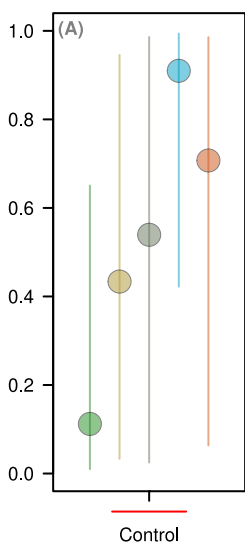


Probability of moving > 20cm



Δ Probability from control

