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Team Notebook

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1. CODE TEMPLATES

```
#include <bits/stdc++.h> -----//84
typedef long long ll; -----//62
typedef unsigned long long ull; -----//ce
typedef std::pair<int, int> ii; -----//6f
typedef std::vector<int> vi; -----//96
typedef std::vector<vi> vvi; -----//b2
typedef std::vector<ii> vii; -----//56
const int INF = ~(1<<31); -----//39
const ll LINF = (1LL << 60); -----//67
const double EPS = 1e-9; -----//75
const double pi = acos(-1); -----//47
```

2. DATA STRUCTURES

2.1. Fenwick Tree.

2.1.1. Point-updates.

2.1.2. Range-updates.

2.2. Mergesort Tree.

2.3. Segment Tree.

2.3.1. Recursive (Point-update).

```
struct segtree { -----//64
- int i, j, val; -----//06
- segtree *l, *r; -----//9d
- segtree(vi &ar, int _i, int _j) : i(_i), j(_j) { -----//88
-- if (i == j) { -----//f1
---- val = ar[i]; -----//ea
---- l = r = NULL; -----//9f
-- } else { -----//e6
---- int k = (i+j) >> 1; -----//50
```

```
----- l = new segtree(ar, i, k); -----//57
----- r = new segtree(ar, k+1, j); -----//d0
----- val = l->val + r->val; } } -----//ff
- void update(int _i, int _val) { -----//28
-- if (i == _i and _i == j) { -----//b3
---- val = _val; -----//62
-- } else if (_i < i or j < _i) { -----//0b
---- // do nothing -----//b7
-- } else { -----//b9
---- l->update(_i, _val); -----//92
---- r->update(_i, _val); -----//c6
---- val = l->val + r->val; } } -----//af
- int sum(int _i, int _j) { -----//fe
-- if (_i <= i and j <= _j) { -----//06
---- return val; -----//39
-- } else if (_j < i or j < _i) { -----//40
---- return 0; -----//5a
-- } else { -----//2f
---- return l->sum(_i, _j) + r->sum(_i, _j); } } }; -----//04
```

2.3.2. Iterative (Point-update and operation can be non-commutative).

```
struct segtree { -----//64
- int n; -----//91
- int *vals; -----//00
- segtree(int *ar, int n) { -----//cf
-- this->n = n; -----//db
-- vals = new int[2*n]; -----//a1
-- for (int i = 0; i < n; ++i) -----//37
---- vals[n+i] = ar[i]; -----//0b
-- for (int i = n-1; i > 0; --i) -----//b3
---- vals[i] = vals[i<<1] + vals[i<<1|1]; } -----//27
- void update(int i, int v) { -----//f7
-- for (vals[i += n] = v; i > 1; i >= 1) -----//be
---- t[i>>1] = t[i] + t[i^1]; } -----//49
- int query(int l, int r) { -----//0d
-- int res = 0; -----//8c
-- for (l += n, r += n; l < r; l >= 1, r >= 1) { -----//9b
---- if (l&1) res += vals[l++]; -----//e7
---- if (r&1) res += vals[--r]; } -----//b3
-- return res; } } -----//80
```

2.3.3. Lazy Propagation (Range-update).

```
struct segtree { -----//64
- int i, j, val, temp_val = 0; -----//47
- segtree *l, *r; -----//cd
- segtree(vi &ar, int _i, int _j) : i(_i), j(_j) { -----//e0
-- if (i == j) { -----//74
---- val = ar[i]; -----//c8
---- l = r = NULL; -----//60
-- } else { -----//e8
---- int k = (i + j) >> 1; -----//61
---- l = new segtree(ar, i, k); -----//75
---- r = new segtree(ar, k+1, j); -----//a7
---- val = l->val + r->val; } } -----//c7
- void visit() { -----//90
-- if (temp_val) { -----//e5
---- val += (j-i+1) * temp_val; -----//84
```

```
----- if (l) { -----//70 --- nodes[nid].lid = update(idx, v, nodes[id].lid); -----//f3 ----- mat[i][j] = INF; -----//78
----- l->temp_val += temp_val; -----//94 --- nodes[nid].rid = update(idx, v, nodes[id].rid); -----//ef ----- mat[i][i] = 0; } } -----//96
----- r->temp_val += temp_val; } -----//b2 --- nodes[nid].val = nodes[id].val + delta; -----//d1 - void add_edge(int u, int v, int w) { -----//36
----- temp_val = 0; } } -----//46 --- return nid; } -----//39 --- mat[u][v] = std::min(mat[u][v], w); -----//5c
- void increase(int _i, int _j, int _inc) { -----//ef - int query(int id, int l, int r) { -----//5c - /*mat[v][u] = std::min(mat[v][u], w);*/ } }; -----//6b
- visit(); -----//af --- if (r < nodes[id].l or nodes[id].r < l) -----//49 Using edge list:
- if (_i <= i && j <= _j) { -----//0a --- return 0; -----//ff struct edge { -----//c7
----- temp_val += _inc; -----//02 --- if (l <= nodes[id].l and nodes[id].r <= r) -----//30 - int u, v, w; -----//03
----- visit(); -----//b7 --- return nodes[id].val; -----//ef - edge(int u, int v, int w) : u(u), v(v), w(w) {} -----//7f
- } else if (_j < i or j < _i) { -----//4e --- return query(nodes[id].l, l, r) + -----//97 - const bool operator < (const edge &other) const { -----//67
----- // do nothing -----//2f --- query(nodes[id].r, l, r); } } }; -----//37 --- return w < other.w; } } }; -----//c9
- } else { -----//c5 2.4. Sparse Table.
----- l->increase(_i, _j, _inc); -----//fc 2.5. Sqrt Decomposition.
----- r->increase(_i, _j, _inc); -----//b0 2.6. Treap.
----- val = l->val + r->val; } } -----//81 2.6.1. Explicit.
- int sum(int _i, int _j) { -----//ae 2.6.2. Implicit.
- visit(); -----//86 2.6.3. Persistent.
- if (_i <= i and j <= _j) { -----//1b 2.7. Union Find.
----- return val; -----//73 struct union_find { -----//42
----- } else if (_j < i || j < _i) { -----//96 - vi p; union_find(int n) : p(n, -1) { } -----//28
----- return 0; -----//0d - int find(int x) { return p[x] < 0 ? x : p[x] = find(p[x]); } -----//28
----- } else { -----//8c - bool unite(int x, int y) { -----//6c
----- return l->sum(_i, _j) + r->sum(_i, _j); } } }; -----//f6 - int xp = find(x), yp = find(y); -----//64
- if (_i <= i and j <= _j) { -----//1b - if (xp == yp) return false; -----//0b
- return val; -----//73 - if (p[xp] > p[yp]) swap(xp,yp); -----//78
- } else if (_j < i || j < _i) { -----//96 - p[xp] += p[yp], p[yp] = xp; -----//88
- return 0; -----//0d - return true; } -----//1f
- } else { -----//8c - int size(int x) { return -p[find(x)]; } }; -----//b9
- return l->sum(_i, _j) + r->sum(_i, _j); } } }; -----//f6 3. GRAPHS

2.3.4. Persistent (Point-update).
struct node { int l, r, lid, rid, val; }; -----//63
struct segtree { -----//c9
- node *nodes; -----//10
- int n, node_cnt = 0; -----//77
- segtree(int n) { -----//96
- this->n = n; -----//83
- nodes = new node[2*n]; } -----//f9
- int build (vi &ar, int l, int r) { -----//21
- if (l > r) return -1; -----//3c
- int id = node_cnt++; -----//2c
- nodes[id].l = l; -----//06
- nodes[id].r = r; -----//89
- if (l == r) { -----//51
- nodes[id].lid = -1; -----//fb
- nodes[id].rid = -1; -----//20
- nodes[id].val = ar[l]; -----//0c
- } else { -----//ed
- int m = (l + r) / 2; -----//63
- nodes[id].lid = build(l, m); -----//e7
- nodes[id].rid = build(m+1, r); -----//ff
- nodes[id].val = nodes[nodes[id].lid].val + -----//95
- nodes[nodes[id].rid].val; } -----//a3
- return id; } -----//31
- int update(int idx, int delta, int id) { -----//a0
- if (id == -1) -----//23
- return -1; -----//66
- if (idx < nodes[id].l or nodes[id].r < idx) -----//fb
- return id; -----//6c
- int nid = node_cnt++; -----//8e
- nodes[nid].l = nodes[id].l; -----//af
- nodes[nid].r = nodes[id].r; -----//cc

3.1. Single-Source Shortest Paths.
3.1.1. Dijkstra.
#include "graph_template_adjlist.cpp" -----//76
void dijkstra(int s, int n, int *dist, vii *adj) { -----//ad
- for (int u = 0; u < n; ++u) -----//24
- dist[u] = INF; -----//6d
- dist[s] = 0; -----//63
- std::priority_queue<ii, vii, std::greater<ii> > pq; -----//e0
- pq.push({0, s}); -----//a3
- while (!pq.empty()) { -----//9b
- int u = pq.top().second; -----//10
- int d = pq.top().first; -----//7b
- pq.pop(); -----//15
- if (dist[u] < d) -----//b1
- continue; -----//27
- dist[u] = d; -----//96
- for (auto &e : adj[u]) { -----//24
- int v = e.first; -----//94
- int w = e.second; -----//0f
- if (dist[v] > dist[u] + w) { -----//ca
- dist[v] = dist[u] + w; -----//d0
- pq.push({dist[v], v}); } } } } -----//4a

3.1.2. Bellman-Ford.
#include "graph_template_adjlist.cpp" -----//76
void bellman_ford(int s, int n, int *dist, vii *adj) { -----//f4
- for (int u = 0; u < n; ++u) -----//2c
- dist[u] = INF; -----//ba
- dist[s] = 0; -----//50
- for (int i = 0; i < n-1; ++i) -----//a0
- for (int u = 0; u < n; ++u) -----//94
- for (auto &e : adj[u]) -----//96
- if (dist[u] + e.second < dist[e.first]) -----//3b
- dist[e.first] = dist[u] + e.second; } -----//b4
// you can call this after running bellman_ford() -----//06
bool has_neg_cycle(int n, int *dist, vii *adj) { -----//26
- for (int u = 0; u < n; ++u) -----//f3
- for (auto &e : adj[u]) -----//e9
```

| | | |
|--|---|---|
| <pre>----- if (dist[e.first] > dist[u] + e.second) -----//b4 ----- return true; -----//ba - return false; } -----//7b</pre> | | |
| 3.2. All-Pairs Shortest Paths. | | |
| 3.2.1. Floyd-Washall. | | |
| <pre>#include "graph_template_adjmat.cpp" -----//6e void floyd_warshall(int n, int **mat) { -----//af - for (int k = 0; k < n; ++k) -----//6i -- for (int i = 0; i < n; ++i) -----//d3 ---- for (int j = 0; j < n; ++j) -----//43 ----- if (mat[i][k] + mat[k][j] < mat[i][j]) -----//a3 ----- mat[i][j] = mat[i][k] + mat[k][j]; } -----//99</pre> | <pre>std::queue<int> q; -----//1b q.push(this->s); -----//f4 while (!q.empty()) { -----//d8 int u = q.front(); q.pop(); -----//e5 for (int v : adj[u]) { -----//c4 if (res(u, v) > 0 and par[v] == -1) { -----//44 par[v] = u; -----//2a if (v == this->t) -----//79 return true; -----//85 q.push(v); } } -----//f5 return false; } -----//da bool aug_path() { -----//08 for (int u = 0; u < n; ++u) -----//7c par[u] = -1; -----//9f par[s] = s; -----//df return bfs(); } -----//3c int calc_max_flow() { -----//96 int ans = 0; -----//b0 while (aug_path()) { -----//19 int flow = INF; -----//bd for (int u = t; u != s; u = par[u]) -----//22 flow = std::min(flow, res(par[u], u)); -----//a6 for (int u = t; u != s; u = par[u]) -----//40 f[par[u]][u] += flow, f[u][par[u]] -= flow; -----//ef ans += flow; } -----//ad return ans; } }; -----//75</pre> | <pre>while (!q.empty()) { -----//1c int u = q.front(); q.pop(); -----//19 for (int v : adj[u]) { -----//28 if (res(u, v) > 0 and dist[v] == -1) { -----//42 dist[v] = dist[u] + 1; -----//00 q.push(v); } } } -----//bd return dist[t] != -1; } -----//72 bool next(int u, int v) { return dist[v] == dist[u] + 1; } bool dfs(int u) { -----//fb if (u == t) return true; -----//66 for (int &i = adj_ptr[u]; i < adj[u].size(); ++i) { ---//c3 int v = adj[u][i]; -----//99 if (next(u, v) and res(u, v) > 0 and dfs(v)) { -----//07 par[v] = u; -----//eb return true; } } -----//ad dist[u] = -1; -----//94 return false; } -----//4b bool aug_path() { -----//6d reset(par, -1); -----//80 par[s] = s; -----//60 return dfs(s); } -----//39 int calc_max_flow() { -----//22 int ans = 0; -----//a3 while (make_level_graph()) { -----//50 reset(adj_ptr, 0); -----//78 while (aug_path()) { -----//45 int flow = INF; -----//1f for (int u = t; u != s; u = par[u]) -----//97 flow = std::min(flow, res(par[u], u)); -----//ae for (int u = t; u != s; u = par[u]) -----//76 f[par[u]][u] += flow, f[u][par[u]] -= flow; -----//a1 ans += flow; } } -----//42 return ans; } }; -----//16</pre> |
| 3.3. Strongly Connected Components. | | |
| 3.3.1. Kosaraju. | | |
| 3.4. Cut Points and Bridges. | | |
| 3.5. Biconnected Components. | | |
| 3.5.1. Bridge Tree. | | |
| 3.5.2. Block-Cut Tree. | | |
| 3.6. Minimum Spanning Tree. | | |
| 3.6.1. Kruskal. | | |
| 3.6.2. Prim. | | |
| 3.7. Topological Sorting. | | |
| 3.8. Euler Path. | | |
| 3.9. Bipartite Matching. | | |
| 3.9.1. Alternating Paths Algorithm. | | |
| 3.9.2. Hopcroft-Karp Algorithm. | | |
| 3.10. Maximum Flow. | | |
| 3.10.1. Edmonds-Karp. | | |
| <pre>struct max_flow { -----//e7 - int n, s, t, *par, **c, **f; -----//07 - vi *adj; -----//22 - max_flow(int n, int s, int t) : n(n), s(s), t(t) { -----//5b -- adj = new std::vector<int>[n]; -----//a8 -- par = new int[n]; -----//71 -- c = new int*[n]; -----//71 -- f = new int*[n]; -----//f7 -- for (int i = 0; i < n; ++i) { -----//0f ---- c[i] = new int[n]; -----//c7 ---- f[i] = new int[n]; -----//ba ---- for (int j = 0; j < n; ++j) -----//e9 ----- c[i][j] = f[i][j] = 0; } } -----//13 - void add_edge(int u, int v, int w) { -----//5f -- adj[u].push_back(v); -----//ce -- adj[v].push_back(u); -----//bb -- c[u][v] += w; } -----//a0 - int res(int i, int j) { return c[i][j] - f[i][j]; } -----//36 - bool bfs() { -----//d0</pre> | <pre>3.10.2. Dinic. struct max_flow { -----//e7 - int n, s, t, *adj_ptr, *dist, *par, **c, **f; -----//b8 - vi *adj; -----//a3 - max_flow(int n, int s, int t) : n(n), s(s), t(t) { -----//0a -- adj = new std::vector<int>[n]; -----//f7 -- adj_ptr = new int[n]; -----//a4 -- dist = new int[n]; -----//61 -- par = new int[n]; -----//19 -- c = new int*[n]; -----//9d -- f = new int*[n]; -----//ff -- for (int i = 0; i < n; ++i) { -----//a8 ---- c[i] = new int[n]; -----//e2 ---- f[i] = new int[n]; -----//df ---- for (int j = 0; j < n; ++j) -----//e8 ----- c[i][j] = f[i][j] = 0; } } -----//37 - void add_edge(int u, int v, int w) { -----//d9 -- adj[u].push_back(v); -----//74 -- adj[v].push_back(u); -----//ca -- c[u][v] += w; } -----//11 - int res(int i, int j) { return c[i][j] - f[i][j]; } -----//4e - void reset(int *ar, int val) { -----//99 -- for (int i = 0; i < n; ++i) -----//a7 ---- ar[i] = val; } -----//3e - bool make_level_graph() { -----//4f -- reset(dist, -1); -----//75 -- std::queue<int> q; -----//fc -- q.push(s); -----//d5 -- dist[s] = 0; -----//0f</pre> | |
| | | 3.11. Centroid Decomposition. |
| | | 3.12. Least Common Ancestor. |
| | | 3.12.1. Binary Lifting. |
| | | 3.12.2. Tarjan's Offline Algorithm. |
| | | 4. STRINGS |
| | | 4.1. Z-algorithm. |
| | | 4.2. Trie. |
| | | 4.3. Hashing. |
| | | 5. DYNAMIC PROGRAMMING |
| | | 5.1. Longest Common Subsequence. |
| | | 5.2. Longest Increasing Subsequence. |
| | | 5.3. Traveling Salesman. |
| | | 6. MATHEMATICS |
| | | 6.1. Special Data Types. |
| | | 6.1.1. Fraction. |

6.1.2. *BigInteger*.

6.1.3. *Matrix*.

6.1.4. *Dates*.

6.2. **Binomial Coefficients**.

6.3. **Euclidean Algorithm**.

6.4. **Primality Test**.

6.4.1. *Optimized Brute Force*.

6.4.2. *Miller-Rabin*.

6.4.3. *Pollard’s Rho Algorithm*.

6.5. **Sieve**.

6.5.1. *Sieve of Eratosthenes*.

6.5.2. *Divisor Sieve (Modified Sieve of Eratosthenes)*.

6.5.3. *Phi Sieve*.

6.6. **Phi Function**.

6.7. **Modular Exponentiation**.

6.8. **Modular Multiplicative Inverse**.

6.9. **Chinese Remainder Theorem**.

6.10. **Numeric Integration (Simpson’s Rule)**.

6.11. **Fast Fourier Transform**.

6.12. **Josephus Problem**.

6.13. **Number of Integer Points Below a Line**.

7. GEOMETRY

7.1. **Primitives**.

7.2. **Lines**.

7.3. **Circles**.

7.4. **Polygons**.

7.5. **Convex Hull (Graham’s Scan)**.

7.6. **Closest Pair of Points**.

7.7. **Rectilinear Minimum Spanning Tree**.

8. OTHER ALGORITHMS

8.1. **Coordinate Compression**.

8.2. **2SAT**.

8.3. **Nth Permutation**.

8.4. **Floyd’s Cycle-Finding**.

8.5. **Simulated Annealing**.

8.6. **Hexagonal Grid Algorithms**.

| | | | |
|---|--|---|--|
| 9. USEFUL INFORMATION (CLEAN THIS UP!!) | | · sufficient: QI and $C[b][c] \leq C[a][d], a \leq b \leq c \leq d$ | |
| 10. Misc | | | |
| 10.1. Debugging Tips. | | | |
| <ul style="list-style-type: none">Stack overflow? Recursive DFS on tree that is actually a long path?Floating-point numbers<ul style="list-style-type: none">Getting NaN? Make sure acos etc. are not getting values out of their range (perhaps 1+eps).Rounding negative numbers?Outputting in scientific notation?Wrong Answer?<ul style="list-style-type: none">Read the problem statement again!Are multiple test cases being handled correctly? Try repeating the same test case many times.Integer overflow?Think very carefully about boundaries of all input parametersTry out possible edge cases:<ul style="list-style-type: none">* $n = 0, n = -1, n = 1, n = 2^{31} - 1$ or $n = -2^{31}$* List is empty, or contains a single element* n is even, n is odd* Graph is empty, or contains a single vertex* Graph is a multigraph (loops or multiple edges)* Polygon is concave or non-simpleIs initial condition wrong for small cases?Are you sure the algorithm is correct?Explain your solution to someone.Are you using any functions that you don't completely understand? Maybe STL functions?Maybe you (or someone else) should rewrite the solution?Can the input line be empty?Run-Time Error?<ul style="list-style-type: none">Is it actually Memory Limit Exceeded? | <ul style="list-style-type: none">GreedyRandomizedOptimizations<ul style="list-style-type: none">Use bitset (/64)Switch order of loops (cache locality)Process queries offline<ul style="list-style-type: none">Mo's algorithmSquare-root decompositionPrecomputationEfficient simulation<ul style="list-style-type: none">Mo's algorithmSqrt decompositionStore 2^k jump pointersData structure techniques<ul style="list-style-type: none">Sqrt bucketsStore 2^k jump pointers2^k merging trickCounting<ul style="list-style-type: none">Inclusion-exclusion principleGenerating functionsGraphs<ul style="list-style-type: none">Can we model the problem as a graph?Can we use any properties of the graph?Strongly connected componentsCycles (or odd cycles)Bipartite (no odd cycles)<ul style="list-style-type: none">* Bipartite matching* Hall's marriage theorem* Stable MarriageCut vertex/bridgeBiconnected componentsDegrees of vertices (odd/even)Trees<ul style="list-style-type: none">* Heavy-light decomposition* Centroid decomposition* Least common ancestor* Centers of the treeEulerian path/circuitChinese postman problemTopological sort(Min-Cost) Max FlowMin Cut<ul style="list-style-type: none">* Maximum Density SubgraphHuffman CodingMin-Cost ArborescenceSteiner TreeKirchoff's matrix tree theoremPrüfer sequencesLovász ToggleLook at the DFS tree (which has no cross-edges)Is the graph a DFA or NFA?<ul style="list-style-type: none">* Is it the Synchronizing word problem?Mathematics<ul style="list-style-type: none">Is the function multiplicative?Look for a pattern | <ul style="list-style-type: none">Permutations<ul style="list-style-type: none">* Consider the cycles of the permutationFunctions<ul style="list-style-type: none">* Sum of piecewise-linear functions is a piecewise-linear function* Sum of convex (concave) functions is convex (concave)Modular arithmetic<ul style="list-style-type: none">* Chinese Remainder Theorem* Linear CongruenceSieveSystem of linear equationsValues too big to represent?<ul style="list-style-type: none">* Compute using the logarithm* Divide everything by some large valueLinear programming<ul style="list-style-type: none">* Is the dual problem easier to solve?Can the problem be modeled as a different combinatorial problem? Does that simplify calculations? <ul style="list-style-type: none">Logic<ul style="list-style-type: none">2-SATXOR-SAT (Gauss elimination or Bipartite matching)Meet in the middleOnly work with the smaller half ($\log(n)$)Strings<ul style="list-style-type: none">Trie (maybe over something weird, like bits)Suffix arraySuffix automaton (+DP?)Aho-CorasickeerTreeWork with $S + S$HashingEuler tour, tree to arraySegment trees<ul style="list-style-type: none">Lazy propagationPersistentImplicitSegment tree of XGeometry<ul style="list-style-type: none">Minkowski sum (of convex sets)Rotating calipersSweep line (horizontally or vertically?)Sweep angleConvex hullFix a parameter (possibly the answer).Are there few distinct values?Binary searchSliding Window (+ Monotonic Queue)Computing a Convolution? Fast Fourier TransformComputing a 2D Convolution? FFT on each row, and then on each columnExact Cover (+ Algorithm X)Cycle-FindingWhat is the smallest set of values that identify the solution? The cycle structure of the permutation? The powers of primes in the factorization?Look at the complement problem | |
| 10.2. Solution Ideas. | | | |
| <ul style="list-style-type: none">Dynamic Programming<ul style="list-style-type: none">Parsing CFGs: CYK AlgorithmDrop a parameter, recover from othersSwap answer and a parameterWhen grouping: try splitting in two2^k trickWhen optimizing<ul style="list-style-type: none">* Convex hull optimization<ul style="list-style-type: none">· $dp[i] = \min_{j < i} \{dp[j] + b[j] \times a[i]\}$· $b[j] \geq b[j + 1]$· optionally $a[i] \leq a[i + 1]$· $O(n^2)$ to $O(n)$* Divide and conquer optimization<ul style="list-style-type: none">· $dp[i][j] = \min_{k < j} \{dp[i - 1][k] + C[k][j]\}$· $A[i][j] \leq A[i][j + 1]$· $O(kn^2)$ to $O(kn \log n)$· sufficient: $C[a][c] + C[b][d] \leq C[a][d] + C[b][c], a \leq b \leq c \leq d$ (QI)* Knuth optimization<ul style="list-style-type: none">· $dp[i][j] = \min_{i < k < j} \{dp[i][k] + dp[k][j] + C[i][j]\}$· $A[i][j - 1] \leq A[i][j] \leq A[i + 1][j]$· $O(n^3)$ to $O(n^2)$ | | | |

- Minimize something instead of maximizing
- Immediately enforce necessary conditions. (All values greater than 0? Initialize them all to 1)
- Add large constant to negative numbers to make them positive
- Counting/Bucket sort

11. FORMULAS

- **Legendre symbol:** $\left(\frac{a}{b}\right) = a^{(b-1)/2} \pmod{b}$, b odd prime.
- **Heron’s formula:** A triangle with side lengths a, b, c has area $\sqrt{s(s-a)(s-b)(s-c)}$ where $s = \frac{a+b+c}{2}$.
- **Pick’s theorem:** A polygon on an integer grid strictly containing i lattice points and having b lattice points on the boundary has area $i + \frac{b}{2} - 1$. (Nothing similar in higher dimensions)
- **Euler’s totient:** The number of integers less than n that are coprime to n are $n \prod_{p|n} \left(1 - \frac{1}{p}\right)$ where each p is a distinct prime factor of n .
- **König’s theorem:** In any bipartite graph $G = (L \cup R, E)$, the number of edges in a maximum matching is equal to the number of vertices in a minimum vertex cover. Let U be the set of unmatched vertices in L , and Z be the set of vertices that are either in U or are connected to U by an alternating path. Then $K = (L \setminus Z) \cup (R \cap Z)$ is the minimum vertex cover.
- A minumum Steiner tree for n vertices requires at most $n-2$ additional Steiner vertices.
- The number of vertices of a graph is equal to its minimum vertex cover number plus the size of a maximum independent set.
- **Lagrange polynomial** through points $(x_0, y_0), \dots, (x_k, y_k)$ is $L(x) = \sum_{j=0}^k y_j \prod_{\substack{0 \leq m \leq k \\ m \neq j}} \frac{x-x_m}{x_j-x_m}$
- **Hook length formula:** If λ is a Young diagram and $h_\lambda(i, j)$ is the hook-length of cell (i, j) , then then the number of Young tableaux $d_\lambda = n! / \prod h_\lambda(i, j)$.
- **Möbius inversion formula:** If $f(n) = \sum_{d|n} g(d)$, then $g(n) = \sum_{d|n} \mu(d) f(n/d)$. If $f(n) = \sum_{m=1}^n g(\lfloor n/m \rfloor)$, then $g(n) = \sum_{m=1}^n \mu(m) f(\lfloor \frac{n}{m} \rfloor)$.
- #primitive pythagorean triples with hypotenuse $< n$ approx $n/(2\pi)$.
- **Frobenius Number:** largest number which can’t be expressed as a linear combination of numbers a_1, \dots, a_n with non-negative coefficients. $g(a_1, a_2) = a_1 a_2 - a_1 - a_2$, $N(a_1, a_2) = (a_1 - 1)(a_2 - 1)/2$. $g(d \cdot a_1, d \cdot a_2, a_3) = d \cdot g(a_1, a_2, a_3) + a_3(d - 1)$. An integer $x > (\max_i a_i)^2$ can be expressed in such a way iff. $x \mid \gcd(a_1, \dots, a_n)$.

11.1. Physics.

- **Snell’s law:** $\frac{\sin \theta_1}{v_1} = \frac{\sin \theta_2}{v_2}$

11.2. **Markov Chains.** A Markov Chain can be represented as a weighted directed graph of states, where the weight of an edge represents the probability of transitioning over that edge in one timestep. Let $P^{(m)} = (p_{ij}^{(m)})$ be the probability matrix of transitioning from state i to state j in m timesteps, and note that $P^{(1)}$ is the adjacency matrix of the graph. **Chapman-Kolmogorov:** $p_{ij}^{(m+n)} = \sum_k p_{ik}^{(m)} p_{kj}^{(n)}$. It follows that $P^{(m+n)} = P^{(m)} P^{(n)}$ and $P^{(m)} = P^m$. If $p^{(0)}$ is the initial probability distribution (a vector), then $p^{(0)} P^{(m)}$ is the probability distribution after m timesteps.

The return times of a state i is $R_i = \{m \mid p_{ii}^{(m)} > 0\}$, and i is *aperiodic* if $\gcd(R_i) = 1$. A MC is aperiodic if any of its vertices is aperiodic. A MC is *irreducible* if the corresponding graph is strongly connected.

A distribution π is stationary if $\pi P = \pi$. If MC is irreducible then $\pi_i = 1/\mathbb{E}[T_i]$, where T_i is the expected time between two visits at i . π_j/π_i is the expected number of visits at j in between two consecutive visits at i . A MC is *ergodic* if $\lim_{m \rightarrow \infty} p^{(0)} P^m = \pi$. A MC is ergodic iff. it is irreducible and aperiodic.

A MC for a random walk in an undirected weighted graph (un-weighted graph can be made weighted by adding 1-weights) has $p_{uv} = w_{uv} / \sum_x w_{ux}$. If the graph is connected, then $\pi_u = \sum_x w_{ux} / \sum_v \sum_x w_{vx}$. Such a random walk is aperiodic iff. the graph is not bipartite.

An *absorbing* MC is of the form $P = \begin{pmatrix} Q & R \\ 0 & I_r \end{pmatrix}$. Let $N = \sum_{m=0}^\infty Q^m = (I_t - Q)^{-1}$. Then, if starting in state i , the expected number of steps till absorption is the i -th entry in $N1$. If starting in state i , the probability of being absorbed in state j is the (i, j) -th entry of NR . Many problems on MC can be formulated in terms of a system of recurrence relations, and then solved using Gaussian elimination.

11.3. **Burnside’s Lemma.** Let G be a finite group that acts on a set X . For each g in G let X^g denote the set of elements in X that are fixed by g . Then the number of orbits

$$|X/G| = \frac{1}{|G|} \sum_{g \in G} |X^g|$$

$$Z(S_n) = \frac{1}{n} \sum_{l=1}^n a_l Z(S_{n-l})$$

11.4. **Bézout’s identity.** If (x, y) is any solution to $ax + by = d$ (e.g. found by the Extended Euclidean Algorithm), then all solutions are given by

$$\left(x + k \frac{b}{\gcd(a, b)}, y - k \frac{a}{\gcd(a, b)}\right)$$

11.5. Misc.

11.5.1. *Determinants and PM.*

$$\det(A) = \sum_{\sigma \in S_n} \text{sgn}(\sigma) \prod_{i=1}^n a_{i, \sigma(i)}$$

$$\text{perm}(A) = \sum_{\sigma \in S_n} \prod_{i=1}^n a_{i, \sigma(i)}$$

$$\begin{aligned} pf(A) &= \frac{1}{2^n n!} \sum_{\sigma \in S_{2n}} \text{sgn}(\sigma) \prod_{i=1}^n a_{\sigma(2i-1), \sigma(2i)} \\ &= \sum_{M \in \text{PM}(n)} \text{sgn}(M) \prod_{(i,j) \in M} a_{i,j} \end{aligned}$$

11.5.2. *BEST Theorem.* Count directed Eulerian cycles. Number of OST given by Kirchoff’s Theorem (remove r/c with root) $\# \text{OST}(G, r) \cdot \prod_v (d_v - 1)!$

11.5.3. *Primitive Roots.* Only exists when n is $2, 4, p^k, 2p^k$, where p odd prime. Assume n prime. Number of primitive roots $\phi(\phi(n))$ Let g be primitive root. All primitive roots are of the form g^k where $k, \phi(p)$ are coprime.

k -roots: $g^{i \cdot \phi(n)/k}$ for $0 \leq i < k$

11.5.4. *Sum of primes.* For any multiplicative f :

$$S(n, p) = S(n, p-1) - f(p) \cdot (S(n/p, p-1) - S(p-1, p-1))$$

11.5.5. *Floor.*

$$\lfloor \lfloor x/y \rfloor / z \rfloor = \lfloor x/(yz) \rfloor$$

$$x \% y = x - y \lfloor x/y \rfloor$$

PRACTICE CONTEST CHECKLIST

- How many operations per second? Compare to local machine.
- What is the stack size?
- How to use printf/scanf with long long/long double?
- Are `__int128` and `__float128` available?
- Does MLE give RTE or MLE as a verdict? What about stack overflow?
- What is `RAND_MAX`?
- How does the judge handle extra spaces (or missing newlines) in the output?
- Look at documentation for programming languages.
- Try different programming languages: C++, Java and Python.
- Try the submit script.
- Try local programs: `i?python[23]`, `factor`.
- Try submitting with `assert(false)` and `assert(true)`.
- Return-value from `main`.
- Look for directory with sample test cases.
- Make sure printing works.
- Remove this page from the notebook.