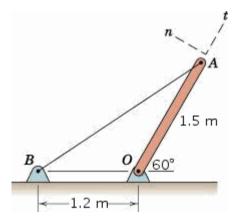
# 1. Chapter 1, Practice Reading Question 1/05

A direction cosine is:

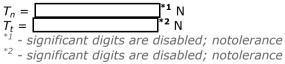
- The cosine of the angle between a vector and a particular coordinate axis.
- A unit vector that points in the direction of a vector.
- The cosine of the angle between a vector and the horizontal plane.
- The magnitude of a vector.

# 2. Chapter 2, Practice Problem 2/06

The cable AB prevents bar OA from rotating clockwise about the pivot O. If the cable tension is 750 N, determine the *n*- and *t*-components of this force acting on point *A* of the bar.



Answers:

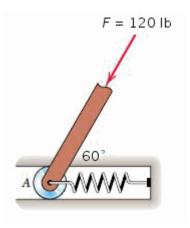


#### 3. Chapter 2, Problem 2/020

Determine the magnitude  $F_s$  of the tensile spring force in order that the resultant of **F**s and **F** is a vertical force. Determine the magnitude R of this vertical resultant force.

<sup>\*2 -</sup> significant digits are disabled; notolerance

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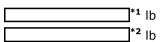
Answers:

 $F_s =$ 

R =

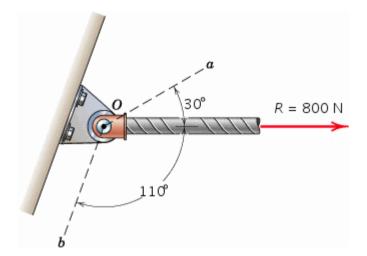
\*1 - significant digits are disabled; notolerance

\*2 - significant digits are disabled; notolerance

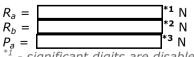


#### 4. Chapter 2, Problem 2/023 (video solution to similar problem attached)

Determine the scalar components  $R_a$  and  $R_b$  of the force **R** along the nonrectangular axes a and b. Also determine the orthogonal projection  $P_a$  of **R** onto axis a.



Answers:



\*1 - significant digits are disabled; notolerance

\*2 - significant digits are disabled; notolerance

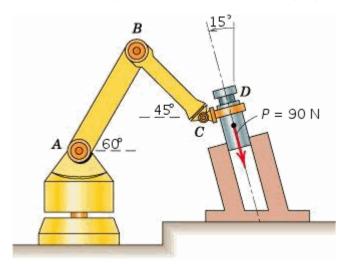
\*3 - significant digits are disabled; notolerance

### 5. Chapter 2, Problem 2/029

In the design of the robot to insert the small cylindrical part into a close-fitting circular hole, the robot arm must exert a 90-N force *P* on the part parallel to the axis of the hole as shown. Determine the components of the force which the

.....

part exerts on the robot along axes (a) parallel and perpendicular to the arm AB, and (b) parallel and perpendicular to the arm BC. The parallel direction is t and the perpendicular direction is n. Report your answers as positive numbers.



Answers:

(a) AB:

 $P_t =$ 

\*1N, l\*³N,  $P_n = \square$ 

(b) BC:  $P_t = \bigsqcup_{*1}^{*1}$  - significant digits are disabled; notolerance

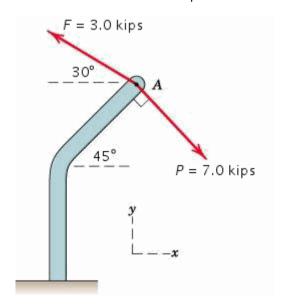
\*2 - significant digits are disabled; notolerance

\*3 - significant digits are disabled; notolerance

\*4 - significant digits are disabled; notolerance

### 6. Chapter 2, Supplemental Problem 2/03

The two forces shown act at point A of the bent bar. Determine the resultant  $\mathbf{R}$  of the two forces.

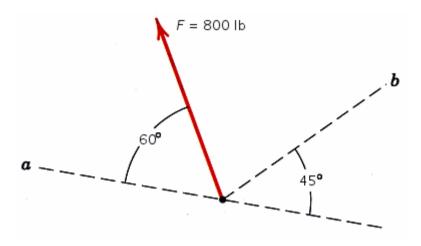


\***²j**) kips

\*2 - significant digits are disabled; notolerance

# 7. Chapter 2, Supplemental Problem 2/06 (detailed solution attached)

Determine the components of the 800-lb force  $\mathbf{F}$  along the oblique axes a and b. Also, determine the projections of  $\mathbf{F}$  onto the a- and b-axes.



Answers:

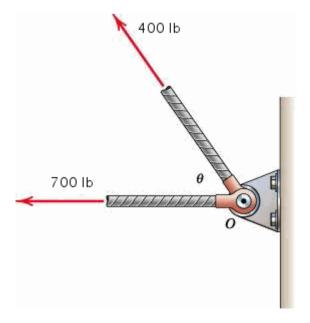
Components:

Projections:

F<sub>a</sub> = \_\_\_\_\_\*1 lb,

# 8. Chapter 2, Supplemental Problem 2/08

At what angle  $\theta$  must the 400-lb force be applied in order that the resultant **R** of the two forces have a magnitude of 1000 lb? For this condition what will be the angle $\beta$  between **R** and the horizontal?



Answers:

<sup>\*1 -</sup> significant digits are disabled; notolerance

<sup>\*2 -</sup> significant digits are disabled; notolerance

<sup>\*3 -</sup> significant digits are disabled; notolerance

<sup>\*4 -</sup> significant digits are disabled; notolerance

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 $\beta = \beta$ \*1 - significant digits are disabled; notolerance
\*2 - significant digits are disabled; notolerance