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# Instruction Selection

*Compilers course*

Masters in Informatics and Computing Engineering (MIEIC), 3rd Year

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# Outline

- Instruction Selection Overview
- Maximal Munch
  - Example
- Dynamic Programming
  - Example
- Other Approaches

# Instruction Selection Overview

Problem:

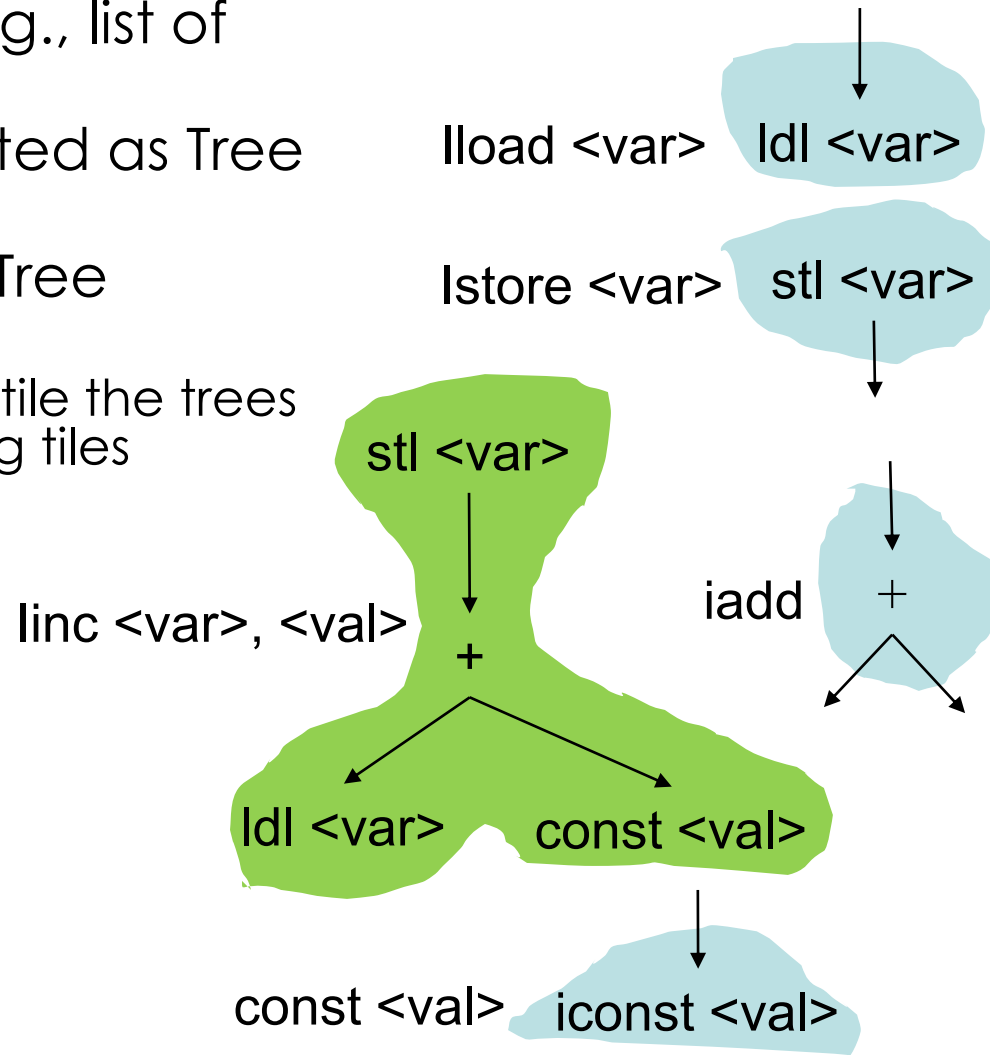
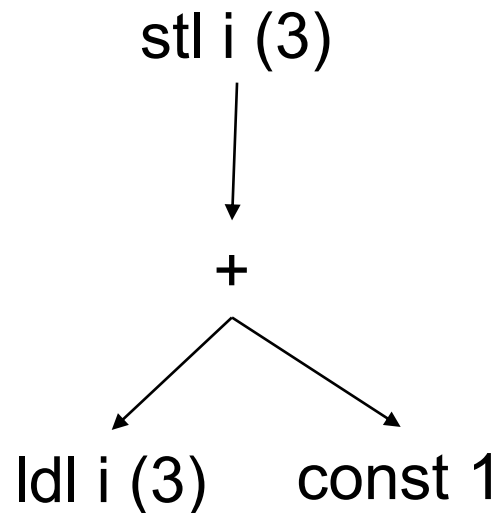
- Find for the operations in the given intermediate representation the appropriate machine instructions



# Instruction Selection Overview

From Tree-based IRs (e.g., list of trees):

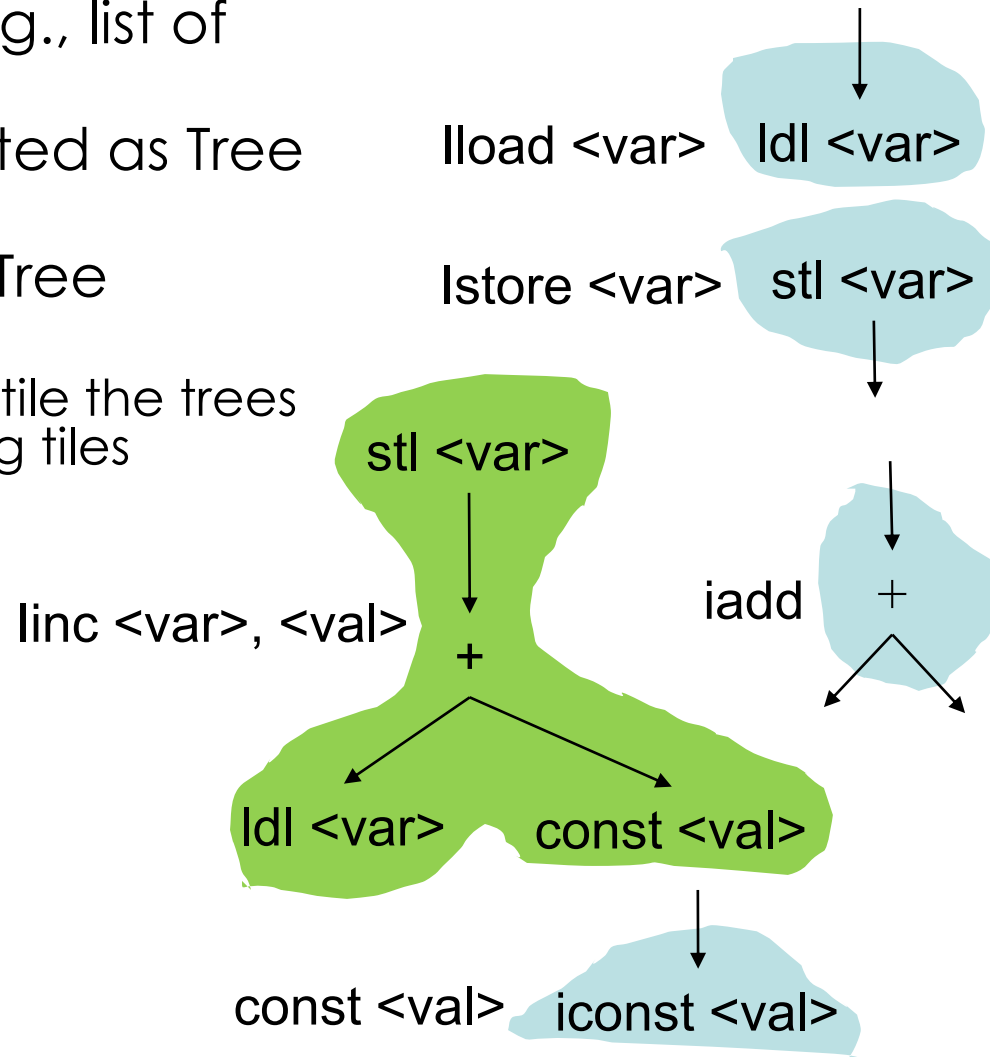
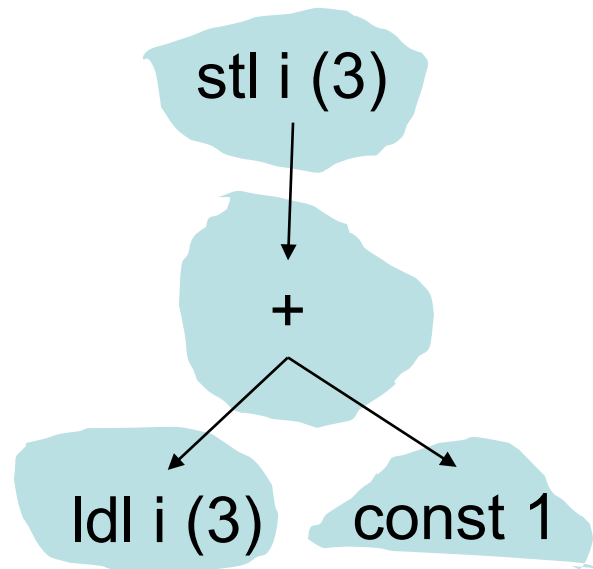
- Instructions represented as Tree Patterns
- Problem resumes to Tree covering/tiling
  - Completely Cover /tile the trees with non-overlapping tiles



# Instruction Selection Overview

From Tree-based IRs (e.g., list of trees):

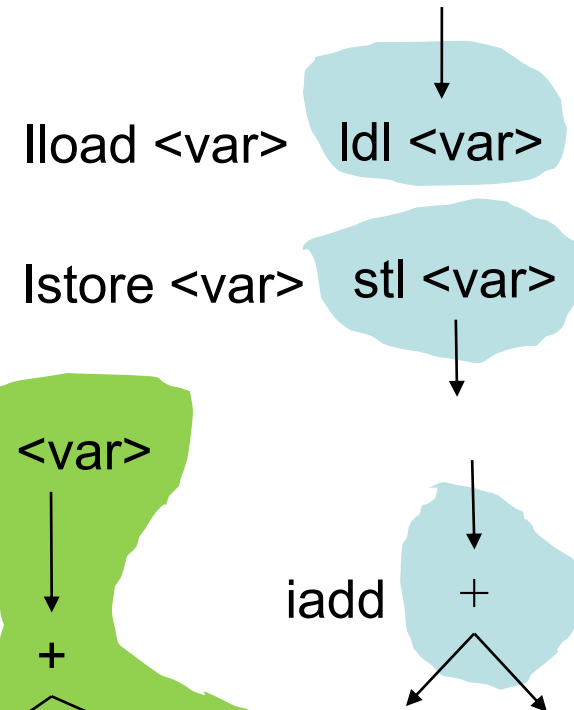
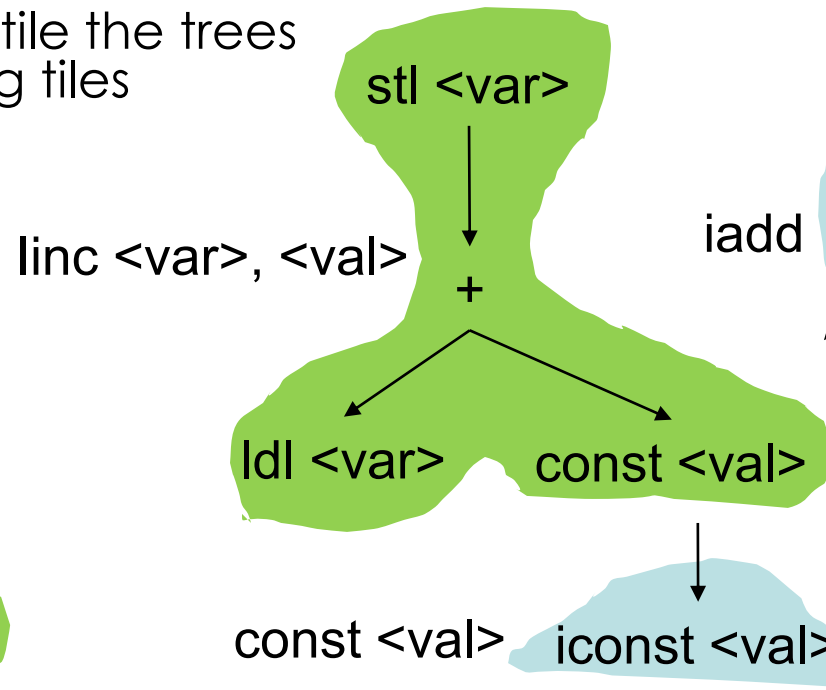
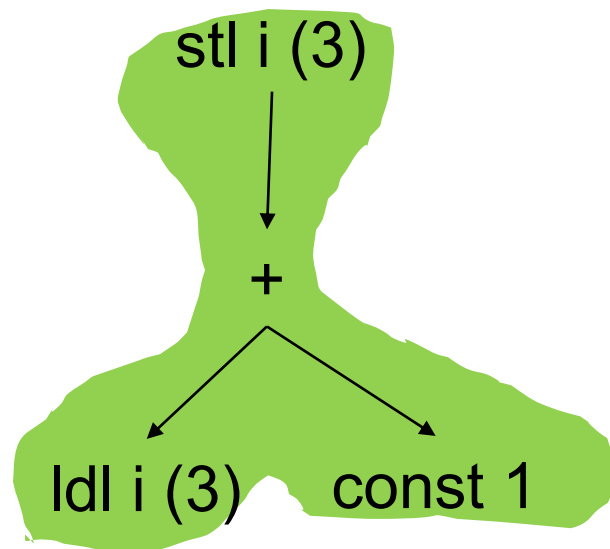
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# Instruction Selection Overview

From Tree-based IRs (e.g., list of trees):

- Instructions represented as Tree Patterns
- Problem resumes to Tree covering/tiling
  - Completely Cover /tile the trees with non-overlapping tiles

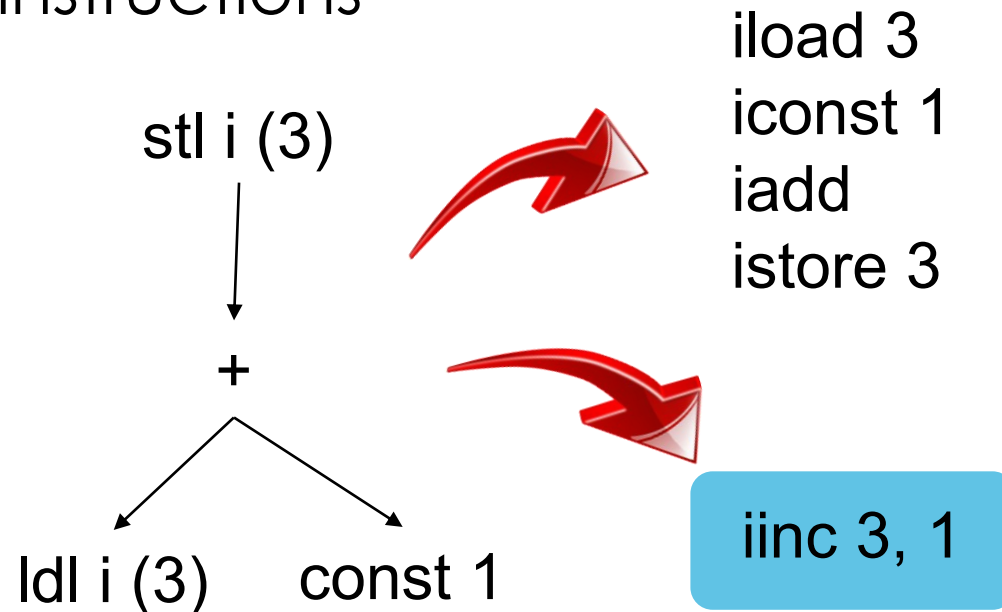


# Instruction Selection Overview

Find the best cover/tile

- The one that gives the instruction sequence of least cost
- Least cost == the shortest sequence of instructions

Not always!



# Instruction Selection Overview

- Each tree pattern can be assigned with a cost
  - Problem is to cover/tile the trees of the program achieving the minimum cost
- However, this simple cost model does not take into account the possible interactions between instructions
- Target machines with reduced instruction set (RISC) have simple tree patterns
  - simple instruction selection algorithms are sufficient

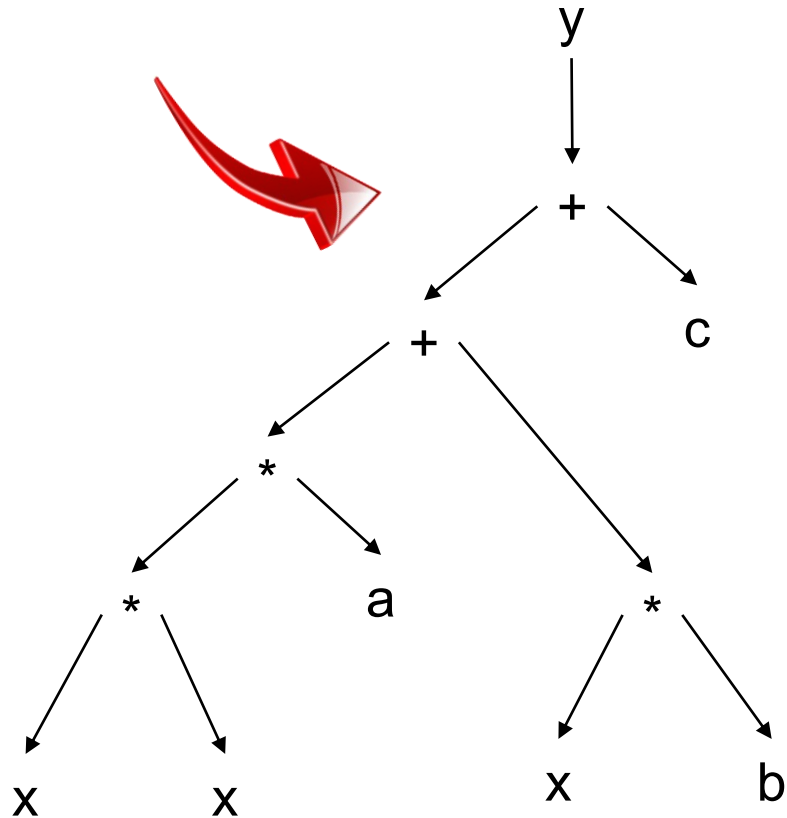


# Instruction Selection: Maximal Munch

- A simple algorithm that finds an optimal tiling: Maximal Munch (greedy, top-down pattern match)
  - Starting at the root of the tree
  - Find the largest tile that fits (the tile with most nodes)
  - Cover the root node and the possible nodes with this tile
  - Repeat the algorithm for each subtree of the tile until all the tree is tiled
  - For each tile generates the instructions of that tile
    - code generation is performed in reverse order, least instruction firsts

# Instruction Selection: Maximal Munch

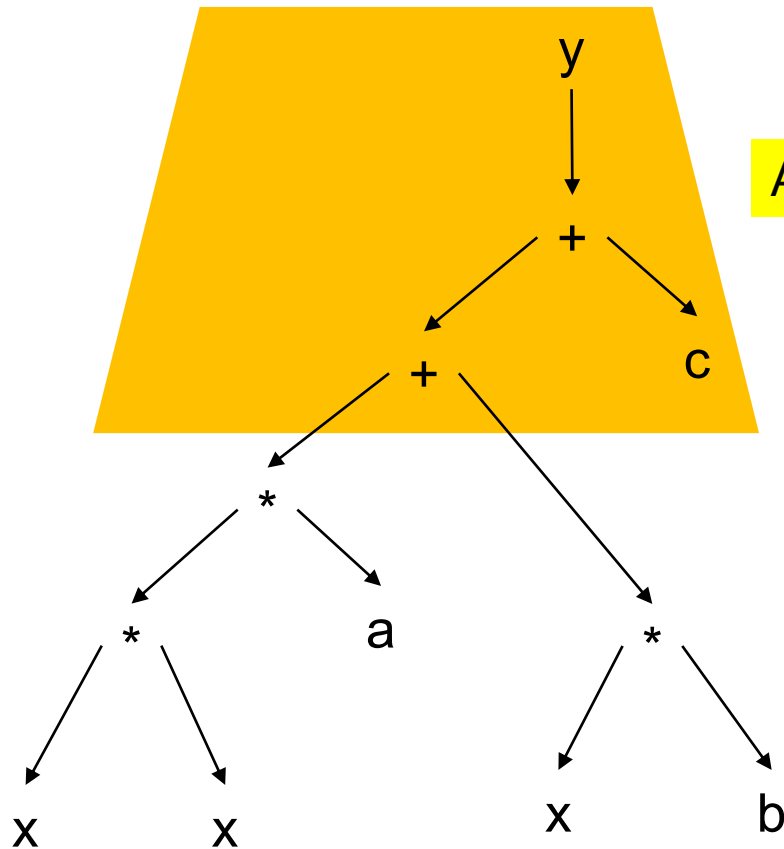
Example:  $y = a * x * x + b * x + c$ ;



Instruction	function	cost
ADD2 (A2)	$a \leftarrow b + c$	1
ADD3 (A3)	$a \leftarrow b + c + d$	2
MUL2 (M2)	$a \leftarrow b * c$	4
MUL3 (M3)	$a \leftarrow b * c * d$	7
MADD (MA)	$a \leftarrow b * c + d$	4

# Instruction Selection: Maximal Munch

➤  $y = a * x * x + b * x + c;$

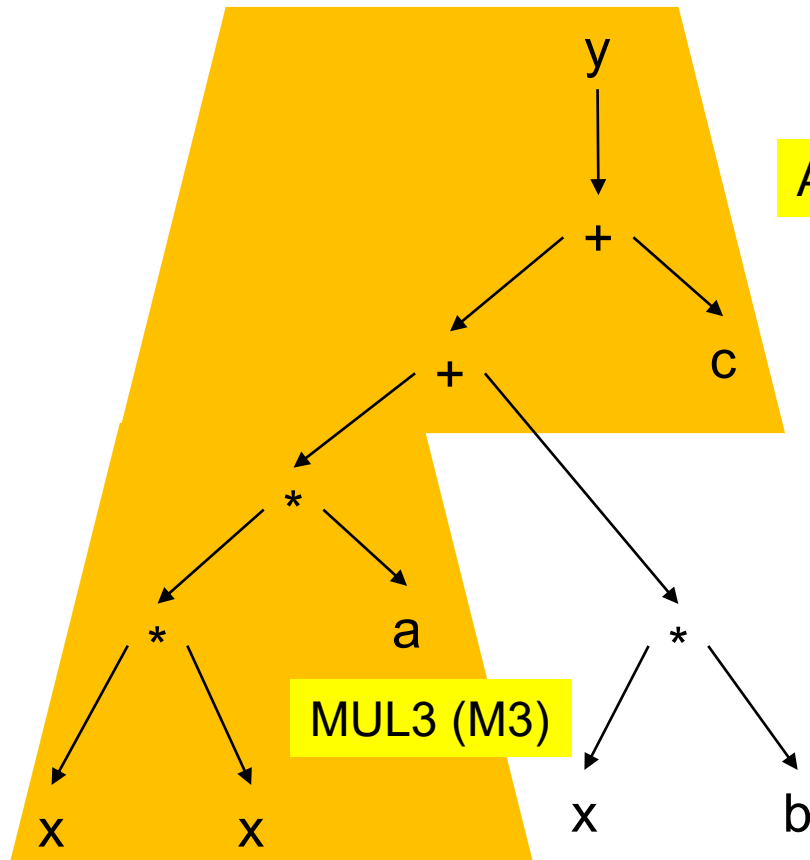


ADD3 (A3)

Instruction	function	cost
ADD2 (A2)	$a \leftarrow b + c$	1
ADD3 (A3)	$a \leftarrow b + c + d$	2
MUL2 (M2)	$a \leftarrow b * c$	4
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# Instruction Selection: Maximal Munch

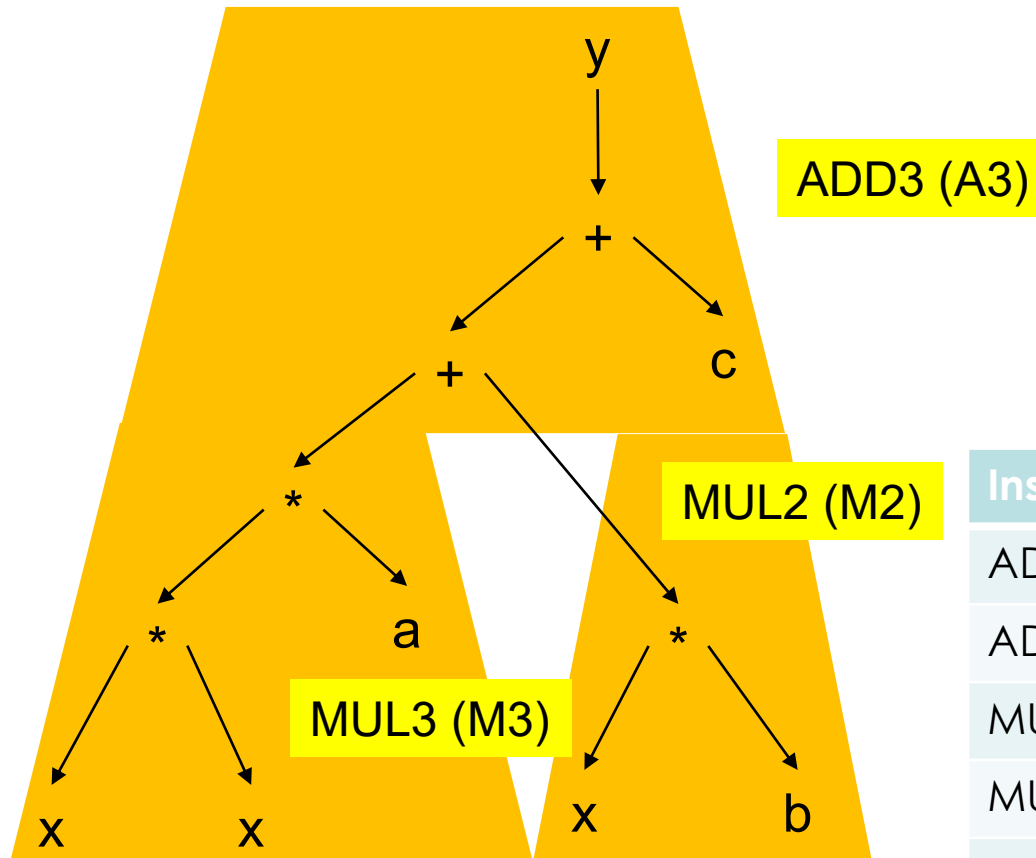
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# Instruction Selection: Maximal Munch

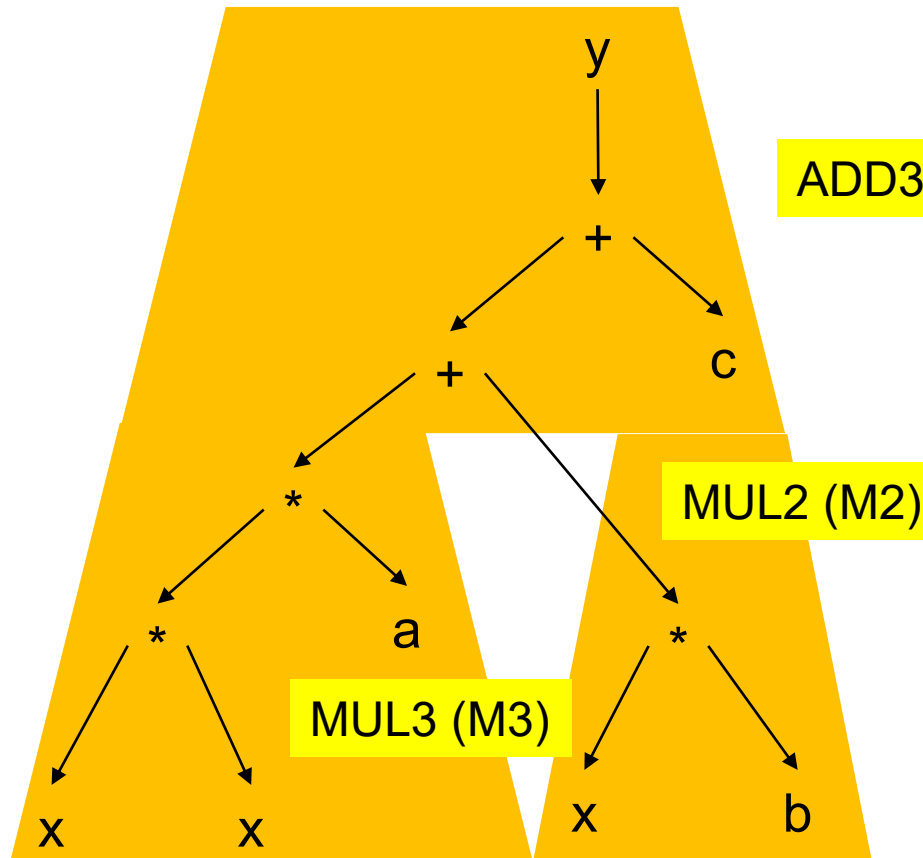
➤  $y = a * x * x + b * x + c;$



Instruction	function	cost
ADD2 (A2)	$a \leftarrow b + c$	1
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# Instruction Selection: Maximal Munch

➤  $y = a * x * x + b * x + c;$



ADD3 (A3)

MUL2 (M2)

MUL3 (M3)

ADD3 (A3)

Cost = 4+7+2  
= 13

Instruction	function	cost
ADD2 (A2)	$a \leftarrow b + c$	1
ADD3 (A3)	$a \leftarrow b + c + d$	2
MUL2 (M2)	$a \leftarrow b * c$	4
MUL3 (M3)	$a \leftarrow b * c * d$	7
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# Instruction Selection: Maximal Munch

- Maximal Munch does not give the tiling with the minimum cost:
  - It decides locally about the largest pattern to fit, this might prevent the tiling of large patterns in the subtrees
- Gives optimal tiling, i.e., no adjacent tiles can form a tile with lower cost
- One possible solution to achieve minimum cost (i.e., tiling with minimum global cost)
  - Dynamic Programming

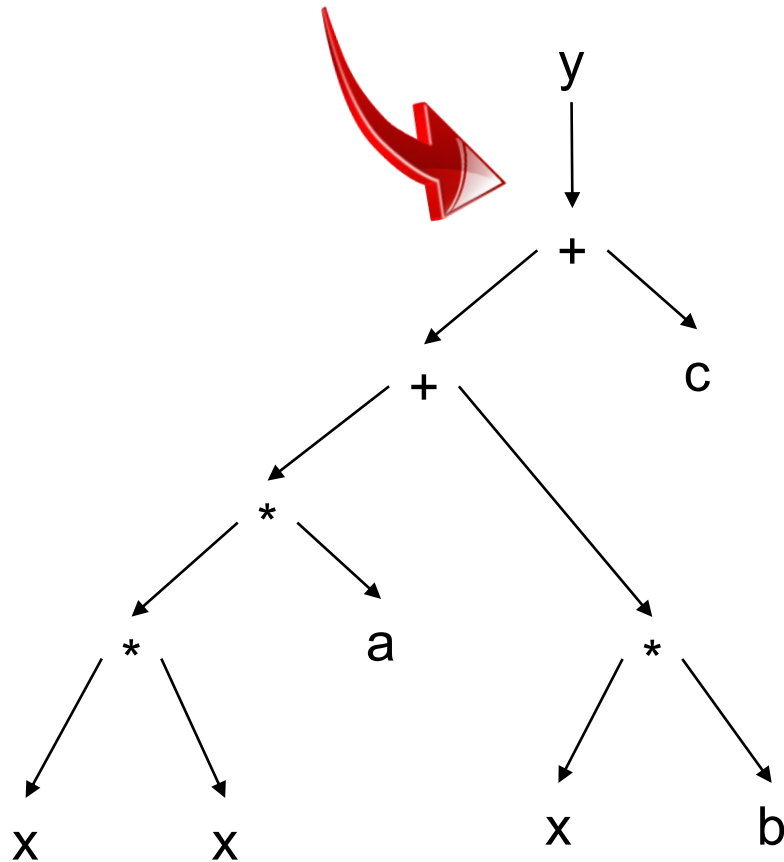
# Instruction Selection: Dynamic Programming

- Bottom-Up Exhaustive Cataloging of Optimum Solutions
- Optimum Solution of Node Based on Optimum Solution of Subnodes
- Delivers the Global Optimum
- Very Efficient
  - Used in, e.g., Twig, and BURG



# Dynamic Programming Example

➤  $y = a * x * x + b * x + c;$

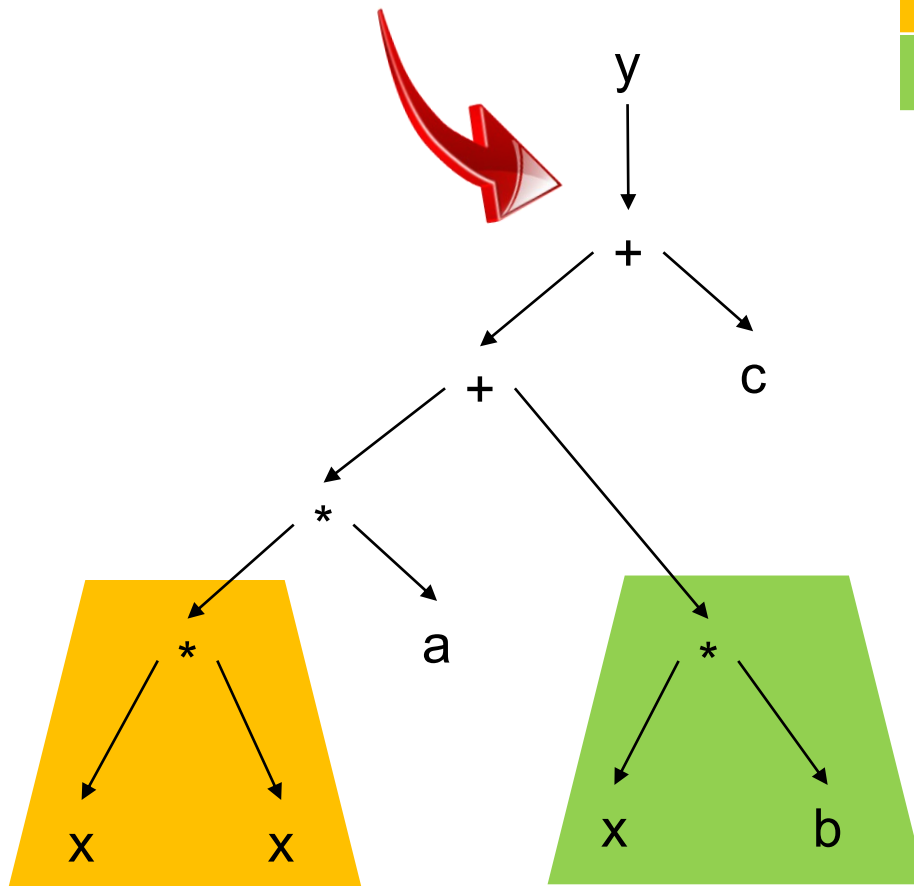


Start at the bottom and tile the first nodes  
Select the tiles with minimum costs

Instruction	function	cost
ADD2 (A2)	$a \leftarrow b + c$	1
ADD3 (A3)	$a \leftarrow b + c + d$	2
MUL2 (M2)	$a \leftarrow b * c$	4
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# Dynamic Programming Example

➤  $y = a * x * x + b * x + c;$



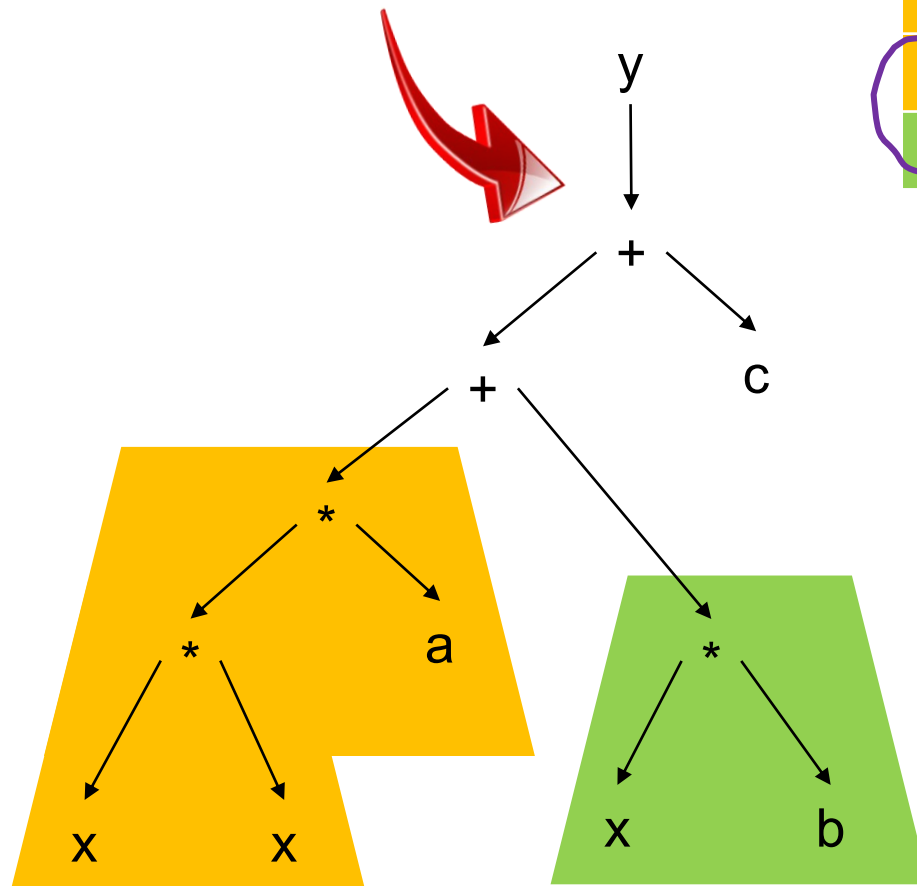
Instructions	Instruction	cost	Leaves cost	total
M2	M2	4	0	4
M2	M2	4	0	4

Go to the next node and tile the subtree with that node as the root

Instruction	function	cost
ADD2 (A2)	$a \leftarrow b + c$	1
ADD3 (A3)	$a \leftarrow b + c + d$	2
MUL2 (M2)	$a \leftarrow b * c$	4
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# Dynamic Programming Example

➤  $y = a * x * x + b * x + c;$



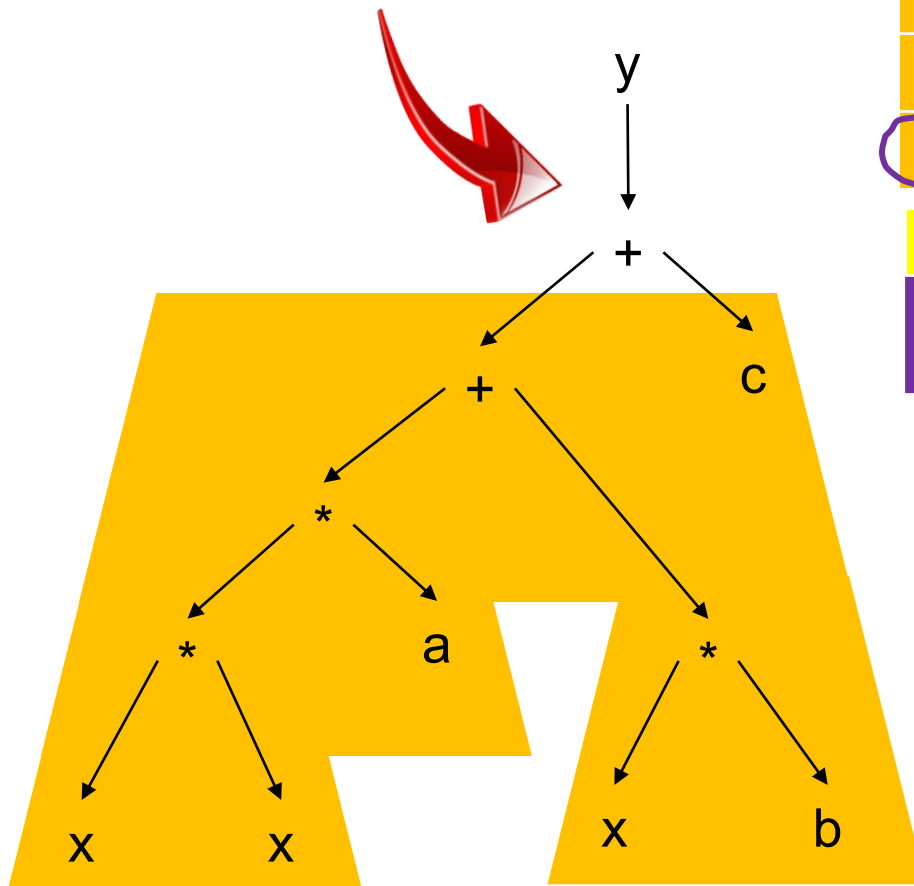
Instructions	Instruction	cost	Leaves cost	total
M2-M2	M2	4	4	8
M3	M3	7	0	7
M2	M2	4	0	4

minimum costs for the subtrees represented as orange and green regions

Instruction	function	cost
ADD2 (A2)	$a \leftarrow b + c$	1
ADD3 (A3)	$a \leftarrow b + c + d$	2
MUL2 (M2)	$a \leftarrow b * c$	4
MUL3 (M3)	$a \leftarrow b * c * d$	7
MADD (MA)	$a \leftarrow b * c + d$	4

# Dynamic Programming Example

➤  $y = a * x * x + b * x + c;$



Instructions	Instruction	cost	Leaves cost	total
M3-A2, M2	A2	1	11	12
M2-MA, M2	MA	4	8	12
M3-MA	MA	4	7	11

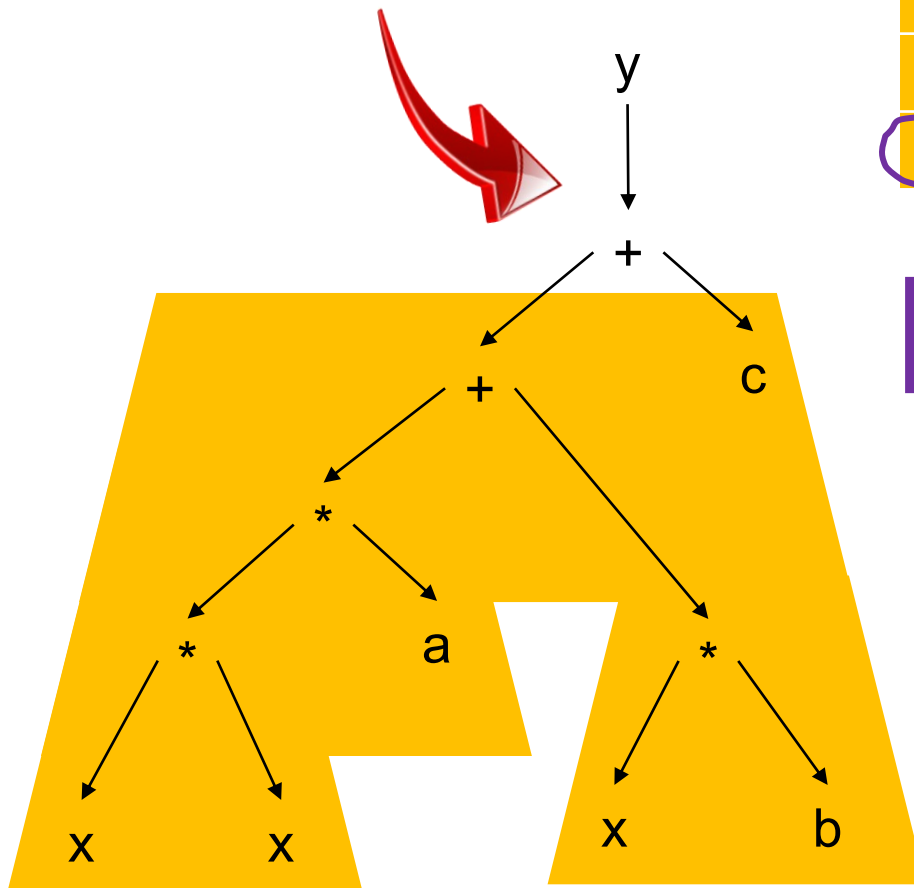
Tile not considered as it uses non-optimal subtree tiles:

M2-M2-A2, M2	A2	1	12	13
--------------	----	---	----	----

Instruction	function	cost
ADD2 (A2)	$a \leftarrow b + c$	1
ADD3 (A3)	$a \leftarrow b + c + d$	2
MUL2 (M2)	$a \leftarrow b * c$	4
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# Dynamic Programming Example

➤  $y = a * x * x + b * x + c;$



Instructions	Instruction	cost	Leaves cost	total
M3-A2, M2	A2	1	11	12
M2-MA, M2	MA	4	8	12
M3-MA	MA	4	7	11

M2-M2-A2,  
M2

A2

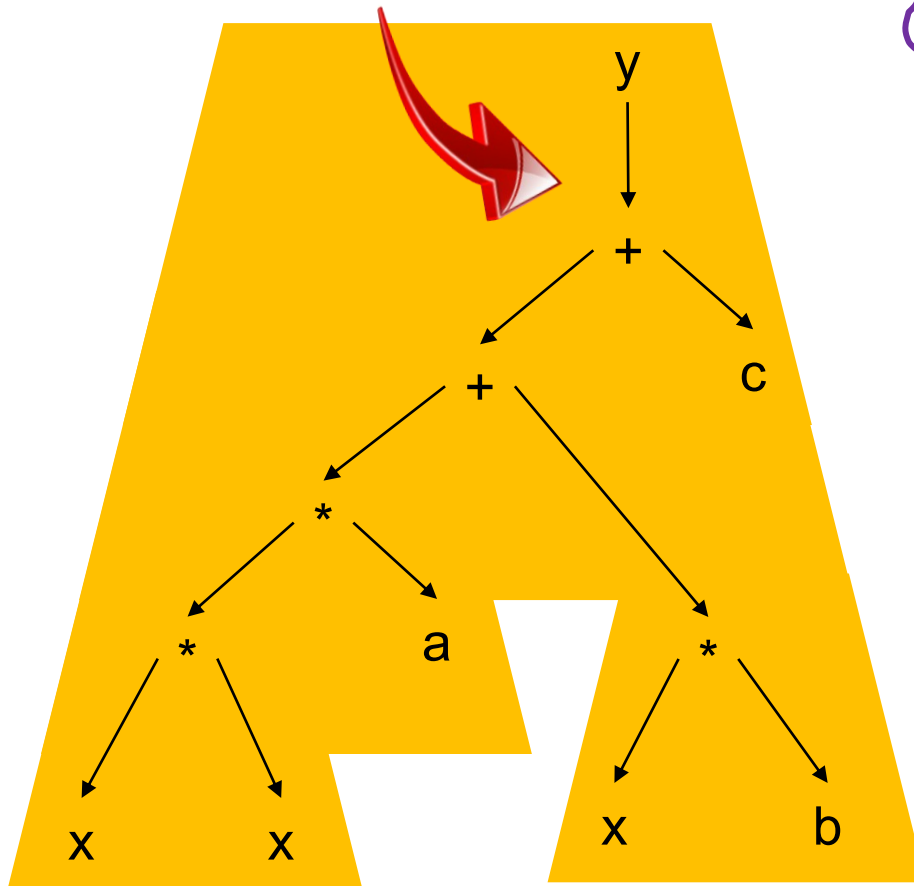
considering the  
commutativity of the  
addition in MA

13

Instruction	function	cost
ADD2 (A2)	$a \leftarrow b + c$	1
ADD3 (A3)	$a \leftarrow b + c + d$	2
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# Dynamic Programming Example

➤  $y = a * x * x + b * x + c;$

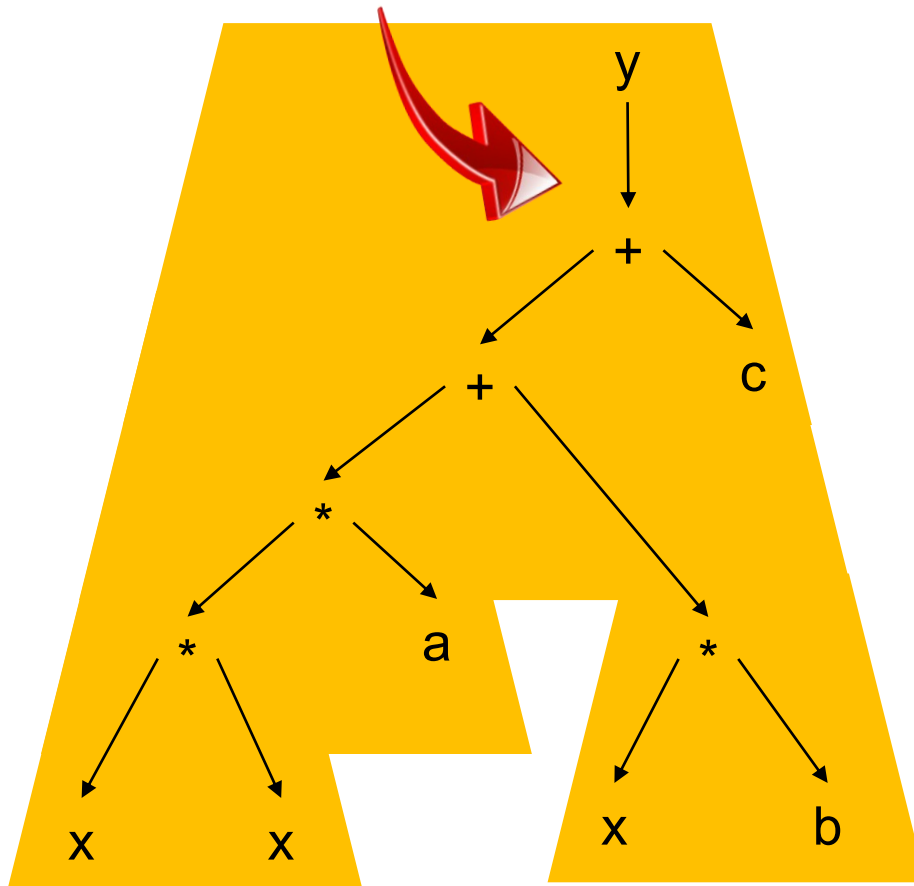


Instructions	Instruction	cost	Leaves cost	total
M3-A3, M2	A3	2	11	13
M3-MA-A2	A2	1	11	12

Instruction	function	cost
ADD2 (A2)	$a \leftarrow b + c$	1
ADD3 (A3)	$a \leftarrow b + c + d$	2
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# Dynamic Programming Example

➤  $y = a * x * x + b * x + c;$



Tiles not considered as they use non-optimal subtree tiles:

M2-M2-A2-A2, M2	A2	1	13	14
M2-M2-A3, M2	A3	2	12	14
M3-A2-A2, M2	A2	1	12	13
M2-MA-A2, M2	A2	1	12	13
M2-M2-A2-A2, M2	A2	1	13	14

Instruction	function	cost
ADD2 (A2)	$a \leftarrow b + c$	1
ADD3 (A3)	$a \leftarrow b + c + d$	2
MUL2 (M2)	$a \leftarrow b * c$	4
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# Other Approaches

- Graham-Glanville Parser-Based Approach
- Naive/Canonical Generation
  - Transform each node in the equivalent sequence of machine instructions
  - Can be followed by Peephole optimization



# EXERCISE

# Exercise

- Consider a microprocessor with the following instructions:
  - $\text{ADD } rd = rs1 + rs2$
  - $\text{ADDI } rd = rs + c$
  - $\text{SUB } rd = rs1 - rs2$
  - $\text{SUBI } rd = rs - c$
  - $\text{MUL } rd = rs1 * rs2$
  - $\text{DIV } rd = rs1 / rs2$
  - $\text{LOAD } rd = M[rs + c]$
  - $\text{STORE } M[rs1 + c] = rs2$
  - $\text{MOVEM } M[rs1] = M[rs2]$
- Where  $rd, rs$  identify registers of the architecture (from  $r0$  to  $r31$  and  $r0$  stores the non-modified value 0) and  $c$  identifies literals

# Exercise

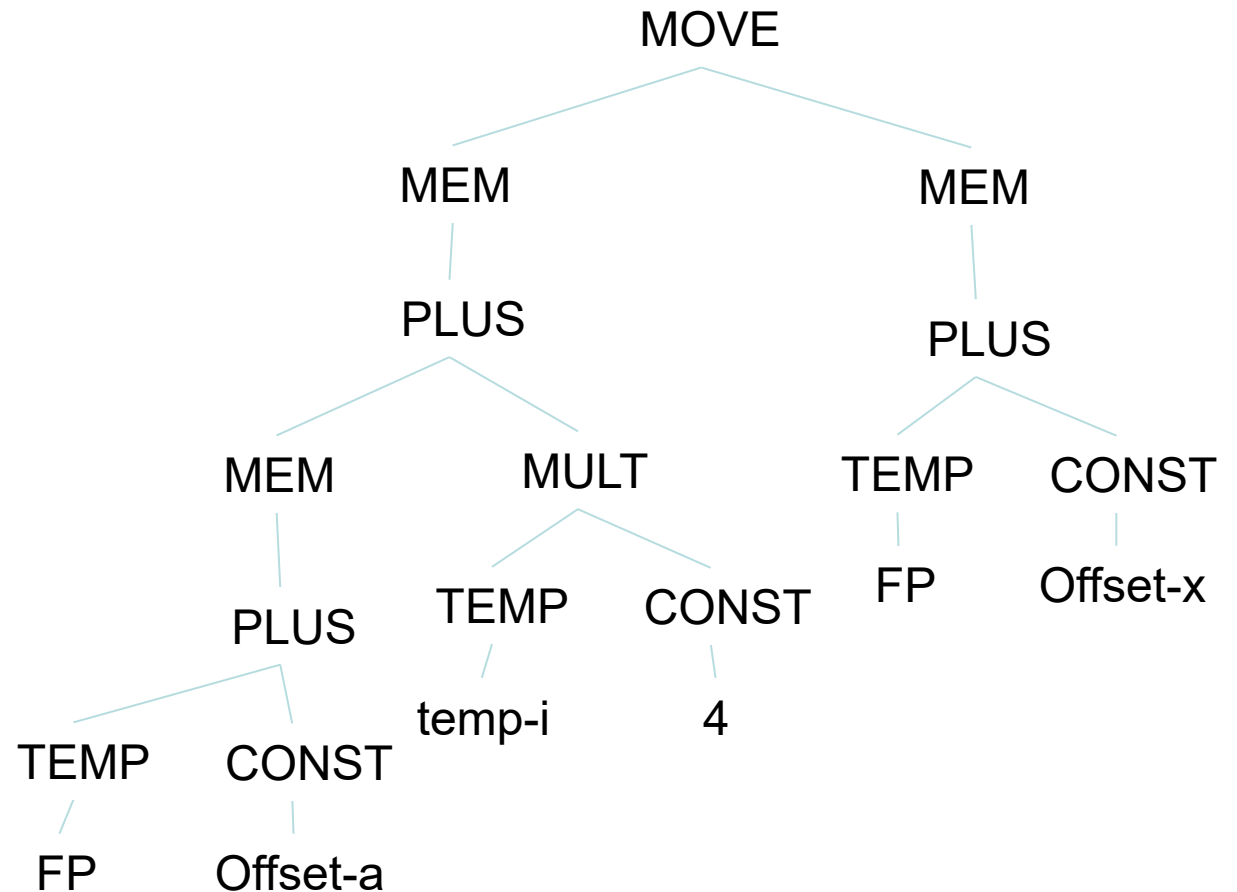
➤ The corresponding Instruction Tree Patterns are the following:

Instruction	Effect	IR Tree Pattern
—	$r_i$	TEMP   $r_i$
add	$r_i \leftarrow r_j + r_k$	+ / \
mul	$r_i \leftarrow r_j * r_k$	*
sub	$r_i \leftarrow r_j - r_k$	-
div	$r_i \leftarrow r_j / r_k$	/
addi	$r_i \leftarrow r_j + c$	+ / \    + CONST    CONST    CONST             c    c    c
subi	$r_i \leftarrow r_j - c$	- / \ CONST   c

Instruction	Effect	IR Tree Pattern
load	$r_i \leftarrow M[r_j + c]$	MEM    MEM    MEM    MEM +    +    CONST      / \    / \           CONST    CONST    c    c
store	$M[r_j + c] \leftarrow r_i$	MOVE    MOVE    MOVE    MOVE MEM    MEM    MEM    MEM +    +    CONST      / \    / \           CONST    CONST    c    c
movem	$M[r_j] \leftarrow M[r_i]$	MOVE MEM    MEM 

# Exercise

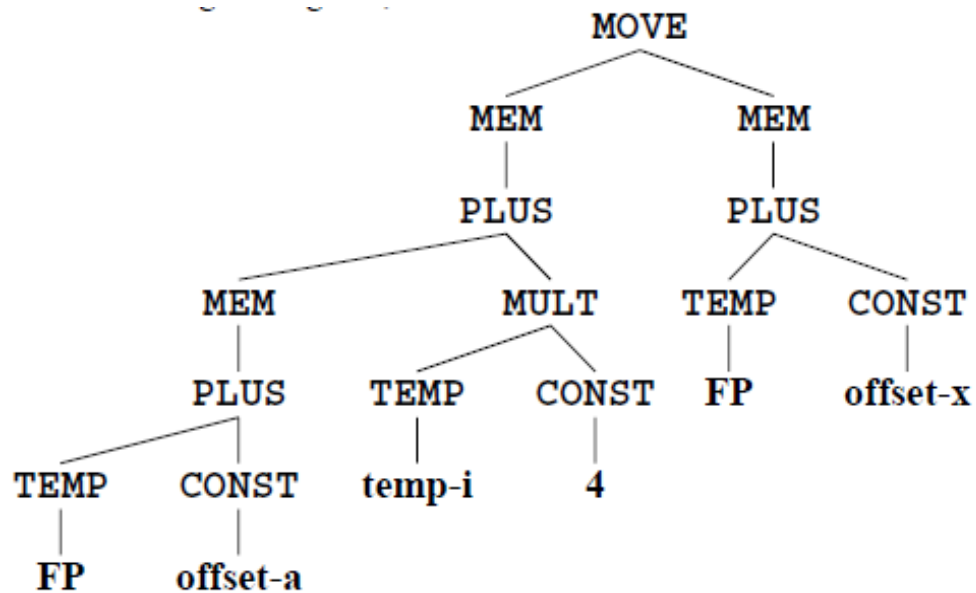
- Consider the input intermediate representation illustrated below for the statement:  $a[i] = x$ ; (assuming  $i$  stored in a register identified by  $r_i$ , and  $a$  and  $x$  are frame residents), where  $FP$  represents the register with the frame pointer,  $offset-a$  and  $offset-x$  represent two constants, and  $temp-i$  identifies the variable  $i$ .



# Exercise

- a) Use individual node selection to generate the assembly instructions.
- b) Use the Maximal-Munch algorithm for instruction selection and write the instructions generated.
- c) Use dynamic programming to obtain an optimum solution for instruction selection (considering as goal the minimum number of instructions) and write the instructions generated.

- Consider the input intermediate representation illustrated below for the statement:  $a[i] = x$ ; (assuming  $i$  stored in a register identified by  $r_i$ , and  $a$  and  $x$  are frame residents), where  $FP$  represents the register with the frame pointer,  $offset-a$  and  $offset-x$  represent two constants, and  $temp-i$  identifies the variable  $i$ .



Instruction	Effect	IR Tree Pattern
load	$r_i \leftarrow M[r_j + c]$	
store	$M[r_j + c] \leftarrow r_i$	
movem	$M[r_j] \leftarrow M[r_i]$	

Instruction	Effect	IR Tree Pattern
—	$r_i$	
add	$r_i \leftarrow r_j + r_k$	
mul	$r_i \leftarrow r_j * r_k$	
sub	$r_i \leftarrow r_j - r_k$	
div	$r_i \leftarrow r_j / r_k$	
addi	$r_i \leftarrow r_j + c$	
subi	$r_i \leftarrow r_j - c$	