# Rockchip Developer Guide DVR&DMS Product

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#### Preface

#### Overview

This document is going to introduce DVR&DMS product solution.

#### **Product Version**

Chipset	Kernel Version
RV1126, RV1109	Linux 4.19

#### **Intended Audience**

This document (this guide) is mainly intended for:

Technical support engineers

Software development engineers

## **Revision History**

Version	Author	Date	Change Description	
V1.0.0	Vicent Chi, Zhihua Wang, Zhichao Yu	2021-01-31	Initial version	
V1.0.1	Vicent Chi	2021-03-01	Add MPI+DVP solution introduction	
V1.0.2	Ruby Zhang	2021-03-15	Update product version	
V1.1.0	Zhichao Yu	2021-04-30	Modify the AD chip access solution introduction; Add VP introduction	
V1.1.1	Vicent Chi	2021-06-03	Add FAQ	
V1.1.2	Zhichao Yu	2021-07-24	Add audio related introduction	
V1.1.3	Ruby Zhang	2021-10-11	Fix some expressions	
V1.1.4	Zhichao Yu	2021-10-26	Support Interlaced Frame Composite	
V1.1.5	Xing Zheng	2021-10-27	Add multichannel audio record introduction	
V1.1.6	Zhichao Yu	2022-03-08	Add additional notes	
V1.1.7	Zhichao Yu	2022-06-08	Add instruction for input different resolution cameras	
V1.1.9	Zhichao Yu	2022-11-29	Add product performance optimization introduction	

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# 1. Rockchip DVR/DMS Product Solution Introduction

RV1126 chip has two MIPI interfaces and one DVP interface. In addition, it provides powerful encoding performance and supports up to 8 channels of 1080@15fps simultaneous encoding. With a built-in 2T computing power NPU, it is very suitable for the development of DVR/DMS products.

## 1.1 Advantages of Developing DVR/DMS Product on RV1126 Platform

- Support up to 8 channels of 1080P analog HD video input;
- Powerful AI processing capabilities, support for operating DMS+ADAS algorithms at the same time;
- Powerful encoding capabilities, up to 8 channels of 1080P@15fps simultaneous encoding;
- Support 8 channels video OSD overlay;
- Support 8 channels video split-screen display demo;

## 1.2 Analog HD RX Chip Support List

At present, RV1126 platform has been adapted to many analog HD RX chips, and the drivers for these chips have been integrated in the SDK. You can select from the following table:

Model	Manufacturer	Interface	Number of Channels	Maximum Supported Resolution
NVP6188	Nextchip	MIPI	4	4K
N4	Nextchip	MIPI	4	1080P
TP2815	Techpoint	MIPI	4	1080P
TP2855	Techpoint	MIPI	4	1080P
TP9930	Techpoint	DVP	4	2K
TP9950	Techpoint	MIPI/DVP	1	1080P

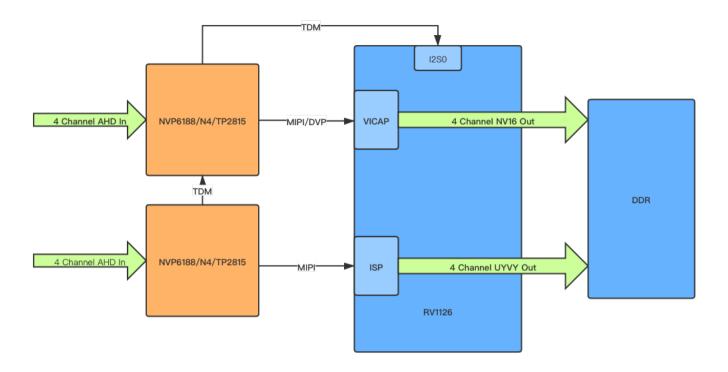
# 1.3 RV1126 DVR/DMS Products Application Block diagram

RV1126 supports different AD chip access methods, MIPI + MIPI and MIPI + DVP.

Due to the limitation of the RV1126 chip, it is necessary to limit the image output formats of different channels:

- VICAP channel: all should adopt NV16 format;
- ISP access: all should adopt UYVY format;

The block diagram of the reference solution of camera input is as follows:



NOTE: The DVP port cannot support different resolution camera input, therefore dual MIPI scheme is recommended.

# 2. Analog HD RX Chip Driver Development Introduction

# 2.1 Kernel Config

Open the relevant config of the RX chip accordingly:

```
CONFIG_VIDEO_NVP6188=y
```

# 2.2 Kernel dts Configuration

Take NVP6188 RX chip as an example:

```
nvp6188_0: nvp6188_0@30 {
  compatible = "nvp6188";
  reg = <0x30>;
  clocks = <&cru CLK_MIPICSI_OUT>;
  clock-names = "xvclk";
  power-domains = <&power RV1126_PD_VI>;
```

```
pinctrl-names = "rockchip, camera default";
 pinctrl-0 = <&mipicsi clk0>;
 reset-gpios = <&gpio4 RK PA0 GPIO ACTIVE HIGH>;
 power-gpios = <&gpio1 RK PD4 GPIO ACTIVE HIGH>;
 vi-gpios = <&gpio3 RK PC0 GPIO ACTIVE HIGH>;
 rockchip, camera-module-index = <0>;
 rockchip, camera-module-facing = "front";
 rockchip, camera-module-name = "nvp6188";
 rockchip,camera-module-lens-name = "nvp6188";
 port {
   ucam out0: endpoint {
     remote-endpoint = <&mipi in ucam0>;
     data-lanes = <1 2 3 4>;
   };
  };
};
nvp6188 1: nvp6188 1@32 {
 compatible = "nvp6188";
 reg = <0x32>;
 clocks = <&cru CLK MIPICSI OUT>;
 clock-names = "xvclk";
 power-domains = <&power RV1126 PD VI>;
 pinctrl-names = "rockchip, camera default";
 pinctrl-0 = <&mipicsi clk1>;
 reset-gpios = <&gpio4 RK PA1 GPIO ACTIVE HIGH>;
 vi-gpios = <&gpio3 RK PC1 GPIO ACTIVE HIGH>;
 rockchip, camera-module-index = <1>;
 rockchip, camera-module-facing = "back";
 rockchip, camera-module-name = "nvp6188";
 rockchip, camera-module-lens-name = "nvp6188";
 port {
   ucam out1: endpoint {
     remote-endpoint = <&csi_dphy1_input>;
     data-lanes = <1 2 3 4>;
   };
  };
};
```

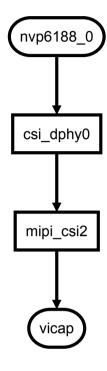
# 3. Data Streams Channels Introduction

# 3.1 Two-channel Solution

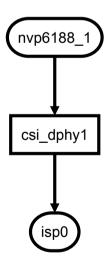
#### **Dual MIPI Solution**

Take the dual NVP6188 as an example:

• VICAP channel 0



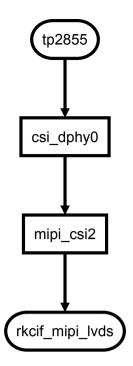
• ISP channel 1



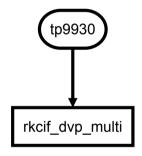
#### MIPI+DVP solution

Take TP9930+TP2855 for example:

• VICAP Channel 0



• VICAP Channel 1



## 3.2 Video Format Restrictions of Channels

#### 3.2.1 VICAP Channel

• Use NV16 format for capturing.

#### 3.2.2 ISP Channel

• Use UYVY format for capturing

## 3.3 Enumeration of Video Nodes of Channels

#### 3.3.1 VICAP Channel

• Capture device node name of stream cif mipi id0/1/2/3 by media-ctl -p -d /dev/mediaX

```
[root@RV1126 RV1109:/]# media-ctl -p -d /dev/media0
Media controller API version 4.19.111
Media device information
_____
driver
               rkcif
model
               rkcif mipi lvds
serial
bus info
hw revision
              0x0
driver version 4.19.111
Device topology
- entity 1: stream cif mipi id0 (1 pad, 4 links)
            type Node subtype V4L flags 0
            device node name /dev/video0
        pad0: Sink
                <- "rockchip-mipi-csi2":1 [ENABLED]
                <- "rockchip-mipi-csi2":2 []</pre>
                <- "rockchip-mipi-csi2":3 []</pre>
                <- "rockchip-mipi-csi2":4 []</pre>
- entity 5: stream cif mipi id1 (1 pad, 4 links)
            type Node subtype V4L flags 0
            device node name /dev/video1
        pad0: Sink
                <- "rockchip-mipi-csi2":1 []</pre>
                <- "rockchip-mipi-csi2":2 [ENABLED]
                <- "rockchip-mipi-csi2":3 []
                <- "rockchip-mipi-csi2":4 []
- entity 9: stream cif mipi id2 (1 pad, 4 links)
            type Node subtype V4L flags 0
            device node name /dev/video2
        pad0: Sink
                <- "rockchip-mipi-csi2":1 []
                <- "rockchip-mipi-csi2":2 []</pre>
                <- "rockchip-mipi-csi2":3 [ENABLED]</pre>
                <- "rockchip-mipi-csi2":4 []</pre>
- entity 13: stream cif mipi id3 (1 pad, 4 links)
             type Node subtype V4L flags 0
             device node name /dev/video3
```

#### 3.3.2 ISP Channel

• Get device node name of rkisp mainpath, rkisp rawwr0/1/2 by media-ctl -p -d /dev/mediaX

```
media-ctl -p -d /dev/media1
Media controller API version 4.19.111
Media device information
_____
driver
             rkisp
rkisp0
serial
bus info
hw revision 0 \times 0
driver version 4.19.111
Device topology
- entity 17: rkisp mainpath (1 pad, 1 link)
             type Node subtype V4L flags 0
             device node name /dev/video5
        pad0: Sink
                <- "rkisp-isp-subdev":2 [ENABLED]</pre>
- entity 29: rkisp_rawwr0 (1 pad, 1 link)
             type Node subtype V4L flags 0
             device node name /dev/video7
        pad0: Sink
                <- "rkisp-csi-subdev":2 [ENABLED]</pre>
- entity 35: rkisp rawwr1 (1 pad, 1 link)
             type Node subtype V4L flags 0
             device node name /dev/video8
        pad0: Sink
                <- "rkisp-csi-subdev":3 [ENABLED]</pre>
- entity 41: rkisp rawwr2 (1 pad, 1 link)
             type Node subtype V4L flags 0
             device node name /dev/video9
        pad0: Sink
```

```
<- "rkisp-csi-subdev":4 [ENABLED]
```

## 3.4 Video Capture Limitation of Channels

#### 3.4.1 ISP channel

• pipeline switch

```
The following code should be added to the boot script(/dev/media1 is determined according to the actual isp registration)

media-ctl -d /dev/media1 -l '"rkisp-isp-subdev":2->"rkisp-bridge-ispp":0[0]'
media-ctl -d /dev/media1 -l '"rkisp-isp-subdev":2->"rkisp_mainpath":0[1]'
```

stream on switch

Because there is no separate switch for the stream on switch of the four channels of rkisp\_mainpath and rkisp\_rawwr0/1/2, therefore, if you want to capture any one of the rkisp\_rawwr0/1/2 three channels, you have to ensure that the three channels will not stream out until the rkisp\_mainpath channel is in the stream on state.

• rkisp mainpath format switch

The output is 1080p by default. If you want to switch the format to 720p, you need to execute:

```
media-ctl -d /dev/media1 --set-v412 '"m01_b_nvp6188 1-
0032":0[fmt:UYVY8_2X8/1280x720]'
media-ctl -d /dev/media1 --set-v412 '"rkisp-csi-subdev":1[fmt:UYVY8_2X8/1280x720]'
media-ctl -d /dev/media1 --set-v412 '"rkisp-isp-subdev":0[fmt:YUYV8_2X8/1280x720]'
media-ctl -d /dev/media1 --set-v412 '"rkisp-isp-subdev":0[crop:(0,0)/1280x720]'
media-ctl -d /dev/media1 --set-v412 '"rkisp-isp-subdev":2[fmt:YUYV8_2X8/1280x720]'
media-ctl -d /dev/media1 --set-v412 '"rkisp-isp-subdev":2[crop:(0,0)/1280x720]'
```

# 3.5 Query Resolution and Video Signal of Channels

• Get subdev node name of sensor by media-ctl -p -d /dev/mediaX

```
media-ctl -p -d /dev/media1
Media controller API version 4.19.111
```

```
Media device information
_____
driver rkisp
model
             rkisp0
serial
bus info
hw revision 0 \times 0
driver version 4.19.111
Device topology
. . . .
- entity 92: m01 b nvp6188 1-0032 (1 pad, 1 link)
            type V4L2 subdev subtype Sensor flags 0
            device node name /dev/v41-subdev6
       pad0: Source
               [fmt:UYVY8_2X8/1920x1080 field:none]
               -> "rockchip-mipi-dphy-rx":0 [ENABLED]
```

#### • Get the resolution before opening the channel

```
#include <stdio.h>
#include <unistd.h>
#include <fcntl.h>
#include <sys/stat.h>
#include <sys/types.h>
#include <sys/time.h>
#include <sys/mman.h>
#include <sys/ioctl.h>
#include <linux/videodev2.h>
#define RKMODULE MAX VC CH 4
struct rkmodule vc fmt info {
   u32 width[RKMODULE MAX VC CH];
   __u32 height[RKMODULE_MAX_VC_CH];
    u32 fps[RKMODULE MAX VC CH];
} attribute ((packed));
struct rkmodule vc hotplug info {
   __u8 detect_status;
} __attribute__ ((packed));
#define RKMODULE_GET_VC_FMT_INFO \
   IOR('V', BASE VIDIOC PRIVATE + 12, struct rkmodule vc fmt info)
```

```
#define RKMODULE GET VC HOTPLUG INFO \
    IOR('V', BASE VIDIOC PRIVATE + 13, struct rkmodule vc hotplug info)
int main(int argc, char *argv[]) {
 int ch = 0;
 struct rkmodule vc hotplug info status;
 struct rkmodule vc fmt info fmt;
 int fd = open("/dev/v4l-subdev2", O RDWR, 0);
 ioctl(fd, RKMODULE GET VC FMT INFO, &fmt);
 ioctl(fd, RKMODULE GET VC HOTPLUG INFO, &status);
  for (ch = 0; ch < 4; ch++) \{
   printf("# ch: %d\n", ch);
   printf("\t width: %d\n", fmt.width[ch]);
   printf("\t height: %d\n", fmt.height[ch]);
   printf("\t fps: %d\n", fmt.fps[ch]);
   printf("\t plug in: %d\n", (status.detect status & (1 << ch)) ? 1 : 0);
  close(fd);
  return 0;
```

## 3.6 Query Hot Plug Interface In Real Time

• Provide sysfs nodes to user layer for read queries.

```
/sys/devices/platform/ff510000.i2c/i2c-1/1-0032/hotplug_status
/sys/devices/platform/ff510000.i2c/i2c-1/1-0030/hotplug_status
```

# 4. Multi-channel Audio Capture

The audio of DVR product is generally collected to RV1126 through TDM, and the following commands can be used to collect audio data from TDM:

```
arecord -Dhw:0,0 -c 8 -f S16_LE -r 8000 /tmp/record.wav -vv
```

And then we can record a specific channel follow the steps below:

1. Modifying /etc/asound.conf to config dsnooper

```
# Copyright © 2021 Rockchip Electronics Co. Ltd.
# Author: Xing Zheng <zhengxing@rock-chips.com>
pcm.!default
   type asym
   playback.pcm "hw:0,0"
   capture.pcm "hw:0,0"
}
pcm.dsnooper 6 {
   type dsnoop
   ipc_key 5978291 # must be unique for all dmix plugins!!!!
   ipc key add uid yes
   slave {
      pcm "hw:0,0"
        channels 6
   bindings {
        0 0
        1 1
        2 2
       3 3
       4 4
       5 5
   }
}
pcm.cap_ch0_rt {
   type route
   slave {
       pcm dsnooper 6
       channels 6
    ttable {
      0.0 1.0
   }
}
pcm.cap ch1 rt {
   type route
   slave {
      pcm dsnooper 6
       channels 6
   }
   ttable {
       0.1 1.0
    }
```

```
pcm.cap_ch2_rt {
  type route
  slave {
     pcm dsnooper 6
      channels 6
   ttable {
    0.2 1.0
   }
}
pcm.cap_ch3_rt {
  type route
   slave {
    pcm dsnooper_6
     channels 6
   ttable {
    0.3 1.0
  }
}
pcm.cap ch4 rt {
  type route
  slave {
     pcm dsnooper 6
      channels 6
   }
   ttable {
    0.4 1.0
   }
pcm.cap_ch5_rt {
  type route
   slave {
     pcm dsnooper 6
     channels 6
   ttable {
   0.5 1.0
  }
}
pcm.cap_ch0 {
  type plug
  slave.pcm "cap_ch0_rt"
```

```
pcm.cap_ch1 {
   type plug
   slave.pcm "cap ch1 rt"
pcm.cap ch2 {
    type plug
    slave.pcm "cap ch2 rt"
}
pcm.cap ch3 {
   type plug
    slave.pcm "cap ch3 rt"
pcm.cap ch4 {
    type plug
    slave.pcm "cap ch4 rt"
}
pcm.cap ch5 {
   type plug
    slave.pcm "cap ch5 rt"
```

2. Use the following command to record the 6th channel (the 1st channel is ch0)

```
arecord -Dcap_ch5 -c 1 -r 16000 -f S16_LE /tmp/record_ch5.wav
```

Finally, in your application, you can open "cap\_chX" to record audio data by calling rkmedia interface (X stands for  $0 \sim 5$ ).

NOTE: On RV1126/RV1109 SoC, only I2S0 supports TDM mode.

# 5. rkmedia\_vmix\_vo\_dvr\_test Application Note

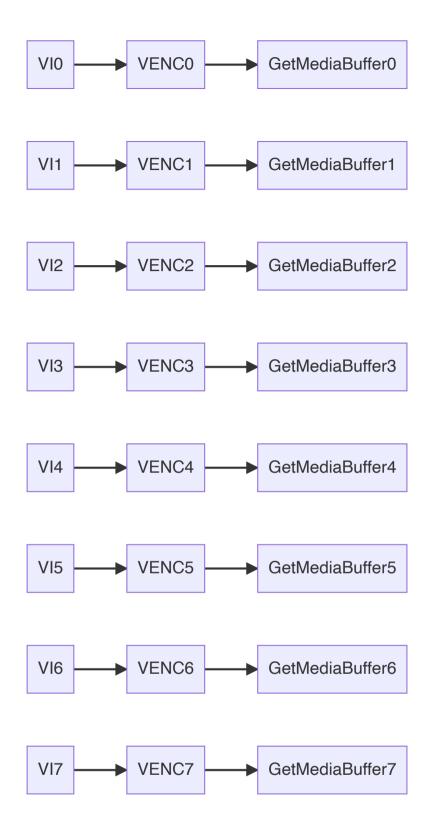
The rkmedia\_vmix\_vo\_dvr\_test is mainly used to realizes 8-channel video capture and encoding, and 8-channel video synthesis display. The source code is located in SDK/external/rkmedia/examples.

## 5.1 8-channel Video Capture and H264 Encoding

The 8-channel video capture node, resolution, and format are configured through an array, which is convenient for users to modify and debug:

According to the recommendation of the dual MIPI solution, it should be modified to:

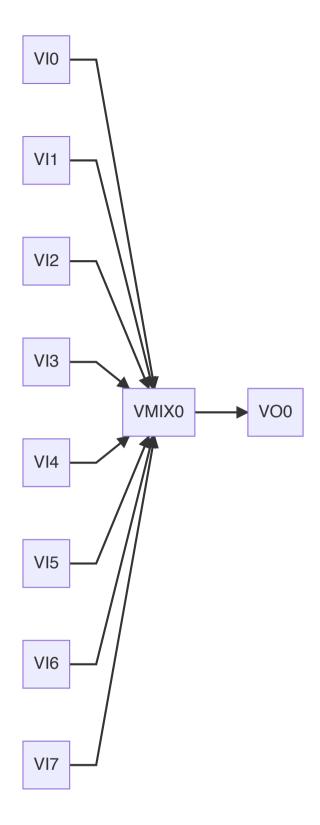
The 8-channel video VI implements 8-channel H264 encoding through bind VENC, and the 8-channel VENC-encoded data can be obtained through the GetMediaBuffer thread. Users can realize video transmission requirements base on it.



# 5.2 Support for 8-channel Video Synthesis Display

The 8-channel video specifies the rectangular area of the screen to be displayed through an array, which is convenient for users to modify and debug:

The 8-channel video synthesis display is realized through the VMIX+VO module:



# **5.3 Support for 8-channel Video Switching to Front 4-channel and Rear 4-channel Display**

Through dvr\_bind and dvr\_unbind, the 8-channel video can be switched to the front 4-channel and the rear 4-channel display. Users only needs to define the rectangular display area of the front 4-channel and the rear 4-channel.

# 5.4 Support for Area Frame

Area frame is realized by drawing lines on the whole screen, increasing the area boundary, and specifying the drawing area through an array. The minimum line width is 2, and an even number is required:

```
RECT_S line_2x4[4] = {
      {0, HEIGHT / 4, WIDTH, 2},
      {0, HEIGHT / 2, WIDTH, 2},
      {0, HEIGHT * 3 / 4, WIDTH, 2},
      {WIDTH / 2, 0, 2, HEIGHT},
};
```

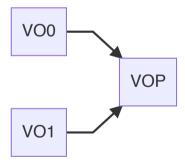
Line drawing area is set through RK\_MPI\_VMIX\_SetLineInfo.

# 5.5 Support for RGN Cover

It is supported to set sensitive areas for each channel, which is realized through RK\_MPI\_VMIX\_RGN\_SetCover.

## **5.6 Support for Screen OSD**

Screen OSD is realized through VO1, users can draw OSD in the buffer (the format is ABGR), after sending to VO1, the OSD can be superimposed on the VO0 video to display the effect through Alpha. In the osd\_thread of application, an OSD switching display of two color blocks is drawn every 500ms.



# 5.7 Support for Channel Display and Hide

Display and hide the channel through RK\_MPI\_VMIX\_ShowChn, RK\_MPI\_VMIX\_HideChn.

## 5.8 Support for Obtaining Regional Brightness of Channels

Regional brightness of channels is obtained through RK\_MPI\_VMIX\_GetChnRegionLuma, you can get up to 64 regional brightness at a time. The coordinate of each channel is the starting coordinate of the region relative to the channel, not the starting coordinate of the relative screen. You can realize the OSD inverse effect of the screen through the regional brightness.

## 6. VP Module Introduction

In DVR/DMS products, RGA is used frequently. In order to relieve the pressure of RGA, we use the scaling function of the ISPP module in the RV1126 chip. Therefore, we provide a VP module in rkmedia, through which the scaling function of ISPP can be used.

For details of VP, please refer to the document: docs/RV1126 RV1109/Multimedia/Rockchip Developer Guide Linux RKMedia CN.pdf.

It should be noted that the scaling function of ISPP limits the width of the Buffer and requires 16 Byte alignment.

# 7. System Performance Optimization

Due to the complicated service logic of DVR products, there may be multi mainstreams or substreams of camera, OSD, algorithm processing and other functions at the same time. System performance often hit bottlenecks. Therefore, this chapter will summarize some regular system performance optimization ways at present, customers should choose according to actual products.

## 7.1 CPU Performance Optimization

Before CPU performance optimization, you can use top, perf and other common tools to analyze CPU occupation to optimized firstly. In addition, applications should also be used to limit the invalid log printing. Log output also increase CPU consumption.

#### 7.1.1 Turn off High Resoultion Timer

Turn off high resolution timer configuration to reduce CPU consumption. To turn off high resolution timers, you should modify the configuration of kernel. The modification way is as follows:

-Config\_high\_res\_timers

After modifying the configuration, please re-build kernel.

**Note:** After the high resolution timer is closed, NPU driver loading may be affected. If the NPU driver fails to load and reports errors, please apply for a NPU driver with a compatible high resolution timer disabled at Redmine.

#### 7.1.2 Turn off IOMMU in ISPP

IOMMU is used to map non-continuous physical memories into continuous physical memories for hardware. IOMMU is enabled in ISPP by default. If using IOMMU, there will be additional CPU usage during memory mapping. You can configure a continuous physical memory for ISPP to achieve the purpose of closing IOMMU. The following patch is a modification example:

```
Diff -Git A/ARCH/ARM/BOOT/DTS/XXX.DTS B/ARCH/ARM/BOOT/DTS/XXX.DTS
index e2501ed7f996..360169b7fdd1 100644
--- A/Arch/ARM/BOOT/DTS/XXX.DTS
+++ B/ARCH/ARM/BOOT/DTS/XXX.DTS
@@ -318,7 +318,15 @@
 };
 & isp reserved {
-\text{Size} = <0 \times 064000000>;
+ \text{ size} = <0 \times 0 \times 000000000>;
+};
+& rkispp mmu {
+ Status = "Disabled";
+};
+& rkispp {
+ memory-region = <& isp reserved>;
 };
 & mipi csi2 {
```

**Note:** The size of continuous physical memory size reserved in isp\_reserved is different from product to product, and a reasonable configuration is needed according to product requirement.

## 7.2 RGA Performance Optimization

#### 7.2.1 To Enable DMA Buffer Cache

DVR products require using RGA for a large number of scaling and cropping operations. The buffer processed by RGA will be mapped before each operation, and therefore increase CPU consumption. This chapter will provide a method of caching the mapping information of RGA DMA Buffer to reduce CPU resources consumption.

DMA Buffer Cache is enabled in SDKs released after V3.0 by default. If it is an earlier SDK, please use the following patches to enable DMA Buffer Cache(Note: The following three patches are required and should be added one by one according to the serial number).

1. The first patch: 0001-dma-buf-dma-buf-cache-fix-error-case-for-attach-deta.patch

```
From 0423f7d60199d4aaf015924d6dd5983ff90b5998 Mon Sep 17 00:00:00 2001
From: Jianqun Xu <jay.xu@rock-chips.com>
Date: Tue, 28 Dec 2021 14:42:56 +0800
Subject: [PATCH] dma-buf: dma-buf-cache: fix error case for attach / detach
Signed-off-by: Jiangun Xu <jay.xu@rock-chips.com>
Change-Id: I84ff3ac7c1357416bb12ca61aa7134fc652538d6
 drivers/dma-buf/dma-buf-cache.c | 13 +++++++----
1 file changed, 8 insertions(+), 5 deletions(-)
diff --git a/drivers/dma-buf/dma-buf-cache.c b/drivers/dma-buf/dma-buf-cache.c
index 79f35d359241..7bfa6a5e5fc4 100644
--- a/drivers/dma-buf/dma-buf-cache.c
+++ b/drivers/dma-buf/dma-buf-cache.c
@@ -29,7 +29,7 @@ static int dma buf cache destructor(struct dma buf *dmabuf, void
*dtor data)
 mutex lock(&data->lock);
 list for each entry safe(cache, tmp, &data->head, list) {
  if (cache->sg table)
  if (!IS ERR OR NULL(cache->sg table))
     dma buf unmap attachment(cache->attach,
             cache->sg table,
             cache->direction);
@@ -83,6 +83,7 @@ EXPORT SYMBOL(dma buf cache detach);
 struct dma buf attachment *dma buf cache attach(struct dma buf *dmabuf,
           struct device *dev)
+ struct dma buf attachment *attach;
 struct dma buf cache list *data;
 struct dma buf cache *cache;
@@ -117,8 +118,13 @@ struct dma buf attachment *dma buf cache attach(struct dma buf
*dmabuf,
   return ERR PTR (-ENOMEM);
 /* Cache attachment */
- cache->attach = dma buf attach(dmabuf, dev);
+ attach = dma buf attach(dmabuf, dev);
+ if (IS_ERR_OR_NULL(attach)) {
  kfree(cache);
+ return attach;
```

```
+ }
+ cache->attach = attach;
mutex_lock(&data->lock);
list_add(&cache->list, &data->head);
mutex_unlock(&data->lock);
@@ -163,9 +169,6 @@ struct sg_table *dma_buf_cache_map_attachment(struct
dma_buf_attachment *attach,
    cache->sg_table = dma_buf_map_attachment(attach, direction);
    cache->direction = direction;

- if (!cache->sg_table)
- return ERR_PTR(-ENOMEM);
- return cache->sg_table;
}
EXPORT_SYMBOL(dma_buf_cache_map_attachment);
```

#### 2. The second patch: 0001-dma-buf-support-to-cache-dma-buf-attachment.patch

```
From 04273ec4b3523ed3420e16828b7731c20ec3a167 Mon Sep 17 00:00:00 2001
From: Jianqun Xu <jay.xu@rock-chips.com>
Date: Fri, 9 Jul 2021 10:00:21 +0800
Subject: [PATCH] dma-buf: support to cache dma-buf-attachment
This patch try to fix this issue by caching the dma-buf attachments and
stores the cache list to dtor data of dma-buf structor. The dma-buf
attach with cache will try to find cached attachment first and return
the valid instance.
This patch also store the deattch operation to dtor of dma-buf structor
by dma buf set destructor.
Change-Id: I4778c3328825f6c04f5d2608994e62fe3478bf1b
Signed-off-by: Jianqun Xu <jay.xu@rock-chips.com>
(cherry picked from commit 36514da674cb71553472a66704eae5981035c44c)
drivers/dma-buf/Kconfig
                              7 ++
 drivers/dma-buf/Makefile
                               1
                                  1 +
 include/linux/dma-buf-cache.h
                              32 +++++
 4 files changed, 211 insertions(+)
 create mode 100644 drivers/dma-buf/dma-buf-cache.c
 create mode 100644 include/linux/dma-buf-cache.h
diff --qit a/drivers/dma-buf/Kconfig b/drivers/dma-buf/Kconfig
index cc70e8bee874..414a05a8b7aa 100644
--- a/drivers/dma-buf/Kconfig
+++ b/drivers/dma-buf/Kconfig
```

```
@@ -1,5 +1,12 @@
menu "DMABUF options"
+config DMABUF CACHE
+ bool "DMABUF cache attachment"
+ default n
+ help
  This option support to store attachments in a list and destroy them by
  set to a callback list in the dtor of dma-buf.
config SYNC FILE
 bool "Explicit Synchronization Framework"
 default n
diff --qit a/drivers/dma-buf/Makefile b/drivers/dma-buf/Makefile
index c33bf8863147..87048e5d5aba 100644
--- a/drivers/dma-buf/Makefile
+++ b/drivers/dma-buf/Makefile
@@ -1,3 +1,4 @@
obj-y := dma-buf.o dma-fence.o dma-fence-array.o reservation.o seqno-fence.o
+obj-$(CONFIG DMABUF CACHE) += dma-buf-cache.o
obj-$(CONFIG SYNC FILE) += sync file.o
obj-$(CONFIG SW SYNC) += sw sync.o sync debug.o
diff --git a/drivers/dma-buf/dma-buf-cache.c b/drivers/dma-buf/dma-buf-cache.c
new file mode 100644
index 000000000000..79f35d359241
--- /dev/null
+++ b/drivers/dma-buf/dma-buf-cache.c
00 - 0.0 + 1.171 00
+// SPDX-License-Identifier: GPL-2.0
+/*
+ * Copyright (c) 2021 Rockchip Electronics Co. Ltd.
+ */
+#include <linux/slab.h>
+#include <linux/dma-buf.h>
+#undef CONFIG DMABUF CACHE
+#include <linux/dma-buf-cache.h>
+struct dma buf cache list {
+ struct list head head;
+ struct mutex lock;
+};
+struct dma buf cache {
+ struct list head list;
+ struct dma buf attachment *attach;
+ enum dma data direction direction;
+ struct sg table *sg table;
+ };
```

```
+static int dma buf cache destructor(struct dma buf *dmabuf, void *dtor data)
+ {
+ struct dma buf cache list *data;
+ struct dma buf cache *cache, *tmp;
+ data = dmabuf->dtor data;
+ mutex lock(&data->lock);
+ list for each entry safe(cache, tmp, &data->head, list) {
   if (cache->sg table)
   dma buf unmap attachment(cache->attach,
            cache->sg table,
             cache->direction);
+
   dma_buf_detach(dmabuf, cache->attach);
+
  list del(&cache->list);
+
  kfree(cache);
+
+ }
+ mutex_unlock(&data->lock);
+ kfree(data);
+ return 0;
+ }
+static struct dma buf cache *
+dma buf cache get cache(struct dma buf attachment *attach)
+ {
+ struct dma buf cache list *data;
+ struct dma buf cache *cache;
+ struct dma buf *dmabuf = attach->dmabuf;
+ if (dmabuf->dtor != dma_buf_cache_destructor)
+ return NULL;
+ data = dmabuf->dtor_data;
+ mutex lock(&data->lock);
+ list for each entry(cache, &data->head, list) {
  if (cache->attach == attach) {
    mutex_unlock(&data->lock);
     return cache;
+
+ }
+ }
+ mutex unlock(&data->lock);
+ return NULL;
+ }
```

```
+void dma buf cache detach(struct dma buf *dmabuf,
      struct dma buf attachment *attach)
+ {
+ struct dma buf cache *cache;
+ cache = dma buf cache get cache (attach);
+ if (!cache)
+ dma buf detach(dmabuf, attach);
+}
+EXPORT SYMBOL (dma buf cache detach);
+struct dma_buf_attachment *dma_buf_cache_attach(struct dma_buf *dmabuf,
          struct device *dev)
+ struct dma_buf_cache_list *data;
+ struct dma buf cache *cache;
+ if (!dmabuf->dtor) {
  data = kzalloc(sizeof(*data), GFP KERNEL);
  if (!data)
    return ERR PTR (-ENOMEM);
  mutex init(&data->lock);
+
  INIT LIST_HEAD(&data->head);
   dma buf set destructor(dmabuf, dma buf cache destructor, data);
+
+ }
+ if (dmabuf->dtor && dmabuf->dtor != dma buf cache destructor)
   return dma buf attach(dmabuf, dev);
+ data = dmabuf->dtor data;
+ mutex lock(&data->lock);
+ list for each entry(cache, &data->head, list) {
+ if (cache->attach->dev == dev) {
    /* Already attached */
    mutex unlock(&data->lock);
     return cache->attach;
+ }
+ }
+ mutex unlock(&data->lock);
+ cache = kzalloc(sizeof(*cache), GFP_KERNEL);
+ if (!cache)
+ return ERR PTR (-ENOMEM);
+ /* Cache attachment */
```

```
+ cache->attach = dma buf attach(dmabuf, dev);
+ mutex lock(&data->lock);
+ list add(&cache->list, &data->head);
+ mutex unlock(&data->lock);
+ return cache->attach;
+}
+EXPORT SYMBOL (dma buf cache attach);
+void dma buf cache unmap attachment(struct dma buf attachment *attach,
            struct sg table *sg table,
            enum dma data direction direction)
+ {
+ struct dma buf cache *cache;
+ cache = dma buf cache get cache(attach);
+ if (!cache)
  dma buf unmap attachment(attach, sg table, direction);
+ }
+EXPORT_SYMBOL(dma_buf_cache_unmap_attachment);
+struct sg table *dma buf cache map attachment(struct dma buf attachment *attach,
                enum dma data direction direction)
+ {
+ struct dma buf cache *cache;
+ cache = dma buf cache get cache (attach);
+ if (!cache)
  return dma buf map attachment(attach, direction);
+ if (cache->sg table) {
  /* Already mapped */
   if (cache->direction == direction)
    return cache->sg table;
   /* Different directions */
+
   dma buf unmap attachment(attach, cache->sg table,
          cache->direction);
+
+ }
+ /* Cache map */
+ cache->sg_table = dma_buf_map_attachment(attach, direction);
+ cache->direction = direction;
+ if (!cache->sg_table)
  return ERR_PTR(-ENOMEM);
```

```
+ return cache->sq table;
+EXPORT SYMBOL (dma buf cache map attachment);
diff --git a/include/linux/dma-buf-cache.h b/include/linux/dma-buf-cache.h
new file mode 100644
index 00000000000..d97545560990
--- /dev/null
+++ b/include/linux/dma-buf-cache.h
@@ -0,0 +1,32 @@
+/* SPDX-License-Identifier: GPL-2.0 */
+/*
+ * Copyright (c) 2021 Rockchip Electronics Co. Ltd.
+ */
+#ifndef LINUX DMA BUF CACHE H
+#define LINUX DMA BUF CACHE H
+#include <linux/dma-buf.h>
+extern void dma buf cache detach(struct dma buf *dmabuf,
         struct dma buf attachment *attach);
+extern void dma buf cache unmap attachment(struct dma buf attachment *attach,
             struct sg table *sg table,
             enum dma data direction direction);
+extern struct dma buf attachment *
+dma buf cache attach(struct dma buf *dmabuf, struct device *dev);
+extern struct sg_table *
+dma buf cache map attachment(struct dma buf attachment *attach,
           enum dma data direction direction);
+#ifdef CONFIG DMABUF CACHE
+/* Replace dma-buf apis to cached apis */
+#define dma buf attach dma buf cache attach
+#define dma buf detach dma buf cache detach
+#define dma_buf_map_attachment dma_buf_cache_map_attachment
+#define dma buf unmap attachment dma buf cache unmap attachment
+#endif
+#endif /* _LINUX_DMA_BUF_CACHE_H */
```

#### 3. The third patch

```
- a/drivers/video/rockchip/rga2/rga2_drv.c
+++ b/drivers/video/rockchip/rga2/rga2_drv.c
@@ -45,7 +45,7 @@

#if (LINUX_VERSION_CODE >= KERNEL_VERSION(4, 4, 0))
#include <linux/pm_runtime.h>
-#include <linux/dma-buf.h>
+#include <linux/dma-buf-cache.h>
#endif
```

Enable the following configuration in kernel:

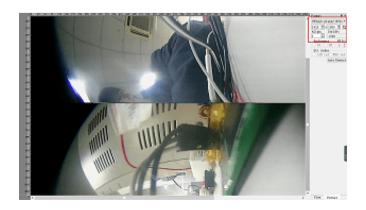
```
CONFIG_DMABUF_CACHE=y
```

You can add log printing to confirm whether RGA DMA-Cache takes effect:

Note: After confirming that the DMA-Cache of RGA is effective, the debugging log should be deleted.

# **8. FAQ**

# 8.1 Pictures are Staggered When Hot Plugging



#### 8.1.1 Solution

Add the following configuration in dts to solve the hot plug problem:

```
&rkcif_mipi_lvds {
    ....
    rockchip,cif-monitor = <3 2 25 1000 5>;
    ....
};
```

# 8.2 Support Interlaced Frame Composite for CVBS

There are limitations for "Interlaced Composite" function:

- 1. MIPI Interace: it should output frame count number (from frame start and frame end short packets) for parity judgement;
- 2. BT656 Interaface: it should output standard SAV/EAV, which has bit 6 for parity judgement;
- 3. In our dirver, only selfpath device support this function, otherwise it will output the following error log:

```
only selfpath support interlaced
```

You can use the following command to check which device is selfpath:

```
media-ctl -p
```

```
entity 3: rkisp_selfpath (1 pad, 1 link)
     type Node subtype V4L flags 0
     device node name /dev/video1
    pad0: Sink
     <- "rkisp-isp-subdev":2 [ENABLED]</pre>
```

#### **Modification In Driver**

You should set format.field to V4L2\_FIELD\_INTERLACED in your driver in xxxx\_get\_fmt function. driver/media/i2c/tc35874x.c would be a nice reference.