$$A = \begin{bmatrix} \omega_{11} & \omega_{12} & \omega_{13} & \cdots & \omega_{1n} \\ \omega_{21} & \omega_{22} & \omega_{23} & \cdots & \omega_{2n} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ \omega_{n1} & \omega_{n2} & \omega_{n3} & \cdots & \omega_{nn} \end{bmatrix} \qquad \begin{cases} b = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix} & b \in \mathbb{R}^m \end{cases}$$

$$A = \begin{bmatrix} \omega_{11} & \omega_{12} & \omega_{13} & \cdots & \omega_{1n} \\ \omega_{21} & \omega_{22} & \omega_{23} & \cdots & \omega_{2n} \\ \vdots & \vdots & \vdots & \vdots \\ \omega_{n1} & \omega_{n2} & \omega_{n3} & \cdots & \omega_{nn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}$$

$$\begin{bmatrix} \omega_{11}x_1 + \omega_{12}x_2 + \cdots + \omega_{1n}x_n \\ \vdots \\ \omega_{21}x_1 + \omega_{22}x_2 + \cdots + \omega_{2n}x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}$$

$$\begin{bmatrix} \omega_{11}x_1 + \omega_{12}x_2 + \cdots + \omega_{1n}x_n \\ \vdots \\ \omega_{1n}x_1 + \omega_{1n}x_1 + \cdots + \omega_{1n}x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}$$

$$\begin{bmatrix} \omega_{11}x_1 + \omega_{12}x_2 + \cdots + \omega_{1n}x_n \\ \vdots \\ \omega_{1n}x_1 + \omega_{1n}x_1 + \cdots + \omega_{1n}x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}$$

$$\begin{bmatrix} \omega_{11}x_1 + \omega_{12}x_2 + \cdots + \omega_{1n}x_n \\ \vdots \\ \omega_{1n}x_1 + \omega_{1n}x_1 + \cdots + \omega_{1n}x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}$$

$$\begin{bmatrix} \omega_{11}x_1 + \omega_{12}x_2 + \cdots + \omega_{1n}x_n \\ \vdots \\ \omega_{1n}x_1 + \omega_{1n}x_1 + \cdots + \omega_{1n}x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}$$

$$\begin{bmatrix} \omega_{11}x_1 + \omega_{12}x_2 + \cdots + \omega_{1n}x_n \\ \vdots \\ \omega_{1n}x_1 + \omega_{1n}x_1 + \cdots + \omega_{1n}x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}$$

THEOREM THE PROBLEM SEARCH FOR X EIRN THAT SATISFY AX = 6 IS EQUIVACENT (THE SOCUTION ARE

THE SAME) TO THE LINEAR SYSTEM ASSOCIATED TO THE AUGMENTED MATRIX [A]6

A
$$\in IR^{4\times 3}$$

A:
$$\begin{bmatrix}
3 & -1 & 0 \\
6 & 6 & 3 \\
-2 & 1 & -4 \\
0 & 0 & 5
\end{bmatrix}$$
SERRCH FOR $\times \in IR^3$ S.T. $A \times = b$

$$\begin{bmatrix}
0 \\
-2 \\
3 \\
1
\end{bmatrix}$$

$$\begin{bmatrix}
3 \times_{1} + - \times_{2} + 0 \times_{3} = 0 \\
6 \times_{1} + 6 \times_{2} + 3 \times_{3} = -2 \\
-2 \times_{1} + \times_{2} - 4 \times_{3} = 3
\end{bmatrix}$$

$$\begin{bmatrix}
3 & -1 & 0 & 0 \\
6 & 6 & 3 & -2 \\
-2 \times_{1} + 4 & 2 & -4 \times_{3} = 3
\end{bmatrix}$$

$$\begin{bmatrix}
0 & 0 & 9 & 1
\end{bmatrix}$$

SEARCH X EIR AEIR MXN GEIRM

Ax = 6

THIS LINEAR SYSTEM WELL HAVE (AT LEAST) A SOLUTION X?

IFF 6 IS A LINEAR COMBINATION OF THE COWMS OF A \ \201, 002 ... 000 of A

b is the span { \omega_1, \omega_2, \dots \frac{\omega_1}{\omega_1}}

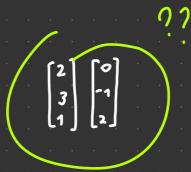
$$\begin{bmatrix} 2 & 0 \\ 3 & -1 \end{bmatrix} = A \qquad b \in \mathbb{R}^3 \qquad \begin{bmatrix} 1 \\ 7 \\ 2 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 2 \end{bmatrix}$$

$$\begin{cases} 2 & 0 & 1 \\ 1 & 2 & 2 \end{bmatrix}$$

$$S \in ARCH \qquad \stackrel{!}{\sim} \in \mathbb{R}^2 \qquad A \times = 6$$

$$\begin{bmatrix} 2 & 0 & 1 \\ 3 & -1 & 7 \\ 1 & 2 & 2 \end{bmatrix}$$



 $A = \left[\underline{\alpha_1}, \underline{\alpha_2}, \underline{\alpha_3}, \dots \underline{\alpha_N} \right] \underline{\alpha_1}, \underline{\alpha_2}, \dots \underline{\alpha_N} \in \mathbb{R}^N$ Ax = 01 x1 + 02 x2+... + 0, x1 = 6

LET A EIR THEN THE FOLLOWING STATEMENTS ARE EQUIVALENT THEOREM

- THE LINEAR SYSTEM HAS AT LEAST ONE SOCUTION FOR EACH GEIRN
- ANY GERN IS A LINEAR COMBINATION OF THE COLUMNS OF A
- THE SPAM & DUJ, DUZ, ... DUNG OF THE COLUMS OF A IS EQUAL TO THE WHOLE IR
- IF A LSO 6 IS O I CAN NOT · EVERY ROW of A HAS A PIVOT POSITION (OR IS A ROW OF O) CONSIDER THAT ROW, BUT IF

FREE VARIABLE, INFINITE SOLUTION

IT ALWAYS EXISTS ATLEAST A SOLUTION

IF EVERY COLUM OF A HAS A PIVOT POSITION THEN THE O + * * O SOCUTION IS UNIQUÉ (ONCY X = 2)

O O THERWISE IF AT LEAST ONE COLUM OF A DOES NOT MAVE

O O O TO TO THERE ARE INFINITE SOCUTION (INC A PIVOUT POSITION THEN THERE ARE INFINITE SOCUTION (INCLUDING X = 9)

A =
$$\begin{bmatrix} 1 & -2 & 1 \\ 0 & 3 & 6 \\ 2 & -4 & 2 \end{bmatrix}$$
 WHAT ARE THE SOCUTION $\underline{x} \in \mathbb{R}^3$ of $A\underline{x} = \underline{9}$?

in echelon form AUGMENTED MATRIX

$$\begin{bmatrix} 1 & -2 & 1 & 0 \\ 0 & 3 & 6 & 0 \\ 2 & -4 & 2 & 0 \end{bmatrix} \begin{bmatrix} 1 & -2 & 1 & 0 \\ 0 & 3 & 6 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$
one or infinite Socutions?

NO PIVOT POSITION ON X3 => X3 IS A FREE VARIABLE X3EIR INFINITE SOCUTION

$$\begin{cases} 3^{1}z^{2} + 6^{1}x_{3} = 0 & \text{if } X_{2} = -2^{1}x_{3} \\ X_{1} - 2^{1}x_{2} + X_{3} = 0 & \text{if } X_{1} = 2^{1}x_{2} - X_{3} & \text{if } X_{2} = -2^{1}x_{3} \\ X_{2} = -2^{1}x_{3} & \text{if } X_{3} = 0 \end{cases}$$

$$Ax = 0 \times \epsilon IR^4$$

$$2^{NO} \left(\frac{2 \times 3}{2} - \frac{2 \times 4}{4} \right)$$

$$1^{ST} \left(\frac{1}{4} + \frac{2 \times 2}{4} + \frac{3 \times 4}{4} + \frac{2}{5} \right) \times 1^{\frac{1}{2} - \frac{2}{4} \times 4} \times 1^{\frac{1}{2} - \frac{2}{4} \times 1^{\frac{1}{2} - \frac{2}{4} \times 4} \times 1^{\frac{1}{2} - \frac{2}{4} \times 1^{\frac{1}{2} - \frac{2}{4} \times 4} \times 1^{\frac{1}{2} - \frac{2}{4} \times 1^{\frac{1}{2} - \frac{2}{4} \times 4} \times 1^{\frac{1}{2} - \frac{2}{4} \times 1^{\frac{1}{2} - \frac{2}{4$$

$$\begin{cases} x_{1} = -2x_{2} - \frac{5}{2}x_{4} \\ x_{2} \in \mathbb{R} \\ x_{3} = \frac{1}{2}x_{4} \\ x_{4} \in \mathbb{R} \end{cases} \times \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \end{bmatrix} \times_{2} + \begin{bmatrix} -\frac{5}{2} \\ 0 \\ \frac{1}{2} \\ 1 \end{bmatrix} \times_{4}$$

$$x \in \mathbb{R}^N$$
 x socution of $6x = 6$

$$A(x + y) = Ax + Ay = 6 + 0 = 6$$

AEIR MXN GEIRM THEOREM ALL SOCUTIONS XEIR OF AX = 6 CAN BE EXPRESSED AS V+ Y WHERE Y IS ANY DNE PARTICULAR SO CUTION OF THE SYSTEM (AY=6) AND YERR IS ANY SOLUTION OF THE HOMO CENEOUS LINEAR SYSTEM AY=0

€x1.

$$\begin{bmatrix} 1 & -2 & 1 \\ 0 & 3 & 6 \\ 2 & -4 & 2 \end{bmatrix} = A \qquad \frac{6}{2} = \begin{bmatrix} 2 \\ 6 \\ 4 \end{bmatrix}$$

AVENTED MATRIX

$$\begin{bmatrix} 1 & -2 & 1 & 2 \\ 0 & 3 & 6 & 6 \\ 2 & -4 & 2 & 4 \end{bmatrix} \xrightarrow{1ST} \begin{bmatrix} 1 & -2 & 1 & 2 \\ 0 & 3 & 6 & 6 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

X3 FREE VARIABLE INFINITE SOCUTIONS

SOLUTION OF THE SYSTEM

$$2^{49}$$
 $(3x_2 + 6x_3 = 6; x_2 = 2 - 2x_3)$
 $(3x_1 - 2x_2 + x_3 = 2; x_1 = 2 + 2x_2 - x_3; x_1 = 2 + 4 - 4x_3 - x_3; x_1 = 6 - 5x_3)$

$$\begin{cases} x_7 = 6 - 5 \times 3 \\ x_2 = 2 - 2 \times 3 \end{cases} \qquad \underbrace{X} = \begin{bmatrix} 6 \\ 2 \\ 0 \end{bmatrix} f \begin{bmatrix} -5 \\ -2 \\ 1 \end{bmatrix} \times 3$$

$$x_3 \in \mathbb{R}$$

$$\begin{cases} x_7 = 6 - 5 \times 3 \\ x_2 = 2 - 2 \times 3 \end{cases} \qquad \underbrace{X} = \begin{bmatrix} 6 \\ 2 \\ 0 \end{bmatrix} f \begin{bmatrix} -5 \\ -2 \\ 1 \end{bmatrix} \times 3$$

$$\begin{cases} x_7 = 6 - 5 \times 3 \\ x_2 = 2 - 2 \times 3 \end{cases} \qquad \underbrace{X} = \begin{bmatrix} 6 \\ 2 \\ 0 \end{bmatrix} f \begin{bmatrix} -5 \\ -2 \\ 1 \end{bmatrix} \times 3$$

EX2:

AND X4 FREE VARIABLES

$$\begin{cases} 2x_3 - x_4 = 2; & x_3 = 1 + \frac{7}{2}x_4 \\ x_4 = 2x_4 + 2x_4 + 2x_5 +$$

 $\begin{cases} 2x_3 - x_4 = 2; & x_3 = 1 + \frac{1}{2}x_4 \\ x_1 + 2x_2 + 3x_3 + x_4 = 7; & x_1 = 7 - 2x_2 - 3x_3 - x_4; & x_1 = 7 - 2x_2 - 3 - \frac{3}{2}x_4 - x_1; & x_1 = 4 - 2x_2 - \frac{7}{2}x_4 \end{cases}$

$$\begin{cases} x_1 = 4 - 2x_2 - 5/2 \times 4 \\ x_2 = x_2 & \in \mathbb{R} \\ x_3 = 1 + \frac{4}{2} \times 4 \\ x_4 = x_4 & \in \mathbb{R} \end{cases}$$

EX3:
$$\begin{bmatrix} 1 & -2 & 1 & 0 & 1 & 3 \\ 2 & -5 & 2 & 3 & 3 & 2 \\ 1 & -3 & 1 & 4 & 4 & 0 \end{bmatrix}^{2} = \begin{bmatrix} 1 & -2 & 1 & 0 & 1 & 3 \\ 0 & -1 & 0 & 3 & 1 & -4 \\ 0 & -1 & 0 & 4 & 3 & -3 \end{bmatrix}^{2} = \begin{bmatrix} 1 & -2 & 1 & 0 & 1 & 3 \\ 0 & -1 & 0 & 3 & 1 & -4 \\ 0 & 0 & 0 & 1 & 2 & 1 \end{bmatrix}$$

$$X_{4} + 2X_{5} = 1; \quad X_{4} = 1 - 2X_{5}$$

$$X_{5} = 1 = 1 - 2X_{5}$$

$$X_{7} + 3X_{5} + 3X_{5} = -1; \quad X_{7} = 1 + 3X_{5} + 3X_{5} + 3X_{5} = 1 + 3X_{5} =$$

$$\begin{cases} -x_2 + 3x_4 + x_5 = -4; & x_2 = 4 + 3x_4 + x_5; & x_2 = 4 + 3 - 6x_5 + x_5; & x_2 = 7^{-5}x_5 \end{cases}$$

X1 -2x2+ x3 +x5=3; x1= 3+2x2-x3-x5; x1=2+14-10x5-x3-x5; x1=17-x3-11x5

$$\begin{cases} x_1 = 17 - x_3 - 11x_5 \\ x_2 = 7 - 5x_5 \\ x_3 = x_3 \in \mathbb{R} \end{cases} \qquad x = \begin{cases} 17 \\ 7 \\ 0 \\ 1 \\ 0 \end{cases} \qquad x_5 = \begin{cases} x_3 \in \mathbb{R} \\ x_4 = 1 - 2x_5 \\ x_5 = x_5 \in \mathbb{R} \end{cases}$$