## **SciPy and Optimization**

## **Optimization in Math/Economics**

Many critical problems in analysis are framed as optimization problems.

- Classification Models
- Regression Models
- Utility Maximization
- Oligopoly Best Response Functions
- Dynamic Programming

## **Optimization**

Framing a problem as a case of optimization provides an intuitive way to solve it, and (typically) clear indications of when a solution has been reached

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## **Optimization**

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- What mathematical conditions allow us to establish the existence of a minimum value?
  - First derivative(s) equal to 0
  - Second derivatives positive

# Optimization in Economics - Utility Maximization

Consider an individual choosing consumption of two goods in order to maximize utility:

$$U(x,y)=x^{lpha}y^{eta}$$

The individual also has a budget constraint:

$$I=p_x\cdot x+p_y\cdot y$$

## **Utility Maximization**

The two equations represent a **constrained optimization** problem.

- Want to consume all the things, but can't afford to.
- How happy can we be, given a limited amount of money?

Stated mathematically:

$$max_{x,y} \;\; U(x,y) \;\; ext{subject to} \ I = p_x \cdot x + p_y \cdot y$$

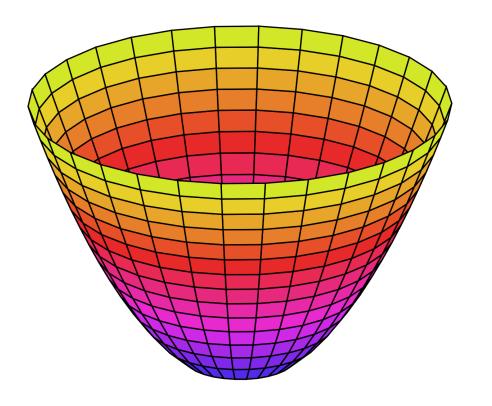
## **Utility Maximization**

We can rewrite these two equations as a single problem in order to find the maximum:

$$\mathcal{L} = x^{lpha}y^{eta} + \lambda(I - p_x \cdot x - p_y \cdot y)$$

This is the Lagrangian expression of our optimization problem.

In this case, we could algebraically solve the problem, **but that is not always the case**!

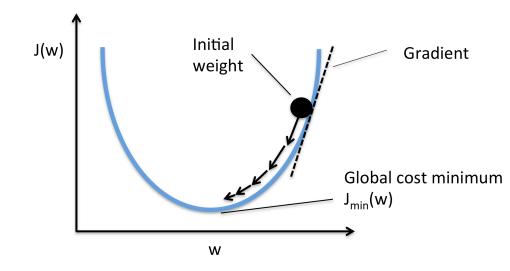


## Geometrically

In a computational optimization problem, we need to find a way to get ourselves to the optimum (minimum in this case), and to know when we get there.

## Geometrically

Typically, we use some form of **gradient descent** to find our way to the minimum value of a function.



## What is a gradient?

A function, f, with two input variables x and y has two partial derivatives:

$$f(x,y) 
ightarrow rac{\partial f}{\partial x} ext{ and } rac{\partial f}{\partial y}$$

Each partial derivative tells us how f changes as we move in a particular dimension while remaining stationary in the other.

## What is a gradient?

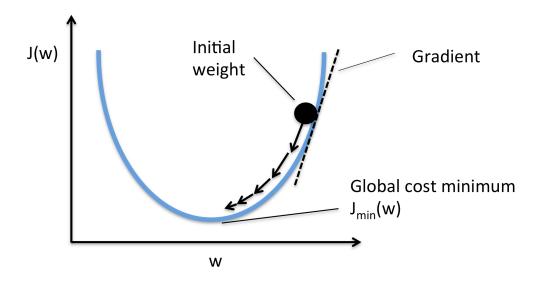
The **gradient**, then, is the vector of all partial derivatives of a given function at any point along the function:

$$abla f = egin{bmatrix} rac{\partial f}{\partial x} \ rac{\partial f}{\partial y} \end{bmatrix}$$

We can use the gradient to determine the linear approximation of a function's shape at any given point.

Think about it as the slope and direction of a hill you are hiking on.

### **Gradient Descent**



**Gradient Descent** is a technique in which we algorithmically move toward what we believe to be the minimum value of our function based on the current slope of our function.

### **Gradient Descent**

#### Steps of a gradient descent algorithm:

- Evaluate the gradient of the function
- Find the direction of steepest descent
- Determine how far to move in that direction
  - Based on slope
- Move to new point
- Reevaluate the gradient
- Stop moving when gradient is approximately 0
  - Choose how close is close

### **Exercise**

Estimate the gradient of the following function (using Python!):

$$y = \sin(x) - (z+3)^2$$

where

1. 
$$x=1$$
 and  $z=10$ 

$$2.\,x=-3$$
 and  $z=2$ 

Hint: try changing x and z by small amounts, and evaluating the difference

#### **Exercise Answer**

```
import numpy as np
# Define function y in terms of x and z
def v(x, z):
  return np.\sin(x) - (z+3)**2
# Approximate gradient in x and z at point 1
(y(1,10) - y(1.1,10))/.1 # x direction, value ~0.497
(y(1,10) - y(1,10.1))/.1 \# z direction, value ~26.1
# Approximate gradient in x and z at point 2
(y(-3,2) - y(-2.9,2))/.1 # x direction, value ~0.981
(y(-3,2) - y(-3,2.1))/.1 \# z direction, value ~10.1
```

## **Gradients and Optimization in Scipy**

When we need to optimize a function, we can easily do so using Scipy's built-in optimize module.

```
import numpy as np
from scipy.optimize import minimize
```

There is NO maximize function.

Why?

## **Gradients and Optimization in Scipy**

When we need to optimize a function, we can easily do so using Scipy's built-in optimize module.

```
import numpy as np
from scipy.optimize import minimize
```

There is NO maximize function.

Why? Because any maximization problem can be restated as a minimization problem! (Multiply by -1)

## Optimizing our exercise function

```
def y(x, z):
    return np.sin(x) - (z+3)**2
```

There are two problems with our function that we need to resolve:

- 1. We need to be able to pass an array of values to our function when using minimize, and here we pass two numbers
- 2. Our problem is concave, and so has a maximum
  - We need to restate it as a minimization problem

## Optimizing our exercise function

```
def y(x, z):
    return np.sin(x) - (z+3)**2

def q(x):
    return -1*y(x[0], x[1])
```

We can wrap our function y in a new function q taking only an array of numbers, and have it return the negative of our original equation.

Now we are ready to minimize!

## Optimizing our exercise function

What happens if you try a different starting point?

## For Lab/Homework

You will add a Logistic Regression method to your RegressionModel class. You will need to do the following in order to implement Logistic Regression:

- Create a function to calculate the log-likelihood function (see these slides for a guide)
- Use gradient descent
- Calculate the model standard error (see Logit primer slides above)
- Calculate coefficient standard errors, z-statistics, and pvalues