

# Electricity and Magnetism

- Physics 259 – L02
- Lecture 42



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# Chapter 29: Magnetic field due to current



# Last time:

- Biot-Savart Law (like Coulomb's Law for magnetism)

# Today:

- B-field of a line of current
- Magnetic force between parallel current-carrying wires
- Ampere's law



For a single charge →

$$\vec{F}_B = q \vec{v}_d \times \vec{B}$$

For N charges moving through the wire  
(current carrying wire) →

$$\vec{F}_B = i \vec{\ell} \times \vec{B}$$

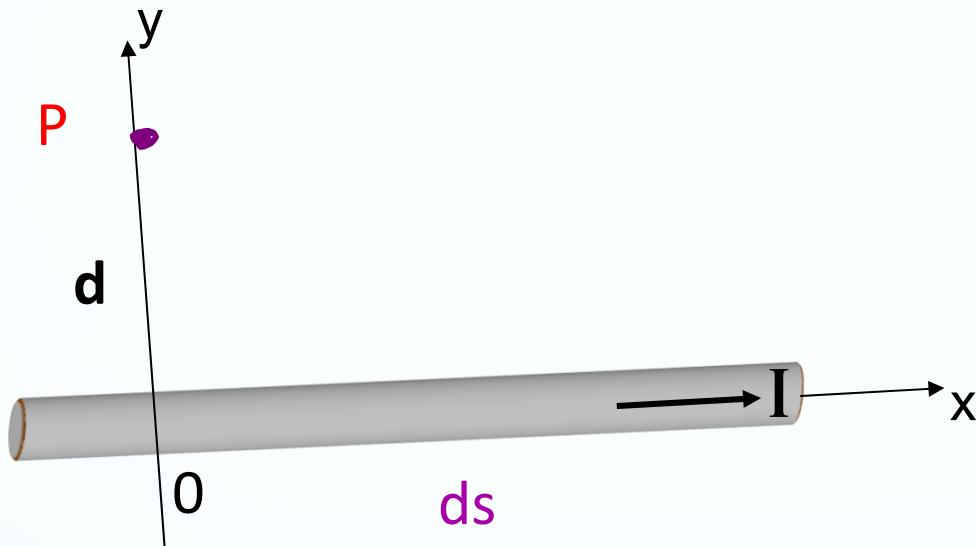
The Biot-Savart Law →

$$\vec{B}_{\text{point charge}} = \frac{\mu_0}{4\pi} \frac{q \vec{v} \times \hat{r}}{r^2}$$

For an electric current →

$$\vec{B}_{\text{current segment}} = \frac{\mu_0}{4\pi} \frac{I \Delta \vec{s} \times \hat{r}}{r^2}$$

# Magnetic field due to current in long straight wire



$$\vec{B} = \frac{\mu_0}{4\pi} \frac{I \Delta \vec{s} \times \hat{r}}{r^2}$$

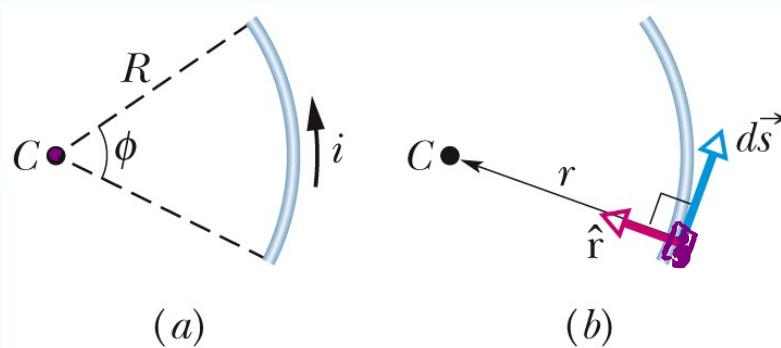
$$B_z = \frac{\mu_0}{2\pi} \frac{I}{d}$$

, tangent to a circle around the wire in the right-hand direction

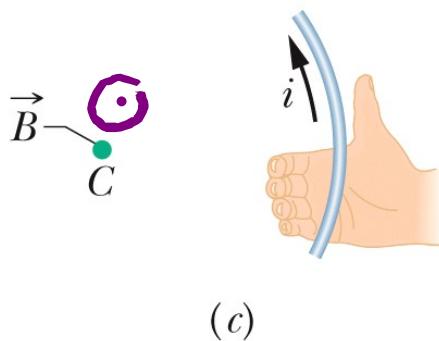
Non-infinite straight wire → Appendix 1-chapter 29

# Magnetic field due to a current in a circular arc of wire

The magnitude of the **magnetic field at the center of a circular arc**, of radius  $R$  and central angle  $\phi$  (in radians), carrying current  $i \rightarrow$



$$\phi = 90^\circ$$



(c)

The right-hand rule reveals the field's direction at the center.

$$dB = \frac{\mu_0}{4\pi} \frac{I \vec{ds} \times \hat{r}}{r^2} \rightarrow$$

$$\rightarrow dB = \frac{\mu_0}{4\pi} \frac{I ds |\hat{r}| \sin\varphi}{R^2}$$

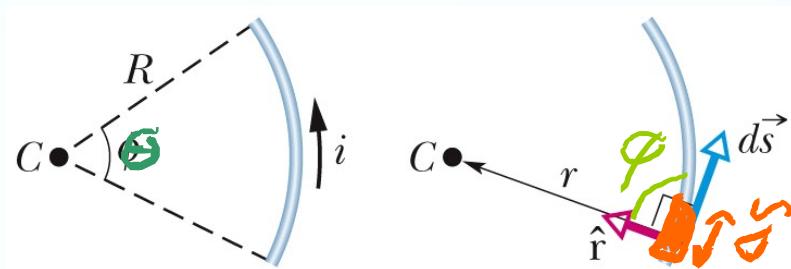
$$\varphi = 90^\circ$$

$$\rightarrow dB = \frac{\mu_0}{4\pi} \frac{I ds}{R^2}$$

$$\rightarrow dB = \frac{\mu_0}{4\pi} \frac{I R d\phi}{R^2} \rightarrow$$

$$B = \int dB = \int_0^\phi \frac{\mu_0}{4\pi} \frac{I R d\phi}{R^2}$$

$$\rightarrow B = \frac{\mu_0}{4\pi} \frac{I}{R} \int_0^\phi d\phi = \frac{\mu_0}{4\pi} \frac{I}{R} \epsilon =$$



$\varphi$  between  $\hat{r}$  and  $d\vec{s}$

$$\sin\varphi = 1$$

$$|\hat{r}| = 1$$

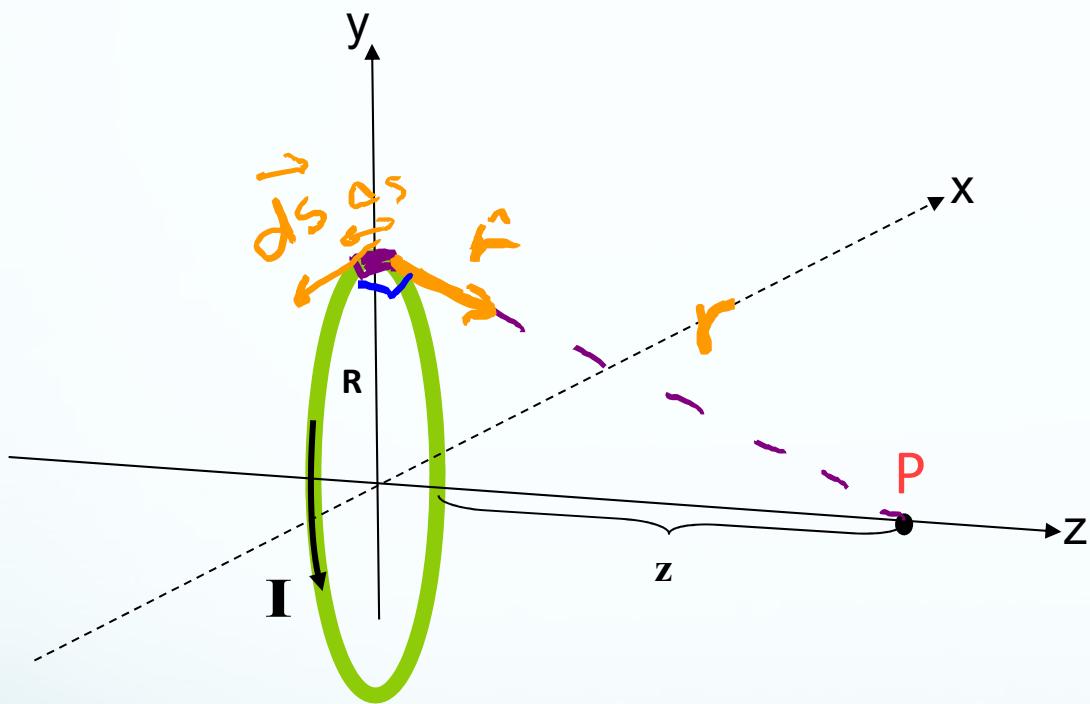
$$ds = R d\theta$$

$I \rightarrow i$

↓

$$B = \frac{\mu_0 i \odot}{4\pi R}$$

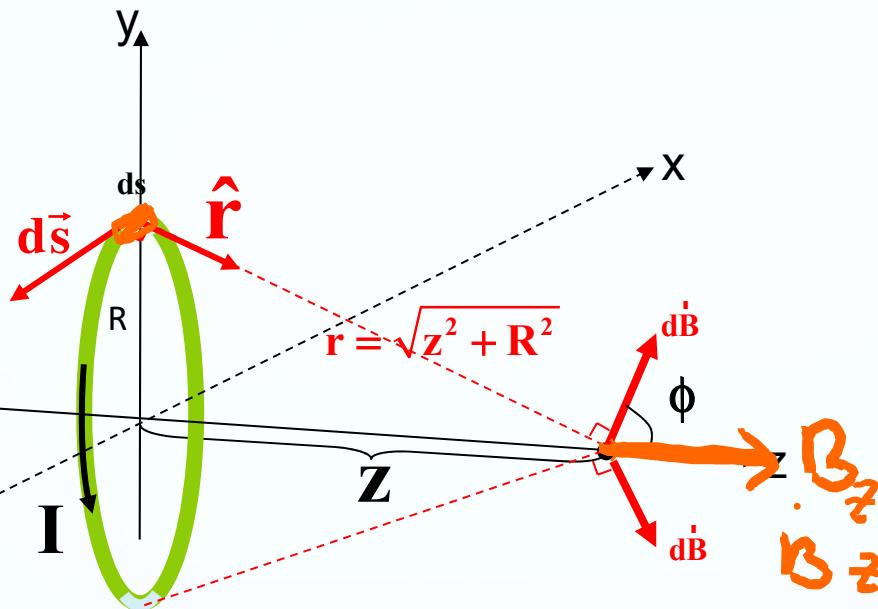
# Magnetic field due to a current in a circular loop (at distance z from the loop)



1. Coordinate system
2. The point to calculate field
3. Segments
4. B

$$\vec{B}_{\text{current segment}} = \frac{\mu_0}{4\pi} \frac{I \Delta \vec{s} \times \hat{r}}{r^2} = \frac{\mu_0}{4\pi} \frac{I ds \hat{r} \sin \phi}{r^2}, \quad \phi = 90^\circ$$

# Magnetic field of a circular loop



1. Coordinate system
2. The point to calculate field
3. Segments
4.  $B$

$$dB_x = dB_y = 0$$

$$dB_z = dB \cos \phi$$

$$\cos \phi = \frac{R}{\sqrt{z^2 + R^2}}$$

$$dB = \frac{\mu_0}{4\pi} \frac{I ds \sin 90^\circ}{r^2} = \frac{\mu_0}{4\pi} \frac{I ds}{r^2} \rightarrow dB_z = \frac{\mu_0}{4\pi} \frac{I ds}{r^2} \cos \phi$$

$$\rightarrow dB_z = \frac{\mu_0}{4\pi} \frac{I ds}{z^2 + R^2} \frac{R}{\sqrt{z^2 + R^2}}$$

$$\rightarrow dB_z = \frac{\mu_0}{4\pi} \frac{IRds}{(z^2 + R^2)^{3/2}}$$

# Integrate!

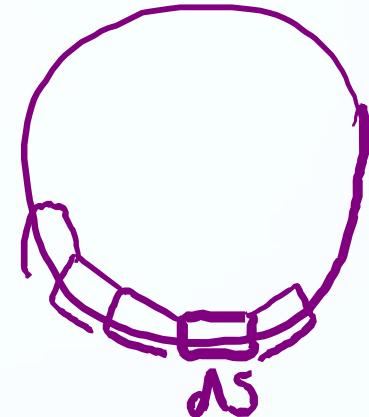
$$dB_z = \frac{\mu_0}{4\pi} \frac{IRds}{(z^2 + R^2)^{3/2}}$$

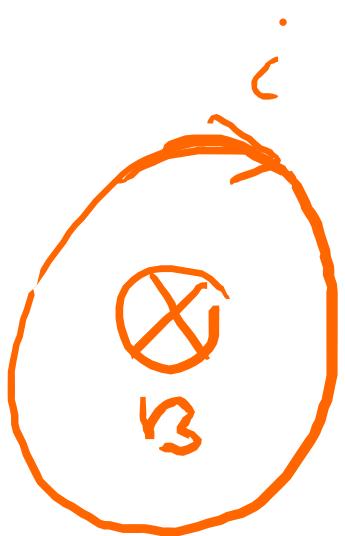
$$B_z = \int_{\text{circle}} dB_z = \int_{\text{circle}} \frac{\mu_0}{4\pi} \frac{IRds}{(z^2 + R^2)^{3/2}}$$

$$\rightarrow B_z = \frac{\mu_0}{4\pi} \frac{IR}{(z^2 + R^2)^{3/2}} \underbrace{\int_{\text{circle}} ds}_{ds}$$

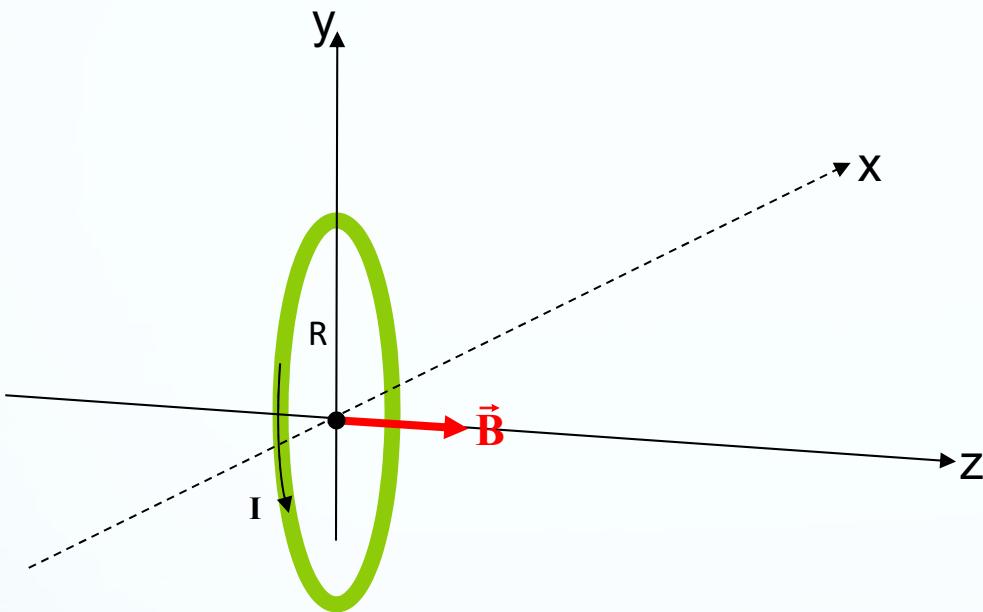
$$\rightarrow B_z = \frac{\mu_0}{\cancel{4\pi}} \frac{IR \cancel{2\pi R}}{(z^2 + R^2)^{3/2}} \rightarrow B_z = \frac{\mu_0 IR^2}{2(z^2 + R^2)^{3/2}}$$

→  $\vec{B} = \frac{\mu_0}{2} \frac{IR^2}{(z^2 + R^2)^{3/2}} \hat{k}$





# Magnetic field of a current loop at the center (z=0)

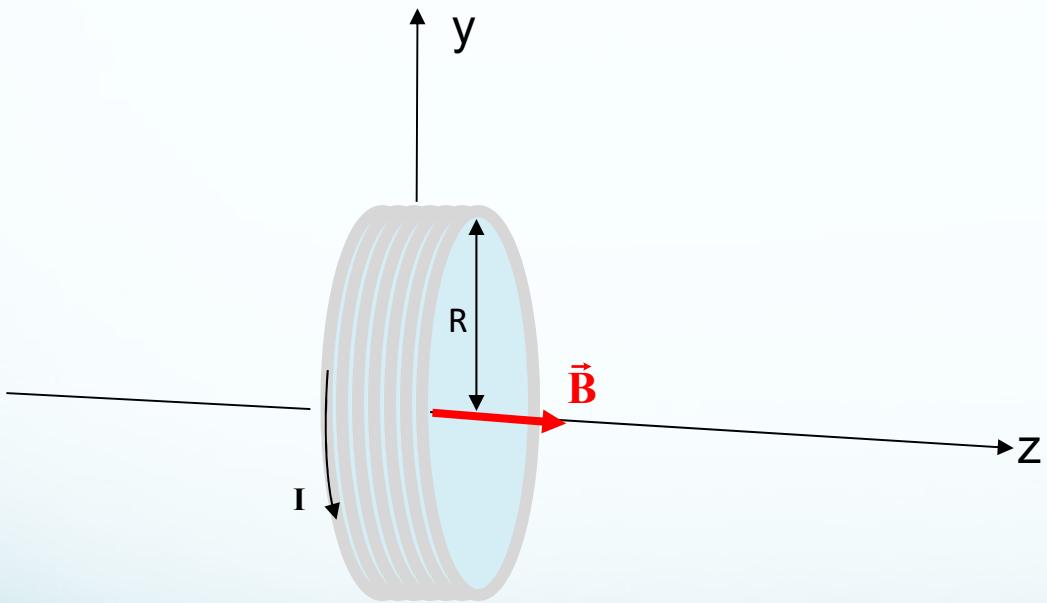


$$\vec{B} = \frac{\mu_0}{2} \frac{IR^2}{(z^2 + R^2)^{3/2}} \hat{k}$$

if  $z = 0$   $\rightarrow B = \frac{\mu_0}{2} \frac{IR^2}{(R^2)^{3/2}} = \frac{\mu_0}{2} \frac{I}{R}$

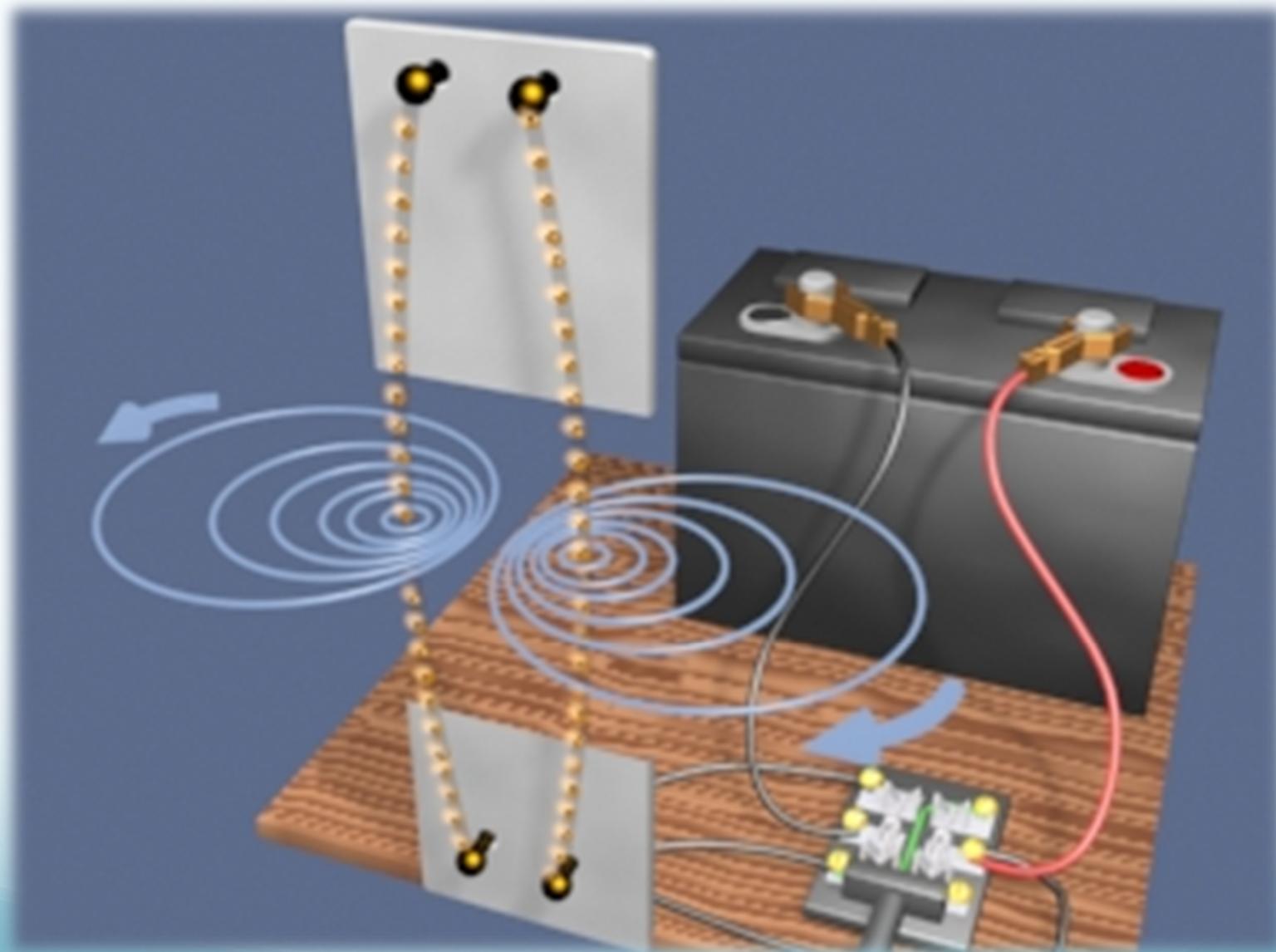
$$\vec{B}_{\text{center}} = \frac{\mu_0}{2} \frac{I}{R} \hat{k}$$

Magnetic field of a coil consists of N current loop (with the radius R) at the center of the coil:



$$\vec{B}_{\text{coil center}} = \frac{\mu_0}{2} \frac{NI}{R} \hat{k}$$

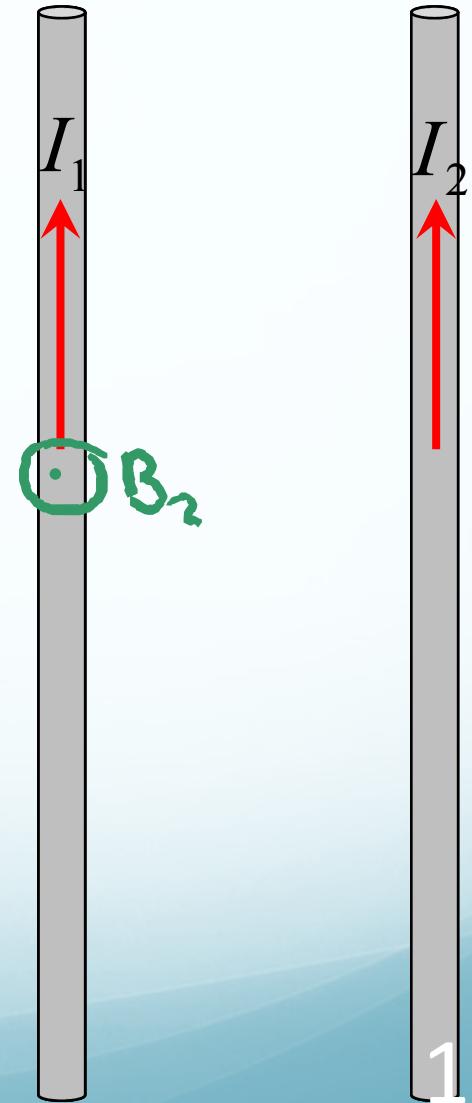
## 29.2: Force between two antiparallel currents



# TopHat Question

Two wires carry currents  $I_1$  and  $I_2$  as shown.  
What direction is the magnetic field produced by wire 2 at the location of wire 1?

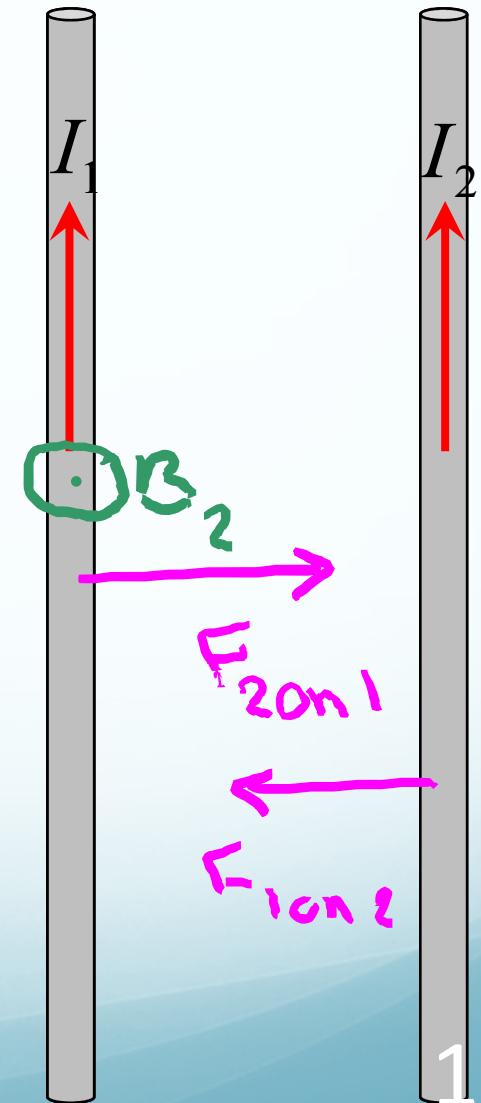
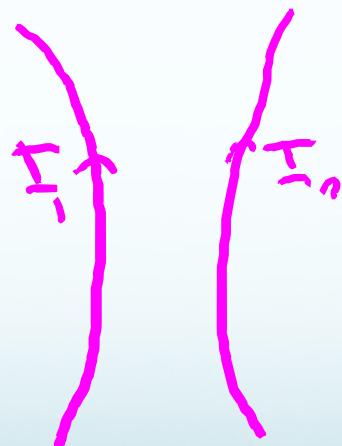
- A. Downward
- B. Upward
- C. Into the page
- D. Out of the page



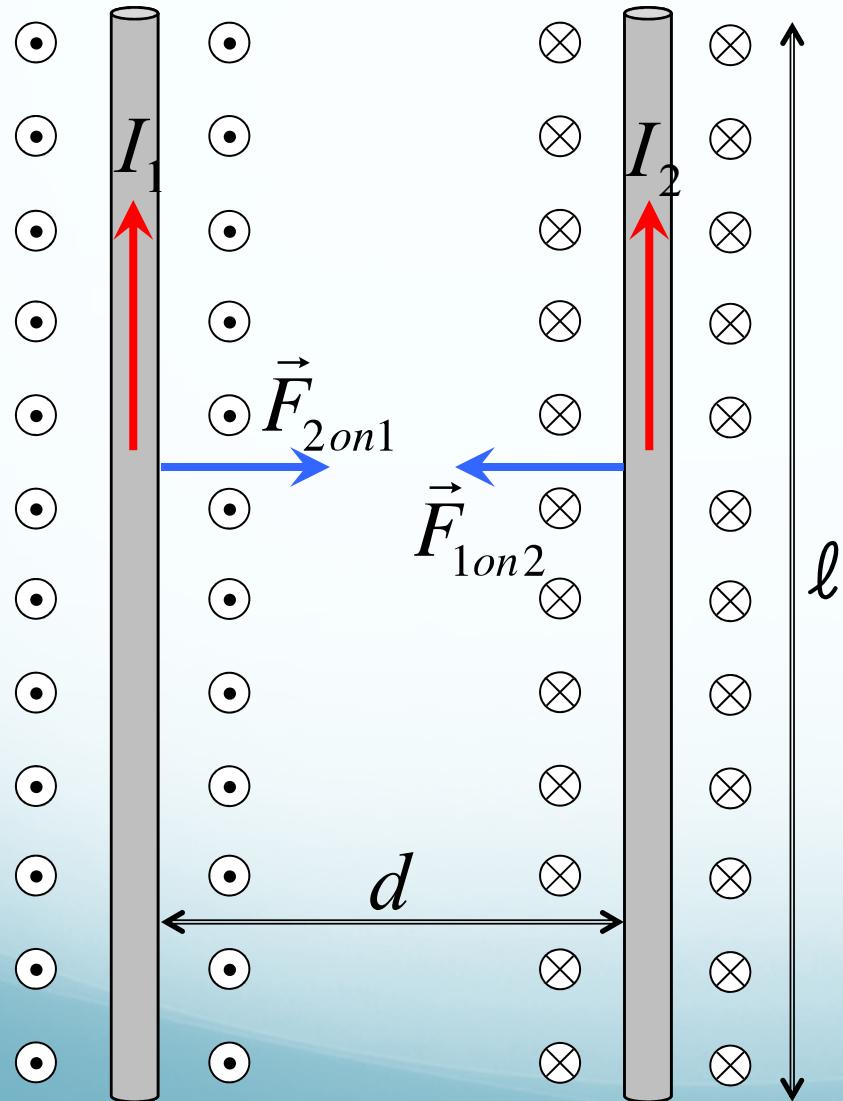
# TopHat Question

Two wires carry currents  $I_1$  and  $I_2$  as shown. What direction is the force of wire 2 on wire 1?

- A. Left
- B. Right
- C. Up
- D. Down



$$|\vec{B}_2| = \frac{\mu_0 I_2}{2\pi d}$$



$$|\vec{B}_1| = \frac{\mu_0 I_1}{2\pi d}$$

Wire 2 exerts a force on wire 1

$$\vec{F}_{2on1} = I_1 \vec{\ell} \times \vec{B}_2$$

$$|\vec{F}_{2on1}| = I_1 \ell \frac{\mu_0 I_2}{2\pi d} = \boxed{\frac{\mu_0 \ell I_1 I_2}{2\pi d}}$$

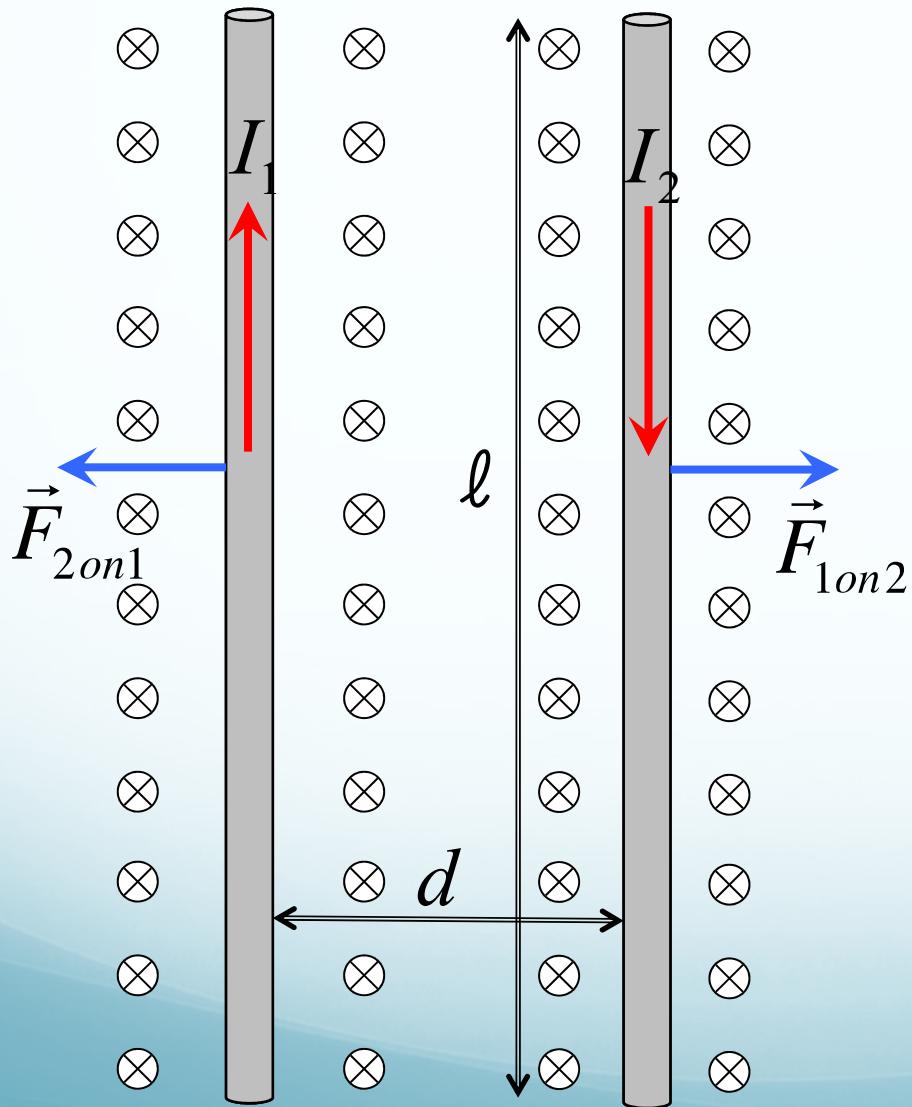
Wire 1 exerts a force on wire 2

$$\vec{F}_{1on2} = I_2 \vec{\ell} \times \vec{B}_1$$

$$|\vec{F}_{1on2}| = I_2 \ell \frac{\mu_0 I_1}{2\pi d} = \boxed{\frac{\mu_0 \ell I_1 I_2}{2\pi d}}$$

Newton's third law!

$$|\vec{B}_2| = \frac{\mu_0 I_2}{2\pi d}$$



$$|\vec{B}_1| = \frac{\mu_0 I_1}{2\pi d}$$

Wire 2 exerts a force on wire 1

$$\vec{F}_{2on1} = I_1 \vec{\ell} \times \vec{B}_2$$

$$|\vec{F}_{2on1}| = I_1 \ell \frac{\mu_0 I_2}{2\pi d} = \boxed{\frac{\mu_0 \ell I_1 I_2}{2\pi d}}$$

Wire 1 exerts a force on wire 2

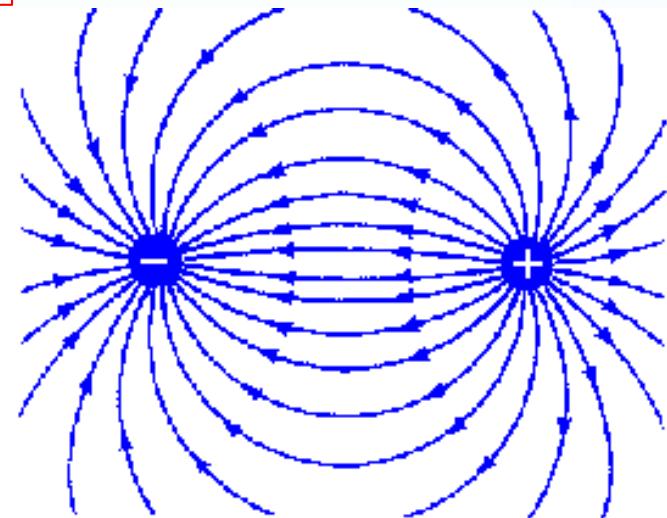
$$\vec{F}_{1on2} = I_2 \vec{\ell} \times \vec{B}_1$$

$$|\vec{F}_{1on2}| = I_2 \ell \frac{\mu_0 I_1}{2\pi d} = \boxed{\frac{\mu_0 \ell I_1 I_2}{2\pi d}}$$

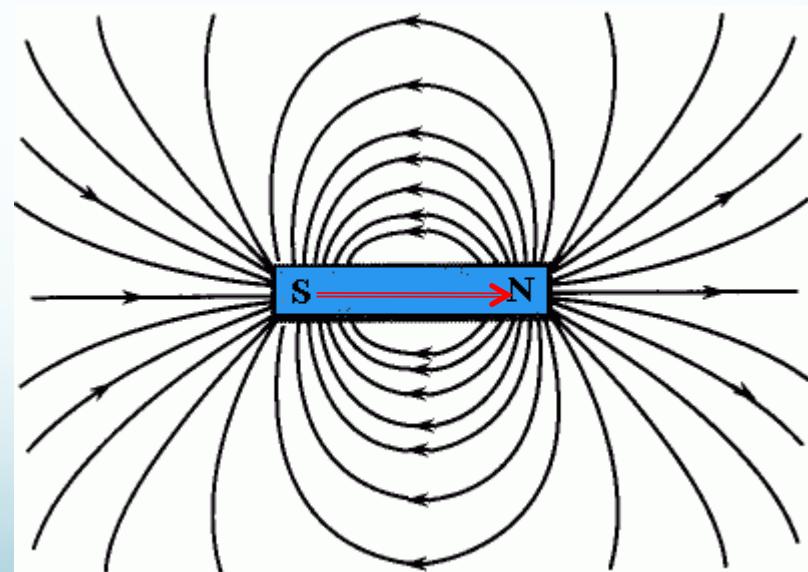
Newton's third law!

# Dipole Fields

Electric field from an electric dipole



Magnetic field from a magnetic dipole. **Note** that the magnetic field lines are **continuous** – they do **NOT** stop at the poles!



Both fields have the same shape!

# Not a Top Hat Question

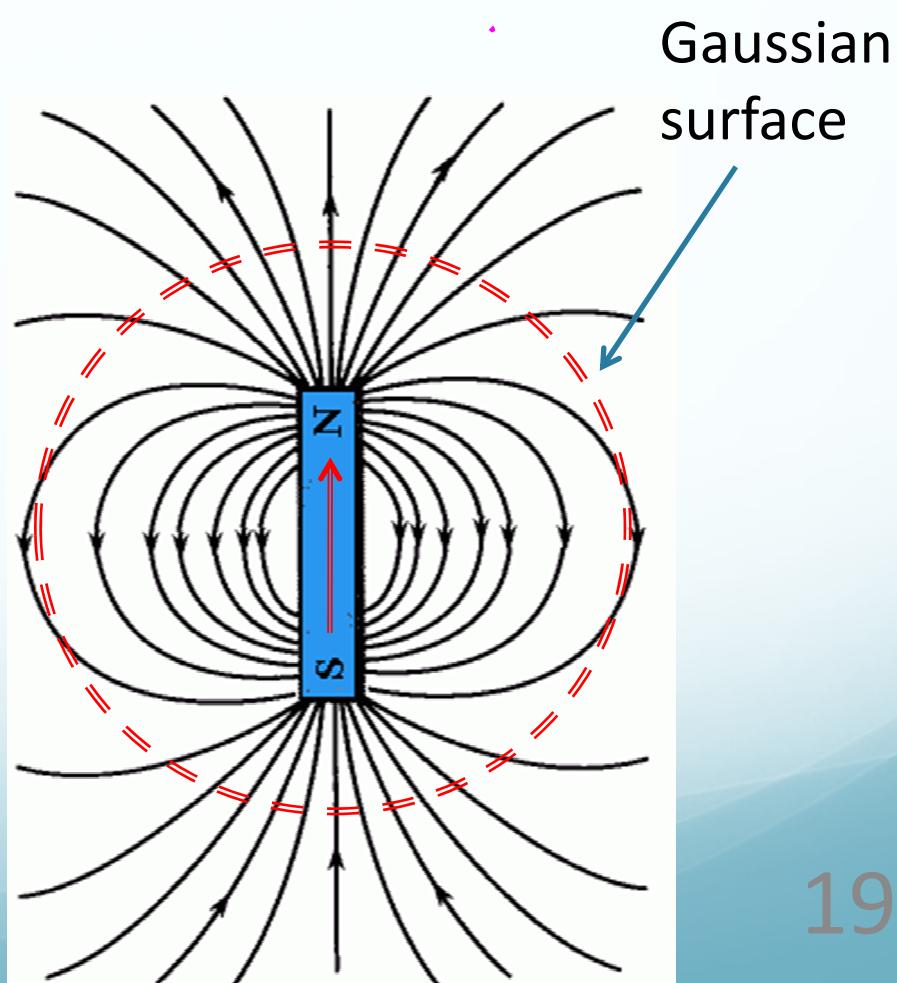
The magnetic field lines from a magnet point out of the North pole and point into the South pole.

What can you say about the magnetic flux passing through this Gaussian surface?

$$\Phi_B = \oint \vec{B} \cdot d\vec{a} = \frac{q_{enc}}{\epsilon_0}$$

$$\Phi_B = 0$$

- A. Magnetic flux is zero 
- B. Magnetic flux is greater than zero
- C. Magnetic flux is smaller than zero
- D. Can't tell without computing the integral



## Gauss' Law for Magnetism

The magnetic flux through a closed surface is ALWAYS zero.

$$\Phi_B = \oint \vec{B} \cdot d\vec{a} = 0$$

no enclosed  
magnetic charges

There is no way to isolate a North or South magnetic pole

The simplest E-field is from a point charge, while the simplest B-field is from a magnetic dipole (e.g. Bar Magnet)

# Maxwell's equations

Essentially all of Electricity & Magnetism can be described by a set of 4 equations, referred to as Maxwell's equations.

$$\nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0}$$
$$\nabla \cdot \vec{B} = 0$$

$\oint \vec{E} \cdot d\vec{A}$

$\oint \vec{B} \cdot d\vec{A} = 0$

$$\nabla \times \vec{E} = - \frac{\partial \vec{B}}{\partial t}$$

$$\nabla \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

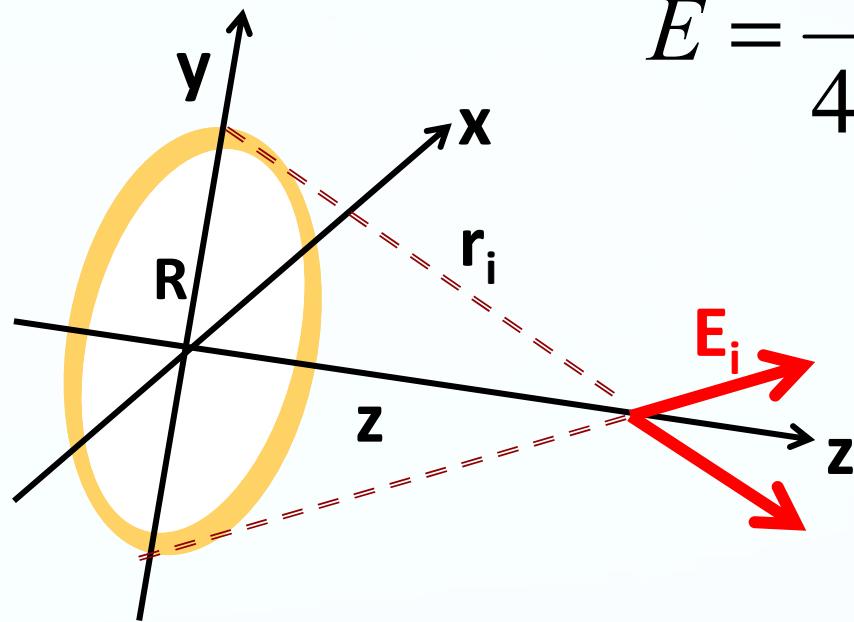
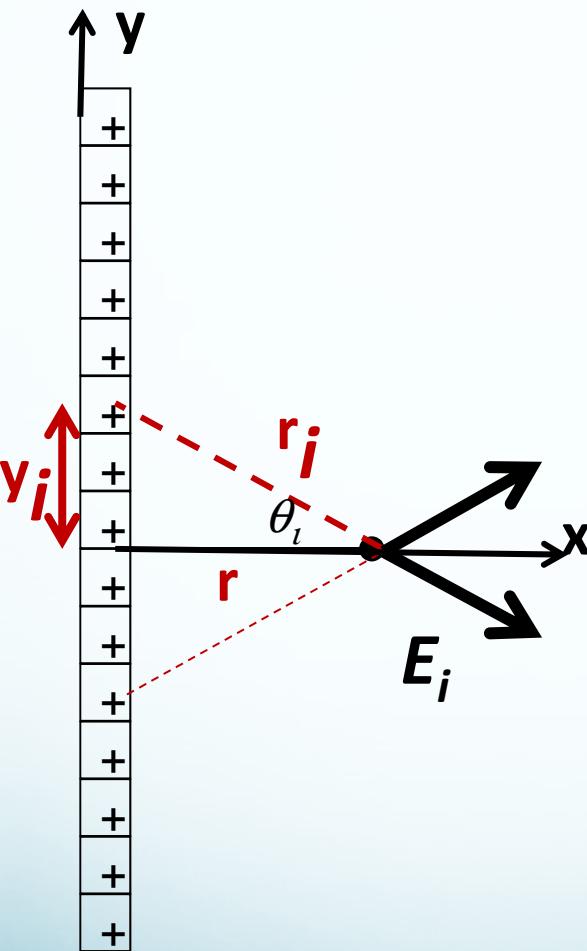
$$c = \frac{1}{\sqrt{\mu_0 \epsilon_0}}$$

→ We now have two of them!

$$\Phi_E = \oint \vec{E} \cdot d\vec{a} = \frac{Q_{encl}}{\epsilon_0}$$

$$\Phi_B = \oint \vec{B} \cdot d\vec{a} = 0$$

# Electrostatics



$$\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} \hat{r}$$

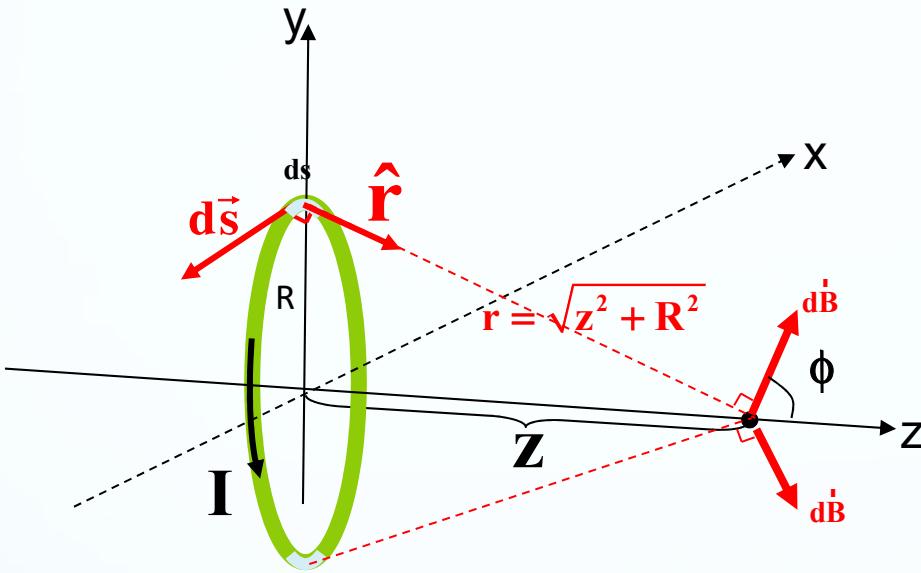
Savior:  
**Gausses' law**



$$\oint \vec{E} \cdot d\vec{A} = \frac{Q_{in}}{\epsilon_0}$$

# Magnetostatics

$$\vec{B}_{\text{current segment}} = \frac{\mu_o}{4\pi} \frac{I \Delta \vec{s} \times \hat{r}}{r^2}$$



Savior:

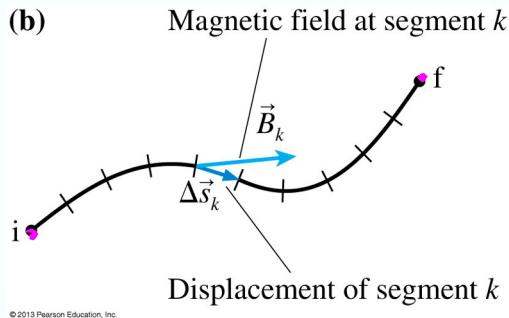
**Ampere's law**

Expression?



# Ampère's law

The line integral of  $\mathbf{B}$  along the path:



$$\int_i^f \vec{B} \cdot d\vec{l}$$

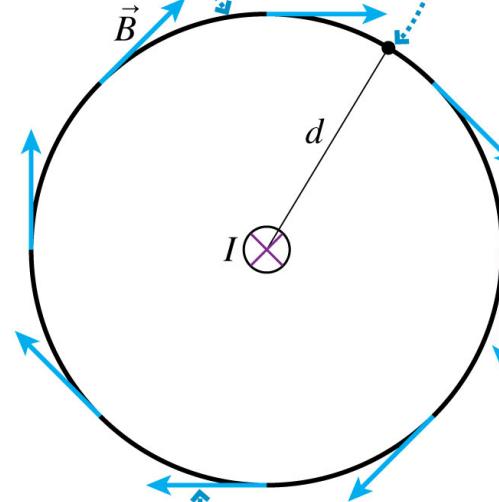
$$\oint \vec{B} \cdot d\vec{l} = (2\pi r) \left( \frac{\mu_0 I}{2\pi r} \right)$$

=  $(\cancel{B}) l$

$\Rightarrow$  i.e.  $\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{encl}$

The integration path is a circle of radius  $d$ .

The integration starts and stops at the same point.



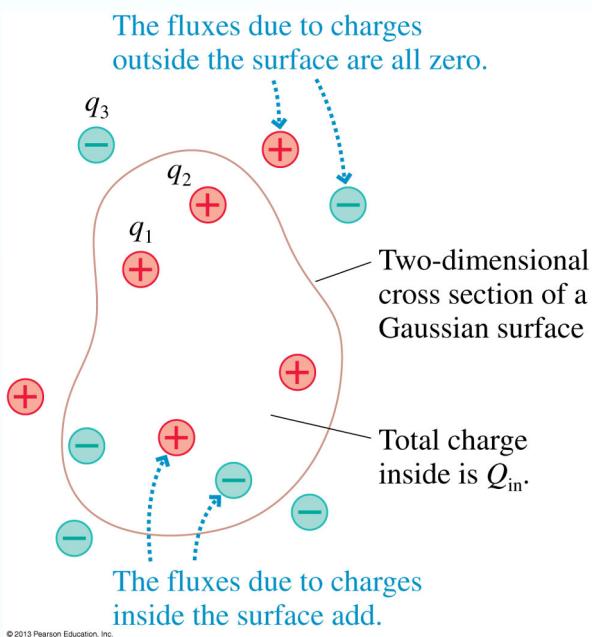
$\vec{B}$  is everywhere tangent to the integration path and has constant magnitude.

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Infinite wire  $\rightarrow B = \frac{\mu_0 I}{2\pi r}$

$\oint E \cdot dA = \frac{q_{encl}}{\epsilon_0}$

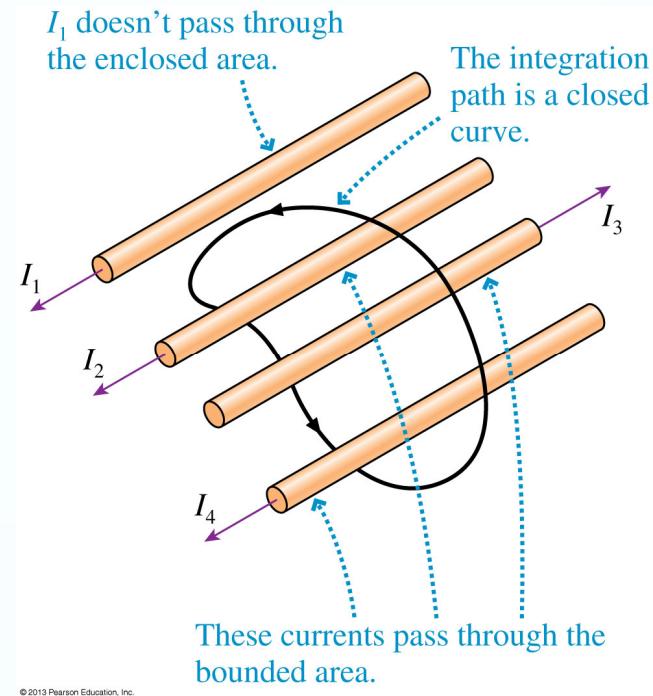
Ampère's Law is true for any shape of path and any current distribution



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$$\oint \vec{E} \cdot d\vec{A} = \frac{Q_{in}}{\epsilon_0}$$

**For a closed surface enclosing total Charge Q**

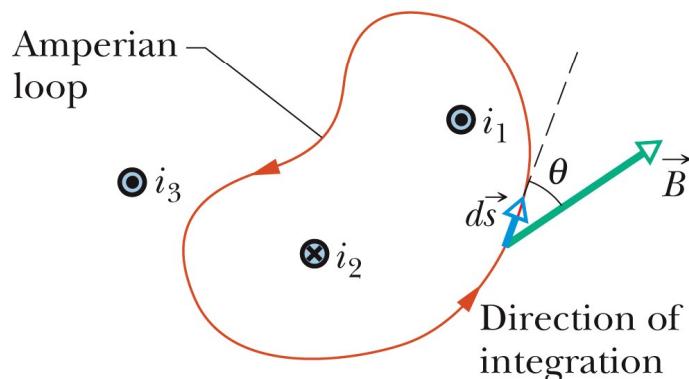


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$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{enclosing}$$

**Current I passes through an area bounded by a closed curve**

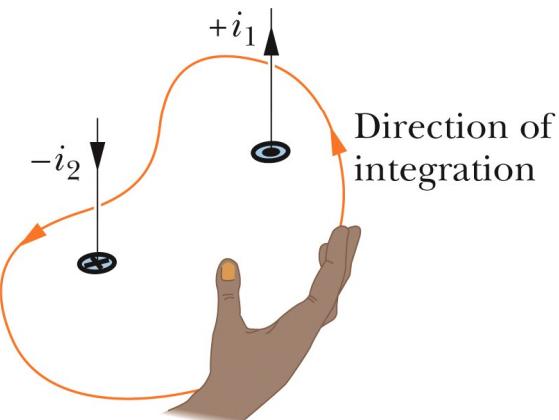
Only the currents encircled by the loop are used in Ampere's law.



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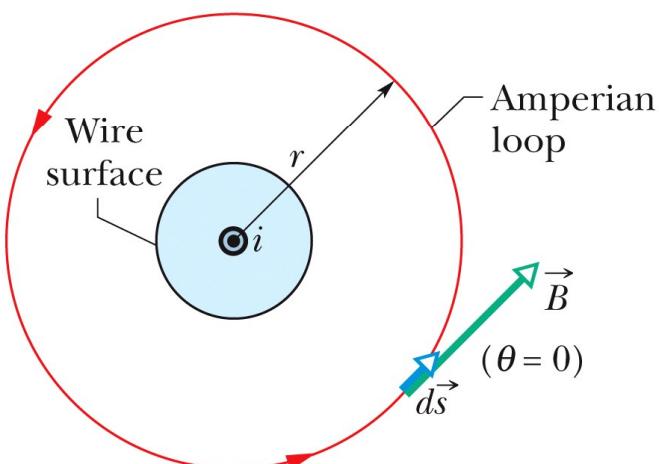
This is how to assign a sign to a current used in Ampere's law.



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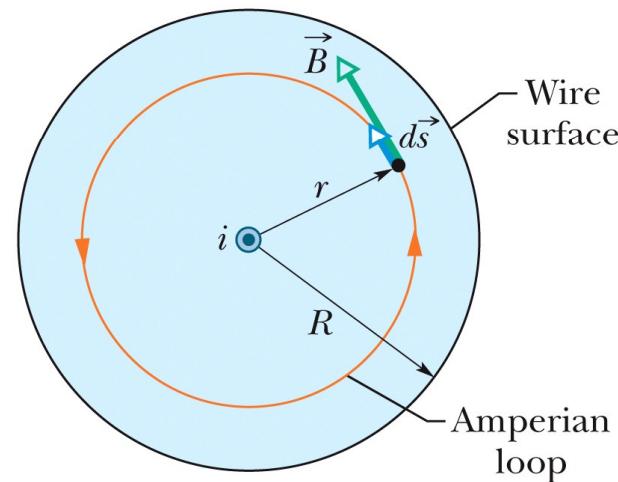
All of the current is encircled and thus all is used in Ampere's law.



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Only the current encircled by the loop is used in Ampere's law.



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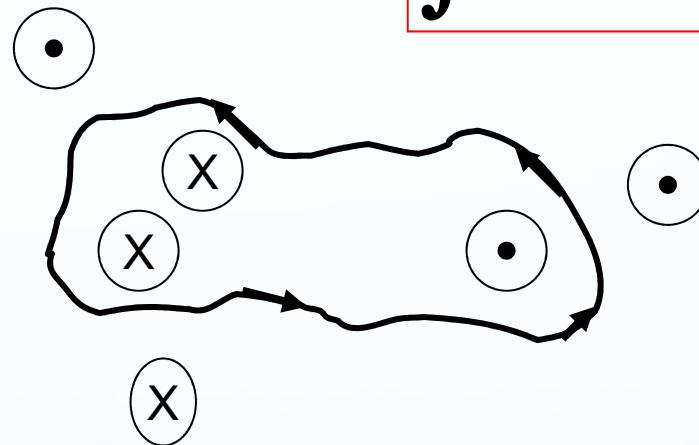
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# TopHat Question

What is  $I_{\text{encl}}$  here, where all three wires have 5 A?

$$\oint \vec{B} \cdot d\vec{L} = \mu_0 I_{\text{through}}$$

- A) -5 A
- B) 5 A
- C) 15 A
- D) -15 A
- E) other



This section we talked about:

Chapter 29

*See you on Thursday*

