

# Rockchip DRM RK628 Porting Guide

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## 前言

文本主要介绍 RK628 的使用与调试方法。

## 读者对象

本文档 (本指南) 主要适用于以下工程师:

技术支持工程师

软件开发工程师

## 修订记录

版本号	作者	修改日期	修改说明
V1.0.0	闭伟勇	2020-12-01	初始发布
V1.1.0	陈顺庆	2020-12-02	补充Post-Process和HDMITX
V1.2.0	黄国椿	2020-12-02	补充rk628_bt1120_rx
V1.3.0	操瑞杰	2020-12-02	补充 HDMIRX
V1.4.0	黄家钊	2020-12-04	补充 GVI
V1.5.0	温定贤	2020-12-09	补充 HDMI to MIPI CSI应用场景说明

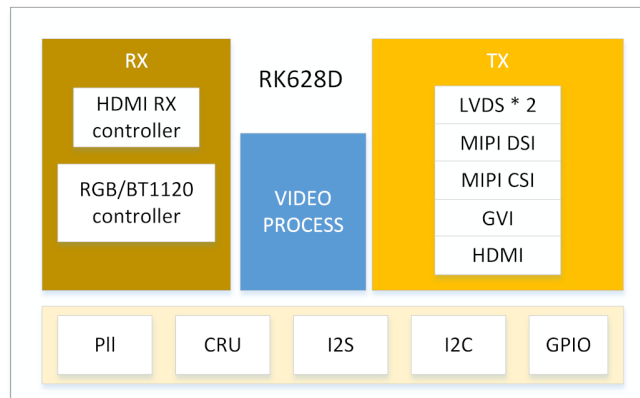
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# Introduction

本文档主要描述多功能转换芯片RK628的软件配置方法以及调试手段，具体功能描述参考datasheet。



RK628D Block Diagram

配置项：

```
CONFIG_MFD_RK628=y
CONFIG_DRM_ROCKCHIP_RK628=y
CONFIG_VIDEO_RK628CSI=y
```

驱动：

```
drivers/mfd/rk628.c
drivers/clock/rockchip/regmap/clock-rk628.c
drivers/pinctrl/pinctrl-rk628.c
drivers/gpu/drm/rockchip/rk628/*
drivers/media/i2c/rk628_csi.c
```

设备树：

```
arch/arm/boot/dts/rk3288-evb-rk628.dtsi
arch/arm/boot/dts/rk3288-evb-rk628-hdmi2gvi-avb.dtb
arch/arm/boot/dts/rk3288-evb-rk628-hdmi2gvi-avb.dts
arch/arm/boot/dts/rk3288-evb-rk628-rgb2dsi-avb.dtb
arch/arm/boot/dts/rk3288-evb-rk628-rgb2dsi-avb.dts
arch/arm/boot/dts/rk3288-evb-rk628-rgb2gvi-avb.dts
arch/arm/boot/dts/rk3288-evb-rk628-rgb2hdmi-avb.dtb
arch/arm/boot/dts/rk3288-evb-rk628-rgb2hdmi-avb.dts
arch/arm/boot/dts/rk3288-evb-rk628-rgb2lvds-avb.dts
arch/arm/boot/dts/rk3288-evb-rk628-rgb2lvds-dual-avb.dts
arch/arm/boot/dts/rk3288-evb-rk628-hdmi2csi-avb.dts
```

## Core

1. arch/arm/boot/dts/rk628.dtsi 包含 RK628 相关模块的基础配置，一般不需要更改，只需要在板级 dts 中包含该 dtsi。
2. arch/arm/boot/dts/rk3288-evb-rk628.dtsi 包含特定板级配置，需要根据硬件设计配置 RK628 相关控制 IO，并且包含 rk628.dtsi。

```

&i2c1 {
    clock-frequency = <400000>;
    status = "okay";

    rk628: rk628@50 {
        reg = <0x50>;
        interrupt-parent = <&gpio7>;
        interrupts = <15 IRQ_TYPE_LEVEL_HIGH>;
        enable-gpios = <&gpio5 RK_PC2 GPIO_ACTIVE_HIGH>;
        reset-gpios = <&gpio7 RK_PB6 GPIO_ACTIVE_LOW>;
        status = "okay";
    };
};

```

## Input

### RGB

注意：rk3288-android7.1 和 rk3288-android8.1 对应的内核基线 RGB 功能在 dts 中是以 lvds 的节点来描述，

在这两个 SDK kernel 中没有关于 rk628 应用方案的配置 dts，可以参考如下相关 dts 配置：

[RKDocs/PATCHES/patch\\_rk628\\_dts\\_for\\_rk3288\\_android8.0.tar.gz](#)

```

&rgb {
    status = "okay";

    ports {
        port@1 {
            reg = <1>;

            rgb_out_post_process: endpoint {
                remote-endpoint = <&post_process_in_rgb>;
            };
        };
    };
};

&video_phy {
    status = "okay";
};

&rgb_in_vopb {
    status = "disabled";
};

&rgb_in_vop1 {
    status = "okay";
};

```

### BT1120

[arch/arm64/boot/dts/rockchip/rk3568-evb6-ddr3-v10-rk628-bt1120-to-hdmi.dts](#)

```

&rgb {

```

```

status = "okay";
pinctrl-names = "default";
pinctrl-0 = <&bt1120_pins>;

ports {
    port@1 {
        reg = <1>;

        rgb_out_bt1120: endpoint {
            remote-endpoint = <&bt1120_in_rgb>;
        };
    };
};

&rk628_bt1120_rx {
    status = "okay";

    ports {
        #address-cells = <1>;
        #size-cells = <0>;

        port@0 {
            reg = <0>;

            bt1120_in_rgb: endpoint {
                remote-endpoint = <&rgb_out_bt1120>;
            };
        };

        port@1 {
            reg = <1>;

            bt1120_out_post_process: endpoint {
                remote-endpoint = <&post_process_in_bt1120>;
            };
        };
    };
};

&rgb_in_vp2 {
    status = "okay";
};

```

## HDMIRX

HDMIRX 目前支持以下输入源格式：

- 3840X2160-60Hz(YUV420-8BIT)
- 3840X2160-30Hz(RGB-8BIT)
- 1920X1080-60Hz(RGB-8BIT)
- 1280X720-60Hz(RGB-8BIT)
- 720X576-60Hz(RGB-8BIT)
- 720X480-60Hz(RGB-8BIT)

### HDMIRX 板级直连模式

DTS 配置如下, 以 HDMI2GVI 为例:

```
&hdmi {
    status = "okay";

    ports {
        #address-cells = <1>;
        #size-cells = <0>;
        port@1 {
            reg = <1>;

            hdmi_out_hdmirx: endpoint {
                remote-endpoint = <&hdmirx_in_hdmi>;
            };
        };
    };
};

&panel {
    compatible = "simple-panel";
    .....
    status = "okay";

    display-timings {
        native-mode = <&timing>;

        timing: timing {
            .....
        };
    };

    port {
        panel_in_gvi: endpoint {
            remote-endpoint = <&gvi_out_panel>;
        };
    };
};

&rk628_gvi {
    pinctrl-names = "default";
    pinctrl-0 = <&gvi_hpd_pins>, <&gvi_lock_pins>;
    status = "okay";
    rockchip, lane-num = <8>;
    /* rockchip, division-mode; */

    ports {
        #address-cells = <1>;
        #size-cells = <0>;

        port@0 {
            reg = <0>;

            gvi_in_post_process: endpoint {
                remote-endpoint = <&post_process_out_gvi>;
            };
        };
    };
};
```

```

    port@1 {
        reg = <1>;

        gvi_out_panel: endpoint {
            remote-endpoint = <&panel_in_gvi>;
        };
    };
};

&rk628_combtxphy {
    status = "okay";
};

&rk628_post_process {
    status = "okay";

    ports {
        #address-cells = <1>;
        #size-cells = <0>;

        port@0 {
            reg = <0>;

            post_process_in_hdmirx: endpoint {
                remote-endpoint = <&hdmirx_out_post_process>;
            };
        };

        port@1 {
            reg = <1>;

            post_process_out_gvi: endpoint {
                remote-endpoint = <&gvi_in_post_process>;
            };
        };
    };
};

&rk628_combrxphy {
    status = "okay";
};

&rk628_hdmirx {
    status = "okay";

    ports {
        #address-cells = <1>;
        #size-cells = <0>;

        port@0 {
            reg = <0>;

            hdmirx_in_hdmi: endpoint {
                remote-endpoint = <&hdmi_out_hdmirx>;
            };
        };
    };
};

```

```

        port@1 {
            reg = <1>;

            hdmirx_out_post_process: endpoint {
                remote-endpoint = <&post_process_in_hdmirx>;
            };
        };
    };

    &hdmi_in_vop1 {
        status = "disabled";
    };

    &hdmi_in_vopb {
        status = "okay";
    };

```

### 注意事项

由于 HDMIRX 最大值支持 4K-60Hz-YUV420，所以当需要输出 4K-60Hz 分辨率时，需要强制限制输入源为 YUV420 颜色格式。必须在输出端限制输入源最大的 TMDS CLK 以及允许 YUV420 格式输出。

以 HDMI2GVI 为例，需要以下修改：

```

--- a/drivers/gpu/drm/rockchip/rk628/rk628_gvi.c
+++ b/drivers/gpu/drm/rockchip/rk628/rk628_gvi.c
@@ -312,7 +312,8 @@ static int rk628_gvi_connector_get_modes(struct
drm_connector *connector)
    info->edid_hdmi_dc_modes = 0;
    info->hdmi.y420_dc_modes = 0;
    info->color_formats = 0;
-    info->max_tmds_clock = 600000;
+    info->max_tmds_clock = 300000;
+    connector->ycbcr_420_allowed = true;

```

## HDMIRX线缆连接模式

HDMIRX线缆连接模式用于HDMIRX to MIPI CSI接口转换，适用于HDMI IN应用场景，支持热拔插、动态分辨率切换等功能。

目前支持以下分辨率，可根据具体项目需求在驱动中继续增加：

- 3840X2160-30Hz(RGB-8BIT/YUV422-8BIT)
- 1920X1080-60Hz(RGB-8BIT/YUV422-8BIT)
- 1280X720-60Hz(RGB-8BIT/YUV422-8BIT)
- 720X576-50Hz(RGB-8BIT/YUV422-8BIT)
- 720X480-60Hz(RGB-8BIT/YUV422-8BIT)

## Output

### Post-Process

如图 1-1所示，输入数据需要经过 Post Process 做缩放或是bypass，然后送到各显示接口，所以 dts 必须要配置 rk628\_post\_process 桥接 RGB 或是 HDMIRX。

以 RGB 为例：



```

&rgb {
    status = "okay";

    ports {
        port@1 {
            reg = <1>;

            rgb_out_post_process: endpoint {
                remote-endpoint = <&post_process_in_rgb>;
            };
        };
    };
};

&rk628_post_process {
    pinctrl-names = "default";
    pinctrl-0 = <&vop_pins>;
    status = "okay";

    ports {
        #address-cells = <1>;
        #size-cells = <0>;

        port@0 {
            reg = <0>;

            post_process_in_rgb: endpoint {
                remote-endpoint = <&rgb_out_post_process>;
            };
        };
    };
};

```

## Scaler

以 RGB(1080p)-> GVI(4K) 为例，因为 RGB 无法输出4K，所以只能经过 Scaler 做缩放。

因为 GVI 只添加了 4K 的分辨率，在上层 modes 列表中会有 4K 分辨率，但是希望上层设置 1080P(源分辨率) 下来，在 Post Process 再放大到 4K(目标分辨率)，所以需要在 Post Process 添加一个源分辨率，配置如下：

```

&rk628_post_process {
    pinctrl-names = "default";
    pinctrl-0 = <&vop_pins>;
    status = "okay";

    ports {
        #address-cells = <1>;
        #size-cells = <0>;

        port@0 {
            reg = <0>;

            post_process_in_rgb: endpoint {
                remote-endpoint = <&rgb_out_post_process>;
            };
        };
    };
};

```

```

        port@1 {
            reg = <1>;

            post_process_out_hdmi: endpoint {
                remote-endpoint = <&hdmi_in_post_process>;
            };
        };

+
+ display-timings {
+     native-mode = <&timing0>;
+
+     timing0: timing0 {
+         clock-frequency = <148500000>;
+         hactive = <1920>;
+         vactive = <1080>;
+         hback-porch = <148>;
+         hfront-porch = <88>;
+         vback-porch = <36>;
+         vfront-porch = <4>;
+         hsync-len = <44>;
+         vsync-len = <5>;
+         hsync-active = <0>;
+         vsync-active = <0>;
+         de-active = <0>;
+         pixelclk-active = <0>;
+     };
+ };
};

```

## 极性配置

```

&rk628_post_process {
    pinctrl-names = "default";
    pinctrl-0 = <&vop_pins>;
    status = "okay";

+
+ mode-sync-pol = <0>;
    ports {
        #address-cells = <1>;
        #size-cells = <0>;

        port@0 {
            reg = <0>;

            post_process_in_rgb: endpoint {
                remote-endpoint = <&rgb_out_post_process>;
            };
        };

        port@1 {
            reg = <1>;

            post_process_out_hdmi: endpoint {
                remote-endpoint = <&hdmi_in_post_process>;
            };
        };
    };
};

```

```
};

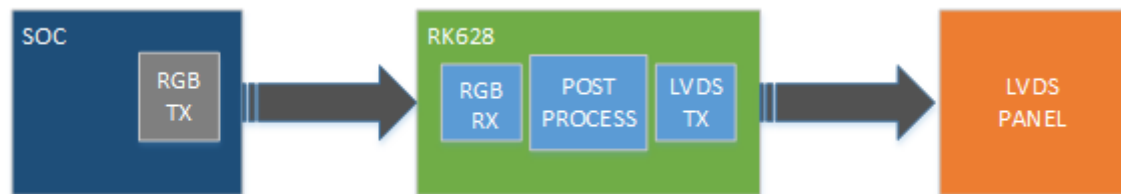
};

};
```

mode-sync-pol 作为一种规避方法而添加的属性，一般情况不需要配置，只有像 RK3568 RGB 和 LVDS 同时输出的时候，极性没有办法配置，只能输出 DRM\_MODE\_FLAG\_NHSYNC/DRM\_MODE\_FLAG\_NVSYNC 的情况下，通过配置 Post Process 的 mode-sync-pol 为 0，来适配前级的极性。

## LVDS

### RGB2LVDS



### Single LVDS

arch/arm/boot/dts/rk3288-evb-rk628-rgb2lvds-avb.dts

```
&rk628_post_process {
    pinctrl-names = "default";
    pinctrl-0 = <&vop_pins>;
    status = "okay";

    ports {
        #address-cells = <1>;
        #size-cells = <0>;

        port@0 {
            reg = <0>;

            post_process_in_rgb: endpoint {
                remote-endpoint = <&rgb_out_post_process>;
            };
        };

        port@1 {
            reg = <1>;

            post_process_out_lvds: endpoint {
                remote-endpoint = <&lvds_in_post_process>;
            };
        };
    };
};
```

```
&rk628_lvds {
    status = "okay";

    ports {
        #address-cells = <1>;
        #size-cells = <0>;
```

```

        port@0 {
            reg = <0>;

            lvds_in_post_process: endpoint {
                remote-endpoint = <&post_process_out_lvds>;
            };
        };

        port@1 {
            reg = <1>;

            lvds_out_panel: endpoint {
                remote-endpoint = <&panel_in_lvds>;
            };
        };
    };

    &rk628_combtxphy {
        status = "okay";
    };

```

```

/ {
    panel {
        compatible = "simple-panel";
        backlight = <&backlight>;
        enable-gpios = <&gpio7 RK_PA2 GPIO_ACTIVE_HIGH>;
        prepare-delay-ms = <20>;
        enable-delay-ms = <20>;
        disable-delay-ms = <20>;
        unprepare-delay-ms = <20>;
        bus-format = <MEDIA_BUS_FMT_RGB888_1X7X4_SPWG>;

        display-timings {
            native-mode = <&timing0>;

            timing0: timing0 {
                clock-frequency = <48000000>;
                hactive = <1024>;
                vactive = <600>;
                hback-porch = <90>;
                hfront-porch = <90>;
                vback-porch = <10>;
                vfront-porch = <10>;
                hsync-len = <90>;
                vsync-len = <10>;
                hsync-active = <0>;
                vsync-active = <0>;
                de-active = <0>;
                pixelclk-active = <0>;
            };
        };

        port {
            panel_in_lvds: endpoint {
                remote-endpoint = <&lvds_out_panel>;
            };
        };
    };
}

```

```
};

};

};
```

## Dual LVDS

```
&rk628_post_process {
    pinctrl-names = "default";
    pinctrl-0 = <&vop_pins>;
    status = "okay";

    ports {
        #address-cells = <1>;
        #size-cells = <0>;

        port@0 {
            reg = <0>;

            post_process_in_rgb: endpoint {
                remote-endpoint = <&rgb_out_post_process>;
            };
        };

        port@1 {
            reg = <1>;

            post_process_out_lvds: endpoint {
                remote-endpoint = <&lvds_in_post_process>;
            };
        };
    };
};
```

```
&rk628_lvds {
    rockchip,link-type = "dual-link-even-odd-pixels";
    status = "okay";

    ports {
        #address-cells = <1>;
        #size-cells = <0>;

        port@0 {
            reg = <0>;

            lvds_in_post_process: endpoint {
                remote-endpoint = <&post_process_out_lvds>;
            };
        };

        port@1 {
            reg = <1>;

            lvds_out_panel: endpoint {
                remote-endpoint = <&panel_in_lvds>;
            };
        };
    };
};
```

```

};

};

};

&rk628_combtxphy {
    status = "okay";
};

```

Property	Value	Comment
rockchip,link-type	dual-link-odd-even-pixels dual-link-even-odd-pixels dual-link-left-right-pixels dual-link-right-left-pixels	双通道 LVDS 需要配置该属性，支持奇偶像素模式和左右像素模式，并且支持数据通道互换。对于左右像素模式，需要在CH0和CH1上分别接上相同的屏，在配置 timing 时，只需要在单屏 timing 的基础上，将 clock-frequency, hactive, hback-porch, hfront-porch, hsync-len 的值分别x2。

```

/ {
    panel {
        compatible = "simple-panel";
        backlight = <&backlight>;
        power-supply = <&vcc33_lcd>;
        enable-gpios = <&gpio5 RK_PC1 GPIO_ACTIVE_HIGH>;
        prepare-delay-ms = <20>;
        enable-delay-ms = <20>;
        disable-delay-ms = <20>;
        unprepare-delay-ms = <20>;
        bus-format = <MEDIA_BUS_FMT_RGB888_1X7X4_SPWG>;

        display-timings {
            native-mode = <&timing0>;

            timing0: timing0 {
                clock-frequency = <149000000>;
                hactive = <1920>;
                vactive = <1080>;
                hback-porch = <96>;
                hfront-porch = <120>;
                vback-porch = <8>;
                vfront-porch = <33>;
                hsync-len = <64>;
                vsync-len = <4>;
                hsync-active = <0>;
                vsync-active = <0>;
                de-active = <0>;
                pixelclk-active = <0>;
            };
        };
    };

    port {

```

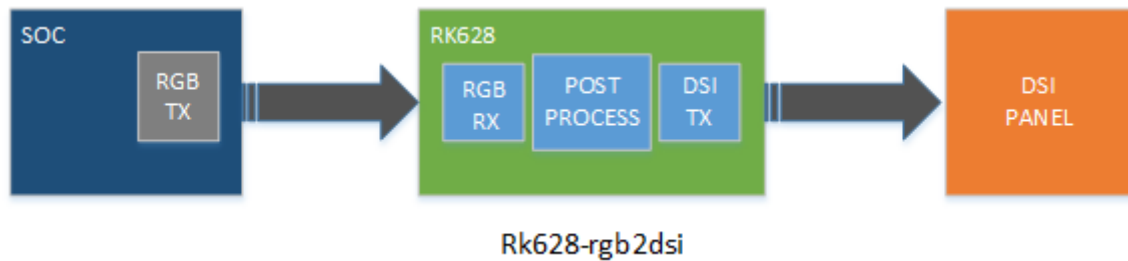
```

        panel_in_lvds: endpoint {
            remote-endpoint = <&lvds_out_panel>;
        };
    };
};
};

```

## DSI

### RGB2DSI



### Single DSI

arch/arm/boot/dts/rk3288-evb-rk628-rgb2dsi-avb.dts

```

&rk628_post_process {
    pinctrl-names = "default";
    pinctrl-0 = <&vop_pins>;
    status = "okay";

    ports {
        #address-cells = <1>;
        #size-cells = <0>;

        port@0 {
            reg = <0>;

            post_process_in_rgb: endpoint {
                remote-endpoint = <&rgb_out_post_process>;
            };
        };

        port@1 {
            reg = <1>;

            post_process_out_dsi0: endpoint {
                remote-endpoint = <&dsi0_in_post_process>;
            };
        };
    };
};

```

```

&rk628_dsi0 {
    status = "okay";

    ports {
        #address-cells = <1>;
        #size-cells = <0>;
    };
};

```

```

port@0 {
    reg = <0>;

    dsi0_in_post_process: endpoint {
        remote-endpoint = <&post_process_out_dsi0>;
    };
};

panel@0 {
    compatible = "simple-panel-dsi";
    reg = <0>;
    backlight = <&backlight>;
    enable-gpios = <&gpio7 RK_PA2 GPIO_ACTIVE_HIGH>;
    prepare-delay-ms = <120>;
    enable-delay-ms = <120>;
    disable-delay-ms = <120>;
    unprepare-delay-ms = <120>;
    init-delay-ms = <120>;

    dsi,flags = <(MIPI_DSI_MODE_VIDEO |
        MIPI_DSI_MODE_VIDEO_BURST |
        MIPI_DSI_MODE_LPM |
        MIPI_DSI_MODE_EOT_PACKET)>;
    dsi,format = <MIPI_DSI_FMT_RGB888>;
    dsi,lanes = <4>;

    panel-init-sequence = [
        05 fa 01 11
        05 14 01 10
    ];

    panel-exit-sequence = [
        05 00 01 28
        05 00 01 10
    ];

    display-timings {
        native-mode = <&timing0>;

        timing0: timing0 {
            clock-frequency = <64000000>;
            hactive = <720>;
            vactive = <1280>;
            hfront-porch = <40>;
            hsync-len = <10>;
            hback-porch = <40>;
            vfront-porch = <22>;
            vsync-len = <4>;
            vback-porch = <11>;
            hsync-active = <0>;
            vsync-active = <0>;
            de-active = <0>;
            pixelclk-active = <0>;
        };
    };
};

```



```
};

&rk628_combtxphy {
    status = "okay";
};
```

## Dual DSI

```
&rk628_post_process {
    pinctrl-names = "default";
    pinctrl-0 = <&vop_pins>;
    status = "okay";

    ports {
        #address-cells = <1>;
        #size-cells = <0>;

        port@0 {
            reg = <0>;

            post_process_in_rgb: endpoint {
                remote-endpoint = <&rgb_out_post_process>;
            };
        };

        port@1 {
            reg = <1>;

            post_process_out_dsi0: endpoint {
                remote-endpoint = <&dsi0_in_post_process>;
            };
        };
    };
};
```

```
&rk628_dsi0 {
    status = "okay";

    ports {
        #address-cells = <1>;
        #size-cells = <0>;

        port@0 {
            reg = <0>;

            dsi0_in_post_process: endpoint {
                remote-endpoint = <&post_process_out_dsi0>;
            };
        };
    };

    panel@0 {
        compatible = "simple-panel-dsi";
        reg = <0>;
        backlight = <&backlight>;
        enable-gpios = <&gpio7 RK_PA2 GPIO_ACTIVE_HIGH>;
    };
};
```

```

prepare-delay-ms = <120>;
enable-delay-ms = <120>;
disable-delay-ms = <120>;
unprepare-delay-ms = <120>;
init-delay-ms = <120>;

dsi,flags = <(MIPI_DSI_MODE_VIDEO |
              MIPI_DSI_MODE_VIDEO_BURST |
              MIPI_DSI_MODE_LPM |
              MIPI_DSI_MODE_EOT_PACKET |
              MIPI_DSI_MODE_VIDEO_HBP)>;
dsi,format = <MIPI_DSI_FMT_RGB888>;
dsi,lanes = <8>;

panel-init-sequence = [
    05 78 01 11
    05 32 01 29
];

panel-exit-sequence = [
    05 00 01 28
    05 00 01 10
];

display-timings {
    native-mode = <&timing0>;

    timing0: timing0 {
        clock-frequency = <260000000>;
        hactive = <1440>;
        vactive = <2560>;
        hfront-porch = <150>;
        hsync-len = <30>;
        hback-porch = <60>;
        vfront-porch = <8>;
        vsync-len = <4>;
        vback-porch = <4>;
        hsync-active = <0>;
        vsync-active = <0>;
        de-active = <0>;
        pixelclk-active = <0>;
    };
};

};

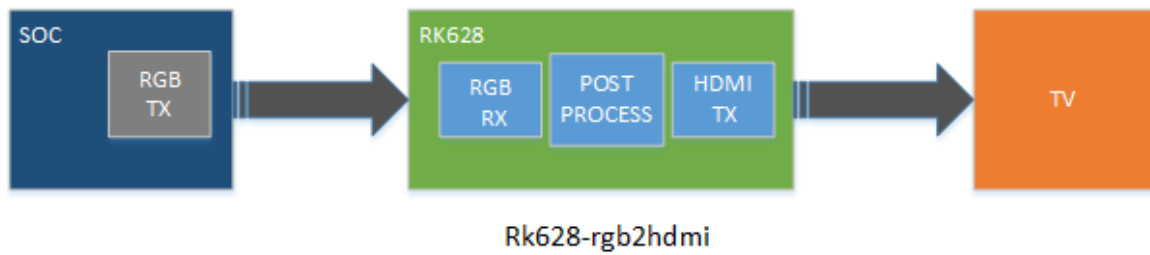
&rk628_dsi1 {
    status = "okay";
};

&rk628_combtxphy {
    status = "okay";
};

```

## HDMITX

## RGB2HDMI



arch/arm/boot/dts/rk3288-evb-rk628-rgb2hdmi-avb.dts

```

&rk628_hdmi {
    status = "okay";

    ports {
        #address-cells = <1>;
        #size-cells = <0>;

        port@0 {
            reg = <0>;

            hdmi_in_post_process: endpoint {
                remote-endpoint = <&post_process_out_hdmi>;
            };
        };
    };
};

&rk628_post_process {
    pinctrl-names = "default";
    pinctrl-0 = <&vop_pins>;
    status = "okay";

    ports {
        #address-cells = <1>;
        #size-cells = <0>;

        port@0 {
            reg = <0>;

            post_process_in_rgb: endpoint {
                remote-endpoint = <&rgb_out_post_process>;
            };
        };

        port@1 {
            reg = <1>;

            post_process_out_hdmi: endpoint {
                remote-endpoint = <&hdmi_in_post_process>;
            };
        };
    };
};

&rgb {
    status = "okay";

```

```

        ports {
            port@1 {
                reg = <1>;

                rgb_out_post_process: endpoint {
                    remote-endpoint = <&post_process_in_rgb>;
                };
            };
        };

    };

    &video_phy {
        status = "okay";
    };

    &rgb_in_vopb {
        status = "disabled";
    };

    &rgb_in_vopl {
        status = "okay";
    };

    &route_rgb {
        connect = <&vopl_out_rgb>;
        status = "disabled";
    };
};

```

## BT1120->HDMI



Rk628-bt1120-2-hdmi

rk3568 平台: arch/arm64/boot/dts/rockchip/rk3568-evb6-ddr3-v10-rk628-bt1120-to-hdmi.dts

```

#include <arm/rk628.dtsi>

&rk628_hdmi {
    status = "okay";

    ports {
        #address-cells = <1>;
        #size-cells = <0>;

        port@0 {
            reg = <0>;

            hdmi_in_post_process: endpoint {
                remote-endpoint = <&post_process_out_hdmi>;
            };
        };
    };
};

```

```

};
};

&rk628_post_process {
    pinctrl-names = "default";
    pinctrl-0 = <&vop_pins>;
    status = "okay";

    mode-sync-pol = <0>;
    ports {
        #address-cells = <1>;
        #size-cells = <0>;

        port@0 {
            reg = <0>;

            post_process_in_bt1120: endpoint {
                remote-endpoint = <&bt1120_out_post_process>;
            };
        };

        port@1 {
            reg = <1>;

            post_process_out_hdmi: endpoint {
                remote-endpoint = <&hdmi_in_post_process>;
            };
        };
    };
};

&rk628_bt1120_rx {
    status = "okay";

    ports {
        #address-cells = <1>;
        #size-cells = <0>;

        port@0 {
            reg = <0>;

            bt1120_in_rgb: endpoint {
                remote-endpoint = <&rgb_out_bt1120>;
            };
        };

        port@1 {
            reg = <1>;

            bt1120_out_post_process: endpoint {
                remote-endpoint = <&post_process_in_bt1120>;
            };
        };
    };
};

&rgb {
    status = "okay";

```



```

+
      COMPOSITE_NOMUX(SCLK_SARADC, "sclk_saradc", "xin24m", 0,
                      RK3288_CLKSEL_CON(24), 8, 8, DFLAGS,
                      RK3288_CLKGATE_CON(2), 8, GFLAGS),
diff --git a/include/dt-bindings/clock/rk3288-cru.h b/include/dt-
bindings/clock/rk3288-cru.h
index 1f9c62f07389..61ae793438b4 100644
--- a/include/dt-bindings/clock/rk3288-cru.h
+++ b/include/dt-bindings/clock/rk3288-cru.h
@@ -100,6 +100,8 @@
#define SCLK_MAC_PLL            150
#define SCLK_MAC                151
#define SCLK_MACREF_OUT        152
+#define SCLK_TESTOUT_SRC      153
+#define SCLK_TESTOUT          154

#define DCLK_VOP0              190
#define DCLK_VOP1              191

```

```

diff --git a/arch/arm/boot/dts/rk3288-evb-rk628-rgb2hdmi-avb.dts
b/arch/arm/boot/dts/rk3288-evb-rk628-rgb2hdmi-avb.dts
index 181ebfdef0ab..0bea70f67a4f 100644
--- a/arch/arm/boot/dts/rk3288-evb-rk628-rgb2hdmi-avb.dts
+++ b/arch/arm/boot/dts/rk3288-evb-rk628-rgb2hdmi-avb.dts
@@ -39,6 +39,20 @@
    status = "okay";
};

+&xin_osc0_func {
+    compatible = "fixed-factor-clock";
+    clocks = <&cru SCLK_TESTOUT>;
+    clock-mult = <1>;
+    clock-div = <1>;
+};
+
+&rk628 {
+    pinctrl-names = "default";
+    pinctrl-0 = <&test_clkout>;
+    assigned-clocks = <&cru SCLK_TESTOUT_SRC>;
+    assigned-clock-parents = <&xin24m>;
+};

    &rk628_hdmi {
        status = "okay";
@@ -114,3 +128,11 @@
        connect = <&vop1_out_rgb>;
        status = "disabled";
    };
+
+    &pinctrl {
+        test {
+            test_clkout: test-clkout {
+                rockchip,pins = <0 17 RK_FUNC_1 &pcfg_pull_none>;
+            };
+        };
+    };

```

如果是 RK3399+RK628 平台，硬件上 RK628 的 24M 时钟需要由 RK3399 的 PIN-U28 clk\_testout2 提供，软件补丁参考 HDMI2GVI 章节。

## GVI

### GVI 说明

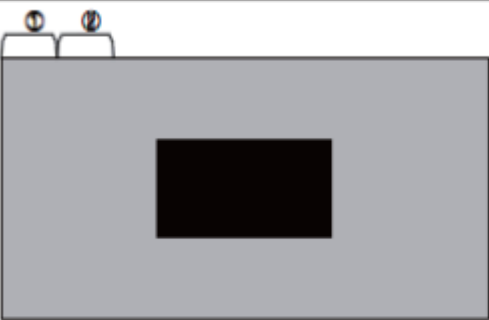
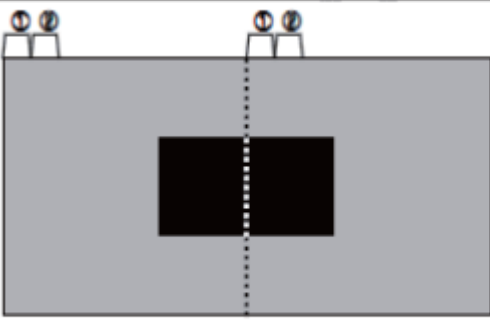
GVI (General Video Interface) 是一种用于视频信号高速传输的通用接口，采用 8B/10B 编码技术和 CDR 架构，支持 one-section/non-division、two-section/2 division 模式，传输带宽为 3.75Gbps/lane，最大可以支持 8lane 3840x2160P60 输出。

### 配置说明

1. divison 模式配置
- GVI 默认为 one section 模式，对于 two section 模式的屏可以通过在 dts 中加入如下属性打开

```
&rk628_gvi {  
  
    rockchip,division-mode;  
  
}
```

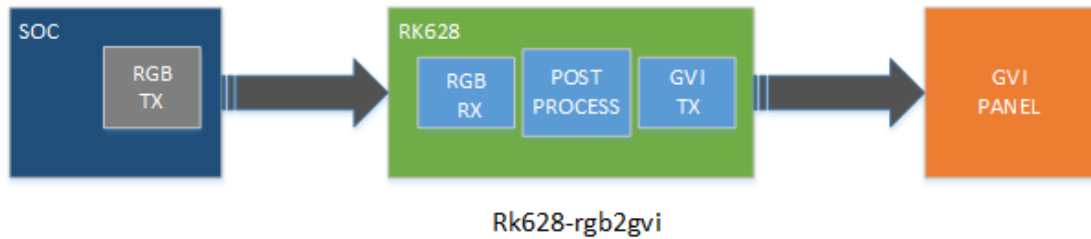
- 不同模式数据传输方式

Mode 1 : Non-Division				Mode 2 : 2 Division			
							
Lane	1 <sup>st</sup> Data	2 <sup>nd</sup> Data	Data#	Lane	1 <sup>st</sup> Data	2 <sup>nd</sup> Data	Data#
Lane0	1	9	3833	Lane0	1	5	1917
Lane1	2	10	3834	Lane1	2	6	1918
Lane2	3	11	3835	Lane2	3	7	1919
Lane3	4	12	3836	Lane3	4	8	1920
Lane4	5	13	3837	Lane4	1921	1925	3837
Lane5	6	14	3838	Lane5	1922	1926	3838
Lane6	7	15	3839	Lane6	1923	1927	3839
Lane7	8	16	3840	Lane7	1924	1928	3840

2. DTS 通路配置demo

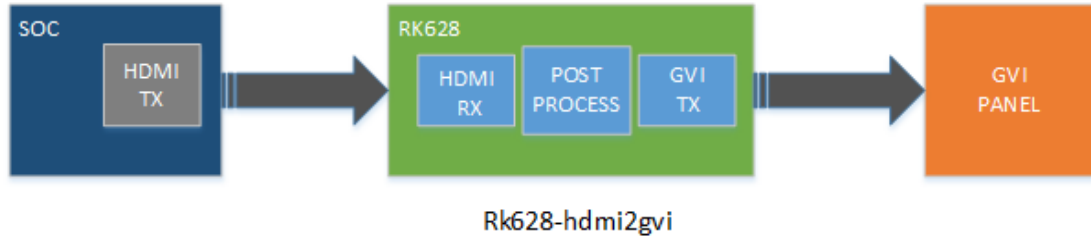


- RGB2GVI



可以参考 dts demo: arch/arm/boot/dts/rk3288-evb-rk628-rgb2gvi-avb.dts

- HDMI2GVI



可以参考 dts demo: arch/arm/boot/dts/rk3288-evb-rk628-hdmi2gvi-avb.dts

如下是 rk3399 平台 HDMI2GVI 软件修改补丁:

```
/ {
+     panel_gvi {
+         compatible = "simple-panel";
+         //backlight = <&backlight>;
+         power-supply = <&vcc_lcd>;
+         prepare-delay-ms = <20>;
+         //enable-gpios = <&gpio7 21 GPIO_ACTIVE_HIGH>;
+         enable-delay-ms = <200>;
+         disable-delay-ms = <20>;
+         unprepare-delay-ms = <20>;
+         bus-format = <MEDIA_BUS_FMT_RGB888_1X24>;
+         width-mm = <136>;
+         height-mm = <217>;
+         status = "okay";
+
+         display-timings {
+             native-mode = <&timing>;
+
+             timing: timing {
+                 clock-frequency = <594000000>;
+                 hactive = <3840>;
+                 vactive = <2160>;
+                 hback-porch = <296>;
+                 hfront-porch = <176>;
+                 vback-porch = <72>;
+                 vfront-porch = <8>;
+                 hsync-len = <88>;
+                 vsync-len = <10>;
+                 hsync-active = <1>;
+                 vsync-active = <1>;
+                 de-active = <0>;
+                 pixelclk-active = <0>;
+             };
+         };
+     };
+ }
```

```

+         port {
+             panel_in_gvi: endpoint {
+                 remote-endpoint = <&gvi_out_panel>;
+             };
+         };
+     };
+ };
+ };

+&i2c7 {
+     clock-frequency = <400000>;
+     status = "okay";
+
+     rk628: rk628@50 {
+         reg = <0x50>;
+         interrupt-parent = <&gpio2>;
+         interrupts = <RK_PA0 IRQ_TYPE_LEVEL_HIGH>;
+         //enable-gpios = <&gpio0 RK_PC5 GPIO_ACTIVE_HIGH>;
+         reset-gpios = <&gpio3 RK_PC0 GPIO_ACTIVE_LOW>;
+         pinctrl-0 = <&rk628_rst>;
+         pinctrl-names = "default";
+         status = "okay";
+     };
+ };
+ };
+
+ #include <arm/rk628.dtsi>
+
+
+&hdmi {
+     status = "okay";
+
+     ports {
+         #address-cells = <1>;
+         #size-cells = <0>;
+         port@1 {
+             reg = <1>;
+
+             hdmi_out_hdmirx: endpoint {
+                 remote-endpoint = <&hdmirx_in_hdmi>;
+             };
+         };
+     };
+ };
+
+&rk628_gvi {
+     pinctrl-names = "default";
+     pinctrl-0 = <&gvi_hpd_pins>, <&gvi_lock_pins>;
+     status = "okay";
+     rockchip, lane-num = <8>;
+     /* rockchip, division-mode; */
+
+     ports {
+         #address-cells = <1>;
+         #size-cells = <0>;
+
+         port@0 {
+             reg = <0>;
+
+             gvi_in_post_process: endpoint {

```

```

+         remote-endpoint = <&post_process_out_gvi>;
+     };
+ };
+
+     port@1 {
+         reg = <1>;
+
+         gvi_out_panel: endpoint {
+             remote-endpoint = <&panel_in_gvi>;
+         };
+     };
+ };
+};
+
+&rk628_combtxphy {
+    status = "okay";
+};
+
+&rk628_post_process {
+    status = "okay";
+
+    ports {
+        #address-cells = <1>;
+        #size-cells = <0>;
+
+        port@0 {
+            reg = <0>;
+
+            post_process_in_hdmirx: endpoint {
+                remote-endpoint = <&hdmirx_out_post_process>;
+            };
+        };
+
+        port@1 {
+            reg = <1>;
+
+            post_process_out_gvi: endpoint {
+                remote-endpoint = <&gvi_in_post_process>;
+            };
+        };
+    };
+};
+
+&rk628_combrxphy {
+    status = "okay";
+};
+
+&rk628_hdmirx {
+    status = "okay";
+
+    ports {
+        #address-cells = <1>;
+        #size-cells = <0>;
+
+        port@0 {
+            reg = <0>;
+

```

```

+         hdmirx_in_hdmi: endpoint {
+             remote-endpoint = <&hdmi_out_hdmirx>;
+         };
+     };
+     port@1 {
+         reg = <1>;
+
+         hdmirx_out_post_process: endpoint {
+             remote-endpoint = <&post_process_in_hdmirx>;
+         };
+     };
+ };
+};

&pinctrl {
+     rk628_gpio {
+         rk628_rst: rk628_rst {
+             rockchip,pins = <3 16 RK_FUNC_GPIO &pcfg_pull_none>;
+         };
+     };
+
+     test {
+         clk_testout2: clk_testout2 {
+             rockchip,pins = <0 8 RK_FUNC_3 &pcfg_pull_none>;
+         };
+     };
+ };

/* rk3399 控制器提供的 24MHz 同源修改如下 */
+&xin_osc0_func {
+     compatible = "fixed-factor-clock";
+     clocks = <&cru SCLK_TESTCLKOUT2>;
+     clock-mult = <1>;
+     clock-div = <1>;
+ };
+

+&rk628: rk628@50 {
+     pinctrl-0 = <&rk628_rst>, <&clk_testout2>;
+     pinctrl-names = "default";
+     assigned-clocks = <&cru SCLK_TESTCLKOUT2>;
+     assigned-clock-rates = <24000000>;
+ };
+

```

## MIPI CSI

MIPI CSI用于HDMIRX to MIPI CSI接口转换，适用于HDMI IN应用场景。

### dts配置

dts配置参考如下，涉及到相关硬件连接，请根据项目实际修改：

1. plugin-det-gpios 用于检测5V状态，即检测HDMI线缆是否插入。
2. power-gpios 用于RK AP端（如RK3288/RK3399）的MIPI CSI接口电源域供电控制。

```

&rk628_combrxphy {

```

```

        status = "okay";
};

&rk628_combtxphy {
    status = "okay";
};

&rk628_csi {
    status = "okay";
    plugin-det-gpios = <&gpio0 13 GPIO_ACTIVE_HIGH>;
    power-gpios = <&gpio0 17 GPIO_ACTIVE_HIGH>;
    rockchip,camera-module-index = <0>;
    rockchip,camera-module-facing = "back";
    rockchip,camera-module-name = "RK628-CSI";
    rockchip,camera-module-lens-name = "NC";

    port {
        hdmiin_out0: endpoint {
            remote-endpoint = <&mipi_in>;
            data-lanes = <1 2 3 4>;
        };
    };
};

&mipi_phy_rx0 {
    status = "okay";

    ports {
        #address-cells = <1>;
        #size-cells = <0>;

        port@0 {
            reg = <0>;
            #address-cells = <1>;
            #size-cells = <0>;

            mipi_in: endpoint@1 {
                reg = <1>;
                remote-endpoint = <&hdmiin_out0>;
                data-lanes = <1 2 3 4>;
            };
        };

        port@1 {
            reg = <1>;
            #address-cells = <1>;
            #size-cells = <0>;

            dphy_rx_out: endpoint@0 {
                reg = <0>;
                remote-endpoint = <&isp_mipi_in>;
            };
        };
    };
};

&rkisp1 {
    status = "okay";
};

```

```
port {
    #address-cells = <1>;
    #size-cells = <0>;

    isp_mipi_in: endpoint@0 {
        reg = <0>;
        remote-endpoint = <&dphy_rx_out>;
    };
};
};
```

## 注意事项

1. RK AP端对MIPI CSI数据接收部分，类似于camera sensor v4l2驱动，可使用media-ctl、v4l2-ctl工具来调试。
2. HDMI IN应用场景，接收3840X2160-30Hz时，MIPI速率较高，ISP频率需要达到625MHz或以上，部分芯片平台（如RK3399）需要修改时钟树配置，使ISP能够获取到需要的频点，同时ISP驱动中需要增加配置对应的频点。以RK3288/RK3399为例，ISP驱动相关代码在：

```
drivers/media/platform/rockchip/isp1/dev.c
```

3. 当HDMI IN为3840X2160-30Hz时，根据实际系统负载，可能会存在带宽不足导致丢帧或MIPI接收异常等问题，此时需要提高DDR频率，若仍无改善，可给ISP预留使用CMA内存，以解决此问题。

- 在rockchip\_defconfig配置预留CMA内存128MB

```
CONFIG_CMA=y
CONFIG_CMA_SIZE_MBYTES=128
```

- 在dts配置ISP关闭IOMMU，使用CMA内存

```
&isp_mmu {
    status = "disabled";
};
```

## DEBUG

### I2C通信异常

如下log表示RK628的I2C通信异常导致RK628的各个模块注册不上，需要检查RK628的时序以及24MHz的基准时钟，以及相关pin的iomux。

```
...
[ 0.960609] rk628 1-0050: failed to access register: -6
...
[ 1.137516] [drm] Rockchip DRM driver version: v1.0.1
[ 1.137982] rockchip-drm display-subsystem: devfreq is not set
[ 1.139225] rockchip-drm display-subsystem: bound ff930000.vop (ops
vop_component_ops)
[ 1.140167] rockchip-drm display-subsystem: bound ff940000.vop (ops
vop_component_ops)
[ 1.140707] dwhdmi-rockchip ff980000.hdmi: registered DesignWare HDMI I2C bus
driver
```

```
[ 1.140838] dwhdmi-rockchip ff980000.hdmi: Detected HDMI TX controller v2.01a
with HDCP (DWC HDMI
2.0 TX PHY)
[ 1.141198] dwhdmi-rockchip ff980000.hdmi: can't find next bridge
[ 1.141563] rockchip-drm display-subsystem: failed to bind ff980000.hdmi (ops
dw_hdmi_rockchip_ops): -517
[ 1.141942] rockchip-drm display-subsystem: master bind failed: -517
[ 1.142933] rockchip-dmc dmc: Get drm_device fail
```

## 寄存器读写

寄存器调试节点:

```
console:/ # ls /d/regmap/
0-001b          1-0050-dsi0          2-001a          rk628-dsi0-phy
1-0050-combtxphy 1-0050-grf          ff890000.i2s
1-0050-cru      1-0050-rk628-pinctrl ff96c000.video-phy
```

寄存器节点默认只读，如果需要寄存器可写，需要添加如下修改：

```
diff --git a/drivers/base/regmap/regmap-debugfs.c b/drivers/base/regmap/regmap-
debugfs.c
index 3f0a7e262d69..b819645edd84 100644
--- a/drivers/base/regmap/regmap-debugfs.c
+++ b/drivers/base/regmap/regmap-debugfs.c
@@ -259,7 +259,7 @@ static ssize_t regmap_map_read_file(struct file *file, char
__user *user_buf,
                                count, ppos);
}

-#undef REGMAP_ALLOW_WRITE_DEBUGFS
+#define REGMAP_ALLOW_WRITE_DEBUGFS
#ifdef REGMAP_ALLOW_WRITE_DEBUGFS
/*
 * This can be dangerous especially when we have clients such as
```

### 1. 读寄存器

```
console:/ # cat /d/regmap/1-0050-grf/registers
000: 0600062b
004: ffffffff
008: 00000000
00c: 00000000
010: 00000001
014: 00000000
018: 00050000
01c: 000a032a
020: 00320302
...
```

### 2. 写寄存器

```
console:/ # echo 0x000 0xffffffff > /d/regmap/1-0050-grf/registers
```

## 输入输出信息

```
console:/ # cat /d/dri/0/summary
VOP [ff930000.vop]: DISABLED
VOP [ff940000.vop]: ACTIVE
Connector: DPI
    overlay_mode[0] bus_format[100a] output_mode[0] color_space[0]
Display mode: 720x1280p60
    clk[64000] real_clk[64000] type[8] flag[5]
    H: 720 760 770 810
    V: 1280 1302 1306 1317
win0-0: ACTIVE
    format: AB24 little-endian (0x34324241) SDR[0] color_space[0]
    csc: y2r[0] r2r[0] r2y[0] csc mode[0]
    zpos: 0
    src: pos[0x0] rect[720x1280]
    dst: pos[0x0] rect[720x1280]
    buf[0]: addr: 0x00384000 pitch: 2880 offset: 0
win1-0: DISABLED
win2-0: DISABLED
win2-1: DISABLED
win2-2: DISABLED
win2-3: DISABLED
win3-0: DISABLED
win3-1: DISABLED
win3-2: DISABLED
win3-3: DISABLED
post: sdr2hdr[0] hdr2sdr[0]
pre : sdr2hdr[0]
post CSC: r2y[0] y2r[0] CSC mode[1]
```

## 主副屏属性配置

以 RGB2DSI 为例，DPI 表示输入为 RGB，DSI 表示输出为 DSI。当需要配置主副屏属性时，应根据输出的对应类型进行配置。

```
console:/ # ls /sys/class/drm/
card0 card0-DSI-1 controlD64 renderD128 version
```

属性配置如下：

```
sys.hwc.device.primary=DSI
```

Android9.0 以上：

```
vendor.hwc.device.primary=DSI
```

## 自测模式



在调试过程中，可以通过以下命令测试输出模块的控制器、对应的 phy、屏端这条链路是否正常工作，如果 color bar 能正常显示，请检查主控输出、RK628 input、RK628 Process 的配置，反之请检查对应输出接口和屏端的配置：

## HDMITX color bar

```
echo 0x70324 0x00 > /d/regmap/1-0050-hdmi/registers
echo 0x70324 0x40 > /d/regmap/1-0050-hdmi/registers
```

## DSI color bar

```
echo 0x50038 0x13f02 > /d/regmap/1-0050-dsi0/registers
```

## GVI color bar

```
echo 0x80060 0x1 > /d/regmap/1-0050-gvi/registers
```

## 行场解析

### rk628\_bt1120\_rx

通过如下命令可以判断 rk628\_bt1120\_rx 解析到行场是否正确：

```
cat /d/regmap/1-0051-grf/registers | grep 12c
[28:16]:Decoder 1120 last line_number of Y
[12:0]:Decoder 1120 last line_number of CbCr

cat /d/regmap/1-0051-grf/registers | grep 130
[24:13]:Decoder 1120 last pixel number of Y
[12:0]:Decoder 1120 last pixel number of CbCr
```