

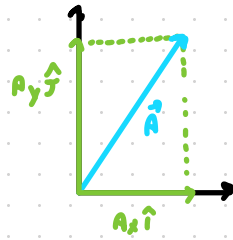
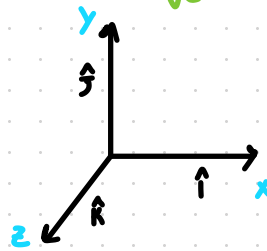


## LAW OF MOTION

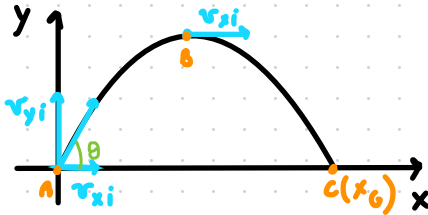
$$\frac{v_f^2 - v_i^2}{2a} = \Delta x$$

$a$  CONSTANT

## VECTORS



## MOTION IN TWO DIMENSION



IN B  $v_y = 0 \text{ m/s}$

THE  $x$  COMPONENT OF  $V_i$  REMAINS CONSTANT

$$v_{xi} = v_i \cos \theta$$

$$v_{yi} = v_i \sin \theta$$

$$v^2 = v_x^2 + v_y^2$$

CONSTANT IN TIME

$$\begin{cases} x(t) = x_0 + v_{xi}t = x_0 + v_i \cos \theta \cdot t \\ y(t) = y_0 + v_{yi}t + \frac{1}{2}at^2 = y_0 + v_i \sin \theta t - \frac{1}{2}gt^2 \end{cases}$$

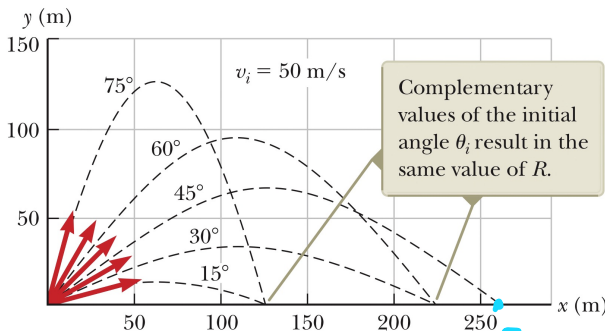
$$\begin{cases} v_{ox} = v_o \cdot \cos \theta \\ v_y(t) = v_{oy} - gt \end{cases}$$

FIND  $x_6$  (GITTATA)

$$\begin{cases} y(t) = y_0 + v_i \sin \theta t - \frac{1}{2}gt^2; & y(t) = 0; \text{ FIND } t_{\text{FLIGHT}} \text{ (ONE OF } t \text{ IS } 0 \text{ S, TAKE THE OTHER ONE)} \\ x_6 = x_0 + v_i \cos \theta t_{\text{FLIGHT}} \end{cases}$$

$$x_6 = G = \frac{2v_{ox}v_{oy}}{g}$$

$$H_{\max} \cdot H_{\max} = \frac{(v_o \sin \theta)^2}{2g}$$



$$\text{MAX } x_6: \theta = 45^\circ$$

# ENERGY OF A SYSTEM

WORK:  $W = F \Delta r \cos \theta$  [J]

$$E = U + K$$

KINETIC ENERGY:  $K = \frac{1}{2} m v^2$  [J]

POTENTIAL ENERGY:  $U = m g h$  [J]

ELASTIC POTENTIAL ENERGY:  $U_s = \frac{1}{2} k x^2$

CONSERVATION OF ENERGY  $E_f = E_i$

## LINEAR MOMENTUM AND COLLISION

LINEAR MOMENTUM:  $\vec{p} = m \vec{v}$

ISOLATED SYSTEM:  $\Delta \vec{p}_{\text{tot}} = 0$

IMPULSE:  $I = F \Delta t$

IMPULSE-MOMENTUM THEOREM:  $\Delta \vec{p} = I$

### COLLISION

- INELASTIC:  $K_{i, \text{tot}} \neq K_{s, \text{tot}}$  (NOT CONSERVED)

- PERFECTLY INELASTIC:

BOTH OBJECTS STICK TOGETHER

- INELASTIC:

NOT STICK TOGETHER BUT SOME  $K$  IS TRANSFORMED OR TRANSFERRED

- ELASTIC:  $K$  IN THE SYSTEM IS CONSERVED

WITH COLLISION IN TWO DIMENSION WORK SEPARATELY ON X AND Y