



# Performance Analysis of Clock Synchronization using IEEE 1588 Protocol

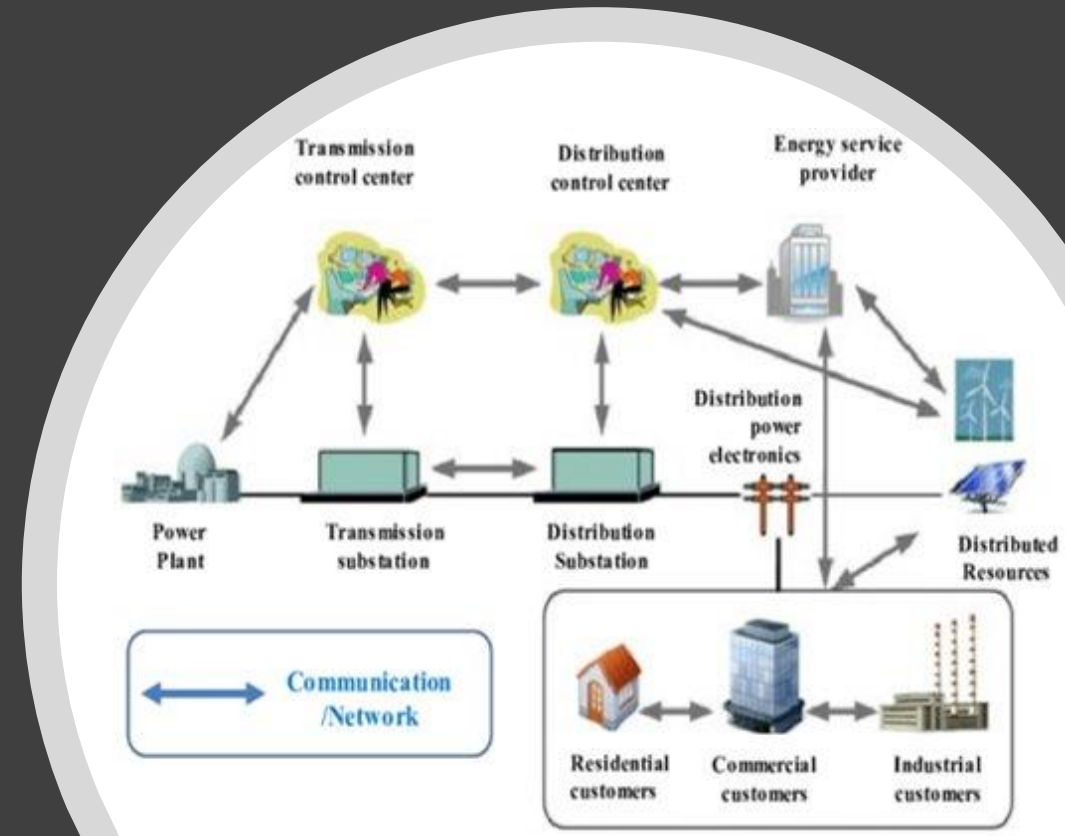
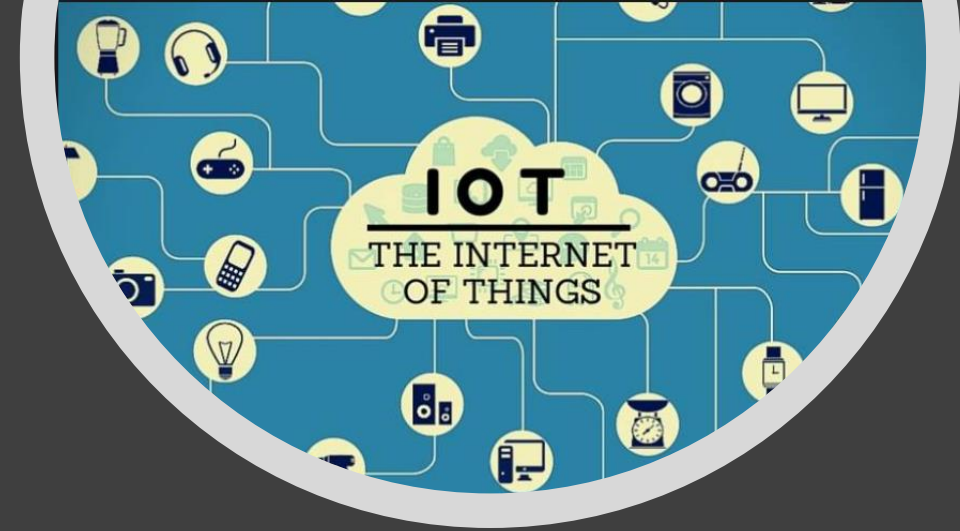
Tinghui Wang, and Partha Sarker

# Introduction

Clock Synchronization is a must for monitoring any Distributed system

## Applications:

- Smart Grid
- Smart Environments
- IoT System



# Requirements of Clock Synchronization in Smart Grid

Application	Requirement
Traveling Wave Fault Detection and Location	100 to 500 ns
Synchrometrology (synchrophasors) Wide Area Protection Frequency Event Detection Anti-Islanding Droop Control Wide Area Power Oscillation Damping (WAPOD)	Better than 1 $\mu$ s
Line Differential Relays	10 to 20 $\mu$ s
Sequence of Events Recording	50 $\mu$ s to ms
Digital Fault Recorder	1 ms
<b>Communication Events</b>	
Substation Local Area Networks (IEC 61850 GOOSE)	100 $\mu$ s to 1 ms
Substation Local Area Networks (IEC 61850 Sample Values)	1 $\mu$ s

Source: National Institute of Standards and Technology (NIST)

# Existing Solutions

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IEEE 1588 Precision Time Protocol (PTP)

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eLOnge-RAnge Navigation (eLORAN)

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Iridium

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Network Time Protocol (NTP)

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Radio (e.g. NIST WWVB time signal radio station)

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Atomic clocks

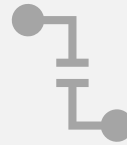
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Different types of terrestrial and satellite-based  
propagation solutions

# Clock Synchronization in LAN



Network topology change



Bursts of network traffic in case of faults detected in the power system



Security attacks including denial of service (DoS), masquerade and multi-cast poisoning

# IEEE 1588 Precision Time Protocol (PTP)



Self-organizing protocol



Small requirements on the network bandwidth and computation footprint on endpoints or network devices

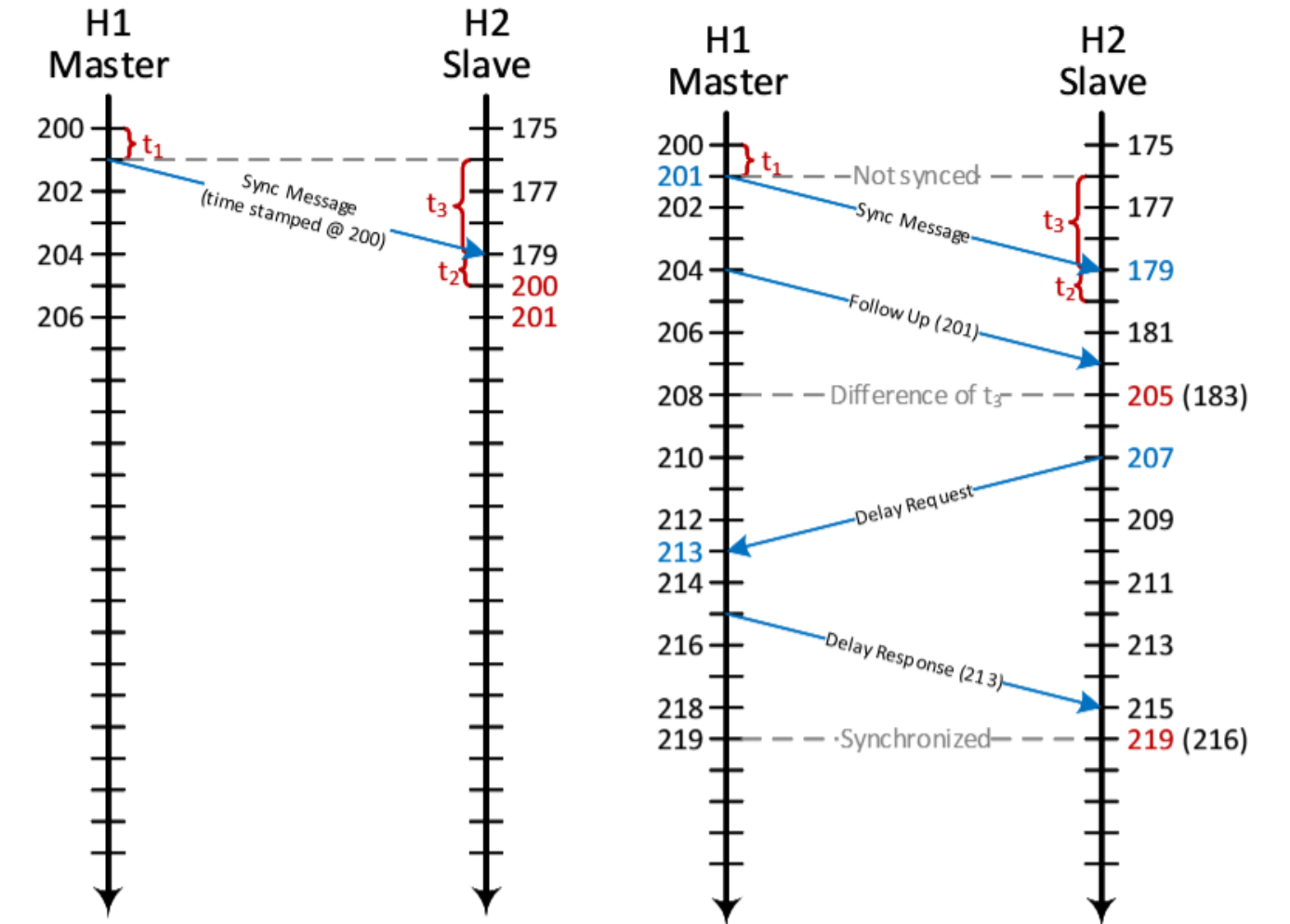


Can achieve precise time synchronization in local area network (LAN) up to several nanosecond with help of hardware time stamping.



Two versions : IEEE 1588-2002 v1 and IEEE 1588-2008 v2.

# PTP Simple Example



# PTP Time Synchronization

$$\tau_2 = \tau_1 + \Delta_t + 0.5 T_{RTT}$$

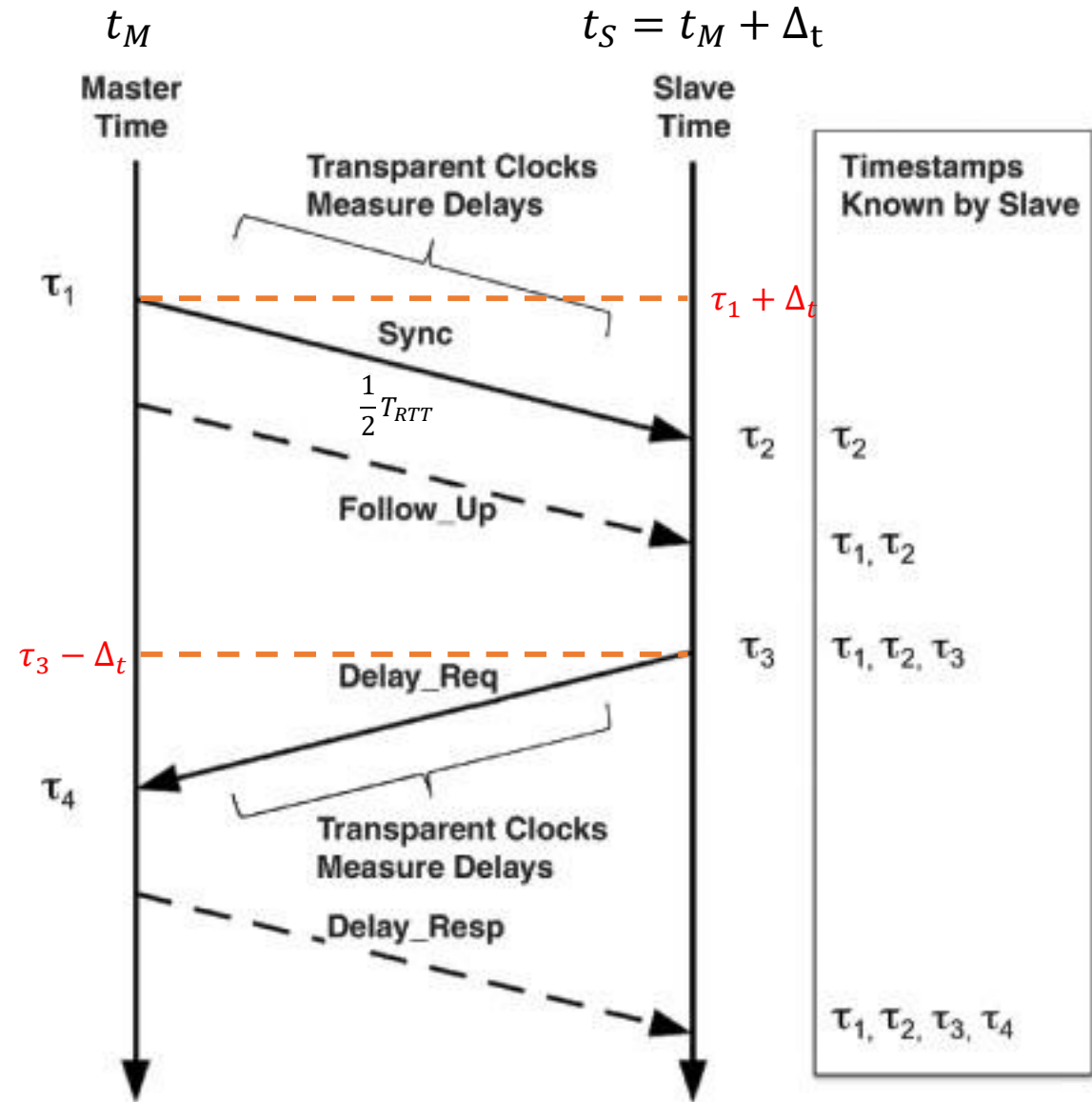
$$\tau_4 = \tau_3 - \Delta_t + 0.5 T_{RTT}$$

- Offset  $\Delta_t$

$$\Delta_t = \frac{(\tau_2 - \tau_1) - (\tau_4 - \tau_3)}{2}$$

- Delay  $T_{RTT}$

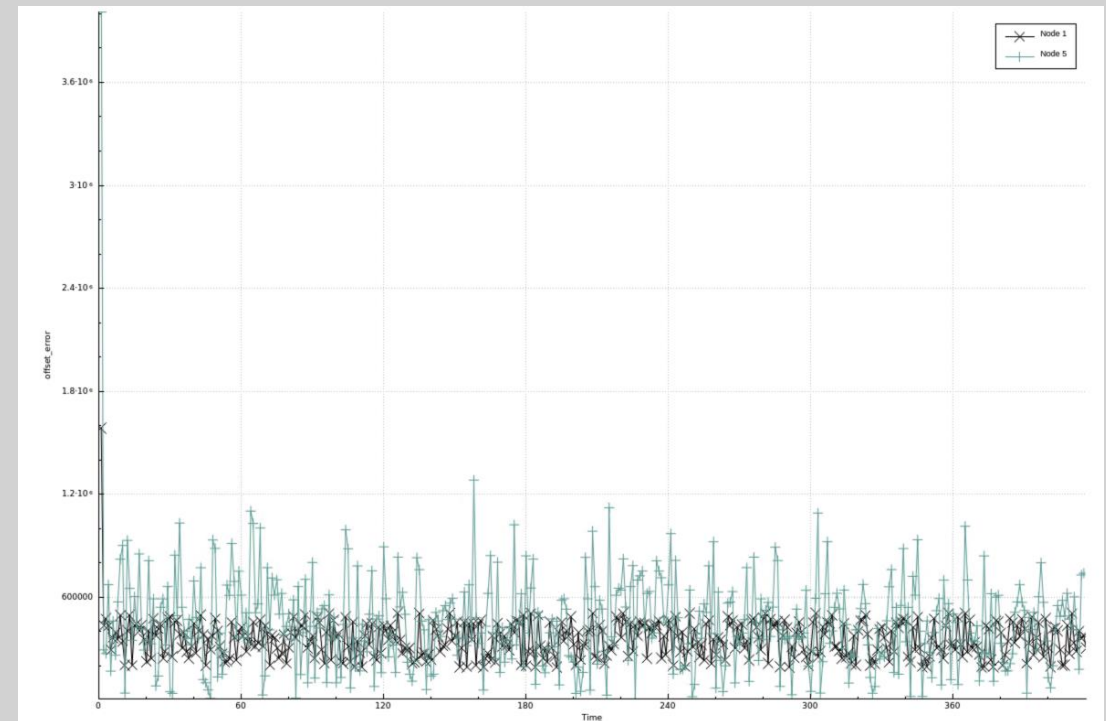
$$T_{RTT} = (\tau_2 - \tau_1) + (\tau_4 - \tau_3)$$



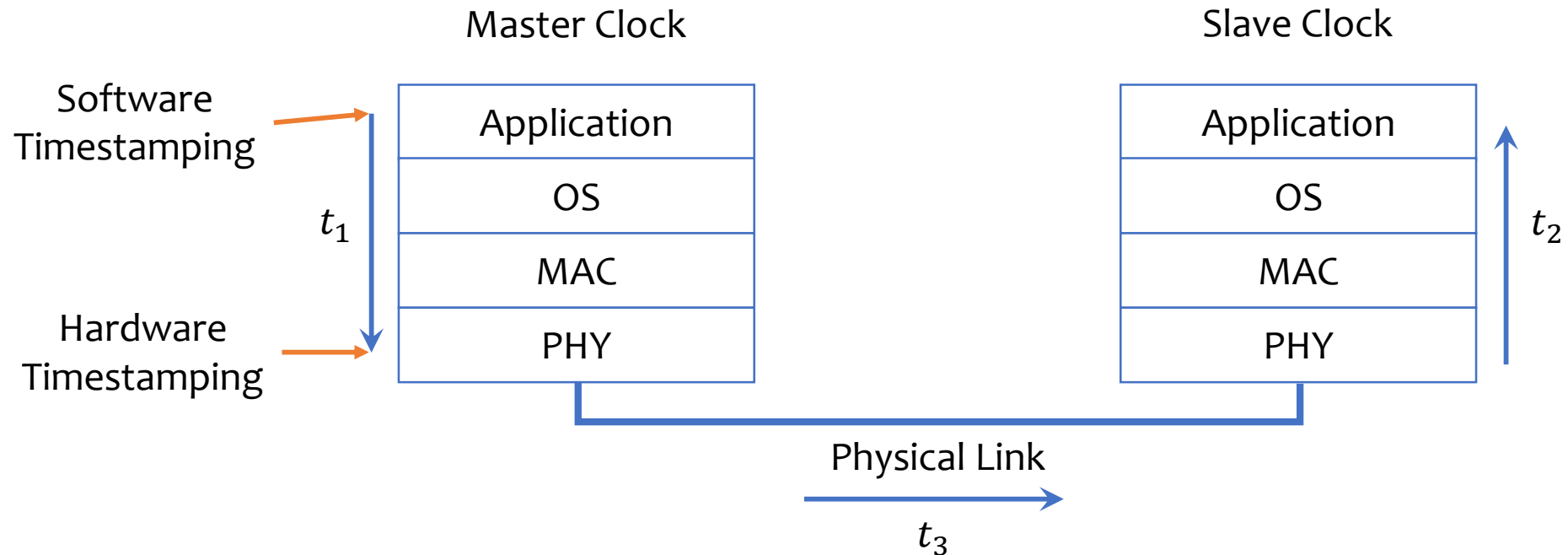


# PTP Simulation Example

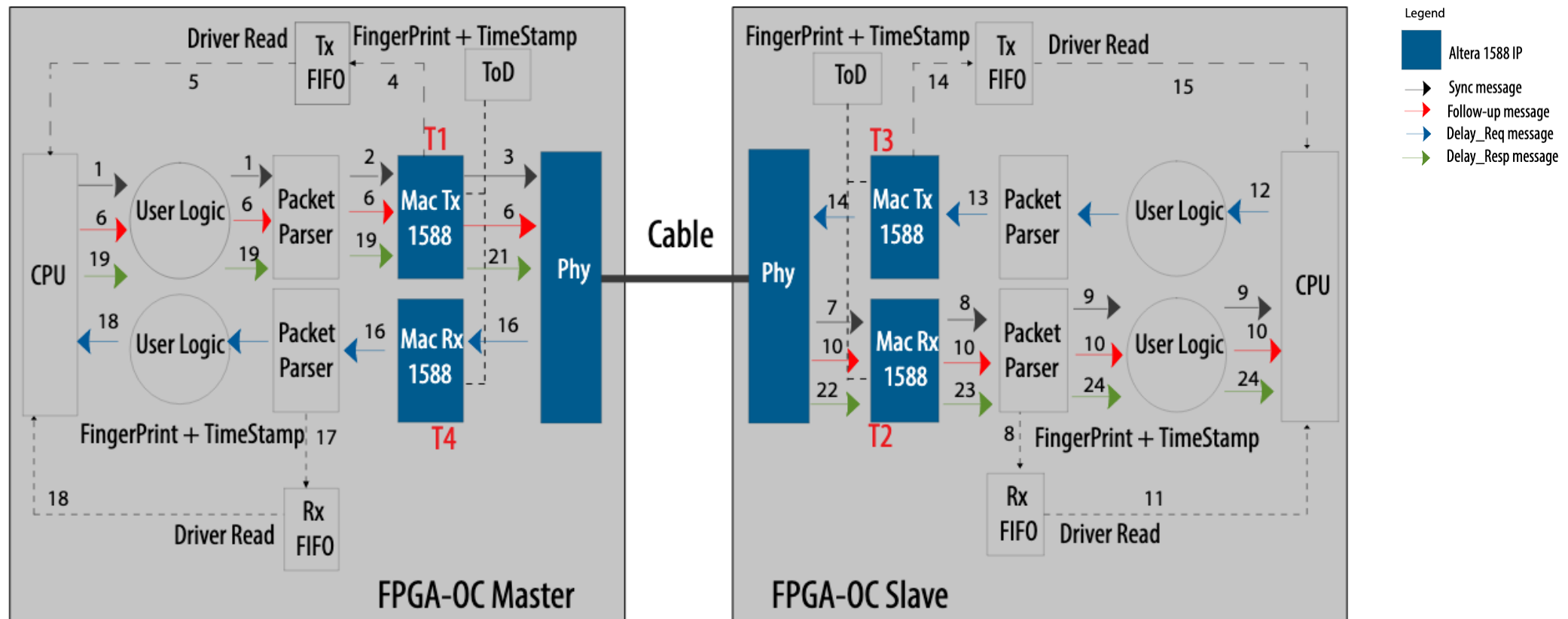
- Simulator: NS-3
  - Simulator virtual time
- Network Environment:
  - Wifi 802.11b adhoc OFDM
- Network Topology
  - $0 \Rightarrow 1 \Rightarrow 2 \Rightarrow 3 \Rightarrow 4 \Rightarrow 5$



# To Achieve High Precision



# IEEE 1588 Hardware Timestamping



# To Achieve High Precision

- Uncertainty in Network Delay
  - Point-to-Point Synchronization
  - Network Traffic
- Local Filtering
  - PI Filtering
  - Kalman Filtering

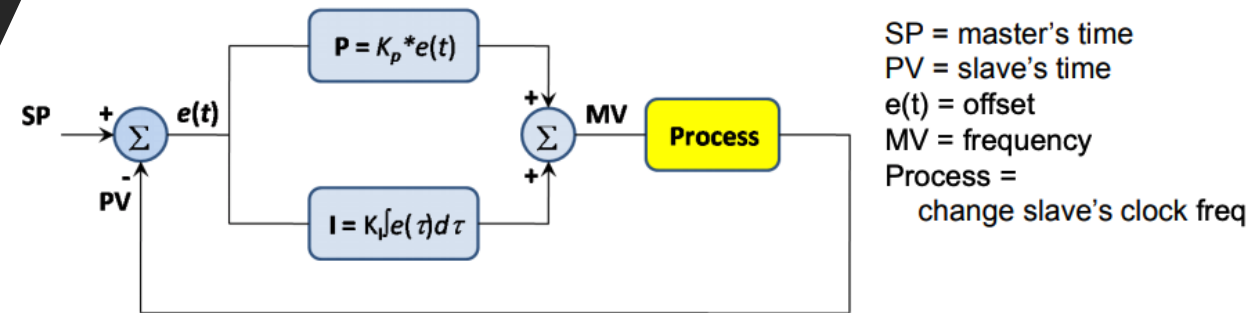
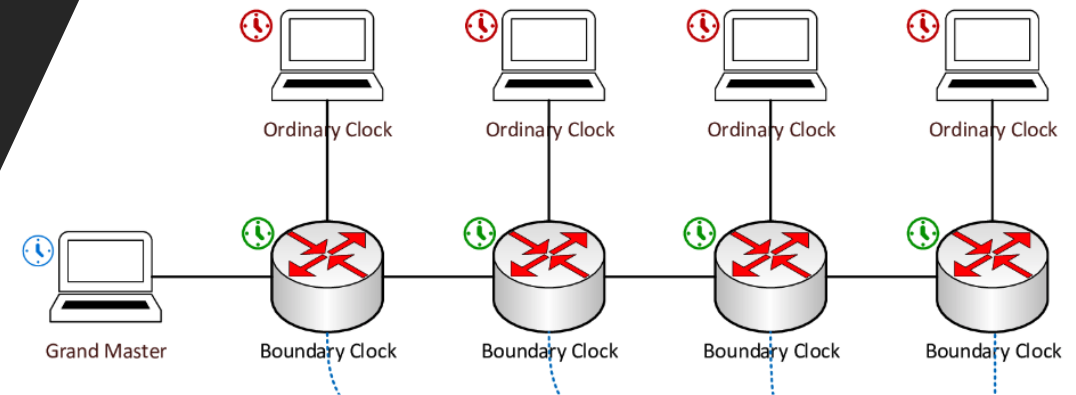


Figure: Basic block of Proportional + Integral controller. (excerpt from wikipedia)

# Security Issues

## Delay Attack:

- Constantly add delay in one direction

## Multicast:

- Inject announcement and sync from false PTP master

## Unicast:

- Capture switch/router, impersonate global master or alter sync message