200-201 ←		Turn Table Servo Motor
200-202 -		Shoulder Joint Servo Motor
200-203 ←		Elbow Joint Servo Motor
200-204 ←		Wrist Joint Servo Motor
200-205 ←		Wrist Turn Joint Servo Motor
200-206 ←		End Effector Grab Servo Motor
200-207 4		Chassis Turn Table Servo Motor
200-208 ←		Shooting Mech Reload Servo Motor
	Wire numbers 200-001 through 200-006 will control the seas follows: 200-201: Turn Table 200-202: Shoulder Joint 200-203: Elbow Joint 200-204: Wrist Joint 200-205: Wrist Turn Joint 200-206: End Effector Grab 200-207: Chassis Turntable 200-208: Shooting Mechanism Reload	ervo motors on the robotic arm 200-201