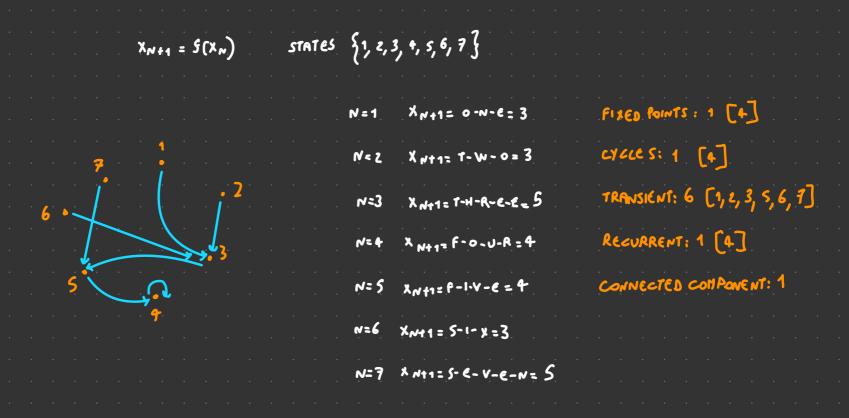


**EXERCISE** Consider an iterated map  $x_{n+1} = f(x_n)$ , with states  $\{1, 2, 3, 4, 5, 6, 7\}$ . The function f(x) computes its values by the following algorithm:

- 1. Take the string of characters that expresses the number x in English (e.g.,  $5 \leadsto$  "five').
- 2. Count the number of letters in the string; this is the value returned by the function (e.g., "five"  $\rightsquigarrow$  4).

Find the fixed points, cycles, transient and recurrent states of this dynamics. How many connected components are there?



**EXERCISE** Consider the same function f as in the previous exercise, but now the set of possible states is  $\{0,1,2,3,4\}$ . Does f represent the update rule of a dynamical system on this set of states?



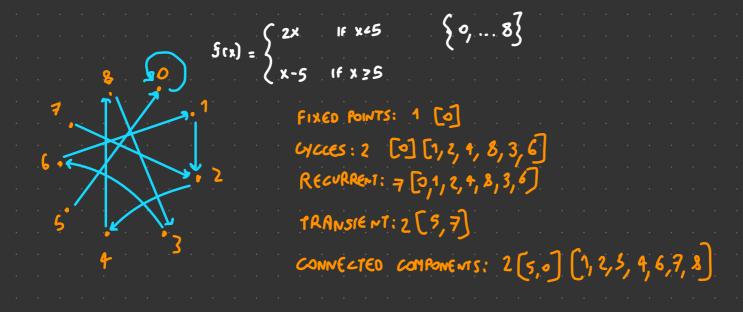
**EXERCISE** Consider the iterated map  $x_{n+1} = f(x_n)$ , in the state space  $\{0, 1, 2, 3, 4, 5, 6, 7, 8\}$ , with

$$f(x) = \begin{cases} 2x & \text{if } x < 5\\ x - 5 & \text{if } x \ge 5 \end{cases}$$

Find the fixed points, cycles, transient and recurrent states. How many connected components are there? Consider the function

$$Q(x) = 5x \mod 5$$

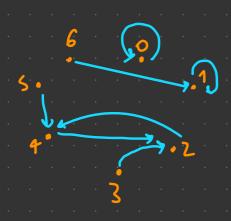
Is this a conserved quantity for the dynamics? Is it a non-trivial conserved quantity?



**EXERCISE** Consider the iterated map  $x_{n+1} = f(x_n)$ , with

$$f(x) = x^2 \mod 7,$$

where  $x \in \{0, 1, 2, 3, 4, 5, 6\}$ . How many connected components are there? Can you write down a non-trivial conserved charge?



FIXED POINTS: 2 [0] [1]

cycces: 3. (0][1][4,2]

RECURRENT: 4 (0)[1][+][2]

TRANSIENT: 3 [6][5][3]

CONNECTED COMPONENTS: 3 [0][1][5,4,3,2]

$$Q(x) = \begin{cases} 0 & \text{if } x=0 \\ 1 & \text{if } x \neq 0 \end{cases}$$

**EXERCISE** Consider the iterated map  $x_{n+1} = f(x_n)$  in the (infinite) set  $\mathbb{N} = \{0, 1, 2, \ldots\}$  with

$$f(x) = x + k$$

where the parameter  $k \geq 2$  is an integer. Describe the dynamics (cycles, etc.) Can you construct a non-trivial conserved quantity?

HINT: If the exercise seems too difficult, try considering the special case k=2 first; then see if and how the picture changes when k > 2.

K=2

TRANSIENT: N

CONNECTED COMPONENTS: 2

TRANSIENT: IN CONNECTED COMPONENTS: 3

FIXED POINTS: \$

- Cycles:  $\phi$ RECURRENT:  $\phi$ 

TRANSIENT: N

CONNECTED COMPONENTS: X

**EXERCISE** [difficult] Consider the iterated map  $x_{n+1} = f(x_n)$  in the (infinite) set  $\mathbb{N} = \{0, 1, 2, \ldots\}$  with

$$f(x) = kx,$$

where the parameter  $k \geq 2$  is an integer. Describe the dynamics (cycles, etc.)

$$X_{N+1} = 5(X_N)$$
  $N = \{0, 1, 2, \dots, 5\}$ 

K = 2



FIXED POINTS: 1 [0]

Cycles: 1[0]

RECURRENT: 1 [0]

TRANSIENT: IN - { 0 }

CONNECTED COMPONENTS: IN/2 + 1 < >0



**EXERCISE** Consider the dynamical system  $x_{n+1} = f(x_n)$ , with

$$f(x) = \sin(\pi x)$$

The dynamics has 2 fixed points. Linearize around the smaller fixed point  $\bar{x}$ . Regarding the stability of  $\bar{x}$ , which one of the following 4 possibilities is realized?

- (a)  $\bar{x}$  is stable (not a spiral)
- (b)  $\bar{x}$  is a stable spiral
- (c)  $\bar{x}$  is unstable (not a spiral)
- (d)  $\bar{x}$  is an unstable spiral

FIND FIXED POINT: (EQUAL TO ITSECF)

$$\overline{X} = SW(\overline{\Pi}\overline{X})$$
;  $\bigcirc$   $SIW(\bigcirc)$ 

DO THE DEANATE

LINEARIZE  $S(x) = SIW(\overline{\Pi}x)$   $\Rightarrow S'(x) = \pi cos(\pi x)$ 
 $S'(o) = \pi cos(o) = \pi$ 

NOT SPIRAL  $\Rightarrow$  UNSTAKE

$$f(x) = \frac{1}{\alpha x + 1}$$

with state  $x \ge 0$  and parameter  $\alpha > 0$ . Show that the dynamical system  $x_{n+1} = f(x_n)$  has a single fixed point, which is always a stable spiral.

## 1) FIND FIXED POINT: \$ = 5(\$)

$$\bar{x} = \frac{1}{\omega \bar{x} + 1} = 0$$
  $\Delta = 6^2 + Ac = 1 - 4(\omega)(H) = 1 - 4\omega$ 

$$x_{1,2} = \frac{-1!\sqrt{1-4\omega}}{2\omega}$$

= -1+ \1-+a

## 2) DERIVATE

$$5(x) = \frac{1}{\omega x + 1} = (\omega x + 1)^{-1} \qquad \frac{d}{dx} \qquad x^3 = 3x^2$$

$$S'(x) = -10 \left(\omega x + 1\right)^{-2} = \left(\frac{-\omega}{\omega x + 1}\right)^{2}$$

## 3) SUBSTITUTE X

$$5'(x) = \frac{-\omega}{(\omega)^{\frac{-1+\sqrt{1-4\omega}}{2\omega}}} + 1$$

$$2 = \frac{\omega}{(\sqrt{1-4\omega} + \frac{1}{2})^{2}} = \frac{\omega}{(\sqrt{1-4\omega} + \frac{1}{4} + \frac{2\sqrt{1-4\omega}}{2} \cdot \frac{1}{2})}$$

$$= \frac{\omega}{(\sqrt{1-4\omega} + \frac{1}{4} + \frac{2\sqrt{1-4\omega}}{2} \cdot \frac{1}{2})}$$

$$= \frac{4\omega}{(2-4\omega + 2\sqrt{1-4\omega})}$$

## EXERCISE Consider the dynamical system obtained by iteration of the logistic map

$$f(x) = rx(1-x),$$

with state  $x \in [0,1]$  and parameter  $r \in [0,4]$ . Obtain analytically the critical values  $r_1 = 1$ ,  $r_2 = 2$ ,  $r_3 = 3$ , that separate the following 3 regimes of the dynamical system  $x_n = f(x_{n-1})$ :

- $0 < r < r_1 x_n$  converges to 0
- $r_1 < r < r_2 x_n$  converges to (r-1)/r monotonically
- $r_2 < r < r_3 x_n$  converges to (r-1)/r with oscillations

General O 5'(0)=+ > x STABLE FOR + ++=1

