

AMERICAN INTERNATIONAL UNIVERSITY-BANGLADESH (AIUB)

FACULTY OF ENGINEERING

Course name: Data Communication

Course code: COE 3201

Section: H

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Group-04

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Experiment No: 08

Experiment name: Study of Frequency Division Multiplexing (FDM) using

MATLAB

Submission date: April 26th, 2024

Performance Task for Lab Report: (your ID = AB-CDEFG-H)

```
You have four message signals:
a) mt1 = am1*cos(2*pi*fm1*t);
b) mt2 = am2*cos(2*pi*fm2*t);
c) mt3 = am3*cos(2*pi*fm3*t);
d) mt4 = am4*cos(2*pi*fm4*t);
where,
am1 = (F+2);
am2 = (F+5);
am3 = (F+8);
am4 = (F+11);
and
fm1 = (G+1);
fm2 = (G+2);
fm3 = (G+3);
fm4 = (G+4);
```

We want to simultaneously transmit these four signals through a single data link that can support a frequency range of 50 Hz to 250 Hz.

*** Write a code that can modulate and multiplex the four given message signals in transmitting side (use appropriate carrier signals for amplitude modulation as required) and de-multiplex (use appropriate cut-off frequencies in your bandpass filters) and de-modulate (use appropriate cut-off frequencies in your lowpass filters) to recover the four message signals in receiving side

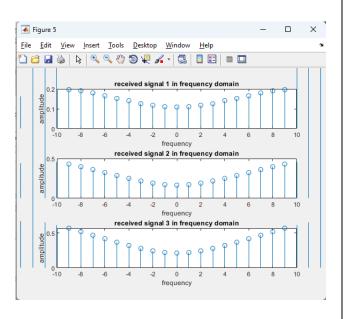
ANSWER OF QUESTION 1

A	В	-	C	D	E	F	G	-	Н
2	2	-	4	7	0	1	9	1	1

MATLAB Code Output Figure HERE, F = 1, G = 9clc: clear all; Figure 1 _ _ close all; <u>F</u>ile <u>E</u>dit <u>V</u>iew <u>I</u>nsert <u>T</u>ools <u>D</u>esktop <u>W</u>indow <u>H</u>elp 🖺 😅 🔒 🖫 | 🔈 🔍 🤏 👋 🧑 😓 🔏 - | 🗒 | 🔲 🔡 | 🖿 🛄 %% Message Signal Generation fs = 4001; %Sampling Frequency Message Signal 1 in Time Domain t = 0:1/fs:1-1/fs; %Generating Time axis 0.3 0.4 0.5 0.6 0.7 Am1 = 3; %Amplitude of First Message Message Signal 2 in Time Domain Signal fm1 = 10; %Frequency of First Message Signal m1 = Am1*cos(2*pi*fm1*t); % First 0.5 0.7 Message Signal Message Signal 3 in Time Domain Am2 = 6; %Amplitude of Second Message Signal fm2 = 11; %Frequency of Second 0.5 Message Signal m2 = Am2*cos(2*pi*fm2*t); % SecondMessage Signal Am3 = 9; %Amplitude of Third Message Figure 2 Signal $\underline{\underline{F}} ile \quad \underline{\underline{F}} dit \quad \underline{\underline{V}} iew \quad \underline{\underline{I}} nsert \quad \underline{\underline{T}} ools \quad \underline{\underline{D}} esktop \quad \underline{\underline{W}} indow \quad \underline{\underline{H}} elp$ fm3 = 12; %Frequency of Third Message 🖺 🗃 📓 🖫 | 🗣 🤏 🤏 💮 ⋑ 🗜 🔏 - | 🛃 | 🔲 🖽 | 📟 🛄 Signal m3 = Am3*cos(2*pi*fm3*t); % ThirdMessage Signal 1 in Frequency Domain Message Signal Am4 = 12; %Amplitude of Fourth Message Signal fm4 = 13; %Frequency of Fourth Message Signal 2 in Frequency Domain Message Signal m4 = Am4*cos(2*pi*fm4*t);%% Carrier Signal Generation Cm1 = 1; %Amplitude of First Carrier Signal Message Signal 3 in Frequency Domain fc1 = 50; %Frequency of First Carrier Signal c1 = Cm1*cos(2*pi*fc1*t); % FirstCarrier Signal frequency Cm2 = 1; %Amplitude of Second Carrier Signal fc2 = 100; %Frequency of Second Carrier Signal c2 = Cm2*cos(2*pi*fc2*t); % SecondCarrier Signal Cm3 = 1; %Amplitude of Third Carrier Signal

```
fc3 = 200; %Frequency of Third
Carrier Signal
c3 = Cm3*cos(2*pi*fc3*t); % Third
Carrier Signal
                                                 Figure 3
                                                                                              <u>F</u>ile <u>E</u>dit <u>V</u>iew <u>I</u>nsert <u>T</u>ools <u>D</u>esktop <u>W</u>indow <u>H</u>elp
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Cm4 = 1; %Amplitude of Third Carrier
                                                                  Composite Signal in Time Domain
Signal
fc4 = 250; %Frequency of Third
Carrier Signal
c4 = Cm4*cos(2*pi*fc4*t); % Third
Carrier Signal
                                                                      0.4
                                                                          0.5
                                                                              0.6
                                                                                  0.7 0.8
%% Composite Signal Generation
                                                                Composite Signal in Frequency Domain
x =
                                                     2.5
(m1) .*c1+(m2) .*c2+(m3) .*c3+(m4) .*c4;
                                                    amplitude
1.5
% Plotting the Signals in Time-Domain
and Frequency-Domain
figure
                                                     0.5
subplot(3,1,1)
                                                        -250 -200 -150 -100 -50
                                                                              50 100 150 200
plot(t,m1)
xlabel('time')
ylabel('amplitude')
                                                 Figure 4
title('Message Signal 1 in Time
                                                 <u>File Edit View Insert Tools Desktop Window Help</u>
Domain')
                                                🖺 👸 🔒 🖒 | 🔍 🤍 🖑 🐌 🐙 🔏 - | 🐉 | 🔲 🖽 | 🖿 🖽
ylim([-Am1 Am1])
subplot(3,1,2)
                                                                   received signal 1 in time domain
plot(t,m2)
xlabel('time')
ylabel('amplitude')
title('Message Signal 2 in Time
                                                              0.2
Domain')
                                                                           time
ylim([-Am2 Am2])
                                                                   received signal 2 in time domain
subplot(3,1,3)
plot(t,m3)
xlabel('time')
ylabel('amplitude')
                                                              0.2
                                                                  0.3
                                                                       0.4
                                                                          0.5
                                                                               0.6
                                                                                   0.7
                                                                           time
title('Message Signal 3 in Time
                                                                   received signal 3 in time domain
Domain')
ylim([-Am3 Am3])
M1 = abs(fftshift(fft(m1)))/(fs/2);
%Fourier Transformation of ml
M2 = abs(fftshift(fft(m2)))/(fs/2);
%Fourier Transformation of m2
M3 = abs(fftshift(fft(m3)))/(fs/2);
%Fourier Transformation of m3
X = abs(fftshift(fft(x)))/(fs/2);
%Fourier Transformation of x
f = fs/2*linspace(-1,1,fs);
figure
subplot(3,1,1)
stem(f,M1)
xlabel('frequency')
ylabel('amplitude')
title('Message Signal 1 in Frequency
Domain')
axis([-10 10 0 2.5])
subplot(3,1,2)
stem(f,M2)
xlabel('frequency')
```

```
ylabel('amplitude')
title('Message Signal 2 in Frequency
Domain')
axis([-10 10 0 3.5])
subplot(3,1,3)
stem(f,M3)
xlabel('frequency')
ylabel('amplitude')
title('Message Signal 3 in Frequency
Domain')
axis([-10 10 0 4.5])
figure
subplot(2,1,1)
plot(t,x)
xlabel('time')
ylabel('amplitude')
title('Composite Signal in Time
Domain')
subplot(2,1,2)
stem(f,X)
xlabel('frequency')
ylabel('amplitude')
title('Composite Signal in Frequency
Domain')
axis([-270 270 0 2.5])
%% Passing the Composite Signal
Through Bandpass Filter
[num1, den1] = butter(5, [(fc1-fm1-
6)/(fs/2), (fc1+fm1+6)/(fs/2)]);
%Butterworth Filter Window
Determining for Bandpass Filter
bpf1 = filter(num1, den1, x);
%Filtering is done here
[num2, den2] = butter(5, [(fc2-fm2-
6)/(fs/2), (fc2+fm2+6)/(fs/2)]);
%Butterworth Filter Window
Determining for Bandpass Filter
bpf2 = filter(num2, den2, x);
%Filtering is done here
[num3, den3] = butter(5, [(fc3-fm3-
6)/(fs/2), (fc3+fm3+6)/(fs/2)]);
%Butterworth Filter Window
Determining for Bandpass Filter
bpf3 = filter(num3, den3, x);
%Filtering is done here
% Mixing
z1 = 2*bpf1.*c1;
z2 = 2*bpf2.*c2;
z3 = 2*bpf3.*c3;
%% Passing the Mixed Signals Through
Lowpass Filter
[num4, den4] = butter(5,
(fm1+3)/(fs/2)); %Low pass filter is
made here
rec1 = filter(num4, den4, z1);
%Filtering is done here
```



```
[num5, den5] = butter(5,
(fm2+3)/(fs/2)); %Low pass filter is
made here
rec2 = filter(num5, den5, z2);
%Filtering is done here
[num6, den6] = butter(5,
(fm3+3)/(fs/2)); %Low pass filter is
made here
rec3 = filter(num6, den6, z3);
%Filtering is done here
% Plotting the Received Signals in
Time-Domain and Frequency Domain
figure
subplot(3,1,1)
plot(t,rec1)
xlabel('time')
ylabel('amplitude')
title('received signal 1 in time
domain')
ylim([-Am1 Am1])
subplot(3,1,2)
plot(t,rec2)
xlabel('time')
ylabel('amplitude')
title('received signal 2 in time
domain')
ylim([-Am2 Am2])
subplot(3,1,3)
plot(t,rec3)
xlabel('time')
ylabel('amplitude')
title('received signal 3 in time
domain')
ylim([-Am3 Am3])
R1 = abs(fftshift(fft(rec1)))/(fs/2);
%Fourier Transformation is done here
R2 = abs(fftshift(fft(rec2)))/(fs/2);
%Fourier Transformation is done here
R3 = abs(fftshift(fft(rec3)))/(fs/2);
%Fourier Transformation is done here
figure
subplot(3,1,1)
stem(f,R1)
xlabel('frequency')
ylabel('amplitude')
title('received signal 1 in frequency
domain')
xlim([-10 10])
subplot(3,1,2)
stem(f,R2)
xlabel('frequency')
ylabel('amplitude')
title('received signal 2 in frequency
domain')
xlim([-10 10])
```

```
subplot(3,1,3)
stem(f,R3)
xlabel('frequency')
ylabel('amplitude')
title('received signal 3 in frequency
domain')
xlim([-10 10])
```