Interface Description Sensirion SCD30 Sensor Module

CO₂, humidity, and temperature sensor

- NDIR CO₂ sensor technology
- Integrated temperature and humidity sensor
- Best performance-to-price ratio
- Dual-channel detection for superior stability
- Small form factor: 35 mm x 23 mm x 7 mm
- Accuracy CO₂ sensor: ± (30 ppm + 3%)
- Fully calibrated with digital interface UART or I²C



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1 Digital interface description

The SCD30 digital interface is compatible with the I2C protocol and the Modbus protocol. For selecting Modbus protocol, the SEL pin needs to be pulled to VDD Voltage. Please refer to datasheet.

1.1 I2C Protocol

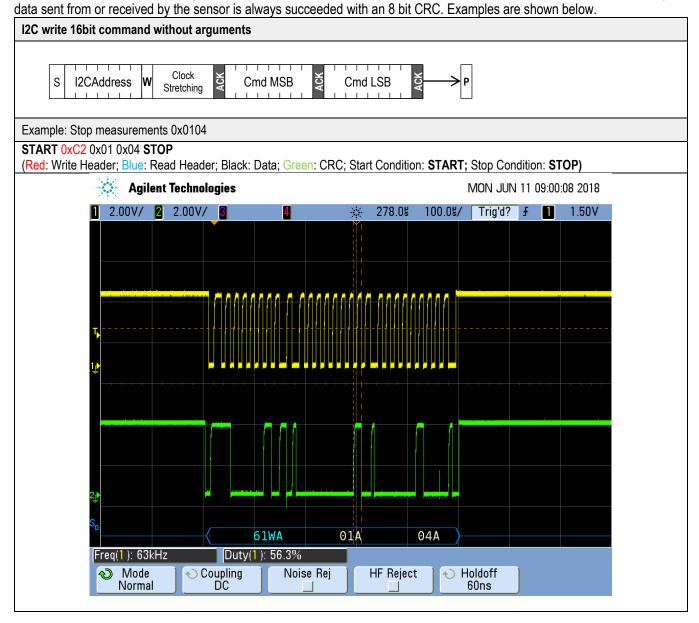
Maximal I2C speed is 100 kHz and the **master has to support clock stretching**. Clock stretching period in write- and read-frames is 12 ms, however, due to internal calibration processes a maximal clock stretching of 150 ms may occur once per day. For detailed information to the I2C protocol, refer to NXP I2C-bus specification¹. SCD30 does not support repeated start condition. Clock stretching is necessary to start the microcontroller and might occur before every ACK. I2C master clock stretching needs to be implemented according to the NXP specification. The boot-up time is < 2 s.

1.1.1 I2C Address

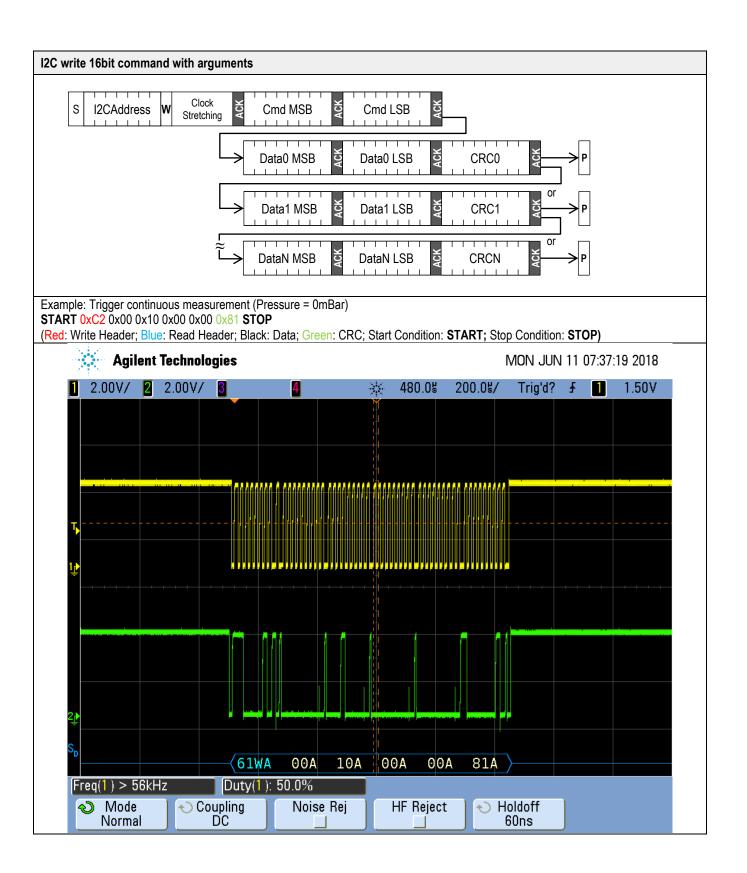
After power-up of the sensor, the I2C address of the prototype module is set to the address 0x61.

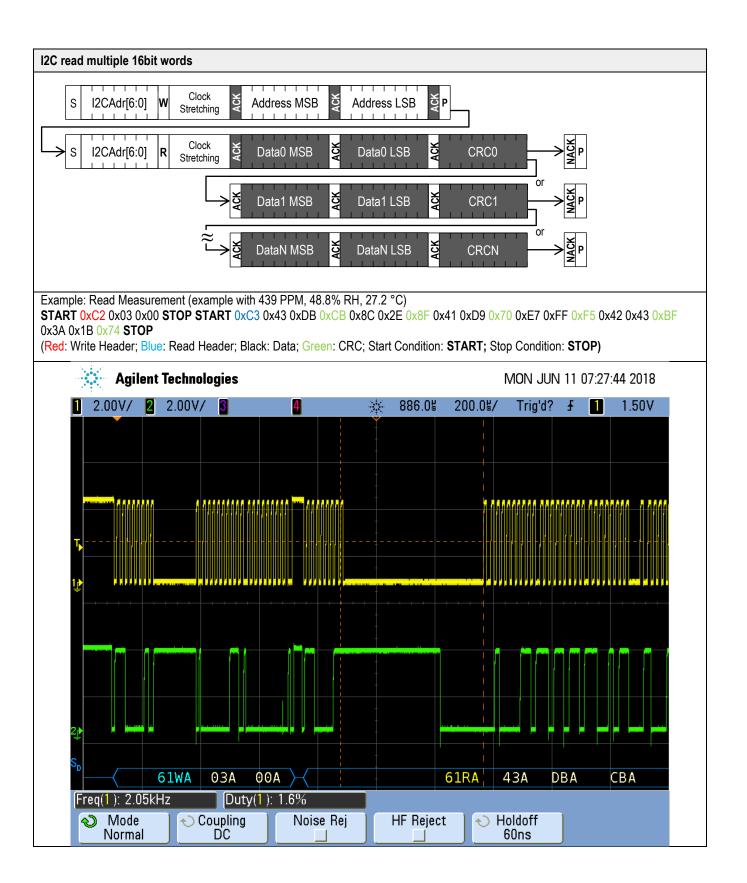
1.1.2 I2C Sequence

The commands issued by the I2C master are 16 bit with an optional parameter. Data sent to the master is protected by a CRC. This also applies to data arguments sent to the sensor, please see chapter 1.1.3 for CRC checksum calculation. 2 byte



¹ http://www.nxp.com/documents/user_manual/UM10204.pdf





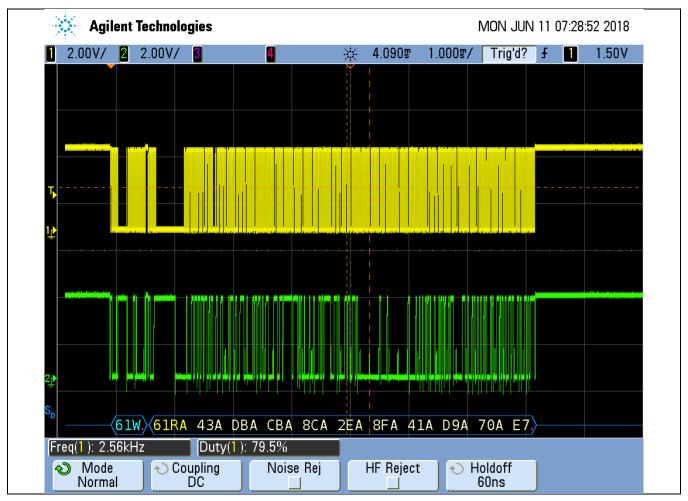


Table 1 I2C write and read communication frames. SDA is controlled by the I2C master in clear blocks and by the sensor in dark blocks.

1.1.3 I²C Checksum calculation

The checksum byte for I²C communication is generated by a CRC algorithm with the following properties:

Preceding Command	Value
Name	CRC-8
Protected Data	read data
Width	8 bits
Polynomial	0x31 (x ⁸ + x ⁵ + x ⁴ + 1)
Initialization	0xFF
Reflect Input	false
Reflect Output	false
Final XOR	0x00
Example	CRC(0xBEEF) = 0x92

1.2 Modbus protocol

For selecting Modbus protocol, the SEL pin needs to be pulled to VDD Voltage. Please refer to datasheet.

The supported baud rate is 19200 Baud with 8 Data bits, 1 Start bit and 1 Stop bit, no Parity bit.

More details on the Modbus protocol can be found here:

Description	Link
General introduction	http://www.modbus.org/docs/Modbus_over_serial_line_V1_02.pdf
Modbus frame generator	http://modbus.rapidscada.net/
Modbus CRC generator	https://www.lammertbies.nl/comm/info/crc-calculation.html

1.2.1 Modbus address

Modbus address is 0x61.

1.2.2 Modbus function codes

Available function codes are

Function code	Description
3	Read holding registers
4	Read input registers
6	Write single holding register

1.3 Sensor commands

The command set of the SCD30 is defined as follows. All commands are available via Modbus and I2C.

- Trigger continuous measurement with optional ambient pressure compensation
- Stop continuous measurement
- Set measurement interval
- Get data ready status
- Read measurement
- (De-)Activate continuous calculation of reference value for automatic self-calibration (ASC)
- Set external reference value for forced recalibration (FRC)
- Set temperature offset for onboard RH/T sensor
- Altitude compensation
- Read firmware version
- Soft reset

1.3.1 Trigger continuous measurement with optional ambient pressure compensation

Starts continuous measurement of the SCD30 to measure CO₂ concentration, humidity and temperature. Measurement data which is not read from the sensor will be overwritten. The measurement interval is adjustable via the command documented in chapter 1.3.3, initial measurement rate is 2s.

Continuous measurement status is saved in non-volatile memory. When the sensor is powered down while continuous measurement mode is active SCD30 will measure continuously after repowering without sending the measurement command.

The CO₂ measurement value can be compensated for ambient pressure by feeding the pressure value in mBar to the sensor. Setting the ambient pressure will overwrite previous and future settings of altitude compensation. Setting the argument to zero will deactivate the ambient pressure compensation. For setting a new ambient pressure when continuous measurement is running the whole command has to be written to SCD30.

Protocol	Command (hex)			Argument	Description		
I2C	0x0010 argumen	t		Format: uint16 Available	Triggers continuous measurement. Ambient pressure is compensated by setting argument. argument		
				range:			
Protocol	Function Code	Address	Data to write	0 & [700 1200]. Pressure			
Modbus	6	0x0036	0x0000 or pressure in mBar	in mBar.	= 0 deactivates pressure compensation.		

Protocol	Data to w	rite / read		Description							
I2C	Start Start	Write Header 0xC2	Cmd MSB 0x00								
Modbus	Request: Slave Addre ss 0x61	Slave Functi Addre Addre Addre on ss ss Code MSB LSI			Conte Conte CRC CRC nt nt LSB MSB MSB LSB 0x00 0x00 0x60 0x64						Start continuous measurement without ambient pressure compensation
	Response Slave Address 0x61	Function	Addres MSB 0x00	ss Ad LS 0x3		Content MSB 0x00	Content LSB 0x00	CRC LSB 0x60	CRC MSB 0x64		

1.3.2 Stop continuous measurement

Stops the continuous measurement of the SCD30.

Protocol	Command (hex)		Description	
I2C	0x0104, no argun			
		Stops continuous		
Protocol	Function Code	Address	Data to write	measurement.
Modbus	6			

Full sequence examples:

Protocol	Data to wr	rite	Description						
I2C	Start Start	Write Header 0xC2							
Modbus	Request: Slave Address 0x61	0x06	Address MSB 0x00	MSB LSB MSB LSB LSB MSB					Stops continuous measurement.
	Response Slave Address 0x61	Function	Address MSB 0x00	Address LSB 0x37	Content MSB 0x00	Content LSB 0x01	CRC LSB 0xF0	CRC MSB 0x64	

1.3.3 Set measurement interval

Sets the interval used by the SCD30 sensor to measure in continuous measurement mode (see chapter 1.3.1). Initial value is 2 s. The chosen measurement interval is saved in non-volatile memory and thus is not reset to its initial value after power up.

Protocol	Command (hex)			Argument	Description		
I2C	0x4600 argument			Format: unit16	Sets the interval for continuous measurement		
				Interval in seconds.			
Protocol	Function Code	Address	Data to write	Available range: [2 1800] given in 2 byte	mode. Standard		
Modbus	6	0x0025	argument	in the order MSB, LSB.	measurement interval is 2.		

Protocol	Data to v	vrite	Description								
	Set me	asurement i									
	Start	Write	Cmd	Cmd	Interval	Interval	CRC	Stop			
		Header	MSB	LSB	MSB	LSB					
	Start	0xC2	0x46	0x00	0x00	0x02	0xE3	Stop			
	Write:	asurement									
I2C	Start	Write	Cmd	Cmd	Stop				Set measurement interval		
120		Header	MSB	LSB						to 2s	
	Start	0xC2	0x46	0x00	Stop						
	Read:					•					
	Start	Read	Interv	Inter	CRC	Stop					
		Header	al	val							
			MSB	LSB							
	Start	0xC3	0x00	0x02	0xE3	Stop					
							•				

	Set measu	rement int	erval							
	Request:									1
	Slave	Functi	Addre	Add	Ire Cont	e Conte	CRC	CRC		Ī
	Addre	on	SS	SS	nt	nt	LSB	MSB		i
	SS	Code	MSB	LSE	B MSB	LSB				i
	0x61	0x06	0x00	0x2	5 0x00	0x02	0x10	0x60		1
	Response	:								l
	Slave	Function	n Addı	ress	Address	Content	Content	CRC	CRC	Ī
	Address			}	LSB	MSB	LSB	LSB	MSB	Ī
	0x61	0x06	0x00)	0x25	0x00	0x02	0x10	0x60	İ
odbus										İ
		surement i	nterval							İ
	Request						ı	ı		İ
	Slave	Function			Address	No. of	No. of	CRC	CRC	Í
	Address	Code	MSE	}	LSB	register	register	LSB	MSB	i
						s MSB	s LSB			İ
	0x61	0x03	0x00)	0x25	0x00	0x01	0x9C	0x61	İ
	Respons	e:								Í
	Slave	Function	n No.	of	Content	Content	CRC	CRC		İ
	Address	Code	Byte	S	MSB	LSB	LSB	MSB		İ
	0x61	0x03	0x02	2	0x00	0x02	0xB9	0x8D		İ

1.3.4 Get data ready status

Data ready command is used to determine if a measurement can be read from the sensor's buffer. Whenever there is a measurement available from the internal buffer this command returns 1 and 0 otherwise. As soon as the measurement has been read by the return value changes to 0.

It is recommended to use data ready status byte before readout of the measurement values.

Protocol	Address (hex)	Description			
I2C	0x0202, no argumen	Data ready status. Status			
		equals "1" when a			
Protocol	Function Code	Address	measurement is available to		
Modbus	3	0x0027	be read from the sensor.		

Full sequence examples:

Protocol	Data to w	rite/Read		Description									
	Write:												
	Start	Write	Cmd	Cm	nd St	юр							
		Header	MSB	LSI	В								
	Start	0xC2	0x02	0x0)2 St	юр							
I2C	Read:												
	Start	Read	Data	Dat	ta CI	RC	Sto	р					
		Header	Ready	Rea									
			MSB	LSI									
	Start	0xC3	0x00	0x0)1 0x	:B0	Stop						
	Request												Reading Data Ready status (returning 1)
	Slave	Function	n Addr	ess	Address	No. of	f	No. c	of	CRC	CRC		(returning r)
	Address	Code	MSB		LSB	regist	ers	regis	ters	LSB	MSB		
						MSB		LSB					
	0x61	0x03	0x00		0x27	0x00		0x01		0x3D	0xA1		
Modbus													
	Response												
	Slave	Function			Content	Content		RC	CR				
	Address	_	Bytes	_	ИSB	LSB	_	SB	MS				
	0x61	0x03	0x02	0)x00	0x01	0:	xF9	0x8	C			

I2C: SDA is controlled by the I2C master in clear blocks and by the sensor in dark blocks.

Read measurement

When new measurement data is available it can be read out with the following command. Make sure that the measurement is completed by reading the data ready status bit before read out.

Protocol	Address (hex)	ddress (hex)						
I2C	0x0300, no argumen	Reads a single						
Protocol	Function Code	Address	measurement of CO ₂ concentration.					
Modbus	3	0x0028 - 0x002D						

Full sequence examples:

Protocol	Data to write/read								Description
	Write:								2000.1940.1
		/rite Cn ader MS		Cmd _SB	Stop				
	Start 0	kC2 0x	03 ()x00	Stop				
	Read:								
	Start Rea		CO2 MLSB	CRO			CO2 LSB	CRC	
I2C	Start 0xC		0xDB	0xCl	B 0x	8C (0x2E	0x8F	
	T	T CI	יוכ	Г	T	CRC			
	MMSB 0x41	MIT2R	70 LM		LSB	0xF5			
	RH	RH o	l p	H I	RH		1		
	MMSB	MLSB CI	LM	SB LI	LSB	CRC	Stop		
	0x42	0x43 0x	BF 0x	3A 0	x1B	0x74	Stop		Example with sensor returning:
	Request	tion Address		I NI-		VI£	ODO	LODO	CO ₂ Concentration = 439 PPM
	Slave Fund Address Code		ss Addre LSB	reg	gister	No. of register	CRC LSB	CRC MSB	Humidity = 48.8 %
	0x61 0x03	3 0x00	0x28			s LSB 0x06	0x4C	0x60	Temperature = 27.2 °C
		, Toxoc	1 0/120		<u> </u>	oxee	<u> </u>	ones .	
	Response: Slave Fund		CO2	CO2	CO				
	Address Code 0x61 0x03		MMSB 0x43	MLSB 0xDB					
Modbus		V.	1	10	II.		•		
	T	T B LMSB	T LLSB	RH MMS	RH MLSB	RH LMSB	RH LL	SB	
	0x41 0xD9		0xFF	B 0x42	0x43	0x3A	0x1B		
			UXFF	UX4Z	UX43	UXSA	מוגטן		
	CRC CRC LSB MSB								
	0x50 0x07								

SDA is controlled by the I2C master in clear blocks and by the sensor in dark blocks.

I2C read-out stream:

Table 2 and Table 3 shows the data layout of the data read out from the sensor.

Using I2C for read-out the sensor will stream out the data in the given order.

Preceding Command	Consecutive read	Description
Read measurement	Byte1: CO ₂ concentration MMSB Byte2: CO ₂ concentration MLSB Byte3: CRC Byte4: CO ₂ concentration LMSB Byte5: CO ₂ concentration LLSB Byte6: CRC Byte7: Temperature MMSB Byte8: Temperature MLSB Byte9: CRC Byte10: Temperature LMSB Byte11: Temperature LLSB Byte11: Temperature LLSB Byte12: CRC Byte13: Humidity MMSB Byte14: Humidity MLSB Byte15: CRC Byte16: Humidity LLSB Byte17: Humidity LLSB Byte18: CRC	Data read-out table for I2C communication. Measurement of CO ₂ concentration, humidity and temperature has to be finished before read-out.

Table 2: I2C data read-out table. Read-out of measurement data can be aborted by sending a NACK followed by a stop condition after any data byte.

Example: The CO₂ concentration 400 ppm corresponds to 0x43c80000 in Big-Endian notation.

Modbus read-out stream:

Words for retrieving CO₂ concentration, humidity and temperature can be read out at the following addresses. The words can be read from the sensor in an arbitrary order.

Preceding Command	Consecutive read	Memory address	Description
Read measurement	Word0: CO ₂ MSW Word1: CO ₂ LSW Word2: Temperature MSW Word3: Temperature LSW Word4: Humidity MSW Word5: Humidity LSW	0x0028 0x0029 0x002A 0x002B 0x002C 0x002D	Data read-out table for Modbus communication. Measurement of CO ₂ concentration, humidity and temperature has to be finished before read-out.

Table 3: Modbus data read-out table.

Example: The CO_2 concentration 400 ppm corresponds to 0x43c80000 in Big-Endian notation.

1.3.5 (De-)Activate Automatic Self-Calibration (ASC)

Continuous automatic self-calibration can be (de-)activated with the following command. When activated for the first time a period of minimum 7 days is needed so that the algorithm can find its initial parameter set for ASC. The sensor has to be exposed to fresh air for at least 1 hour every day. Also during that period, the sensor may not be disconnected from the power supply, otherwise the procedure to find calibration parameters is aborted and has to be restarted from the beginning. The successfully calculated parameters are stored in non-volatile memory of the SCD30 having the effect that after a restart the previously found parameters for ASC are still present. Note that the most recently found self-calibration parameters will be actively used for self-calibration disregarding the status of this feature. Finding a new parameter set by the here described method will always overwrite the settings from external recalibration (see chapter 0) and vice-versa. The feature is switched off by default.

To work properly SCD30 has to see fresh air on a regular basis. Optimal working conditions are given when the sensor sees fresh air for one hour every day so that ASC can constantly re-calibrate. ASC only works in continuous measurement mode.

ASC status is saved in non-volatile memory. When the sensor is powered down while ASC is activated SCD30 will continue with automatic self-calibration after repowering without sending the command.

Protocol	Command (hex)			Argument	Description		
I2C	0x5306 argument			Format: uint16			
				"1": Activate continuous	See notes above, feature is		
Protocol	Function Code	Address	Data to write	ASC "0": Deactivate continuous	switched off by default.		
Modbus	6	0x003A	Argument	ASC			

Activate Automatic Self-Calibration	Protocol	Data to writ	е	Description						
Start		Activate Au	tomatic Sel	-Calibratio	 າ					·
Start						C A	SC CR	C Stop)	
Cet Automatic Self-Calibration Status				MSB L				·		
Virite		Start	0xC2	0x53 0x	k06 0x0	00 00	(00 0x8	31 Stop)	
No. Header MSB LSB		Write:								
Start	12C	Start								
Read	120	01 1								
Start		Start	0xC2	$0x53 \mid 0x$	(06 Stop					
Header MSB LSB Start 0xC3 0x00 0x00 0x81 Stop										
Start		Start				Stop)			
Request:		Start				Stop)			
Request: Slave										
Slave Function Address Address Content Content CRC CRC Address Code MSB LSB MSB LSB MSB LSB MSB LSB MSB MSB MSB LSB MSB		Activate Au	tomatic Sel	f-Calibratio	ı					1
Address										
Ox61										Example: deactivate ASC
Response: Slave Function Address Address Content Content CRC CRC Address Code MSB LSB MSB LSB MSB Dx61 0x06 0x00 0x3A 0x00 0x00 0xA0 0x67 Get Automatic Self-Calibration Request Slave Function Address Address No. of Registers Code MSB LSB MSB LSB MSB LSB MSB Dx61 0x03 0x00 0x3A 0x00 0x01 0xAD 0xA7 Response: Slave Function No. of Content Content CRC CRC Address Code Bytes MSB LSB MSB LSB MSB										
Slave		0x61	UXUb	0x00	UX3A	0x00	0x00	UXA0	0x67	
Address		Response:								
Ox61										
Modbus Get Automatic Self-Calibration Request										
Get Automatic Self-Calibration Request Slave Function Address Address No. of No. of CRC CRC Address Code MSB LSB registers registers LSB MSB 0x61 0x03 0x00 0x3A 0x00 0x01 0xAD 0xA7 Response: Slave Function No. of Content Content CRC CRC Address Code Bytes MSB LSB LSB MSB		0x61	0x06	0x00	0x3A	0x00	0x00	0xA0	0x67	
Address Code MSB LSB registers MSB LSB MSB 0x61 0x03 0x00 0x3A 0x00 0x01 0xAD 0xA7 Response: Slave Function No. of Content Content CRC CRC Address Code Bytes MSB LSB LSB MSB	Modbus		natic Self-C	alibration						
0x61 0x03 0x00 0x3A 0x00 0x01 0xAD 0xA7 Response: Slave Function No. of Content CRC CRC Address Code Bytes MSB LSB LSB MSB		Address	Code	MSB	LSB			LSB	MSB	
Response: Slave Function No. of Content CRC CRC Address Code Bytes MSB LSB LSB MSB		0v61	0,02	0,00	0.24			0۷۸۵	0,47	
Slave Function No. of Content CRC CRC Address Code Bytes MSB LSB LSB MSB				UXUU	UXSA	UXUU	UXUI	UXAD	UXAI	
Address Code Bytes MSB LSB LSB MSB										
UXO UXU3 UXU2 UXUU UXUU UX38 UX4C		0x61	0x03	0x02	0x00	0x00	0x38	0x4C	1	

Set Forced Recalibration value (FRC)

Forced recalibration (FRC) is used to compensate for sensor drifts when a reference value of the CO_2 concentration in close proximity to the SCD30 is available. For best results, the sensor has to be run in a stable environment in continuous mode at a measurement rate of 2s for at least two minutes before applying the FRC command and sending the reference value. Setting a reference CO_2 concentration by the method described here will always supersede corrections from the ASC (see chapter 1.3.5) and vice-versa. The reference CO_2 concentration has to be within the range 400 ppm $\leq c_{ref}(CO_2) \leq 2000$ ppm.

The FRC method imposes a permanent update of the CO₂ calibration curve which persists after repowering the sensor. The most recently used reference value is retained in volatile memory and can be read out with the command sequence given below. After repowering the sensor, the command will return the standard reference value of 400 ppm.

Protocol	Command (hex)			Argument	Description
I2C	0x5204 argument				
				Format: uint16	
Protocol	Function Code	Address	Data to write	CO ₂ concentration in ppm	See notes above.
Modbus	6	0x0039	Argument		

Protocol	Data to writ	е			Description				
	Set Forced	Recalibration	n value						
	Start	Write Header	Cmd MSB	Cmd LS	B FRO			Stop	
	Start	0xC2	0x52	0x04	0x0			Stop	
	Write:	d Recalibra							
I2C	Start	Write Header	Cmd MSB	Cmd LS	'				
	Start	0xC2	0x52	0x04	Sto	0			
	Read:								
	Start	Read Header	FRC MSB	FRC LS					
	Start	0xC3	0x01	0xC2	0x5	0 Stop			
	Set Forced Request: Slave Address 0x61 Response:	Function Code 0x06	Address MSB 0x00	Address LSB 0x39	Content MSB 0x01	Content LSB 0xC2	CRC LSB 0xD0	CRC MSB 0x66	Example: Set FRC with argument 450 ppm
	Slave Address	Function Code	Address MSB	Address LSB	Content MSB	Content LSB	CRC LSB	CRC MSB	
	0x61	0x06	0x00	0x39	0x01	0xC2	0xD0	0x66	
Modbus	Get Force Request:	d Recalibra	tion value			•	1		
	Slave Address	Function Code	Address MSB	Address LSB	No. of registers MSB	No. of registers LSB	CRC LSB	CRC MSB	
	0x61	0x03	0x00	0x39	0x00	0x01	0x5D	0xA7	
	Response					,	_	-	
	Slave Address	Function Code	No. of Bytes	Content MSB	Content LSB	CRC LSB	CRC MSB		
	0x61	0x03	0x02	0x01	0xC2	0xB8	0x4D		

1.3.6 Set Temperature Offset

The on-board RH/T sensor is influenced by thermal self-heating of SCD30 and other electrical components. Design-in alters the thermal properties of SCD30 such that temperature and humidity offsets may occur when operating the sensor in end-customer devices. Compensation of those effects is achievable by writing the temperature offset found in continuous operation of the device into the sensor.

Temperature offset value is saved in non-volatile memory. The last set value will be used for temperature offset compensation after repowering.

Protocol	Command (hex)			Argument	Description	
I2C	0x5403 argument			Format: uint16		
				Temperature offset, unit	See notes above.	
Protocol	Function Code	Address	Data to write	[°C x 100], i.e. one tick		
Modbus	6	0x003B	argument	corresponds to 0.01°C		

Б	5								D
Protocol	Data to write								Description
	Set Temperatur Offset Start			Cmd LSB	SHT Offse MSB	SHT Offset LSB	CRC	Stop	
	Start	0xC2	0x54	0x03	0x01	0xF4	0x33	Stop	
	Get Temper Write: Start	rature Offse	et Cmd	Cmd	Stop				
I2C	Ctart	Heade		LSB	Otop				
0	Start	0xC2	0x54	0x03	Stop				
	Read:		•	<u>.</u>		Otar	\neg		
	Start	Read Heade	MSB	LSB		Stop			
	Start	0xC3	0x01	0xF4	0x33	Stop		_	
	Set Temperat Request:			· · · · ·			1		Example: Set temperature
	Slave F Address	Function Code	Address MSB	Address LSB	Content MSB	Content LSB	CRC LSB	CRC MSB	offset to 5 K
	0x61	0x06	0x00	0x3B	0x01	0xF4	0xF1	0xB0	
	0.01	0,000	0,00	ONOD	ONOT	OAL I	OXI I	ONDO	
	Response:								
			Address	Address	Content	Content	CRC	CRC	
	Address	Code	MSB	LSB	MSB	LSB	LSB	MSB	
	0x61	0x06	0x00	0x3B	0x01	0xF4	0xF1	0xB0	
Modbus	Get Temper Request:						_		
	I I		Address	Address	No. of	No. of	CRC	CRC	
	Address	Code	MSB	LSB	registers MSB	registers LSB	LSB	MSB	
	0x61	0x03	0x00	0x3B	0x00	0x01	0xFC	0x67	
	Response:						_		
		Function	No. of	Content	Content	CRC	CRC		
	Address	Code	Bytes	MSB	LSB	LSB	MSB		
	0x61	0x03	0x02	0x01	0xF4	0x38	0x5B		

1.3.7 Altitude Compensation

Measurements of CO_2 concentration based on the NDIR principle are influenced by altitude. SCD30 offers to compensate deviations due to altitude by using the following command. Setting altitude is disregarded when an ambient pressure is given to the sensor, please see section 1.3.1.

Altitude value is saved in non-volatile memory. The last set value will be used for altitude compensation after repowering.

Protocol	Command (hex)			Argument	Description	
I2C	0x5102 argument					
				Format: uint16		
Protocol	Function Code	Address	Data to write	Height over sea level in [m] above 0.	See notes above.	
Modbus	6	0x0038	argument	, [m] abovo o.		

Protocol	Data to wri	te		Description					
	Set altitude);							
	Start	Write Header	Cmd MSB	Cmd LSB	Altitude MSB	Altitude LSB	CRC	Stop	
	Start	0xC2	0x51	0x02	0x03	0xE8	0xD4	Stop	
	Get altitud					_			
I2C	Start	Write Header	Cmd MSB	Cmd LSB	Stop				
	Start	0xC2	0x51	0x02	Stop				
	Read:						_		
	Start	Read Header	Altitude MSB	Altitude LSB	CRC	Stop			
	Start	0xC3	0x03	0xE8	0xD4	Stop			
	Set altitude Request: Slave Address 0x61	Function Code 0x06	Address MSB 0x00	Address LSB 0x38	Content MSB 0x03	Content LSB 0xE8	LSB	CRC MSB 0x19	Set altitude to 1000m above sea level
	Response:								
	Slave Address	Function Code	Address MSB	Address LSB	Content MSB	Content LSB	CRC LSB	CRC MSB	
	0x61	0x06	0x00	0x38	0x03	0xE8	0x01	0x19	
Modbus	Get altitud Request:	de:							
	Slave Address	Function Code	Address MSB	Address LSB	No. of registers MSB	No. of registers LSB	CRC LSB	CRC MSB	
	0x61	0x03	0x00	0x38	0x00	0x01	0x0C	0x67	
	Response	e:						_	
	Slave	Function	No. of	Content	Content	CRC	CRC		
	Address 0x61	Code 0x03	Bytes 0x02	MSB 0x03	LSB 0xE8	LSB 0x38	MSB 0xF2	-	
	LOXOI	UXU3	UXUZ	UXU3	UX⊏Ö	UXJÖ	UXFZ	J	

1.3.8 Read firmware version

Following command can be used to read out the firmware version of SCD30 module

Protocol	Address (hex)	Description			
I2C	0xD100, no argume				
		Returns the firmware			
Protocol	Function Code	Address	version		
Modbus	3	0x0020			

Protocol	Data to w	Data to write/Read									Description		
	Write:	Write		al .	_	کسما		Cton	7				
ļ	Start	Header		Cmd MSB		Cmd LSB		Stop					
	Start	0xC2	0xE)1	0x00			Stop					
I2C	Read:												
	Start	Read	Firmv			mware		CRC	Stop				
		Header	ader version major		version minor								
	Start	0xC3	0x0		()x42		0xF3	Stop				
	Request											F	
	Slave	Functi	Addre	Add	lre	No. c		No. of	CRC	CRC		Firmware version:	
	Addre	on	SS	SS		regis	t	regist	LSB	MSB		Major.Minor	
	SS	Code	MSB	LSE	3	ers MSB		ers LSB					
	0x61	0x03	0x00	0x2	0	0x00		0x01	0x8C	0x60			
NA. II.	Response:												
Modbus	Slave Funct		ion No	No. of Firmwa		Fir	mwa	CRC	CRC	1			
	Addres	ss Code	Ву	tes	re		re		LSB	MSB			
					_	sion	ver mir	rsion					
	0x61	0x03	0x(02	ma 0x0		0x4		0xB8	0x8D			
											-		
ISC: SDA :		11 (1 1/	20						(1	· .			

I2C: SDA is controlled by the I2C master in clear blocks and by the sensor in dark blocks.

1.3.9 Soft reset

The SCD30 provides a soft reset mechanism that forces the sensor into the same state as after powering up without the need for removing the power-supply. It does so by restarting its system controller. After soft reset the sensor will reload all calibrated data. However, it is worth noting that the sensor reloads calibration data prior to every measurement by default. This includes previously set reference values from ASC or FRC as well as temperature offset values last setting.

The sensor is able to receive the command at any time, regardless of its internal state. In order to start the soft reset procedure the following command should be sent.

Protocol	Command (hex)			Argument	Description
I2C	0xD304			Restarts the sensor	
Protocol	Function Code	Address	Data to write		Restarts the sensor
Modbus	6	0x0034	0x0001		

Protocol	Data to wri	te	Description						
I2C	Start Write Cmd Cmd Stop Header MSB LSB Start 0xC2 0xD3 0x04 Stop								
Modbus	Address Code M		Address MSB 0x00	Address LSB 0x34	Content MSB 0x00	Content LSB 0x01	CRC LSB 0x00	CRC MSB 0x64	Restarts the sensor
	Slave Address 0x61	Function Code 0x06	Address MSB 0x00	Address LSB 0x34	Content MSB 0x00	Content LSB 0x01	CRC LSB 0x00	CRC MSB 0x64	

1.4 Signal conversion to physical values

All data read from the sensor are float numbers in big-endian format². Conversion of digital values S_x , (x = c(CO2), RH, T) to physical values and respective units are shown in the following table

Physical quantity	Conversion formula	Units	Range
CO ₂ concentration c(CO ₂)	$c(CO_2) = S_{c(CO_2)}$	ppm	0 – 10000
Temperature T	$T = S_T$	°C	-40 – 125°C
Relative humidity RH	RH = S _{RH}	%RH	0 – 100

Table 4: Signal conversion table.

Conversation of temperature to °F as well as relative humidity to absolute humidity and dew point temperature can be found in Sensirion's online support center³

Sample pseudo code for converting data read from the sensor to physical value can be found below.

```
// CO2 concentration
float co2Concentration;
unsigned int tempU32;
// read data is in a buffer. In case of I2C CRCs have been removed
// beforehand. Content of the buffer is the following
unsigned char buffer[4];
buffer[0] = 0x43; //
                      MMSB CO2
buffer[1] = 0xDB; //
                      MLSB CO2
buffer[2] = 0x8C; // LMSB CO2
buffer[3] = 0x2E; // LLSB CO2
// cast 4 bytes to one unsigned 32 bit integer
tempU32 = (unsigned int)((((unsigned int)buffer[0]) << 24) |
                          (((unsigned int)buffer[1]) << 16) |</pre>
                          (((unsigned int)buffer[2]) << 8) |</pre>
                           ((unsigned int)buffer[3]));
// cast unsigned 32 bit integer to 32 bit float
co2Concentration = *(float*)&tempU32; // co2Concentration = 439.09f
```

² IEEE 754 applies.

³ https://www.sensirion.com/fileadmin/user_upload/customers/sensirion/Dokumente/2_Humidity_Sensors/Sensirion_Humidity_Sensors_at_a_Glance_V1.pdf

2 Important Notices

2.1 Warning, Personal Injury

Do not use this product as safety or emergency stop devices or in any other application where failure of the product could result in personal injury. Do not use this product for applications other than its intended and authorized use. Before installing, handling, using or servicing this product, please consult the data sheet and application notes. Failure to comply with these instructions could result in death or serious injury.

If the Buyer shall purchase or use SENSIRION products for any unintended or unauthorized application, Buyer shall defend, indemnify and hold harmless SENSIRION and its officers, employees, subsidiaries, affiliates and distributors against all claims, costs, damages and expenses, and reasonable attorney fees arising out of, directly or indirectly, any claim of personal injury or death associated with such unintended or unauthorized use, even if SENSIRION shall be allegedly negligent with respect to the design or the manufacture of the product.

2.2 ESD Precautions

The inherent design of this component causes it to be sensitive to electrostatic discharge (ESD). To prevent ESD-induced damage and/or degradation, take customary and statutory ESD precautions when handling this product.

See application note "ESD, Latchup and EMC" for more information.

2.3 Warranty

SENSIRION warrants solely to the original purchaser of this product for a period of 12 months (one year) from the date of delivery that this product shall be of the quality, material and workmanship defined in SENSIRION's published specifications of the product. Within such period, if proven to be defective, SENSIRION shall repair and/or replace this product, in SENSIRION's discretion, free of charge to the Buyer, provided that:

- notice in writing describing the defects shall be given to SENSIRION within fourteen (14) days after their appearance;
- such defects shall be found, to SENSIRION's reasonable satisfaction, to have arisen from SENSIRION's faulty design, material, or workmanship;
- the defective product shall be returned to SENSIRION's factory at the Buyer's expense; and
- the warranty period for any repaired or replaced product shall be limited to the unexpired portion of the original period.

This warranty does not apply to any equipment which has not been installed and used within the specifications recommended by SENSIRION for the intended and proper use of the equipment. EXCEPT FOR THE WARRANTIES EXPRESSLY SET FORTH HEREIN, SENSIRION MAKES NO WARRANTIES, EITHER EXPRESS OR IMPLIED, WITH RESPECT TO THE PRODUCT. ANY AND ALL WARRANTIES, INCLUDING WITHOUT LIMITATION, WARRANTIES OF MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE, ARE EXPRESSLY EXCLUDED AND DECLINED.

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