



NumPy: Vectorized Operations and Linear Algebra

What is a vectorized operation in NumPy?

- ❖ A vectorized operation is an operation that can be evaluated on all elements of an array at once instead of looping over individual entries.

NumPy Array

```
a = numpy.random.random((100000))  
b = 2  
c = a + b
```

Python List

```
a = numpy.random.random((100000)).tolist()  
b = 2  
c = []  
for aa in a:  
    c.append(aa + b)
```

What is a vectorized operation in NumPy?

- ❖ A vectorized operation is an operation that can be evaluated on all elements of an array at once instead of looping over individual entries.
- ❖ The main advantage of vectorized operation is **speed** in computation.
Example: adding a number to an array:

NumPy Array

```
a = numpy.random.random((100000))  
b = 2  
c = a + b
```

1.65 ms ± 50.4 µs per loop (mean ± std.

Python List

```
a = numpy.random.random((100000)).tolist()  
b = 2  
c = []  
for aa in a:  
    c.append(aa + b)
```

28.2 ms ± 1.8 ms per loop (mean ± std. dev.

All **NumPy** functions are
implemented as
vectorized operations.

Vectorized Operations in NumPy

There are in general three types of vectorized operations in NumPy:

- 1) **Vectorized Transformation**: that refers to vectorized operations that are applied to an array and produce an array of the same shape.
 - a) Simple scalar transformations
 - b) Boolean operations
 - c) Mathematical functions

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- 2) **Vectorized Dimension Reduction**: that reduces the dimensionality of the input array.

Questions?

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- 2) **Vectorized Dimension Reduction**: that reduces the dimensionality of the input array.
- 3) **Vectorized Linear Algebra Operations**

Linear Algebra Operations in NumPy

❖ Element-wise operations

❖ On arrays with the same shape

$$\mathbf{A}^{n \times m} + \mathbf{B}^{n \times m} = \mathbf{C}^{n \times m}$$

$$\mathbf{A}^{n \times m} - \mathbf{B}^{n \times m} = \mathbf{D}^{n \times m}$$

$$\mathbf{A}^{n \times m} * \mathbf{B}^{n \times m} = \mathbf{E}^{n \times m}$$

$$\mathbf{A}^{n \times m} / \mathbf{B}^{n \times m} = \mathbf{F}^{n \times m}$$

Linear Algebra Operations in NumPy

- ❖ Element-wise operations

- ❖ On arrays with the same shape

- ❖ On arrays with different shape (using broadcasting)

But what is broadcasting?

Broadcasting in Numpy

- ❖ **Broadcasting** enables NumPy to handle arrays with different shapes during vectorized operations.
- ❖ Broadcasting conditions (being “**broadcastable**”):
 - ❖ Array dimensions must be equal, or
 - ❖ for non-equal dimensions, either of them must be 1.

A (3d array): 5 x 4 x 3
B (3d array): 5 x 4 x 3



A (3d array): 1 x 4 x 3
B (3d array): 5 x 4 x 3



A (3d array): 5 x 4 x 3
B (2d array): 4 x 3



A (3d array): 5 x 4 x 3
B (3d array): 4 x 5 x 3



A (3d array): 5 x 1 x 3
B (3d array): 1 x 4 x 1



A (3d array): 5 x 4 x 3
B (2d array): 5 x 4



Broadcasting in Numpy

❖ **Broadcasting** is performed in five steps:

- i. **Shift:** If the number of dimensions is different, shift the array with smaller dimension to the right.
- ii. **Match:** Add 1 to the left so that the arrays have the same number of dimensions.
- iii. **Check:** Check if they are broadcastable: if yes continue to the next step.
- iv. **Stretch:** “copy” the single dimensions to match dimensions between the arrays.
- v. **Perform** the element-wise operation.

A (3d array): 5 x 4 x 3
B (2d array): 4 x 3



A (3d array): 5 x 4 x 3
B (2d array): 4 x 3



A (3d array): 5 x 4 x 3
B (3d array): 1 x 4 x 3



A (3d array): 5 x 4 x 3
B (3d array): 5 x 4 x 3

Broadcasting in Numpy

❖ **Broadcasting** is performed in five steps:

- i. **Shift:** If the number of dimensions is different, shift the array with smaller dimension to the right.
- ii. **Match:** Add 1 to the left so that the arrays have the same number of dimensions.
- iii. **Check:** Check if they are broadcastable: if yes continue to the next step.
- iv. **Stretch:** “copy”* all the single dimensions to match dimensions between the arrays.
- v. **Perform** the element-wise operation.

A (3d array): 5 x 4 x 3
B (2d array): 5 x 4



A (3d array): 5 x 4 x 3
B (2d array): 5 x 4



A (3d array): 5 x 4 x 3
B (3d array): 1 x 5 x 4

Check
A large red 'X' mark, indicating that the arrays are not broadcastable.

* In the stretch step, no actual copy occurs in the memory, it can be considered a virtual copy. This is why we call it stretch and not copy.

Questions?

Linear Algebra Operations in NumPy

- ❖ Element-wise operations

 - ❖ On arrays with the same shape

 - ❖ On arrays with different shape (using broadcasting)

- ❖ Dot product

 - ❖ Between two vectors

Dot Product Between Two Vectors

- ❖ The dot product is the sum of the products of the corresponding entries of two vectors.

$$[a_1 \quad a_2 \quad \dots \quad a_n] \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix} = a_1 b_1 + a_2 b_2 + \dots + a_n b_n$$

$$[1 \quad 2 \quad 3] \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix} = 1 \times 4 + 2 \times 5 + 3 \times 6 = 32$$

Linear Algebra Operations in NumPy

- ❖ Element-wise operations

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- ❖ Dot product

 - ❖ Between two vectors

 - ❖ Between two matrices

Matrix Dot Product

$$\mathbf{A}^{n \times m} \cdot \mathbf{B}^{m \times p} = \mathbf{C}^{n \times p}$$

$$\begin{bmatrix} a_{11} & a_{12} & \dots & a_{1m} \\ a_{21} & a_{22} & \dots & a_{2m} \\ \vdots & \vdots & \dots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nm} \end{bmatrix} \begin{bmatrix} b_{11} & b_{12} & \dots & b_{1p} \\ b_{21} & b_{22} & \dots & b_{2p} \\ \vdots & \vdots & \dots & \vdots \\ b_{m1} & b_{m2} & \dots & b_{mp} \end{bmatrix} = \begin{bmatrix} c_{11} & c_{12} & \dots & c_{1p} \\ c_{21} & c_{22} & \dots & c_{2p} \\ \vdots & \vdots & \dots & \vdots \\ c_{n1} & c_{n2} & \dots & c_{np} \end{bmatrix}$$

$$a_{11}b_{11} + a_{12}b_{21} + \dots + a_{1m}b_{m1} = c_{11}$$

Matrix Dot Product

$$\mathbf{A}^{n \times m} \cdot \mathbf{B}^{m \times p} = \mathbf{C}^{n \times p}$$

$$\begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1m} \\ a_{21} & a_{22} & \cdots & a_{2m} \\ \vdots & \vdots & \cdots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nm} \end{bmatrix} \begin{bmatrix} b_{11} & b_{12} & \cdots & b_{1p} \\ b_{21} & b_{22} & \cdots & b_{2p} \\ \vdots & \vdots & \cdots & \vdots \\ b_{m1} & b_{m2} & \cdots & b_{mp} \end{bmatrix} = \begin{bmatrix} c_{11} & c_{12} & \cdots & c_{1p} \\ c_{21} & c_{22} & \cdots & c_{2p} \\ \vdots & \vdots & \cdots & \vdots \\ c_{n1} & c_{n2} & \cdots & c_{np} \end{bmatrix}$$

$$a_{11}b_{12} + a_{12}b_{22} + \cdots + a_{1m}b_{m2} = c_{12}$$

Matrix Dot Product

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{bmatrix} = \begin{bmatrix} 1 \times 1 + 2 \times 3 + 3 \times 5 & 1 \times 2 + 2 \times 4 + 3 \times 6 \\ 4 \times 1 + 5 \times 3 + 6 \times 5 & 4 \times 2 + 5 \times 4 + 6 \times 6 \end{bmatrix} = \begin{bmatrix} 22 & 28 \\ 49 & 64 \end{bmatrix}$$

```
A = numpy.array([[1,2,3],[4,5,6]])  
B = numpy.array([[1,2],[3,4],[5,6]])  
C = A.dot(B)  
print(C)
```

```
[[22 28]  
 [49 64]]
```

Questions?

Linear Algebra Operations in NumPy

- ❖ Element-wise operations

 - ❖ On arrays with the same shape

 - ❖ On arrays with different shape (using broadcasting)

- ❖ Dot product

 - ❖ Between two vectors

 - ❖ Between two matrices

- ❖ Matrix transpose

Matrix Transpose

- ❖ The transpose of a matrix (or a vector) switches the row and column indices of the matrix A , often denoted by A^T .

```
A = numpy.array([[1,2],[3,4],[5,6]])  
print(A)  
print('#####')  
print(A.T)
```

```
[[1 2]  
 [3 4]  
 [5 6]]  
#####  
[[1 3 5]  
 [2 4 6]]
```

Linear Algebra Operations in NumPy

- ❖ Element-wise operations
 - ❖ On arrays with the same shape
 - ❖ On arrays with different shape (using broadcasting)
- ❖ Dot product
 - ❖ Between two vectors
 - ❖ Between two matrices
- ❖ Matrix transpose
- ❖ Matrix inversion

Matrix Inversion

- ❖ The inverse matrix of a **square** matrix is the inverse element of that matrix with respect to the dot product operation.
- ❖ Conditions for an invertible matrix:
 - ❖ It must be a square matrix
 - ❖ It must be a non-singular matrix, i.e., $\det(A) \neq 0$.
- ❖ Important properties:
 - ❖ $(A^{-1})^{-1} = A$
 - ❖ $A^{-1}A = I$
 - ❖ $(A^T)^{-1} = (A^{-1})^T$

```
from numpy.linalg import inv
A = numpy.random.uniform(0,1,(3,3))
print(inv(A))
```

```
[[-0.92714039  0.11653039  1.41232812]
 [-0.40393881  1.46465429 -0.11835523]
 [ 2.1522805  -0.64040583 -0.23933963]]
```

Thanks!