# Model Checking BSML

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#### Abstract

Bilateral State-based Modal Logic (BSML) was introduced in [Alo22] to model Free-Choice (FC) and related inferences which arise from speakers' distaste for interpretations that verify a sentence by empty configuration (neglect-zero tendency). To preclude such empty configurations, BSML uses state-based semantics (propositions evaluated at sets of worlds rather than individual worlds) and extends basic modal logic with a pragmatic enrichment function []<sup>+</sup> which requires supporting states to be nonempty. We implement an explicit model checker for BSML $^{\mathbb{W}}$ , an extension of BSML with global disjunction, and use this to verify some properties, like Free-Choice inference, as described in [AAY24]. Further, we implement a type for representing Natural Deduction proofs for BSML $^{\mathbb{W}}$ .

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# 1 Introduction

This section outlines the motivation for BSML by walking through a simple example from [Alo22]. Readers interested only in the implementation can safely skip this section.

### 1.1 Motivating example

Free-Choice (FC) inferences are instances of a disjunctive sentence ("or") unexpectedly yielding a conjunctive reading ("and"). In the following example, a modalized disjunction (1) yields a conjunction of modals (2).

- 1.  $\Diamond(b \lor c)$  You may go to the beach **or** to the cinema
- 2.  $\Diamond b \land \Diamond c$  You may go to the beach **and** you may go to the cinema

Aloni [Alo22] posits that speakers interpret a sentence by identifying structures of reality that reflect it. Such a structure, or "information state", is a set of possible worlds.

In our disjunction, there are four associated worlds:

- 1.  $W_{bc}$  in which both b and c are true (you go to both the beach and the cinema)
- 2.  $W_b$  in which b is true (you go to the beach)
- 3.  $W_c$  in which c is true (you go to the cinema)
- 4.  $W_z$  in which neither b nor c is true (you don't go anywhere)

We can use BSML to model the information states (i.e. sets of worlds) in which the disjunction  $b \lor c$  is assertable (or rejectable). A disjunction  $\varphi \lor \psi$  is assertable in a state s if s is the union of two substates t and u, where  $\varphi$  is assertable in t and  $\psi$  is assertable in u.

- 1. Where state  $s_1$  is the union of  $W_b$  and  $W_c$ ,  $b \vee c$  is assertable since b is assertable in  $W_b$  and c is assertable in  $W_c$
- 2. Where state  $s_2$  is the union of  $W_{bc}$  and  $W_b$  (or  $W_{bc}$  and  $W_c$ ),  $b \lor c$  is assertable since b is assertable in  $W_b$  and c is assertable in  $W_{bc}$
- 3. Where state  $s_3$  is the union of  $W_b$  and the empty set (or  $W_c$  and the empty set),  $b \lor c$  is assertable since
  - since each of the disjuncts is assertable in a substate. b is assertable in  $W_b$ , and c is supportable in the empty state.
- 4. In a state consisting of  $W_z$  and  $W_b$  (and any other state which includes  $W_z$ ),  $b \lor c$  is not assertable because in  $W_z$  both b and c are false, so no substate containing  $W_z$  would allow assertion of b or c.

So, among the four types of states,  $b \lor c$  is assertable in all but the last. This is a problem, because if  $b \lor c$  is assertable in a state consisting only of  $W_b$  (or a state consisting of only  $W_c$ ) then we have that

 $\Diamond(b \lor c)$  is true while  $\Diamond b \land \Diamond c$  is false, so the FC inference fails. The problematic state, then, is the zero-model: one of the states which it uses to satisfy the disjunction is the empty state.

How do we account for FC inferences then? Aloni argues pragmatically that a speaker would not consider the zero-model as one of the candidate states. Neglecting the zero model then, the FC inference would hold because the only states that would support  $b \lor c$  would be (1) or (2). To model neglect-zero (to make sure that  $b \lor c$  is not assertable in the zero-model), we require that to satisfy a disjunction, the state must be the union of two non-empty substates rather than just the union of two substates. This is modelled by enriching formulas using a pragmatic enrichment function which conjuncts to each subformula a non-emptiness atom (NE), which requires supporting states to be inhabited.

The enrichment of  $b \vee c$  (denoted  $[b \vee c]^+$ ) is no longer assertable in a state consisting of only  $W_b$  (or a state consisting of only  $W_c$ ) since NE would not be assertable in any substates that could (vacuously) support c. Finally then, since the only states in which the enriched disjunction holds are (1) and (2), the FC inference holds.

#### 1.2 Our contribution

This report details our explicit model checker for BSML. In the last section, we create a framework for writing Natural Deduction style proofs for BSML in Haskell.

Developing model-checkers is useful for any logic - it helps us understand quickly whether a formula is true on a particular model (while removing any human error involved in this process), and also makes it easy for the user to check the satisfiability of a list of formulas on a large list of models quickly. The goal is to ensure model-checkers are accurate and efficient: while in BSML the latter criterion is hard to achieve on account of the unique semantics of the logic, we have tried to ensure that the model-checker is as quick as possible while remaining precise.

Representing Natural Deduction style proofs is the first step to building a functional theorem prover for the language. As with model-checkers, this makes the job of anyone working in the field easier as they may now systematically verify the correctness of their proofs. Our representation of Natural Deduction is built by creating a new Proof type, and ensuring that the only way one can get from one proof to another is by following the rules of deduction outlined in [AAY24].

# 2 Model checking BSML

This section describes the implementation of the explicit model checker for BSML. More precisely, we will focus on BSML<sup>V</sup>, an extension of BSML with so-called *global disjunction*. This extension was not chosen for conceptual reasons, but merely to make the implementation of Natural Deduction more palatable, as we will see later. Throughout this report, we will not need to differentiate between BSML and BSML<sup>V</sup>, so we will be somewhat sloppy and simply write BSML for our language.

### 2.1 Syntax

```
{-# LANGUAGE LambdaCase #-}
{-# LANGUAGE TemplateHaskell #-}
{-# LANGUAGE DeriveDataTypeable #-}
{-# LANGUAGE RankNTypes #-}
module Syntax where

import Data.Data (Data)
```

```
import Control.Lens
import Control.Lens.Extras (is)
import Test.QuickCheck
```

This module describes the syntactical elements of BSML. We define formulas, some syntactical operations and provide generators for random formulas.

The formulas of BSML are defined as follows:

Readers familiar with Modal Logic (see e.g.[BRV01]) should recognize this as the basic modal language, extended with NE, the nonemptiness atom, and  $\forall$ , global disjunction. As we will see when defining the semantics, NEis used to exclude the assertion of logical statements due to empty information-configurations (i.e. empty states/teams).

For the sake of more legible output, we also define a pretty-printer for formulas. Note that we print  $\vee$  as V/ rather than V to avoid having to worry about the escape character.

Further, we define some abbreviations for formulas, following [AAY24]. As usual,  $\square$  is defined as the dual of  $\lozenge$ . As will become evident when we define the semantics,  $\bot$  is supported in a state if and only if that state is empty. It is therefore referred to as the *weak contradiction*. The strong contradiction, defined as  $\bot := \bot \land NE$ , will never be supported. Dually, the formula  $\top := NE$  serves as the *weak tautology*, being supported by non-empty states and the strong tautology  $\top := \neg \bot$  is always supported.

```
-- Define box as the dual of diamond.
box :: Form -> Form
box = Neg . Dia . Neg

-- Define the strong contradiction (which is never assertable).
botbot :: Form
botbot = And Bot NE

-- NE functions as a weak tautology (assertable in non-empty states).
top :: Form
top = NE

-- Define the strong tautology (which is always assertable).
toptop :: Form
```

```
toptop = Neg Bot
```

As in [AAY24], we can use these notions of contradiction and tautology to interpret finite (global) disjunctions and conjunctions:

```
bigOr :: [Form] -> Form
bigOr [] = Bot
bigOr fs = foldr1 Or fs

bigAnd :: [Form] -> Form
bigAnd [] = toptop
bigAnd fs = foldr1 And fs

bigGor :: [Form] -> Form
bigGor [] = botbot
bigGor fs = foldr1 Gor fs
```

Note that we could have (semantically equivalently) defined e.g.

```
bigor :: [Form] -> Form
bigor = foldr Or Bot
```

but this would have had the undesired side-effect of including Bot in *every* disjunction, including non-empty ones.

#### 2.1.1 Random formulas

In order to verify some properties of BSML, we would like to be able to generate random formulas. We will use QuickCheck's ecosystem for this purpose, so we only need to define an instance of Arbitrary for Form.

First, we fix a number of propositions, which we will also use when generating random valuations for models. This guarantees that random models and formulas have a more meaningful interaction, in the sense that the formulas will actually refer to the propositions that occur in the model.

```
-- We use proposition in the range (1, numProps).
numProps :: Int
numProps = 32
```

One might wonder why we do not use the size parameter of a generator to determine the range of propositions. We intentionally avoid this, because it would introduce a bias in the occurrence of Propositions, where more nested subformulas will not contain high propositions.

Now we can define the Arbitrary Form-instance using a standard sized generator, where formulas generated with size 0 are random atoms and larger formulas are generated by applying a random constructor to random smaller formulas.

```
-- Generate a random atom.
randomAtom :: Gen Form
randomAtom = oneof [Prop <$> choose (1, numProps), pure NE, pure Bot]

instance Arbitrary Form where
arbitrary = sized $ \case
0 -> randomAtom
_ -> oneof [
    randomAtom,
    Neg <$> f,
    And <$> f <*> f,
    Gor <$> f <*> f,
    Gor <$> f <*> f,
    Dia <$> f
```

```
where f = scale ('div' 2) arbitrary
```

The choice to scale the size of the generator by dividing it by 2 is completely arbitrary, but seems to work well in practice and is used in similar projects, see e.g. [GVLM24].

Last, we also define shrinks of formulas that empower QuickCheck to attempt simplifying counterexamples when/if it finds any.

```
shrink (Neg f) = [Bot, NE, f] ++ [Neg f' | f' <- shrink f]
shrink (Dia f) = [Bot, NE, f] ++ [Dia f' | f' <- shrink f]
shrink (And f1 f2) = [Bot, NE, f1, f2] ++ [And f1' f2' | (f1',f2') <- shrink (f1,f2)]
shrink (Or f1 f2) = [Bot, NE, f1, f2] ++ [Or f1' f2' | (f1',f2') <- shrink (f1,f2)]
shrink (Gor f1 f2) = [Bot, NE, f1, f2] ++ [Gor f1' f2' | (f1',f2') <- shrink (f1,f2)]
shrink _ = []</pre>
```

### 2.1.2 Boilerplate for subformulas

This section is slightly technical and can safely be skipped. It introduces some functions that allow us to check properties of subformulas (e.g. whether a formula contains NE anywhere in its subformulas).

The Lens-library defines a typeclass Plated that implements a lot of boilerplate code for the transitive descendants of values of recursively defined types, so let us make Form an instance.

```
-- Use default implementation: plate = uniplate instance Plated Form
```

We also derive a prism corresponding to every constructor of Form.

```
-- Derives prisms _Bot, _NE, ..., _Gor, _Dia makePrisms ',Form
```

For readers unfamiliar with this, aPrism is to a constructors what a Lens is to a field. For example, the derived Prism for Or is of type

```
_Or :: Prism', Form (Form, Form)
```

which can loosely be interpreted as a pair of functions; one that turns a (Form, Form) into a Form (by applying Or in this case), and one that tries to turn a Form into a (Form, Form) (in this case, by taking the arguments out of the constructor if the formula is a disjunction). As we are familiar with from Lens, this is suitably generalized.

Now, we can e.g. check whether a formula uses the constructors NE or Gor by seeing if any of its transitive descendants is built using one of these constructors.

```
isBasic :: Form -> Bool
isBasic = any ((||) . is _NE <*> is _Gor) . universe
```

Or more generally, check whether a certain constructor was used.

```
hasCr :: Prism', Form fs -> Form -> Bool
hasCr = (. universe) . any . is
```

### 2.2 Semantics

We quickly recall the most important aspects of the semantics of BSML from [AAY24]. We interpret formulas on (Kripke) models, which consist of

- a set of worlds W;
- a binary relation  $R \subseteq W \times W$  between worlds;
- and a valuation  $V: W \to \wp(\mathsf{Prop})$  mapping a world to the propositions that hold in it. <sup>1</sup>

A team or state (we will use these terms interchangably) on a model is a subset  $s \subseteq W$ . To link back to the introduction, the worlds represent information-configurations and a team represents the worlds that a speaker perceives as possible.

As the name Bilateral State-based Modal Logic suggests, formulas are evaluated with respect to a team (rather than a world). The "bilateral" part refers to the fact that we make use of two fundamental semantics notions; support and anti-support, rather than just truth. Support (resp. antisupport) of a formula by a team represents the speaker's ability to assert (resp. reject) the formula, given the worlds deemed possible in the team.

```
{-# LANGUAGE MultiParamTypeClasses #-}
{-# LANGUAGE FlexibleInstances #-}
module Semantics where

import Syntax

import Data.List
import Data.Set (Set)
import Data.IntMap (IntMap)
import qualified Data.Set as Set
import qualified Data.IntMap as IntMap

import Test.QuickCheck
```

In our implementation, we will represent worlds as Int's and teams as lists of worlds. For the relation and valuation, we use IntMap's, which are conceptually identical to association lists with Int-valued keys, but allow for fast lookup of the successors and satisfied proposition letters of a world.

We also define the following shorthands for looking up successors and valuations of worlds, that allow us to treat rel and val as (partial) functions:

```
rel' :: KrM -> World -> Team
rel' = (IntMap.!) . rel

val' :: KrM -> World -> Set Proposition
val' = (IntMap.!) . val
```

<sup>&</sup>lt;sup>1</sup>In the paper, the valuation is defined as a function  $Prop \to \wp W$ , but this is easily seen to be equivalent.

To allow defining a (anti)support-relation for different structures as well, we use the following typeclasses, that contain a both a curried and uncurried version of the function for (anti)support for ease of use (only one is required to be provided; the other is the curried/uncurried equivalent).

```
class Supportable model state formula where
   support :: model -> state -> formula -> Bool
   support = curry (|=)

   (|=) :: (model, state) -> formula -> Bool
   (|=) = uncurry support

   {-# MINIMAL (|=) | support #-}

class Antisupportable model state formula where
   antisupport :: model -> state -> formula -> Bool
   antisupport = curry (=|)

   (=|) :: (model, state) -> formula -> Bool
   (=|) = uncurry antisupport

   {-# MINIMAL (=|) | antisupport #-}
```

Before we implement the semantics, we need a function that computes all pairs of teams whose union is a given team s. Naively, we may define e.g.

```
teamParts :: Team -> [(Team, Team)]
teamParts s = [(t,u) | t <- ps, u <- ps, sort . nub (t ++ u) == sort s]
where ps = subsequences s</pre>
```

Computationally however, this is incredibly expensive and will form a major bottleneck for the efficiency of the model checking. While finding such partitions is inherently exponential in complexity, we can still do better (at least on average) than the above:

```
teamParts :: Team -> [(Team, Team)]
teamParts s = do
    t <- subsequences s
    u <- subsequences t
    return (t, s \\ u)</pre>
```

Now, we are ready to define our semantics, in accordance to [AAY24]:

```
instance Supportable KrM Team Form where
  (\_,s) \mid = Bot
                    = null s
  (_,s) |= NE
                    = not (null s)
  (m,s) \mid = Prop n = all (elem n . val', m) s
  (m,s) = Neg f = (m,s) = | f
  (m,s) \mid = And f g = (m,s) \mid = f && (m,s) \mid = g
  (m,s) \mid = 0r f g = any ((t,u) \rightarrow (m,t) \mid = f && (m,u) \mid = g)  teamParts s
  (m,s) \mid = Gor f g = (m,s) \mid = f \mid \mid (m,s) \mid = g
  (m,s) \mid = Dia f
                    = all (any (t \rightarrow not (null t) && (m,t) |= f) . subsequences . rel' m) s
instance Antisupportable KrM Team Form where
        =| Bot
                    = True
  (_,s) =| NE
                     = null s
  (m,s) = | Prop n = not $ any (elem n . val, m) s
  (m,s) = | Neg f
                     = (m,s) |= f
  (m,s) = | And f g = any (\((t,u) -> (m,t) = | f && (m,u) = | g) $ teamParts s
  (m,s) = | Or f g = (m,s) = | f && (m,s) = | g
  (m,s) = | Gor f g = (m,s) = | Or f g
  (m,s) = | Dia f
                    = all (\w -> (m, rel'm w) = | f) s
```

One may also easily extend the above semantics to lists of formulae, as shown below.

```
instance Supportable KrM Team [Form] where
  support = (all .) . support

instance Antisupportable KrM Team [Form] where
  antisupport = (all .) . antisupport
```

#### 2.3 Random models

As for formulas, we want to be able to generate random models to verify properties of BSML, and will use QuickCheck for this.

We will need a function that generates a Set containing random elements of a list, so we define the following analogue of sublistOf:

```
subsetOf :: Ord a => [a] -> Gen (Set a)
subsetOf = (Set.fromList <$>) . sublistOf
```

When shrinking the valuation of models, we want to have QuickCheck try valuation with fewer propositions occurring in the model, but it does not make sense to shrink the values of the propositions, so we define the following functions to only shrink which propositions occur:

```
-- Shrink a list without shrinking individual elements
shrinkList' :: [a] -> [[a]]
shrinkList' = shrinkList (const [])

-- Shrink a set without shrinking individual values
shrinkSet :: Set Proposition -> [Set Proposition]
shrinkSet = fmap Set.fromList . shrinkList' . Set.toList

-- Shrink a valuation by uniformly restricting the occuring propositions
shrinkVal :: Val -> [Val]
shrinkVal v = do
  let allProps = Set.unions v
  newProps <- shrinkSet allProps
  return (Set.intersection newProps <$> v)
```

Then, an arbitrary model M = (W, R, V) can be generated as follows:

```
instance Arbitrary KrM where
arbitrary = sized $ \n -> do
```

The size parameter n gives an upper bound to the amount of worlds; we pick some  $k \leq n$  and define W = 0, 1, ..., k. For every  $w \leq k$ , we then generate a random set of successors R[w] and random set of propositions V(w) that hold at w.

```
k <- choose (0, n)
let ws = [0..k]
r <- IntMap.fromList . zip ws <$> vectorOf (k+1) (sublistOf [0..k])
v <- IntMap.fromList . zip ws <$> vectorOf (k+1) (subsetOf [1..numProps])
return (KrM ws r v)
```

When finding counterexamples, it is useful to find models that are as small as possible, so we also define shrink that tries to restrict the worlds of the model.

```
shrink m = do
   ws' <- init $ subsequences $ worlds m
  let r' = IntMap.fromList [(w, rel' m w 'intersect' ws') | w <- ws']
  let v' = IntMap.filterWithKey (const . ('elem' ws')) $ val m
  KrM ws' r' <$> shrinkVal v'
```

When testing, we will often want to generate a random model with a random team or world of that model. Generating a random Int or [Int] would not work then, since there is no guarantee that the generated value is a valid team/world in the model. To remedy that, we define wrappers for models with a team/world and define Arbitrary-instances for those wrappers:

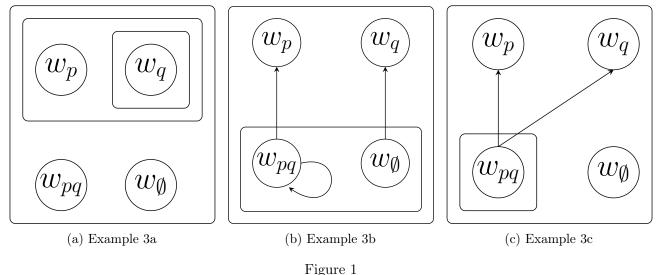
```
data TeamPointedModel = TPM KrM Team
deriving (Show)

data WorldPointedModel = WPM KrM World
```

```
deriving (Show)
instance Arbitrary TeamPointedModel where
 arbitrary = do
   m <- arbitrary
   s <- sublistOf $ worlds m
   return (TPM m s)
 shrink (TPM m s) = filter (\(TPM m' s') -> s' 'isSubsequenceOf' worlds m') (TPM <$>
      shrink m <*> shrinkList', s)
instance Arbitrary WorldPointedModel where
 arbitrary = do
   m <- arbitrary
   w <- elements $ worlds m
   return (WPM m w)
 shrink (WPM m w) = filter (\(WPM m' w') -> w' 'elem' worlds m') (WPM <$> shrink m <*> [w
```

Note that when shrinking, we should only allow shrinks where the world/team is still contained in the model.

### Verifying basic properties



We now use the library QuickCheck to randomly generate input for our functions and test some properties.

The following uses the HSpec library to define different tests. We use a mix of QuickCheck and specific inputs, depending on what we are testing for.

The "Figure 3" section corresponds to the three examples labeled 3a, 3b, and 3c [AAY24]. The paper gives a couple formulas per example to illustrate the semantics of BSML. We test each of these formulas to confirm our implementation contains the expected semantics.

The "Figure 3" section corresponds to the three examples labeled 3a, 3b, and 3c in Figure 1 and in the paper [AAY24]. The paper gives a couple formulas per example to illustrate the semantics of BSML. We test each of these formulas to confirm our implementation contains the expected semantics.

```
main :: IO ()
main = hspec $ do
 describe "Figure 3" $ do
```

```
it "Figure 3a1, p v q" $
(m3a, s3a1) |= (p 'Or' q) 'shouldBe' True it "Figure 3a1, (p ^ NE) v (q ^ NE)" $
 (m3a, s3a1) |= (And p NE 'Or' And q NE) 'shouldBe' False
it "Figure 3a2, (p ^ NE) v (q ^ NE)" $
 (m3a, s3a2) |= (And p NE 'Or' And q NE) 'shouldBe' True
it "Figure 3b, <>q" $
  (m3b, s3b) |= Dia q 'shouldBe' True
it "Figure 3b, <>p" $
 (m3b, s3b) |= Dia p 'shouldBe' False
it "Figure 3b, []q" $
 (m3b, s3b) |= box q 'shouldBe' False
it "Figure 3b, []p v []q" $
 (m3b, s3b) |= (box p 'Or' box q) 'shouldBe' True
it "Figure 3b, <>p ^ <>q" $
 (m3b, s3b) |= (Dia p 'And' Dia q) 'shouldBe' False
it "Figure 3c, <>(p v q)" $
  (m3c, s3c) |= Dia (p 'Or' q) 'shouldBe' True
```

Below we test the tautologies that should hold for BSML logic ensuring our implementation is correct. Here we use QuickCheck, but we need to limit the maximal size of the arbitrary models we generate. This is necessary because the evaluation of support in team semantics is inherently exponential in complexity (see e.g. the clause for support of disjunctions).

```
describe "Tautologies" $ modifyMaxSize (const 20) $ do
  modifyMaxSize (const 10) $ prop "box f <==> !<>!f" $
    \TPM m s) f \rightarrow (m,s) = box (f::Form) == (m,s) = Neg(Dia (Neg f))
  prop "<>(p v q) <==> <>p v <>q" $
    \TPM m s) -> (m,s) \mid = Dia (p 'Or' q) == (m,s) \mid = (Dia p 'Or' Dia q)
  prop "<>(p ^ q) ==> <>p ^ <>q"
  \((TPM m s) -> (m,s) |= Dia (p 'And' q) ==> (m,s) |= (Dia p 'And' Dia q) modifyMaxSize (const 25) $ prop "<>p ^ <>q !==> <>(p ^ q)" $
    expectFailure $ \(TPM m s) -> (m,s) |= (Dia p 'And' Dia q) ==> (m,s) |= Dia (p 'And'
        q)
  prop "box(p ^ q) <==> box p ^ box q" $
  \((TPM m s) -> (m,s) |= box (p 'And' q) == (m,s) |= (box p 'And' box q)
  prop "box p v box q ==> box(p v q)" $
    \TPM m s) -> (m,s) |= (box p 'Or' box q) ==> (m,s) |= box (p 'Or' q)
  modifyMaxSize (const 25) $ modifyMaxSuccess (const 1000) $ prop "box(p v q) !==> box p
    v box q" $
    expectFailure \ (TPM m s) \rightarrow (m,s) \mid = box (p 'Or' q) ==> (m,s) \mid = (box p 'Or' box q)
  prop "DeMorgan's Law" $
    \T = \mathbb{R}  (TPM m s) -> (m,s) |= Neg (p 'And' q)== (m,s) |= (Neg p 'Or' Neg q)
  prop "Dual-Prohibition, !<>(a v b) |= !<>a ^ !<>b" $
    \( TPM m s) \rightarrow (m, s) \mid = Neg (Dia (p 'Or' q)) == (m,s) \mid = (Neg(Dia p) 'And' Neg(Dia q) 
  prop "strong tautology is always supported" $
    \TPM m s) -> (m,s) |= toptop
  prop "strong contradiction is never supported" $
    \TPM m s) \rightarrow not $ (m,s) | = botbot
  modifyMaxSize (const 10) $ prop "p v ~p is never supported" $
    \(TPM m s) -> (m,s) |= (p 'Or' Neg p)
  prop "NE v ~NE *can* be supported" $
   expectFailure $ \((TPM m s) -> not $ (m,s) |= (top 'Or' Neg top)
  prop "strong tautology !== top" $
    expectFailure \ \(TPM m s) \rightarrow (m,s) \mid = toptop == (m,s) \mid = top
  where
      p = Prop 1
      q = Prop 2
```

# 3 Verifying inference

## 3.1 Pragmatic enrichment

To define the *pragmatic enrichment* function mentioned in the introduction, we define a type to represent formulas of basic Modal Logic (ML) and implement the standard Kripke semantics.

```
{-# LANGUAGE MultiParamTvpeClasses #-}
{-# LANGUAGE FlexibleInstances #-}
{-# LANGUAGE LambdaCase #-}
module ML where
import Syntax
import Semantics
import Test.QuickCheck
-- Basic Modal Logic formulas
data MForm
   MProp Proposition
  | MNeg MForm
  | MAnd MForm MForm
  | MOr MForm MForm
  | MDia MForm
  deriving (Eq,Show)
-- Kripke semantics
instance Supportable KrM World MForm where
  (m,w) |= MProp n = n 'elem' val' m w
(m,w) |= MNeg f = not $ (m,w) |= f
  (m,w) = MAnd f g = (m,w) = f && (m,w) = g
  (m,w) \mid = MOr f g = (m,w) \mid = f \mid \mid (m,w) \mid = g
  (m,w) \mid = MDia f
                     = any (\v -> (m,v) |= f) $ rel' m w
```

Formally, pragmatic enrichment is given by the function  $[\cdot]^+$ : ML  $\to$  BSML, defined as

```
\begin{split} [p]^+ &\coloneqq p \wedge \mathtt{NE} & \text{for } p \in \mathtt{Prop} \\ [\heartsuit \varphi]^+ &\coloneqq \heartsuit[\varphi]^+ \wedge \mathtt{NE} & \text{for } \heartsuit \in \{\neg, \lozenge\} \\ [\varphi \odot \psi]^+ &\coloneqq ([\varphi]^+ \odot [\psi]^+) \wedge \mathtt{NE} & \text{for } \odot \in \{\lor, \land\} \end{split}
```

which is straightforward to implement in Haskell.

```
-- The pragmatic enrichment function [.]+ : ML -> BSML.
enrich :: MForm -> Form
enrich (MProp n) = Prop n 'And' NE
enrich (MNeg f) = Neg (enrich f) 'And' NE
enrich (MDia f) = Dia (enrich f) 'And' NE
enrich (MAnd f g) = (enrich f 'And' enrich g) 'And' NE
enrich (MOr f g) = (enrich f 'Or' enrich g) 'And' NE
```

To test the semantic effect of enrichment, and some other properties of ML as a fragment of BSML, we also implement the canonical embedding of ML into BSML.

```
-- Embedding ML >-> BSML

toBSML :: MForm -> Form

toBSML (MProp n) = Prop n

toBSML (MNeg f) = Neg (toBSML f)

toBSML (MAnd f g) = And (toBSML f) (toBSML g)

toBSML (MOr f g) = Or (toBSML f) (toBSML g)

toBSML (MDia f) = Dia (toBSML f)
```

As the reader should expect at this point, we also implement an arbitrary instance for formulas of ML, which is completely analogous to that for BSML:

```
{\tt randomMProp} :: Gen MForm
randomMProp = MProp <$> choose (1, numProps)
instance Arbitrary MForm where
  arbitrary = sized $ \case
    0 -> randomMProp
     -> oneof [
      randomMProp.
      MNeg <$> f,
      MAnd < > f < * > f,
      MOr <$> f <*> f,
      MDia <$> f]
    where f = scale ('div' 2) arbitrary
  shrink (MNeg f)
                       = f
                                      [MNeg f'
                                                     | f'
  shrink (MDia f)
                       = f
                                      [MDia f'
                                                     | f'
                                                                  <- shrink f]
                      = [f1, f2] ++ [MAnd f1', f2'
                                                    | (f1',f2') <- shrink (f1,f2)]
  shrink (MAnd f1 f2)
                       = [f1, f2] ++ [MOr f1', f2', | (f1', f2')
  shrink (MOr f1 f2)
                                                                 <- shrink (f1,f2)]
  shrink
                       = []
```

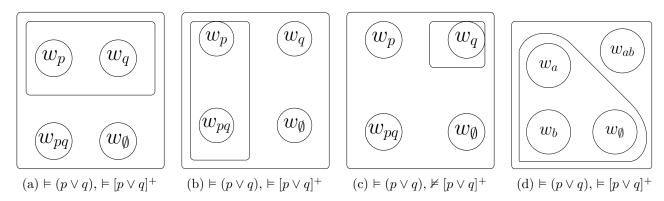


Figure 2

### 3.2 Free-Choice inference

The way FC-inference is now modelled, is that given a formula/statement like  $\Diamond(\alpha \vee \beta)$  in ML, we enrich it to obtain a formula BSML:

$$[\lozenge(\alpha \vee \beta)]^+ = \lozenge((\alpha \wedge NE) \vee (\beta \wedge NE)) \wedge NE$$

This formula more accurately represents the meaning of a sentence in linguistics, given speakers' distaste for null verification. To accurately model FC, we should then be able to infer  $\Diamond \alpha \wedge \Diamond \beta$  from  $[\Diamond (\alpha \vee \beta)]^+$ .

### 3.3 Testing Enrichment and FC

We can use the library QuickCheck to test the enriched behavior of our implementation of BSML, to make sure we correctly implemented FC.

The following uses the HSpec library to define different tests. We use a mix of QuickCheck and specific inputs, depending on what we are testing for.

The "Figure 3" section in the tests corresponds to Figure 1 described above in a previous section of the paper. The "Motivating Example" uses the Figure 2 models in order to show our disjunction behaves as expected. The paper [AAY24] describes some formulas that make use of enrichment that must hold in these models.

```
main :: IO ()
main = hspec $ do
      describe "Figure 3" $ do
             it "Figure 3b, [<>(p ^ q)]+"$
                   (m3b, s3b) |= enrich (MDia (ma 'MAnd' mb)) 'shouldBe' False
             it "Figure 3c, [<>(p v q)]+" $
                    (m3c, s3c) |= enrich (MDia (ma 'MOr' mb)) 'shouldBe' True
      describe "Motivating Example" $ do
             it "(a) |= (a v b) == True" $
                  (mM, sMA) |= toBSML (ma 'MOr' mb) 'shouldBe' True
             it "(a) |= [a v b]+ == True" $
                    (mM, sMA) |= enrich (ma 'MOr' mb) 'shouldBe' True
             it "(b) |= (a v b) == True" $
                  (mM, sMB) |= toBSML (ma 'MOr' mb) 'shouldBe' True
             it "(b) |= [a v b]+ == True" $
                    (mM, sMB) |= enrich (ma 'MOr' mb) 'shouldBe' True
             it "(c) |= (a v b) == True" $
                   (mM, sMC) |= toBSML (ma 'MOr' mb) 'shouldBe' True
             it "(c) |= [a v b]+ == False" $
                    (mM, sMC) |= enrich (ma 'MOr' mb) 'shouldBe' False
             it "(d) |= (a v b) == False" $
                    (mM, sMD) |= toBSML (ma 'MOr' mb) 'shouldBe' False
              it "(d) |= [a v b]+ == False" $
                    (mM, sMD) |= enrich (ma 'MOr' mb) 'shouldBe' False
             prop "Arbitrary |= (a v b) !== Arbitrary |= [a v b]+ == False" $
                    expectFailure \ \(\text{TPM m s}) \rightarrow (\text{m,s}) = \text{toBSML (ma 'MOr' mb)} == (\text{m,s}) = \text{enrich (ma 'mor' mb)} == (\text{m,s}) = (\text{m
                                MOr' mb)
```

Narrow-scope and wide-scope relate to the "pragmatic enrichment function," and these tests confirm that FC-inference holds in our implementation. The flatness test confirms that our implementation of team semantics is flat on ML-formulas.

```
describe "Properties from Paper" $ modifyMaxSize (const 25) $ do
    prop "NarrowScope, <>(a v b) = | (<>a ^ <>b)" $
        \(TPM m s) -> (m,s) |= enrich (MDia (ma 'MOr' mb)) == (m,s) |= enrich (MDia ma 'MAnd' MDia mb)
    prop "Wide Scope, <>a v <>b) = | <>a ^ <>b" $
        \(TPM m s) -> all (\w -> rel' m w == s) s <= ((m,s) |= enrich (MDia ma 'MOr' MDia mb ) <= (m,s) |= enrich (MDia ma 'MAnd' MDia mb))

describe "Flatness" $ modifyMaxSize (const 15) $ do
    modifyMaxSize (const 10) $ prop "(M,s) |= f <==> M,{w} |= f forall w in s" $
        \(TPM m s) f -> (m,s) |= toBSML (f::MForm) == all (\w -> (m, [w]) |= toBSML f) s
        prop "M,{w} |= f <==> M,w |= f" $
        \(WPM m w) f -> (m, [w]) |= toBSML (f::MForm) == (m,w) |= f
        prop "Full BSML is *not* flat" $ expectFailure $
        \(TPM m s) f -> (m,s) |= (f::Form) == all (\w -> (m, [w]) |= f) s
```

We also test our ability to correctly parse and pretty print, however the specifics of these functions are explained in the following sections.

```
describe "Pretty Print and Parsing" $ do
  prop "formula -> prettyPrint -> Parsing == original formula" $
    \f -> parseFormula (ppForm (f::Form)) == Right f
where
    ma = MProp 1
    mb = MProp 2
```

To run the all the tests, use stack test.

# 4 Lexing and Parsing BSML Formulae

### 4.1 Lexing

Below we describe our code for lexing and parsing BSML formulas. We use the well-known tools Alex and Happy for lexing and parsing, respectively. This code is partially inspired by [Dvo18].

We start by telling Alex how to recognize certain (series of) symbols in the string we will be parsing and turn them into the corresponding token. These tokens are symbols that are assigned some meaning while a string is being parsed. Our set of tokens are defined in a separate file, Token.hs, which is omitted here since it is utterly uninspiring.

```
module Lexer where
import Token
%wrapper "posn"
$dig = 0 -9 -- digits
tokens:-
-- ignore whitespace and comments :
$white + ;
-- keywords and punctuation :
     { \ p _ -> TokenCB p }
"_|_" { \ p _ -> TokenBot p }
"NE" { \ p _ -> TokenNE p}
"[]"
    { \ p _ -> TokenBox p
    { \ p _ -> TokenDmd p
     { \ p _ -> TokenNot p
11 & 11
     { \ p _ -> TokenCon p
     { \ p _ -> TokenDis p }
-- Integers and Strings :
dig + { p s -> TokenInt (read s) p}
[p - z] \{ p s \rightarrow TokenPrp (ord (head s) - ord 'p' + 11) p \}
```

This file, Lexer.x is not a valid Haskell file, it is only meant to be input to Alex. A user may run alex Lexer.x to generate Lexer.hs, a fully functioning lexer for the above tokens built by Alex.

#### 4.2 Parsing

We now take a look at the code for the parser, which works using Happy. We first import the modules, including Lexer, that we require to run the parser.

```
> {
> module Parser where
>
> import Data.Char
> import Token
> import Lexer
> import Syntax
> import Semantics
> import ML
> }
```

Below, we describe the tokens that Happy needs to keep track of while reading the string. These tokens are congruent with those in the module Lexer.

```
> %name formula
> %tokentype { Token AlexPosn }
> %monad { ParseResult }
>
> %token
> BOT { TokenBot _ }
> NE {TokenBot _ }
> AND { TokenCon _ }
> OR { TokenDis _ }
> NOT { TokenNot _ }
> BOX { TokenBox _ }
> DMD { TokenDmd _ }
> ORDIS {TokenDmd _ }
> CDIS {TokenDis _ }
> NUM { TokenInt $$ _ }
> NUM { TokenInt $$ _ }
> '(' { TokenOB _ }
> ')' { TokenOB _ }
```

We describe also the binding hierarchy for binary operators in our language. The order of precedence is described by listing operators from weakest to strongest, as evidenced below. Note that the binding for all unary operators is stronger than the binding for binary operators, and unary operators operate at the same binding strength. This behaviour keeps in line with the way we would like to parse formulas in our language.

```
> %left OR
> %left AND
> %left GDIS
>
> %%
```

We now detail two different types of formulas - bracketed formulas and non-bracketed formulas. The reasoning for the distinction is rather simple - the presence of parentheses around a formula requires that any operations within the parentheses need to be given priority over operations outside of them. This may break regular precedence rules, and hence need to be accounted for.

```
> Form :: { Form }
> Form : BrForm { $1 }
> | Form AND Form { And $1 $3 }
> | Form GDIS Form { Or $1 $3 }
> | Form GDIS Form { Gor $1 $3 }
> BrForm :: { Form }
> BrForm : NUM { Prop $1 }
> | BOT { Bot }
> | NE { NE }
> | NOT BrForm { Neg $2 }
> | BOX BrForm { Syntax.box $2 }
> | DMD BrForm { Dia $2 }
> | '(' Form AND Form ')' { And $2 $4 }
> | '(' Form GDIS Form ')' { Or $2 $4 }
> | '(' Form GDIS Form ')' { Gor $2 $4}
```

Next, we define error messages for our parser, as in [Dvo18]. These error messages describe where the error occurs exactly in the string, and why Happy failed to parse it.

```
> happyError ( t : ts ) = Left $
                                    , pe_msg = " Parse error : " , pe_col = col }
       ParseError { pe_str = " "
>
       where ( AlexPn abs lin col ) = apn t
>
> myAlexScan :: String -> ParseResult [ Token AlexPosn ]
> myAlexScan str = go ( alexStartPos , '\n' ,[] , str )
    where
        go :: AlexInput -> ParseResult [ Token AlexPosn ]
>
        go inp@( pos ,_ ,_ , str ) =
             case alexScan inp 0 of
>
                 AlexEOF -> Right []
                 AlexError (( AlexPn _ _ column ) ,_ ,_ , _ ) -> Left $
ParseError { pe_str = str , pe_msg = " Lexical error : " , pe_col =
>
>
    column -1}
                  AlexSkip inp' len -> go inp'
>
>
                  AlexToken inp' len act -> go inp'
                      (\ x -> Right \$ act pos ( take len str ) : x )
```

Finally, we describe the actual parsing function itself, called parseFormula. Upon running happy Parser.ly, we get a Haskell file Parser.hs which contains the parseFormula function. The output for parseFormula is of type Either ParseError Form, since parser might fail (on invalid input).

```
> parseFormula :: String -> ParseResult Form
> parseFormula str = go $ myAlexScan str >>= formula
> where
> go ( Left err ) = Left $ err { pe_str = str }
> go ( Right res ) = Right res
> }
```

## 5 An Executable Function

We now describe a simple executable function. Upon running main, the function asks the user to provide a BSML formula as input. Using the parser, we parse this string, and try to come up with an example that does not satisfy the formula.

Note that as with any other QuickCheck based testing suite, the function's inability to find a counter-example does not suggest that one does not exist! Below, we have a function that runs 100 tests (as standard, as we will soon see), which is usually sufficient to find a counter-example.

```
module Main where
import Syntax
import Semantics
import Parser
import Test.QuickCheck
import Text.Read (readMaybe)
```

After importing the necessary modules, we describe two small helper functions. The first is simply for notational convenience: we use it to check whether a given model falsifies a given formula.

The second uses QuickCheck to generate arbitrary models, and terminates when it finds a model falsifying the given formula.

```
falsifies :: TeamPointedModel -> Form -> Bool
falsifies (TPM m s) f = not ((m, s) |= f)

findCounterexample :: Form -> Int -> IO ()
findCounterexample f n = quickCheck (withMaxSuccess n ('falsifies' f))
```

The main function asks the user to provide a BSML formula as a string. It first checks that the string represents a well-formed formula using the parser, and then uses the helper functions above to produce (if it can find such an example, of course!) a model and a team that falsify the formula provided by the user. The user is also asked to specify the maximum number of tests they wish to run within the function. The default number of tests is fixed at 100.

### 6 Natural Deduction

This section explains the implementation of Natural Deduction proofs for BSML. Our code should still be considered *Work in progress*, but already has useful functionality, with clear potential for future extensions and/or improvements.

Since we want users of this module to solely be able to construct proofs using the supplied axioms, we explicitly name the exports of this module and omit the constructor for the Proof-type.

```
module ND
(
Proof
, sorry
, assume
-- Rules
.
.
.
.
```

To represent an ND-proof, we use the Proof-type, which stores the conclusion of the proof and all of its open (non-discharged) assumptions. We use a Set to represent proofs to allow easy omission of duplicates and removal (discharges) of assumptions. For the sake of simplicity, we decided not to store the entire ND-tree leading to a conclusion, but it would be a straightforward adaptation to make, if desired.

Next, we define a function to represent making a new assumption in a proof; given any formula  $\varphi$ , it returns the proof with conclusion  $\varphi$  and open assumptions  $\{\varphi\}$ .

```
assume :: Form -> Proof
assume = Prf <*> Set.singleton
```

Further, we define some functions for convenience. Here, sorry completely subverts our system by creating a proof for any conclusion and set of assumptions, but it can be useful for users as a placeholder value in proofs. It is similar to Lean's sorry, and triggers a warning anytime it is used. The hasNE and hasGor functions check whether a formula uses the NE or Gor constructor anywhere, which is needed for checking some side-conditions on ND-rules. Recall that hasCr was defined in 2.1.2.

```
sorry :: Form -> Set Form -> Proof
sorry = Prf
{-# WARNING sorry "Proof uses sorry!" #-}

-- Used for checking side-conditions
hasNE :: Form -> Bool
hasNE = hasCr _NE
hasGor :: Form -> Bool
hasGor = hasCr _Gor
```

Now, we can define all of the rules axiomatizing BSML, as proven in [AAY24] (see Chapter 4). There are quite a lot of rules (32 to be exact, we implemented all of them!), so we will not show all of them here, but we will highlight a few to give a good idea of the implementations.

Take e.g. the rule  $\forall I$ , which introduces  $\varphi \lor \psi$  from a proof of  $\varphi$  under the condition that  $\psi$  does not contain NE. This is implemented as:

```
-- (c) Rules for v

orIntroR :: Form -> Proof -> Proof
orIntroR g (Prf f ass)

| hasNE g = error "Cannot vIntro a formula containing NE!"
| otherwise = Prf (Or f g) ass
```

For a more complicated example, we can consider  $\vee E$ , the rule for disjunction-elimination:

Note in particular how we use a combination of guards and pattern matching to ascertain whether the formulas have the correct form and that all the side-conditions are met.

For the sake of completeness, we wil also show  $\square$ Mon, a rule involving modal operators and an interesting side condition: for every assumptions  $\varphi$  of the first proof,  $\square \varphi$  should be the conclusion of one of the latter proofs. Also note how we use **foldMap** to extract the assumptions from each of the latter proofs and take their union.

```
boxMon :: Proof -> [Proof] -> Proof
boxMon (Prf g ass) ps
    | Set.map box ass 'Set.isSubsetOf' Set.fromList (map conclusion ps) =
          Prf (box g) $ foldMap assumptions ps
          | otherwise = error "Cannot apply []Mon, former proof has undischarged assumptions!"
```

# 7 Future work

- Nicer user interface
- Efficiency (using implicit model checking, like SMCDEL)
- Automated proof search

# References

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