# COMP3467 Advanced Computer Systems Parallel programming and system administration Lecturer:Laura Morgenstern Durham University

Hien Ha Student ID: 000931275

### 1.1

Above is an example of a timer that was used to measure magic\_matrix.cpp performance. The function isMagicSquare requires the most computation time, but to be exact, it would be isPairwiseDistinct. The computation time of sumRow and sumColumn is the average of the N times the functions have been called, while isPairwiseDistinct is timed innately from within the function. The computation time in tabular form:

Function Name	Computation Time(s)
sumRow	0.000001917481422
sumColumn	0.000001057386398
isEqual	0.00000002384186
isPairwiseDistinct	59.494616985321045
generateMagicMatrix	0.003712177276611
isMagicSquare	59.495847940444946
Total:	59.499560117721558

Porting code to GPU leverages parallelism to allow GPU computations. The main OpenMP directive below is #pragma omp parallel for. This employs parallelising for loops and distributing workload between threads.

For nested loops above, the collapse construct is used to collapse 2 loops to one, reducing overhead. A guided scheduling clause is used to enhance load balancing by dynamically distributing loop iterations based on workload.

```
#pragma omp parallel for collapse(2) shared(magicSquare, pattern, modifier) private(iOuter, jOuter)
```

Other constructs are: shared, where variables are shared amongst threads to enhance memory management and reduce data transfer overhead; private, which ensures thread safety by creating private copies of variables for each thread, preventing data races, avoiding contention, and optimising performance through efficient memory access; reduction, which simplifies parallel code, ensuring thread-safe accumulation, enhancing performance in reductions.

```
#pragma omp parallel for reduction(+:sum) schedule(guided)
for (int i = 0; i < N; i++)
{
    sum += matrix[i][col];
}
return sum;</pre>
```

Using cache blocking/matrix tiling, matrices are broken down into smaller blocks to improve cache locality and reduce cache misses.

Compared to:

```
for (int i = 0; i < M; i++)
{
    for (int j = 0; j < M; j++)
    {
        int patternRow = i % N;
        int patternCol = j % N;
        magicSquare[i][j] = pattern[patternRow][patternCol];
        magicSquare[i][j] += modifier[i/N][j/N];
    }
}</pre>
```

Function is Pairwise Distinct had a time complexity of  $O(n^4)$ , is then optimised using a set to store seen elements. This reduces the time complexity to  $O(n^2)$ .

The best runtime for GPU code for N=20 recorded is: 0.068506956100464s, compared to best case: 52.17411s for sequential runtime, which is around 750 times faster.

# 2.2

With MPI to distribute the workload among the MPI processes, magic\_matrix.cpp can be parallelised. MPI\_Init, MPI\_Comm\_rank, MPI\_Comm\_size initialise MPI. For data distribution, the magic matrix can be distributed between processes where each process run on a subset of the matrix with size (N\*N) \* (N\*N): rank 0 process row 0 to (N \* N)/(num\_ranks - 1), rank 1 work row (N \* N)/num\_ranks to 2(N \* N)/(num\_ranks - 1), and so on.

Each process gets the entire pattern and the relevant row of the modifier using:

```
MPI_Bcast(&(pattern[0][0]), N*N, MPI_INT, 0, MPI_COMM_WORLD);
```

Where pattern is broadcasted as a whole to all ranks.

```
MPI_Scatter(&(modifier[0][0], N * M/num_ranks, MPI_INT, local_modifier, N * M/num_ranks, MPI_INT, 0, MPI_COMM_WORLD);
```

Where modifier is split/scattered between ranks, M/num\_ranks is the number of rows per rank, and local\_modifier is an array populated with the specific row of modifier relevant to each rank. MPI\_Scatterv can be used if data distribution is not uniform.

Local computations take place in each process, then aggregated using MPI\_Gather/MPI\_Allgather or MPI\_Reduce/MPI\_Allreduce depending on the function, ie. gather to aggregate data portions into one:

MPI\_Gather(&(magicSquare[rank \* M/num\_ranks)[0]), M/num\_ranks \* N, MPI\_INT, &(magicSquare[0][0]), M/num\_ranks \* N, MPI\_INT, 0, MPI\_COMM\_WORLD);

Or reduce for a reduction operation across all values:

MPI\_Reduce(&local\_result, &global\_result, 1, MPI\_C\_BOOL, MPI\_LOR, 0, MPI\_COMM\_WORLD);
This is used in isPairwiseDistinct function, where any duplicates found will return true due to OR operation

Where local\_result is the bool from each process, reduced to global\_result.

Use MPI\_Barrier(MPI\_COMM\_WORLD) for synchronisation where processes depend on data from each other.

For 9x9 output matrix to be distributed among 3 processes, this is a graph for data distribution where each row in a process represents a row of the magic matrix:

### -Rank 0:

[0,0]	[0, 1]	[0, 2]	[0, 3]	[0, 4]	[0, 5]	[0, 6]	[0, 7]	[0, 8]
[1, 0]	[1, 1]	[1, 2]	[1, 3]	[1, 4]	[1, 5]	[1, 6]	[1, 7]	[1, 8]
[2, 0]	[2, 1]	[2, 2]	[2, 3]	[2, 4]	[2, 5]	[2, 6]	[2, 7]	[2, 8]

#### -Rank 1:

[3,0]	[3, 1]	[3, 2]	[3, 3]	[3, 4]	[3, 5]	[3, 6]	[3, 7]	[3, 8]
[4, 0]	[4, 1]	[4, 2]	[4, 3]	[4, 4]	[4, 5]	[4, 6]	[4, 7]	[4, 8]
[5, 0]	[5, 1]	[5, 2]	[5, 3]	[5, 4]	[5, 5]	[5, 6]	[5, 7]	[5, 8]

## -Rank 2:

[6,0]	[6, 1]	[6, 2]	[6, 3]	[6, 4]	[6, 5]	[6, 6]	[6, 7]	[6, 8]
[7, 0]	[7, 1]	[7, 2]	[7, 3]	[7, 4]	[7, 5]	[7, 6]	[7, 7]	[7, 8]
[8, 0]	[8, 1]	[8, 2]	[8, 3]	[8, 4]	[8, 5]	[8, 6]	[8, 7]	[8, 8]

2.3
By running command numact1 -H and cat numact1.out, the output obtained is:

available: 2 nodes (0-1)

node 0 cpus: 0 1 2 3 4 5 6 7 16 17 18 19 20 21 22 23

node 0 size: 31847 MB node 0 free: 4080 MB

node 1 cpus: 8 9 10 11 12 13 14 15 24 25 26 27 28 29 30 31

node 1 size: 32211 MB node 1 free: 5110 MB

node distances:

node 0 1 0: 10 21 1: 21 10

### 2.4

To make an installation of magic\_matrix.cpp available to all users on the PVM, a centralised shared file system could be implemented by creating a shared directory in the head node containing magic\_matrix.cpp and any required dependencies. Users on the PVM nodes can access this shared directory. Deploying Ansible in the head node, an Ansible playbook can define the tasks needed to deploy magic\_matrix.cpp, such as copying files to target machines, setting up permissions and authorisation, or updating dependencies and configuration files in the shared directory. An inventory file is useful in listing all nodes and their connection details.

The advantages for this approach are: scalable, flexible, idempotent, automation, reduce storage costs, performant in fast local networks, enables same file access on multiple nodes, reduce system admin overhead, centralised updates and modifications to magic\_matrix.cpp or dependencies,.etc.

Its disadvantages are: require fast network connection, overhead for small-scale deployments, potential for conflicts when programs are run simultaneously leading to resource competition, potentially loose version control, security concerns where stored sensitive information is at risk.

By carefully considering security, version control and conflicts, this approach is an excellent way to make magic matrix.cpp available to users.