ANY MATRIX CAN BE TRANSFORMED IN ECHELON FORM (EF) BY THE ROW REDUCTION ALGORITHM

SEQUENCE OF ELEMENTARY
ROW EQUATION

IMPORTANT ANY MATRIX IS ROW EQUIVACENT

TO A MATRIX IN EF

SUCH EF MATRIX IS NOT UNIQUE

THERE MIGTH BE MANY EF

MATPIX THAT ARE ROW EXVIVACENT

TO THE STARTING MATRIX

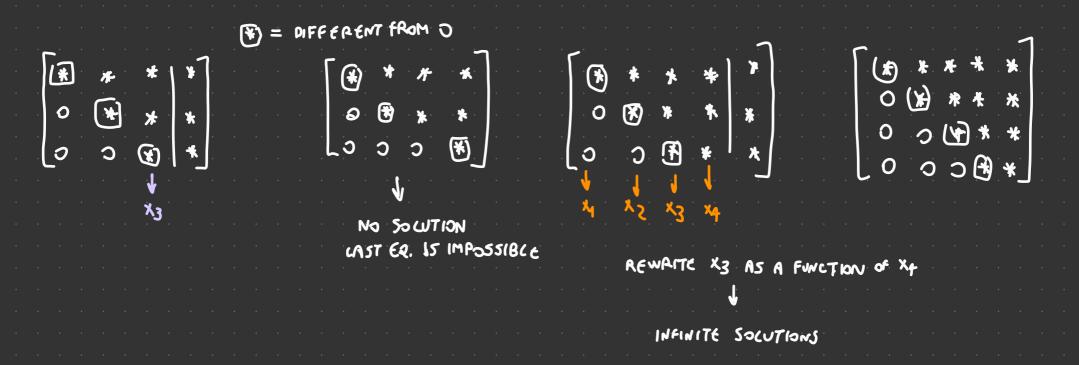
BUT THE POSITION OF THE LEADING ENTRY OF ACC ROWS OF ACC SUCH EF MATPIXES ART THE SAME

(AND TAKE THE MAME OF PINOT POSITION)

A PIVOT POSITION IS THE POSITION OF THE CENDING ENTRY OF ALL ROWS OF AN EFMARIX

$$\omega_{11}x_{1} + \omega_{12}x_{2} + \omega_{13}x_{3} = 6_{4}$$
 $\omega_{21}x_{1} + \omega_{22}x_{2} + \omega_{23}x_{3} = 6_{2}$
 $\omega_{31}x_{1} + \omega_{32}x_{2} + \omega_{33}x_{3} = 6_{3}$

$$\begin{bmatrix} \omega_{44} & \omega_{42} & \omega_{43} & 6_{1} \\ \omega_{21} & \omega_{22} & \omega_{23} & 6_{2} \\ \omega_{31} & \omega_{32} & \omega_{33} & 6_{3} \end{bmatrix}$$



THEOREM (Existence AND UNIQUESS THEOREM, VERBUSE VERSION)
AUGMENTED MATRIX ASSOCIATED TO A LINEAR SYSTEM IN EF

1) IF THERE IS AT LEAST ROW IN WHICH ALL ENTRIES ARE O APPART THE LAST ONE WHICH IS DIFFERENT FROM D, THEN THE SOLUTION SET IS VOID NO SOCUTION

IN THIS CASE THE CINEAR SYSTEM IS CALLED INCONSISTENT

- 2) OTHERWISE THE SYSTEM IS CONSISTENT (THERE MAY BE ONE of INFINITE SO CUTIONS)
 - IF EACH COCUM (EXCLUDING THE LAST ONE) HAS A PIVOT POSITION, THEN THE SOCUTION IS UNIQUE AND YOU CAN FIND BY "BACK PROPAGATION"
 - O DTHERWISE THE SOLUTION ARE INFINITE AND CAN BE EXPRESSED AS A SET PARAMETRIZED BY THE VARIABLES ASSOCIATED TO THE GOLUM WITHOUT A PIVOT POSITION (FREE VARIABLES)

IF YOU HAVE MORE COLUMS THAN ROWS YOU ARE SURPTHAT YOU WILL HAVE NO SOLUTION OR INFINITE SOLUTIONS (CAN'T HAVE ONLY ONE SOLUTION)

$$\begin{bmatrix} 1 & -1 & 2/3 & | & 2/3 \\ -2 & 2 & -2 & | & 0 \\ 2 & 1 & 1 & | & 1 \\ 3 & 1 & 1 & | & -1 \end{bmatrix} = \begin{bmatrix} 1 & -1 & 2/3 & 2/3 \\ 0 & 0 & -2/3 & 4/3 \\ 0 & 3 & -N/3 & N/3 \\ 0 & 9 & -1 & -3 \end{bmatrix} = \begin{bmatrix} 1 & -1 & 2/3 & 2/3 \\ 0 & 3 & -N/3 & -N/3 \\ 0 & 0 & -2/3 & 9/3 \\ 0 & 0 & -2/3 & 9/3 \\ 0 & 0 & -2/3 & 9/3 \end{bmatrix} = \begin{bmatrix} 1 & -1 & 2/3 & 2/3 \\ 0 & 3 & -N/3 & -N/3 \\ 0 & 0 & -2/3 & 9/3 \\ 0 & 0 & -2/3 & 9/3 \\ 0 & 0 & -2/3 & 9/3 \\ 0 & 0 & -2/3 & 9/3 \end{bmatrix}$$

. TRANSFORM TO EF

$$= \begin{bmatrix} 1 & -1 & 2/3 & 2/3 \\ 0 & 9 & -1 & -1 \\ 0 & 0 & -2 & 4 \\ 0 & 4 & -1 & -3 \end{bmatrix} \cdot \frac{3}{3} \quad \forall 9 = \begin{bmatrix} 1 & -1 & 2/3 & 1/3 \\ 0 & 9 & -1 & -1 \\ 0 & 0 & -2 & 4 \\ 0 & 0 & -5/9 & -\frac{23}{9} \end{bmatrix} \cdot 9 = \begin{bmatrix} 1 & -1 & 2/3 & 1/3 \\ 0 & 9 & -1 & -1 \\ 0 & 0 & -5/9 & -\frac{23}{9} \end{bmatrix} \cdot 9 = \begin{bmatrix} 1 & -1 & 2/3 & 1/3 \\ 0 & 9 & -1 & -1 \\ 0 & 0 & -5/9 & -\frac{23}{9} \end{bmatrix} \cdot 9 = \begin{bmatrix} 1 & -1 & 2/3 & 1/3 \\ 0 & 0 & -5/9 & -\frac{23}{9} \\ 0 & 0 & -5/9 & -\frac{23}{9} \end{bmatrix} \cdot 9 = \begin{bmatrix} 1 & -1 & 2/3 & 1/3 \\ 0 & 0 & -5/9 & -\frac{23}{9} \\ 0 & 0 & -5/9 & -\frac{23}{9} \end{bmatrix} \cdot 9 = \begin{bmatrix} 1 & -1 & 2/3 & 1/3 \\ 0 & 0 & -5/9 & -\frac{23}{9} \\ 0 & 0 & -5/9 & -\frac{23}{9} \end{bmatrix} \cdot 9 = \begin{bmatrix} 1 & -1 & 2/3 & 1/3 \\ 0 & 0 & -5/9 & -\frac{23}{9} \\ 0 & 0 & -5/9 & -\frac{23}{9} \end{bmatrix} \cdot 9 = \begin{bmatrix} 1 & -1 & 2/3 & 1/3 \\ 0 & 0 & -5/9 & -\frac{23}{9} \\ 0 & 0 & -5/9 & -\frac{23}{9} \end{bmatrix} \cdot 9 = \begin{bmatrix} 1 & -1 & 2/3 & 1/3 \\ 0 & 0 & -5/9 & -\frac{23}{9} \\ 0 & 0 & -5/9 & -\frac{23}{9} \end{bmatrix} \cdot 9 = \begin{bmatrix} 1 & -1 & 2/3 & 1/3 \\ 0 & 0 & -5/9 & -\frac{23}{9} \\ 0 & 0 & -5/9 & -\frac{23}{9} \end{bmatrix} \cdot 9 = \begin{bmatrix} 1 & -1 & 2/3 & 1/3 \\ 0 & 0 & -5/9 & -\frac{23}{9} \\ 0 & 0 & -5/9 & -\frac{23}{9} \end{bmatrix} \cdot 9 = \begin{bmatrix} 1 & -1 & 2/3 & 1/3 \\ 0 & 0 & -5/9 & -\frac{23}{9} \end{bmatrix} \cdot 9 = \begin{bmatrix} 1 & -1 & 2/3 & 1/3 \\ 0 & 0 & -5/9 & -\frac{23}{9} \end{bmatrix} \cdot 9 = \begin{bmatrix} 1 & -1 & 2/3 & 1/3 \\ 0 & 0 & -5/9 & -\frac{23}{9} \end{bmatrix} \cdot 9 = \begin{bmatrix} 1 & -1 & 2/3 & 1/3 \\ 0 & 0 & -5/9 & -\frac{23}{9} \end{bmatrix} \cdot 9 = \begin{bmatrix} 1 & -1 & 2/3 & 1/3 \\ 0 & 0 & -5/9 & -\frac{23}{9} \end{bmatrix} \cdot 9 = \begin{bmatrix} 1 & -1 & 2/3 & 1/3 \\ 0 & 0 & -5/9 & -\frac{23}{9} \end{bmatrix} \cdot 9 = \begin{bmatrix} 1 & -1 & 2/3 & 1/3 \\ 0 & 0 & -5/9 & -\frac{23}{9} \end{bmatrix} \cdot 9 = \begin{bmatrix} 1 & -1 & 2/3 & 1/3 \\ 0 & 0 & -5/9 & -\frac{23}{9} \end{bmatrix} \cdot 9 = \begin{bmatrix} 1 & -1 & 2/3 & 1/3 \\ 0 & 0 & -5/9 & -\frac{23}{9} \end{bmatrix} \cdot 9 = \begin{bmatrix} 1 & -1 & 2/3 & 1/3 \\ 0 & 0 & -5/9 & -\frac{23}{9} \end{bmatrix} \cdot 9 = \begin{bmatrix} 1 & -1 & 2/3 & 1/3 \\ 0 & 0 & -5/9 & -\frac{23}{9} \end{bmatrix} \cdot 9 = \begin{bmatrix} 1 & -1 & 2/3 & 1/3 \\ 0 & 0 & -5/9 & -\frac{23}{9} \end{bmatrix} \cdot 9 = \begin{bmatrix} 1 & -1 & 2/3 & 1/3 \\ 0 & 0 & -5/9 & -\frac{23}{9} \end{bmatrix} \cdot 9 = \begin{bmatrix} 1 & -1 & 2/3 & 1/3 \\ 0 & 0 & -5/9 & -\frac{23}{9} \end{bmatrix} \cdot 9 = \begin{bmatrix} 1 & -1 & 2/3 & 1/3 \\ 0 & 0 & -5/9 & -\frac{23}{9} \end{bmatrix} \cdot 9 = \begin{bmatrix} 1 & -1 & 2/3 & 1/3 \\ 0 & 0 & -5/9 & -\frac{23}{9} \end{bmatrix} \cdot 9 = \begin{bmatrix} 1 & -1 & 2/3 & 1/3 \\ 0 & 0 & -5/9 & -\frac{23}{9} \end{bmatrix} \cdot 9 = \begin{bmatrix} 1 & -1 & 2/3 & 1/3 \\ 0 & 0 & -5/9 & -\frac{23}{9} \end{bmatrix} \cdot 9 = \begin{bmatrix} 1 & -1 & 2/3 & 1/3 \\ 0 & 0 & -5/9 &$$

No SOUTION

$$\begin{bmatrix} 1 & 2 & -2 & | & 1 \\ 2 & -2 & -2 & | & -2 \\ -3 & 0 & 1 & | & -2 \\ 1 & 1 & 1 & 3 \end{bmatrix}^{2} = \begin{bmatrix} 1 & 2 & -2 & | & 1 \\ 0 & -6 & 2 & | & -4 \\ 0 & 6 & -5 & | & 1 \\ 0 & -1 & 3 & | & 2 \end{bmatrix} = \begin{bmatrix} 1 & 2 & -2 & 1 \\ 0 & -1 & 3 & 2 \\ 0 & 6 & -5 & 1 \\ 0 & -1 & 3 & 2 \end{bmatrix}^{-6}$$

$$\begin{bmatrix} 1 & 2 & -2 & 1 \\ 0 & -1 & 3 & 2 \\ 0 & 0 & 13 & 13 \\ 0 & 0 & -76 & -16 \end{bmatrix} = \begin{bmatrix} 1 & 2 & -2 & 1 \\ 0 & -1 & 3 & 2 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & -1 & -1 \end{bmatrix} = \begin{bmatrix} 1 & 2 & -2 & 1 \\ 0 & -1 & 3 & 2 \\ 0 & 0 & -1 & -1 \end{bmatrix}$$

3 RoW:
$$x_3 = 1$$

 2^{10} RoW: $(-x_2 + 3x_3 = 2)$; $x_2 = 1$
 1^{st} RoW: $(x_1 + 2x_2 - 2x_3 = 1)$; $x_1 = 1$

HOLLMAN TOWN

(BECAUSE EACH COCUMN)
LHAS A PIVOT POSITION)

$$\begin{bmatrix} 1 & -1 & 0 & -1 & | & 0 \\ 2 & 3 & 1 & 2 & | & 1 \\ -3 & -1 & -2 & -1 & | & 4 \end{bmatrix} \xrightarrow{2} = \begin{bmatrix} 1 & -1 & 0 & -1 & | & 0 \\ 0 & 5 & 1 & 4 & | & 1 \\ 0 & -4 & -2 & -4 & | & 4 \end{bmatrix} \xrightarrow{2} = \begin{bmatrix} 1 & -1 & 0 & -1 & | & 0 \\ 0 & 5 & 1 & 4 & | & 1 \\ 0 & -4 & -2 & -4 & | & 4 \end{bmatrix} \xrightarrow{2} = \begin{bmatrix} 1 & -1 & 0 & -1 & | & 0 \\ 0 & -7 & -1 & -2 & | & 2 \\ 0 & 5 & 1 & 4 & | & 1 \end{bmatrix} \xrightarrow{-\frac{3}{2}} \xrightarrow{3} \xrightarrow{-\frac{3}{2}} \xrightarrow{-\frac{3}{2}} \xrightarrow{3} \xrightarrow{-\frac{3}{2}} \xrightarrow{-\frac{3}{2$$

-> -3/2×3->4=6 ; ×3=-4-2×4

1, 12 ×3 ×4

by X4 MAS NO PIVOT POSITION INFINITE SOCUTIONS

$$\begin{bmatrix} 1 & -2 & 1 & 4 & | & -1 \\ 2 & -4 & 5 & 7 & | & 0 \\ 1 & -2 & 4 & 3 & | & 1 \end{bmatrix} \begin{bmatrix} 2 \\ 1 \\ 0 & 0 & 3 \\ 0 & 0 & 3 \end{bmatrix} = \begin{bmatrix} 1 & -2 & 1 & 4 & | & -1 \\ 0 & 0 & 3 & -1 & 2 \\ 0 & 0 & 3 & -1 & 2 \end{bmatrix} \begin{bmatrix} 1 & -2 & 1 & 4 & | & -1 \\ 0 & 0 & 3 & -1 & 2 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & -2 & 1 & 4 & | & -1 \\ 0 & 0 & 3 & -1 & 2 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & -2 & 1 & 4 & | & -1 \\ 0 & 0 & 3 & -1 & 2 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & -2 & 1 & 4 & | & -1 \\ 0 & 0 & 3 & -1 & 2 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

2 ROWS ARE THE SAME

X2 AND X+ ARE FREE VARIABLE

$$\begin{cases} x_1 = -5/3 + 2x_2 - \frac{13}{3} \times 4 \\ x_2 \in \mathbb{R} & (PREE VARIABLE) \\ x_3 = \frac{2}{3} + \frac{1}{3} \times 4 \\ x_1 \in \mathbb{R} & (FREE VARIABLE) \end{cases}$$

VECTOR: A VECTOR Y & IR" IS A COLLECTION [V1, V2, V3..., Vn] WITH V1, V2, V3..., VN & IR

SIMPLE OPERATIONS W/ VECTORS

CAN'T SUM OF VECTORS WI/ DIFFERENT LENGTH

SUM OR DIFFERENCE OF VECTORS

$$V \downarrow W \in \mathbb{R}^{N} \quad V + W \Rightarrow \begin{bmatrix} V_{1} \\ V_{2} \\ V_{3} \\ \vdots \\ V_{N} \end{bmatrix} + \begin{bmatrix} W_{1} \\ W_{2} \\ W_{3} \\ \vdots \\ W_{N} \end{bmatrix} = \begin{bmatrix} V_{1} + W_{1} \\ V_{2} + W_{2} \\ V_{3} + W_{3} \\ \vdots \\ V_{N} + W_{N} \end{bmatrix}$$

$$\begin{bmatrix} 3 \\ 2 \\ -6 \end{bmatrix} + \begin{bmatrix} -1 \\ 7 \\ 2 \end{bmatrix} = \begin{bmatrix} 3-1 \\ 2+7 \\ -6+2 \end{bmatrix} = \begin{bmatrix} 2 \\ 9 \\ -4 \end{bmatrix}$$

MULTIPLICATION OF A VECTOR
TIMES A REAL NUMBER (SCALAR)

$$\underline{V} = \begin{bmatrix} V_1 \\ V_2 \\ \vdots \\ V_N \end{bmatrix} \quad \alpha \in \mathbb{R} \quad \alpha \underline{V} = \begin{bmatrix} \alpha V_1 \\ \alpha V_2 \\ \vdots \\ \alpha V_N \end{bmatrix} \qquad 5 \begin{bmatrix} 3 \\ 2 \\ -6 \end{bmatrix} = \begin{bmatrix} 15 \\ 10 \\ -30 \end{bmatrix}$$

$$\partial (\alpha \beta) \underline{\vee} = \alpha (\beta \underline{\vee})$$

$$A \in \mathbb{R}^{m \times N}$$
 $y \in \mathbb{R}^{N}$

$$A = \begin{bmatrix} \omega_{11} & \omega_{12} & \omega_{13} & ... & \omega_{1N} \\ \omega_{21} & \omega_{22} & \omega_{23} & ... & \omega_{2N} \\ \vdots & & & & & & & \\ \omega_{M1} & \omega_{M3} & ... & \omega_{MN} \end{bmatrix}$$

$$\begin{bmatrix} 3 & 4 & 2 \\ 2 & 0 & 2 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} = \begin{bmatrix} 3 \\ 2 \\ 1 \end{bmatrix} + 2 \begin{bmatrix} 4 \\ 0 \\ 1 \end{bmatrix} + 3 \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix} + \begin{bmatrix} 3 \\ 2 \\ 2 \end{bmatrix} + \begin{bmatrix} 6 \\ 6 \\ 3 \end{bmatrix} = \begin{bmatrix} 17 \\ 8 \\ 6 \end{bmatrix}$$

$$A \qquad \qquad \underline{\vee}$$

$$\begin{bmatrix} \omega_{11} & \omega_{12} & \omega_{13} \\ \omega_{21} & \omega_{22} & \omega_{23} \\ \omega_{33} & \omega_{32} & \omega_{33} \end{bmatrix} \begin{bmatrix} v_{1} \\ v_{2} \\ v_{3} \end{bmatrix} = \begin{bmatrix} \omega_{41} \\ \omega_{21} \\ \omega_{31} \end{bmatrix} v_{1} + \begin{bmatrix} \omega_{12} \\ \omega_{22} \\ \omega_{32} \end{bmatrix} v_{2} + \begin{bmatrix} \omega_{41} v_{1} \\ \omega_{21} v_{1} \\ \omega_{31} v_{1} \end{bmatrix} + \begin{bmatrix} \omega_{42} v_{2} \\ \omega_{42} v_{2} \\ \omega_{32} v_{2} \end{bmatrix} + \begin{bmatrix} \omega_{13} v_{3} \\ \omega_{23} v_{3} \\ \omega_{33} v_{3} \end{bmatrix}$$

$$\underline{A} \in \mathbb{R}^{3\times 2} \qquad \underline{v} \in \mathbb{R}^{3}$$

$$\underline{v} \in \mathbb{R}^{3}$$

$$\underline{v} \in \mathbb{R}^{3}$$

$$\begin{bmatrix} \omega_{11} & \omega_{12} & ... & \omega_{1N} \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ \omega_{11} & v_{12} & v_{22} \\ \vdots \\ \omega_{11} & v_{11} & v_{12} & v_{21} \\ \vdots \\ \omega_{11} & v_{11} & v_{12} & v_{21} & v_{11} \\ \vdots \\ \omega_{11} & v_{11} & v_{12} & v_{21} & v_{11} \\ \vdots \\ \omega_{11} & v_{11} & v_{12} & v_{21} & v_{11} \\ \vdots \\ \omega_{11} & v_{11} & v_{12} & v_{21} & v_{11} \\ \vdots \\ \omega_{11} & v_{11} & v_{11} \\ \vdots \\ \omega_{11} & v_{11} & v_{11} \\ \vdots \\ \omega_{11} & v_{11} & v_{$$

DEFINITION: LINEAR COMBINATION OF VECTORS

A CINEAR COMBINATION OF <u>VECTORS</u> $\{V_1, V_2, V_3, ..., V_p\}$ EACH IN \mathbb{R}^N IS MY VECTOR <u>N</u> THAT CAN BE WRITTEN AS $\underline{w} = c_1v_1 + c_2v_2 + c_3v_3 + ... + c_pv_p \in \mathbb{R}^N$

WITH C1, C2 ... CP ER

$$\begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix} \begin{bmatrix} 0 \\ 6 \\ 0 \\ 6 \end{bmatrix} \begin{bmatrix} 2 \\ -1 \\ 2 \\ 0 \end{bmatrix}$$

$$C_{1} \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix} + C_{2} \begin{bmatrix} 0 \\ 6 \\ 0 \\ 5 \end{bmatrix} + C_{3} \begin{bmatrix} 2 \\ -1 \\ 2 \\ 0 \end{bmatrix}$$

$$AS AN EXAMPLE:$$

$$C_{1} = 2 \quad C_{2} = 0 \quad C_{3} = 3$$

$$C_{1} = 2 \quad C_{2} = 0 \quad C_{3} = 3$$

$$C_{1} = 2 \quad C_{2} = 0 \quad C_{3} = 3$$

DEFINITION THE SPAN & V1, V2, ... Vp } IS THE SET OF ALL LINEAR COMBINATIONS OF SUCH VECTORS

$$C_{1}, C_{2} \in \mathbb{R}$$

$$C_{1} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + C_{2} \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} C_{1} \\ 0 \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ C_{2} \\ 0 \end{bmatrix} = \begin{bmatrix} C_{1} \\ C_{2} \\ 0 \end{bmatrix}$$

$$C_{1} \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} C_{1} \\ C_{2} \\ 0 \end{bmatrix}$$