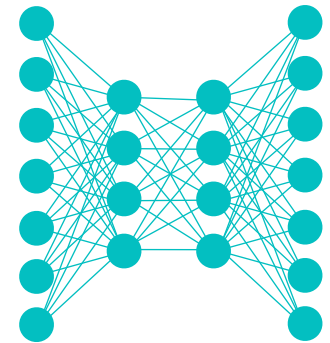


Lecture Notes for **Neural Networks and Machine Learning**



Fully Convolutional Learning II: Object Detection

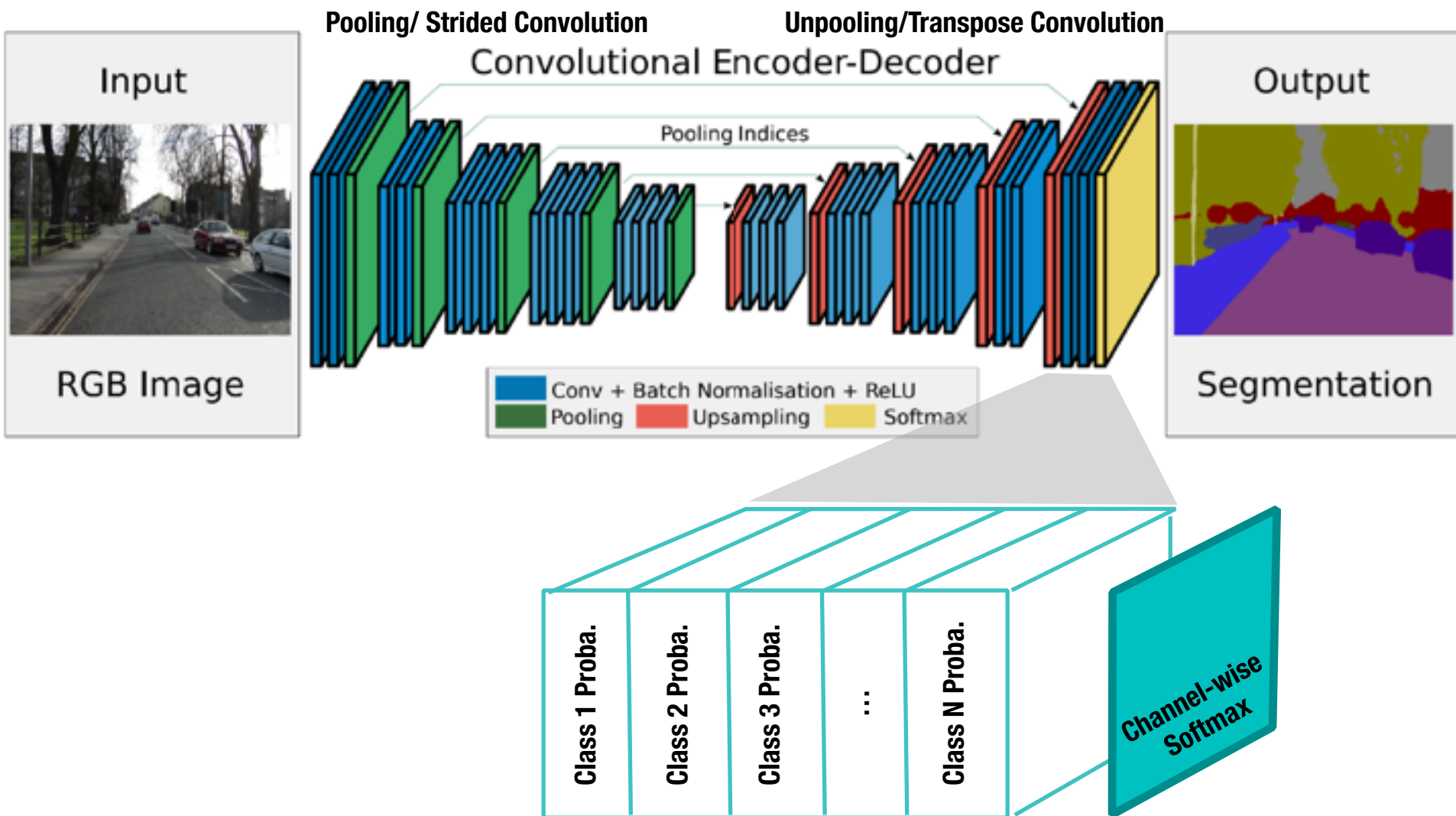


Logistics and Agenda

- Logistics
 - Lab due dates
 - Lab grading updates
- Agenda
 - Full Convolutional Architectures
 - ◆ Semantic Segmentation Basics (last time)
 - ◆ Object Detection (this time):
 - RCNN, YOLO
 - ◆ Instance Segmentation (next time, probably):
 - Mask-RCNN, YOLACT

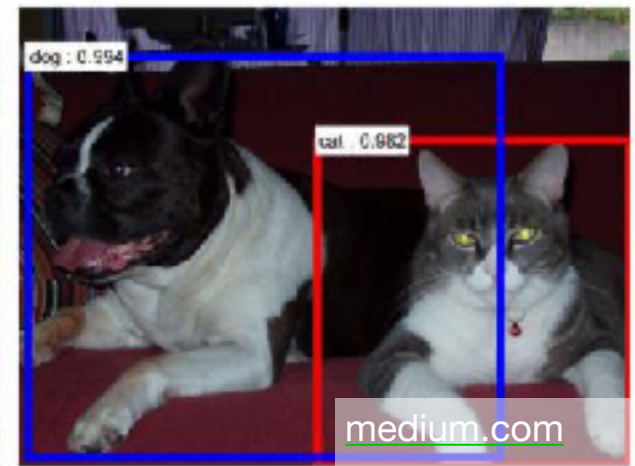
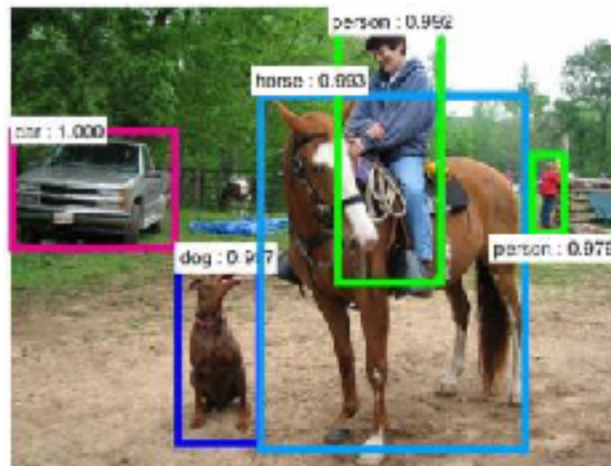


Last Time



This time... Object Detection Methods

- Semantic segmentation has good mIoU values (up to 90%) but this is exaggerated by background recognition, many classes are $<40\%$
- How to adapt these techniques to get bounding boxes, not semantic segmentations?
 - Could this be easier? More stable?
 - More consistent labeling?
 - Suitable for “higher risk” tracking applications?



Object Detection with RCNN

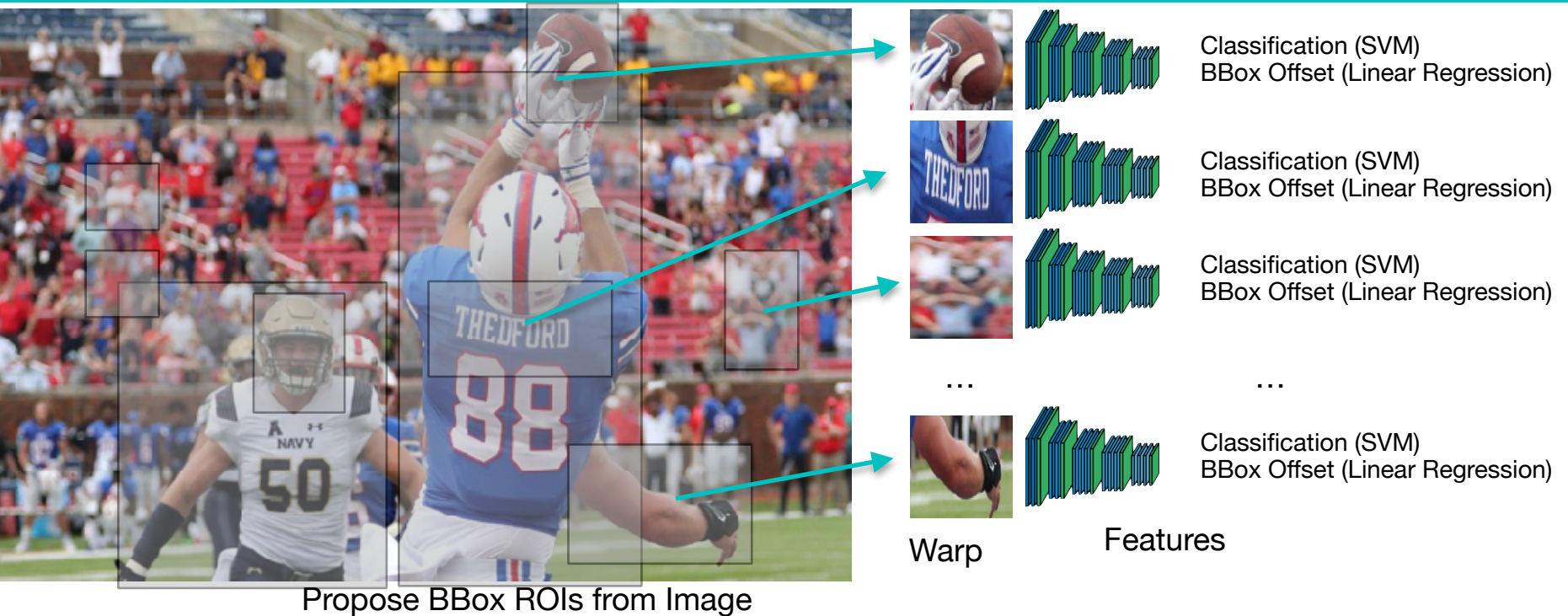


**A history in naming one network five different times
with five different papers
each time changing one thing about the architecture**

Research!



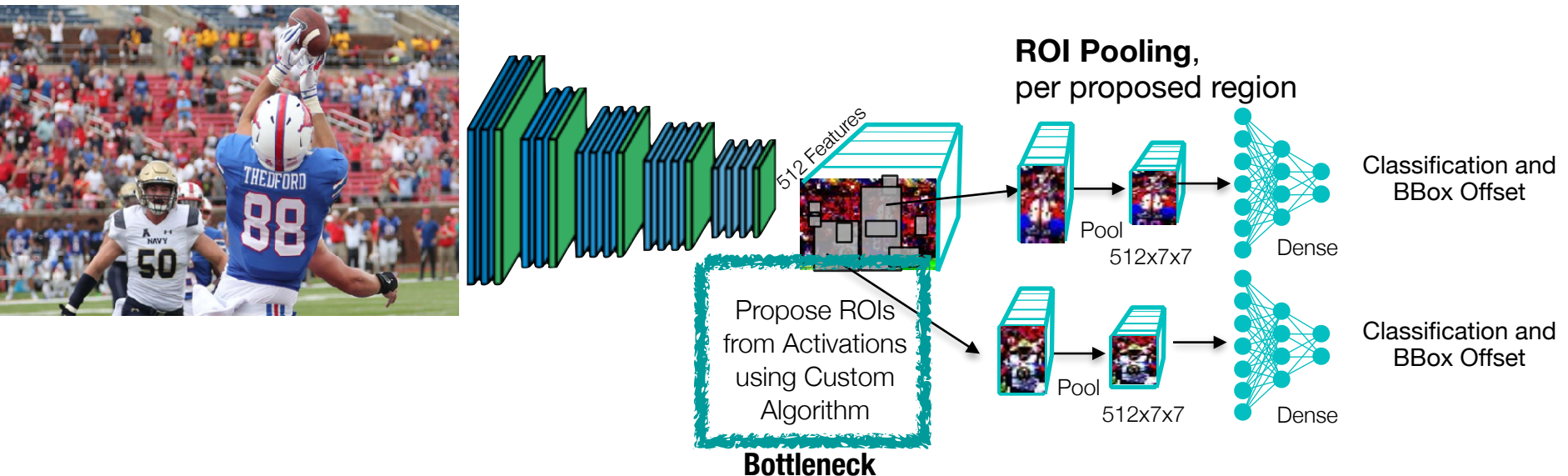
2014: R-CNN



- Too Slow to Be Useful
- SVM and BBox Regression Trained Separately
- Fine Tuned Existing ConvNet (for Warped Images)
- ~50 Seconds per Image when Deployed



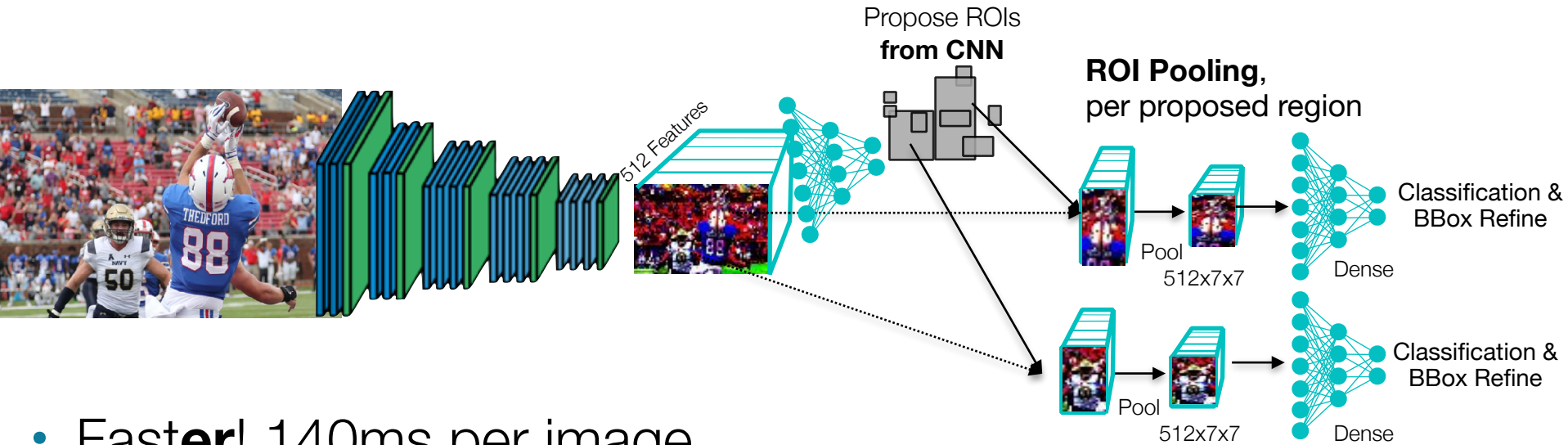
2015: Fast R-CNN



- Fast! 2.3 seconds per image (not ~50)
- But still not real time...



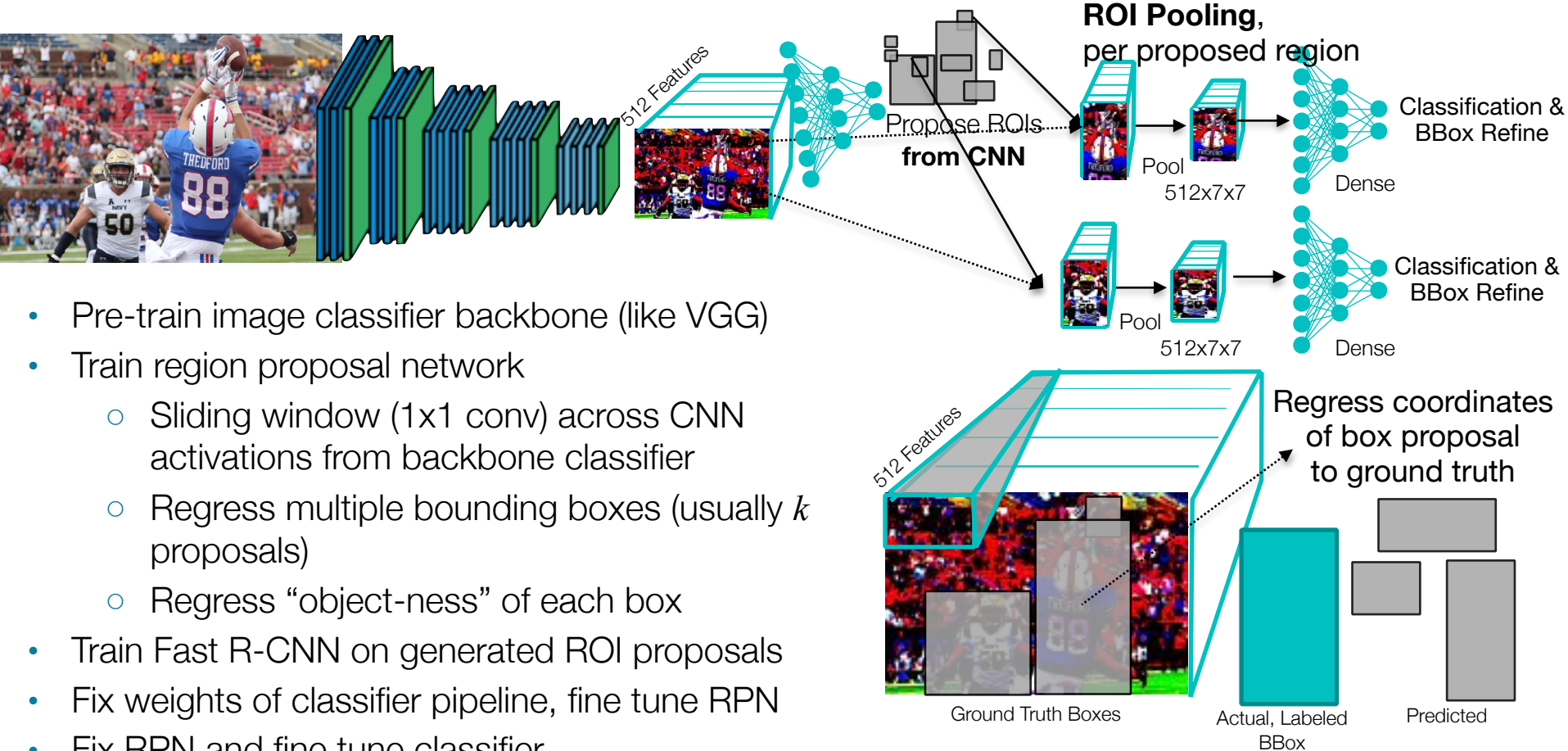
2015: Faster R-CNN



- **Faster!** 140ms per image (7 FPS)
- **Highly Accurate**



2015: Faster R-CNN, Training



- Pre-train image classifier backbone (like VGG)
- Train region proposal network
 - Sliding window (1x1 conv) across CNN activations from backbone classifier
 - Regress multiple bounding boxes (usually k proposals)
 - Regress “object-ness” of each box
- Train Fast R-CNN on generated ROI proposals
- Fix weights of classifier pipeline, fine tune RPN
- Fix RPN and fine tune classifier
- Rinse, repeat fine tuning

$$l_{box} = \sum_i \hat{p}_i \left[(x - \hat{x}_i)^2 + (y - \hat{y}_i)^2 + (\log w - \log \hat{w}_i)^2 + (\log h - \log \hat{h}_i)^2 \right]$$

$$l_{class} = \sum_c CE(c, \hat{c})$$

$$l_{obj} = \sum_i CE(p_i, \hat{p}_i)$$



Lecture Notes for Neural Networks and Machine Learning

FCN Learning: Detection



Next Time:
Instance Segmentation
Reading: None

