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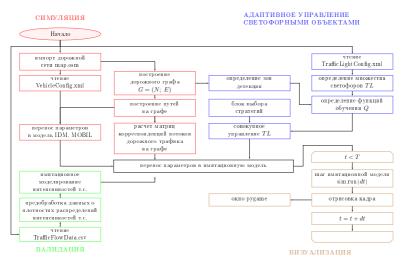
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$$(1) s' = (a \oplus s) = (a+s) \bmod |\mathcal{S}|.$$

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$$V(\{s_{t}, \delta_{t}\}) = \lim_{T \to \infty} V(T) = \sum_{t=0}^{\infty} \gamma^{t} r\left(s_{t+1} \mid s_{t}, \delta_{t}\right) =$$

$$= \sum_{t=0}^{\infty} \gamma^{t} r\left(s_{t}, \delta_{t}\right) = \lim_{T \to \infty} \mathbb{E}_{T} \sum_{t=0}^{T} \gamma^{t} R_{t},$$

$$= \sum_{t=0}^{\infty} \gamma^{t} r\left(s_{t}, \delta_{t}\right) = \lim_{T \to \infty} \mathbb{E}_{T} \sum_{t=0}^{T} \gamma^{t} R_{t},$$

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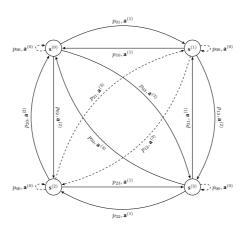
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a	s s'	$s^{(0)}$	s ⁽¹⁾	$s^{(2)}$	s ⁽³⁾	a	s'	$s^{(0)}$	$s^{(1)}$	$s^{(2)}$	s ⁽³⁾
${\bf a}^{(0)}$	s ⁽⁰⁾	1	0	0	0	a (2)	$s^{(0)}$	0	0	1	0
	s ⁽¹⁾	0	1	0	0		$s^{(1)}$	0	0	0	1
a · ·	s ⁽²⁾	0	0	1	0	a.	s ⁽²⁾	1	0	0	0
	s ⁽³⁾	0	0	0	1		$s^{(3)}$	0	1	0	0
$a^{(1)}$	s ⁽⁰⁾	0	1	0	0	$\begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}$ $\mathbf{a}^{(3)}$	$s^{(0)}$	0	0	0	1
	s ⁽¹⁾	0	0	1	0		$s^{(1)}$	1	0	0	0
	$s^{(2)}$	0	0	0	1		$s^{(2)}$	0	1	0	0
	s ⁽³⁾	1	0	0	0		$s^{(3)}$	0	0	1	0



$$\mathbf{s}' = \mathbf{a} \oplus \mathbf{s}.$$

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(4)
$$V(\mathbf{s}) = \sum_{t=0}^{\infty} \gamma^t r(\mathbf{s}_t, \mathbf{a}_t),$$

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(5)
$$V^* = \max_{a \in \mathcal{A}} \sum_{s' \in \mathcal{S}} p(s' \mid s, a) (r(s, a) + \gamma V^*(s')).$$

$$V^* \left(\{ \mathbf{s}_{t'}, \delta \}_{t'=0}^{t'=t} \right) = \max_{\mathbf{a} \in \mathcal{A}} Q_t(\mathbf{s}_t, \mathbf{a}),$$

$$Q_t(\mathbf{s}_t, \mathbf{a}) = \sum_{\mathbf{s}_{t+} \in \mathcal{S}} p(\mathbf{s}_{t+1} \mid \mathbf{s}_t, \mathbf{a}) \left(r(\mathbf{s}_{t+1} \mid \mathbf{s}_t, \mathbf{a}) + \gamma \max_{\mathbf{a}' \in \mathcal{A}} Q_{t-1}(\mathbf{s}_{t-1}, \mathbf{a}') \right).$$

$$Q_t(\mathbf{s}, \mathbf{a}) = \sum_{\mathbf{s}'} p(\mathbf{s}' \mid \mathbf{s}, \mathbf{a}) r(\mathbf{s}, \mathbf{a}) + \gamma \sum_{\mathbf{s}'} p(\mathbf{s}' \mid \mathbf{s}, \mathbf{a}) V^* \left(\mathbf{s}' \right).$$

$$Q_{t}(\mathbf{s}, \mathbf{a}) = \underbrace{p(s_{t+1}|s, a) \left(r_{t+1} + \gamma V^{*}(\mathbf{s}_{t+1})\right)}_{\alpha_{\hat{t}}} + \underbrace{\sum_{\mathbf{s}' \in S/\mathbf{s}_{t+1}} p(\mathbf{s}'|\mathbf{s}, \mathbf{a}) \left(r(\mathbf{s}'|\mathbf{s}, \mathbf{a}) + \gamma V(\mathbf{s}')\right)}_{1 - \alpha_{\hat{t}}} = \alpha_{\hat{t}} \left(r_{\hat{t}} + \gamma \max_{\mathbf{s}'} Q_{\hat{t}}(\mathbf{s}_{t+1}, \mathbf{s}')\right) + \left(1 - \alpha_{\hat{t}}\right) Q_{\hat{t}}(\mathbf{s}, \mathbf{a}) = Q_{\hat{t}+1}(\mathbf{s}, \mathbf{a}).$$

$$\begin{split} Q_{\hat{t}}^k(\mathbf{s}, a^k) &= \sum_{a^j \in \mathcal{A}^j} p(a^j \mid s, a^k) \Big(r(\mathbf{s}, \mathbf{a}^{kj}) + \\ &+ \gamma \sum_{\mathbf{a}'} p\left(\mathbf{s}, \mathbf{a}^{kj}\right) \max_{\mathbf{a}'} Q_{\hat{t}-1}(\mathbf{s}', \mathbf{a}') \Big). \end{split}$$

(7)
$$a_{\hat{t}}^k = \arg\max_{a^k \in \mathcal{A}^k} Q_{\hat{t}}^k(\mathbf{s}_{\hat{t}}, a^k).$$

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$$\rho(Q_n, Q_0) \leqslant \frac{\gamma^n \rho(Q_1, Q_0)}{1 - \gamma},$$

(8)
$$V^*(s) = \max_{a \in \mathcal{A}} \lim_{t \to +\infty} Q_t(s, a),$$

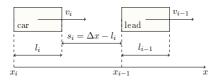
(9)
$$a_t(s) = \arg\max_{a' \in A} Q_t(s, a').$$

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highway	secondary	пїЅпїЅпїЅг
	terliary	пїЅпїЅпїЅп
	unclassified	пїЅпїЅпїЅп
lanes	str	пїЅпїЅпїЅі
oneway	bool	пїЅпїЅпїЅі
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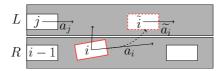
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(10)
$$\begin{cases} \frac{dv_{i}}{dt} = \underbrace{a_{i} \left(1 - \left(\frac{v_{i}}{v_{0,i}}\right)^{\delta}\right)}_{a_{\text{free}}} - \underbrace{a_{i} \left(\frac{s^{*}\left(v_{i}\Delta v_{i}\right)}{s_{i}}\right)^{2}}_{a_{\text{deceleration}}}, \\ s^{*}\left(v_{i}, \Delta v_{i}\right) = s_{0,i} + v_{i}T_{i} + \frac{v_{i}\Delta v_{i}}{\sqrt{2a_{i}b_{i}}}. \end{cases}$$

$$\begin{cases} \frac{dv}{dt}(t) = a_{\text{free}}(t) + a_{\text{deceleration}}(t), \\ v(t + \Delta t) = v(t) + \frac{dv}{dt}(t)\Delta t, \\ x(t + \Delta t) = x(t) + v(t)\Delta t + \frac{1}{2}\frac{dv}{dt}(t)(\Delta t)^{2}, \\ s(t + \Delta t) = x_{i}(t + \Delta t) - x(t + \Delta t) - l_{i}. \end{cases}$$

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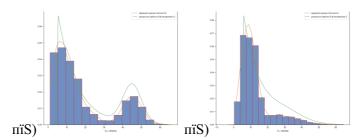
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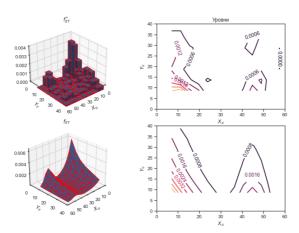
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(11)
$$H_{XY}(x,y) = C(F(x), G(y)), \quad \forall x, y \in \mathbb{R}.$$

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$$0 \le \alpha, \beta \le 1$$
(12) $C_{\alpha,\beta}(u,v) = uv \min(u^{-\alpha}, v^{-\beta}).$

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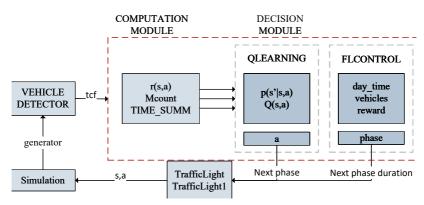


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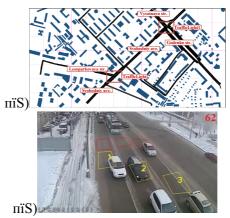
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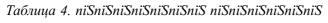
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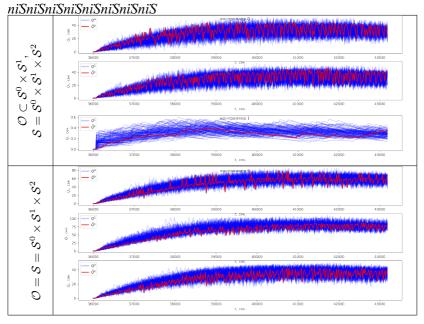
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ARTICLE TITLE

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Abstract: 150–200 words. Describes the standards of articles' formatting for "Large systems control" papers collection. Provides the examples for typical elements of an article. 150–200 words. Describes the standards of articles' formatting for "Large systems control" papers collection. Provides the examples for typical elements of an article. 150–200 words. Describes the standards of articles' formatting for "Large systems control" papers collection. Provides the examples for typical elements of an article. 150–200 words. Describes the standards of articles' formatting for "Large systems control" papers collection. Provides the examples for typical elements of an article.

Keywords: large systems control, electronic scientific publication, article formatting template.

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Поступила в редакцию ... Дата опубликования ...