ServoMotor

- Adafruit_PWMServoDriver
  * m_servo
- uint16_t m_pwm_min
- uint16_t m_pwm_max
- uint8_t m_pin

+ ServoMotor(uint8_t
 pin, uint16_t pwm_min,
 uint16_t pwm_max)
+ ~ServoMotor()
+ void init()
+ void setPWM(uint16
_t pwm)
+ void setPercent(float
 percent)