

RCReceiver

- unsigned long m_last_pulse
- unsigned long m_rudder_pulse
- unsigned long m_rudder_pulse_raw
- unsigned long m_sail_pulse
- unsigned long m_sail_pulse_raw
- unsigned long m_offset_min
- unsigned long m_offset_max
- bool m_is_receiving

- + RCReceiver()
- + ~RCReceiver()
- + void init()
- + void update()
- + void checkRC()
- + bool isReceiving()
- + bool status()
- + float getCmdRudder()
- + float getCmdSail()
- float convertToPercent
(unsigned long pulse,
int ch)