COMP1002 DATA STRUCTURES AND ALGORITHMS

LECTURE 7: HASH TABLES



Discipline of Computing

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This Week

- Hashtables and hashing
- Properties of a good hashtable
- Collisions and collision handling methods
 - Open addressing (probing) approaches
 - Separate chaining
- Hashtable Big-O analysis
- Some good hash functions and poor hash functions

Hash Tables – Hashing

- A hash table stores each data element using an associated key
 - The key is later used to find the element efficiently
 - Hash tables convert the key into an index via an arithmetic function and then place the data at this index
 - This conversion is referred to as "hashing": applying an arithmetic function to a key to map it to a location (index) in an array for storing the data associated with that key
 - The arithmetic function is called the hashing function
 - The location it maps a key to is called the hash index

A Simple Example

- Simple hash function: add up the letters in a string
 - How is this possible? Because chars are actually numbers
 - The application just reinterprets them as symbols for the user
 - Char values are encoded according to Unicode standard
 - ASCII is a subset of Unicode for the European alphabets
 - Unicode is actually an extension of ASCII in order to handle non-Latin languages such as Mandarin, Japanese, Arabic, etc
 - So let's have a look at the ASCII character set...

ASCII Character Set

Ctrl	Dec	Hex	Char	Code	Dec	Hex	Char
^@	0	00		NUL	32	20	
^A	1	01		SOH	33	21	!
^В	2	02		STX	34	22	::
^C	3	03		ETX	35	23	#
^D	4	04		EOT	36	24	\$
^E	5	05		ENQ	37	25	%
^F	6	06		ACK	38	26	&
^G	7	07		BEL	39	27	'
^Н	8	08		BS	40	28	(
^I	9	09		нт	41	29)
^]	10	0A		LF	42	2A	*
^K	11	0B		VT	43	2B	+
^L	12	0C		FF	44	2C	`
^M	13	0D		CR	45	2D	-
^N	14	0E		so	46	2E	•
^0	15	0F		SI	47	2F	/
^P	16	10		DLE	48	30	0
^Q	17	11		DC1	49	31	1 2 3
^R	18	12		DC2	50	32	2
^S	19	13		DC3	51	33	3
^T	20	14		DC4	52	34	4
^U	21	15		NAK	53	35	5
^V	22	16		SYN	54	36	4 5 6 7
^w	23	17		ETB	55	37	7
^X	24	18		CAN	56	38	8
^Y	25	19		EM	57	39	9
^Z	26	1A		SUB	58	3A	:
^[27	1B		ESC	59	3B	89 ٧
^\	28	1C		FS	60	3C	<
^]	29	1D		GS	61	3D	=
^^	30	1E	A	RS	62	3E	= >?
^-	31	1F	▼	US	63	3F	?

Dec	Hex	Char
64	40	@
65	41	Ă
66	42	B
67	43	C
68	44	D
69	45	E
70	46	F
71	47	G
72	48	H
73	49	I
74	4A	J
75	4B	K
76	4C	L
77	4D	M
78	4E	N
79	4F	0
80	50	P
81	51	Q
82	52	R
83	53	S
84	54	T
85	55	U
86	56	V.
87	57	W
88	58	X
89	59	<u>Y</u>
90	5A	Z
91	5B	[
92	5C	ABCDEFGHIJKLMNOPQRSTUVWXYZ[/]
93	5D]
94	5E	^

Dec	Hex	Char
96	60	'
97	61	a
98	62	a b c d e f g h i j k l
99	63	c
100	64	d
101	65	e
102	66	f
103	67	g
104	68	h
105	69	i
106	6A	j
107	6B	k
108	6C	
109	6D	m
110	6E	n
111	6F	m n o p q r s t u
112	70	p
113	71	q
114	72	r
115	73	S
116	74	t
117	75	u
118	76	V
119	77	w
120	78	x
121	79	у
122	7A	Z
123	7B	{
124	7C	
125	7D	}
126	7E	У Z { } ~ å
127	7F	0

Dec	Hex	Char
128	80	
129	81	ii l
130	82	ě
131	83	â
132	84	ä
133	85	à
134	86	å
135	87	Ç
136	88	ê
137	89	ë
138	8A	è
139	8B	i
140	8C	î
141	8D	ì
142	8E	Ä
143	8F	Å
144	90	É
145	91	æ
146	92	Æ
147	93	ô
148	94	ö
149	95	Ò
150	96	û
151	97	ù
152	98	ÿ
153	99	Ö
154	9A	Ü
155	9B	¢
156	9C	£
157	9D	子大子の(の:0:0/C:C/C) (0:0
158	9E	
150	OF	t l

Dec	Hex	Char
160	A0	á 1 to tu n N a
161	A1	ĺ
162	A2	Ó
163	А3	ű
164	A4	ñ
165	A5	Ñ
166	A6	₫
167	Α7	<u>o</u>
168	A8	خ
169	Α9	<u>و</u> خ ای
170	AA	٦.
171	AB	1/2
172	AC	1/4 i
173	AD	i
174	AE	<<
175	AF	>>
176	В0	8
177	B1	
178	B2	
179	В3	Ī
180	B4	ļ -ļ
181	B5	=
182	В6	H
183	В7	i
184	В8	7
185	В9	
186	ВА	
187	вв	'n
188	вс	T
189	BD	
190	BE	7
191	BF	٦

			ır
Dec	Hex	Char	
192	C0	L	
193	C1	1	
194	C2	Ţ	
195	C3	-	
196	C4		
197	C5	+==	
198	C6	=	
199	C7	l ⊩	
200	C8	L.	
201	C9	[
202	CA		
203	СВ	Ī	
204	CC	╠	
205	CD	=	
206	CE	# _	
207	CF		
208	D0	1	
209	D1	丁	
210	D2	Т	
211	D3	L	
212	D4	L	
213	D5	Г	
214	D6	Г	
215	D7	₩	
216	D8	 _	
217	D9		
218	DA	<u>_</u>	
219	DB		
220	DC		
221	DD	L	
222	DE		
223	DF		

1	Dec	Hex	Char
1	224	E0	ox
	225	E1	В
	226	E2	Г
	227	E3	П
	228	E4	Σ
	229	E5	σ
	230	E6	μ
	231	E7	۲
	232	E8	δ
	233	E9	θ
	234	EΑ	⊕└≡┗╏╏┸┝汲⊕ਊ७8ΦШ□□+△↘←─→÷≋०•
	235	EB	δ
	236	EC	œ
	237	ED	Ф
	238	EE	E
	239	EF	N
	240	F0	■
	241	F1	±
	242	F2	5
	243	F3	2
	244	F4	ſſ
	245	F5	J
	246	F6	+
	247	F7	≈
	248	F8	0
	249	F9	
	250	FA	
	251	FB	1
	252	FC	n
	253	FD	2
	254	FE	•
	255	FF	

ASCII Character Set

- So each letter can be converted into a number...
 - Range of ASCII values is 0-255
 - Each character can then be represented using a byte = 2⁸

Examples:

- "0" (zero) is 48 in decimal ← numbers are all less than letters
- "**9**" is 57
- "A" is 65 "Z" is 90
- "a" is 97 ← this is how "apple" is less than "bear" and "zombie"
- "**z**" is 122
- "!" is 33
- Hex values are more interesting:
 - 0011 0001 is "1" clear bits 4-5 to convert from character to num (0000 0001)
 - 0100 0001 is "A" and 0110 0001 is "a" set or clear bit 5 to convert

ASCII Character Set

- Notice the blank chars early on...
 - These are special 'control' chars, some of which have been defined as special 'escape characters' \x in Java/Python/C/C++
 - Examples:
 - 10 is LF (line feed), which is '\n' in
 - 13 is CR (carriage return), which is '\r'
 - Under Linux, end-of-line is \n. Under Windows, eol is \r\n
 - 0 is NULL which is '\0'
 - Particularly important in C for null-terminated strings
 - 9 is HT (horizontal tab) == '\t'
 - Not all these control chars have escape chars
 - These are typically unprintable characters (don't show up) or produce odd symbols depending on the display program
 - e.g. Notepad will show a □

A Simple Example

Back to the example: hash function for string keys

```
FUNCTION hashFunction IMPORT key (string) EXPORT hashIndex (integer)
hashIndex ← 0
FOR ii ← 0 TO len(key)-1 DO
hashindex ← hashindex + key.charAt(ii)

hashIndex ← hashindex % hashArray.length // We'll discuss this line later
```

Java

- key.charAt(ii) returns the char at index ii (zero-based)
- Since chars are numbers, we can add them to an int arithmetically.
- So "abcde" would be:
 - hashldx = 'a'+'b'+'c'+'d'+'e'; // =495
- Python
 - Use ord() function to get ASCII values
 - hashindex = hashindex + ord(key[ii])

Hashing

- So a hash table has two major components:
 - Array: (table) to store the data
 - Hash function: to map keys to integer indexes in the array
- When a new element is to be added, both a key and data must be provided to the hash table
 - The hash table hashes the key and stores both the key and data at the calculated hash index
 - Key must be unique
 - Thus time complexity is the time it takes to perform the hash calculation
 O(?) plus the O(1) array access time
 - Accessing data in the hash table is the same

Hash Table – Example

hash("Flintstone")
returns 3

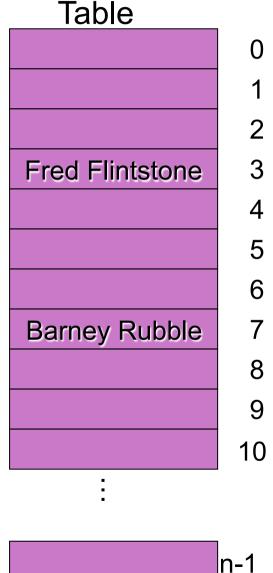
"Flintstone"
hash function

hash("Rubble")
returns 7

"Rubble"
hash function

Keyed on last name

Hash function converts each key to a (hopefully different!) hash index



HASH FUNCTIONS

Properties of a Good Hash Function

- A good hash function should:
 - 1. Return indexes that fit within the size of the array
 - *i.e.,* [0 .. arrayLength-1]
 - 2. Be fast to compute
 - The hash function is a critical factor in access time
 - 3. Be repeatable (i.e., always return same index) for a given key
 - 4. Distribute keys evenly over the full range of the array
 - This is to minimise collisions, a major issue in hash tables
- Properties 1–3 are easy to ensure, Property 4 is not
 - You don't know what keys you'll be getting in advance, so it's not possible to ensure they will be evenly distributed

Property 1: Hash Indexes Must Fit Table

- Let's consider a simple hash function that operates on integer keys (e.g., student IDs)
 - A bad implementation would be:

- What's the problem with it?
 - Key can be larger than table.length or possibly negative, this will make hashIndex out of the table's index range.

Property 1: Hash Indexes Must Fit Table

- So why not make the table big enough to handle any integer key that we expect from the application?
 - That's a waste of space: there are far fewer actual data items than the number of possible key values
 - e.g., Student IDs are large numbers that track all students ever (~15 million), but there are only ~50,000 current students
 - We thus only want to reserve space for 50,000, not all 15m
- What the hash function must do is 'compress' the range of the key down into the range of the table
 - Easy to do! Just take the modulus of the hashIndex
 - Although there are better and worse modulus values...

Property 1: Hash Indexes Must Fit Table

 The obvious modulus is the table's length, since any integer's remainder will then fit inside the table

```
FUNCTION hashFunction IMPORT key (integer) EXPORT hashIndex (integer)
hashIndex ← key % table.length
```

- Prime numbers often make good modulo values
 - Primes will usually distribute the keys most evenly
 - ... although it does depend somewhat on the hash function used
 - So when allocating the table, size it with a prime number
 - ideal prime sizes are as far as possible from powers of 2
 - 769, 1543, 3079, 6151, 12289, 24593, 49157, 98317 etc.
 - If the user is allowed to specify the max size of the hash table in the constructor, round the max up to the nearest prime number
 - Finding the next prime can be done by incrementing a starting candidate value and testing for primality an $O(N^{\frac{1}{2}})$ problem

Finding the Next Prime

```
FUNCTION findNextPrime IMPORT startVal (integer) EXPORT prime (integer)
IF (startVal % 2 == 0) THEN
   primeVal ← startVal + 1
                                           ← Even numbers are never prime, so make it odd
ELSE
  primeVal ← startVal
ENDIF
                                           ← Pre-decrement since we will be looking for the NEXT prime,
primeVal ← primeVal - 2
                                             but want to include start Val as a candidate
isPrime ← FALSE
WHILE (NOT isPrime)
                                           ← There is always a prime number to be found
                                           ← Next candidate
   primeVal ← primeVal + 2
   // Test if primeVal candidate is actually a prime number
   ii ← 3
   isPrime = TRUE
                                                   ← No need to check beyond sqrt(primeVal)
   WHILE (ii*ii <= primeVal) AND (isPrime)</pre>
                                                        (if the values up to ii are not whole divisors, the final
      IF (primeVal % ii == 0) THEN
          isPrime ← FALSE
                                                         (ii-1)/primeVal percentile won't be divisors either)
       ELSE
          ii \leftarrow ii + 2
                                                      ← Skip testing with even numbers
       ENDIF
   ENDWHILE
ENDWHILE
```

Finding the Next Prime (improved)

```
FUNCTION findNextPrime IMPORT startVal (integer) EXPORT prime (integer)
IF (startVal % 2 == 0) THEN
   primeVal ← startVal -1
                                          ← Even numbers are never prime, so make it odd 1 less as primeval+2
ELSE
 primeVal ← startVal
ENDIF
isPrime ← FALSE
                                   // Test if primeVal candidate is actually a prime number
DO
                                                     ← Next candidate
   primeVal ← primeVal + 2
   ii ← 3
   isPrime = TRUE
   rootVal = SQRT primeVal
                                                     ← No need to check beyond sqrt(primeVal)
   DO
                                                       (if the values up to ii are not whole divisors, the final
      IF (primeVal % ii == 0) THEN
          isPrime ← FALSE
                                                        (ii-1)/primeVal percentile won't be divisors either)
       ELSE
                                                     ← Skip testing with even numbers
          ii ← ii + 2
       ENDIF
   WHILE (ii <= rootVal) AND (isPrime)</pre>
WHILE (NOT isPrime)
                                                     ← There is always a prime number to be found
```

Property 2: Fast to Compute

- In general, access time in a hash table is:
 - (speed of hash function) + (speed of array access)
 - Array access is O(1), so the hash function is the limiting factor
- Fortunately, hash functions can be pretty fast
 - The hash function only needs to operate on the key
 - Thus it will take constant time regardless of how many elements exist in the hash table (exact time depends on hash func)
 - Constant time complexity: $O(k) \rightarrow \approx O(1)$
 - e.g., consider string keys (such as LastName)
 - Time complexity = $O(L) \approx O(1)$, where L = average name length
 - Independent of table size N, hence stays O(1) regardless of N

Property 3: Repeatable

- A hash function is useless if it returns different hash indexes every time for the same key
 - It won't be able to remember where it stored keys/values!
- Solution: Avoid using time-varying values in the calculation of the hash function
 - e.g., no random numbers, date/time, or hash table statistics
- Issue: Table size must be used as the modulo!
 - Resizing the table means hash function modulo changes
 - Thus you must re-hash all existing entries after a resize
 - *i.e.*, rebuild the hash table from scratch, re-inserting each existing element again into the new hash table

Property 4: Distributes Keys Evenly

- The toughest property to achieve
 - It is very difficult to even evaluate that a hash function distributes evenly
 - Need to perform statistical tests with a large set of sample keys
 - The problem is that you don't quite know what keys you will be receiving from an application
 - You can often see (in the code) if a hash function will be poor, but guaranteeing a hash function will be good is more difficult
 - Fortunately, much effort has already gone into developing hash functions that work well for a range of typical keys
 - e.g., dictionary words, names, etc.

Collisions

- Let's take a little detour and discuss some issues affecting hash tables
 - This will help with understanding how Property 4 (Evenly Distributed) can be best achieved
 - ... or at least in realising when it isn't achieved!
- A collision is when two (or more) keys map to the same hash index
 - Not a good thing, but must be expected to occur at least sometimes since the hash function 'compresses' the range of the key into the range of the hash table size
 - Unless you are lucky, some keys will hash to the same index

Collisions

- Since collisions are inevitable, we must handle them
- First: Never fill up the hashtable
 - The fuller the table, the more likely a collision
 - Try to avoid going over about 50% full (rough rule of thumb)
 - i.e., allocate about twice as much space as you expect to use
 - But don't go too sparsely-populated (< 10%) waste of space!
- Second: Use a collision-handling method
 - There are four typical approaches, split into two broad categories: open addressing and separate chaining

Collision Handling Methods

- Open Addressing: Upon a collision, jump forward ('probe') a set amount to a new index and try again
 - If the new index is also used, repeat the probe until an empty index is found
 - 1. <u>Linear Probing</u> probe by step size of one every time
 - 2. Quadratic Probing probe forward by (probeNum)²
 - *i.e.*, probe first by 1, then 4, then 9, 16, 25, 36, 49, ...
 - 3. <u>Double Hashing</u> use a *secondary* (different) hash function on the key to generate the probe step length
- 4. <u>Separate Chaining:</u> Key-value pairs are added to a linked list anchored at the colliding hash index

Property 4: Distributes Keys Evenly

- Why do we need even (*i.e.*, uniform) distribution?
 - Consider the opposite case: all keys hash to index 0
 - This means all keys end up at the same position
 - i.e., every key collides worst case!
 - Inserting the Nth item takes O(N) probes (for linear/quad probing)
 - Sep-chaining is O(1), double-hashing will vary but won't be good
 - Accessing an item takes (on average) N/2 probes = O(N)
 - Even for separate chaining and (probably) double-hashing
 - Terrible: we should be getting O(1) from our hash table on both!
 - Uniform = each key maps to a different index

- Let's take a look at a couple of hash functions proposed for use in hashtables
 - Only given in Java and here for your interest not examinable!
 - These operate on either Strings or byte arrays so that they can apply to any type of data
 - A string can be considered a byte array that is limited to text values (alphanumerics, punctuation and symbols)
 - They are by no means 'optimal', since optimality will depend on your actual keys being used
 - And nobody can predict that in advance!
 - Still, they are pretty good at distributing 'average' keys evenly amongst the table
 - Code assumes that hashArray is the hash table array

Java's hashCode() implementation for String class

```
private int hash(String key)
{
  int hashIdx = 0;

  for (int ii = 0; ii < key.length(); ii++) {
    hashIdx = (31 * hashIdx) + key.charAt(ii);
  }
  return hashIdx % hashArray.length;
}</pre>
```

- Strange (often prime) numbers like 31 are popular
- A variant is the 'Bernstein' hash function
 - Uses 33 instead of 31 apparently this is even more effective in practice hash functions are black magic!

Another fairly simple but good hash function

```
private int hash(byte[] key)
{
  int a = 63689;
  int b = 378551;
  int hashIdx = 0;

  for (int ii = 0; ii < key.length; ii++)
  {
     hashIdx = (hashIdx * a) + key[ii];
     a *= b;
  }
  return hashIdx % hashArray.length;
}</pre>
```

- Non-commutative multiplications by weird numbers a and b are apparently important here
 - Again, only borne out in practice

FNV Hash

- More complex and does a lot of integer overflow
 - It's not the complexity that makes it better, but in practice this is a pretty good hash
 - See http://www.isthe.com/chongo/tech/comp/fnv/

Shift-Add-XOR Hash

```
private int hash(byte[] key)
{
   int hashIdx = 0;
   for (int ii = 0; ii < len; ii++) {
      hashIdx = hashIdx ^ ( (hashIdx << 5) + (hashIdx << 2) + key[ii] );
   }
   return hashIdx % hashArray.length;
}</pre>
```

- Bit shifting is also pretty common in good hash functions
 - It's a fast way to take a number to a power-of-2
 - But it's not the bit-shifting itself that makes it a good hash!

ELF Hash

Another bit-shifter: quite old, and reasonably good too

Poor Hash Functions

Take-the-first-value:

```
private int hash(byte[] key)
{
   hashIdx = key[0];
   return hashIdx % hashArray.length;
}
```

- Very poor:
 - Collisions with keys that start with the same value
 - Hash indexes will also only be between 0...255
 - Means slots past 255 can never be used

Poor Hash Functions

Add-them-all-up:

```
private int hash(byte[] key)
{
   int hashIdx = 0;
   for (int ii = 0; ii < len; ii++) {
      hashIdx += key[ii];
   }
   return hashIdx % hashArray.length;
}</pre>
```

- Poor:
 - Collisions when two keys are an anagram of one another
 - Eg: "fred", "derf", "rfde" all hash to the same index
 - Changing the add to a multiply doesn't help any either anagrams still produce the same hash index

Poor Hash Functions

XOR-them-all-together:

- Poor:
 - Hash indexes will also only be between 0...255
 - Means slots past 255 can never be used

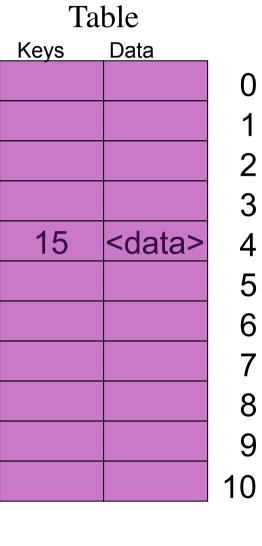
COLLISION HANDLING

Linear Probing

- Upon a collision, add 1 to the index and try again
 - Repeatedly probe by 1 until a free slot (bucket) is found
 - Remember to wrap-around the array!
 - *i.e.,* if hash index == tableLen-1, then stepping by 1 will exceed the table size. In this case, we must 'wrap' and probe to index 0
- Linear probing is simple to implement, but has some unfortunate consequences if collisions build up
 - See the next slides for an example

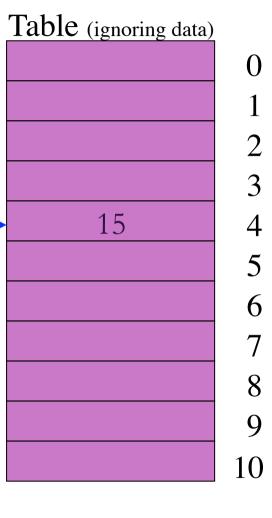
Basic (poor!) hash function:

Keys:



Basic (poor!) hash function:

Keys:

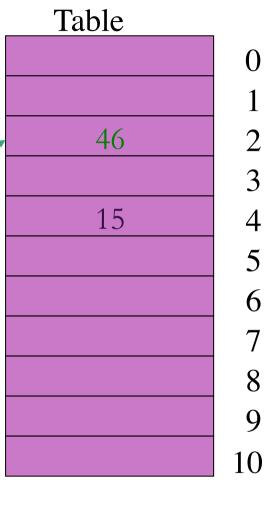


Basic (poor!) hash function:

FUNCTION hashFunction IMPORT key (integer) $\qquad \qquad \text{EXPORT hashIndex (integer)} \\ \text{hashIndex} \leftarrow \text{key } \$ \ 11$

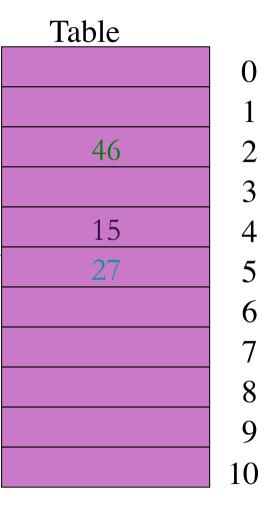
Keys:

15



Basic (poor!) hash function:





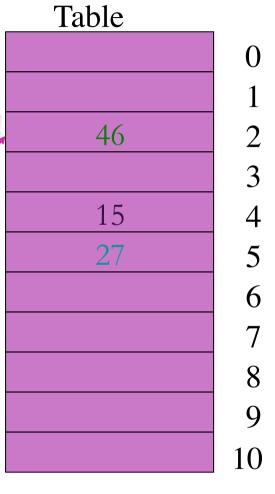
Basic (poor!) hash function:

FUNCTION hashFunction IMPORT key (integer Collision!

EXPORT hashIndex (integer)

hashIndex ← key % 11





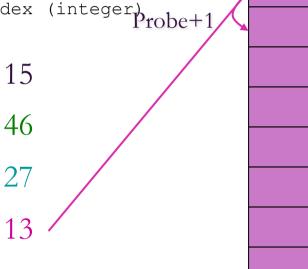
Basic (poor!) hash function:

FUNCTION hashFunction IMPORT key (integer)

EXPORT hashIndex (integer)

hashIndex ← key % 11

Keys:

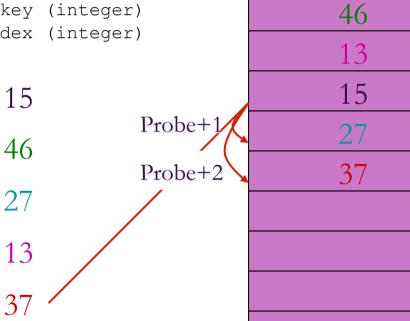


Table

0
1
2
2 3 4 5 6 7
4
5
6
7
8 9
10

Basic (poor!) hash function:

Keys:



Table

3

6

9

Linear Probing – Analysis

- When collisions occur, linear probing tends to create clusters of filled slots
 - Since it probes one step at a time, it always fills in gaps
 - ... thus creating blocks of filled indexes
 - This is called primary clustering
 - Primary clusters will slow down access time
 - Need multiple probing steps to find end of the primary cluster
 - And then insertion at the end makes the cluster even larger/worse!
 - e.g., try inserting 24 into the previous table
 - Can make fast O(1) insertion degrade considerably, especially if table gets pretty full

Primary Clusters

Basic (poor!) hash function:

```
FUNCTION hashFunction IMPORT key (integer)

EXPORT hashIndex (integer)

hashIndex ← key % 11

• Keys:

15

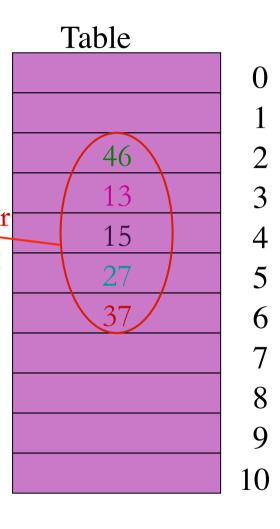
Primary cluster

from probing

46

27

13
```



Primary Clusters Table Basic (poor!) hash function: FUNCTION hashFunction IMPORT key (integer) EXPORT hashIndex (integer) hashIndex ← key % 11 Keys: O(5) insertion when N=5!

Quadratic Probing

- Exactly like linear probing, except that the step-size increases at each probe iteration
 - In particular, stepSize = probeNum^2
 - *i.e.*, probe1 = +1, probe2 = +4, probe3 = +9, probe4 = +16, *etc.*
 - Hence called *quadratic* probing (due to squaring of probe)
- The increasing step-size means that more gaps will be left in the table when probing
 - Avoids (or at least greatly reduces) primary clusters
 - Step size increases by > 1 as well: means that a probe can 'leap' past a cluster

Quadratic Probing Table Basic (poor!) hash function: FUNCTION hashFunction IMPORT key (integer) 46 EXPORT hashIndex (integer) 3 hashIndex ← key % 11 Keys: 15 15 Probe+1 46 6 27 Probe+4 13 37 8 9 10

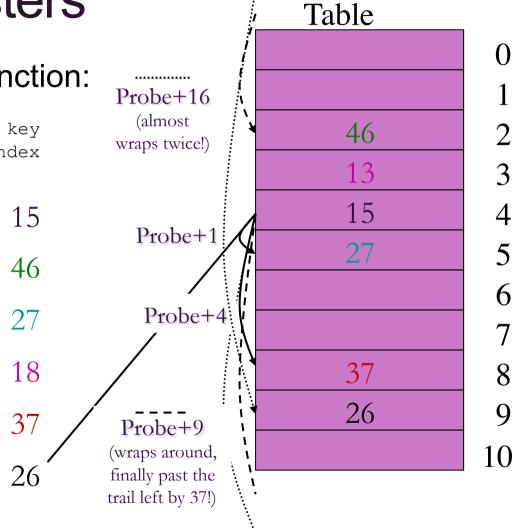
Quadratic Probing – Analysis

- Doesn't get primary clusters since step-size > 1
 - Ensures that gaps are left between step jumps
- Not inefficient: deal with (multi-)wrap-around via modulo
 - newHashIdx = (origHashIdx + probeNum^2) % tblSize
- But does get secondary clusters
 - Multiple keys mapping to the same hash index: the initial collision then
 occurs on the same place as a previous value's initial collision, so the new
 value will follow the exact same path as the previous collider
- Also, can't guarantee it will visit all slots
 - Step size always increasing: may miss empty slots

Secondary Clusters

Basic (poor!) hash function:

FUNCTION hashFunction IMPORT key EXPORT hashIndex hashIndex \leftarrow key % 11



- Quadratic probing's increasing-step-size is an issue
 - Cannot guarantee that all slots will be visited
 - So if only one free slot, the quadratic stepping might miss it
 - Although hash tables aren't usually that full
- The secondary clustering is also an issue: inefficient
- Double hashing seeks to solve these problems
 - Calculate a step size based on the key
 - Each key will have its own step-size increment
 - Greatly reduces secondary clustering
 - Step-size for a given key won't change, thus with a prime-sized table it is *guaranteed* to be able to visit all slots
 - Because no common divisor between step-size and table-size

- Step-size calc is done by a second hash function
 - Simple hash functions are good enough: we aren't overly concerned with even distribution since it's just step-size
 - Define a maximum step-size and make that the modulo
 - Must not produce 0 step sizes though
 - A good secondary hash function is:

- MAX_STEP should be small-ish; certainly << table size!
- Use a prime number for MAX_STEP

Basic (poor!) hash function:

15

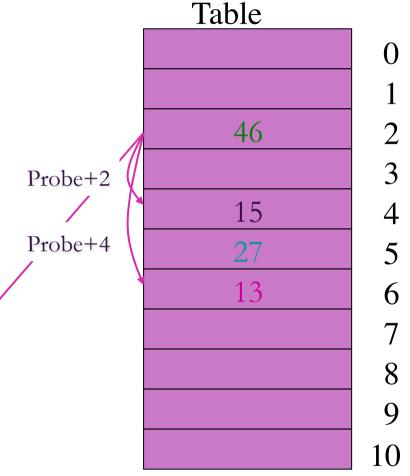
46

27

Secondary hash:

FUNCTION stepHash IMPORT key
EXPORT hashStep

 $hashStep \leftarrow 5 - (key % 5)$



Basic (poor!) hash function:

15

46

27

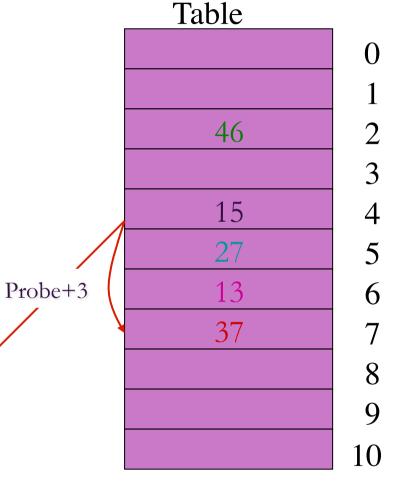
13

FUNCTION hashFunction IMPORT key EXPORT hashIndex hashIndex \leftarrow key % 11

Secondary hash:

FUNCTION stepHash IMPORT key EXPORT hashStep

 $hashStep \leftarrow 5 - (key % 5)$



Basic (poor!) hash function:

15

13

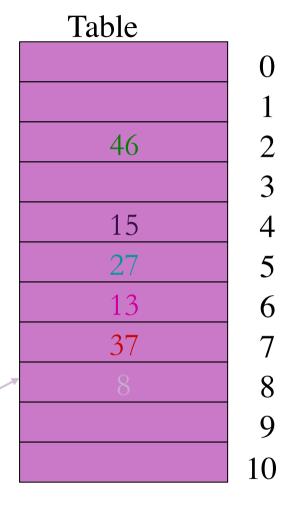
37

```
FUNCTION hashFunction IMPORT key EXPORT hashIndex hashIndex \leftarrow key % 11
```

Secondary hash:

FUNCTION stepHash IMPORT key 46
EXPORT hashStep

hashStep \leftarrow 5 - (key % 5) 27



• Basic (poor!) hash function:

FUNCTION hashFunction IMPORT key

EXPORT hashIndex

15

46

27

13

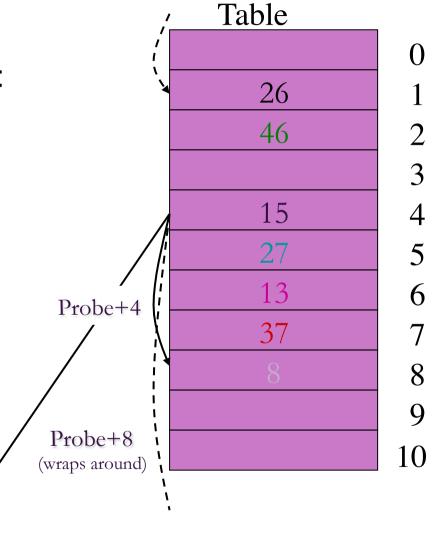
37

Secondary hash:

hashIndex ← key % 11

FUNCTION stepHash IMPORT key EXPORT hashStep

 $hashStep \leftarrow 5 - (key % 5)$



Double Hashing – Analysis

- No primary OR secondary clustering
 - Since step sizes will often be > 1, gaps will be left when probing, thus primary clusters are unlikely
 - Each key has its own step-size, so no secondary clusters
- Having a prime table length is important here:
 - Guarantees that an empty slot will be found, since no common divisor between table length and any step size
 - Otherwise 'resonances' can occur when wrapping-around to the beginning of the table during probing – you'd keep visiting the same slots on each pass, and hence miss other slots

Separate Chaining

- The previous approaches used probing on collisions
- Separate chaining uses an entirely different method
 - Make each hashtable entry a pointer to a linked list
 - When a collision occurs, the new key-value pair is simply added to the linked list
 - That way, all items are stored at their key's hash index position
 - Collisions just mean that a chain (linked list) of items are stored at the colliding hash index position

Separate Chaining – Analysis

- This makes for quite different behaviour
 - Must 'probe' by traversing across the linked lists
 - No limits on the amount of items you can put in
 - Although performance still degrades as the table fills up
 - O(1) insertion ... no matter how full the table is
 - Just insert the new item at the front of the linked list
 - But still can degrade to O(N) for access/removal
 - Just like open addressing, but now traversing the linked list
 - But makes things more complicated
 - Every entry is now a linked list : extra coding
 - Space overhead of 'next' pointers is also unavoidable: every entry is now data + next pointer

Separate Chaining

Basic (poor!) hash function:

```
FUNCTION hashFunction IMPORT key

EXPORT hashIndex
hashIndex ← key % 11

• Keys:

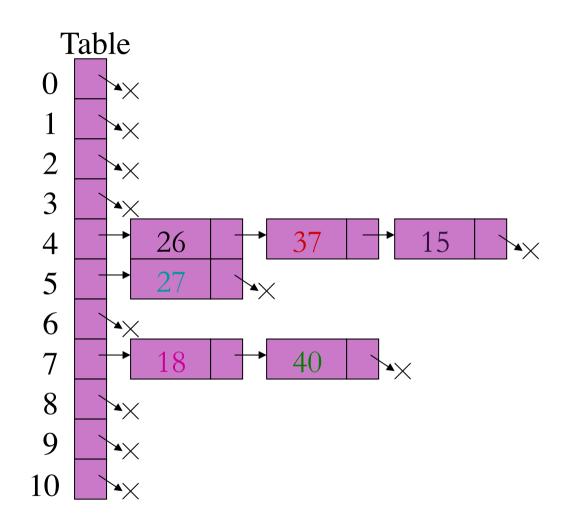
15

40

27

18

37
```



ACCESSING AND REMOVING

Acessing Values in a Hashtable

- So far, we've focused on inserting key-value pairs
- But accessing a value already in the hashtable is almost the same:
 - The main difference is that instead of hashing and finding a free slot, we instead hash and find the key
 - Thus we must store the key as well as the value in the table
 - Otherwise we won't know whether we are at the right value

Accessing Values in a Hashtable

- Separate chaining: hash the key to retrieve the hash index, then search the linked list to find that key
- Open addressing: hash the key and probe (according to the probing algorithm used in insertion) until we find that key
 - We can abort early if we hit an empty slot, since this indicates that the key isn't even in the table
- Depending on how many collisions have occurred, access time can vary from O(1) to O(N)
 - But it will generally be at the lower end: O(1)
 - ...unless the load factor of hashtable is high

Removal of Items From a Hash Table

- Removal in separate chaining is easy enough:
 - Just find the item to remove (same as accessing) and delete it from the linked list it resides in
- Open addressing seems easy:
 - Just probe to the item (same as accessing) and make the slot empty so that it is free for subsequent inserts
 - There's a small problem with this:
 - Accessing relies on finding empty slots to conclude that the key is not in the table and so abort probing
 - But now we just removed an item that may have been in the middle of a chain of historical probes

Open Addr Removing Issue Table

Basic (poor!) hash function:

Assume linear probing

14010	
	0
	1
46	2
13	2 3 4 5 6 7
15	4
27	5
37	6
24	7
	8
	8 9
	10

Open Addr Removing Issue Table

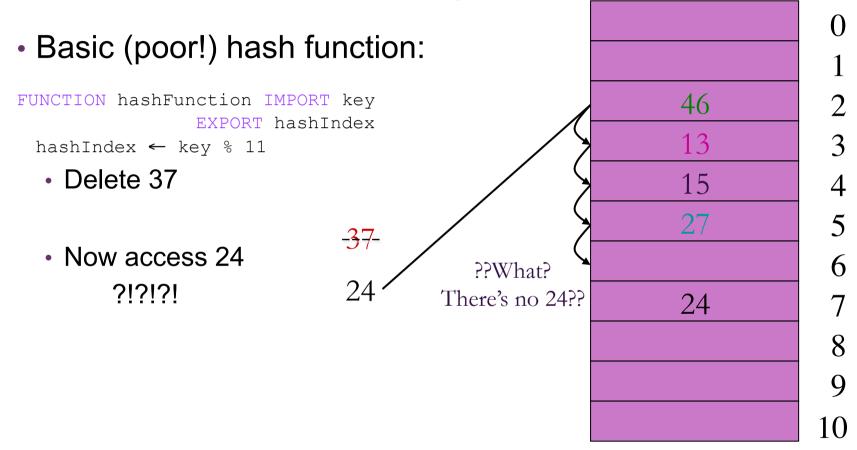
Basic (poor!) hash function:

FUNCTION hashFunction IMPORT key EXPORT hashIndex hashIndex \leftarrow key % 11

• Delete 37

	0
	1
46	2
13	2 3 4 5 6 7 8 9
15	4
27	5
3 7-	6
24	7
	8
	9
	10

Open Addr Removing Issue Table



Removal Solution

- The solution for removal is to mark a removed slot as "free-but-formerly-used"
 - Tells access probes that the key it is looking for might be found further down due to the removal
 - Thus access probes can only stop once it encounters a "free-and-never-been-used" slot
 - This does not affect insert: insert still adds to first free slot
 - This can be a problem for hashtables that experience a lot of adds and removes (e.g., due to long lifetime)
 - Eventually, all slots will be marked as "free-but-formerly-used"
 - re-build the hashtable!
 - Which means access time for keys that aren't in the table degenerates to O(N):
 - only if the key exists can it stop early

Linear Probing – PseudoCode

ENDFOR

```
CLASS DSAHashEntry
FIELD key (String)
                                                                ← Can be any appropriate data type
FIELD value (Object)
                                                                ← So that we can store any kind of data values!
                                                                \leftarrow 0 = never used, 1 = used, -1 = formerly-used
FIELD state (int)
CONSTRUCTOR IMPORT nothing
key ← ""
value ← null
state ← 0
                                                                  There are other ways to do this!
CONSTRUCTOR IMPORT inKey, inValue
kev ← inKev
value ← inValue
state ← 1
CLASS DSAHashTable
FIELD hashArray (DSAHashEntry array)
                                                                 ← The actual hashtable
                                                                 ← Number of items inserted in the hashtable
FIELD count (int)
CONSTRUCTOR IMPORT tableSize
actualSize ← NextPrime(tableSize)
allocate hashArray[actualSize]
FOR ii ← 0 TO actualSize-1 DO
                                                                 ← Initialise entries
   hashArray [ii] ← allocate HashEntry
```

Linear Probing – PseudoCode

```
METHOD get IMPORT inKey EXPORT retValue
hashIdx \leftarrow hash(inKey)
origIdx \leftarrow hashIdx
                                                      ← Just in case the hashtable is 100% full!
found ← FALSE
giveUp ← FALSE
WHILE (NOT found) AND (NOT giveUp) DO
   IF (hashArray[hashIdx].state = 0) THEN
                                                                ← Stop if we hit a never-used entry
       giveUp = TRUE
   ELSEIF (hashArray[hashIdx].key = inKey)
                                                                ← Check if this is the key we want
       found = TRUE
   ELSE
      hashIdx \leftarrow (hashIdx + 1) % hashArray.length
                                                                ← Probe, handling wrap-around
      IF (hashIdx = origIdx) THEN
          qiveUp = TRUE
                                                                ← Stop if we have checked all nodes
      ENDIF
   ENDIF
ENDWHILE
IF (NOT found) THEN
                                                                  ← ie: throw an exception
   ABORT
ENDIF
retValue = hashArray [hashIdx].value
```

Linear Probing – PseudoCode

- You work out the other methods in the practical
- UML Class diagrams hint:

DSAHashEntry

key (String)
value (Object)
state (int)

- + CONSTRUCTOR/INIT(nothing)
- + CONSTRUCTOR/INIT(inKey, inValue)
- + SETTERS/GETTERS (or private inner class in Java justify)

DSAHashTable

hashArray (DSAHashEntry array)
count (int)

- + CONSTRUCTOR/INIT(tableSize)
- + put(inKey, inValue)
- + get(inKey)
- + remove(inKey)
- + getLoadFactor()
- + export()
- resize(size)
- hash(inKey)
- stepHash(inKey)
- nextPrime(inNum)
- findKey(inKey) (optional methods)
- findEmpty(inKey)
- + indicates "public" methods and "—" is used for private methods.
- In Python, everything is public, but we can use an underscore to show something is "private" e.g. _hash(inKey)

Load Factor

- Notice collisions are more likely if the table has more items in it
 - More items means less unused slots
- Load factor is a measure of how 'full' a hash table is

$$LF = \frac{numItems}{tableCapacity}$$

- Has important consequences for the frequency of collisions in openaddressing (probing) approaches
 - Similar for separate chaining but not as catastrophic, as we will see

Load Factor and Collisions – Open Addr

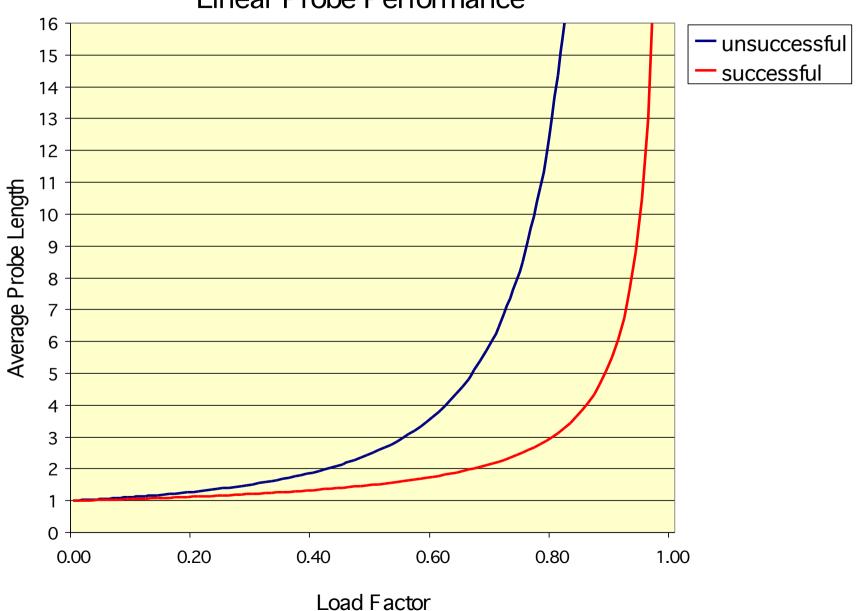
- In <u>open addressing</u>, load factor directly indicates the proportion of used slots
 - LF = 0.0: collision is impossible (nothing to collide with!)
 - LF = 1.0: collision is guaranteed (all slots are filled!)
 - And worse: no free slots means you can't insert the new item!
 - LF cannot exceed 1.0 in open addressing approaches
 - Can't put in more items than there are table slots!
 - Collisions will increase as we move from LF = 0.0 to 1.0
 - Exactly what the curve looks like depends on the hash function; better (uniform)
 hash functions will only get bad at higher LFs

Load Factor and Collisions - Sep. Chain

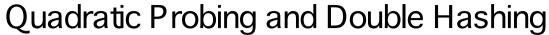
- Separate chaining is not so badly affected
 - Insertion in separate chaining is always O(1)
 - Only access/deletion time is affected
 - Consider: LF = 1.0 indicates that each slot has, on average, 1 entry in the linked list for that slot
 - Some entries will have more, some entries will have none
 - Thus access time will be, on average, O(2)
 - In comparison: with probing methods, access time depends on the number of probes, which is often >> 1 when LF $\rightarrow 1.0$
 - Access time increases as LF increases: approx O(LF)
 - But only on average: some individual slots may be very full

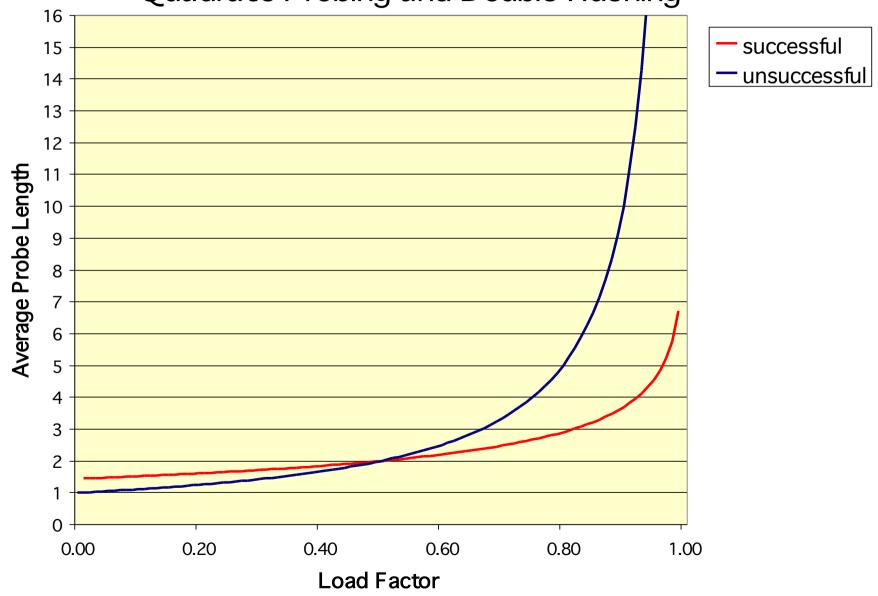
Load Factor Impact:





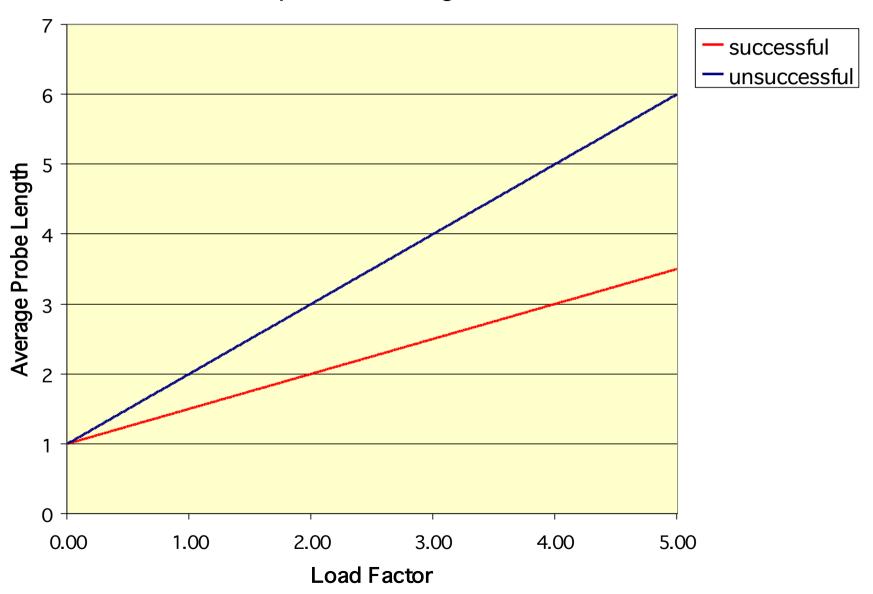
Load Factor Impact:





Load Factor Impact:

Separate-Chaining Performance



Performance Conclusions

- For open addressing, make sure the hash table isn't too full
 - i.e., Keep the load factor below 0.6 or 0.7
- But don't make the table too big
 - LF < 0.4 means 60% of the table is unused (wasted) space
- Not so much of a problem for separate chaining
 - Overall, separate chaining tends to be less 'brittle', but also more complex to implement since you need the linked lists

Collision-Handling Comparison

- Separate chaining pros (vs open addressing methods)
 - \square O(1) insertion regardless of how full the table is
 - ✓ No limit on number of items that can be stored
 - i.e., load factor can exceed 1.0
 - ☑ Performance is better with higher load factors
 - ✓ No need to specially mark slots with removed items
 - The linked list will automatically 'close up' the gap
- Separate chaining cons

 - Node pointer memory overhead for each element
 - Access time tends to be slower when load factor is low

Collision-Handling Comparison

- Linear probing (vs other open addressing approaches):
 - ☑ Simplest open addressing approach
 - ☑ Will always find a free slot
 - Suffers from primary clustering
 - This can make insertion/accessing quite slow if it gets bad
- Quadratic probing
 - ☑ Largely eliminates primary clustering
 - Suffers from secondary clustering
 - May fail to find free slots (eg: if there are only a few left)
 - ... and so also can't tell when to give up looking for a key!

Collision-Handling Comparison

- Double Hashing:
 - ☑ No problems with primary or secondary clustering
 - ☑ Will always find a free slot
 - ... as long as the table size is prime
 - Needs a secondary hash function (extra complexity)

Next Week

Heaps