## Existence and uniqueness theorem:

A linear system is consistent if and only if the rightmost column of the augmented matrix is *not* a pivot column—that is, if and only if an echelon form of the augmented matrix has *no* row of the form

$$[0 \cdots 0 b]$$
 with b nonzero

If a linear system is consistent, then the solution set contains either (i) a unique solution, when there are no free variables, or (ii) infinitely many solutions, when there is at least one free variable.

# Equivalent ways to write a linear system:

If A is an  $m \times n$  matrix, with columns  $\mathbf{a}_1, \dots, \mathbf{a}_n$ , and if **b** is in  $\mathbb{R}^m$ , the matrix equation

$$A\mathbf{x} = \mathbf{b} \tag{4}$$

has the same solution set as the vector equation

$$x_1\mathbf{a}_1 + x_2\mathbf{a}_2 + \dots + x_n\mathbf{a}_n = \mathbf{b} \tag{5}$$

which, in turn, has the same solution set as the system of linear equations whose augmented matrix is

$$\begin{bmatrix} \mathbf{a}_1 & \mathbf{a}_2 & \cdots & \mathbf{a}_n & \mathbf{b} \end{bmatrix} \tag{6}$$

## Span of the columns of A:

Let A be an  $m \times n$  matrix. Then the following statements are logically equivalent. That is, for a particular A, either they are all true statements or they are all false.

- a. For each **b** in  $\mathbb{R}^m$ , the equation  $A\mathbf{x} = \mathbf{b}$  has a solution.
- b. Each **b** in  $\mathbb{R}^m$  is a linear combination of the columns of A.
- c. The columns of A span  $\mathbb{R}^m$ .
- d. A has a pivot position in every row.

# Decomposition of the solution of a linear system:

Suppose the equation  $A\mathbf{x} = \mathbf{b}$  is consistent for some given  $\mathbf{b}$ , and let  $\mathbf{p}$  be a solution. Then the solution set of  $A\mathbf{x} = \mathbf{b}$  is the set of all vectors of the form  $\mathbf{w} = \mathbf{p} + \mathbf{v}_h$ , where  $\mathbf{v}_h$  is any solution of the homogeneous equation  $A\mathbf{x} = \mathbf{0}$ .

# **Characterization of linearly independent set:**

An indexed set  $S = \{\mathbf{v}_1, \dots, \mathbf{v}_p\}$  of two or more vectors is linearly dependent if and only if at least one of the vectors in S is a linear combination of the others. In fact, if S is linearly dependent and  $\mathbf{v}_1 \neq \mathbf{0}$ , then some  $\mathbf{v}_j$  (with j > 1) is a linear combination of the preceding vectors,  $\mathbf{v}_1, \dots, \mathbf{v}_{j-1}$ .

## Cases that are surely linearly dependent:

If a set contains more vectors than there are entries in each vector, then the set is linearly dependent. That is, any set  $\{\mathbf{v}_1,\ldots,\mathbf{v}_p\}$  in  $\mathbb{R}^n$  is linearly dependent if p>n.

If a set  $S = \{\mathbf{v}_1, \dots, \mathbf{v}_p\}$  in  $\mathbb{R}^n$  contains the zero vector, then the set is linearly dependent.

# Invertibility implies uniqueness:

If A is an invertible  $n \times n$  matrix, then for each **b** in  $\mathbb{R}^n$ , the equation  $A\mathbf{x} = \mathbf{b}$  has the unique solution  $\mathbf{x} = A^{-1}\mathbf{b}$ .

# Properties of the inverse operator:

a. If A is an invertible matrix, then  $A^{-1}$  is invertible and

$$(A^{-1})^{-1} = A$$

b. If A and B are  $n \times n$  invertible matrices, then so is AB, and the inverse of AB is the product of the inverses of A and B in the reverse order. That is,

$$(AB)^{-1} = B^{-1}A^{-1}$$

c. If A is an invertible matrix, then so is  $A^T$ , and the inverse of  $A^T$  is the transpose of  $A^{-1}$ . That is,

$$(A^T)^{-1} = (A^{-1})^T$$

## Row equivalence for invertible matrixes:

An  $n \times n$  matrix A is invertible if and only if A is row equivalent to  $I_n$ , and in this case, any sequence of elementary row operations that reduces A to  $I_n$  also transforms  $I_n$  into  $A^{-1}$ .

#### The rank theorem:

The dimensions of the column space and the row space of an  $m \times n$  matrix A are equal. This common dimension, the rank of A, also equals the number of pivot positions in A and satisfies the equation

$$\operatorname{rank} A + \dim \operatorname{Nul} A = n$$

### The invertible matrix theorem:

Let A be a square  $n \times n$  matrix. Then the following statements are equivalent. That is, for a given A, the statements are either all true or all false.

- a. A is an invertible matrix.
- b. A is row equivalent to the  $n \times n$  identity matrix.
- c. A has n pivot positions.
- d. The equation  $A\mathbf{x} = \mathbf{0}$  has only the trivial solution.
- e. The columns of A form a linearly independent set.
- f. The linear transformation  $\mathbf{x} \mapsto A\mathbf{x}$  is one-to-one.
- g. The equation  $A\mathbf{x} = \mathbf{b}$  has at least one solution for each  $\mathbf{b}$  in  $\mathbb{R}^n$ .
- h. The columns of A span  $\mathbb{R}^n$ .
- i. The linear transformation  $\mathbf{x} \mapsto A\mathbf{x}$  maps  $\mathbb{R}^n$  onto  $\mathbb{R}^n$ .
- j. There is an  $n \times n$  matrix C such that CA = I.
- k. There is an  $n \times n$  matrix D such that AD = I.
- 1.  $A^T$  is an invertible matrix.
- m. The columns of A form a basis of  $\mathbb{R}^n$ .
- n.  $\operatorname{Col} A = \mathbb{R}^n$
- o.  $\dim \operatorname{Col} A = n$
- p. rank A = n
- q. Nul  $A = \{0\}$
- r.  $\dim \text{Nul } A = 0$

### The basis theorem:

Let V be a p-dimensional vector space,  $p \ge 1$ . Any linearly independent set of exactly p elements in V is automatically a basis for V. Any set of exactly p elements that spans V is automatically a basis for V.

**Stability result for linear systems:** *NALS:stability of a linear system????* 

### **Properties of determinants:**

Let A and B be  $n \times n$  matrices.

- a. A is invertible if and only if det  $A \neq 0$ .
- b.  $\det AB = (\det A)(\det B)$ .
- c.  $\det A^T = \det A$ .
- d. If A is triangular, then det A is the product of the entries on the main diagonal of A.
- e. A row replacement operation on A does not change the determinant. A row interchange changes the sign of the determinant. A row scaling also scales the determinant by the same scalar factor.

### Similar matrices theorem:

If  $n \times n$  matrices A and B are similar, then they have the same characteristic polynomial and hence the same eigenvalues (with the same multiplicities).

## The diagonalization theorem:

An  $n \times n$  matrix A is diagonalizable if and only if A has n linearly independent eigenvectors.

In fact,  $A = PDP^{-1}$ , with D a diagonal matrix, if and only if the columns of P are n linearly independent eigenvectors of A. In this case, the diagonal entries of D are eigenvalues of A that correspond, respectively, to the eigenvectors in P.

### The QR factorization:

If A is an  $m \times n$  matrix with linearly independent columns, then A can be factored as A = QR, where Q is an  $m \times n$  matrix whose columns form an orthonormal basis for Col A and R is an  $n \times n$  upper triangular invertible matrix with positive entries on its diagonal.

## Equivalent statements for least square problems:

Let A be an  $m \times n$  matrix. The following statements are logically equivalent:

- a. The equation  $A\mathbf{x} = \mathbf{b}$  has a unique least-squares solution for each  $\mathbf{b}$  in  $\mathbb{R}^m$ .
- b. The columns of A are linearly independent.
- c. The matrix  $A^{T}A$  is invertible.

When these statements are true, the least-squares solution  $\hat{\mathbf{x}}$  is given by

$$\hat{\mathbf{x}} = (A^T A)^{-1} A^T \mathbf{b} \tag{4}$$

### QR factorization for least square problems:

Given an  $m \times n$  matrix A with linearly independent columns, let A = QR be a QR factorization of A as in Theorem 12. Then, for each  $\mathbf{b}$  in  $\mathbb{R}^m$ , the equation  $A\mathbf{x} = \mathbf{b}$  has a unique least-squares solution, given by

$$\hat{\mathbf{x}} = R^{-1} Q^T \mathbf{b} \tag{6}$$