

Surface Parameterization

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SIGGRAPH2006

Outline

- Motivation
- Objectives and Discrete Mappings
- Angle Preservation
 - Discrete Harmonic Maps
 - Discrete Conformal Maps
 - Angle Based Flattening
- Reducing Area Distortion
- Alternative Domains

Surface Parameterization



Mercator-Projektion



Mollweide-Projektion

[www.wikipedia.de]

Surface Parameterization



Mollweide-Projektion



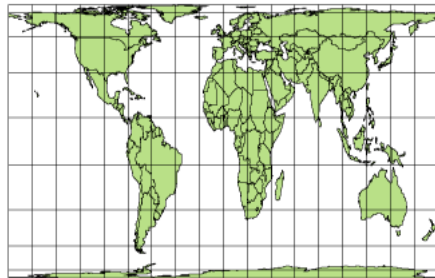
Mercator-Projektion



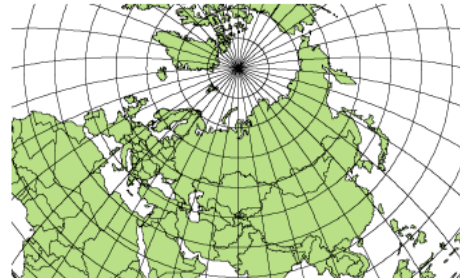
Zylinderprojektion nach Miller



Hammer-Aitoff-Projektion



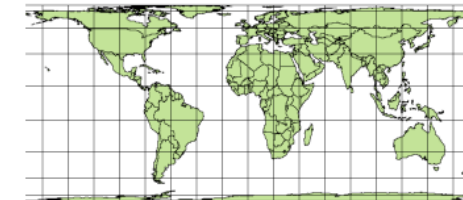
Peters-Projektion



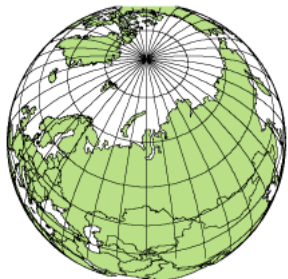
Längentreue Azimuthalprojektion



Stereographische Projektion



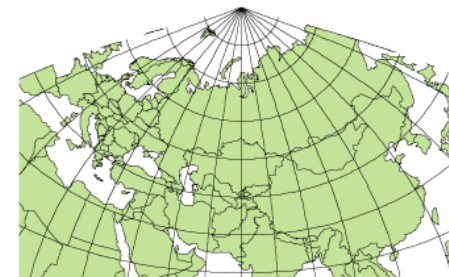
Behrmann-Projektion



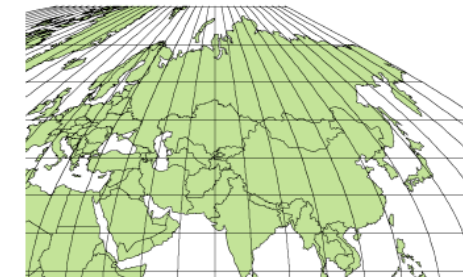
Senkrechte Umgebungsperspektive



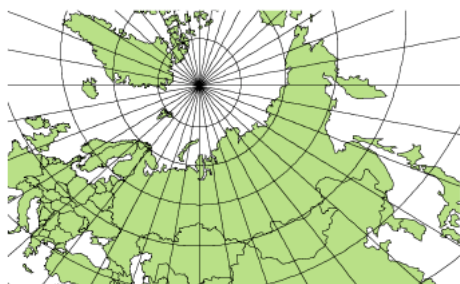
Robinson-Projektion



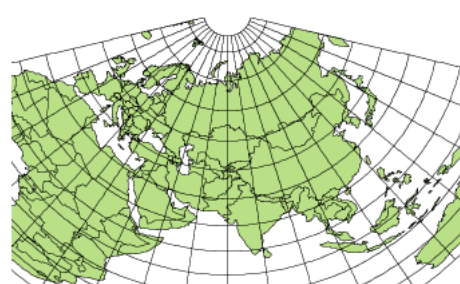
Hotine Oblique Mercator-Projektion



Sinusoidale Projektion



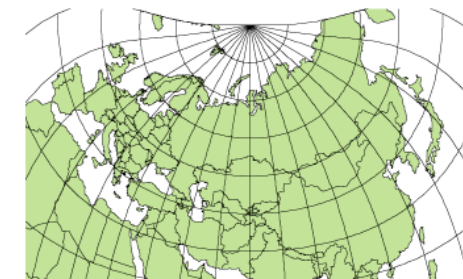
Gnomonische Projektion



Flächentreue Kegelprojektion



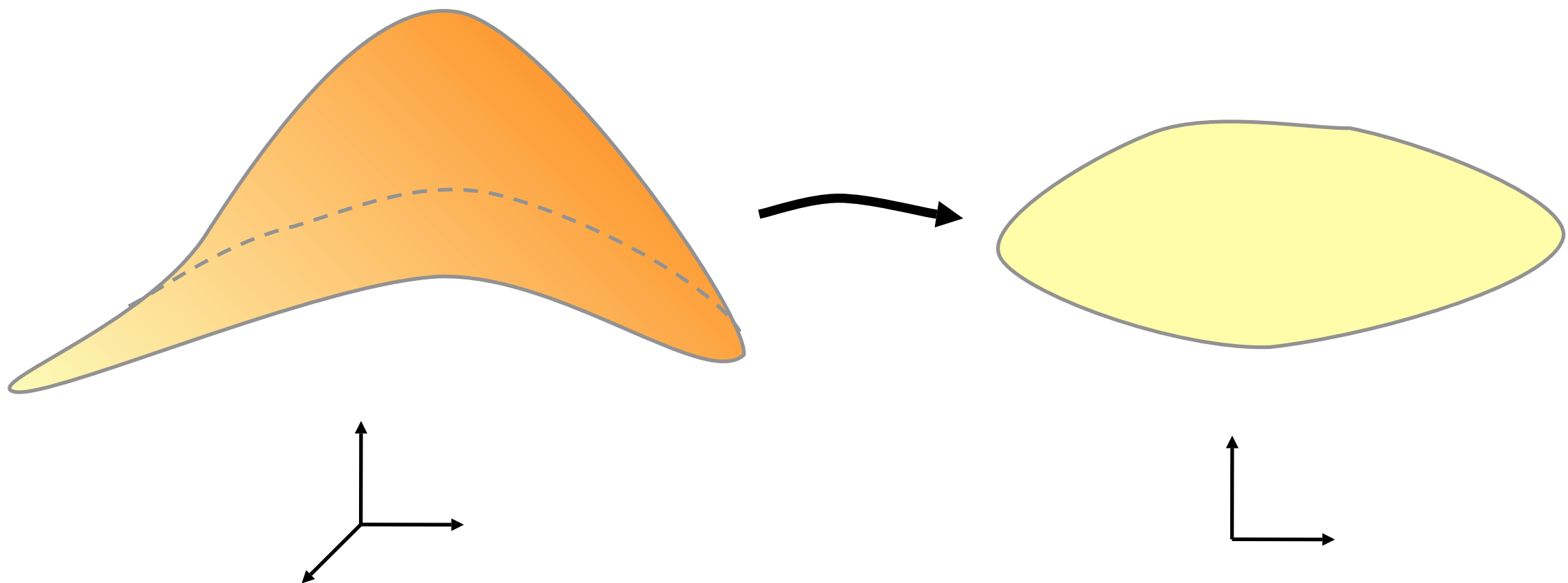
Transverse Mercator-Projektion



Cassini-Soldner-Projektion

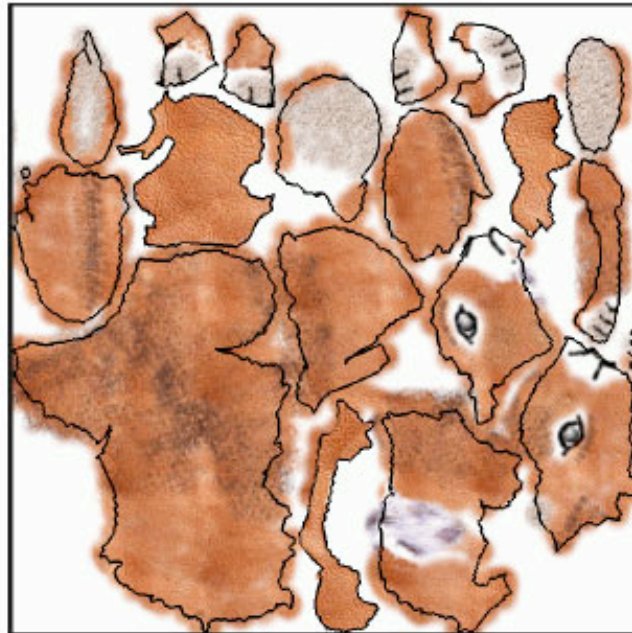
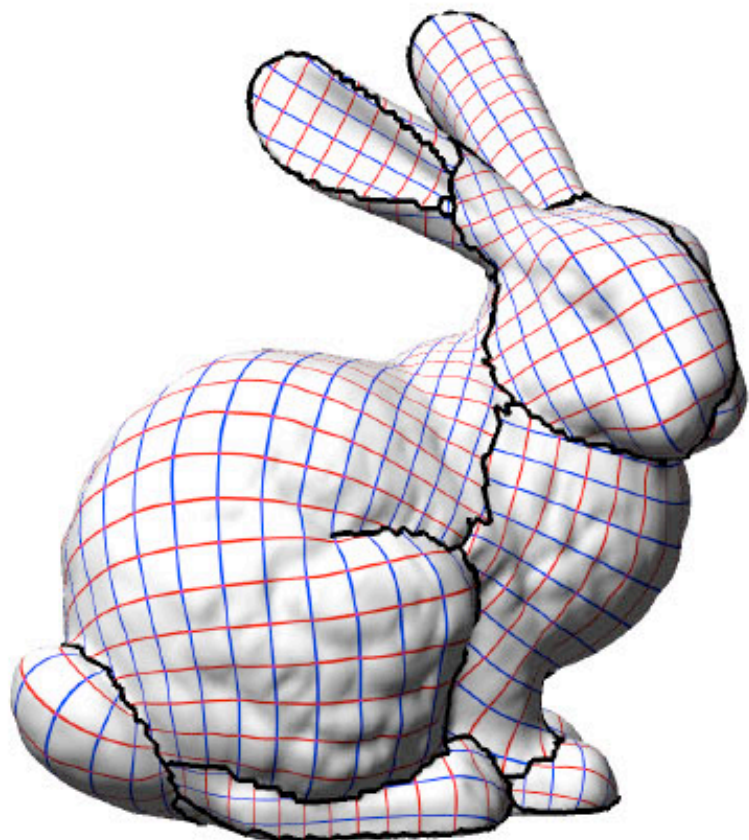
[www.wikipedia.de]

Surface Parameterization



Motivation

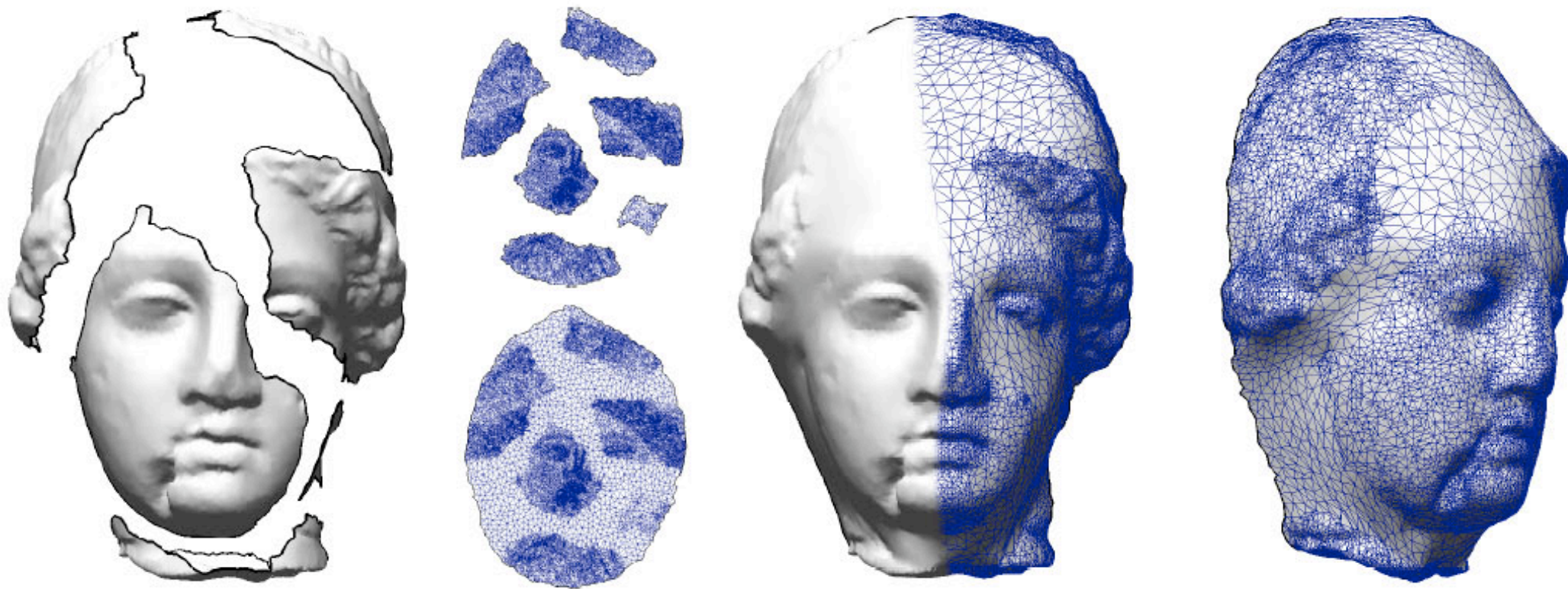
- Texture mapping



Lévy, Petitjean, Ray, and Maillot: *Least squares conformal maps for automatic texture atlas generation*, SIGGRAPH 2002

Motivation

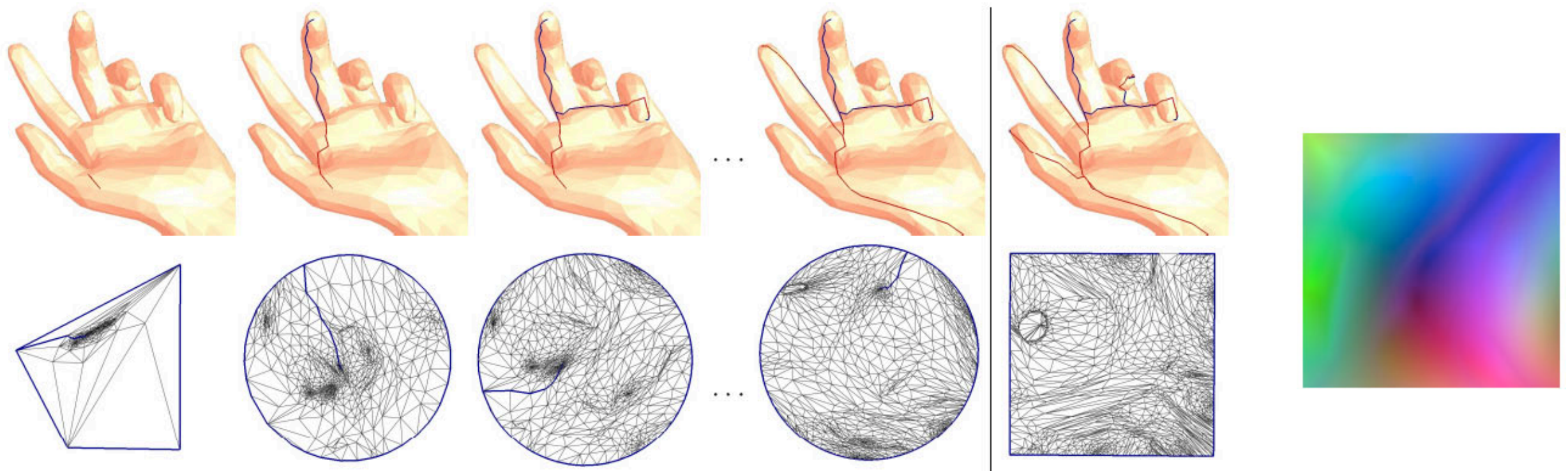
- Many operations are simpler on planar domain



Lévy: *Dual Domain Extrapolation*, SIGGRAPH 2003

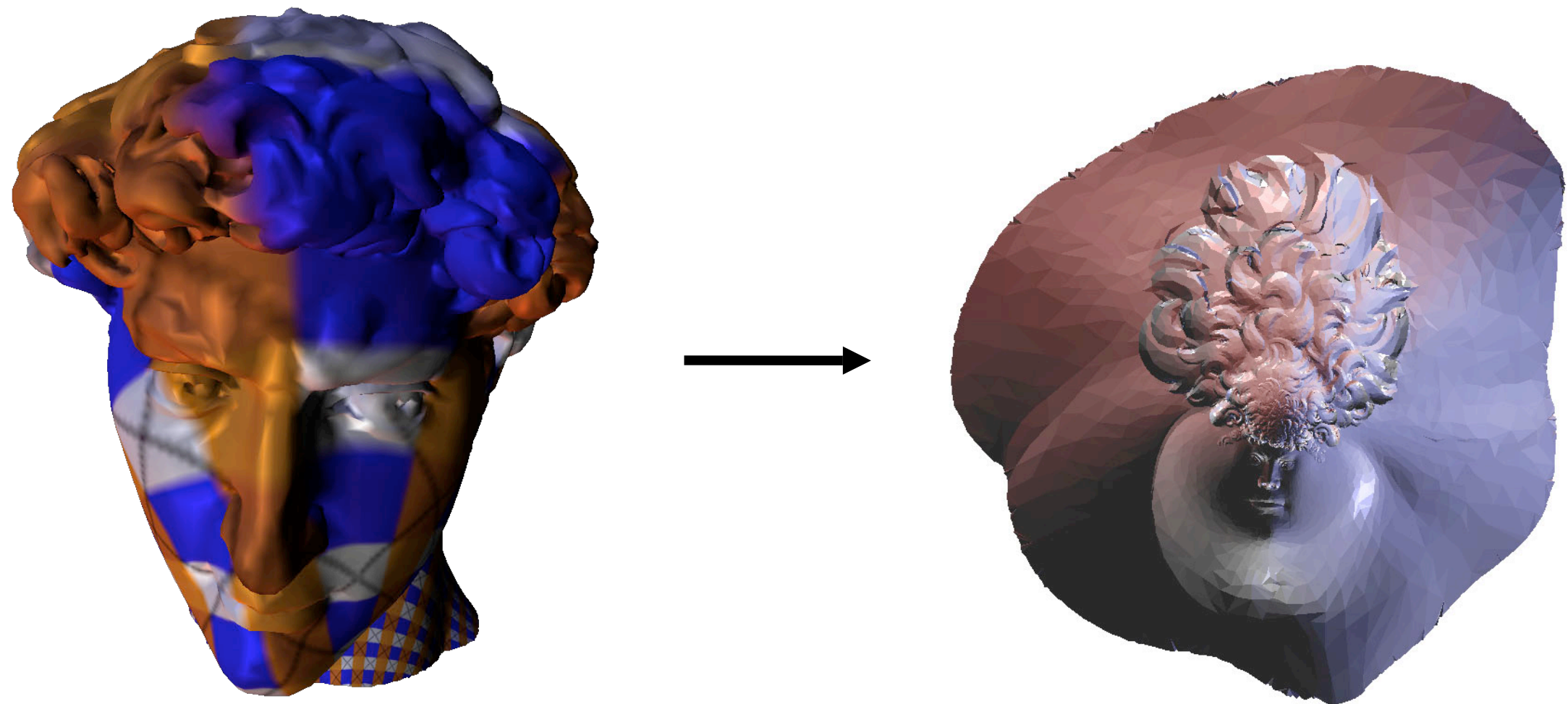
Motivation

- Exploit regular structure in domain

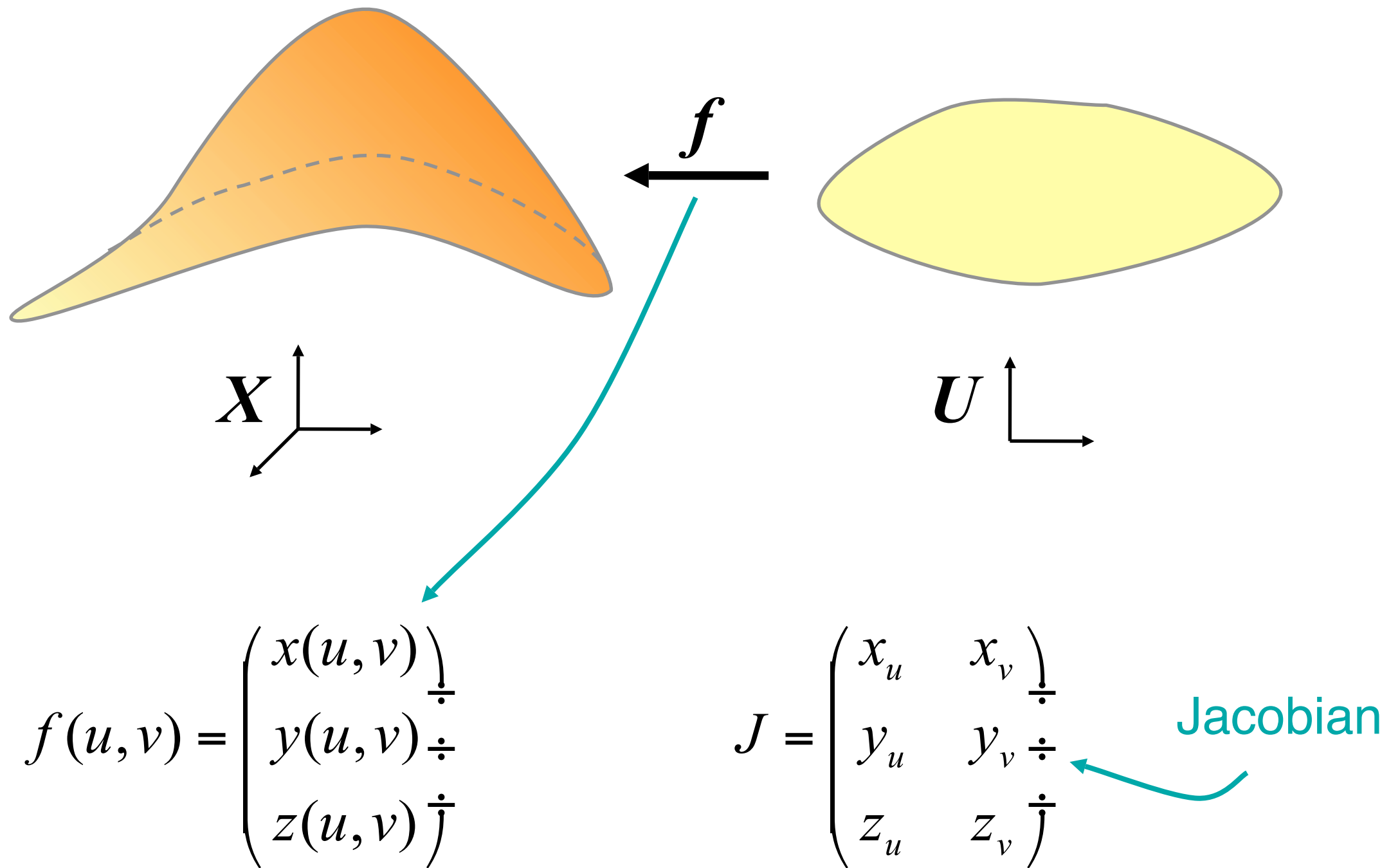


Gu, Gortler, Hoppe: *Geometry Images*, SIGGRAPH 2002

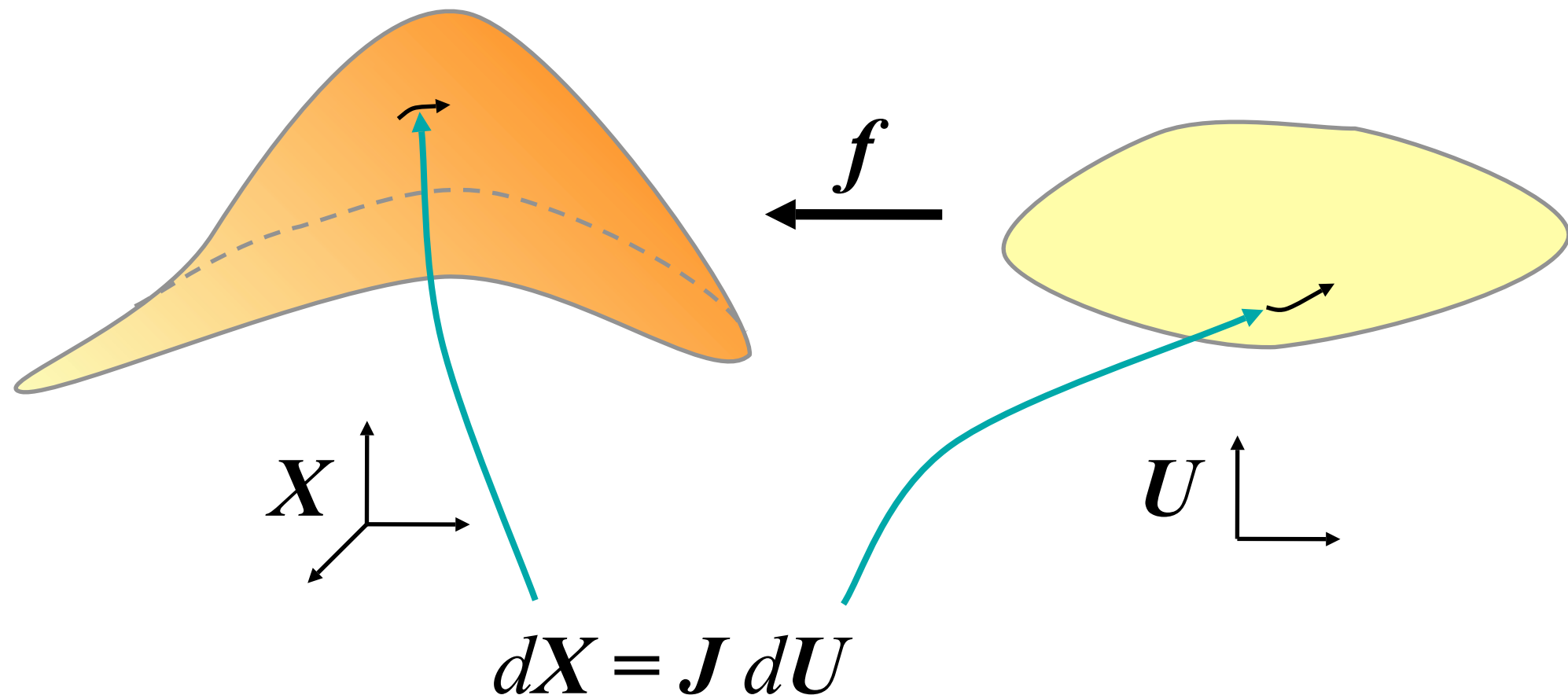
Surface Parameterization



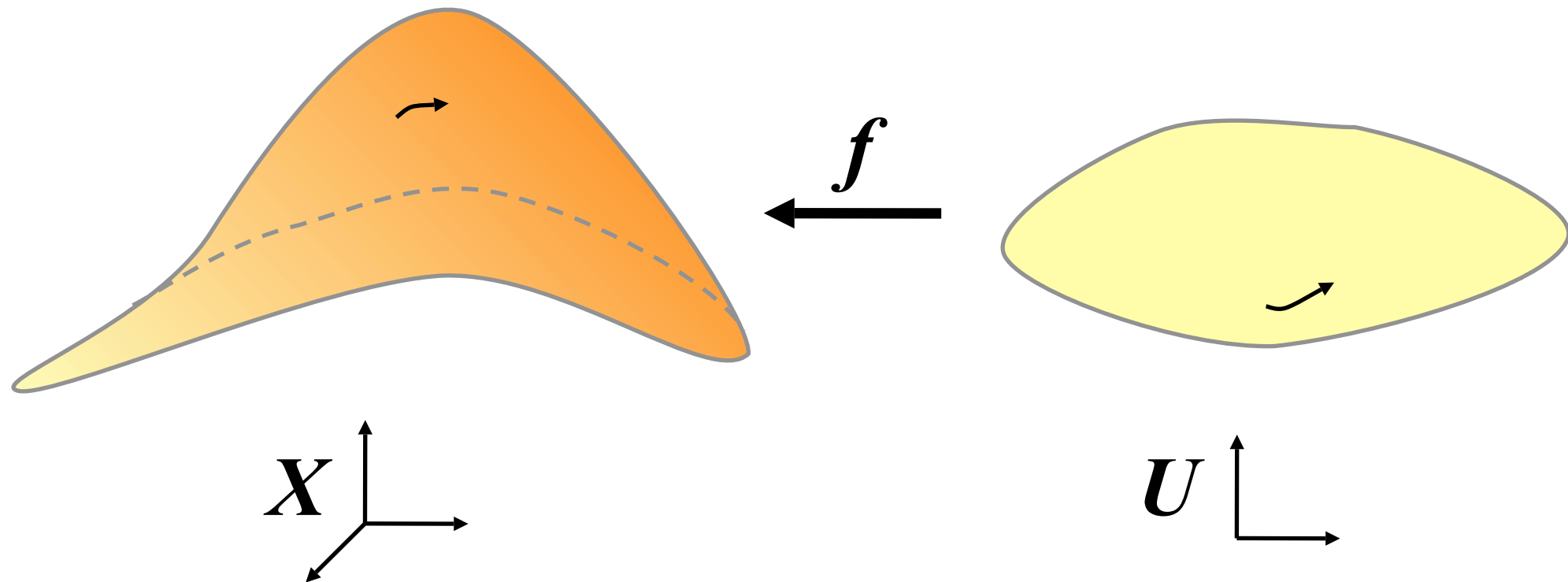
Surface Parameterization



Surface Parameterization



Surface Parameterization



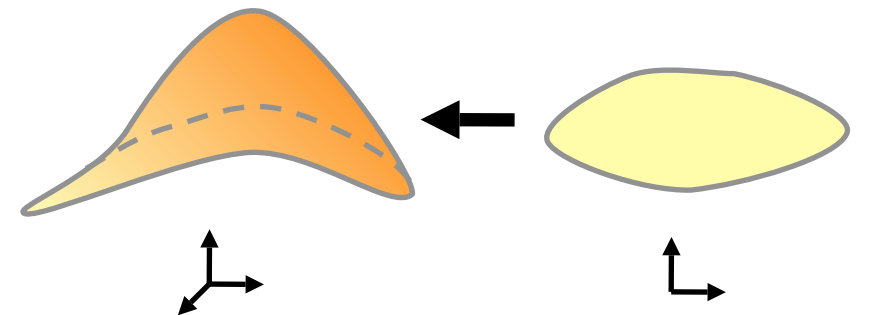
$$dX = J dU$$

$$\|dX\|^2 = dU \underbrace{J^T J}_{\text{First Fundamental Form}} dU$$

$$\mathbf{I} = \begin{pmatrix} x_u x_u & x_u x_v \\ x_u x_v & x_v x_v \end{pmatrix}$$

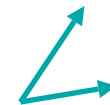
Characterization of Mappings

- By first fundamental form I
 - Eigenvalues $\lambda_{1,2}$ of I
 - Singular values $\sigma_{1,2}$ of J ($\sigma_i^2 = \lambda_i$)



- *Isometric*

- $I = Id$, $\lambda_1 = \lambda_2 = 1$



- *Conformal*

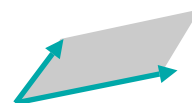
- $I = \mu Id$, $\lambda_1 / \lambda_2 = 1$



angle preserving

- *Equiareal*

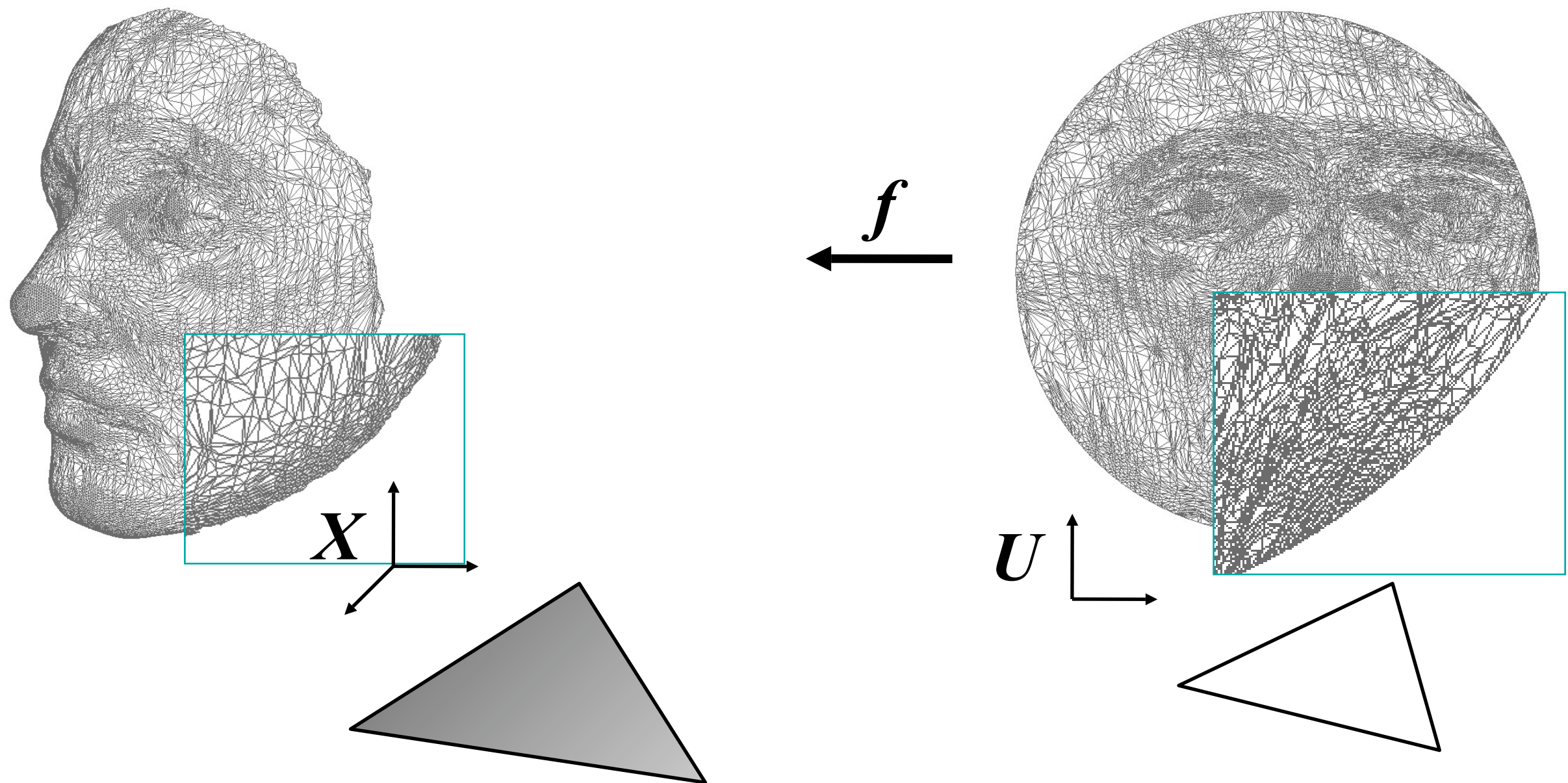
- $\det I = 1$, $\lambda_1 \lambda_2 = 1$



area preserving

Piecewise Linear Maps

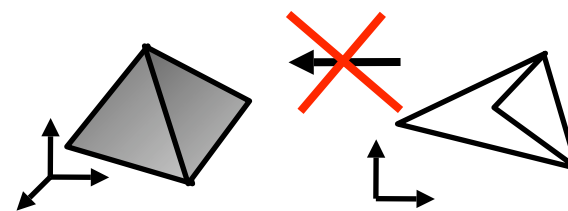
- Mapping = 2D mesh with same connectivity



Objectives

- Isometric maps are rare
- Minimize distortion w.r.t. a certain measure

- Validity (bijective map)



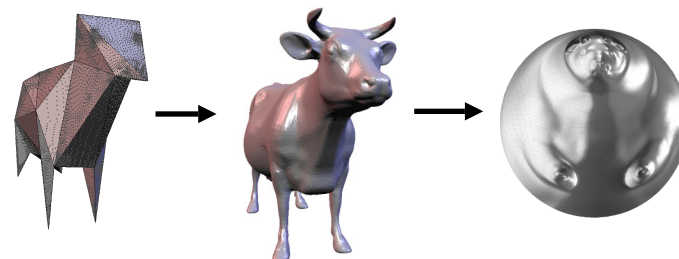
triangle flip

- Boundary



fixed / free?

- Domain



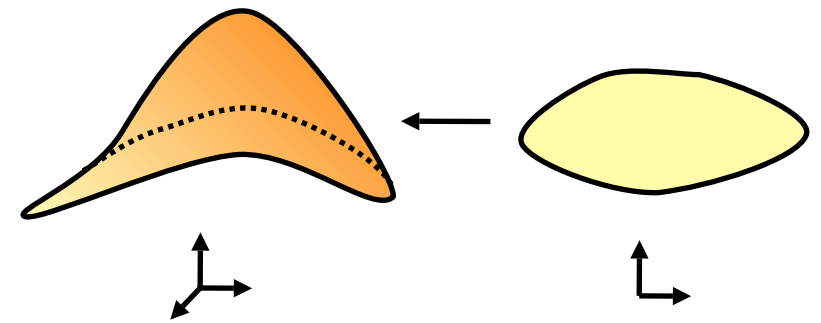
e.g., spherical

- Numerical solution

linear / non-linear?

Discrete Harmonic Maps

- f is *harmonic* if $\Delta f = 0$
- Solve Laplace equation



$$\begin{cases} \Delta u = 0 \\ \Delta v = 0 \\ (u, v)|_{\partial\Omega} = (u_0, v_0) \end{cases}$$

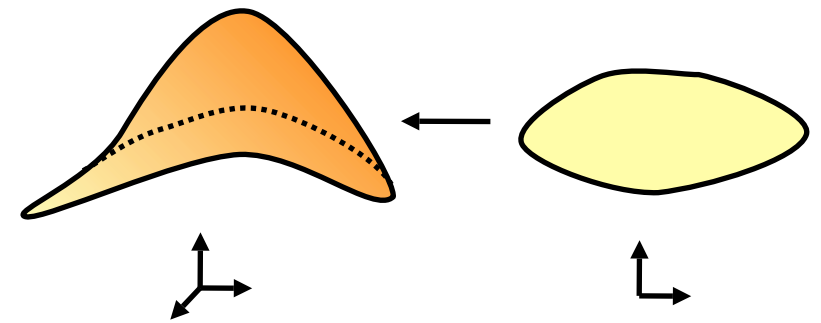
u and v are *harmonic*

Dirichlet boundary conditions

- In 3D: "fix planar boundary and smooth"

Discrete Harmonic Maps

- f is *harmonic* if $\Delta f = 0$
- Solve Laplace equation
- Yields linear system (again)



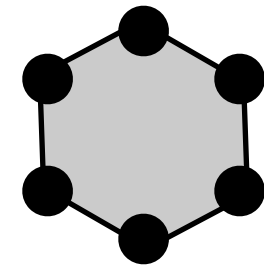
$$L(p_i) = \sum_{j \in N_i} w_{ij} (p_j - p_i) = 0 \quad \text{vertices } 1 \leq i \leq n$$

- *Convex combination maps*
 - *Normalization*
 - *Positivity*

$$\sum_{j \in N_i} w_{ij} = 1$$
$$w_{ij} > 0$$

Convex Combination Maps

- Every (interior) planar vertex is a *convex combination* of its neighbors
- Guarantees *validity* if boundary is mapped to a convex polygon (e.g., rectangle, circle)
- Weights
 - Uniform (*barycentric mapping*)
 - Shape preserving [Floater 1997]
 - Mean Value Coordinates [Floater 2003]
 - Use mean value property of harmonic functions



Reproduction of
planar meshes

Conformal Maps

- Planar *conformal mappings* $f(x, y) = \begin{pmatrix} u(x, y) \\ v(x, y) \end{pmatrix}$ satisfy the *Cauchy-Riemann conditions*

$$\frac{\partial u(x, y)}{\partial x} = \frac{\partial v(x, y)}{\partial y} \quad \text{and} \quad \frac{\partial u(x, y)}{\partial y} = -\frac{\partial v(x, y)}{\partial x}$$

Conformal Maps

- Planar *conformal mappings* $f(x, y) = \begin{pmatrix} u(x, y) \\ v(x, y) \end{pmatrix}$ satisfy the *Cauchy-Riemann conditions*

$$u_x = v_y \quad \text{and} \quad u_y = -v_x$$

- Differentiating once more by x and y yields

$$u_{xx} = v_{xy} \quad \text{and} \quad u_{yy} = -v_{xy} \quad \Rightarrow \quad u_{xx} + u_{yy} = \Delta u = 0$$

and similar $\Delta v = 0$

- conformal \Rightarrow harmonic

Discrete Conformal Maps

- Planar *conformal mappings* $f(x, y) = \begin{pmatrix} u(x, y) \\ v(x, y) \end{pmatrix}$ satisfy the *Cauchy-Riemann conditions*

$$u_x = v_y \quad \text{and} \quad u_y = -v_x$$

- *In general, there are no conformal mappings for piecewise linear functions!*

Discrete Conformal Maps

- Planar *conformal mappings* $f(x, y) = \begin{pmatrix} u(x, y) \\ v(x, y) \end{pmatrix}$ satisfy the *Cauchy-Riemann conditions*

$$u_x = v_y \quad \text{and} \quad u_y = -v_x$$

- Conformal energy (*per triangle* T)

$$E_T = (u_x - v_y)^2 + (u_y + v_x)^2$$

- Minimize $\sum_{T \in \mathcal{T}} E_T A_T \rightarrow \min$

Discrete Conformal Maps

- Least-squares conformal maps [Lévy et al. 2002]

$$\sum_{T \in \mathcal{T}} E_T A_T \rightarrow \min \quad \text{where} \quad E_T = (u_x - v_y)^2 + (u_y + v_x)^2$$

- Satisfy Cauchy-Riemann conditions in *least-squares* sense
- Leads to solution of linear system
- *Alternative formulation leads to same solution...*

Discrete Conformal Maps

- Same solution is obtained for

$$\Delta_S u = 0$$

cotangent weights

$$\Delta_S v = 0$$

$$n \times \nabla u \big|_{\partial\Omega} = c$$

Neumann boundary conditions

$$n \times \nabla v \big|_{\partial\Omega} = c$$

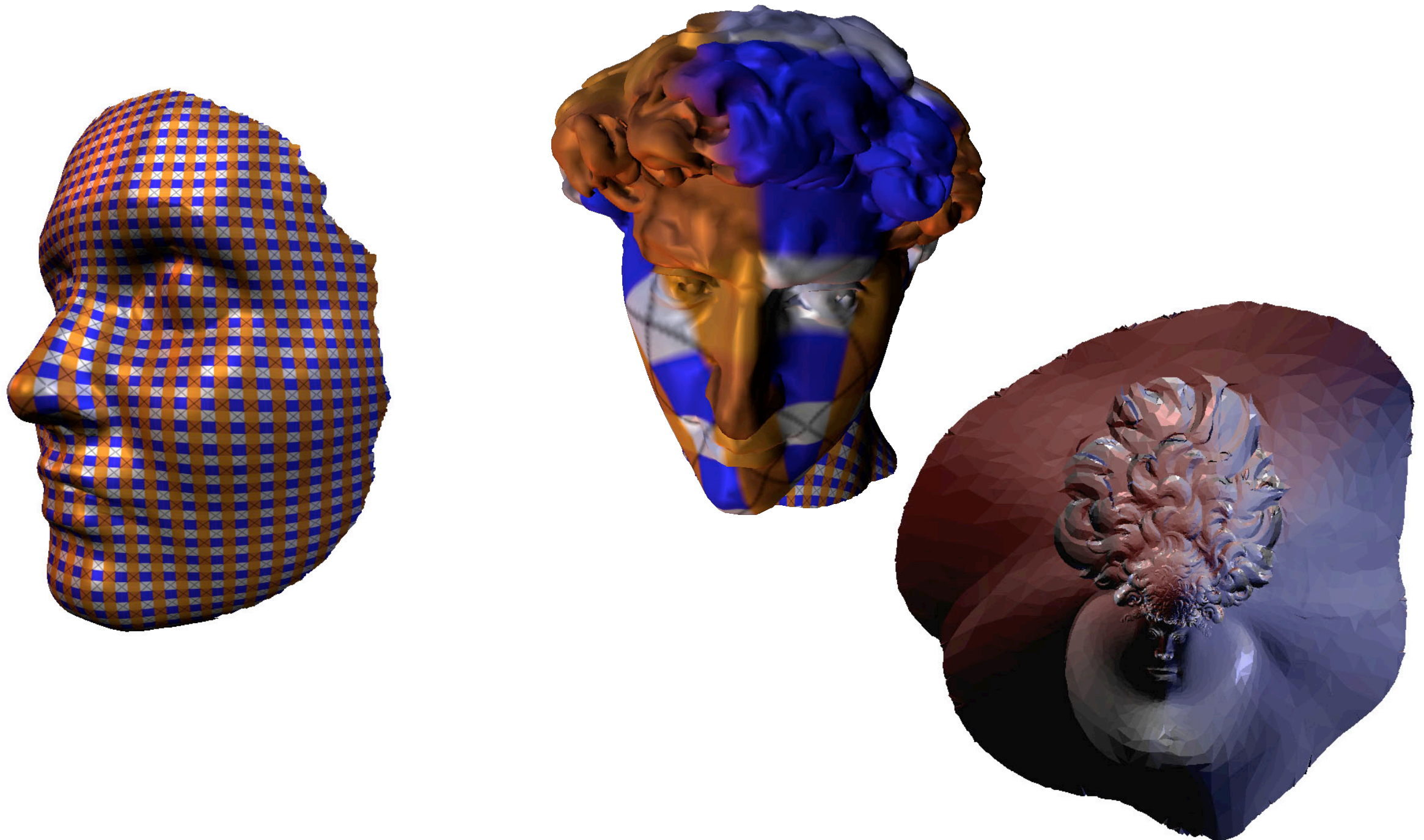
$$(u, v)_{|\partial\Omega_0} = (u_0, v_0)$$

+ fixed vertices

Discrete Conformal Maps

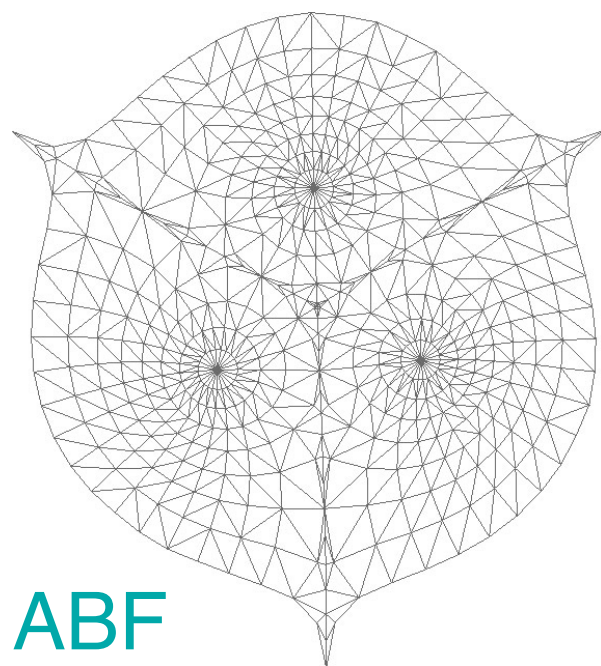
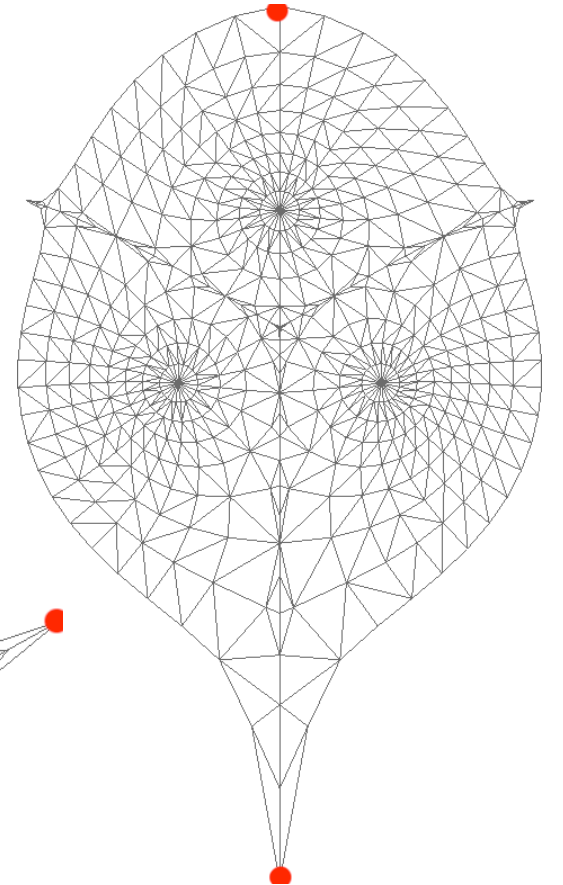
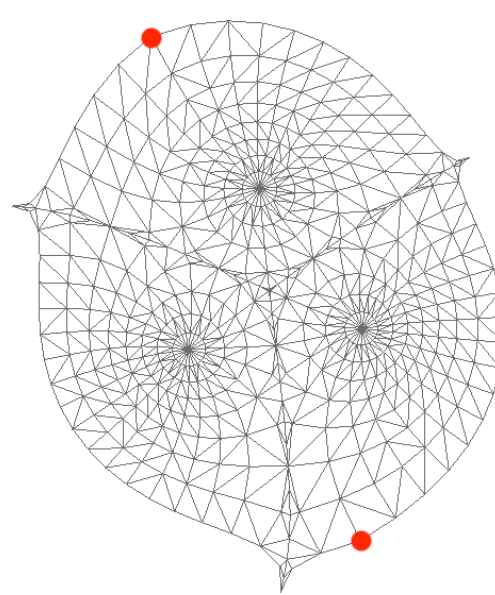
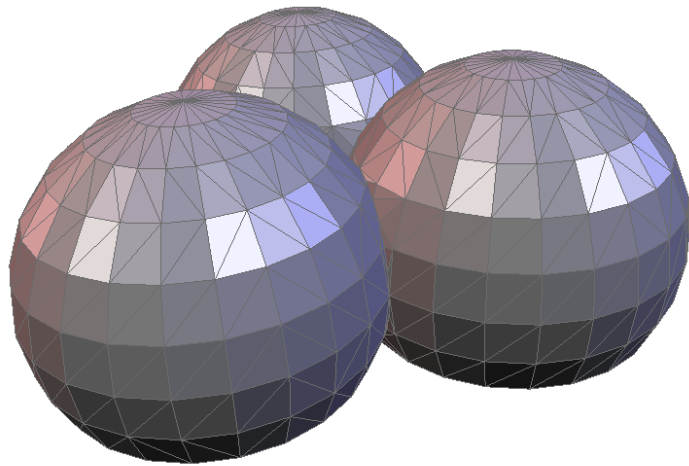
[Desbrun et al. 2002]

Discrete Conformal Maps

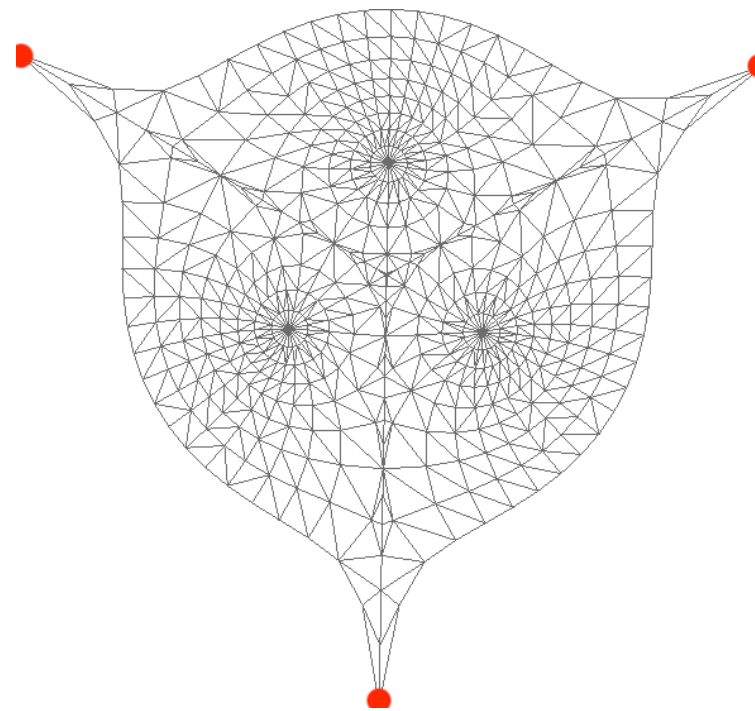


Discrete Conformal Maps

- Free boundary depends on choice of *fixed* vertices (>1)



ABF



Angle Based Flattening [Sheffer&de Sturler 2000]

- Preserve angles \Rightarrow specify problem in angles

- Constraints

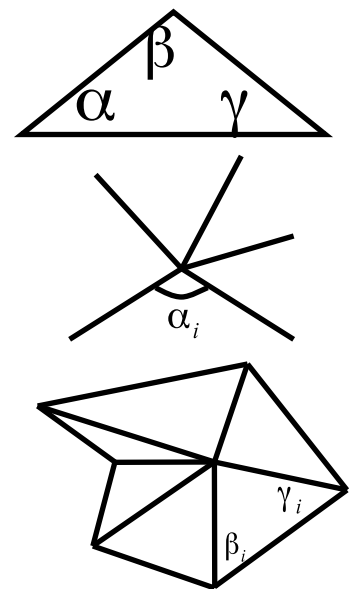
- triangle
- Internal vertex
- Wheel consistency

$$\alpha + \beta + \gamma - \pi = 0$$

$$\sum_i \alpha_i - 2\pi = 0$$

$$\prod_i \sin(\beta_i) - \prod_i \sin(\gamma_i) = 0$$

ensure validity



- Objective function

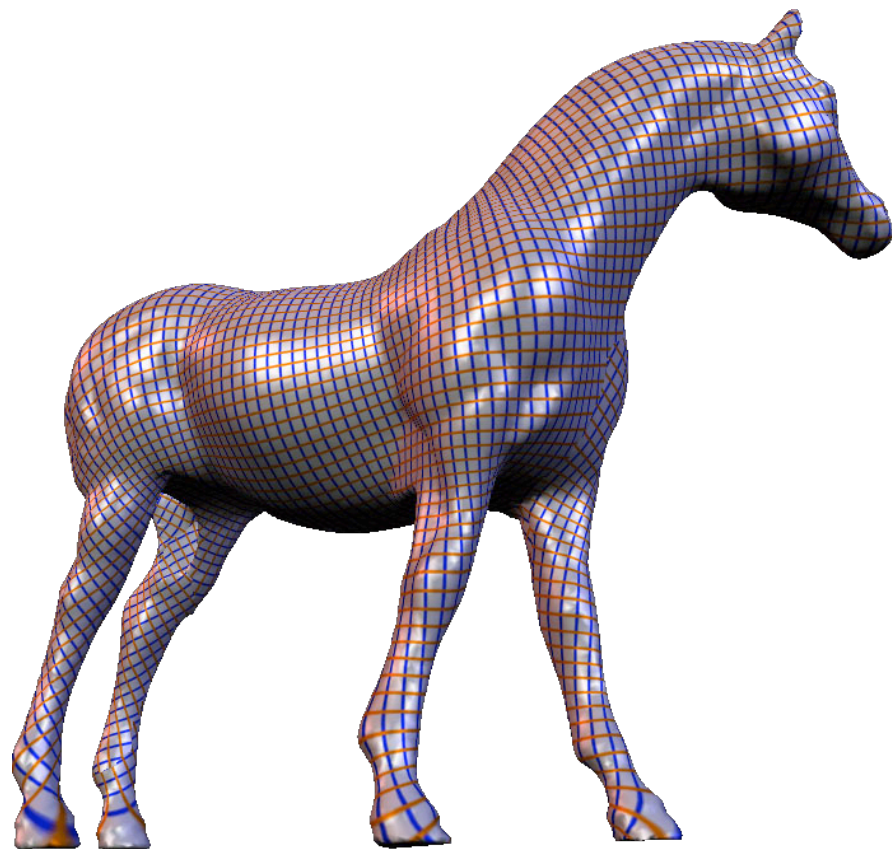
$$f(x) = \sum_{i=1}^N w_i (\alpha_i - \alpha_i^*)^2$$

preserve angles 2D ~3D

"optimal" angles (uniform scaling)

Angle Based Flattening

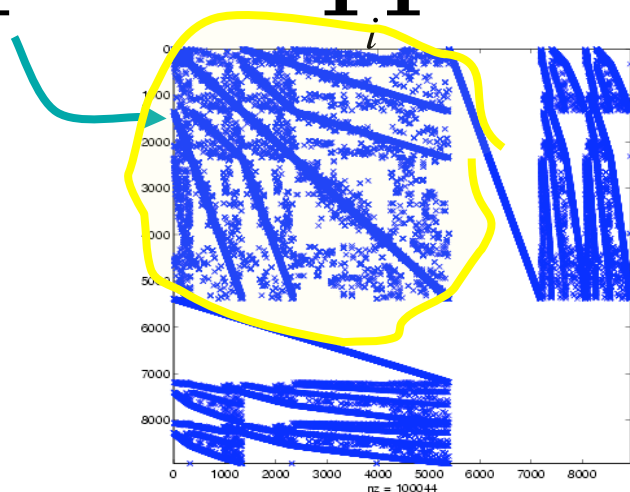
- Free boundary
- Validity: no local self-intersections
- Non-linear optimization



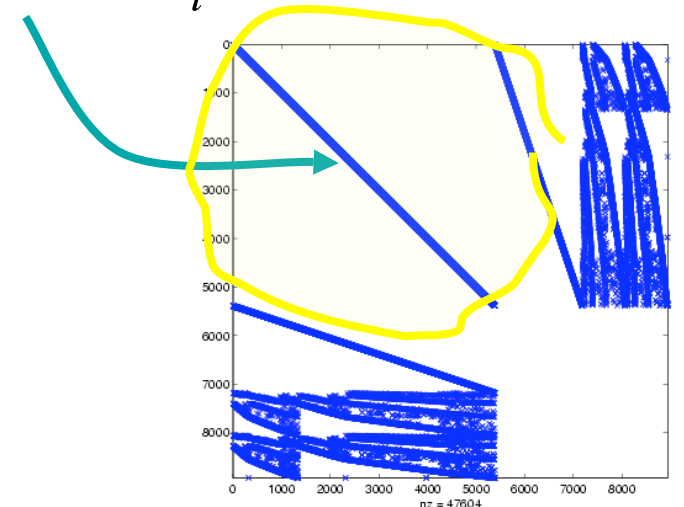
Angle Based Flattening

- Free boundary
- Non-linear optimization
 - Newton iteration
 - Solve linear system in every step

$$\prod_i \sin(\alpha_i) - \prod_i \sin(\beta_i) = 0$$

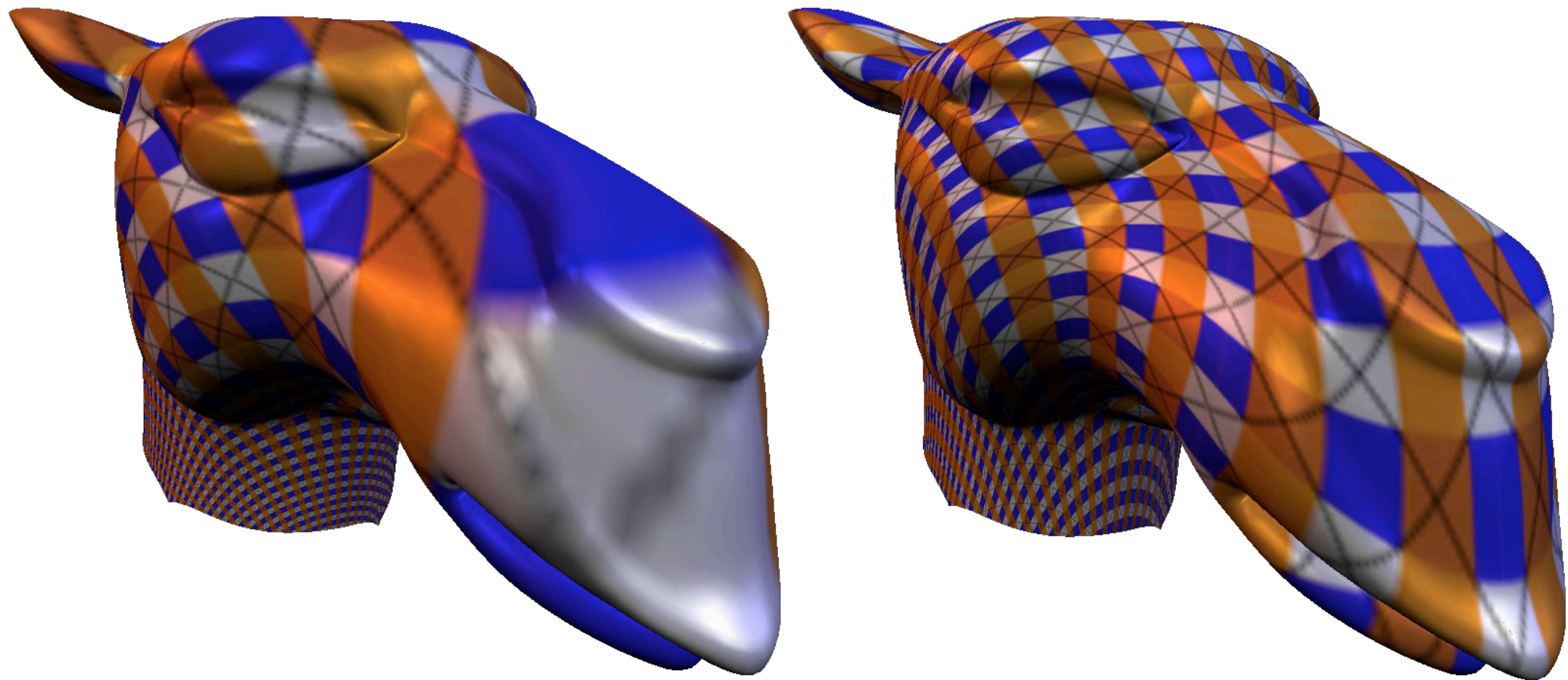


$$\prod_i \log \sin(\alpha_i) - \prod_i \log \sin(\beta_i) = 0$$



[Zayer et al. 2005]

And how about area distortion?



Reducing Area Distortion

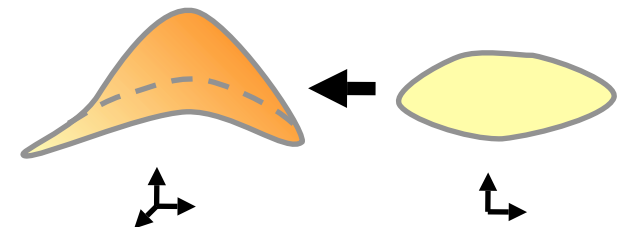
- Energy minimization based on

- MIPS [Hormann & Greiner 2000]

- *modification* [Degener et al. 2003]

- "Stretch" [Sander et al. 2001]

- *modification* [Sorkine et al. 2002]



$$\|J\|_F \|J^{-1}\|_F = \frac{\sigma_1}{\sigma_2} + \frac{\sigma_2}{\sigma_1}$$

$$\det J + \frac{1}{\det J} = \sigma_1 \sigma_2 + \frac{1}{\sigma_1 \sigma_2}$$

$$\|J\|_F = \sqrt{\sigma_1 + \sigma_2} \quad \text{or} \quad \|J\|_\infty = \sigma_1$$

$$\max \left\{ \sigma_1, \frac{1}{\sigma_2} \right\}$$

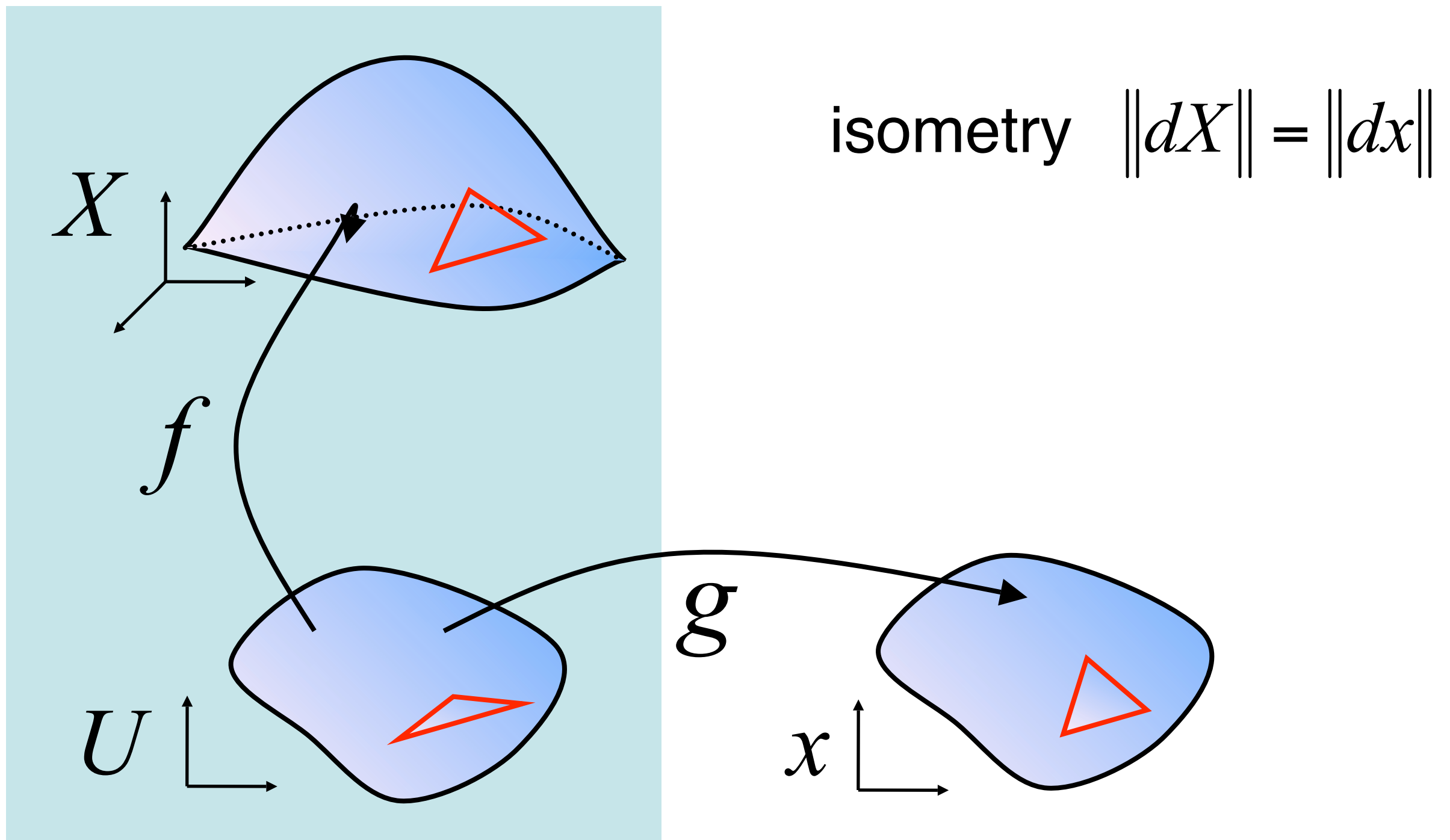
Non-Linear Methods

- Free boundary
- Direct control over distortion
- No convergence guarantees
- May get stuck in local minima
- May not be suitable for large problems
- May need feasible point as initial guess
- May require hierarchical optimization even for moderately sized data sets

Linear Methods

- Efficient solution of a sparse linear system
- Guaranteed convergence
- Fixed convex boundary
- May suffer from area distortion for complex meshes
- *An alternative approach to reducing area distortion...*
 - *How accurately can we reproduce a surface on the plane?*
 - *How do we characterize the mapping?*

Reducing Area Distortion



Reducing Area Distortion

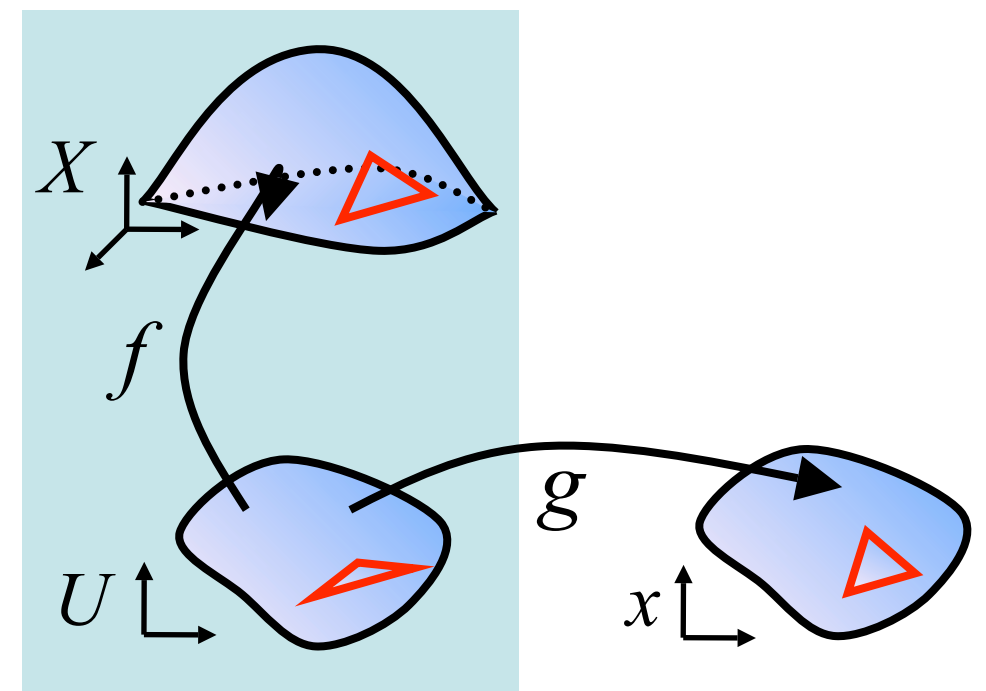
- Quasi-harmonic maps [Zayer et al. 2005]

$$\int C \nabla g \times \nabla g \, d\mathbb{R} \min$$

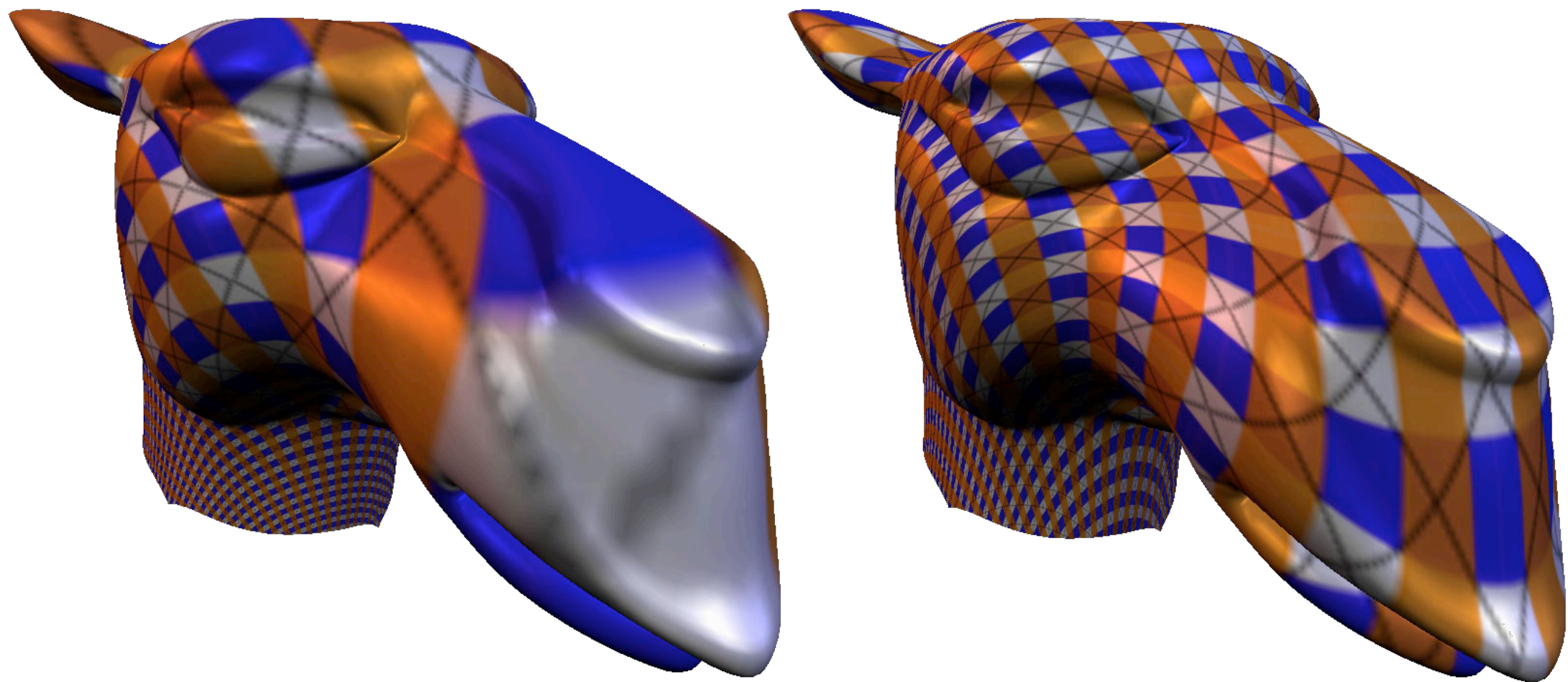
$$\operatorname{div}(C \nabla g) = 0$$

estimate from f

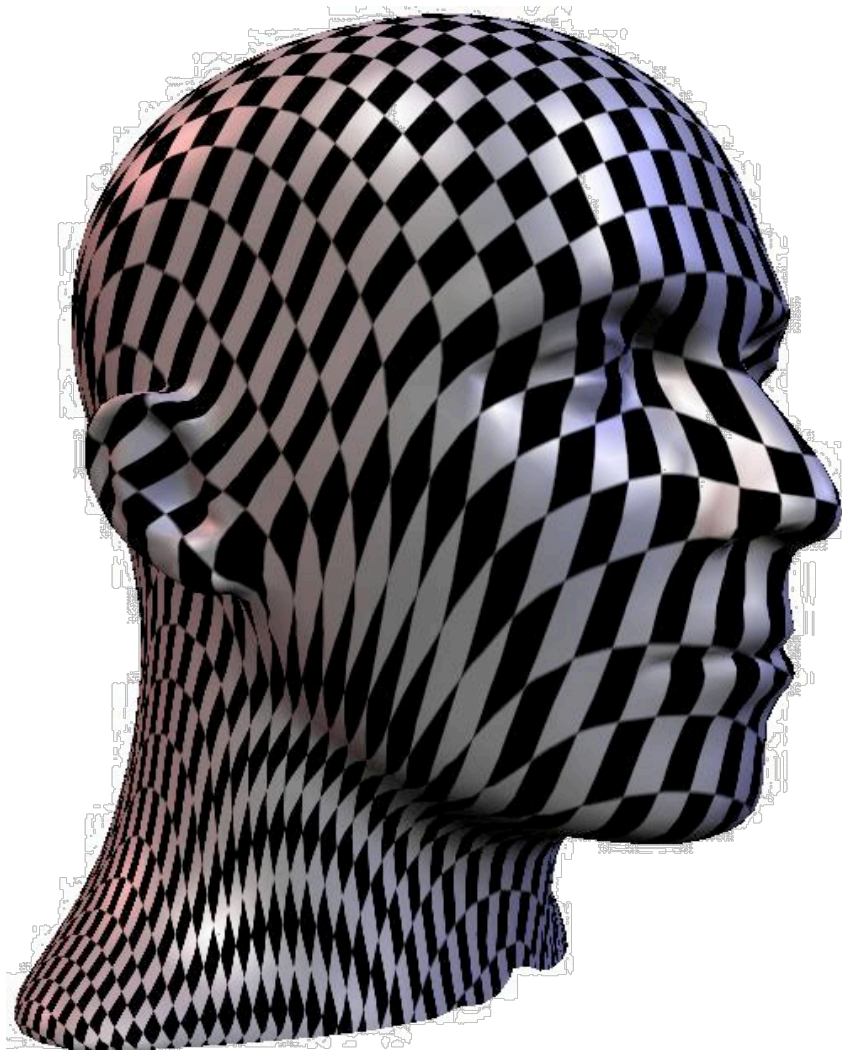
- Iterate (*few iterations*)
 - Determine tensor C from f
 - Solve for g



Examples



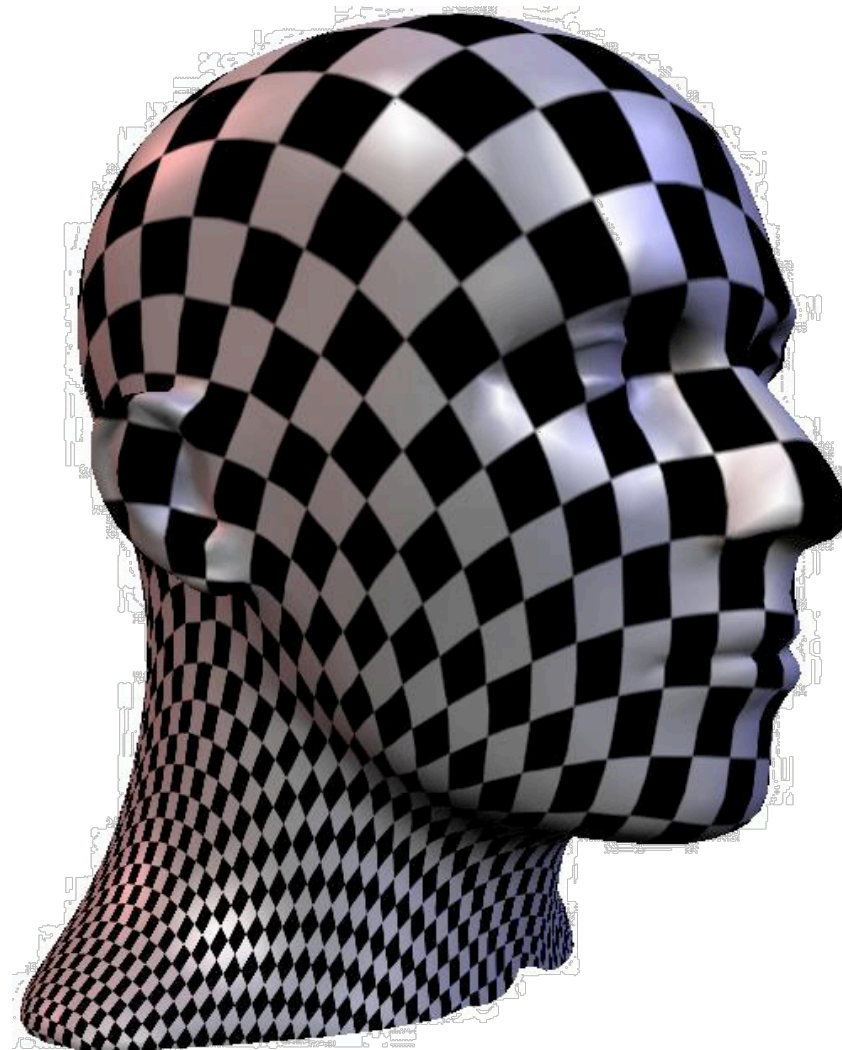
Examples



$$\sqrt{\sigma_1 + \sigma_2} \rightarrow \min$$

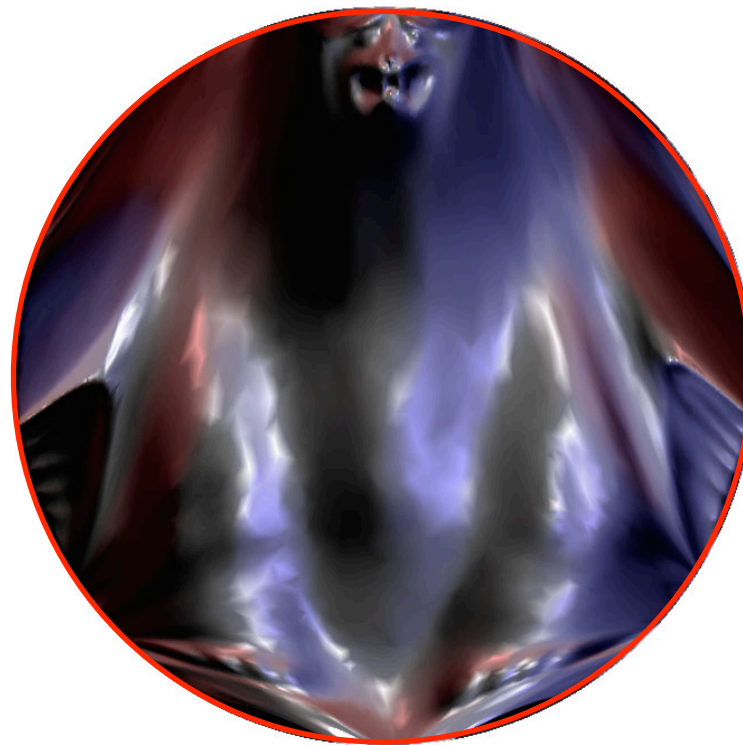
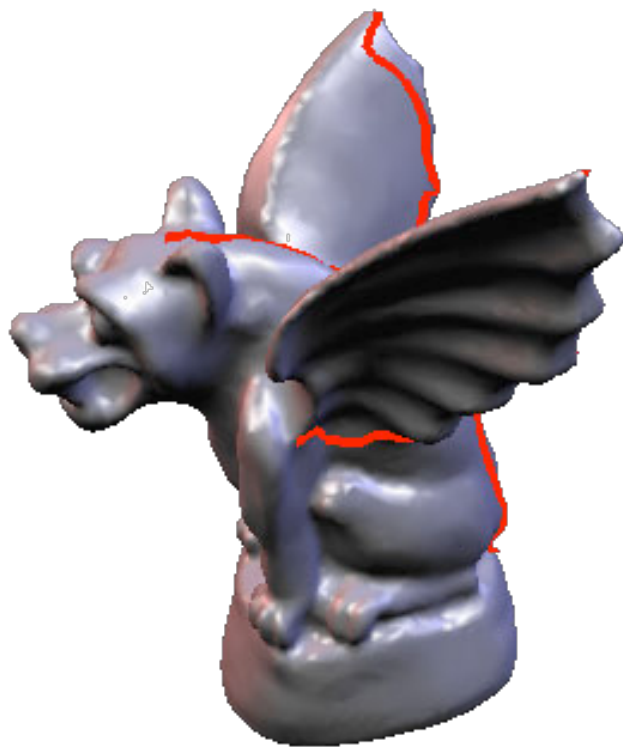
Stretch metric minimization

Using [Yoshizawa et. al 2004]



Reducing Area Distortion

- Introduce cuts \Rightarrow area distortion vs. continuity
- Often cuts are unavoidable (e.g., open sphere)



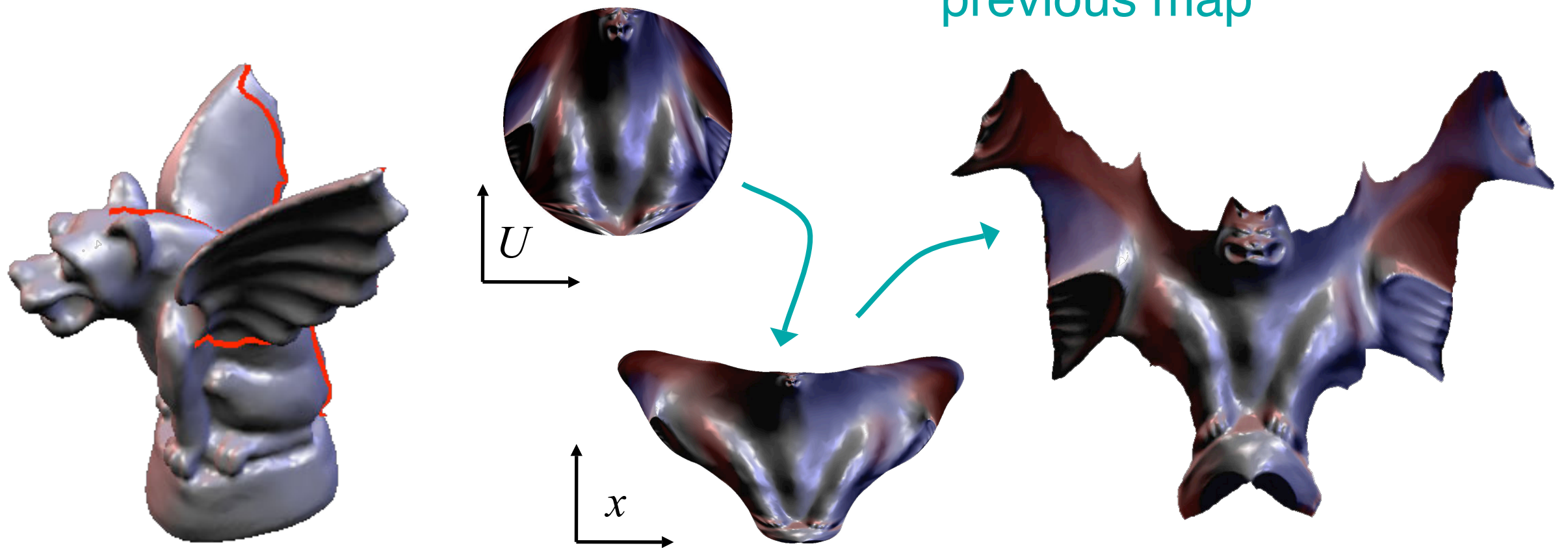
Treatment of boundary
is important!

Reducing Area Distortion

- Solve Poisson^{*} system [Zayer et al. 2005]

$$\Delta x = \operatorname{div} \nabla U'$$

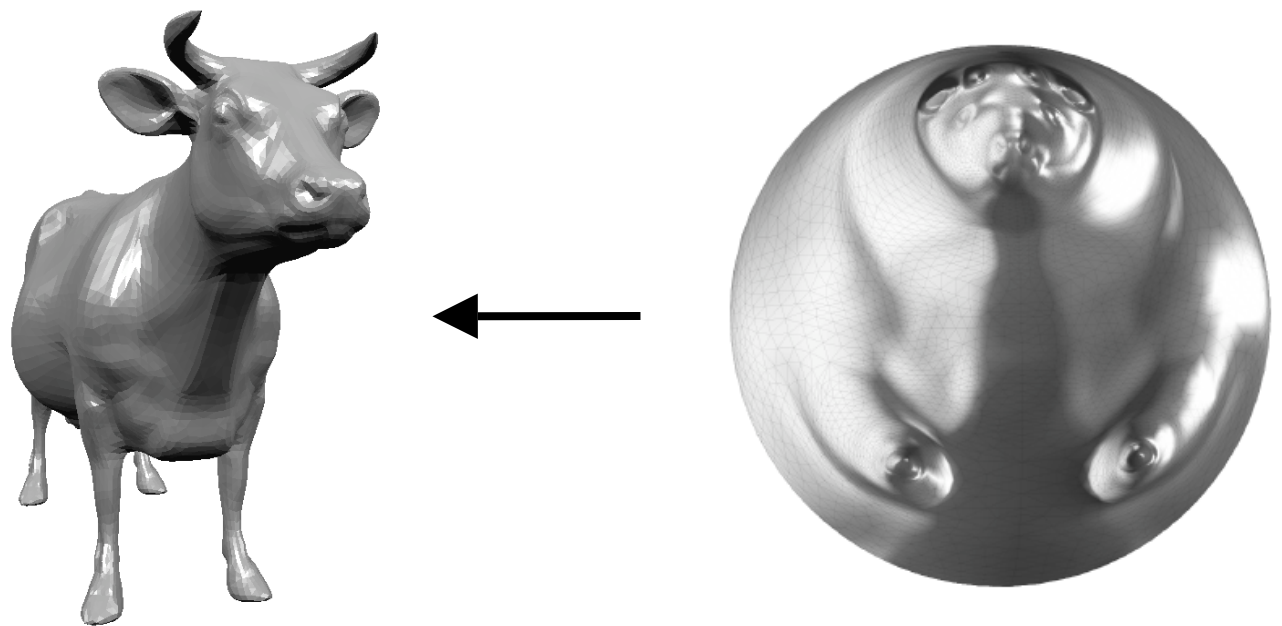
← estimate from previous map



* Similar setting used in *mesh editing*

Spherical Parameterization

- Sphere is natural domain for genus-0 surfaces
- Additional constraint $\|U\|^2 = 1$



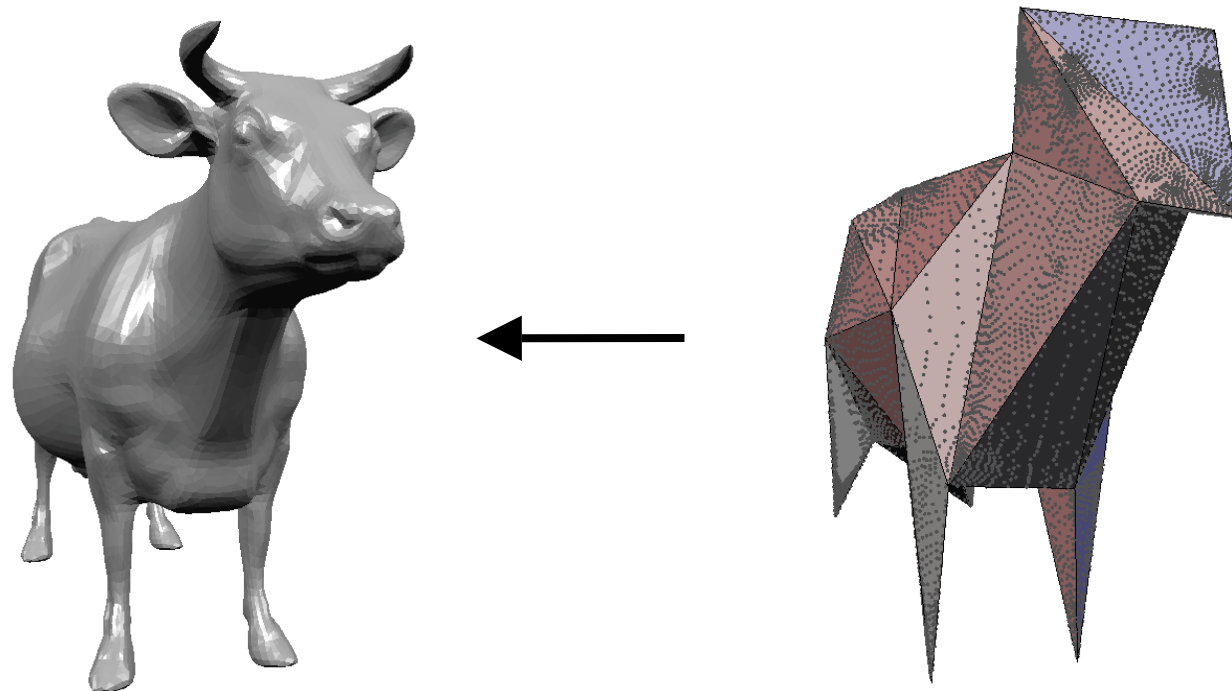
- Naïve approach
 - Laplacian smoothing and back-projection
 - Obtain minimum for degenerate configuration

Spherical Parameterization

- (Tangential) Laplacian Smoothing and back-projection
 - Minimum energy is obtained for *degenerate* solution
- Theoretical guarantees are expensive
 - [Gotsman et al. 2003]
- A compromise?!
 - Stereographic projection
 - Smoothing in curvilinear coordinates

Arbitrary Topology

- Piecewise linear domains
 - *Base mesh* obtained by *mesh decimation*
 - Piecewise maps
 - Smoothness



Literature

- Floater & Hormann: *Surface parameterization: a tutorial and survey*, Springer, 2005
- Lévy, Petitjean, Ray, and Maillot: *Least squares conformal maps for automatic texture atlas generation*, SIGGRAPH 2002
- Desbrun, Meyer, and Alliez: *Intrinsic parameterizations of surface meshes*, Eurographics 2002
- Sheffer & de Sturler: *Parameterization of faceted surfaces for meshing using angle based flattening*, Engineering with Computers, 2000.