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# **POINT PROCESS AND ITS APPLICATION**

## **POINT PROCESS III — HAWKES PROCESSES**

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# review

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1. Density, Survival function, Cumulative Distribution Function and Intensity
2. Likelihood
3. Simulation: inversed method and thinning method

# Survival Analysis

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- $f$  be the **density** function of the inter-event time  $T$
- Cumulative distribution function

$$F(t) = P(T \leq t) = \int_0^t f(\tau) d\tau$$

- The survival function

$$S(t) = 1 - F(t) = P(T > t) = \int_t^{\infty} f(\tau) d\tau$$

- Hazard function (intensity)

$$\lambda(t) = \frac{f(t)}{S(t)} = -\frac{1}{dt} d \log S(t)$$

# Example: homogeneous Poisson Process

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- homogeneous Poisson Process

- density of **inter-event times**  $t$

$$f(t) = \lambda e^{-\lambda t}$$

- Cumulative distribution function

$$F(t) = \int_0^t f(\tau) d\tau = 1 - e^{-\lambda t}$$

- The survival function

$$S(t) = 1 - F(t) = P(T > t) = e^{-\lambda t}$$

- Hazard function (intensity)

$$\lambda(t) = \frac{f(t)}{S(t)} = \lambda$$

# inhomogeneous Poisson Process

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- For inhomogeneous Poisson Process
- Hazard function (intensity)  $\lambda(t)$  only depends on  $t$
- The survival function

$$\lambda(t) = \frac{f(t)}{S(t)} = -\frac{1}{dt} d \log S(t) \rightarrow S(t) = \exp\left(-\int_0^t \lambda(\tau) d\tau\right)$$

- Density and Cumulative distribution function

$$f(t) = \lambda(t)e^{-\int_0^t \lambda(\tau) d\tau} \text{ and } F(t) = 1 - \exp\left(-\int_0^t \lambda(\tau) d\tau\right)$$

- Integrated intensity (intensity measure)

$$\Lambda(t) = \int_0^t \lambda(\tau) d\tau = EN(t)$$

# Conditional intensity function

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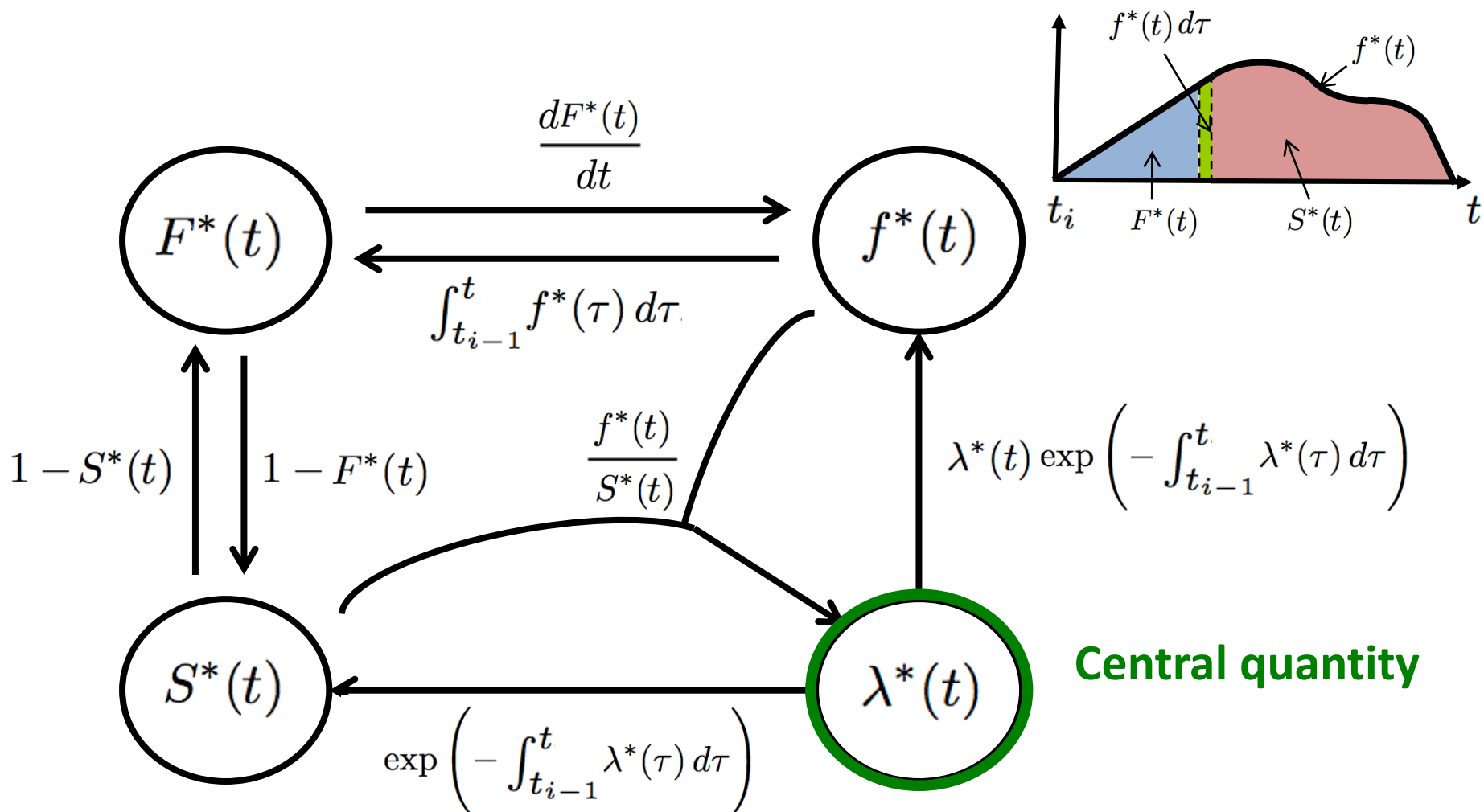
- It turns out the **conditional intensity function** (hazard function) is more convenient and intuitive (think about exponential distribution)
- conditional intensity function:

The difference with  $f(t)$

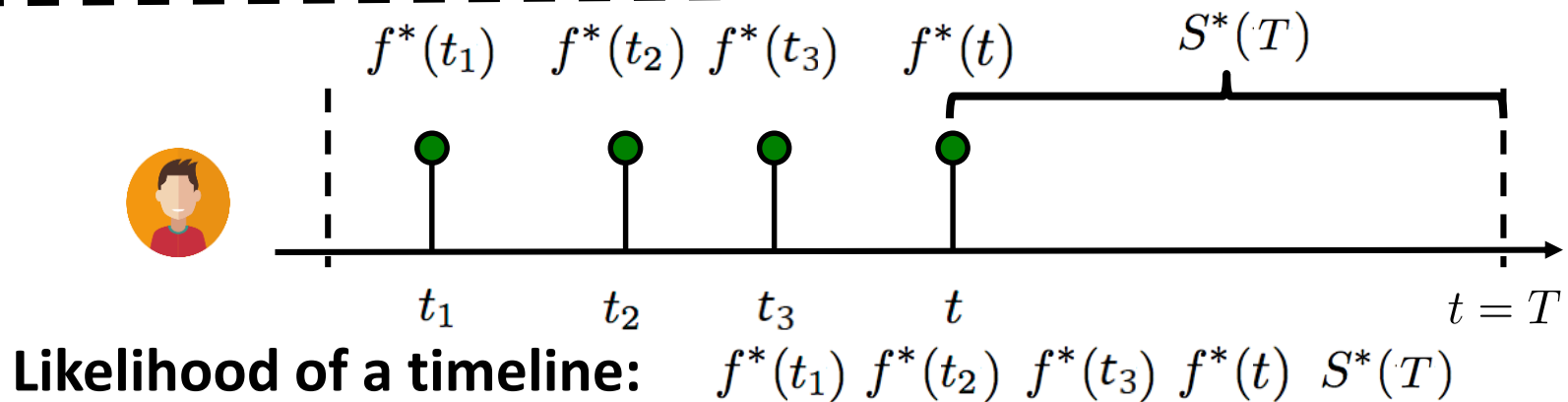
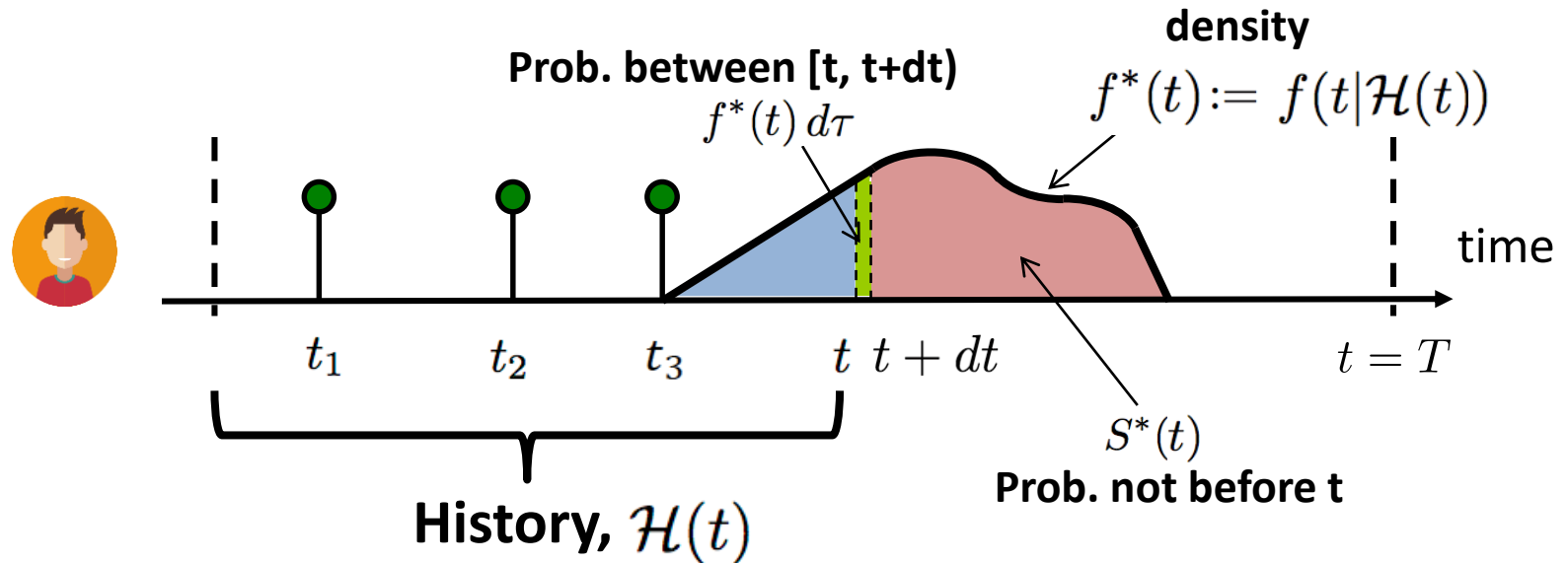
$$\lambda(t|H_{t_n}) = \frac{f(t|H_{t_n})}{1 - F(t|H_{t_n})} = \frac{f^*(t)}{1 - F^*(t)} = \frac{f^*(t)}{S^*(t)}$$

- Notation:  $\lambda^*(t) = \lambda(t|H_{t_n})$
- Derivation:  $\lambda^*(t) = \frac{f^*(t)}{S^*(t)} = \frac{E[N(t, t+dt)|H_t]}{dt}$  the expectation of event number

# Relation between $f^*$ , $F^*$ , $S^*$ , $\lambda^*$



# Density and likelihood





# Likelihood

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let  $t_1 < t_2 < \dots < t_{n-1} < t_n$ , be the event times observed over  $[0, T]$ , use factorization, we can get the likelihood

$$\begin{aligned} L &= f^*(t_1) \cdot f^*(t_2) \cdot \dots \cdot f^*(t_n) \cdot S^*(T) \\ &= \left( \prod_{i=1}^n \lambda^*(t_i) \cdot \exp \left( - \int_{t_{i-1}}^{t_i} \lambda^*(s) ds \right) \right) \cdot \exp \left( - \int_{t_n}^T \lambda^*(s) ds \right) \\ &= \left( \prod_{i=1}^n \lambda^*(t_i) \right) \cdot \exp \left( - \int_0^T \lambda^*(s) ds \right) \end{aligned}$$

# Simulation—the inversed method

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- Algorithm 1. The inverse method algorithm
- 1. set  $t = 0$ ,  $t_0 = 0$ ,  $s_0 = 0$ ,  $i = 1$
- 2. while *true*:
  - (i) generate  $U \sim \text{Uniform}([0,1])$
  - (ii) calculate  $\tau_i = -(\log U)/\lambda$
  - (iii) set  $s_i = s_{i-1} + \tau_i$
  - (iv) calculate  $t$  where  $t = \Lambda^{*-1}(s_n)$
  - (v) if  $t < T$  :  $i = i + 1, t_i = t$  else break
- Output: Retrieve the simulated process  $\{t_n\}$  on  $[0, T]$

# Simulation—thinning method

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- ▶ Algorithm 2. Ogata's modified thinning algorithm
- ▶ 1. set  $t = 0$ ,  $i = 1$
- ▶ 2. while  $t \leq T$ :
  - ▶ (i) calculate  $m(t), l(t)$
  - ▶ (ii) generate  $U \sim \text{Unif}([0,1])$  then set  $s = -(\log U)/\lambda$   
and generate  $U' \sim \text{Unif}([0,1])$
  - ▶ (iii) if:  $s > l(t)$ , set  $t = t + l(t)$
  - ▶ (iv) elif:  $t + s > T$  or  $U' > \lambda^*(t + s)/m(t)$ , set  $t = t + s$
  - ▶ (v) else: set  $n = n + 1$ ,  $t_n = t + s$ ,  $t = t + s$
- ▶ Output: Retrieve the simulated process  $\{t_n\}$  on  $[0, T]$

# outline

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1. Introduction
2. One-dimensional Hawkes Process
3. Multi-dimensional Hawkes Process
4. Marked Hawkes Processes

# Event data for point process

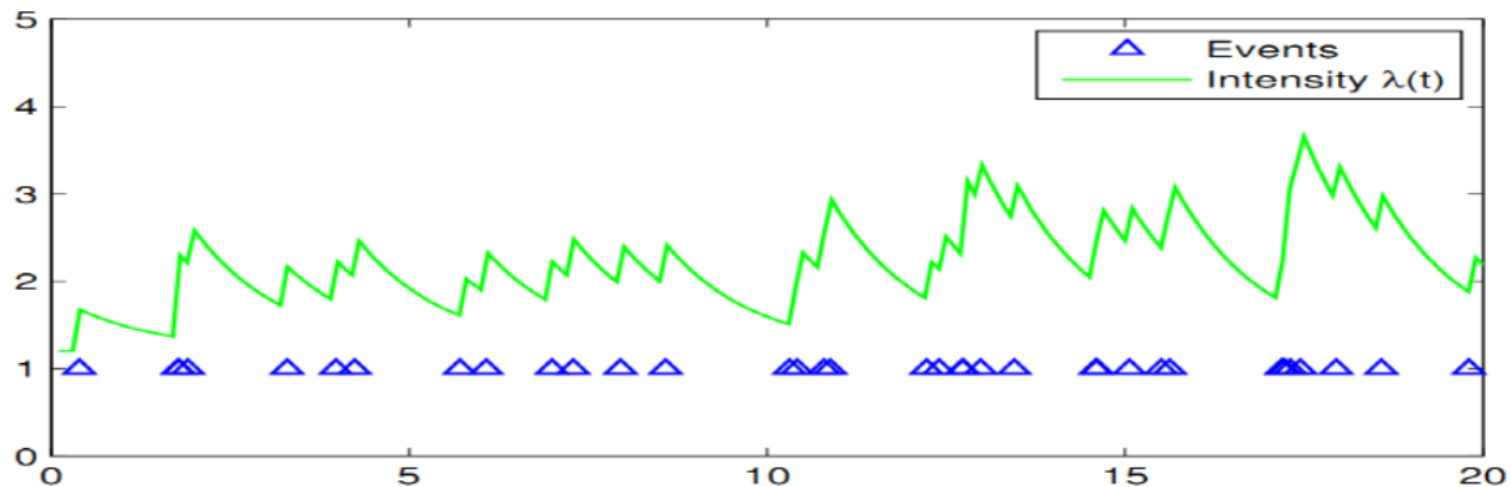
- **Temporal events:** occurrences of events over time

$$t_1 < t_2 < \dots < t_{n-1} < t_n$$

usually recorded over an observation window  $[0, T]$

- **Conditional Intensity function:**

$$\lambda^*(t) = \lambda(t|H_{t_n}) = \frac{f^*(t)}{1 - F^*(t)} = \frac{dE[N(t+h) - N(t)|H_t]}{dh}$$



# temporal point process

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- **Counting process** : Given  $T_1 < T_2 < \dots T_{n-1} < T_n$  , define counting process

$$N(t) = \sum 1_{T_i < t}$$

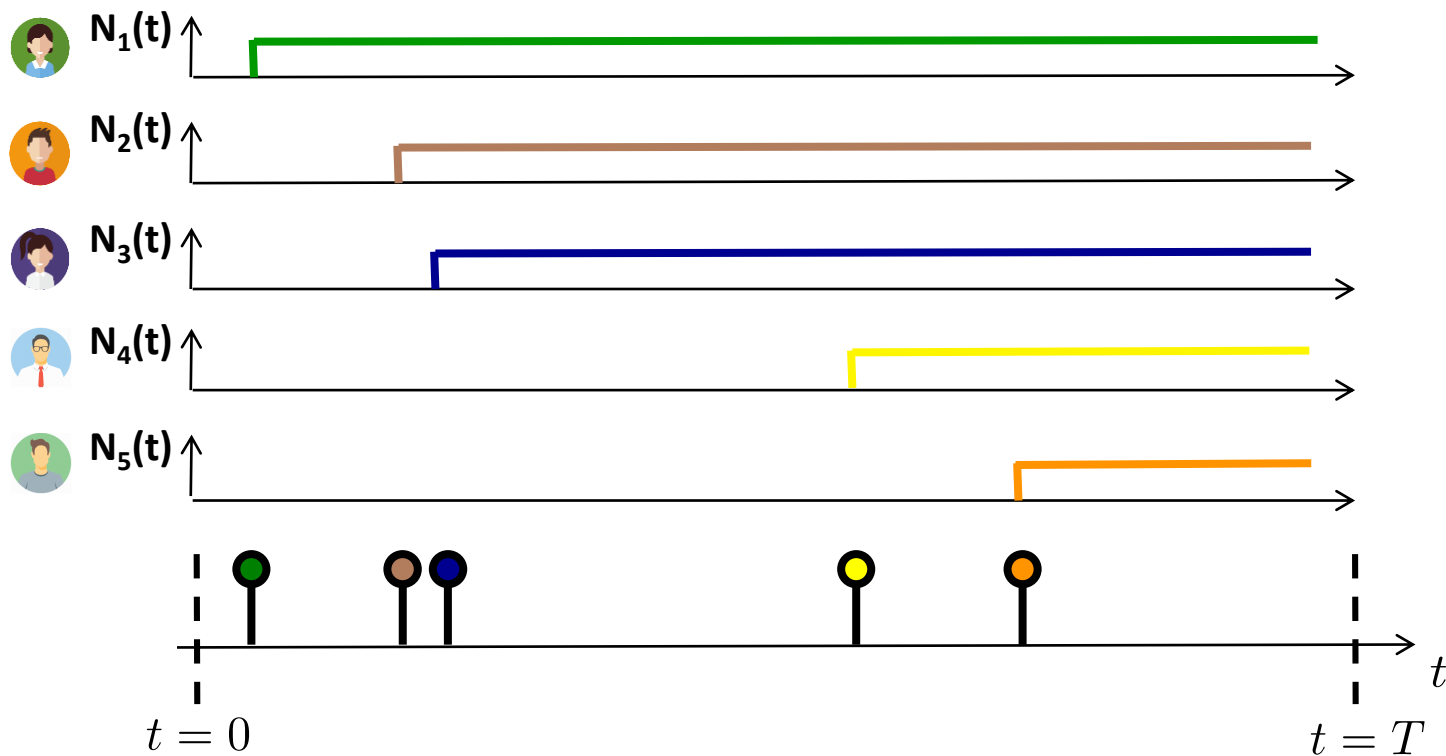
Right continuous and monotonous without decrement

- **Multi-dimensional point process**

event data:  $\{(t_i^m)_i\}_{m=1}^M$  or  $\{(t_1, u_1), (t_2, u_2), \dots, (t_n, u_n)\}$

associated counting process  $N(t) = (N_1(t), N_2(t), \dots, N_m(t))$  as M-dimensional point process

# Multi-dimensional point process



# Hawkes process

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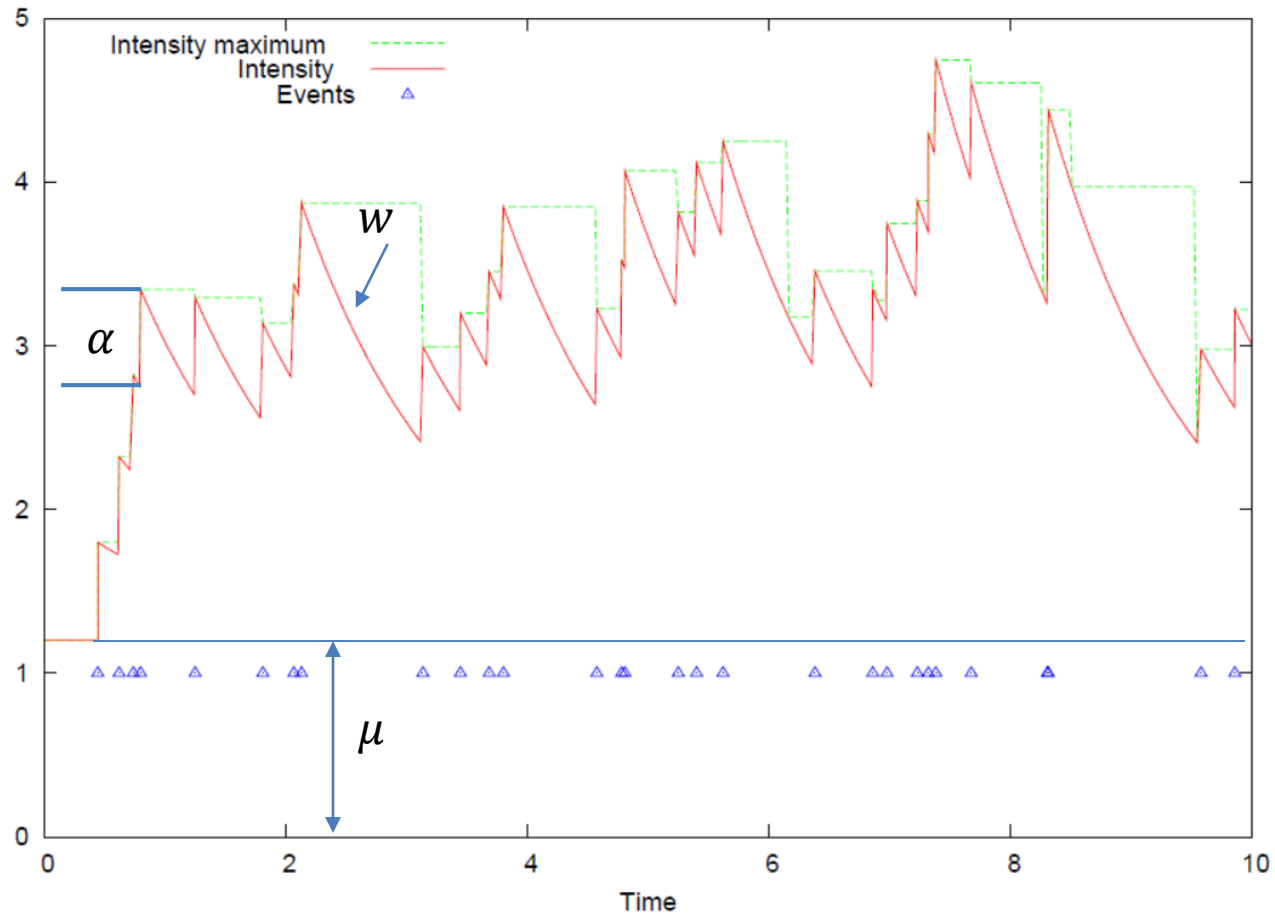
- ▶ conditional intensity function of Hawkes process:  
given  $t_1 < t_2 < \dots < t_n$  in the window  $[0, T]$

$$\lambda(t) = \mu + \alpha \sum_{t_i < t} \exp(-w(t - t_i))$$

- ▶  $\mu, \alpha$  are positive parameters.
- ▶ the conditional intensity grows by  $\alpha$  and decreases exponentially back towards  $\mu$



# Explanations of the parameters



# Hawkes process

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- More general formulation (1):

$$\lambda(t) = \mu + \alpha \sum_{t_i < t} g(t - t_i)$$

- $\mu, \alpha$  are positive parameters and  $g(t)$  is the decaying kernel, for example  $g(t) = \omega e^{-\omega t}$

- More general formulation (2):

$$\lambda(t) = \mu(t) + \alpha \sum_{t_i < t} g(t - t_i)$$

- $\mu$  is time-dependent and  $\mu: R_+ \rightarrow R_+$

# Hawkes process

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- More general formulation (3):

$$\lambda(t) = \mu(t) + \sum_{t_i < t} \gamma(t - t_i)$$

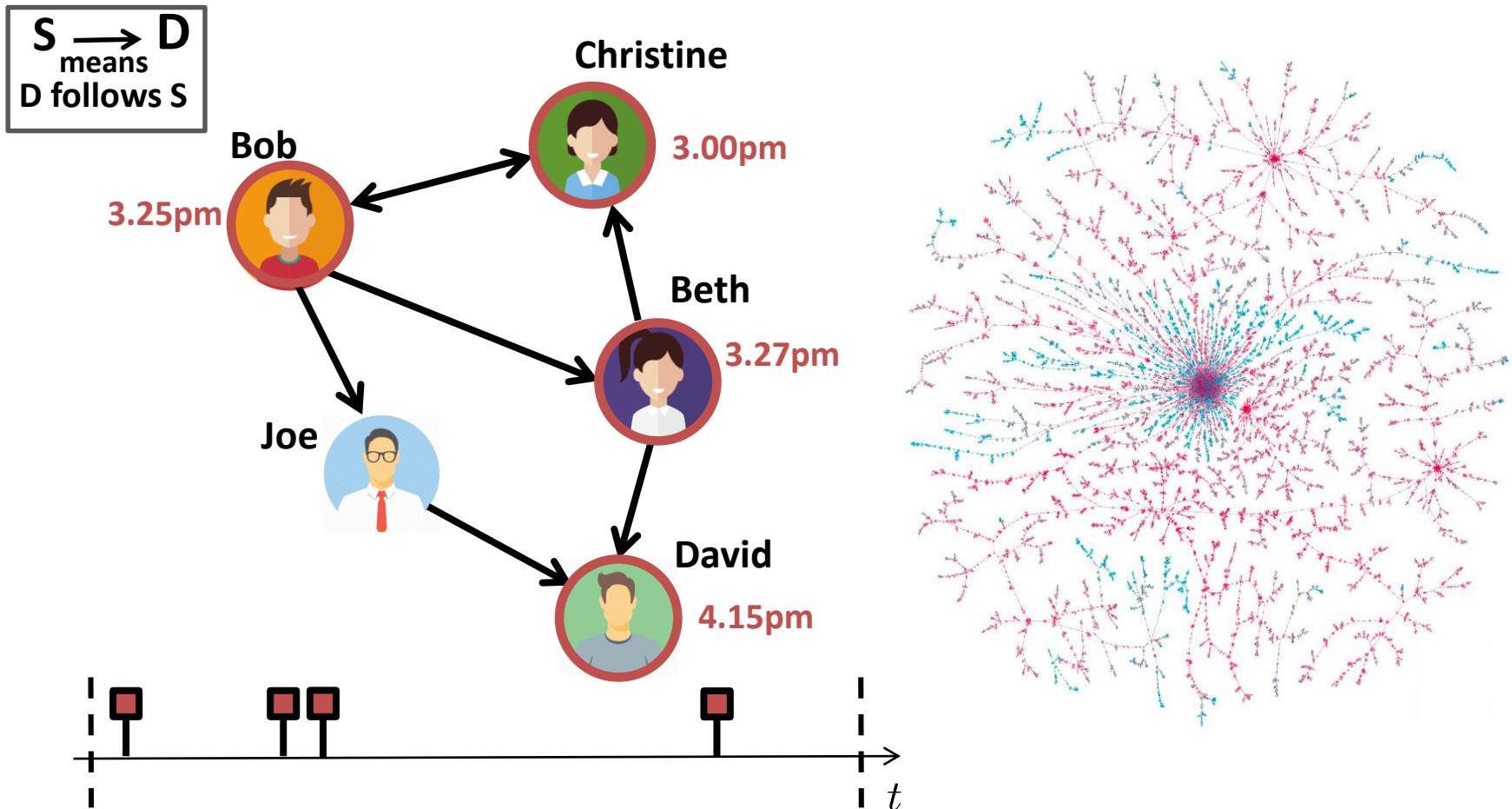
- $\mu: R \rightarrow R_+$  is a deterministic base intensity, for example,  $\mu(t) = \mu$  or  $\mu(t) = \mu e^{-\omega t} + \mu_0$
- $\gamma: R_+ \rightarrow R_+$  expresses the positive influence of the past events  $t_i$  on the current value of the intensity process. For example,  $\gamma(t) = \sum_{j=1}^P \alpha_j e^{-\beta_j t} \cdot 1_{R^+}$ .

# Multi-dimensional Hawkes process

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- Intensity of multi-dimensional Hawkes process: given event data  $\{(t_i^m)_i\}_{m=1}^M$ 
$$\lambda_u(t) = \mu_u + \sum_{n=1}^M \sum_{t_i^n < t} \alpha_{uu_i} g(t - t_i^n)$$
- where  $\mu_u \geq 0$  is the base intensity for the  $u$ -th Hawkes process
- The coefficient  $\alpha_{uu'}$  captures the mutually exciting property between the  $u$ -th and the  $u'$ -th dimension. It shows how much influence the events in  $u'$ -th process have on future events in the  $u$ -th process.

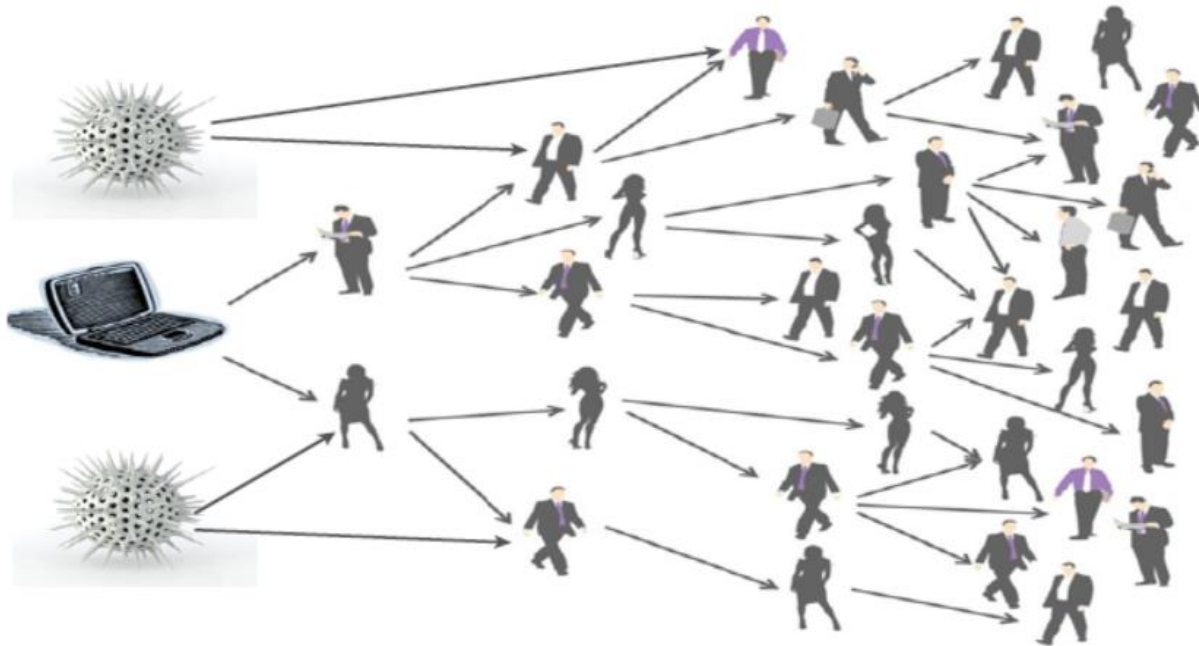
# Application: Information propagation in Social Networks



# Application : Information propagation in Social Networks

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- Multiple memes are evolving and spreading through the same network
- Explore the content of the information diffusing through a network
- Simultaneous diffusion network inference and meme tracking



# outline

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1. Introduction
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# One-dimensional Hawkes Process

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- Definition of One-dimensional Hawkes processes
- (also called self-exciting process)
- Intensity:

$$\lambda(t) = \mu(t) + \int_{-\infty}^t \gamma(t-s) dN_s = \mu(t) + \sum_{t_i < t} \gamma(t-t_i)$$

where  $\mu: R \rightarrow R_+$  is a deterministic base intensity and  $\gamma: R_+ \rightarrow R_+$  expresses the positive influence of the past events  $t_i$  on the current value of the intensity process.



# One-dimensional Hawkes Process

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- given an exponential kernel  $\gamma(t) = \sum_{j=1}^P \alpha_j e^{-\beta_j t} \cdot 1_{R^+}$

$$\begin{aligned}\lambda(t) &= \mu(t) + \int_{-\infty}^t \sum_{j=1}^P \alpha_j e^{-\beta_j(t-s)} dN_s \\ &= \mu(t) + \sum_{t_i < t} \sum_{j=1}^P \alpha_j e^{-\beta_j(t-t_i)}\end{aligned}$$

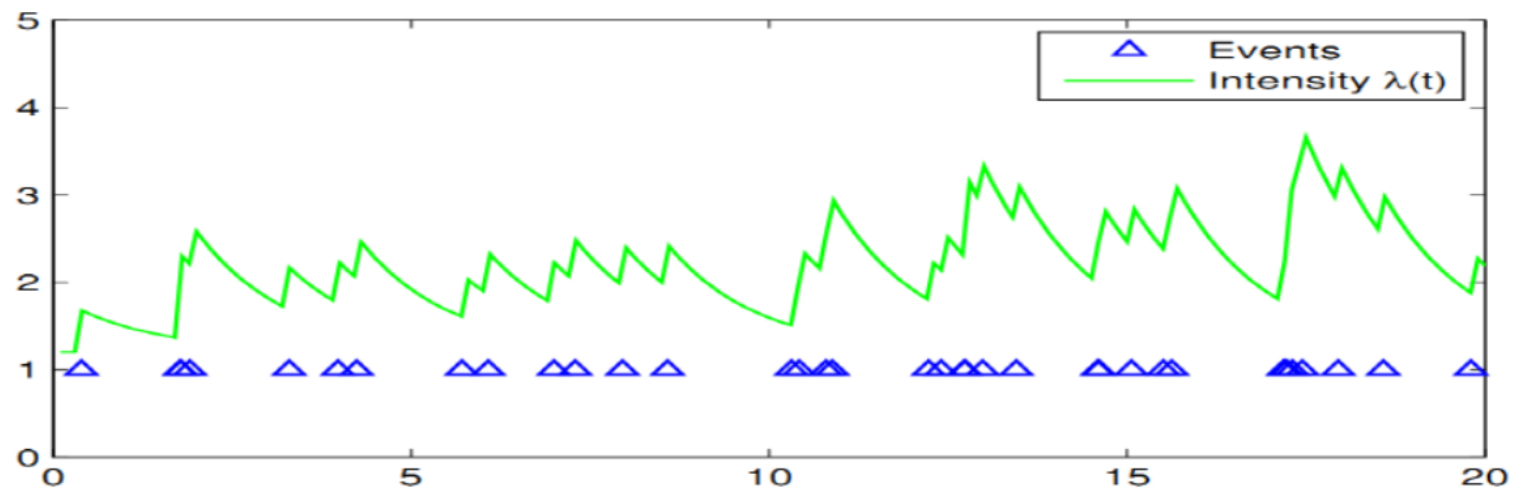
where  $\alpha_j, \beta_j$  are positive parameters

# One-dimensional Hawkes Process

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- The simplest version with  $P = 1$  and  $\mu(t) = \mu$  constant

$$\begin{aligned}\lambda(t) &= \mu + \int_{-\infty}^t \alpha e^{-\beta(t-s)} dN_s \\ &= \mu + \sum_{t_i < t} \alpha e^{-\beta(t-t_i)}\end{aligned}$$



# Stationarity of One-dimensional Hawkes Process

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Assuming stationarity gives  $E[\lambda(t)] = m$  constant.

Thus,

$$\begin{aligned} m = E[\lambda(t)] &= E \left[ \mu + \int_{-\infty}^t \gamma(t-s) dN_s \right] \\ &= \mu + E \left[ \int_{-\infty}^t \gamma(t-s) \lambda(s) ds \right] \\ &= \mu + \int_{-\infty}^t \gamma(t-s) \cdot m \cdot ds \\ &= \mu + m \int_0^{\infty} \gamma(v) dv \end{aligned}$$

# Stationarity of One-dimensional Hawkes Process

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So we can get the **stationarity** that

$$m = \frac{\mu}{1 - \int_0^\infty \gamma(v) dv}$$

When  $\gamma(t) = \sum_{j=1}^P \alpha_j e^{-\beta_j t} \cdot 1_{R^+}$ , so that

$$\lambda(t) = \mu(t) + \sum_{t_i < t} \sum_{j=1}^P \alpha_j e^{-\beta_j(t-t_i)}$$

So the stationarity is

$$m = \frac{\mu}{1 - \int_0^\infty \gamma(v) dv} = \frac{\mu}{1 - \sum_{j=1}^P \frac{\alpha_j}{\beta_j}} > 0$$

# Stationarity of One-dimensional Hawkes Process

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**Stationarity condition** for a 1D-Hawkes process

$$\sum_{j=1}^P \frac{\alpha_j}{\beta_j} < 1$$

for the one-dimensional Hawkes process with  $P = 1$  the unconditional expected value of the intensity process is :

$$E[\lambda(t)] = \frac{\mu}{1 - \alpha/\beta}$$

## Ogata's modified thinning method for 1D-Hawkes process

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- a thinning algorithm based on simulating homogeneous Poisson processes with too high intensities and then thin out the points
- at time  $t$ , find next point  $t_i > t$
- Simulate a homogeneous Poisson process on interval  $[t, t + l(t)]$  for some chosen function  $l(t)$
- high constant intensity on  $[t, t + l(t)]$  that fullfills

$$m(t) \geq \sup_{s \in [t, t + l(t)]} (\lambda^*(s))$$

# Ogata's modified thinning method for 1D-Hawkes process

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- ▶ 1D-Hawkes process, for example

$$\lambda(t) = \mu + \sum_{t_i < t} \alpha e^{-\beta(t-t_i)}$$

- ▶  $\lambda(t)$  monotonous with decrement before next point
- ▶ so  $l(t) = +\infty$
- ▶  $m(t)$  right continuous and piecewise function

# Simulation algorithm

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- ① Initialization:  $t = 0, n = 0, m(t) = \lambda(0)$
- ② First event:
  - (1) generate  $V \sim \text{Uniform}([0,1])$ ,  $t \sim \text{Exp}(m(t))$  (i.e.  $t \leftarrow -\frac{1}{m(t)} \log V$ )
  - (2) if:  $t < T$ :  $t_1 \leftarrow t, n += 1$
  - (3) else: go to last step (empty)
- ③ While  $t \leq T$ : (General routine)
  - (1) Update maximum intensity  $m(t) = \lambda(t_n) + \alpha$ ,  $\alpha$  a jump size
  - (2) generate  $s \sim \text{Exp}(m(t))$  and  $U \sim \text{Uniform}([0,1])$
  - (3) if:  $t + s > T$  or  $U > \lambda^*(t + s)/m(t)$ , let  $t = t + s$
  - (5) else:  $n = n + 1, t_n = t + s, t = t + s$
- ④ Retrieve the simulated process  $\{t_1, t_2, t_3, \dots, t_n\}$  on  $[0, T]$



# Examples of simulations

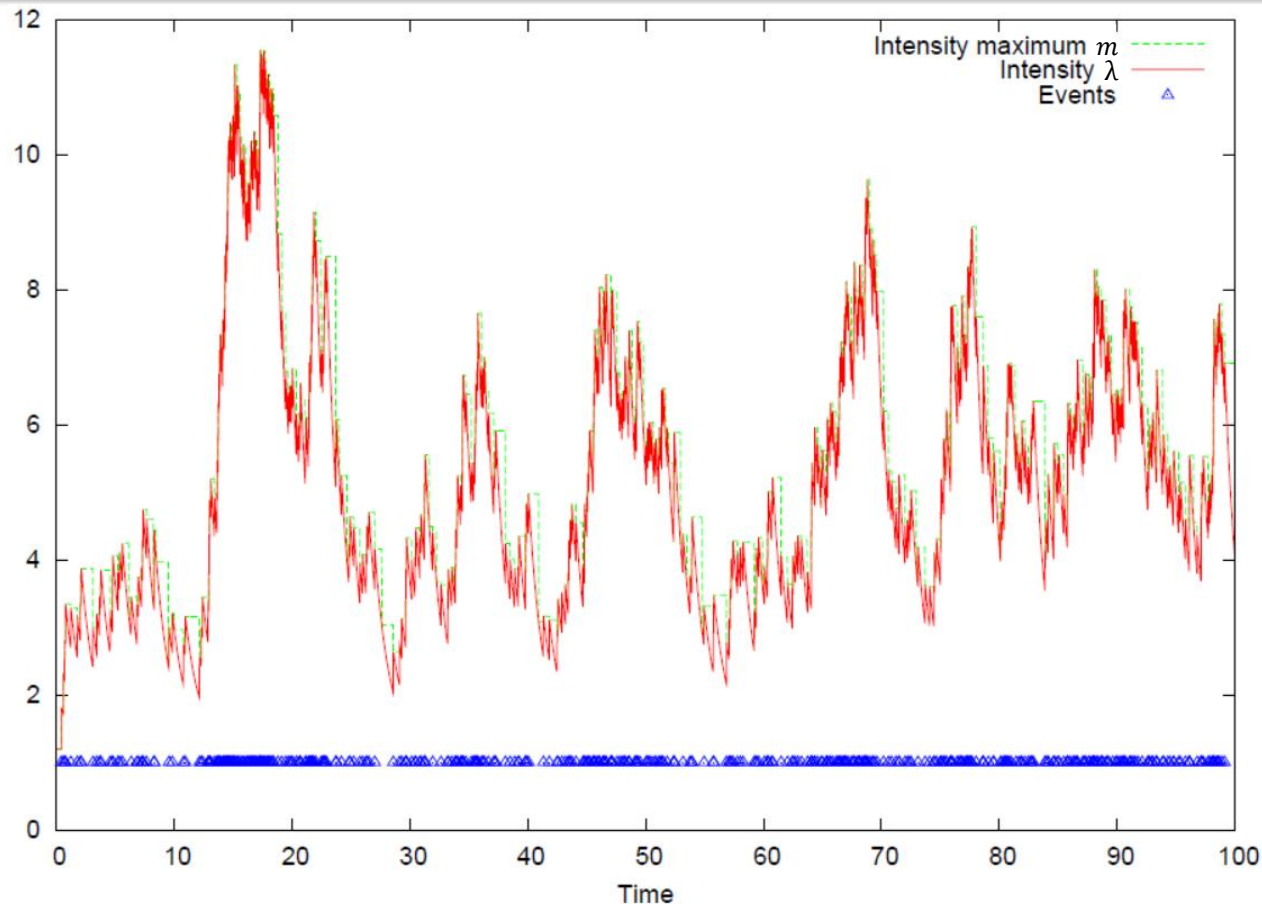


Figure: Simulation of a one-dimensional Hawkes process with parameters  $P = 1, \lambda_0 = 1.2, \alpha_1 = 0.6, \beta_1 = 0.8$ .

# Examples of simulations

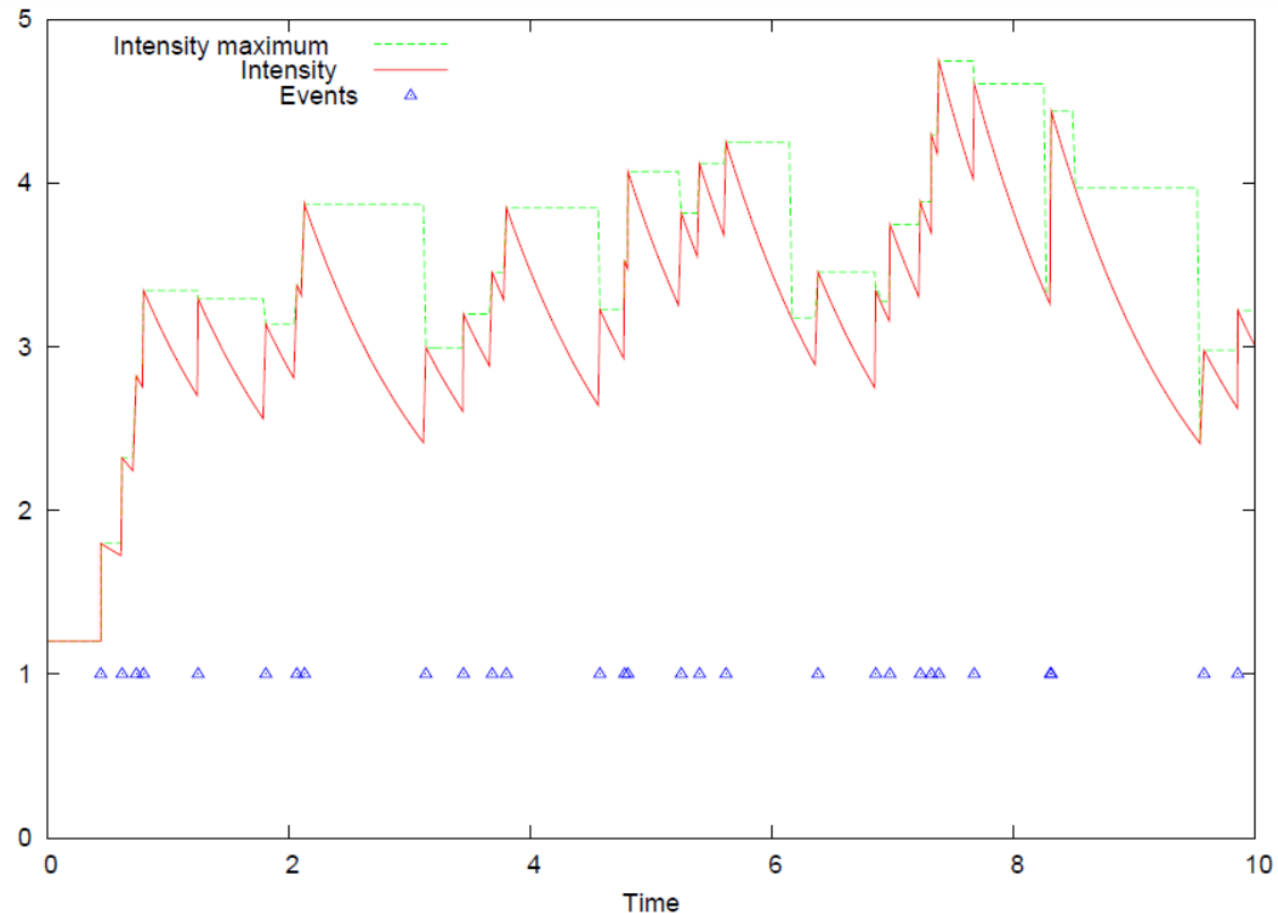


Figure: Simulation of a one-dimensional Hawkes process with parameters  $P = 1, \lambda_0 = 1.2, \alpha_1 = 0.6, \beta_1 = 0.8$ . (Zoom of the previous figure).

# Testing the simulated process

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For any consecutive events  $t_{i-1}$  and  $t_i$

$$\begin{aligned}\Lambda(t_{i-1}, t_i) &= \int_{t_{i-1}}^{t_i} \lambda(s) ds \\ &= \int_{t_{i-1}}^{t_i} \mu(s) ds + \int_{t_{i-1}}^{t_i} \sum_{t_k < s} \sum_{j=1}^P \alpha_j e^{-\beta_j(s-t_k)} ds \\ &= \int_{t_{i-1}}^{t_i} \mu(s) ds + \int_{t_{i-1}}^{t_i} \sum_{t_k \leq t_{i-1}} \sum_{j=1}^P \alpha_j e^{-\beta_j(s-t_k)} ds \\ &= \int_{t_{i-1}}^{t_i} \mu(s) ds + \sum_{t_k \leq t_{i-1}} \sum_{j=1}^P \frac{\alpha_j}{\beta_j} (e^{-\beta_j(t_{i-1}-t_k)} - e^{-\beta_j(t_i-t_k)})\end{aligned}$$

# Testing the simulated process

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This computation can be simplified with a **recursive element**.  
Let us denote

$$A_j(i-1) = \sum_{t_k \leq t_{i-1}} e^{-\beta_j(t_{i-1}-t_k)}$$

We observe that

$$\begin{aligned} A_j(i-1) &= \sum_{t_k \leq t_{i-1}} e^{-\beta_j(t_{i-1}-t_k)} \\ &= 1 + e^{-\beta_j(t_{i-1}-t_{i-2})} \sum_{t_k \leq t_{i-1}} e^{-\beta_j(t_{i-1}-t_k)} \\ &= 1 + e^{-\beta_j(t_{i-1}-t_{i-2})} A_j(i-2) \end{aligned}$$

# Testing the simulated process

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Finally, the integrated density can be written  $i \in N$

$$\begin{aligned}\Lambda(t_{i-1}, t_i) &= \int_{t_{i-1}}^{t_i} \mu(s) ds + \sum_{t_k \leq t_{i-1}} \sum_{j=1}^P \frac{\alpha_j}{\beta_j} (e^{-\beta_j(t_{i-1}-t_k)} - e^{-\beta_j(t_i-t_k)}) \\ &= \int_{t_{i-1}}^{t_i} \mu(s) ds + \sum_{j=1}^P \frac{\alpha_j}{\beta_j} (1 - e^{-\beta_j(t_i-t_{i-1})}) A_j(i-1)\end{aligned}$$

where  $A_j(i-1) = \sum_{t_k \leq t_{i-1}} e^{-\beta_j(t_{i-1}-t_k)}$

# Testing the simulated process

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Defining  $\{\tau_i\}$  as

$$\tau_0 = \int_0^{t_0} \lambda(s) ds = \Lambda(0, t_0)$$

$$\tau_i = \tau_{i-1} + \int_{t_{i-1}}^{t_i} \lambda(s) ds = \tau_{i-1} + \Lambda(t_{i-1}, t_i)$$

the durations  $\tau_i - \tau_{i-1} = \Lambda(t_{i-1}, t_i)$  are **exponentially distributed**

# Maximum-likelihood estimation

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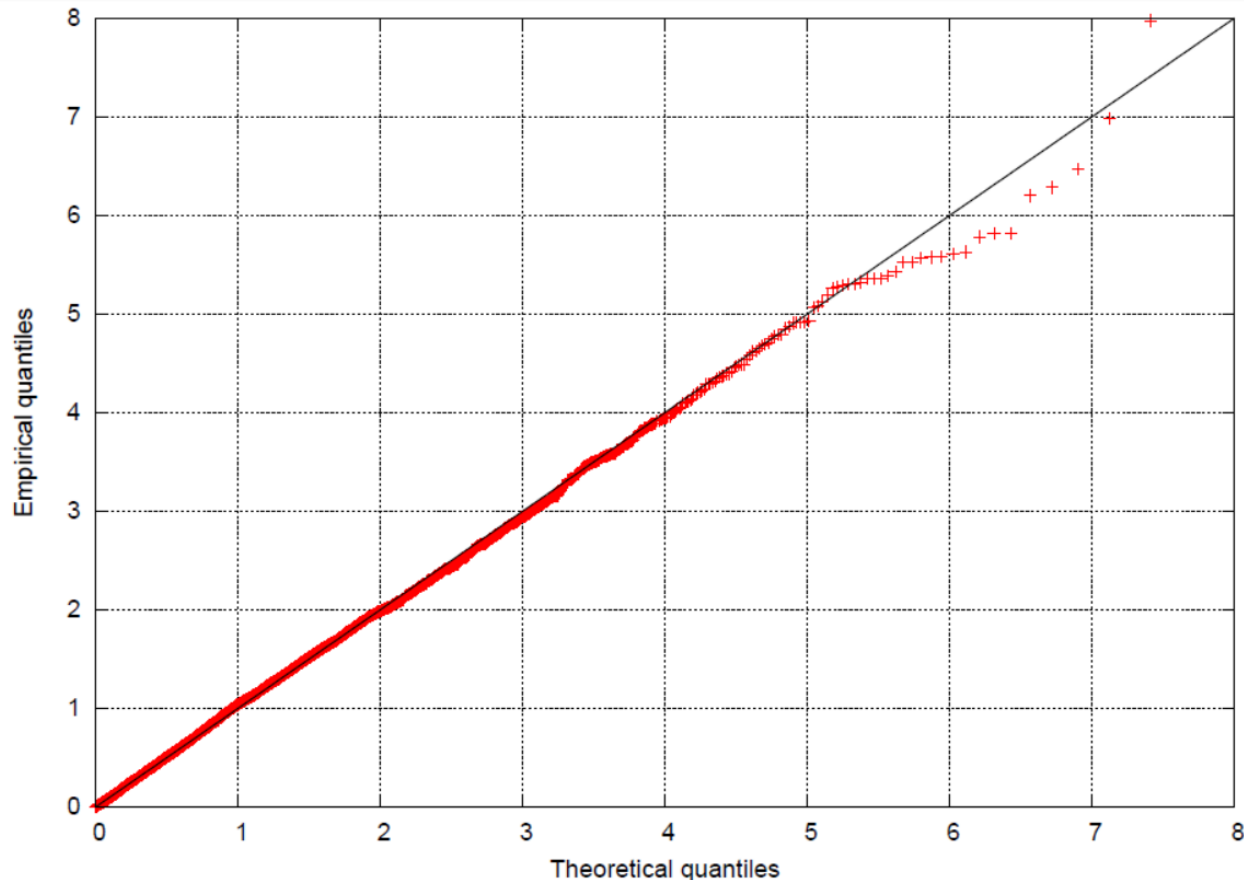


Figure: Quantile plot for one sample of simulated data of a one-dimensional Hawkes process with parameters  $P = 1, \lambda_0 = 1.2, \alpha_1 = 0.6, \beta_1 = 0.8$ , on an interval  $[0, 10000]$ .

# Maximum-likelihood estimation

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1D-Hawkes process, for example

$$\lambda(t) = \mu + \sum_{t_i < t} \alpha e^{-\beta(t-t_i)}$$

The likelihood is

$$L = \exp\left(-\int_0^T \lambda(s) ds\right) \prod_{i=1}^n \lambda(t_i)$$

The log-likelihood is

$$\begin{aligned} \log L &= \sum_{i=1}^n \log \lambda(t_i) - \int_0^T \mu + \sum_{t_i < t} \alpha e^{-\beta(t-t_i)} dt \\ &= \sum_{i=1}^n \log \lambda(t_i) - \left( \mu T + \sum_{j=1}^n \alpha G(T - t_j) \right) \end{aligned}$$



# Maximum-likelihood estimation

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The log-likelihood for three parameters  $\mu, \alpha, \beta$

$$\begin{aligned}\log L &= \sum_{i=1}^n \log \lambda(t_i) - \int_0^T \mu + \sum_{t_i < t} \alpha e^{-\beta(t-t_i)} dt \\ &= \sum_{i=1}^n \log \lambda(t_i) - \left( \mu T + \sum_{j=1}^n \alpha G(T - t_j) \right) \\ &= \sum_{i=1}^n \log \left( \mu + \sum_{j=1}^{i-1} \alpha e^{-\beta(t_i-t_j)} \right) - \left( \mu T + \sum_{j=1}^n \alpha G(T - t_j) \right)\end{aligned}$$

where  $G(t) = \int_0^t e^{-\beta\tau} d\tau = -\frac{1}{\beta} (e^{-\beta t} - 1)$

# EM algorithm

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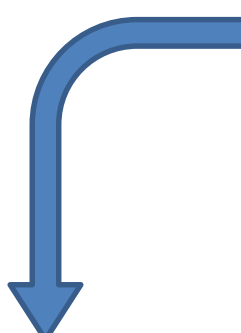
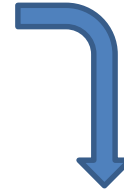
Then use EM algorithm to estimate the parameter  
Jensen's inequality:

$$\begin{aligned}\log L &= \sum_{i=1}^n \log \left( \mu + \sum_{j=1}^{i-1} \alpha e^{-\beta(t_i - t_j)} \right) - \left( \mu T + \sum_{j=1}^n \alpha G(T - t_j) \right) \\ &\geq \underbrace{\sum_{i=1}^n \left( p_{ii} \log \frac{\mu}{p_{ii}} + \sum_{j=1}^{i-1} p_{ij} \log \frac{\alpha e^{-\beta(t_i - t_j)}}{p_{ij}} \right)}_{\text{lower bound}} - \left( \mu T + \sum_{j=1}^n \alpha G(T - t_j) \right)\end{aligned}$$

# EM algorithm

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For E-step


$$p_{ii}^{(k+1)} = \frac{\mu^{(k)}}{\mu^k + \sum_{j=1}^{i-1} \alpha^{(k)} e^{-\beta^{(k)}(t_i - t_j)}}$$
$$p_{ij}^{(k+1)} = \frac{\alpha^{(k)} e^{-\beta^{(k)}(t_i - t_j)}}{\mu^k + \sum_{j=1}^{i-1} \alpha^{(k)} e^{-\beta^{(k)}(t_i - t_j)}}$$


The probability that the event  $i$  is triggered by the base intensity  $\mu$

The probability that the event  $i$  is triggered by the event  $j$

# EM algorithm

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For M-step (do partial differential equation for  $\mu$  and  $\alpha$ )

$$\mu^{(k+1)} = \frac{1}{T} \sum_{i=1}^n p_{ii}^{(k+1)}$$
$$\alpha^{(k+1)} = \frac{\sum_{i>j} p_{ij}^{(k)}}{\sum_{j=1}^n G(T - t_j)}$$

For  $\beta$ , if  $e^{-\beta(T-t_i)} \approx 0$

$$\beta^{(k+1)} = \frac{\sum_{i>j} p_{ij}^{(k+1)}}{\sum_{i>j} (t_i - t_j) p_{ij}^{(k+1)}}$$

# Inference

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- Why not other optimal algorithm based on gradient?
- For example: SGD, ADAM
- For log-likelihood of event data

$$\log L = \sum_{i=1}^n \log \left( \mu + \sum_{j=1}^{i-1} \alpha e^{-\beta(t_i - t_j)} \right) - \left( \mu T + \sum_{j=1}^n \alpha G(T - t_j) \right)$$

- the objective is very long for (most) event datasets.

# outline

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# Multi-dimensional Hawkes Process

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Multi-dimensional Hawkes process  $N(t) = (N_1(t), N_2(t), \dots, N_M(t))$  is defined with intensities  $\lambda_m$  for  $m = 1, 2, \dots, M$  given by

$$\lambda_m(t) = \mu_m(t) + \sum_{n=1}^M \int_0^t \sum_{j=1}^P \alpha_{mn}^j e^{-\beta_{mn}^j(t-s)} dN_s$$

in its simplest version with  $P = 1$  and  $\mu_m(t)$  constant

$$\begin{aligned} \lambda_m(t) &= \mu_m + \sum_{n=1}^M \int_0^t \alpha_{mn} e^{-\beta_{mn}(t-s)} dN_s \\ &= \mu_m + \sum_{n=1}^M \sum_{t_i^n < t} \alpha_{mn} e^{-\beta_{mn}(t-t_i^n)} \end{aligned}$$

Multi-dimensional Hawkes process is also called **multivariate Hawkes process**

# Multi-dimensional Hawkes Process

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Take  $P = 1$  here to simplify the notations. Rewriting the intensities of multi-dimensional Hawkes processes using vectorial notation, we have :

$$\lambda(t) = \mu + \int_0^t \mathbf{G}(t-s) d\mathbf{N}_s$$

where

$$\mathbf{G}(t) = (\alpha_{mn} e^{-\beta_{mn} t})_{m,n=1,\dots,M}$$

Assuming stationarity gives  $\nu = E[\lambda(t)]$  constant vector, and thus stationary intensities must satisfy :

$$\nu = \left( \mathbf{I} - \int_0^\infty \mathbf{G}(u) du \right)^{-1} \mu$$



# Stationarity of Multivariate Hawkes process

---

A sufficient condition for a multivariate Hawkes process to be stationary is that the spectral radius of the matrix

$$\Gamma = \int_0^\infty \mathbf{G}(u) du = \left( \frac{\alpha_{mn}}{\beta_{mn}} \right)_{m,n=1,\dots,M}$$

be strictly smaller than 1.

---

Recall the spectral radius of the matrix  $G$  is defined as :

$$\rho(G) = \max_{a \in S(G)} |a|$$

where  $S(G)$  denotes the set of all eigenvalues of  $G$

# Simulation of multivariate Hawkes process

---

Define the sum of the intensities of the first  $K$  components of the multivariate process as

$$I^K(t) = \sum_{n=1}^K \lambda_n(t)$$

$I^M(t) = \sum_{n=1}^M \lambda_n(t)$  is thus the total intensity of the multivariate process and we set  $I^0 = 0$ , so

$$I^M(0) = \sum_{n=1}^M \mu_n(0)$$

# Simulation algorithm

---

- ① Initialization: set  $i = 1, i^1 = 1, i^2 = 1, \dots, i^M = 1, I^* = I^M(0)$
- ② First event:
  - (1) generate  $V \sim \text{Uniform}([0,1]), t \sim \text{Exp}(I^*)$  (i.e.  $t \leftarrow -\frac{1}{m(t)} \log V$ )
  - (2) if  $t > T$ : go to last step (empty)
  - (3) **Attribution Test**: generate  $D \sim \text{Uniform}([0,1])$  and set  $t_1^{n_0} = t$   
where  $n_0$  satisfies that  $\frac{I^{n_0-1}}{I^*} \leq D \leq \frac{I^{n_0}}{I^*}$

# Simulation algorithm

---

- ③ While true: (General routine) set  $i^{n_0} = i^{n_0} + 1$  and  $i = i + 1$
- (1) Update maximum intensity:  $I^* = I^M(t) + \sum_{n=1}^M \sum_{j=0}^P \alpha_{nn_0}^j$
- (2) New event: generate  $s \sim \text{Exp}(I^*)$ ,  $t += s$  and  $U \sim \text{Uniform}([0,1])$
- if:  $t > T$ , then go to last step (break )
- (3) **Attribution-Rejection test** : generate  $D \sim \text{Uniform}([0,1])$
- if:  $D \leq \frac{i^{n_0-1}}{I^*}$ ,
- then set  $t_{i^{n_0}}^{n_0} = t$  where  $n_0$  satisfy  $\frac{i^{n_0-1}}{I^*} \leq D \leq \frac{i^{n_0}}{I^*}$
- ④ Retrieve the simulated process  $\{t_i^n\}$  on  $[0, T]$

# Simulation

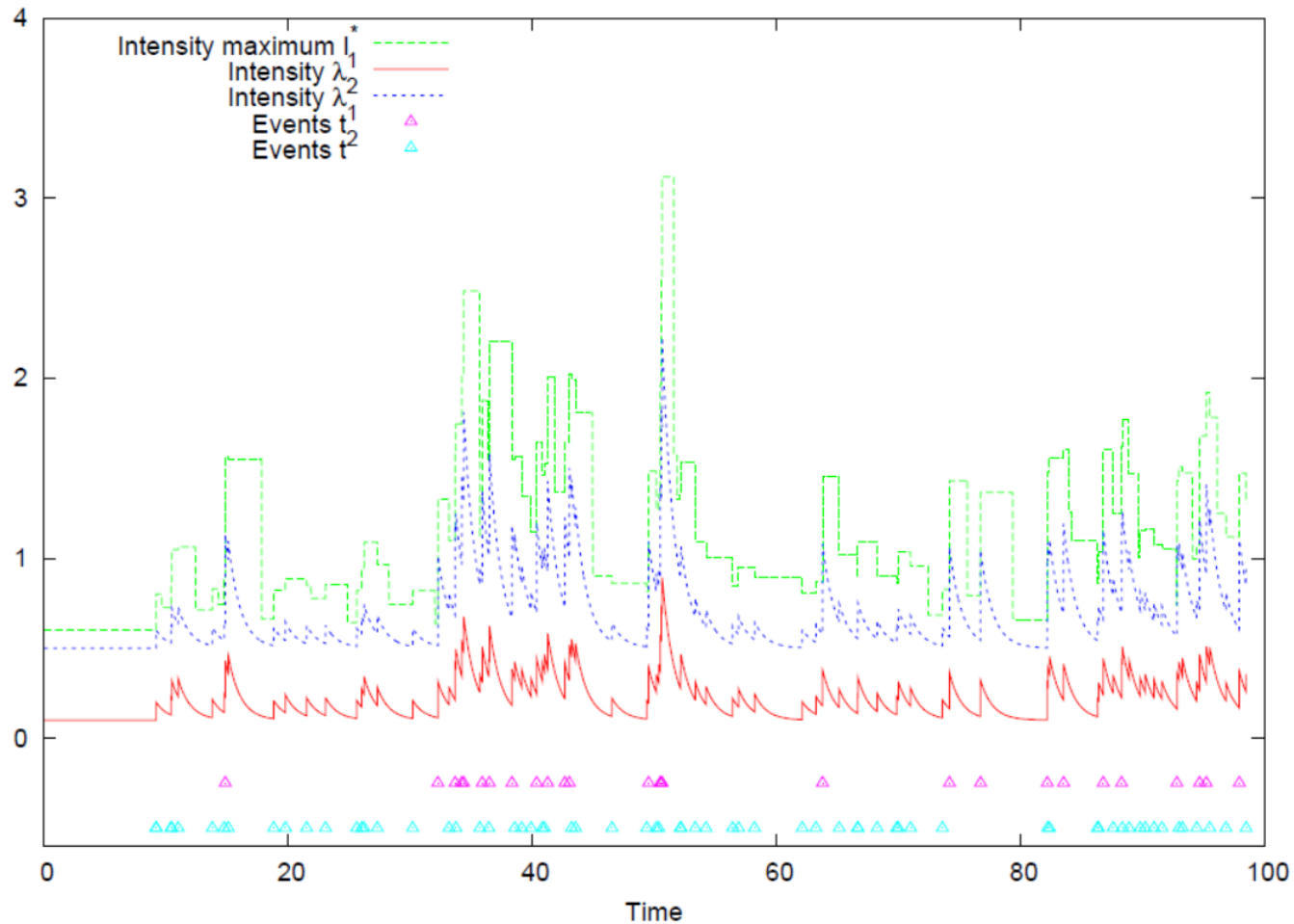
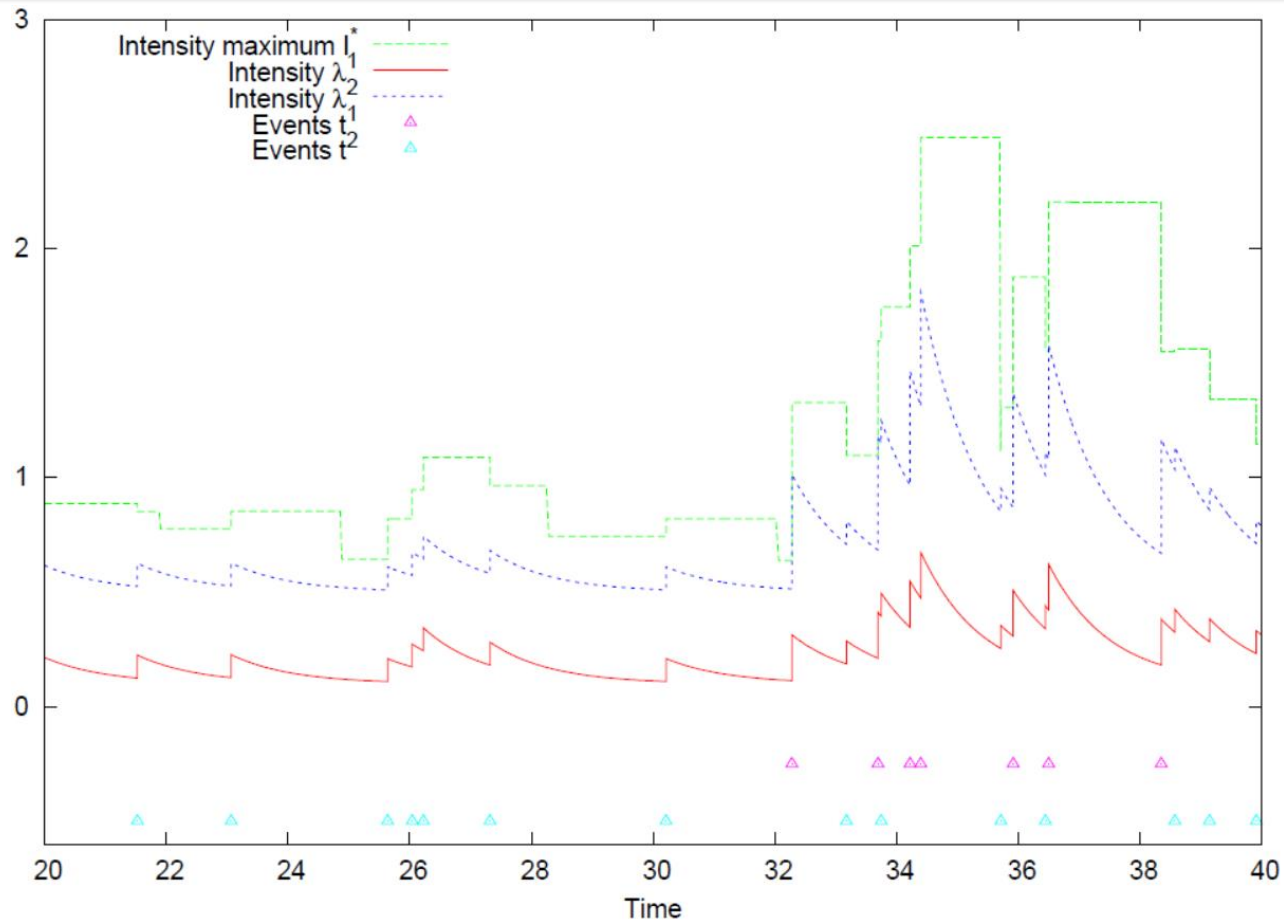


Figure: Simulation of a two-dimensional Hawkes process with  $P = 1$

# Simulation



**Figure:** Simulation of a two-dimensional Hawkes process with  $P = 1$  (Zoom of the previous figure).

# Testing the simulated data

---

The integrated intensity of the  $m$ -th coordinate of a multidimensional Hawkes process between two consecutive events  $t_{i-1}^m$  and  $t_i^m$  of type  $m$  is computed as:

$$\begin{aligned}\Lambda_m(t_{i-1}, t_i) &= \int_{t_{i-1}^m}^{t_i^m} \lambda_m(s) ds \\ &= \int_{t_{i-1}^m}^{t_i^m} \mu_m(s) ds + \int_{t_{i-1}^m}^{t_i^m} \sum_{n=1}^M \sum_{t_k^n < s} \sum_{j=1}^P \alpha_{mn}^j e^{-\beta_{mn}^j (s - t_k^n)} ds \\ &= \int_{t_{i-1}^m}^{t_i^m} \mu_m(s) ds + \int_{t_{i-1}^m}^{t_i^m} \sum_{n=1}^M \sum_{t_k^n < t_{i-1}^m} \sum_{j=1}^P \alpha_{mn}^j e^{-\beta_{mn}^j (s - t_k^n)} ds \\ &\quad + \int_{t_{i-1}^m}^{t_i^m} \sum_{n=1}^M \sum_{t_{i-1}^m < t_k^n < s} \sum_{j=1}^P \alpha_{mn}^j e^{-\beta_{mn}^j (s - t_k^n)} ds\end{aligned}$$

# Testing the simulated data

---

$$\begin{aligned}\Lambda_m(t_{i-1}, t_i) &= \int_{t_{i-1}^m}^{t_i^m} \mu_m(s) ds + \int_{t_{i-1}^m}^{t_i^m} \sum_{n=1}^M \sum_{t_k^n < t_{i-1}^m} \sum_{j=1}^P \alpha_{mn}^j e^{-\beta_{mn}^j(s-t_k^n)} ds \\ &\quad + \int_{t_{i-1}^m}^{t_i^m} \sum_{n=1}^M \sum_{t_{i-1}^m \leq t_k^n < s} \sum_{j=1}^P \alpha_{mn}^j e^{-\beta_{mn}^j(s-t_k^n)} ds \\ &= \int_{t_{i-1}^m}^{t_i^m} \mu_m(s) ds + \sum_{n=1}^M \sum_{t_k^n < t_{i-1}^m} \sum_{j=1}^P \frac{\alpha_{mn}^j}{\beta_{mn}^j} (e^{-\beta_{mn}^j(t_{i-1}^m - t_k^n)} - e^{-\beta_{mn}^j(t_i^m - t_k^n)}) \\ &\quad + \sum_{n=1}^M \sum_{t_{i-1}^m \leq t_k^n < s} \sum_{j=1}^P \frac{\alpha_{mn}^j}{\beta_{mn}^j} (1 - e^{-\beta_{mn}^j(t_i^m - t_k^n)})\end{aligned}$$



# Testing the simulated data

---

This computation can be simplified with a **recursive** element.  
Let us denote

$$A_j^{mn}(i-1) = \sum_{t_k^n < t_{i-1}^m} e^{-\beta_{mn}^j(t_{i-1}^m - t_k^n)}$$

We observe that

$$\begin{aligned} A_j^{mn}(i-1) &= \sum_{t_k^n < t_{i-1}^m} e^{-\beta_{mn}^j(t_{i-1}^m - t_k^n)} \\ &= e^{-\beta_{mn}^j(t_{i-1}^m - t_{i-2}^m)} \sum_{t_k^n < t_{i-2}^m} e^{-\beta_{mn}^j(t_{i-1}^m - t_k^n)} + \sum_{t_{i-2}^m \leq t_k^n < t_{i-1}^m} e^{-\beta_{mn}^j(t_{i-1}^m - t_k^n)} \\ &= e^{-\beta_{mn}^j(t_{i-1}^m - t_{i-2}^m)} A_j^{mn}(i-2) + \sum_{t_{i-2}^m \leq t_k^n < t_{i-1}^m} e^{-\beta_{mn}^j(t_{i-1}^m - t_k^n)} \end{aligned}$$

# Testing the simulated data

---

Finally, the integrated density can be written  $i \in N$

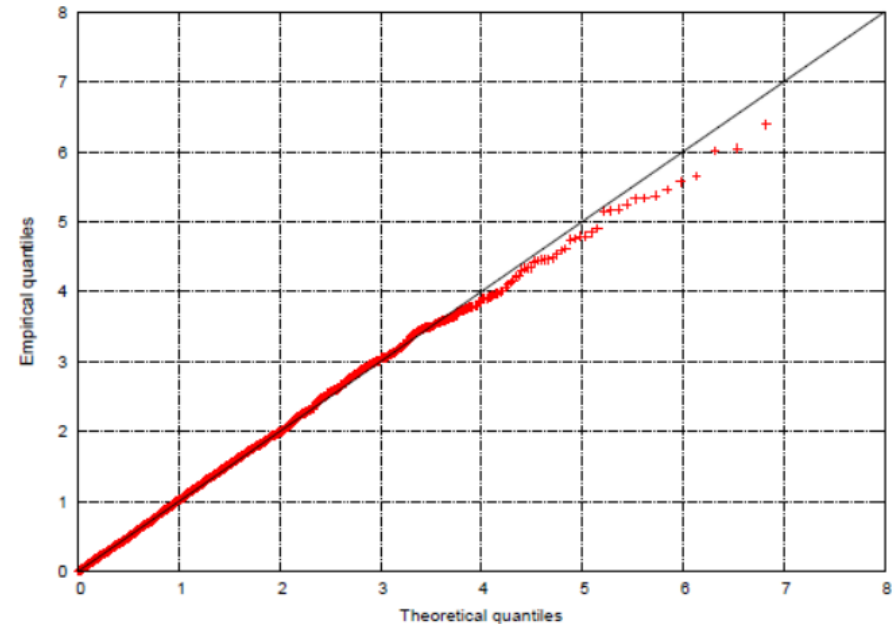
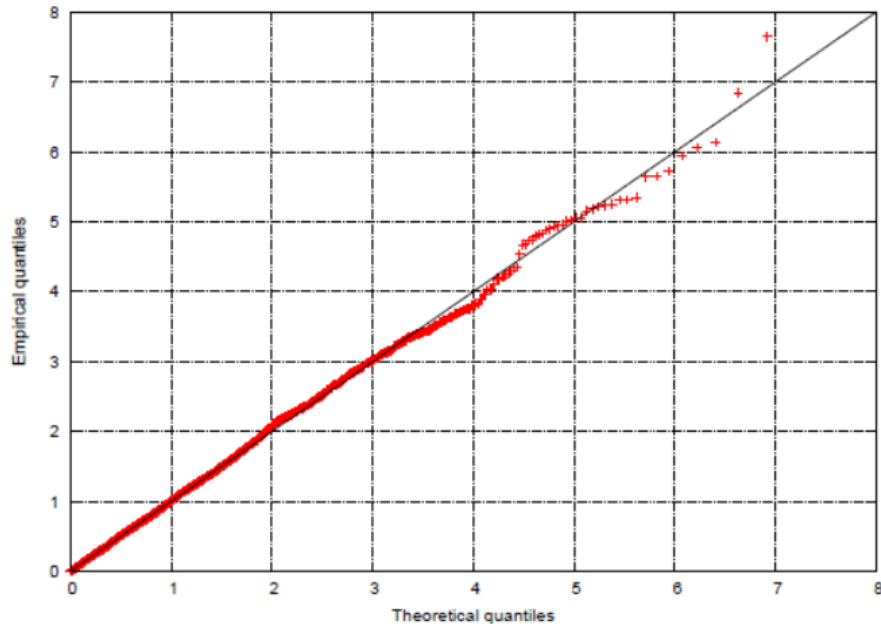
$$\begin{aligned}\Lambda_m(t_{i-1}, t_i) &= \int_{t_{i-1}^m}^{t_i^m} \lambda_m(s) ds \\ &= \int_{t_{i-1}^m}^{t_i^m} \mu_m(s) ds + \sum_{n=1}^M \sum_{j=1}^P \frac{\alpha_{mn}^j}{\beta_{mn}^j} [(1 - e^{-\beta_{mn}^j(t_i^m - t_{i-1}^m)}) \times A_j^{mn}(i-1) \\ &\quad + \sum_{t_{i-1}^m \leq t_k^n < s} (1 - e^{-\beta_{mn}^j(t_i^m - t_k^n)})]\end{aligned}$$

Time change property:

the durations  $\tau_i^m - \tau_{i-1}^m = \Lambda_m(t_{i-1}, t_i)$  are **exponentially distributed**

# Testing the simulated data

---



**Figure:** Quantile plots for one sample of simulated data of a two-dimensional Hawkes process with  $P = 1$ . (Left)  $m = 0$ . (Right)  $m = 1$ .

# Maximum-likelihood estimation

---

For MLE, we use the data  $\{t_i, d_i\}_{i=1}^N$  instead of  $\{(t_i^m)_i\}_{m=1}^M$

For a simple multi-dimensional Hawkes processes:

$$\lambda_d = \mu_d + \sum_{i:t_i < t} \alpha_{dd_i} e^{-\beta(t-t_i)}$$

log-likelihood:

$$\begin{aligned} \log L &= \sum_{d=1}^M \left\{ \sum_{(t_i, d_i) | d_i = d} \log \lambda_{d_i}(t_i) - \int_0^T \lambda_d(t) dt \right\} \\ &= \sum_{i=1}^n \log \left( \mu_{d_i} + \sum_{t_j < t_i} \alpha_{d_i d_j} e^{-\beta(t_i - t_j)} \right) - T \sum_{d=1}^M \mu_d - \sum_{d=1}^M \sum_{j=1}^n \alpha_{dd_j} G_{dd_j}(T - t_j) \end{aligned}$$

# Maximum-likelihood estimation

---

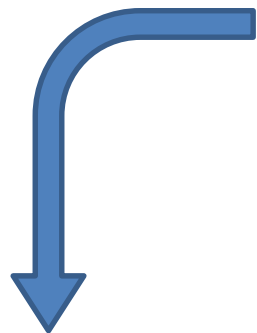
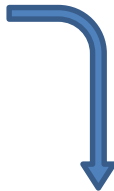
Jensen equality:

$$\begin{aligned}\log L &= \sum_{i=1}^n \log \left( \mu_{d_i} + \sum_{t_j < t_i} \alpha_{d_i d_j} e^{-\beta(t_i - t_j)} \right) - T \sum_{d=1}^M \mu_d - \sum_{d=1}^M \sum_{j=1}^n \alpha_{d d_j} G_{d d_j}(T - t_j) \\ &\geq \underbrace{\sum_{i=1}^n \left( p_{ii} \log \frac{\mu_{d_i}}{p_{ii}} + \sum_{j=1}^{i-1} p_{ij} \log \frac{\alpha_{d_i d_j} e^{-\beta(t_i - t_j)}}{p_{ij}} \right) - T \sum_{d=1}^M \mu_d - \sum_{d=1}^M \sum_{j=1}^n \alpha_{d d_j} G_{d d_j}(T - t_j)}_{\text{lower bound}}\end{aligned}$$

# Maximum-likelihood estimation

---

So for E-step


$$p_{ii}^{(k+1)} = \frac{\mu_{d_i}^{(k)}}{\mu_{d_i}^{(k)} + \sum_{j=1}^{i-1} \alpha_{d_i d_j}^{(k)} e^{-\beta(t_i - t_j)}}$$
$$p_{ij}^{(k+1)} = \frac{\alpha^{(k)} e^{-\beta(t_i - t_j)}}{\mu_{d_i}^{(k)} + \sum_{j=1}^{i-1} \alpha_{d_i d_j}^{(k)} e^{-\beta(t_i - t_j)}}$$


The probability that the event  $i$  is triggered by the base intensity  $\mu$

The probability that the event  $i$  is triggered by the event  $j$

# Maximum-likelihood estimation

---

M-step (do partial differential equation for  $\mu$  and  $\alpha$ )

$$\mu_d^{(k+1)} = \frac{1}{T} \sum_{i=1, d_i=d}^n p_{ii}^{(k+1)}$$
$$\alpha_{uv}^{(k+1)} = \frac{\sum_{i=1, d_i=u}^n \sum_{j=1, d_j=v}^{i-1} p_{ij}^{(k+1)}}{\sum_{j=1, d_j=v}^n G(T - t_j)}$$

For  $\beta$ , if  $e^{-\beta(T-t_i)} \approx 0$

$$\beta^{(k+1)} = \frac{\sum_{i>j} p_{ij}^{(k+1)}}{\sum_{i>j} (t_i - t_j) p_{ij}^{(k+1)}}$$

# Application

---

- For  $\alpha_{ij}$ , influence from dimension  $i$  to  $j$
- Social Infectivity
- If high dimension, overfitting for  $A = [\alpha_{ij}]$
- **Sparse Low-rank Networks**
- regularize the maximum likelihood estimator

$$\min_{A \geq 0, \mu \geq 0} -L(A, \mu) + \lambda_1 \|A\|_* + \lambda_2 \|A\|_1$$

- $\|A\|_*$  is the nuclear norm of matrix  $A$ , which is defined to be the sum of its singular value



# Sparse Low-rank

---

- Optimization with Sparse Low-rank constraint

$$\min_{A \geq 0, \mu \geq 0} -L(A, \mu) + \lambda_1 \|A\|_* + \lambda_2 \|A\|_1$$

- which are equivalent by introducing two auxiliary variables  $Z_1$  and  $Z_2$

$$\min_{A \geq 0, \mu \geq 0, Z_1, Z_2} -L(A, \mu) + \lambda_1 \|Z_1\|_* + \lambda_2 \|Z_2\|_1$$

- In ADMM, we optimize the augmented Lagrangian of the above problem

$$L_\rho = -L(A, \mu) + \lambda_1 \|Z_1\|_* + \lambda_2 \|Z_2\|_1 + \rho \text{trace} \left( \overset{\text{dual variable}}{\underbrace{U_1^T}} (A - Z_1) \right) \\ + \rho \text{trace} \left( \underbrace{U_2^T} (A - Z_2) \right) + \frac{\rho}{2} (\|A - Z_1\|^2 + \|A - Z_2\|^2)$$

# Sparse Low-rank

---

- solving the above augmented Lagrangian problem involves the following key iterative steps

$$A^{k+1}, \mu^{k+1} = \underset{A \geq 0, \mu \geq 0}{\operatorname{argmin}} L_{\rho}(A, \mu, Z_1^k, Z_2^k, U_1^k, U_2^k)$$

$$Z_1^{k+1} = \underset{A \geq 0, \mu \geq 0}{\operatorname{argmin}} L_{\rho}(A^{k+1}, \mu^{k+1}, Z_1, Z_2^k, U_1^k, U_2^k)$$

$$Z_2^{k+1} = \underset{A \geq 0, \mu \geq 0}{\operatorname{argmin}} L_{\rho}(A^{k+1}, \mu^{k+1}, Z_1^k, Z_2, U_1^k, U_2^k)$$

$$U_1^{k+1} = U_1^k + (A^{k+1} - Z_1^{k+1})$$

$$U_2^{k+1} = U_2^k + (A^{k+1} - Z_2^{k+1})$$

# Sparse Low-rank — Solving for $Z_1$ and $Z_2$

---

- When solving for  $Z_1$  for equation

$$Z_1^{k+1} = \operatorname{argmin}_{A \geq 0, \mu \geq 0} L_\rho(A^{k+1}, \mu^{k+1}, Z_1, Z_2^k, U_1^k, U_2^k)$$

- the relevant terms from  $L_\rho$  are

$$\lambda_1 \|Z_1\|_* + \rho \operatorname{trace} \left( (U_1^k)^T (A^{k+1} - Z_1) \right) + \frac{\rho}{2} (\|A^{k+1} - Z_1\|^2)$$

- which can be simplified to an equivalent problem

$$\lambda_1 \|Z_1\|_* + \frac{\rho}{2} (\|A^{k+1} - Z_1 + U_1^k\|^2)$$

- The above problem has a closed form solution

$$Z_1^{k+1} = S_{\lambda_1/\rho}(A^{k+1} + U_1^k)$$

- where  $S_\alpha$  is a soft-thresholding function defined as

# Sparse Low-rank — Solving for $Z_1$ and $Z_2$

---

$$\lambda_1 \|Z_1\|_* + \frac{\rho}{2} \left( \|A^{k+1} - Z_1 + U_1^k\|^2 \right)$$

- which can be simplified to an equivalent problem

$$Z_1^{k+1} = \underset{Z_1}{\operatorname{argmin}} \lambda_1 \|Z_1\|_* + \frac{\rho}{2} \left( \|A^{k+1} - Z_1 + U_1^k\|^2 \right)$$

- The above problem has a closed form solution

$$Z_1^{k+1} = S_{\lambda_1/\rho}(A^{k+1} + U_1^k)$$

- where  $S_\alpha$  is a soft-thresholding function defined as

$$S_\alpha(X) = U((\sigma_i - \alpha)_+)V^T$$

- for all matrix  $X$  with singular value decomposition

$$X = U(\sigma_i)V^T$$

# Sparse Low-rank — Solving for $Z_1$ and $Z_2$

---

- Similarly, the optimization for  $Z_2$  can be simplified into the following equivalent form

$$Z_2^{k+1} = \underset{A \geq 0, \mu \geq 0}{\operatorname{argmin}} \lambda_2 \|Z_2\|_1 + \frac{\rho}{2} \left( \|A^{k+1} - Z_2 + U_2^k\|^2 \right)$$

- In this case, depending on the magnitude of the  $ij$ -th entry of the matrix  $A^{k+1} + U_2^k$ , the corresponding  $(Z_2^{k+1})_{ij}$  is updated as

$$\begin{cases} (A^{k+1} + U_2^k)_{ij} - \frac{\lambda_2}{\rho} & (A^{k+1} + U_2^k)_{ij} \geq \frac{\lambda_2}{\rho} \\ (A^{k+1} + U_2^k)_{ij} + \frac{\lambda_2}{\rho} & (A^{k+1} + U_2^k)_{ij} \leq -\frac{\lambda_2}{\rho} \\ 0 & \text{else} \end{cases}$$

# Sparse Low-rank — Solving for $A, \mu$

---

- The optimization problem is equivalent to

$$A^{k+1}, \mu^{k+1} = \underset{A \geq 0, \mu \geq 0}{\operatorname{argmin}} f(A, \mu)$$

- Where  $f(A, \mu) = -L(A, \mu) + \frac{\rho}{2} \left( \|A - Z_1 + U_1^k\|^2 + \|A^{k+1} - Z_2 + U_2^k\|^2 \right)$ . Then similar above with EM algorithm

$$Q(A, \mu | A^{(k)}, \mu^{(k)}) = \sum_{i=1}^n \left( p_{ii} \log \frac{\mu_{d_i}}{p_{ii}} + \sum_{j=1}^{i-1} p_{ij} \log \frac{\alpha_{d_i d_j} e^{-\beta(t_i - t_j)}}{p_{ij}} \right) \\ - T \sum_{d=1}^M \mu_d - \sum_{d=1}^M \sum_{j=1}^n \alpha_{dd_j} G_{dd_j}(T - t_j) + \frac{\rho}{2} \left( \|A - Z_1 + U_1^k\|^2 + \|A^{k+1} - Z_2 + U_2^k\|^2 \right)$$

---

where

$$p_{ii}^{(k+1)} = \frac{\mu_{d_i}^{(k)}}{\mu_{d_i}^{(k)} + \sum_{j=1}^{i-1} \alpha_{d_i d_j}^{(k)} e^{-\beta(t_i - t_j)}}$$
$$p_{ii}^{(k+1)} = \frac{\alpha^{(k)} e^{-\beta(t_i - t_j)}}{\mu_{d_i}^{(k)} + \sum_{j=1}^{i-1} \alpha_{d_i d_j}^{(k)} e^{-\beta(t_i - t_j)}}$$

and

$$\mu_d^{(k+1)} = \frac{1}{T} \sum_{i=1, d_i=d}^n p_{ii}^{(k+1)}$$
$$\alpha_{uv}^{(k+1)} = \frac{-B + \sqrt{B^2 + 8\rho C}}{4\rho}$$

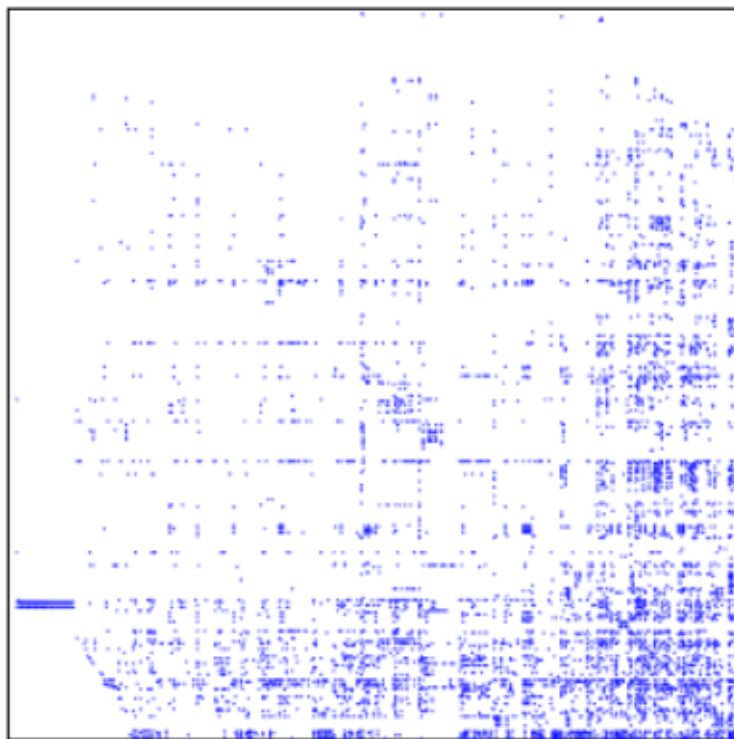
---

where

$$B = \sum_{j=1, d_j=v}^n G(T - t_j) + \rho(-z_{1,uv} + u_{1,uv} - z_{2,uv} + u_{2,uv})$$

$$C = \sum_{i=1, d_i=u}^n \sum_{j=1, d_j=v}^{i-1} p_{ij}^{(k+1)}$$





Influence structure estimated from the MemeTracker dataset

# outline

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1. introduction
2. One-dimensional Hawkes Process
3. Multi-dimensional Hawkes Process
4. Marked Hawkes Processes

# Conditional Intensity Function: Marked Point Processes

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- The conditional intensity function for the marked case

$$\lambda^*(t, k) = \lambda^*(t) f^*(k|t)$$

- $\lambda^*(t)$  ground intensity, history dependent, also may depend on all the past marks as well
- $f^*(k|t) = f(k|t, \{(t_i, k_i)\}_{t_i < t})$

# Marked Hawkes Processes

---

Marked Hawkes Process is given by the conditional density

$$\begin{aligned}\lambda^*(t, k) &= f^*(k|t)(\mu(t) + \sum_{t_i < t} \alpha(k_i)g(t - t_i, k_i)) \\ &= f^*(k|t)(\mu(t) + \int_0^t \alpha(k)\beta(t - s, k)N(ds, dk))\end{aligned}$$

# Marked Hawkes Processes

---

Defined in terms of conditional density functions

- ▶ **Immigration intensity:**  $\mu(t)$  with parameter  $\theta_\mu$
- ▶ **Total offspring intensity:**  $\alpha(k)$  with parameter  $\theta_\alpha$
- ▶ **Normalized offspring intensity:**  $g(t, k)$  with parameter  $\theta_g$
- ▶ **Mark density:**  $f^*(k|t)$  with parameter  $\theta_f$
- ▶ The product function  $\alpha(k)g(t, k)$  is called offspring intensity (infectivity function, triggering kernel)

# Marked Hawkes Processes

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- ▶ **Example:** Reproducing population with exponential survival time, and individuals reproduce uniformly throughout their survival time
- ▶  $\mu(t) = \mu_1$ ,  $\alpha(k) = \alpha_1 k$ ,  $g(t, k) = 1_{[0, k]}(t)/k$ ,
- ▶  $f^*(k|t) = f_1 \exp(-f_1 k)$
- ▶ Then the intensity function

$$\lambda^*(t, k) = f_1 \exp(-f_1 k) \left( \mu_1 + \sum_{t_i < t} \alpha_1 1_{[0, k_i]}(t) \right)$$

# Marked Hawkes Processes

---

## ■ Example:

■ A simple earthquake model  $k = (m, x, y)$

■  $\mu(t) = \mu_1$ ,  $\alpha(k) = \alpha_1 \exp(\alpha_2 k)$ ,

■  $g(t, k) = \beta_2 / \beta_1 \cdot (1 + t / \beta_1)^{-\beta_2 - 1}$ ,

■  $f^*(k|t) = f_1 \exp(-f_1 k) 1_{(x,y) \in W} / |W|$

■ Then the intensity function

$$\lambda^*(t, k) = f_1 \exp(-f_1 k) 1_{(x,y) \in W} / |W| \cdot (\mu_1 + \sum_{t_i < t} \alpha_1 \exp(\alpha_2 k) \beta_2 / \beta_1 \cdot (1 + (t - t_i) / \beta_1)^{-\beta_2 - 1})$$

---

# Thanks