

Wednesday March 29, 2017

Last time:

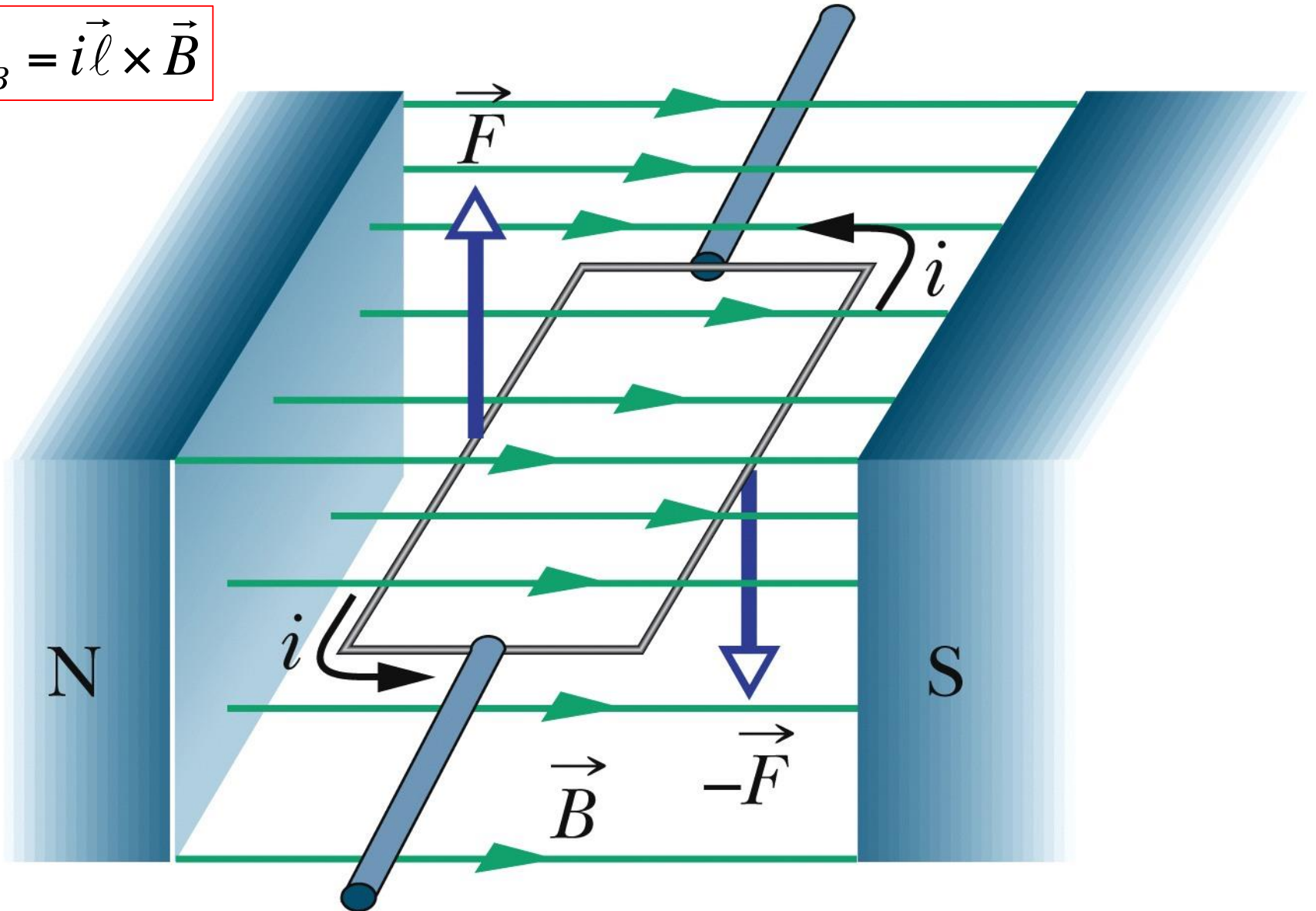
- Magnetic force between parallel current-carrying wires
- Torque on a current loop

Today:

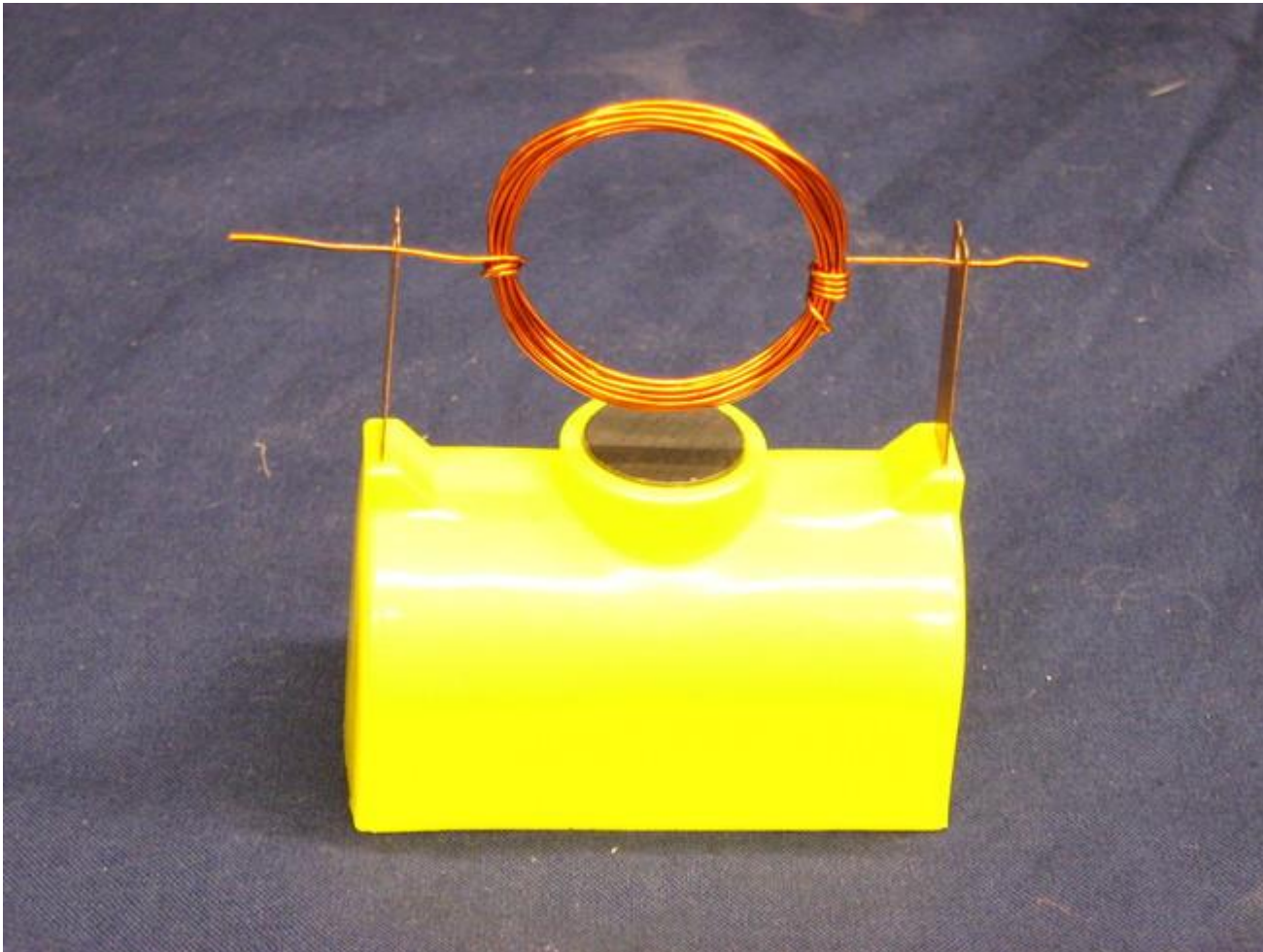
- Biot-Savart Law (like Coulomb's Law for magnetism)
- B-field of a line of current
- Magnetic force between parallel current-carrying wires
- Applying the Biot-Savart Law:
 - Circular arc of current
- Ampère's Law: Like Gauss' Law, but named after Ampère
- Magnetic field of a long wire (inside and outside)

Torque on a current loop

$$\vec{F}_B = i\vec{\ell} \times \vec{B}$$



Demonstration more info



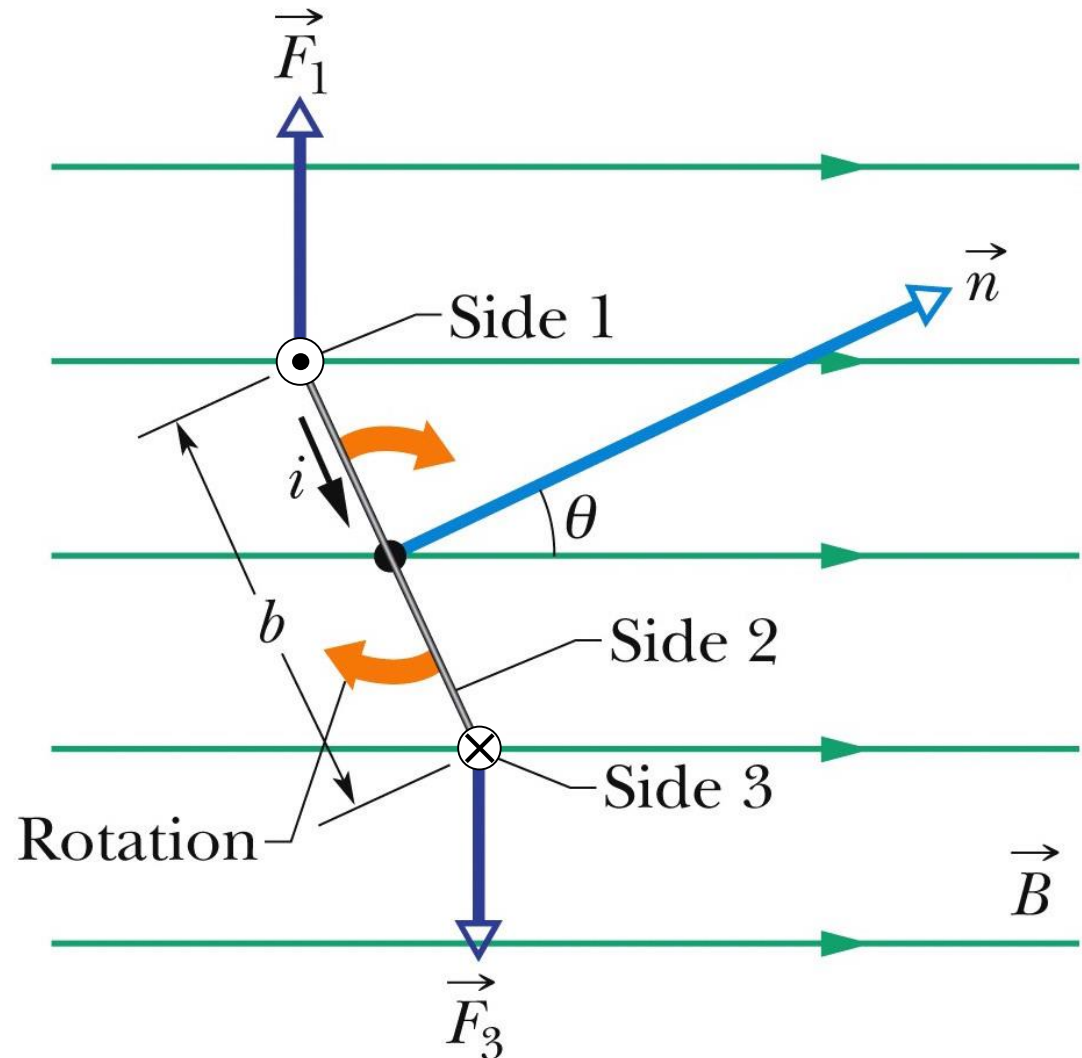
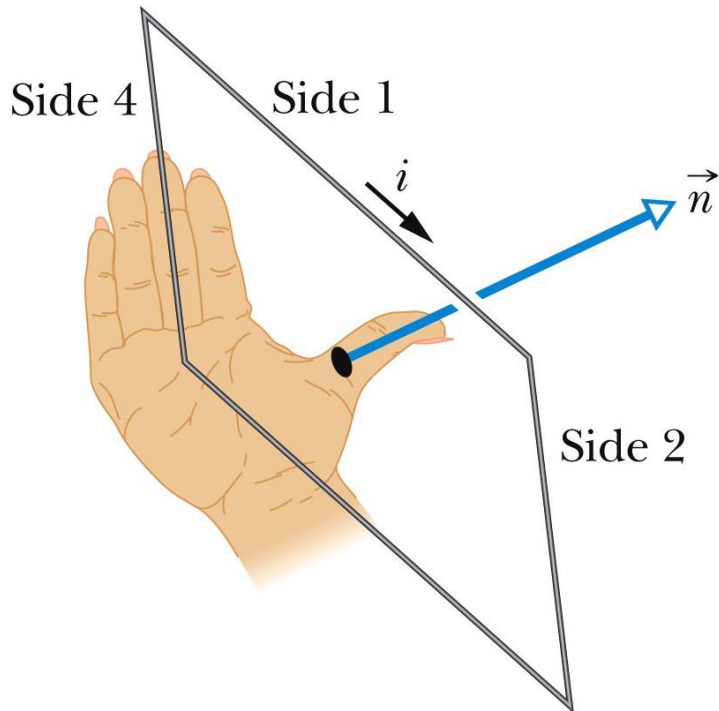
http://www.phas.ucalgary.ca/files/phas/5k40_05_worlds_simplest_motor_pic1.jpg

<https://www.youtube.com/watch?v=LAprCA8QaXA>

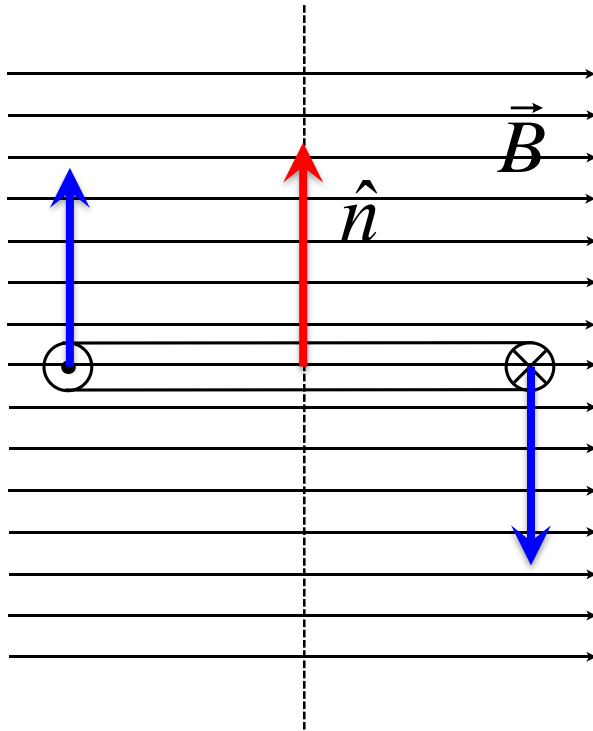
<http://scitoys.com/scitoys/scitoys/electro/electro.html>

Torque on a current loop

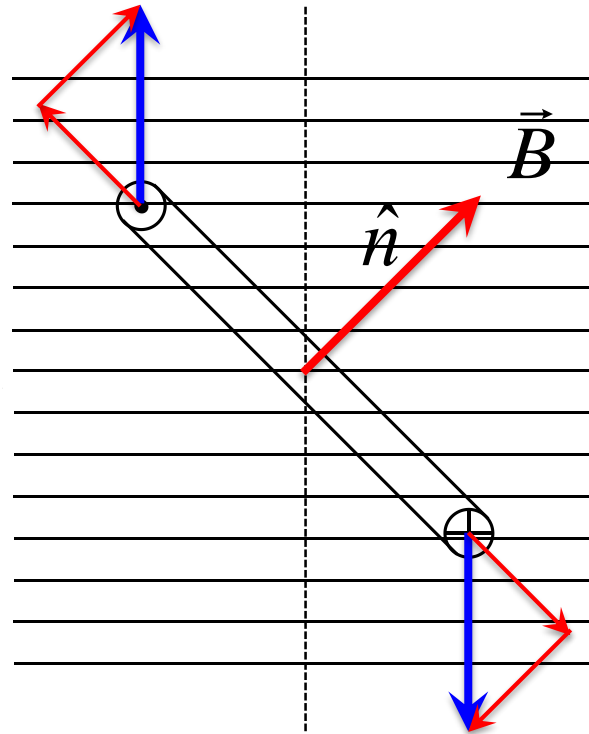
Pick the normal vector to the loop area by RHR: curl your fingers in the direction of i , thumb points in direction of \vec{n}



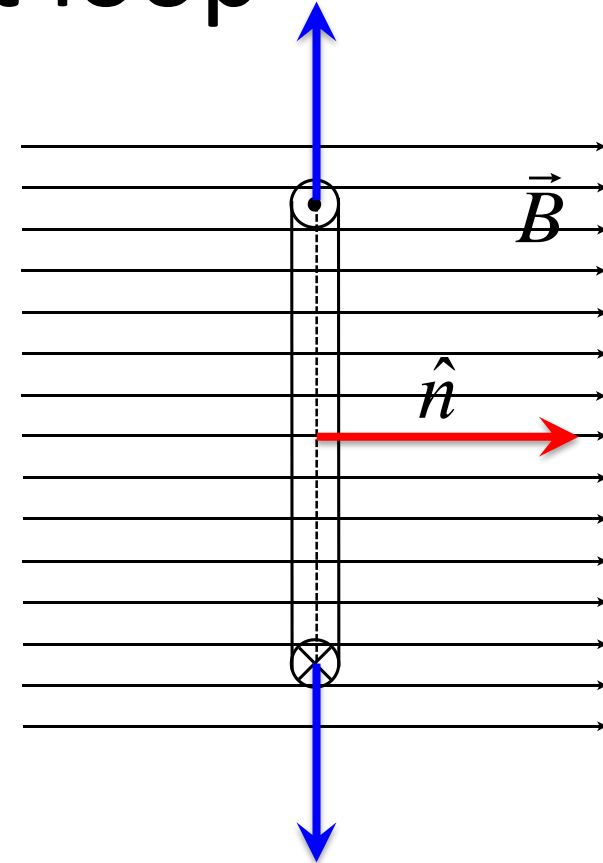
Torque on a current loop



The normal vector is at right angles to the B-field: all magnetic force causes rotation of the loop



The normal vector is at some angle to the B-field: some of the magnetic force causes rotation of the loop



The normal vector is parallel to the B-field: none of the magnetic force causes rotation of the loop

Conclusion: components of magnetic force (anti)parallel to normal vector that cause torque

Magnetic moment

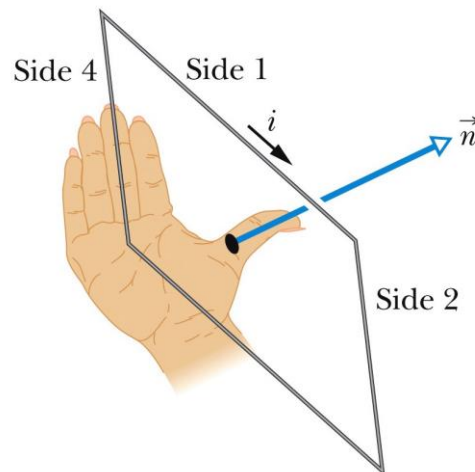
$$\vec{\mu} = I\vec{A}$$

- I is the current, \vec{A} is area vector (magnitude equal to the surface area, direction same as \vec{n})

$$\vec{\tau} = \vec{r} \times \vec{F}$$

$$\vec{\tau} = \vec{\mu} \times \vec{B}$$

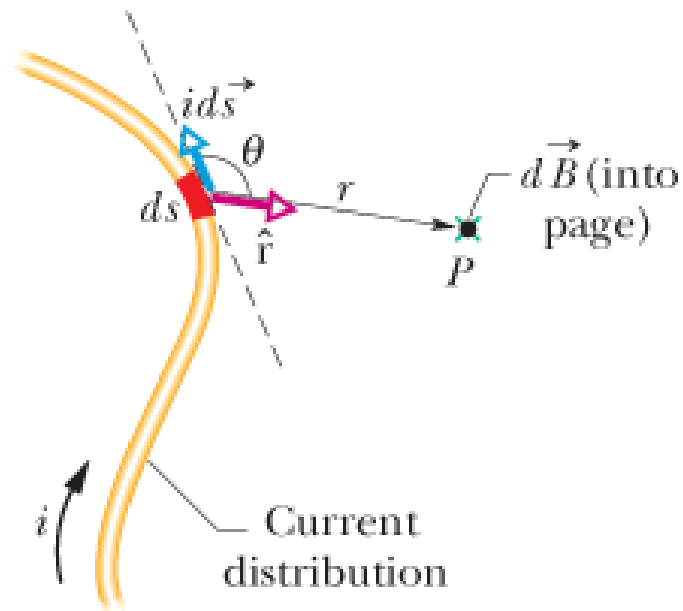
- Labatorial 9



The Biot-Savart Law

(Bee-oh Sah-var)

This element of current creates a magnetic field at P , into the page.



$$d\vec{B} = \frac{\mu_0}{4\pi} \frac{I d\vec{l} \times \hat{r}}{r^2}$$

$$\mu_0 = 4\pi \cdot 10^{-7} \frac{\text{Ns}^2}{\text{C}^2}$$

“Permeability of free space”

Constants of nature

“Permittivity of free space”

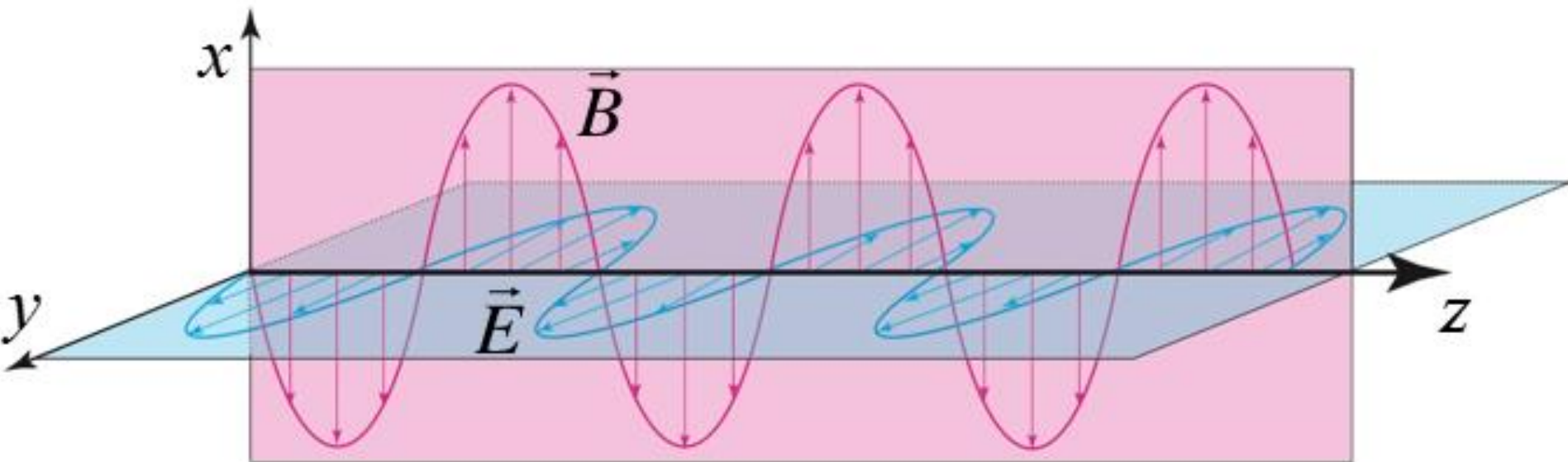
$$\epsilon_0 = 8.85418781719 \times 10^{-12} \frac{C^2}{N \cdot m^2}$$

“Permeability of free space”

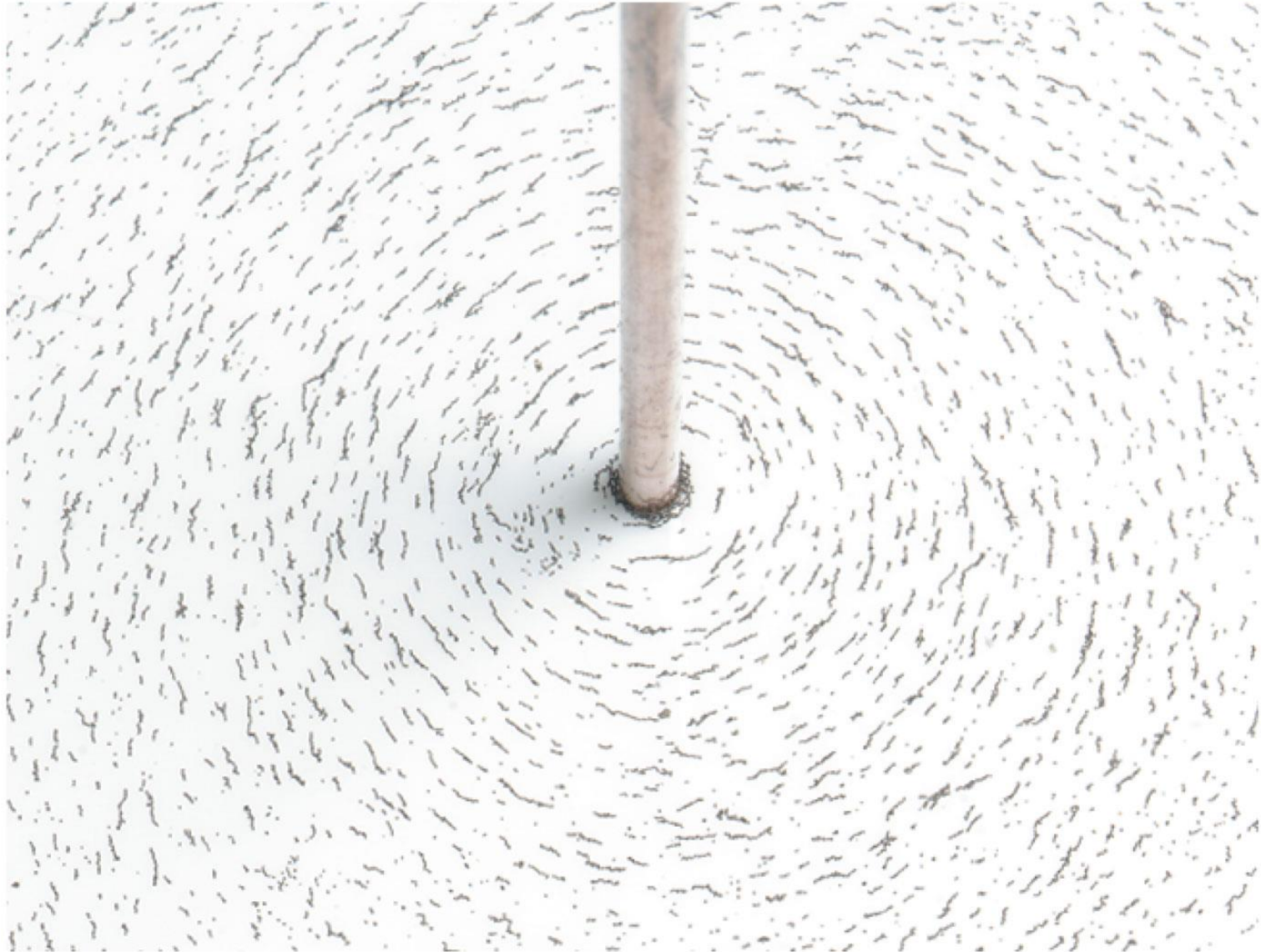
$$\mu_0 = 4\pi \times 10^{-7} \frac{N \cdot s^2}{C^2}$$

$$\frac{1}{\sqrt{\mu_0 \epsilon_0}} = 299,792,458 \text{ m/s}$$

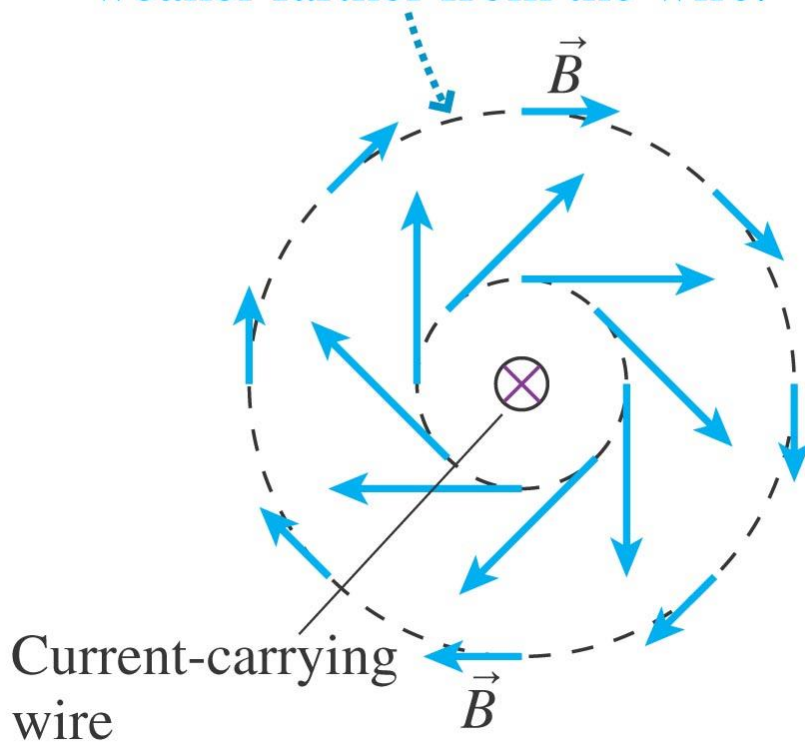
Speed of light!



Magnetic Field of a Long, Straight Wire

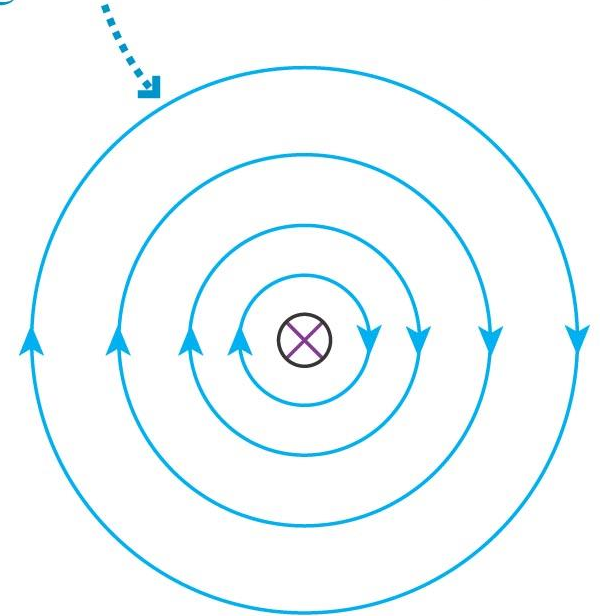


- (a) The magnetic field vectors are tangent to circles around the wire, pointing in the direction given by the right-hand rule. The field is weaker farther from the wire.

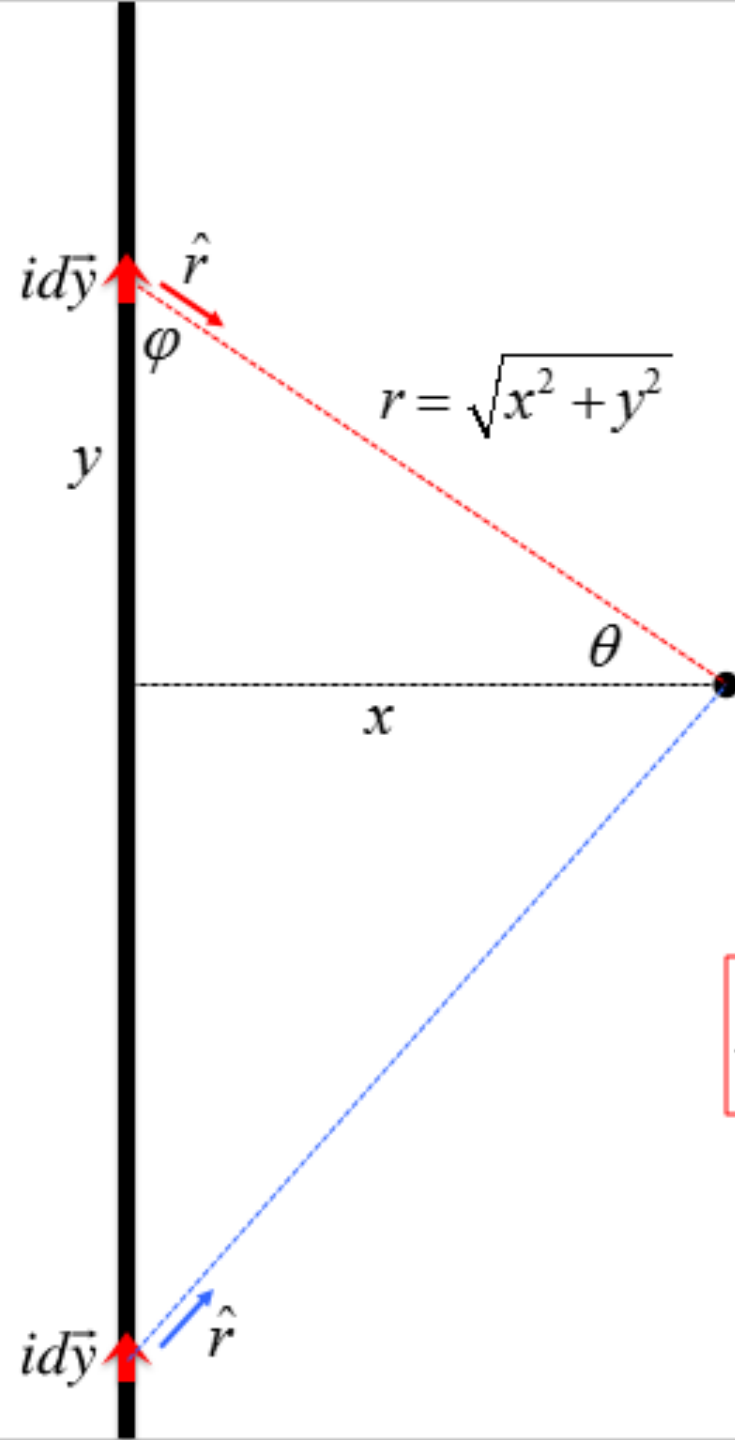


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- (b) Magnetic field lines are circles.



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$$d\vec{B} = \frac{\mu_0}{4\pi} \frac{i d\vec{y} \times \hat{r}}{r^2}$$

$$i d\vec{y} \times \hat{r} = i dy \sin \varphi (-\hat{k}) = -i dy \frac{x}{\sqrt{x^2 + y^2}} \hat{k}$$

$$d\vec{B} = -\frac{\mu_0}{4\pi} \frac{i x dy}{(x^2 + y^2)^{3/2}} \hat{k}$$

All contributions are in the same direction

$$B = \int_{-\infty}^{\infty} \frac{\mu_0}{4\pi} \frac{i x dy}{(x^2 + y^2)^{3/2}}$$

Can just worry about the magnitude

$$B_{\text{wire}} = \frac{\mu_0 i}{2\pi x}$$

Magnetic field strength of a long straight wire. Direction from RHR

Wednesday March 29, 2017
lecture 2

TopHat Question

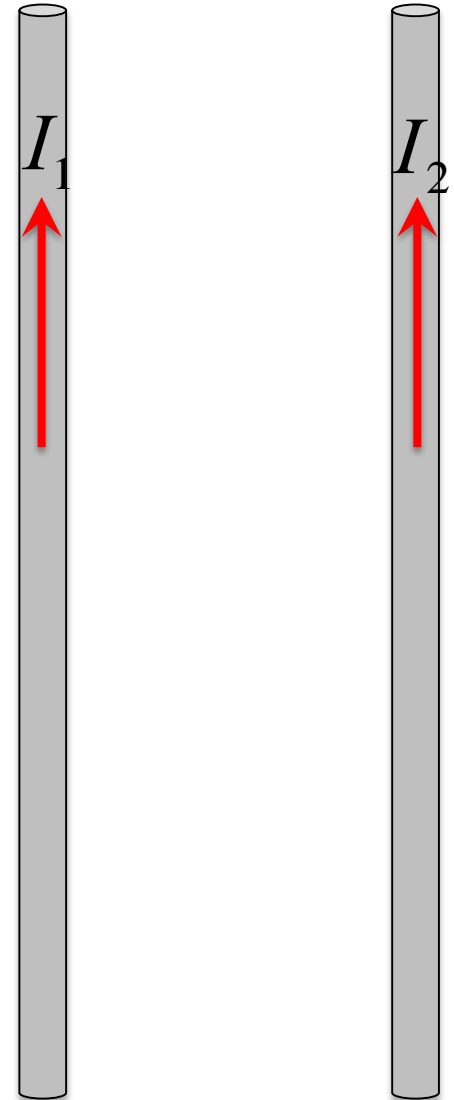
Two wires carry currents I_1 and I_2 as shown. What direction is the magnetic field produced by wire 2 at the location of wire 1?

A. Downward

B. Upward

A. Into the page

A. Out of the page



TopHat Question

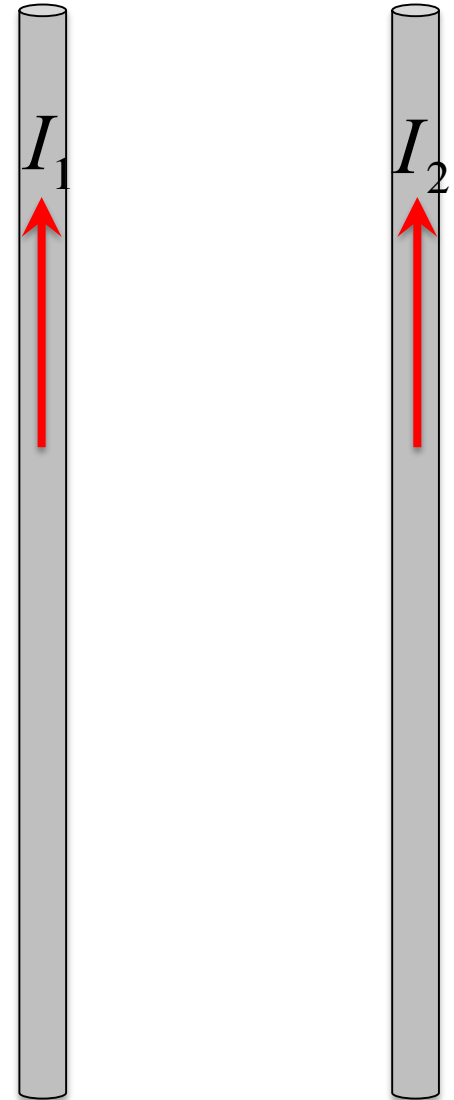
Two wires carry currents I_1 and I_2 as shown. What direction is the force of wire 2 on wire 1?

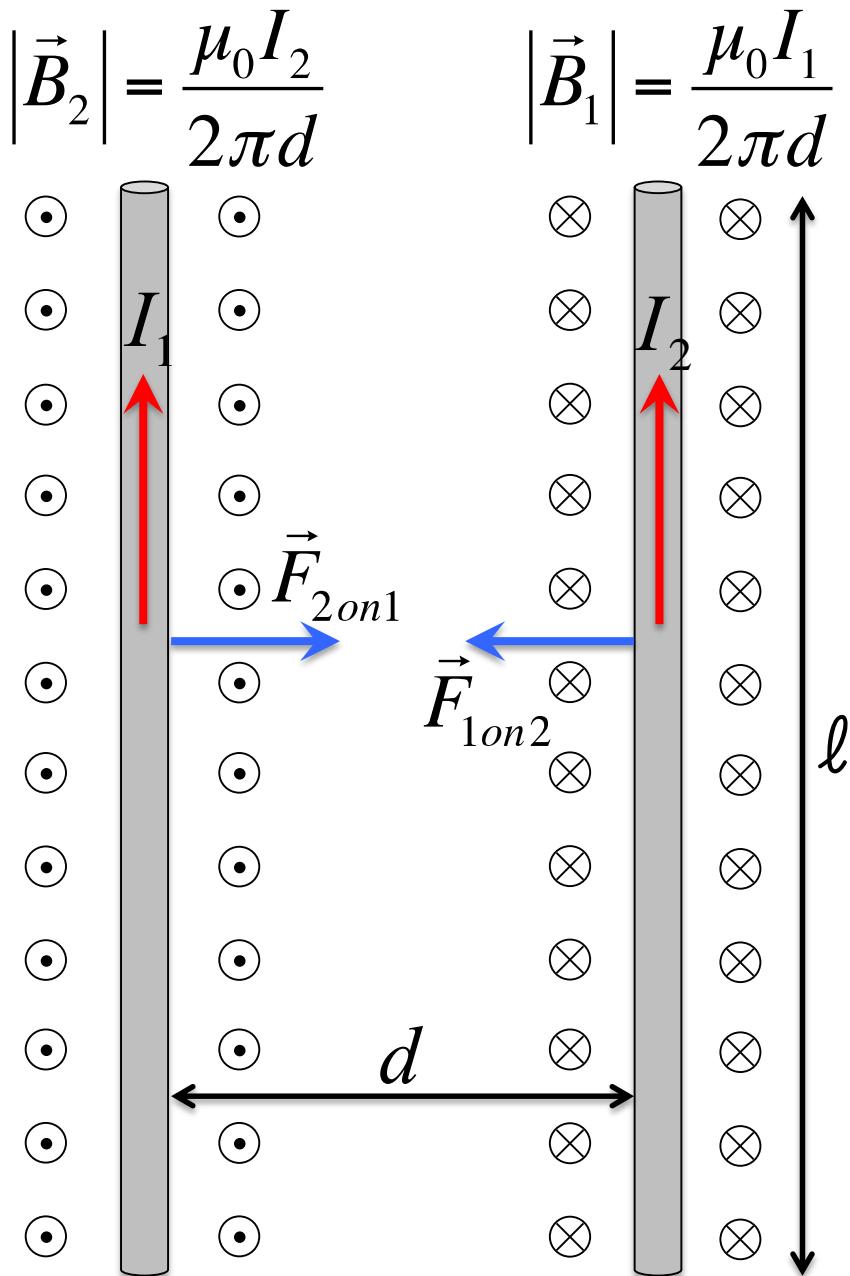
A. Left

A. Right

B. Up

C. Down





Wire 2 exerts a force on wire 1

$$\vec{F}_{2on1} = I_1 \vec{\ell} \times \vec{B}_2$$

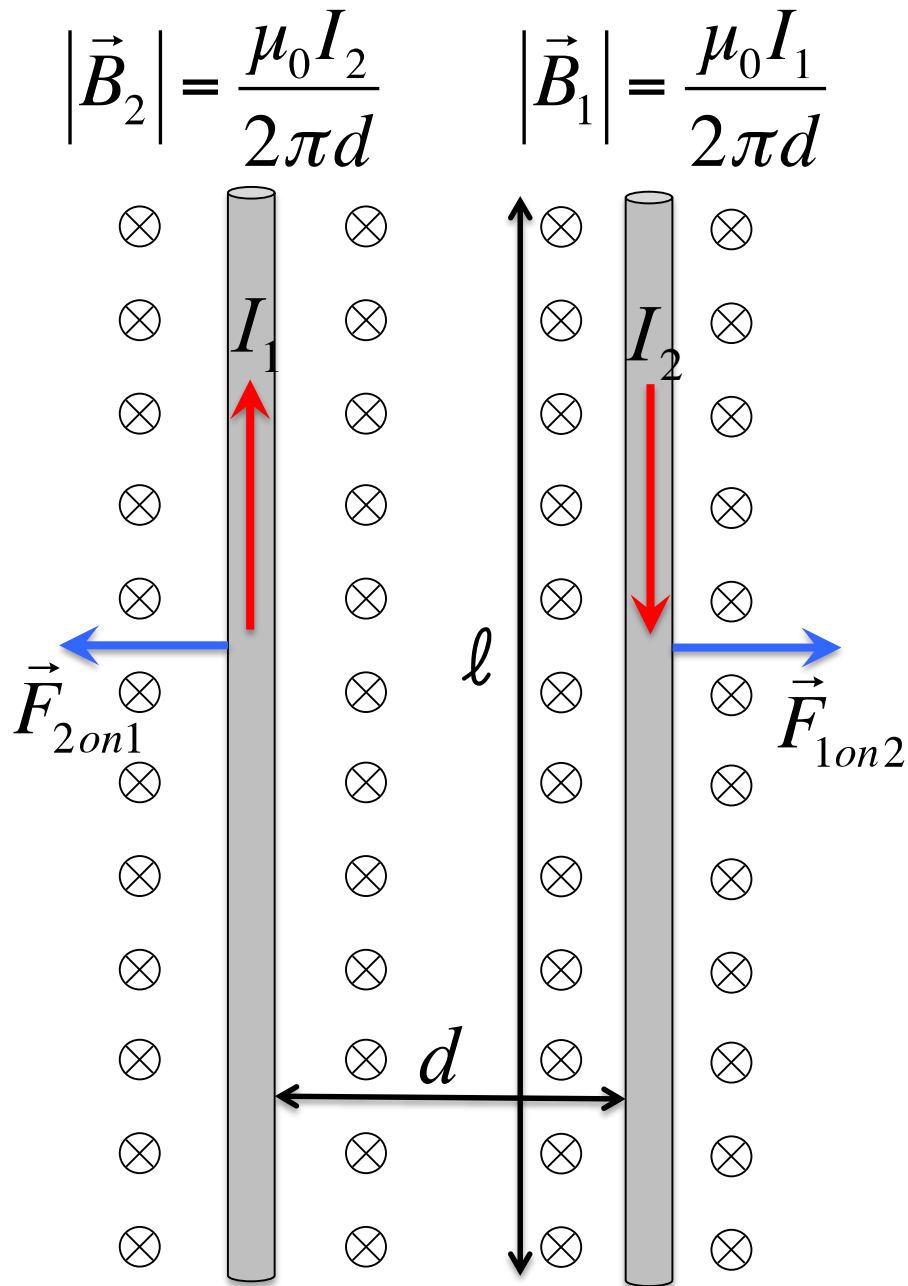
$$|\vec{F}_{2on1}| = I_1 \ell \frac{\mu_0 I_2}{2\pi d} = \boxed{\frac{\mu_0 \ell I_1 I_2}{2\pi d}}$$

Wire 1 exerts a force on wire 2

$$\vec{F}_{1on2} = I_2 \vec{\ell} \times \vec{B}_1$$

$$|\vec{F}_{1on2}| = I_2 \ell \frac{\mu_0 I_1}{2\pi d} = \boxed{\frac{\mu_0 \ell I_1 I_2}{2\pi d}}$$

Newton's third law!



$$|\vec{B}_2| = \frac{\mu_0 I_2}{2\pi d}$$

$$|\vec{B}_1| = \frac{\mu_0 I_1}{2\pi d}$$

Wire 2 exerts a force on wire 1

$$\vec{F}_{2on1} = I_1 \vec{\ell} \times \vec{B}_2$$

$$|\vec{F}_{2on1}| = I_1 \ell \frac{\mu_0 I_2}{2\pi d} = \boxed{\frac{\mu_0 \ell I_1 I_2}{2\pi d}}$$

Wire 1 exerts a force on wire 2

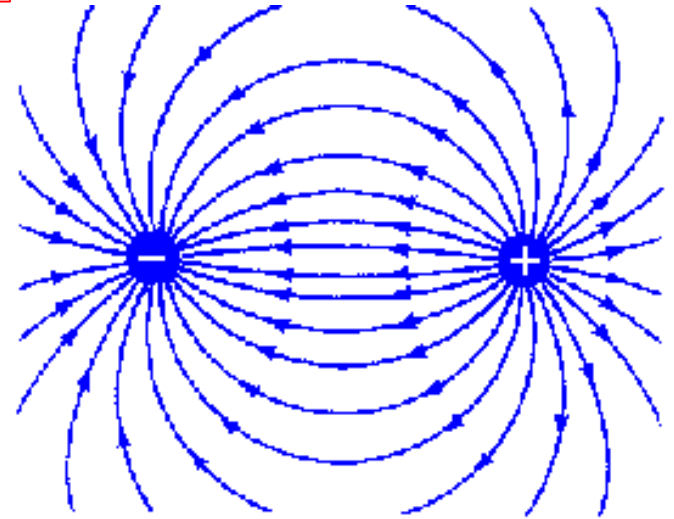
$$\vec{F}_{1on2} = I_2 \vec{\ell} \times \vec{B}_1$$

$$|\vec{F}_{1on2}| = I_2 \ell \frac{\mu_0 I_1}{2\pi d} = \boxed{\frac{\mu_0 \ell I_1 I_2}{2\pi d}}$$

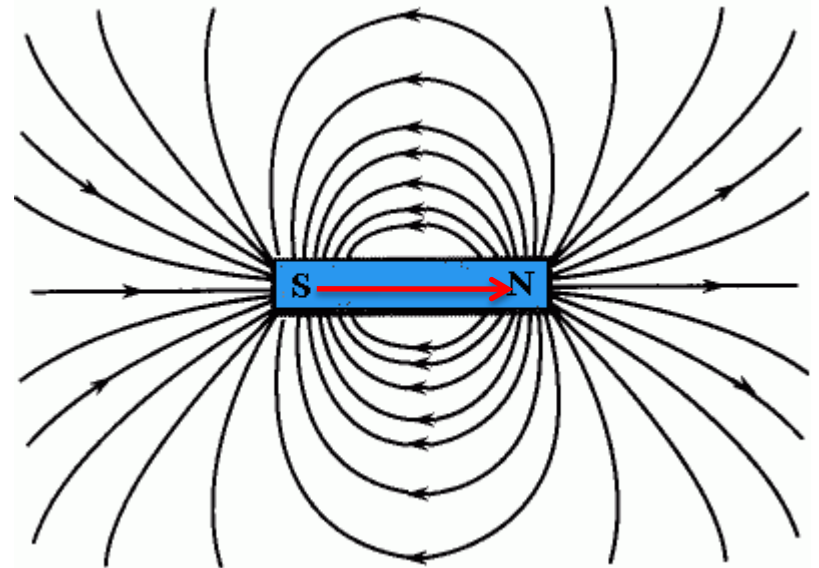
Newton's third law!

Dipole Fields

Electric field from an electric dipole



Magnetic field from a magnetic dipole. **Note** that the magnetic field lines are **continuous** – they do **NOT** stop at the poles!



Both fields have the same shape!

Not a Top Hat Question

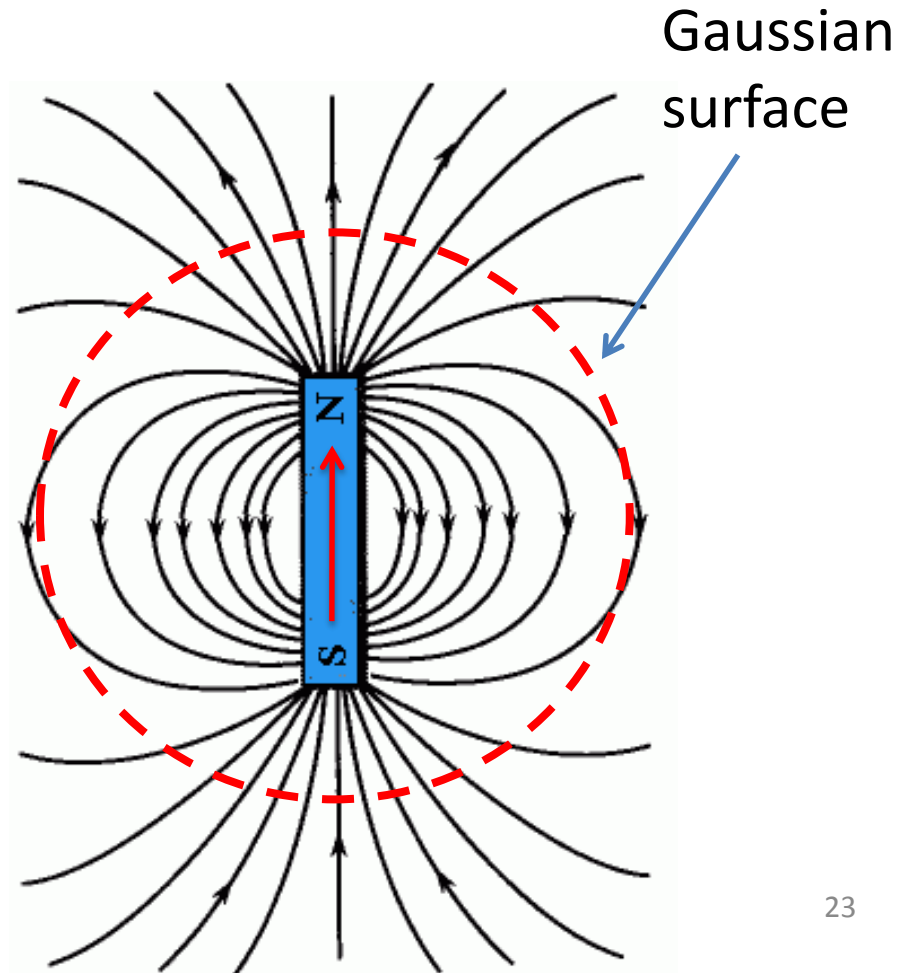
The magnetic field lines from a magnet point out of the North pole and point into the South pole.

What can you say about the magnetic flux passing through this Gaussian surface?

$$\Phi_B = \oint \vec{B} \cdot d\vec{a}$$

- A. Magnetic flux is zero
- B. Magnetic flux is greater than zero
- C. Magnetic flux is smaller than zero
- D. Can't tell without computing the integral

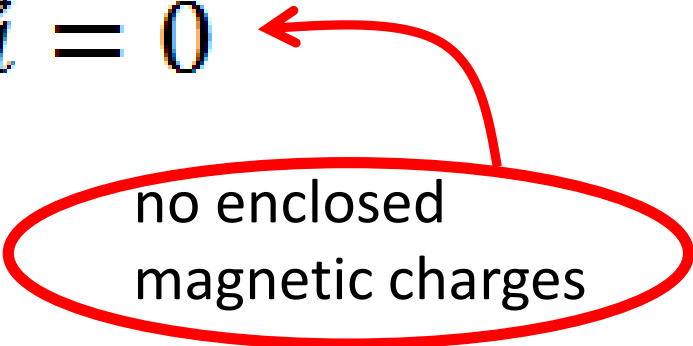
By symmetry the same number of flux lines enter and leave the spherical Gaussian surface



Gauss' Law for Magnetism

The magnetic flux through a closed surface is ALWAYS zero.

$$\Phi_B = \oint \vec{B} \cdot d\vec{a} = 0$$



no enclosed
magnetic charges

There is no way to isolate a North or South magnetic pole

The simplest **E-field** is from a **point charge**, while the simplest **B-field** is from a **magnetic dipole** (e.g. Bar Magnet)

Maxwell's equations

Essentially all of Electricity & Magnetism can be described by a set of 4 equations, referred to as Maxwell's equations.

$$\nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0}$$

$$\nabla \cdot \vec{B} = 0$$

$$\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$\nabla \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

$$c = \frac{1}{\sqrt{\mu_0 \epsilon_0}}$$

We now have **two** of them!

$$\Phi_E = \oint \vec{E} \cdot d\vec{a} = \frac{Q_{encl}}{\epsilon_0}$$

$$\Phi_B = \oint \vec{B} \cdot d\vec{a} = 0$$

$$\oint \vec{E} \cdot d\vec{l} = -\frac{d\Phi_B}{dt}$$

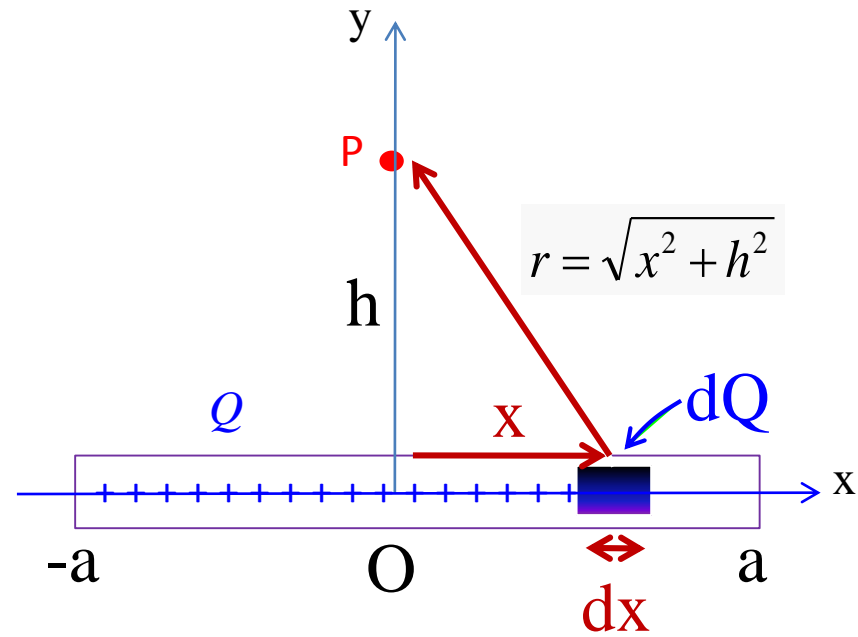
$$\oint \vec{B} \cdot d\vec{l} = \mu_0 i_{encl} + \frac{1}{c^2} \frac{d\Phi_E}{dt}$$

We will learn about these other two Maxwell equations today and next week

Remember this activity?
Solving for E_p for an infinitely long line of charge (i.e. $a \gg h$) using Coulomb's Law was harder than using

GAUSS'S LAW

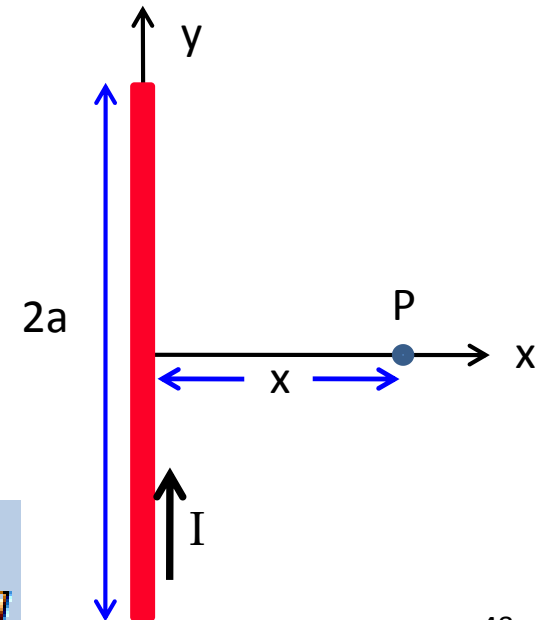
$$\oint \vec{E} \cdot d\vec{a} = \frac{Q_{encl}}{\epsilon_0}$$



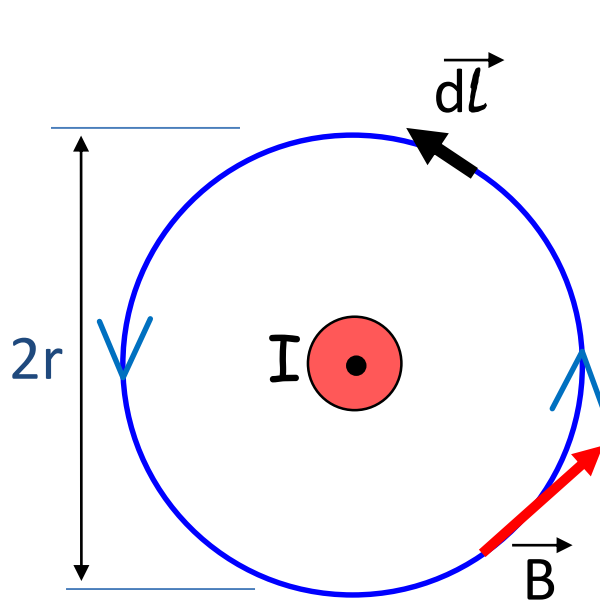
Solving for B_p for an infinitely long current carrying wire (i.e. $a \gg x$) using Biot-Savart's Law was also hard, but there is a MUCH easier alternative!

AMPERE'S LAW

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 i_{encl}$$



Ampère's Law



Suppose we calculate $\oint \vec{B} \cdot d\vec{l}$ around path shown for the simple case of an infinitely long straight line of current

Using our previous result we obtain:

$$B = \frac{\mu_0 I}{2\pi r}$$

$$\oint \vec{B} \cdot d\vec{l} = (2\pi r) \left(\frac{\mu_0 I}{2\pi r} \right)$$

$$\text{i.e. } \oint \vec{B} \cdot d\vec{l} = \mu_0 I_{encl}$$

Ampère's Law is true for any shape of path and any current distribution