

Problem 1

For the circuit shown,

$$\begin{aligned}\bar{I} &= \frac{260\sqrt{2}\angle 50^\circ - 220\sqrt{2}\angle 30^\circ}{5 + j12} \\ &= \frac{236.35 + j281.67 - 269.44 - j155.56}{5 + j12} \\ &= \frac{-33.09 + j126.11}{5 + j12} = \frac{130.38\angle 104.70^\circ}{13\angle 67.38^\circ} \\ &= 10.03\angle 37.32^\circ\end{aligned}$$

The rms current is $I_{rms} = \frac{10.03}{\sqrt{2}} = 7.09 \text{ A}$

Average power absorbed by the resistor $P_R = I_{rms}^2 R = 251 \text{ W}$
 Reactive power "absorbed" by the inductor $Q_L = I_{rms}^2 X = 603 \text{ VAR}$

Source \bar{V}_1 :

$$\bar{S}_1 = -\frac{1}{2} \bar{V}_1 \bar{I}^* = -(\bar{V}_1)_{rms} (\bar{I}^*)_{rms}$$

↑
thanks to passive reference convention

$$\begin{aligned}\bar{S}_1 &= -260\angle 50^\circ \times 7.09\angle -37.32^\circ \\ &= 260\angle 50^\circ - 180^\circ \times 7.09\angle -37.32^\circ\end{aligned}$$

↑
could add or subtract 180°!

$$\bar{S}_1 = 1843.4\angle -167.32^\circ = -1798 - j405 \text{ VA}$$

Average power delivered is 1798 W
 Reactive power "delivered" is 405 VAR

Source \bar{V}_2 :

$$\begin{aligned}\bar{S}_2 &= (\bar{V}_2)_{rms} (\bar{I}^*)_{rms} \\ &= 220\angle 30^\circ \times 7.09\angle -37.32^\circ\end{aligned}$$

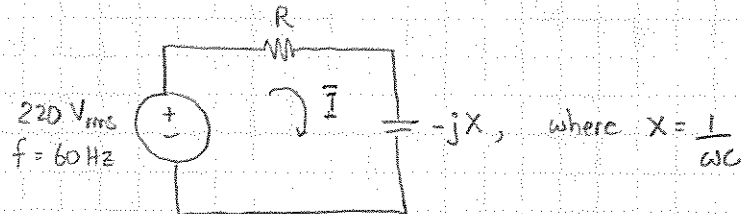
$$\bar{S}_2 = 1559.8 \angle -7.32^\circ = 1547 - j199 \text{ VA}$$

Average power absorbed is 1547 W

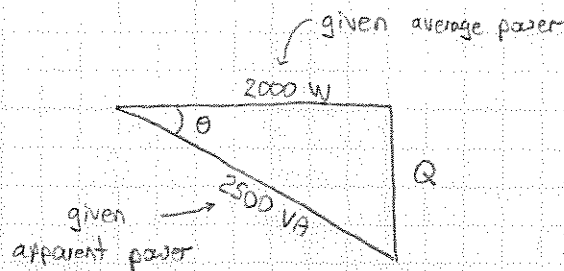
Reactive power "delivered" is -199 VAR

Energy balance is observed by adding all average power and all reactive power.

Problem 2



The power triangle:



The power angle $\theta = \theta_V - \theta_I$ is the angle of the load's impedance, which is negative, so $Q < 0$.

$$Q = -\sqrt{2500^2 - 2000^2} \\ = -1500 \text{ VAR}$$

$$\bar{S} = (\bar{V}_{rms})(\bar{I}_{rms}^*) = 2000 - j1500 \text{ VA}$$

$$\bar{S} = (\bar{V}_{rms}) \left(\frac{\bar{V}_{rms}}{Z} \right)^* = (\bar{V}_{rms}) \frac{(\bar{V}_{rms})^*}{Z^*}$$

With $\bar{V}_{rms} = 220 \angle 0^\circ$, then $\bar{V}_{rms}^* = 220 \angle 0^\circ$

$$\text{so } \bar{S} = \frac{(\bar{V}_{rms})^2}{Z^*} \Rightarrow \text{so } Z^* = \frac{(\bar{V}_{rms})^2}{\bar{S}}$$

$$Z^* = \frac{(220)^2}{2000 - j1500} = 15.49 + j11.62$$

giving $Z = 15.49 - j11.62 \Omega$

From this value of Z , $R = 15.49 \Omega$, and $X = 11.62 \Omega$

$$X = \frac{1}{\omega C}, \text{ so } C = \frac{1}{\omega X}$$

$$C = \frac{1}{2\pi \times 60 \times 11.62} = 228.3 \mu\text{F}.$$

Problem 3

We are given information that will allow us to determine the machine constant

$$E_A = 200 \text{ V at } n_m = 1200 \text{ rpm}$$

$$\text{We have } \omega_m = 1200 \times \frac{2\pi}{60} = 125.66 \text{ rad/sec.}$$

From one of the machine equations, $E_A = K\phi\omega_m$, so $K\phi = \frac{E_A}{\omega_m}$.

$$K\phi = \frac{200}{125.66} = 1.591$$

With the motor running at $n_{m2} = 1500 \text{ rpm}$, $P_{dev} = 5 \text{ HP}$.

$$\omega_m = 1500 \times \frac{2\pi}{60} = 157.08 \text{ rad/sec}$$

$$P_{dev} = 5 \text{ HP} \times \frac{746 \text{ W}}{\text{HP}} = 3730 \text{ W}$$

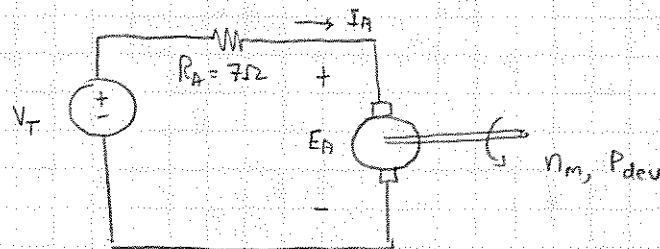
$$\text{So } T_{dev} = \frac{P_{dev}}{\omega_m} = \frac{3730}{157.08} = \boxed{23.746 \text{ Nm}}$$

The other machine equation allows us to find I_A

$$T_{dev} = K\phi I_A, \text{ so } I_A = \frac{T_{dev}}{K\phi} = \frac{23.746}{1.591} = \boxed{14.92 \text{ A}}$$

Problem 4

The simple circuit model for the motor is



From the information given, we may determine the machine constant and rotational losses.

At no-load, $I_A = 1\text{ A}$, $n_m = 1500\text{ rpm}$.

$$\text{We have } \omega_m = 1500 \times \frac{2\pi}{60} = 157.08\text{ rad/sec}$$

$$\text{and } E_A = V_T - I_A R_A = 240 - 1 \times 7 = 233\text{ V}$$

From one of the machine equations, $K\phi = \frac{E_A}{\omega_m}$

$$K\phi = \frac{E_A}{\omega_m} = \frac{233}{157.08} = \boxed{1.483}$$

We also know that $P_{dev} = E_A I_A = 233 \times 1 = 233\text{ W}$. Since there is no mechanical load attached, P_{dev} is used entirely to overcome rotational losses at 1500 rpm.

$$\text{Thus, } P_{rot} = P_{dev} = 233\text{ W.}$$

$$\text{Frictional torque loss} = T_{rot} = \frac{P_{rot}}{\omega_m} = \frac{233}{157.08}$$

$$\boxed{T_{rot} = 1.483\text{ Nm}}$$

With the load now attached, the speed drops to $n_m = 1300\text{ rpm}$. At the lower speed, P_{rot} reduces proportionally.

$$P_{rot} = T_{rot} \omega_m, \quad \omega_m = 1300 \times \frac{2\pi}{60} = 136.14\text{ rad/sec}$$

$$\text{so } P_{\text{rot}} = 1.483 \times 136.14 \text{ rad/sec} = 201.93 \text{ W}$$

The induced voltage E_A will also decrease proportionally

$$E_A = \frac{1300}{1500} \times 233 = 201.93 \text{ V}$$

$$\text{so the new } I_A = \frac{V_T - E_A}{R_A} = \frac{240 - 201.93}{7} = 5.439 \text{ A}$$

$$\text{For the efficiency calculation, } P_{\text{in}} = V_T \times I_A = 240 \times 5.439 = 1305.26 \text{ W}$$

$$\begin{aligned} \text{and } P_{\text{out}} &= P_{\text{dev}} - P_{\text{rot}} = E_A I_A - 201.93 \\ &= 201.93 \times 5.439 - 201.93 \\ &= 896.4 \text{ W} \end{aligned}$$

$$\text{Efficiency } \eta = \frac{P_{\text{out}}}{P_{\text{in}}} \times 100\% = \frac{896.4}{1305.26} \times 100\% = \boxed{68.7\%}$$

Problem 5

From the information given, we may determine the machine constant

$$\text{At } 1200 \text{ rpm, } \omega_m = 1200 \times \frac{2\pi}{60} = 125.66 \text{ rad/sec}$$

$$E_A = K\phi\omega_m, \text{ so } K\phi = \frac{E_A}{\omega_m} = \frac{175}{125.66} = 1.393$$

Rotational losses at 1200 rpm: $P_{\text{rot}} = 50 \text{ W}$.

$$\text{so } T_{\text{rot}} = \frac{P_{\text{rot}}}{\omega_m} = \frac{50}{125.66} = 0.398 \text{ Nm}$$

When the machine is run with no mechanical load, $T_{\text{dev}} = T_{\text{rot}}$.
From this, we can find I_A , E_A , then ω_m

$$I_A = \frac{T_{\text{dev}}}{K\phi} = \frac{0.398}{1.393} = 0.2857 \text{ A}$$

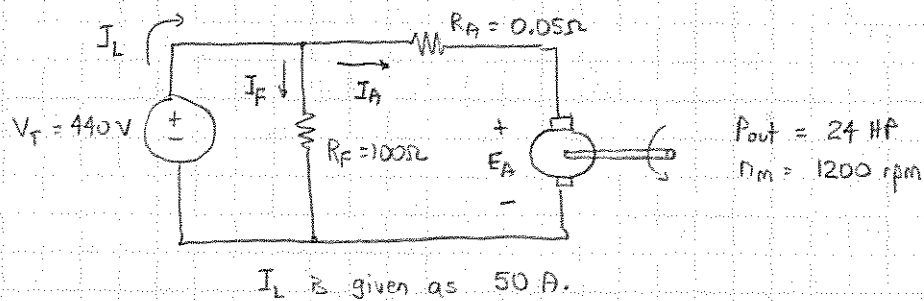
$$\begin{aligned} \text{and } E_A &= V_T - I_A R_A \\ &= 200 - 0.2857 \times 1 = 199.714 \text{ V} \end{aligned}$$

$$\text{so } \omega_m = \frac{E_A}{K\phi} = \frac{199.714}{1.393} = 143.41 \text{ rad/sec}$$

$$\text{Finally, } n_m = 143.41 \times \frac{60}{2\pi} = \boxed{1369.5 \text{ rpm}}$$

Problem 6

The electric circuit model for the motor:



From the information given, we may determine I_A , E_A , then the machine constant $K\phi$.

$$\text{We have, by KCL, } I_L = I_F + I_A. \text{ } I_F \text{ will be } I_F = \frac{440}{100} = 4.4 \text{ A}$$

$$\text{so } I_A = 50 - 4.4 = 45.6 \text{ A}$$

$$\text{From KVL, } E_A = V_T - I_A R_A = 440 - 45.6 \times 0.05$$

$$E_A = 437.72 \text{ V}$$

$$\text{At } 1200 \text{ rpm, } \omega_m = 1200 \times \frac{2\pi}{60} = 125.66 \text{ rad/sec}$$

$$\text{so } E_A = K\phi \omega_m, \text{ and } K\phi = \frac{E_A}{\omega_m} = \frac{437.72}{125.66}$$

$$K\phi = 3.483.$$

$$\text{We can now find } T_{dev} = K\phi I_A = 3.483 \times 45.6 = \boxed{158.84 \text{ Nm}}$$

For efficiency, we already know $P_{out} = 24 \text{ HP}$

$$P_{out} = 24 \times 746 \frac{W}{HP} = 17904 W$$

$$\text{and } P_{in} = V_T I_L = 440 \times 50 = 22000 W$$

$$\eta = \frac{P_{out}}{P_{in}} \times 100\% = \frac{17904}{22000} \times 100\% = \boxed{81.4\%}$$