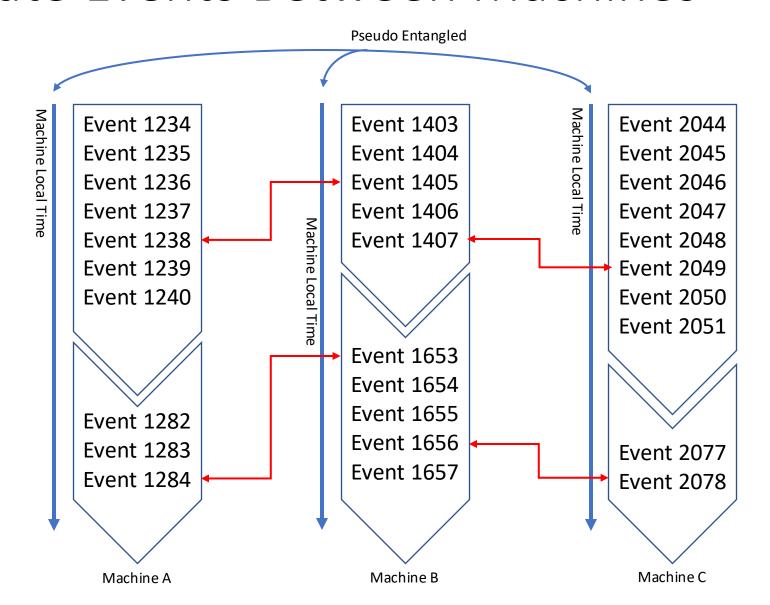
Tangle

Associating Events Across Machines

Problem Formulation

- Each machines runs on its own local time scale
- Events on each machine are time stamped with the local time scale
- It is necessary to associate event time stamps between machines
- Universal Time Coordination (UTC) can be used as a common time scale on all machines
- It is necessary to convert local time scale to UTC on each machines with the necessary precision
- Necessary precision is driven from the fastest event logging frequency
- For multiple machines, the necessary precision increases with the scale
- It is important to calculate the window of uncertainty on each machine

Correlate Events Between Machines



Precision Requirement

- CPU level
- OS (Kernel) level
- Distributed System level

Precision Requirement at CPU level

- Nyquist sampling theorem
 - Sampling interval required to avoid aliasing
 - Sampling frequency should be at least twice the highest frequency contained in the signal
- Frequency in event occurrence
 - Instruction Latency
 - Instruction Throughput

```
// mov = 1 CPU cycle
// xchg = 3 CPU cycles
// rdtsc = 1 CPU cycle
```

Precision Requirement at OS level

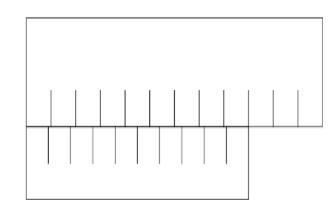
dmesg

```
52603.373642] {38}[Hardware Error]: event severity: corrected
              {38}[Hardware Error]: Error 0, type: corrected
              {38}[Hardware Error]:
                                       section type: PCIe error
[52603.373644]
[52603.373644]
              {38}[Hardware Error]:
                                       port type: 4, root port
              {38}[Hardware Error]:
[52603.373645]
                                       version: 3.0
              {38}[Hardware Error]:
                                       command: 0x0547, status: 0x0010
[52603.373645]
                                       device_id: 0000:b7:01.0
[52603.373646]
              {38}[Hardware Error]:
              {38}[Hardware Error]:
                                       slot: 255
[52603.373647]
[52603.373648] {38}[Hardware Error]:
                                       secondary bus: 0xb8
              {38}[Hardware Error]:
                                       vendor_id: 0x8086, device_id: 0x352a
[52603.373648]
[52603.373649]
              {38}[Hardware Error]:
                                       class code: 060400
                                       bridge: secondary_status: 0x0000, control: 0x0013
[52603.373649]
              {38}[Hardware Error]:
```

System Logging is based on clock_boottime (clock_minotone_RAW) with a quanta on 1us Events occur faster than the quanta of 1us (aliasing)

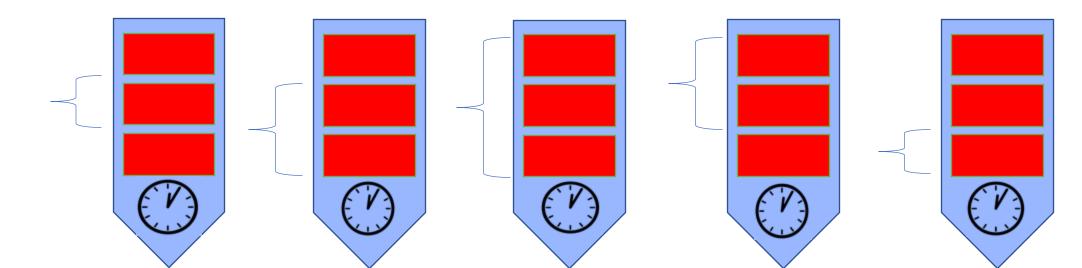
Challenges and the Precision Requirement

Vernier acuity

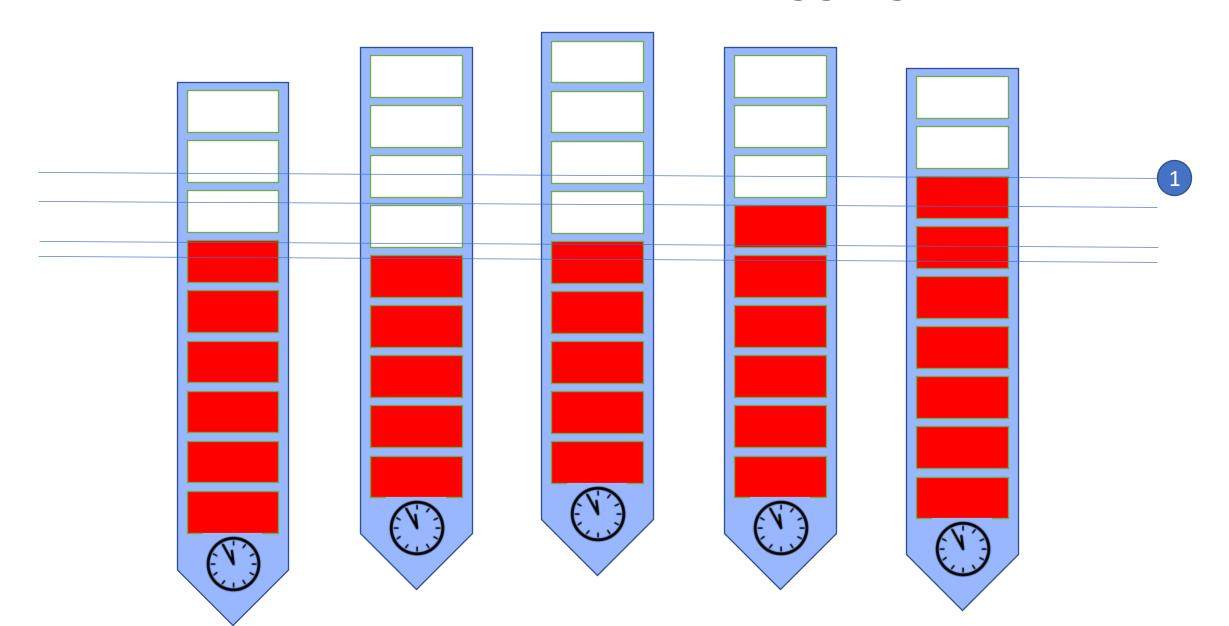


Compounding of Events

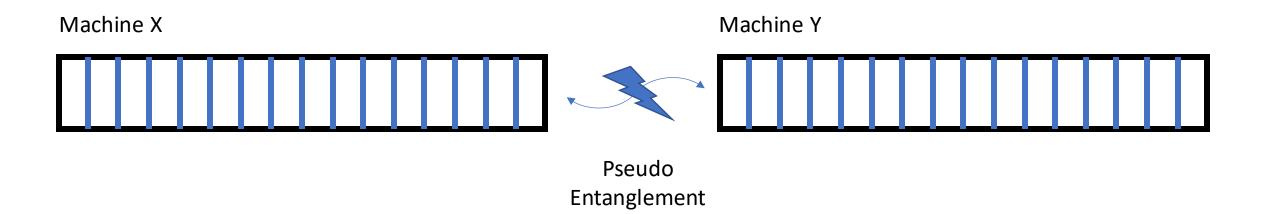
$$1^n = 1$$



Use case for correlated event logging



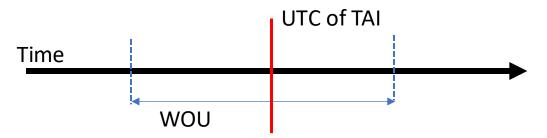
What comes out of Precision Time Sync?



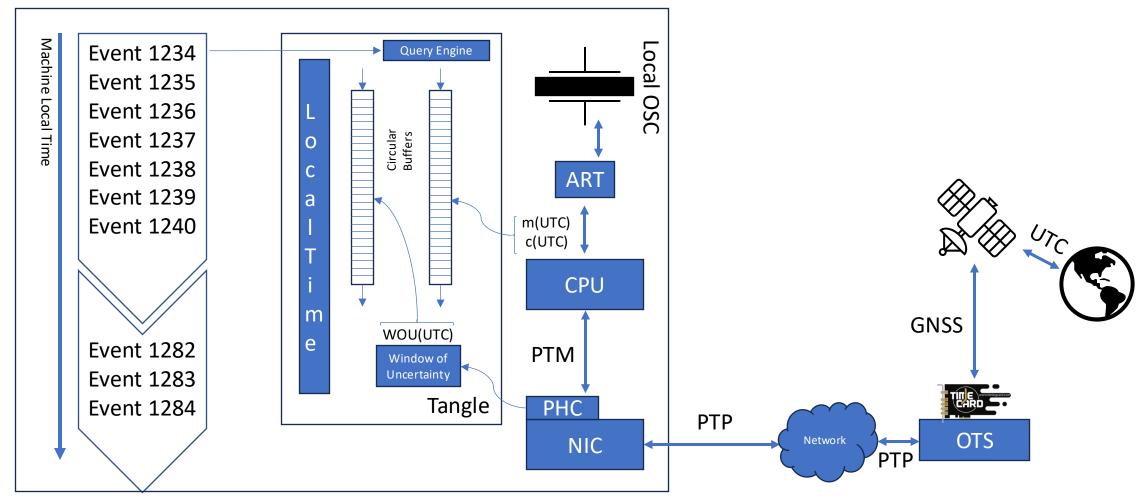
Machine X and Y are any two machines across the globe or inside a local network

Pseudo Entanglement: Probabilistic Entanglement of two Registers (Machine Y and Y) within the Windows of Uncertainty

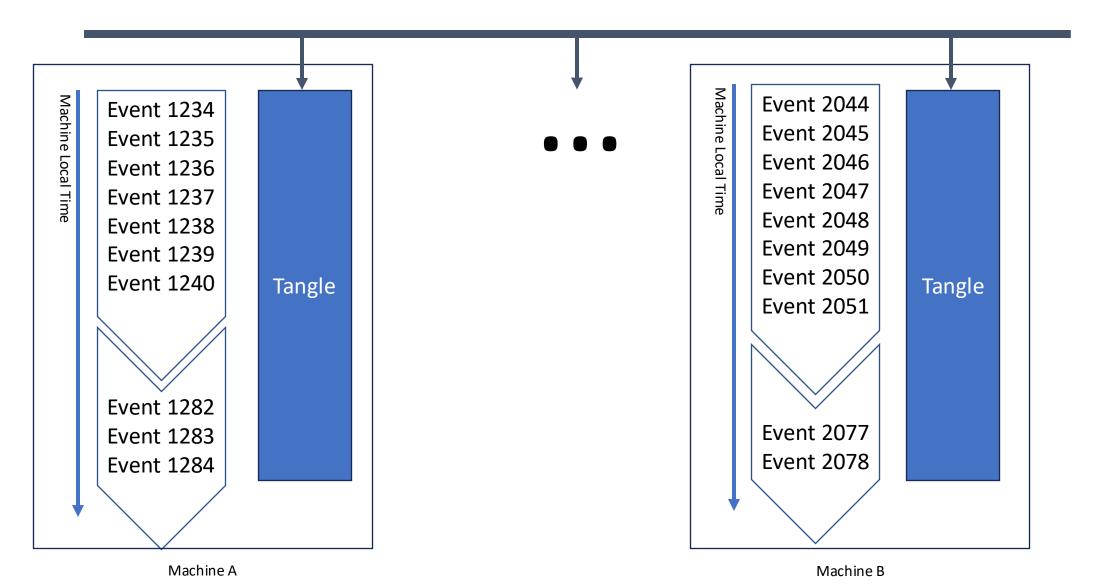
Window of Uncertainty: An ongoing estimation of a time interval that UTC (or TAI) sits inside it (with a given probability)



Architecture



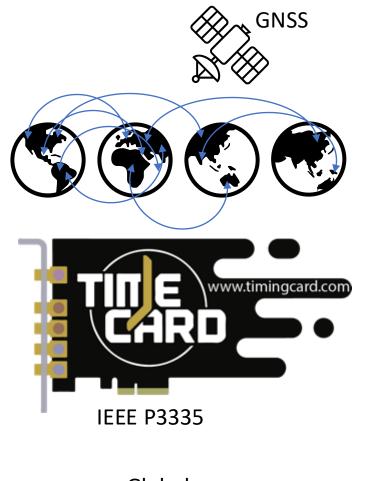
Multiple Systems

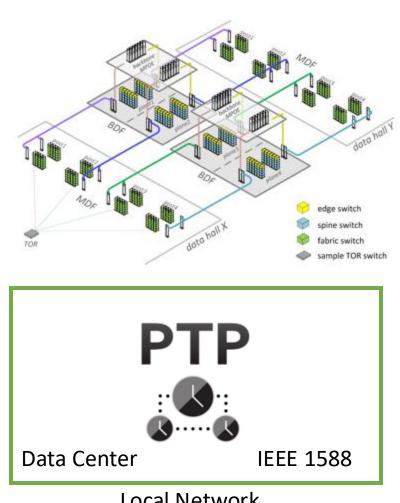


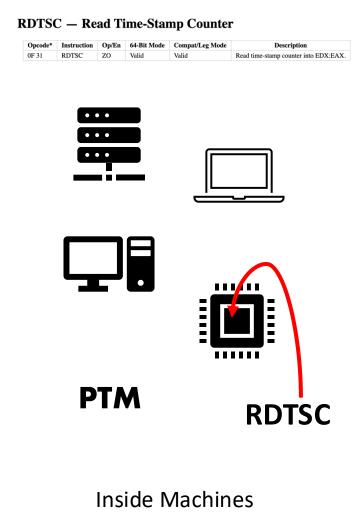
Functions

- Identify concurrent event in another machine[s]
- Find the timestamp of an event in another machine[s]
- Chronologically Rank a given event across machines
- Measure the one-way-latency between machines
- Identify concurrent events with one-way-latency consideration
- Trace chronological order for sequence of events
- Benchmark machines by precise runtime measurement
- Directly utilize RDTSC for maximum precision in event timestamping

Precision Time Sync Across Different Domains







Global

Local Network

Why is PTP+PTM needed?

Applications for Precision Time Synchronization in Data Centers

- Distributed Databases
- Distributed Load Balancers
- In Network Telemetry
- Distributed Al Systems

Time Precision and Applications

