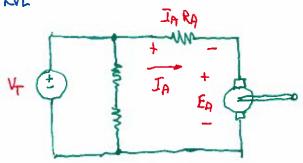
$$K\phi = \frac{E_A}{\omega_M} = \frac{300}{1200 \times 2T} = 2.387$$
 Friday, April 8,

Total torque required is Tout = 200 Nm. Add rotational losses

Strategy: Find IA, then EA, then speed.

$$I_A = \frac{T_{dev}}{K\phi} = \frac{212}{2.387} = 88.8$$

From KVL



$$E_A = V_T - I_A R_A$$

= 300 - 88.8 (0.065)

$$So \ \omega_{m} = \frac{E_{A}}{K\phi} = \frac{294.2}{2.387} = 123.6 \text{ rad/sec}$$

$$n_m = \omega_m \times \frac{60}{2\pi} = 1177 \text{ rpm}$$

And efficiency: Part = Tart
$$\omega_m = 200 \times 123.6$$

= 24,652 ω

$$P_{in} = V_{T}I_{L} = 300(I_{F}+I_{P})$$

= 300(10+888)
= 29,640 W.

$$\eta = \frac{P_{\text{out}}}{P_{\text{li}}} \times 100\% = \frac{24,632}{29,640} \times 100\%$$

$$= 83.2\%$$

Example: Suppose fan blades are attached to the shaft of the above motor.

· this adds 15 Nm of additional torque loss, independent of speed.

What is the new speed?

Armature current increases:
$$I_A = \frac{T_{dev}}{K\phi} = \frac{227}{2.387} = 95.1$$
.

By KVL,
$$E_A = V_T - I_A R_A = 300 - (95.1)(0.065)$$

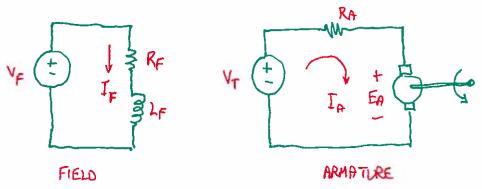
= 293.82

Then,
$$\omega_{m} = \frac{E_{A}}{K\phi} = \frac{293.82}{2387} = 123.09 \text{ rad/sec}$$

So
$$n_m = \omega_m \times \frac{60}{2\pi} = 1175.4 \text{ ppm}$$

Separately excited DC machines

This configuration is similar to shunt-connected, except field and armature have separate sources.



$$\eta = \frac{P_{\text{out}}}{P_{\text{in}}} \times 100\% = \frac{24652}{29640} \times 100\%$$

$$= 83.2\%$$

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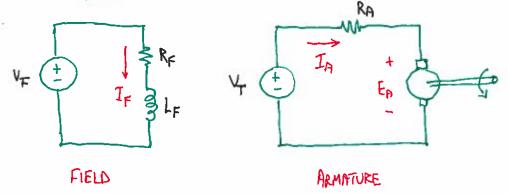
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Then,
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$$n_m = \omega_m \times \frac{60}{2T} = 1175.4 \text{ rpm}$$

Separately excited DC machines

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Permament - magnet DC motors

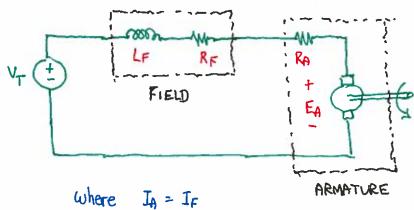
Similar to separately excited, except field is produced by permanent magnets.

Useful in fractional-horsepower applications

- · Small fans
- · power windows, windshield wipers
- · Servos

Series - connected DC motors

field and armature connected in series



Series - connected motors have high torque at low speeds. Suitable for many applications

- · electric automothie starter motors
- · electric drills, screndrivers
- . handheld mixers.

Torque - speed characteristics

All motors are characterized by torque-speed characteristics.