Recorded at time: 1752793443.773337 map Broadcaster: default authority Average rate: $6\overline{0}.632$ Buffer length: 1.583 Most recent transform: 385.883353 Oldest transform: 384.30002 odom Broadcaster: default authority Average rate: $6\overline{0.632}$ Buffer length: 1.583 Most recent transform: 384.883353 Oldest transform: 383.30002 base link Broadcaster: default_authority Broadcaster: default authority Average rate: 13.645 Average rate: $6\overline{0.632}$ Buffer length: 5.35 Buffer length: 1.583 Most recent transform: 1752793443.726137 Most recent transform: 384.883353 Oldest transform: 1752793438.376173 Oldest transform: 383.30002 link1 inertial_link front_left_wheel_link front_right_wheel_link rear_left_wheel_link rear_right_wheel_link Broadcaster: default authority Average rate: 13.645 Buffer length: 5.35
Most recent transform: 1752793443.726137 Oldest transform: 1752793438.376173 link2 Broadcaster: default_authority Average rate: $1\overline{3.645}$ Buffer length: 5.35 Most recent transform: 1752793443.726137 Oldest transform: 1752793438.376173 link3 Broadcaster: default authority Average rate: 13.645 Buffer length: 5.35 Most recent transform: 1752793443.726137 Oldest transform: 1752793438.376173 link4 Broadcaster: default authority Average rate: $1\overline{3.645}$ Buffer length: 5.35 Most recent transform: 1752793443.726137 Oldest transform: 1752793438.376173 link5 Broadcaster: default authority Average rate: 13.645 Buffer length: 5.35 Most recent transform: 1752793443.726137 Oldest transform: 1752793438.376173 link6 Broadcaster: default authority Broadcaster: default authority Average rate: $1\overline{3.645}$ Average rate: 13.645 Buffer length: 5.35 Buffer length: 5.35 Most recent transform: 1752793443.726137 Oldest transform: 1752793438.376173 Most recent transform: 1752793443.726137 Oldest transform: 1752793438.376173

link7

link8

view frames Result

Broadcaster: default authority

Average rate: $6\overline{0.632}$

Buffer length: 1.583

Most recent transform: 384.883353

Oldest transform: 383.30002

lidar_frame