

Introduction to Model Checking (Summer Term 2018)

— Solution 11 (due 16th July) —

General Remarks

- The exercises are to be solved in groups of *three* students.
- You may hand in your solutions for the exercises just before the exercise class starts at 12:15 or by dropping them into the “Introduction to Model Checking” box at our chair *before 12:00*. Do *not* hand in your solutions via L2P or via e-mail.
- If a task asks you to justify your answer, an explanation of your reasoning is sufficient. If you are required to prove a statement, you need to give a *formal* proof.
- This is the last exercise sheet. If you have gained at least **90.5 points in total** (40% of 226), you are admitted to the exam. If you have gained at least **59 bonus points** (70% of 84), you get a 0.3 bonus on your grade for the exam.

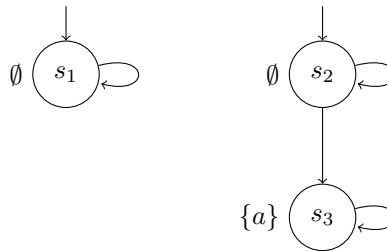
Exercise 1★

(2 + 3 Points)

- (a) Give a transition system TS without terminal states that contains two states s_1 and s_2 such that $s_1 \not\models_{\text{LTL}} s_2$ and there is *no* LTL formula φ with $s_2 \models \varphi$ and $s_1 \not\models \varphi$.
- (b) Let TS_1 and TS_2 be transition systems over AP without terminal states such that $\text{TS}_1 \not\models_{\text{CTL}} \text{TS}_2$. Prove or disprove: there exists a CTL formula Φ over AP such that $\text{TS}_1 \models \Phi$ and $\text{TS}_2 \not\models \Phi$.

Solution: _____

- (a) Consider the following states s_1, s_2 in the transition system TS below.



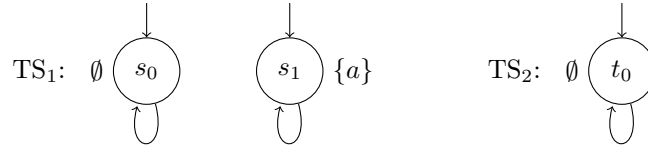
It is $s_1 \not\models_{\text{LTL}} s_2$, because for $\psi = \Box \neg a$ we have $s_1 \models \psi$ but $s_2 \not\models \psi$.

We observe that $\text{Traces}(s_1) \subseteq \text{Traces}(s_2)$ (*). Let φ be an arbitrary LTL formula. Then

$$\begin{aligned}
 & s_2 \models \varphi \\
 \iff & \text{Traces}(s_2) \subseteq \text{Words}(\varphi) \\
 \stackrel{(*)}{\implies} & \text{Traces}(s_1) \subseteq \text{Words}(\varphi) \\
 \implies & s_1 \models \varphi
 \end{aligned}$$

Consequently, there exists no LTL formula φ such that $s_2 \models \varphi$ and $s_1 \not\models \varphi$.

- (b) We disprove the claim. Consider the transition systems $TS_1 = (S_1, Act_1, \rightarrow_1, S_0^1, AP, L_1)$ and $TS_2 = (S_2, Act_2, \rightarrow_2, S_0^2, AP, L_2)$ below.



First of all, $TS_1 \not\models_{CTL} TS_2$, because $TS_2 \models \forall \Box \neg a$ and $TS_1 \not\models \forall \Box \neg a$.

Let Φ be an arbitrary CTL formula. Since $s_0 \sim t_0$, we have $s_0 \models_{CTL^*} \Phi \iff t_0 \models_{CTL^*} \Phi$. Then

$$\begin{aligned}
 & TS_1 \models \Phi \\
 \iff & \forall s \in S_0^1 . s \models \Phi \\
 \implies & s_0 \models \Phi \\
 \iff &^{s_0 \sim t_0} t_0 \models \Phi \\
 \iff &^{S_0^2 = \{t_0\}} \forall t \in S_0^2 . t \models \Phi \\
 \iff & TS_2 \models \Phi
 \end{aligned}$$

Consequently, there exists no CTL formula Φ such that $TS_1 \models \Phi$ and $TS_2 \not\models \Phi$.

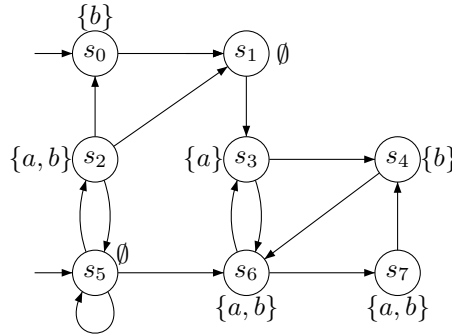
Exercise 2

(5 Points)

Consider the CTL*-formula (with derived operators) over $AP = \{a, b\}$

$$\Phi = \forall \Diamond \Box \exists \bigcirc (a \cup \exists \Box b)$$

and the transition system TS outlined below:



Apply the CTL* Model Checking algorithm to compute $Sat(\Phi)$ and decide whether $TS \models \Phi$.

Hint: You may infer the satisfaction sets for LTL formulas directly.

Solution: _____

We consider the maximal proper state subformulas $Sub(\Phi)$:

1. $\Psi = a$: $Sat(a) = \{s_2, s_3, s_6, s_7\}$
2. $\Psi = b$: $Sat(b) = \{s_0, s_2, s_4, s_6, s_7\}$
3. $\Psi = \exists \Box b$:

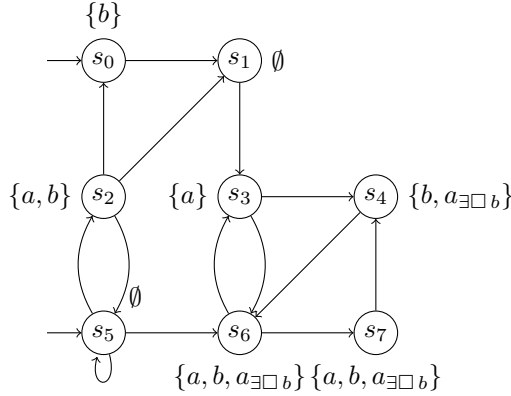
The following equivalence is used to compute $Sat(\exists \Box b)$:

$$s \models_{CTL^*} \exists \varphi \iff s \models_{CTL^*} \neg \forall \neg \varphi \iff s \not\models_{CTL^*} \forall \neg \varphi \iff s \not\models_{LTL} \neg \varphi$$

According to the LTL semantics, we have $Sat_{LTL}(\neg \Box b) = Sat_{LTL}(\Diamond \neg b) = \{s_0, s_1, s_2, s_3, s_5\}$. Then, $S \setminus Sat_{LTL}(\neg \Box b) = \{s_4, s_6, s_7\}$ is the satisfaction set $Sat_{CTL^*}(\exists \Box b)$:

$$Sat_{CTL^*}(\exists \Box b) = \{s_4, s_6, s_7\}.$$

The labelling is extended by a fresh atomic proposition $a_{\exists \Box b}$ according to $Sat_{CTL^*}(\exists \Box b)$. The corresponding subformula $\exists \Box b$ of Φ is replaced by $a_{\exists \Box b}$.



4. $\Psi = \exists \bigcirc (a \cup a_{\exists \Box b})$:

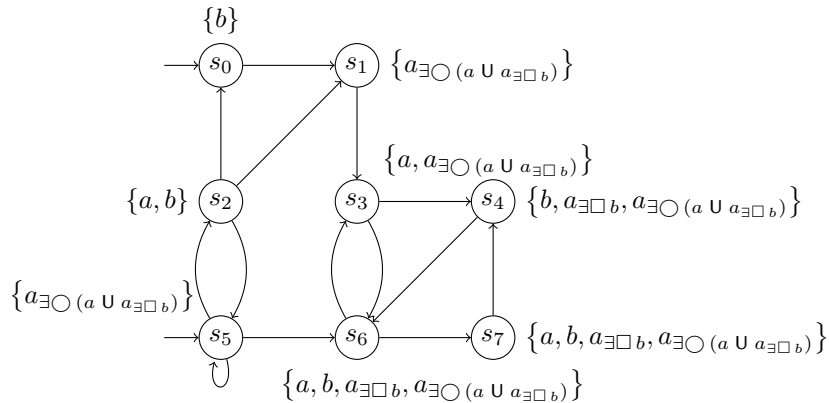
The above equivalence for existentially quantified path formulas yields:

$$s \models_{CTL^*} \exists \bigcirc (a \cup a_{\exists \Box b}) \iff s \not\models_{LTL} \neg \bigcirc (a \cup a_{\exists \Box b}).$$

By the equivalence $\neg \bigcirc (a \cup a_{\exists \Box b}) \equiv \bigcirc \neg (a \cup a_{\exists \Box b})$, the satisfaction set of $\neg (a \cup a_{\exists \Box b})$ can be inferred:

$$\begin{aligned} Sat_{LTL}(\neg (a \cup a_{\exists \Box b})) &= \{s_0, s_1, s_2, s_5\} \\ Sat_{LTL}(\bigcirc \neg (a \cup a_{\exists \Box b})) &= \{s_0, s_2\} \\ Sat_{CTL^*}(\exists \bigcirc (a \cup a_{\exists \Box b})) &= S \setminus Sat_{LTL}(\bigcirc \neg (a \cup a_{\exists \Box b})) \\ &= S \setminus \{s_0, s_2\} \\ &= \{s_1, s_3, s_4, s_5, s_6, s_7\} \end{aligned}$$

The labelling is extended by a new atomic prop. $a_{\exists \bigcirc (a \cup a_{\exists \Box b})}$ according to $Sat_{CTL^*}(\exists \bigcirc (a \cup a_{\exists \Box b}))$. Again, the corresponding subformula Ψ of Φ is replaced by $a_{\exists \bigcirc (a \cup a_{\exists \Box b})}$:



5. $\Psi = \forall \Diamond \Box a_{\exists \bigcirc (a \cup a_{\exists \Box b})}$:

In the case of universal quantification, we can directly apply the LTL-semantics:

$$Sat_{LTL}(\Diamond \Box a_{\exists \bigcirc (a \cup a_{\exists \Box b})}) = \{s_0, s_1, s_3, s_4, s_6, s_7\}.$$

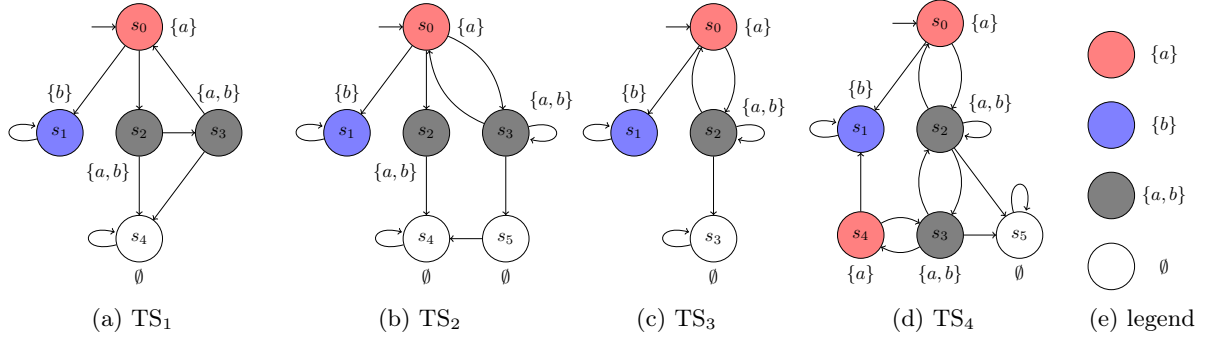
$$\text{Therefore, } Sat(\Phi) = Sat_{CTL^*}(\forall \Diamond \Box a_{\exists \bigcirc (a \cup a_{\exists \Box b})}) = \{s_0, s_1, s_3, s_4, s_6, s_7\}.$$

Because of $s_5 \in S_0$, but $s_5 \notin Sat(\Phi)$, this yields $TS \not\models_{CTL^*} \Phi$.

Exercise 3

(2+2 Points)

Consider the following transition systems TS_1, \dots, TS_4 .



- (a) Which transition systems are trace equivalent? Justify your answers by either providing the set of traces or a counterexample trace.
- (b) Which transition systems are bisimulation equivalent? Justify your answers by either providing a bisimulation relation or a CTL formula that distinguishes the considered transition systems.

Solution:

- (a) • $Traces(TS_1) \neq Traces(TS_2), Traces(TS_3), Traces(TS_4)$.

Consider the trace

$$\pi := \{a\} \{a, b\} \{a\} \{b\}^\omega.$$

It is $\pi \in Traces(TS_2), Traces(TS_3), Traces(TS_4)$ but $\pi \notin Traces(TS_1)$.

- $Traces(TS_2) = Traces(TS_3) = Traces(TS_4)$.

The traces are

$$Traces(TS_2) := \left\{ \left(\{a\} \{a, b\}^+ \right)^* \{a\} \{b\}^\omega, \left(\{a\} \{a, b\}^+ \right)^+ \emptyset^\omega, \left(\{a\} \{a, b\}^+ \right)^\omega, \left(\{a\} \{a, b\}^+ \right)^* \{a\} \{a, b\}^\omega \right\}$$

- (b) • $TS_1 \not\sim TS_2, TS_3, TS_4$.

A distinguishing formula is

$$\Phi_1 = \exists \bigcirc (a \wedge b \wedge \exists \bigcirc (a \wedge \neg b)).$$

Then $TS_1 \not\models_{CTL} \Phi_1$ but $TS_2, TS_3, TS_4 \models_{CTL} \Phi_1$.

- $TS_2 \not\sim TS_3, TS_4$.

A distinguishing formula is

$$\Phi_2 = \exists \bigcirc (a \wedge b \wedge \forall \bigcirc (\neg a \wedge \neg b)).$$

Then $TS_2 \models_{CTL} \Phi_2$ but $TS_3, TS_4 \not\models_{CTL} \Phi_2$.

- $TS_3 \sim TS_4$.

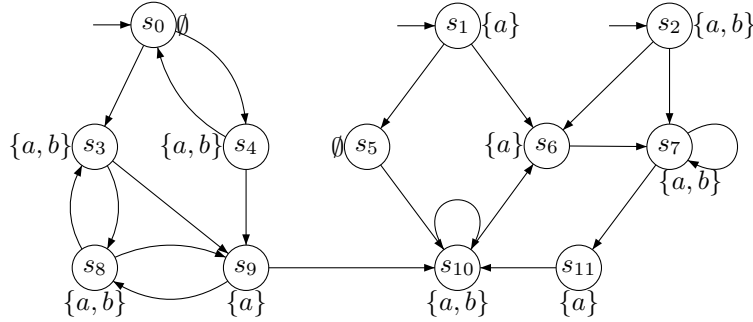
A bisimulation relation $\mathcal{R} \subseteq S_3 \times S_4$ is

$$\mathcal{R} := \left\{ (s_0, s_0), (s_0, s_4), (s_1, s_1), (s_2, s_2), (s_2, s_3), (s_3, s_5) \right\}.$$

Exercise 4

(3+3 Points)

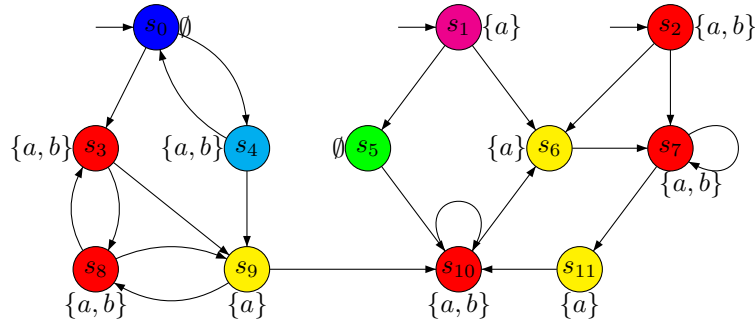
Consider the transition system TS over $AP = \{a, b\}$ outlined below:



- Determine the bisimulation equivalence \sim_{TS} and depict the bisimulation quotient system TS/\sim .
- For each bisimulation equivalence class C , provide a CTL formula Φ_C that holds only in the states in C .

Solution: _____

- The bisimulation equivalence classes are depicted in the following (indicated by color):

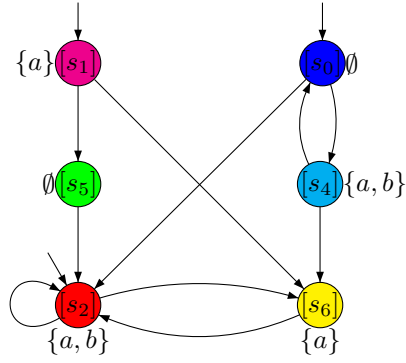


The bisimulation relation $\mathcal{R} \subseteq S \times S$ is given as

$$\begin{aligned} \mathcal{R} := & \left\{ (s_2, s_3), (s_2, s_7), (s_2, s_8), (s_2, s_{10}), (s_3, s_2), (s_3, s_7), (s_3, s_8), (s_3, s_{10}), \right. \\ & (s_7, s_2), (s_7, s_3), (s_7, s_8), (s_7, s_{10}), (s_8, s_2), (s_8, s_3), (s_8, s_7), (s_8, s_{10}), \\ & (s_{10}, s_2), (s_{10}, s_3), (s_{10}, s_7), (s_{10}, s_8), \\ & \left. (s_6, s_9), (s_6, s_{11}), (s_9, s_6), (s_9, s_{11}), (s_{11}, s_6), (s_{11}, s_9) \right\} \cup \mathcal{I} \end{aligned}$$

where $\mathcal{I} := \{(s, s) \mid s \in S\}$ is the identity relation.

Correspondingly, the bisimulation quotient system TS/\sim can be constructed as follows:



(b) Formulae that characterize the equivalence classes are:

$$\Phi_{[s_0]} = \neg a \wedge \neg b \wedge \exists \bigcirc \exists \bigcirc \neg a$$

$$\Phi_{[s_1]} = a \wedge \neg b \wedge \exists \bigcirc (\neg a \wedge \neg b)$$

$$\Phi_{[s_4]} = a \wedge b \wedge \exists \bigcirc (\neg a \wedge \neg b)$$

$$\Phi_{[s_5]} = \neg a \wedge \neg b \wedge (\forall \bigcirc \forall \bigcirc a)$$

$$\Phi_{[s_6]} = a \wedge \neg b \wedge \forall \bigcirc (a \wedge b)$$

$$\Phi_{[s_2]} = a \wedge b \wedge \forall \bigcirc a$$