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POWER LAWS

IF I CHANGE BOTH y
AND x APPROPRIATELY
→ GET BACK EXACTLY THE
SAME FUNCTION

• $y = c x^\alpha$ ← **SCALE INVARIANT**

• EXPONENTIAL ARE NOT SCALE INVARIANT

$$c \exp(\beta x)$$

↑
THE CHARACTERISTIC SCALE

$$x_0 = \frac{1}{\beta}$$

POWER LAWS

if I change both y and x appropriately
 LET BACK EXACTLY THE SAME FUNCTION

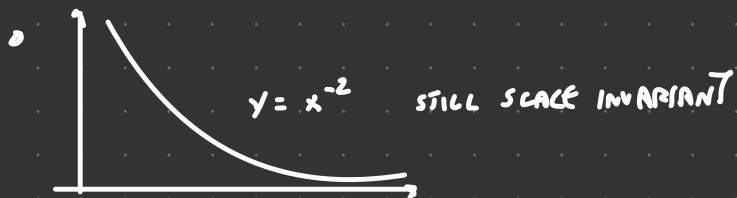
• $y = c x^\alpha \leftarrow$ **SCALE INVARIANT**

• EXPONENTIAL ARE NOT SCALE INVARIANT

$c \exp(\beta x)$

↑
THE CHARACTERISTIC SCALE

$x_0 = \frac{1}{\beta}$



• $\lambda = 100$ SCALE DOWN of 100 (100m \rightarrow 1m)

SKYSCRAPER OF IT FALLING FOR RECORD THE MOVIE. HOW SLOW SHOULD I RECORD THE MINIATURE TO MAKE IT REALISTIC



DON'T CARE ABOUT THE BUILD JUST FOCUS TOP PART (SIMPLIFIED ASSUMPTION)

$V_0 = 0 \text{ m/s}$

$\Delta s = \frac{1}{2} g t^2$

$t \propto \sqrt{\Delta s}$



$s' = \lambda s$

$\Delta s = \frac{\Delta s'}{\lambda}$

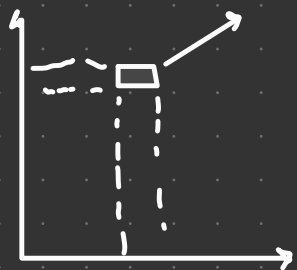
$\Delta s' = -\frac{1}{2} \lambda g t^2$

INSTEAD of g . g DOES NOT CHANGE BETWEEN THE MODEL IN THE STUDIO AND THE SKYSCRAPER.

DEFIN t' S.T.

$(t')^2 = \lambda t^2 \rightarrow \Delta s' = -\frac{1}{2} g (t')^2$

$t' = \sqrt{\lambda} t$



CASE 2. PIECE EXPLODE w/ HIGH VELOCITY

$\Delta s = v_0 t$

$\Delta s' = \lambda v_0 t$

CAN NOT REPEAT SAME ARGUMENT AS BEFORE THE ONLY CONSTANT IS v_0 THAT IS NOT UNIVERSAL

IF IT WAS A UNIV. CONSTANT I SHOULD SCALE THE TIME LINEARLY

IN THIS NEW COORDINATE SYSTEM.

NOTE:

$\left[\frac{dA}{dB} \right] = \frac{[A]}{[B]}$

$\frac{dx}{dt}$

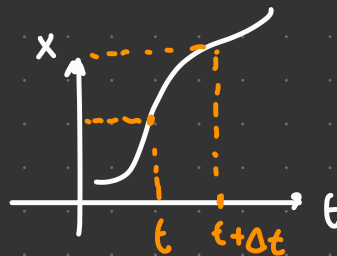
x AS A FUNCTION of t

$\lim_{\Delta t \rightarrow 0} \frac{x(t + \Delta t) - x(t)}{\Delta t}$

SAME DIMENSION of $\frac{dx}{dt}$
 x ON TOP AND Δt DOWN $\frac{dx}{dt}$

THE DIMENSION DOES NOT CHANGE w/ THE LIMIT

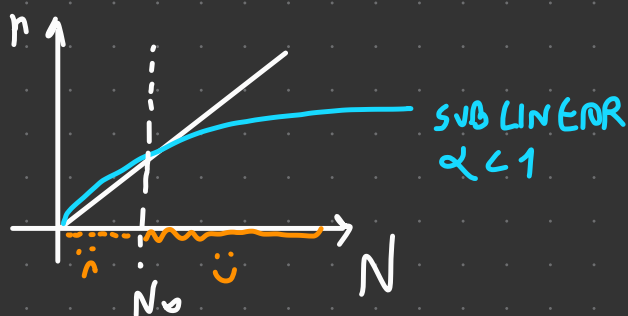
$\left[\frac{dx}{dt} \right] = \frac{[x]}{[t]}$



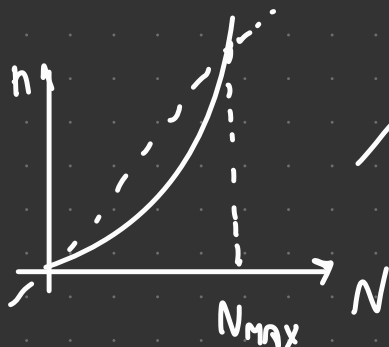
SCALING ARGUMENT

1. PREDICTING $C = AB$
2. PREDICTING THE EXISTENCE OF BOUNDS
3. USEFUL FOR MODELING

$$N \geq h \propto N^{\alpha > 1}$$



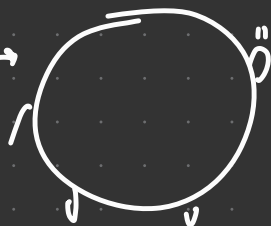
THE PROPORTIONALITY ARE GOOD IN "FAR" CASES



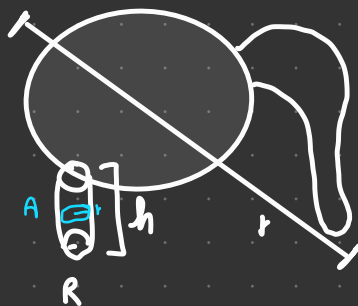
BOUND ABOVE WHICH IT DOES NOT HOLD

"SPHERICAL COW" MODELS

DESCRIBE A COW AS A SPHERE FIRST APPROXIMATION



ELEPHANT



WEIGHT FORCE

$$F_W = \rho g V$$

$$F_{MAX} = \sigma A$$

SURFACE AREA ON A SECTION OF A CYLINDER

FORCE IF LEG BEFORE IT BREAKS

$$C_2 R^2 = C_1 h^2$$

$$F_{MAX} = \sigma R^2$$

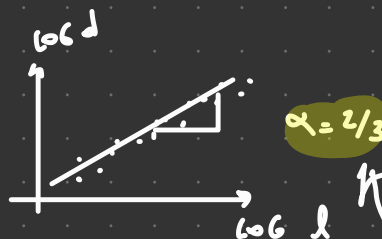
$$F_W \leq F_{MAX}$$

IT BREAKS IN THIS CASE

$$C_1 h^3 \rho g = C_2 h^2 \Rightarrow h = \frac{C_2}{C_1 \rho g}$$

CONSTANT

A NAIL



$$\alpha = 2/3$$

$$F_B$$

SUCKING (AKA BENDING)

IF $F > F_B$ IT IS FAVORABLE TO BEND

MINIMIZE THE FORCE F USED TO THE NAIL

$$F \propto d$$

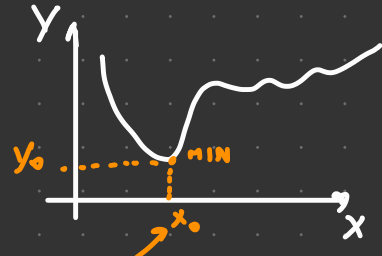
F DEPENDS ON d MINIMIZE d TO \emptyset

$$F_B \propto \frac{d^4}{l^2}$$

CAPPER DIAMETER \rightarrow LARGE FORCE CAN BE SUSTAINED

ARG MIN $f(d)$

$$y_0 = \min y(x) \\ x_0 = \text{ARG MIN } y(x)$$



$$d = \arg \min F(d)$$

$$d \propto \frac{d^4}{l^2} \Rightarrow d^3 \propto l^2 \Rightarrow d \propto l^{2/3}$$

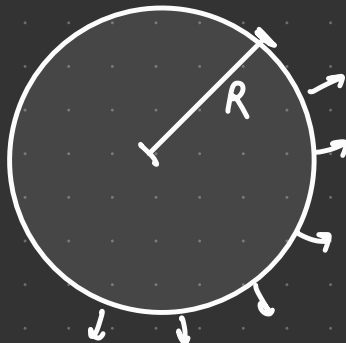
IS WHAT WE EXPECTED

CONSIDERING SPHERICAL COW

$$\left. \begin{array}{l} b \propto A \propto R^2 \\ M = \rho V \propto R^3 \end{array} \right\} \rightarrow R \propto M^{1/3}, \quad b \propto M^{2/3}$$

ASSUMPTION: ρ IS CONSTANT

$\rho = \text{CONSTANT}$



IF $A \propto B$ THEN $B \propto A$

ALSO IF $A \propto \frac{C}{B}$ THEN $AB \propto C$