Challenges of The Week

1. Get the robot to spin in circles

2. Get the robot to run forwards for 3 sec then stop. Turn 90° left, and run forwards for 3 sec.

3. Get the robot to keep moving until it is on top of a black line (bottom of page)
   ↳ Then it should stop, turn 90° left, and run forwards for 2 sec
   ↳ <u>Bonus</u> make it work with reflected light values

4. Get the robot to follow a black line