


"Simple Linear Regression"

Landscape

- Types of Linear Reg.
- ① simple
- ④ multivariable
- ③ polynomial
- ② regularization

#Simple LR

1 i/p \rightarrow 1 o/p



$$y = mx + b$$

we can do it in 2 ways

using some
sort of
formulas

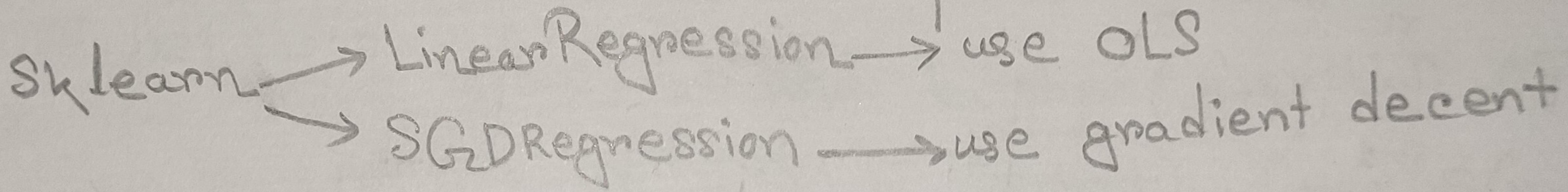
Closed form
solution

non-closed form
solution

• It solves a given problem
in terms of functions (sin, log), variable
constant and mathematical operation

• using OLS (Ordinary Least
square)
good when lower
dimension

• approximation technique
• Gradient Descent method
↓
easy to use in higher
dimension



"Linear Regression using OLS"

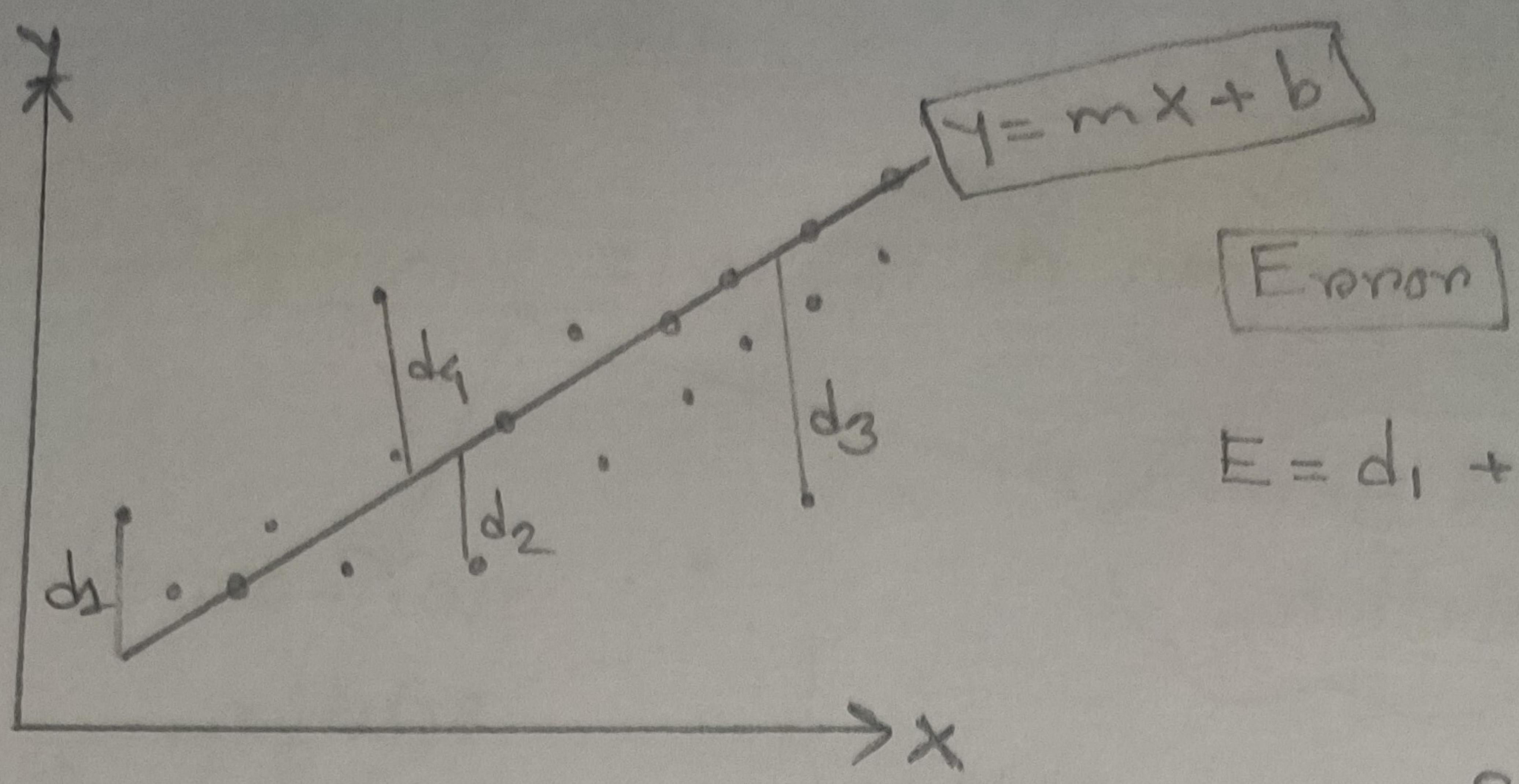
$$b = \bar{y} - m\bar{x}$$

$$m = \frac{\sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})}{\sum_{i=1}^n (x_i - \bar{x})^2}$$

\bar{y} → mean of target column.

\bar{x} → mean of input column

n → total point



$$E = d_1 + d_2 + d_3 + \dots \times$$

$$\times E = |d_1| + |d_2| + \dots$$

(R1) → want to penalize outlier

(R2) → doing differentiation of mode function is not easy

$$E = d_1^2 + d_2^2 + d_3^2 + \dots$$

$$E = \sum_{i=1}^n d_i^2$$

→ loss function

(L)

$$d = \hat{y}_i - \hat{y}_i$$

↑
predicted
actual

$$E = \sum_{i=1}^n (\hat{y}_i - y_i)^2$$

$$\hat{y}_i = mx_i + b$$

$$E(m, b) = \sum_{i=1}^n (y_i - mx_i - b)^2$$

→ now we need to minimize $E(m, b)$

$E(m, b) \rightarrow m, b$ is the tuning parameter we can tune it. Both m, b or individual m, b what's impact on E ?

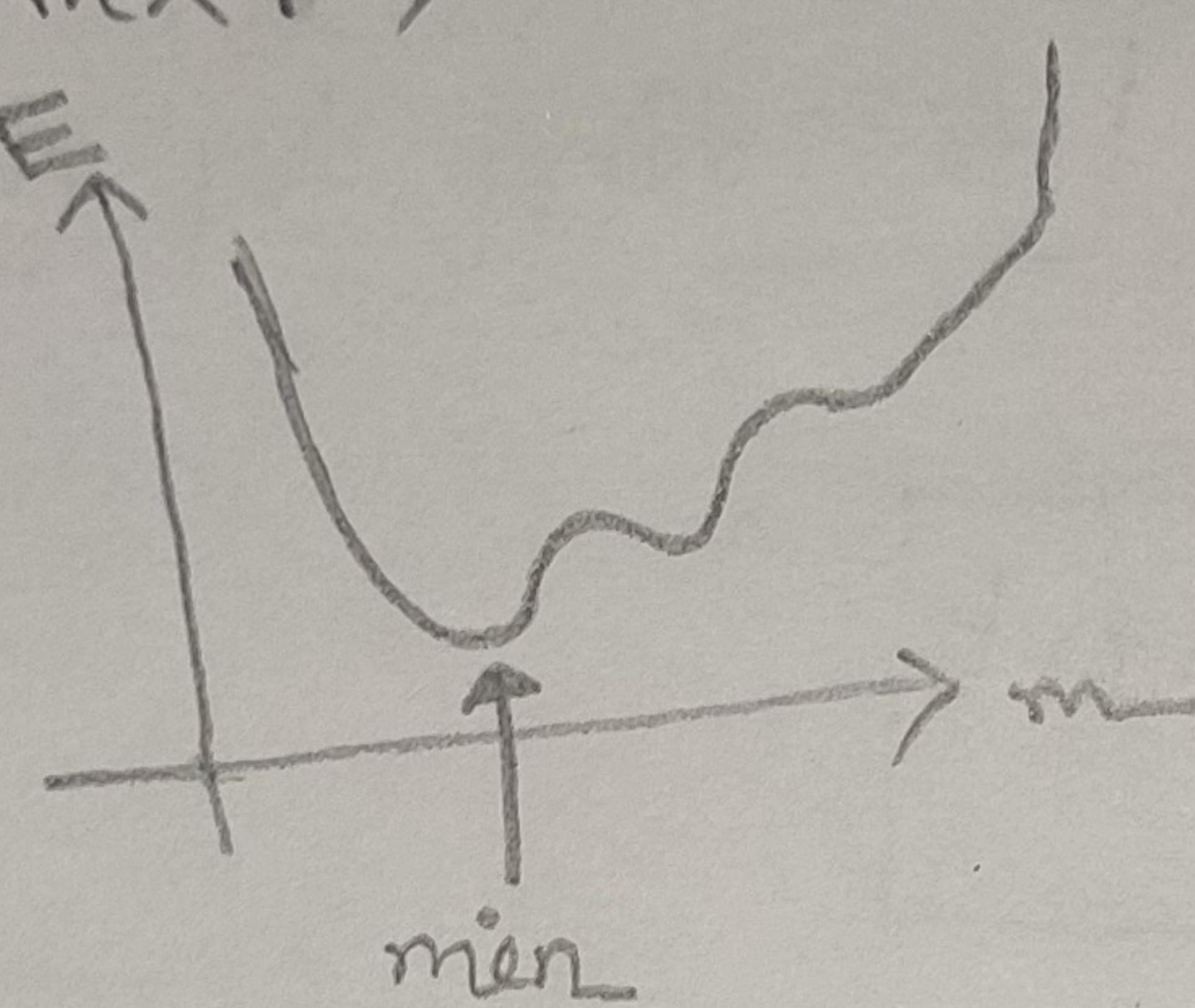
Impact of m only

let's $b = 0$

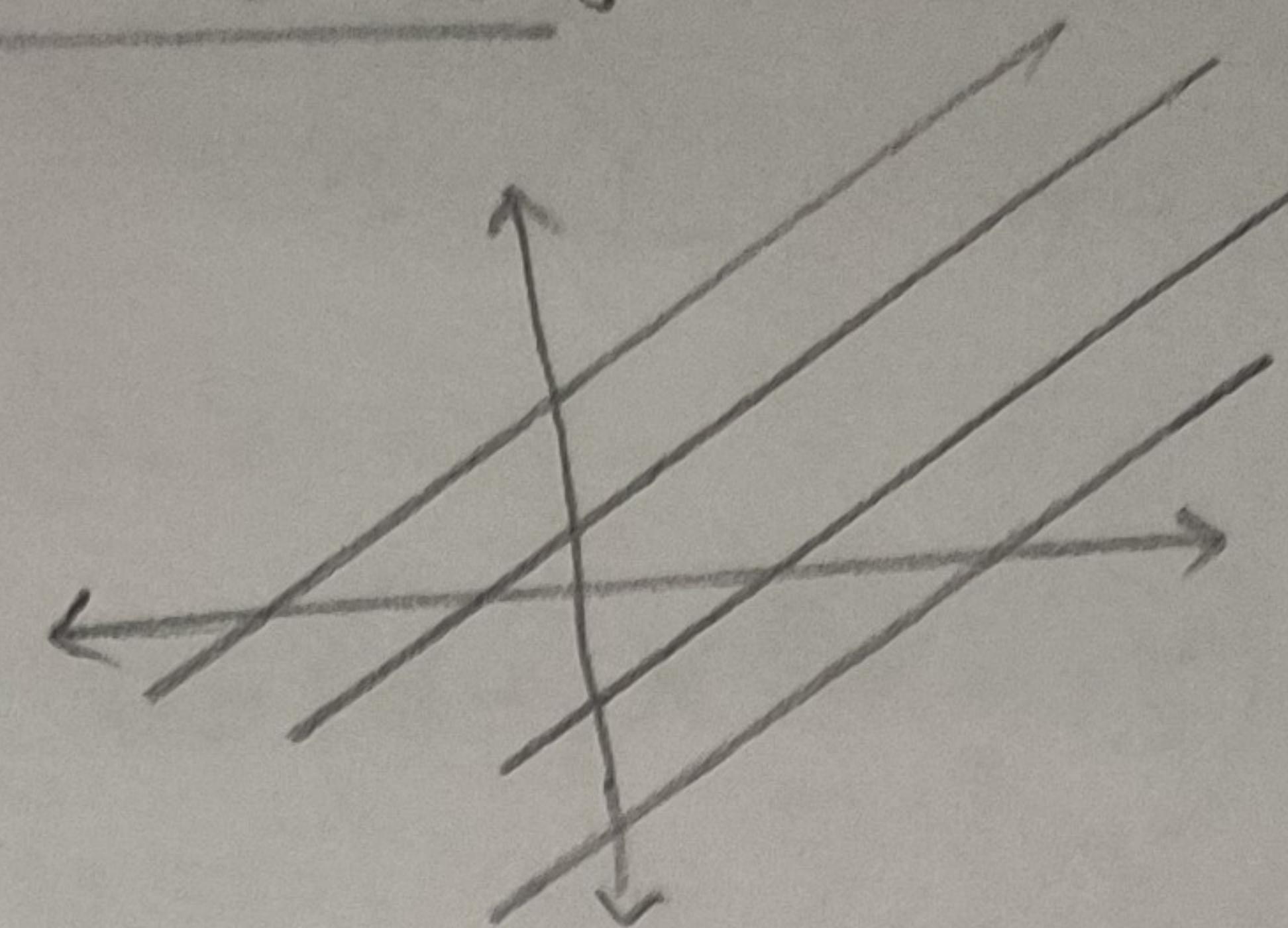


$$E(m) = \sum_{i=1}^n \left(\underbrace{y_i - mx_i}_a \right)^2$$

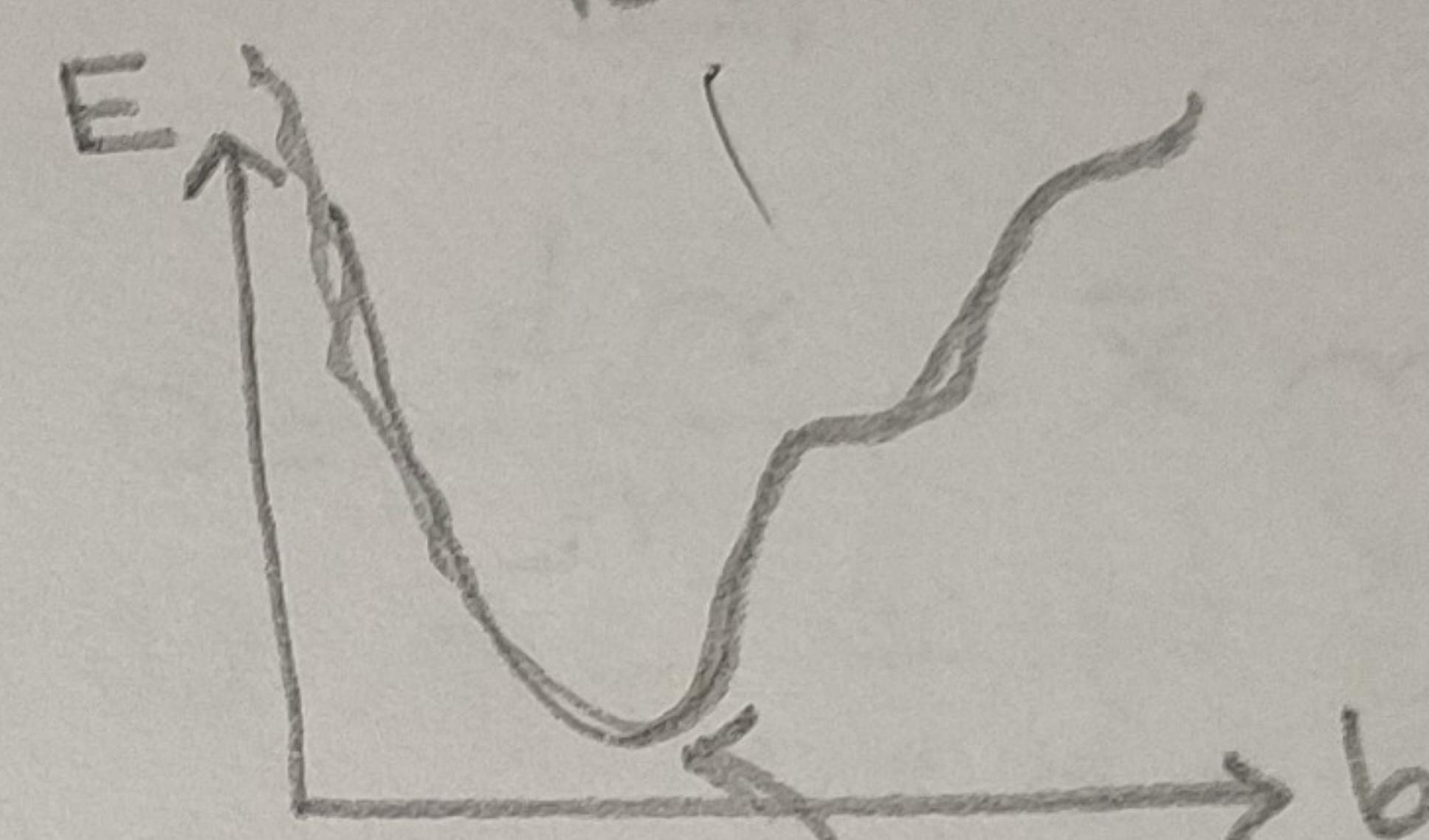
$$m \uparrow \Rightarrow mx \uparrow \Rightarrow a \uparrow \Rightarrow a^2 \uparrow$$



let $m = 1$; $\tan \theta = 1 \rightarrow \theta = 45^\circ$



any line which make $\theta = 45^\circ$ with x axis



If we tune both m and b then we will get a 3d plot. there will be point where $E(m,b)$ will be min

this point is call

Minima

since we have m and b

so both $\frac{\partial}{\partial m}$ and $\frac{\partial}{\partial b}$ will be 0

means 1st derivative will be 0

$$E(m,b) = \sum_{i=1}^n \left(y_i - mx_i - b \right)^2$$

$$\frac{\partial E}{\partial m} = 0$$

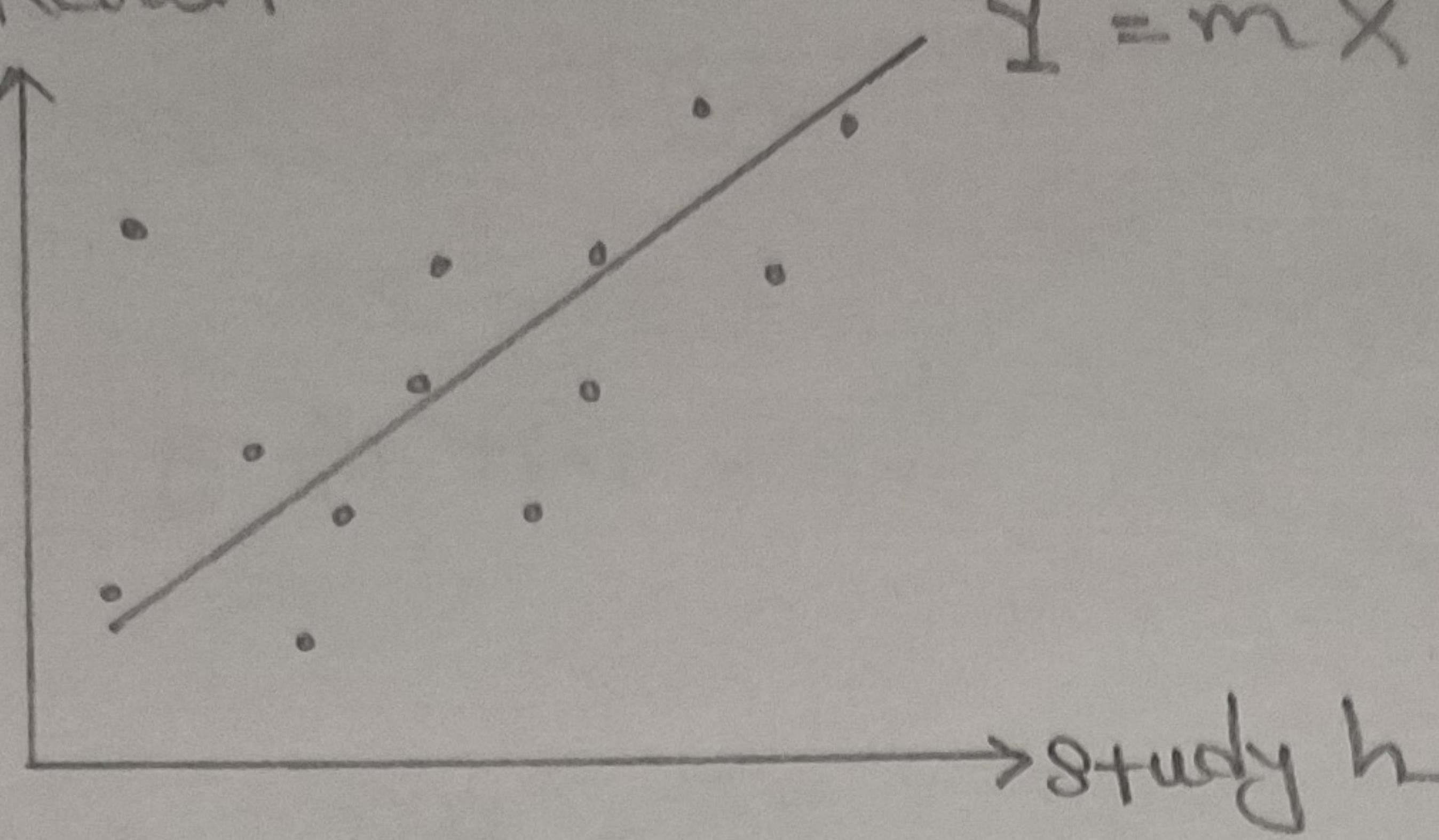
$$\frac{\partial E}{\partial b} = 0$$

$$\begin{aligned}
 & \Rightarrow \sum_{i=1}^n 2x_i \left(\bar{x}_i - mx_i - b \right) = 0 \\
 & \Rightarrow \sum_{i=1}^n 2 \left(\bar{x}_i - mx_i - b \right)^2 = 0 \\
 & \Rightarrow \sum_{i=1}^n \frac{\partial L}{\partial b} = \sum_{i=1}^n \bar{x}_i - mx_i = 0 \\
 & \Rightarrow \bar{x} - mx - b = 0 \quad \boxed{b = \bar{x} - mx} \\
 & \Rightarrow \sum_{i=1}^n \left(\bar{x}_i - mx_i - \bar{x} + mx \right)^2 = 0 \\
 & \Rightarrow \sum_{i=1}^n \left(\bar{x}_i - \bar{x} \right)^2 = \sum_{i=1}^n \left(x_i - \bar{x} \right)^2
 \end{aligned}$$

$$\begin{aligned}
 & \Rightarrow \sum_{i=1}^n \left(\bar{x}_i - \bar{x} \right) \left(x_i - \bar{x} \right) = \sum_{i=1}^n \left(x_i - \bar{x} \right)^2 \\
 & \Rightarrow \frac{\sum_{i=1}^n \left(\bar{x}_i - \bar{x} \right) \left(x_i - \bar{x} \right)}{\sum_{i=1}^n \left(x_i - \bar{x} \right)^2} = \frac{\sum_{i=1}^n \left(x_i - \bar{x} \right)^2}{\sum_{i=1}^n \left(x_i - \bar{x} \right)^2}
 \end{aligned}$$

"Simple Linear Regression using Gradient Descent"

Result



$$y = mx + b$$

\rightarrow study h

cost function

Error Function (MSE)

$$E(m, b) = \frac{1}{n} \sum_{i=1}^n (y_i - \hat{y}_i)^2$$

$$E(m, b) = \frac{1}{n} \sum \{(y_i - mx_i - b)\}^2$$

Mean square Error \rightarrow need to minimize this

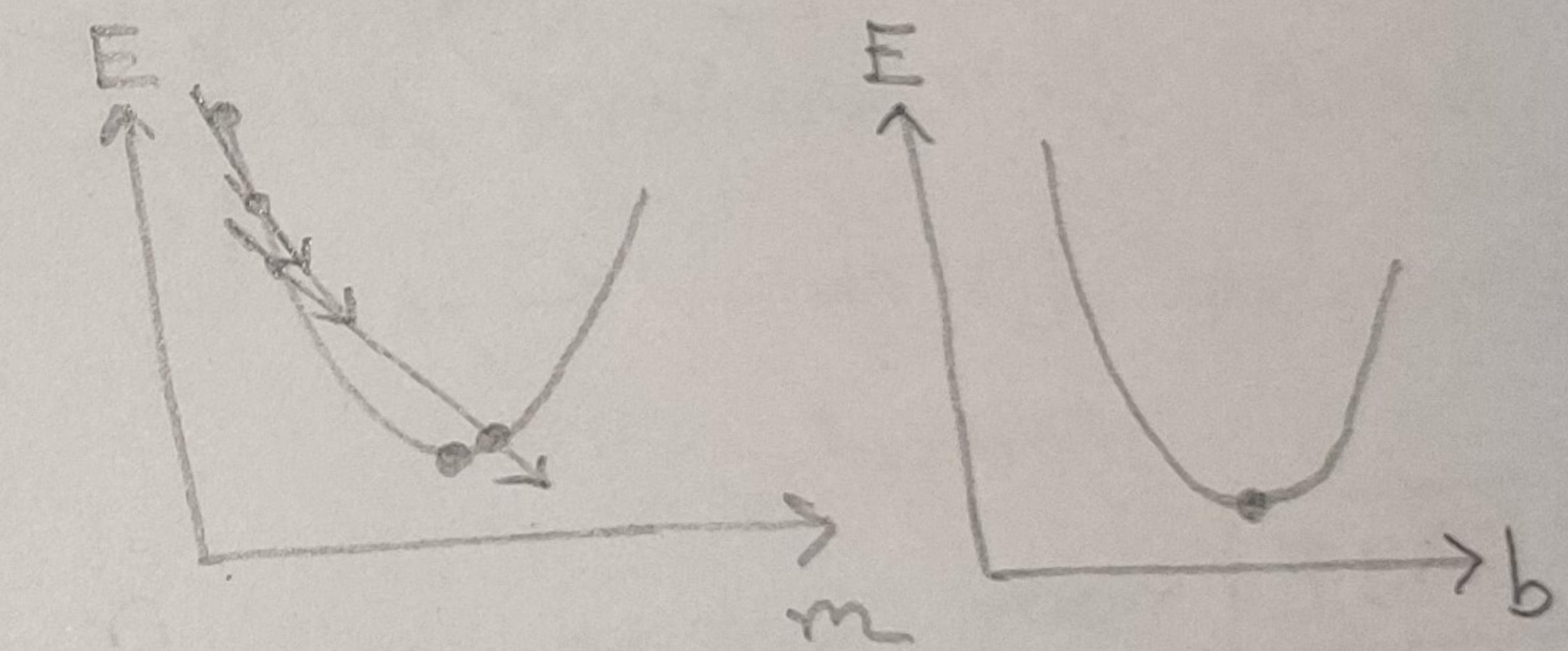
$$\frac{\partial E}{\partial m} = \frac{1}{n} \sum_{i=1}^n (y_i - mx_i - b)(-x_i)$$

our task is to minimize th E. If we could find the value and direction of the gradient

Partial derivative of E will give direction of steepest ascend with respect to m and b so how can we change m & b to maximally increase E. Then will go the opposite and b.

to minimize.

$$\frac{\partial E}{\partial m} = \frac{-2}{n} \sum_{i=1}^n x_i (y_i - mx_i - b)$$



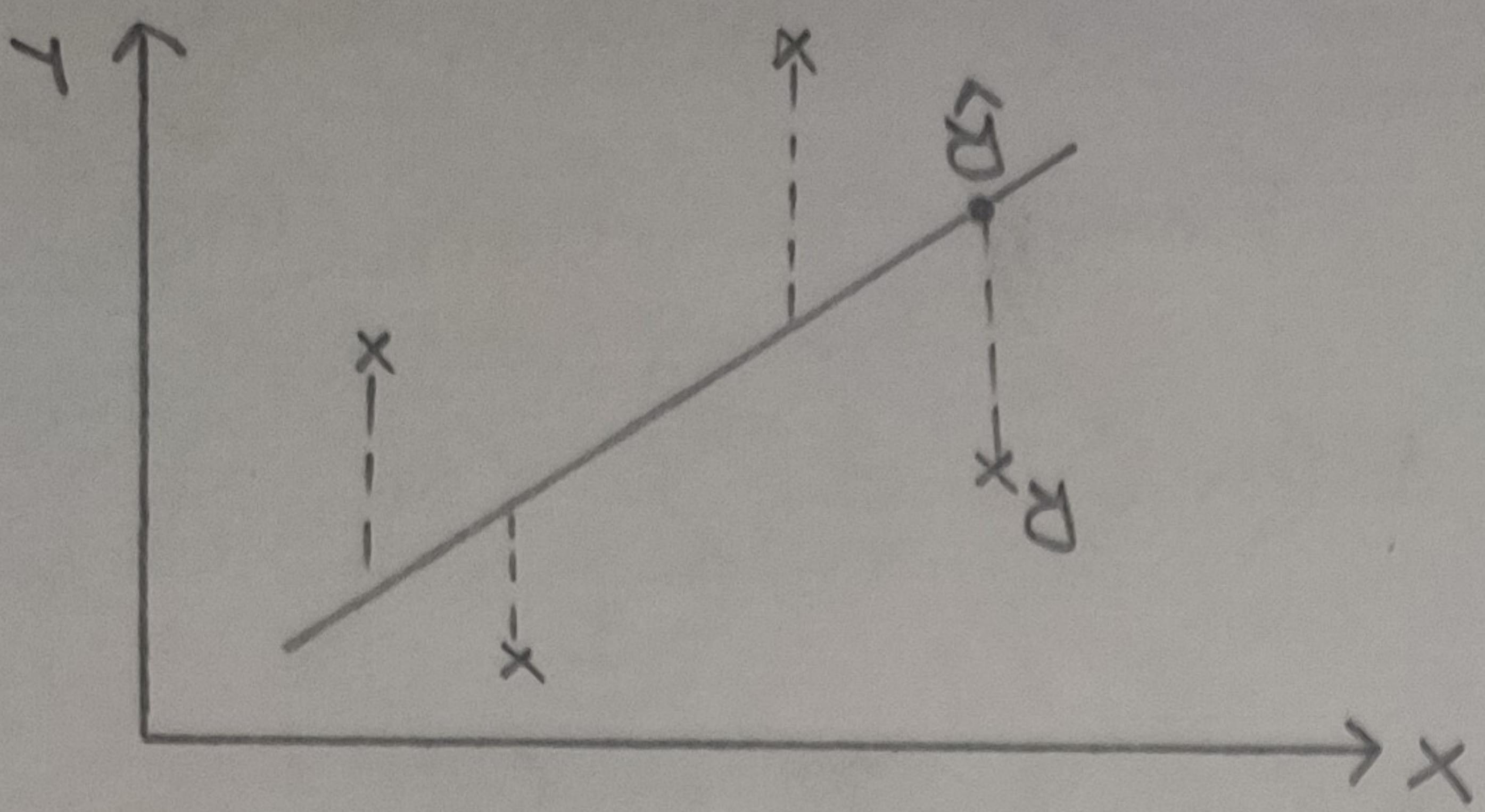
$$m = m - LR * \frac{\partial E}{\partial m}$$

$$b = b - LR * \frac{\partial E}{\partial b}$$

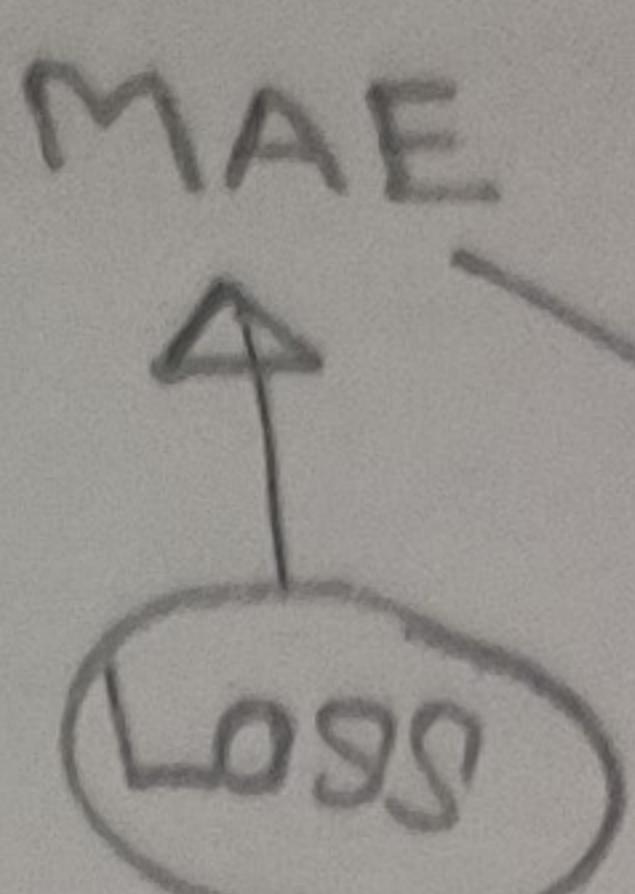
dot product: $\sum_{i=1}^n x_i \cdot \text{error}$
 $= n \cdot \text{dot}(x_i, \text{error})$

$$\frac{\partial E}{\partial m} = \frac{-2}{n} \sum_{i=1}^n x_i (y_i - \hat{y}_i)$$

MAE Mean Absolute Error



$$MAE = \frac{\sum_{i=1}^n |y_i - \hat{y}_i|}{n}$$

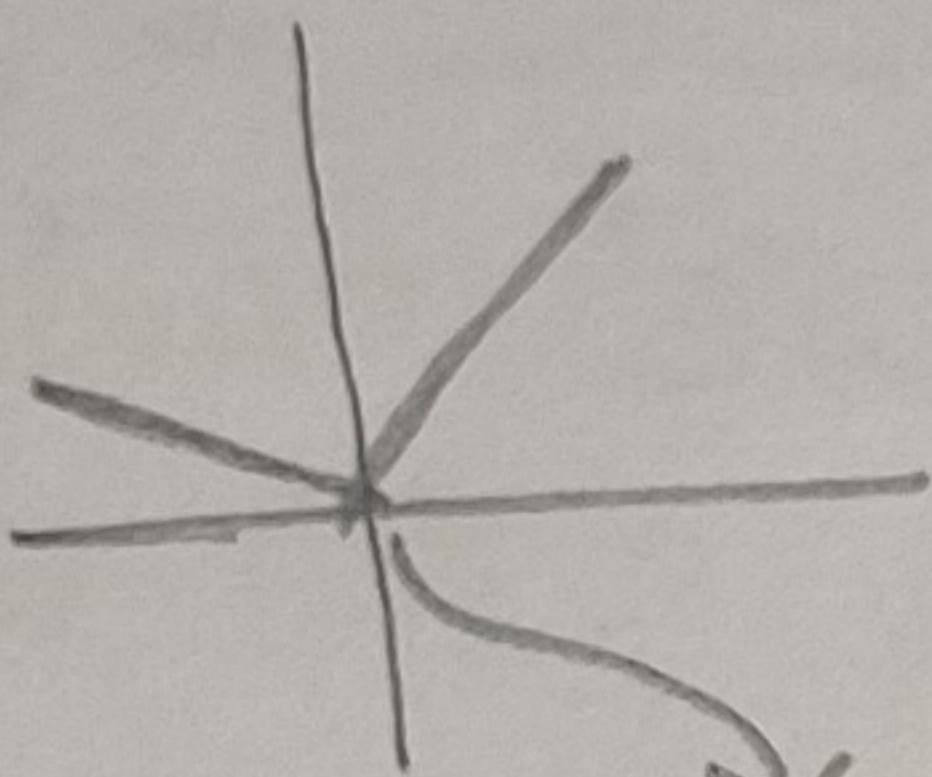


unit = unit of y

Advantage:

- ① Same unit
- ② Robust to outliers (not that much effect)

Disadvantage:



at zero graph is not differentiable

MSE mean squared error

$$MSE = \frac{1}{n} \sum_{i=1}^n (y_i - \hat{y}_i)^2$$

advantage

- ① can be used as loss function cause it's differentiable

disadvantage

- ① unit = $(\text{target unit})^2$

- ② hugely effected by outliers

RMSE root mean square error

$$RMSE = \sqrt{MSE}$$

R₂ score MAE, MSE, RMSE → context depended

context independent. → goodness of fit

$$R^2 = 1 - \frac{SS_R}{SS_m} \rightarrow \begin{array}{l} \text{sum of squared error in} \\ \text{regression line} \end{array}$$

→ sum of squared error in
the mean line

$$R^2 = 0 \rightarrow SS_R = SS_m \rightarrow \text{worst}$$

$$R^2 = 1 \rightarrow SS_R \ll SS_m \rightarrow \text{Best}$$

$$R^2 < 0 \rightarrow SS_m >> SS_R \rightarrow \text{worst worst}$$

cg | LPA → $R^2 = 0.80 \rightarrow$ means cg explain 80% of
variance of lpa

Sometimes by adding irrelevant feature R₂ score gets
better which should not. That's where we use
adjusted R₂ score.

$$R^2_{adj} = 1 - \left[\frac{(1-R^2)(n-1)}{(n-1-k)} \right] \quad \begin{array}{l} R^2 \rightarrow R^2 \text{ score} \\ n \rightarrow \text{number of rows} \\ k \rightarrow \text{num of independent columns.} \end{array}$$