



Wire numbers 200-001 through 200-006 will control the servo motors on the robotic arm as follows:
200-201: Turn Table
200-202: Shoulder Joint
200-203: Elbow Joint
200-204: Wrist Joint
200-205: Wrist Turn Joint
200-206: End Effector Grab
200-207: Chassis Turntable
200-208: Shooting Mechanism Reload