Computer Science

Fall 2024: CSCI 181RT Real-Time Systems in the Real World

Lecture 22

Tuesday, November 12, 2024 Edmunds Hall 105 2:45 PM - 4:00 PM

Professor Jennifer DesCombes



Agenda

- Go Backs
- Discussion on Assignments
- Software Package Structure Functional & Data Privacy
- Lab #11 Preview
- Look Ahead
- Assignment
- Action Items



Go Backs

- General?
- Announcements
 - Lab Tomorrow (13 November) Will End at 3:30
 - No Lecture on Tuesday, 26 November 2024
- Action Item Status
 - Al240910-2: Find recommended book on computer architecture.
 - Al240924-1: At what point as a development team grows does it make sense to have dedicated software and integration testers?
 - Al241024-1: Provide documentation on how to disable compiler optimization.
 - Al241107-1: Generate drawing showing location of Task Test Points on evaluation board.



Discussion on Readings

- The Soul Of A New Machine
 - Chapters 5 and 6: Midnight Programmer, Flying Upside Down



Discussion on Readings

- The Soul Of A New Machine
 - Chapters 5 and 6: Midnight Programmer, Flying Upside Down



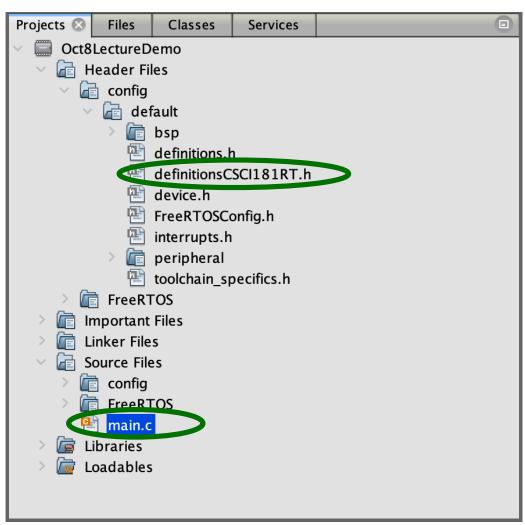
Software Package Structure - Functional & Data Privacy

- Arrangement of Files and Folders
- Arrangement of Code in Project Viewer
- Minimize Code Interdependency / Knowledge
- Reduce Risk of Inadvertent Edits / Corruption
- Maximize Reuse of Functions
- Maximize Understanding of Each File



Software Package Structure - MPLab Structure

- Base Structure of Distributed RTOS Lab Template in MPLab
- Added Files:
 - main
 - definitionsCSCI181RT.h
- All Code in Single File





Software Package Structure - MPLab Structure

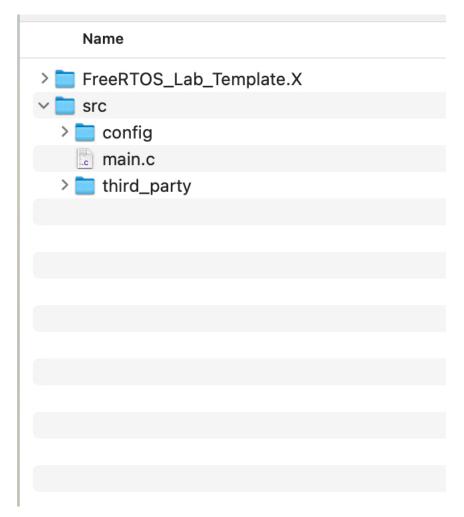
- Microchip Code Files Partitioned / Divided by Functionality
- Include Files are Also Similarly Partitioned





Software Package Structure - Host Structure

- File Folder Structure on Host Computer
- Not Necessarily Same as MPLab File Structure

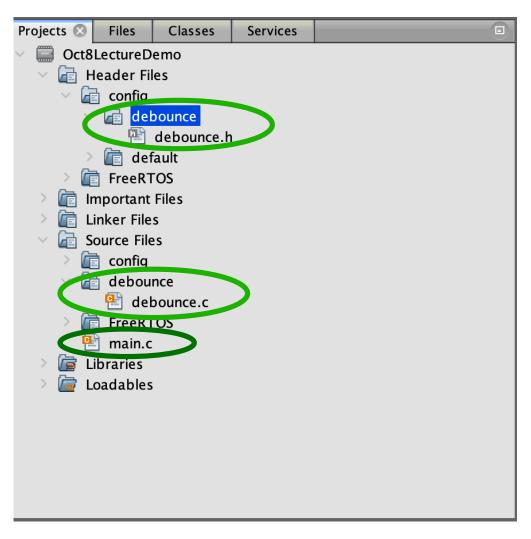




Software Package Structure - MPLab Structure

- Debounce Function Used as Case Study
- Logical Folders Used Within MPLab (right click)
- Not related to Physical Location of Source File

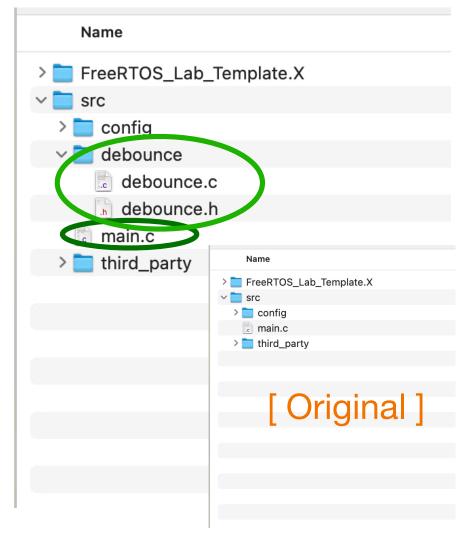
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Software Package Structure - Host Structure

- File Folder Structure on Host Computer
- Not Necessarily Same as MPLab File Structure
- Both .c and .h in Same Folder for Portability
- Other Files Could Be Included
 - Test Files
 - Functional Descriptive
 Files
 - ???





- Original main.c Includes and Data Types
- "definitionsCSCI181RT.h" is only added file
- typedef for Structures Used Within main.c

```
□ #include <stddef.h>
  #include <stdbool.h>
  #include <stdlib.h>
  #include "definitions.h"
  #include "definitionsCSCI181RT.h"
  #include "FreeRTOS.h"
  #include "task.h"
  #include "semphr.h"
 // Type Declarations
□ typedef struct {
      int buttonValue;
      int buttonSameCount;
      bool buttonStatusChange;
  } debounceStruct;
□ typedef struct {
      int pwmLevelMinCount;
      int pwmLevelMaxCount;
      int pwmCountMaximum;
       int pwmCount;
   } pwmStruct:
```



- Improved main.c Includes and Data Types
- "debounce.h" is added
 - Note Folder Directory Listing
- The typedef for 'debounceStruct' has been removed from main.c

```
#include <stddef.h>
#include <stdbool.h>
#include <stdlib.h>
#include "definitions.h"
#include "definitionsCSCI181RT.h"
#include "debounce/debounce.h"
#include "FreeRTOS.h"
#include "task.h"
#include "semphr.h"
typedef struct {
     int pwmLevelMinCount;
     int pwmLevelMaxCount;
     int pwmCountMaximum;
     int pwmCount;
  pwmStruct:
```



Improved main.c Includes and Types - Side-by-side

```
□ #include <stddef.h>
  #include <stdbool.h>
  #include <stdlib.h>
  #include "definitions.h"
  #include "definitionsCSCI181RT.h"
 #include "debounce/debounce.h"
  #include "FreeRTOS.h"
  #include "task.h"
  #include "semphr.h"
  // Type Declarations
□ typedef struct {
      int pwmLevelMinCount;
      int pwmLevelMaxCount;
      int pwmCountMaximum;
      int pwmCount;
   } pwmStruct:
```

```
#include <stddef.h>
  #include <stdbool.h>
  #include <stdlib.h>
  #include "definitions.h"
  #include "definitionsCSCI181RT.h"
  #include "FreeRTOS.h"
  #include "task.h"
  #include "semphr.h"
          [ Original ]
  // Type Declarations
  typedef struct {
      int buttonVolue;
      int butconsameCount;
      bool buttonStatuschange;
   debounceStruct:
□ typedef struct {
      int pwmLevelMinCount;
      int pwmLevelMaxCount;
      int pwmCountMaximum;
      int pwmCount;
  } pwmStruct;
```



- Original main.c Function Prototypes
- Includes Prototype for 'debounceInput' Method

```
void vP1Task(void *pvParameters);  // Highest Priority Task (P1)
void vP2Task(void *pvParameters);  // Task Priority 2 (P2)
void vP3Task(void *pvParameters);  // Task Priority 3 (P3)
void vP4Task(void *pvParameters);  // Task Priority 4 (P3)
void dummyTask(void *pvParameters);  // Lowest Priority Task
void monitorGPIO1PinState( void );
ledStates pwmProcessing( int currentLevel, pwmStruct *pwmStructure );
void debounceInput( int currentInput, debounceStruct *inputStructure );
void levelLED3Adjust( void );
```



- Improved main.c Function Prototypes
- Removes Prototype for 'debounceInput' Method
- Function Prototype for this Method Now Contained within "debounce.h"

```
void vP1Task(void *pvParameters);  // Highest Priority Task (P1)
void vP2Task(void *pvParameters);  // Task Priority 2 (P2)
void vP3Task(void *pvParameters);  // Task Priority 3 (P3)
void vP4Task(void *pvParameters);  // Task Priority 4 (P3)
void dummyTask(void *pvParameters);  // Lowest Priority Task
void monitorGPIO1PinState( void );
ledStates pwmProcessing( int currentLevel, pwmStruct *pwmStructure );
void levelLED3Adjust( void );
```



Improved main.c Function Prototypes - Side-by-side

```
// Method Definitions
                                    // Highest Priority Task (P1)
void vP1Task(void *pvParameters);
void vP2Task(void *pvParameters);
                                     // Task Priority 2 (P2)
void vP3Task(void *pvParameters);
                                    // Task Priority 3 (P3)
void vP4Task(void *pvParameters);
                                    // Task Priority 4 (P3)
void dummyTask(void *pvParameters);
                                    // Lowest Priority Task
void monitorGPIO1PinState( void );
ledStates pwmProcessing( int currentLevel, pwmStruct *pwmStructure );
void levelLED3Adjust( void );
     // Method Definitions
     void vP1Task(void *pvParameters);  // Highest Priority Task (P1)
     void vP2Task(void *pvParameters);
                                          // Task Priority 2 (P2)
                                            // Task Priority 3 (P3)
     void vP3Task(void *pvParameters);
                                           ask Priority 4 (P3)
     void vP4Task(void *pvParameters)
     void dummyTask(void *pvParameters);
      void monitorGPIO1PinState( void );
     ledStates pwmProcessing( int currentLevel, pwmStruct *pwmStructure );
      void debounceImput( int currentImput, debounceStruct *imputStructure ),
      void levelLED3Adjust( void );
```



- Original main.c and improved main.c Have Identical Global Variables
- Globals Required When Multiple Tasks Share Data
 - Other Data Sharing Schemes Could be Implemented
 - Limitations on Data Integrity

```
// Global Data Declarations
// Global data used by fiveMSProcessing()
int gIntInputSignalState;
int gIntLevelControl;
// Global data used by PWM code
pwmStruct qPWMLED3;
pwmStruct gPWMLEDRGB;
// Global data used by button de-bounce code
debounceStruct gDebounceButton1;
debounceStruct gDebounceButton2;
debounceStruct gDebounceButton3;
debounceStruct gDebounceButton4;
```



- Original main.c Variable Initialization
- main.c Needs to Utilize / Understand Structure Elements

```
// Initialize global data
gIntInputSignalState = 1;
gIntLevelControl = levelInitialCount;
gPWMLED3.pwmLevelMaxCount = levelMaxCount;
gPWMLED3.pwmLevelMinCount = levelMinCount;
gPWMLED3.pwmCount = 0;
gPWMLED3.pwmCountMaximum = levelMaxCount;
gPWMLEDRGB.pwmLevelMaxCount = levelMaxCount;
gPWMLEDRGB.pwmLevelMinCount = levelMinCount;
gPWMLEDRGB.pwmCount = 0;
gPWMLEDRGB.pwmCountMaximum = levelMaxCount;
gDebounceButton1.buttonValue = 0,
gDebounceButton1.buttonSameCount = 0;
gDebounceButton1.buttonStatusChange = false;
gDebounceButton2.buttonValue = 0;
gDebounceButton2.buttonSameCount = 0;
gDebounceButton2.buttonStatusChange = false;
gDebounceButton3.buttonValue = 0;
gDebounceButton3.buttonSameCount = 0;
gDebounceButton3.buttonStatusChange = false;
gDebounceButton4.buttonValue = 0;
gDebounceButton4.buttonSameCount = 0;
gbehounceButton4.buttonStatusChange = false;
```



- Improved main.c Variable Initialization
- main.c DOES NOT Need to Utilize / Understand Structure Elements

```
// Initialize global data
gIntInputSignalState = 1;
gIntLevelControl = levelInitialCount;
gPWMLED3.pwmLevelMaxCount = levelMaxCount;
qPWMLED3.pwmLevelMinCount = levelMinCount;
gPWMLED3.pwmCount = 0;
qPWMLED3.pwmCountMaximum = levelMaxCount;
gPWMLEDRGB.pwmLevelMaxCount = levelMaxCount;
gPWMLEDRGB.pwmLevelMinCount = levelMinCount;
gPWMLEDRGB.pwmCount = 0;
gPWMLEDRGB.pwmCcarravaXimum = levelMaxCount;
initDebounceInput( &gDebounceButton1,
                                          // Pointer to de-bounce data structure
                   3);
                                          // Number of sequential states for de-bounce
initDebounceInput( &gDebounceButton2,
                                          // Pointer to de-bounce data structure
                   3);
                                          // Number of sequential states for de-bounce
initDebounceInput( &qDebounceButton3,
                                          // Pointer to de-bounce data structure
                   3):
                                          // Number of sequential states for de-bounce
initDebounceInput( &gDebounceButton4,
                                          // Pointer to de-bounce data structure
                                          // Number of sequential states for de-bounce
                   3);
```



Improved main.c Variable Initialization - Side-by-side

```
gIntLevelControl = levelInitialCount;
                                                                             gPWMLED3.pwmLevelMaxCount = levelMaxCount;
                                                                             qPWMLED3.pwmLevelMinCount = levelMinCount;
                                                                             gPWMLED3.pvmCountry
                                                                             gPWMLED3.pvmCountMaxinum = 'deve' MaxCount;
                                                                             gPWMLEDRGB.pwmLevelMaxCount = levelMaxCount;
// Initialize global data
                                                                             gPWMLEDRGB.pwmLevelMinCount = levelMinCount;
gIntInputSignalState = 1;
                                                                             gPWMLEDRGB.pwmCount = 0;
gIntLevelControl = levelInitialCount;
                                                                             gPWMLEDRGB.pwmCountMaximum = levelMaxCount;
qPWMLED3.pwmLevelMaxCount = levelMaxCount;
                                                                             QebounceButton1.buttonValue = 0;
gPWMLED3.pwmLevelMinCount = levelMinCount;
                                                                             gDebcunceButton1.buttonSameCount = 0;
gPWMLED3.pwmCount = 0;
                                                                             gDebounceButton1.buttonStatusChange = false;
gPWMLED3.pwmCountMaximum = levelMaxCount;
                                                                             qDebounceButton2.buttonValue = 0;
gPWMLEDRGB.pwmLevelMaxCount = levelMaxCount;
                                                                             gDebounceButton2.buttonSameCount = 0;
qPWMLEDRGB.pwmLevelMinCount = levelMinCount;
                                                                             gDebounceButton2.buttorStatusChange = false;
gPWMLEDRGB.pwmCount = 0;
                                                                             gDebounceButton3.buttonvalue = 0;
gPWMLEDRGB.pwmCountMaximum = levelMaxCount;
                                                                             gDebounceButtop2.buttonSamecount = 0;
                                                                             gDebounceButcon3.buttonStatusCharge = false;
                                                                             gDebourgeButton4.buttonValue = 0;
initbenounceInput( &gDebounceButton1,
                                           // reinter to de-bounce data :
                                                                             gDebounceButton4.buttonSameCount = 0;
                   3):
                                           // Number of sequential state:
                                                                             gDebounceButton4.buttonStatusChange = false;
                                           // Pointer to 8
initDebounceInput( &gDebounceButton2,
                                                           e-bounce data :
                   3);
                                           // Number of sequential states ron de-pounce
                                           // Pointer to de-bounce data structure
initDebounceInput( &gDebounceButton3,
                   3);
                                           // Number of sequential states for de-bounce
initDebounceInput( &gDebounceButton4,
                                           // Pointer to de-bounce data structure
                                           // Number of sequential states for de-bounce
```

// Initialize global data
gIntInputSignalState = 1;



 Original main.c and improved main.c Have Identical Global Calls to 'debounceInput' Method

```
// De-bounce pushbutton inputs
debounceInput( GPI0_PinRead( PushButton_1 ), &gDebounceButton1 );
debounceInput( GPI0_PinRead( PushButton_2 ), &gDebounceButton2 );
debounceInput( GPI0_PinRead( PushButton_3 ), &gDebounceButton3 );
debounceInput( GPI0_PinRead( PushButton_4 ), &gDebounceButton4 );
```



- Original main.c Accessing of Pushbutton States
- main.c Needs to Utilize / Understand Structure Elements

```
if (gDebounceButton3.buttonValue == ) // NOTE: button pushed
       gIntLevelControl -= 1;
       if (gIntLevelControl < levelMinCount)</pre>
          gIntLevelControl = levelMinCount;
 (gDebounceButton4.buttonStatusChange = true)
      (gDebounceButton4.buttonValue == 0) / NOTE: button pushed
       gIntLevelControl += 1;
       if (gIntLevelControl > levelMaxCount)
          gIntLevelControl = levelMaxCount;
```



- Improved main.c
 Accessing of Pushbutton
 States
- main.c DOES NOT Need to Utilize / Understand Structure Elements

```
// Decrease level by pressing button 3
qetDebounceStatusChange( &gDebounceButton3 == true)
  If (getDebounceValue( &gDebounceButton3 ) ==> )
       gIntLevelControl -= 1;
       if (gIntLevelControl < levelMinCount)</pre>
           gIntLevelControl = levelMinCount;
// Increase level by pressing button 4
 qetDebounceStatusChange( &gDebounceButton4 >> == true)
 If (getDebounceValue( &gDebounceButton4 ) ==>)
       gIntLevelControl += 1;
       if (gIntLevelControl > levelMaxCount)
           gIntLevelControl = levelMaxCount;
```



Improved main.c Accessing of Pushbutton States - Side-by-side

```
if (getDebounceStatusChange( &gDebounceButton3 ) == +=>)
{
   if (getDebounceValue( &gDebounceButton3 ) == 0) //->TE: but1
   {
      gIntLevelControl -= 1;
      if (gIntLevelControl < levelMinCount)
      {
            gIntLevelControl = levelMinCount;
      }
   }
}

// Increase level by process settend
if (getDebounceStatusChange( &gDebounceButton4 ) == true

{
   if (getDebounceValue( &gDebounceButton4 ) == 0) // N=>E: but1
   {
      gIntLevelControl += 1;
      if (gIntLevelControl > levelMaxCount)
      {
            gIntLevelControl = levelMaxCount;
      }
   }
}
```



- So Why Bother?
- Debounce Code Can be Enhanced / Modified Without Impacting Code Users
- Reduce Risk of Inadvertent Edits / Corruption
- Maximize Reuse of Functions
- Maximize
 Understanding of Each
 File

```
// NOTE: do not access the individual elements of the structure
      // as the type, name, and location of these elements may change as
      // improvements are made to the code. Use the access methods to
      // access information about the de-bounced pushbutton.
      typedef struct {
          int buttonEndCount:
          int buttonValue;
          int buttonSameCount;
          bool buttonStatusChange;
          int buttonTime;
      } debounceStruct;
   Initialize data within the debounce structure
void initDebounceInput( debounceStruct *inputStructure, int debounceMaxCount )
   inputStructure->buttonEndCount = debounceMaxCount;
   inputStructure->buttonValue = 0;
   inputStructure->buttonSameCount = 0;
   inputStructure->buttonStatusChange = false;
   inputStructure->buttonTime = 0;
    [ Code Compiled and Executed
        Properly Without Modifying
                      Other Files
                                                             26
```



What Additional Partitioning Should Be Performed?

```
void vP1Task(void *pvParameters);  // Highest Priority Task (P1)
void vP2Task(void *pvParameters);  // Task Priority 2 (P2)
void vP3Task(void *pvParameters);  // Task Priority 3 (P3)
void vP4Task(void *pvParameters);  // Task Priority 4 (P3)
void dummyTask(void *pvParameters);  // Lowest Priority Task
void monitorGPIO1PinState( void );
ledStates pwmProcessing( int currentLevel, pwmStruct *pwmStructure );
void levelLED3Adjust( void );
```



Lab 11 Preview

- Use Newest Version of Template with RTOS
 - Improved Partitioning with Functional & Data Privacy
- Incorporate Hardware Input Capture Function
 - Digital Input via Function Generator
 - Assess Capture Rate Improvement
- Lab Will End 30 Minutes Early



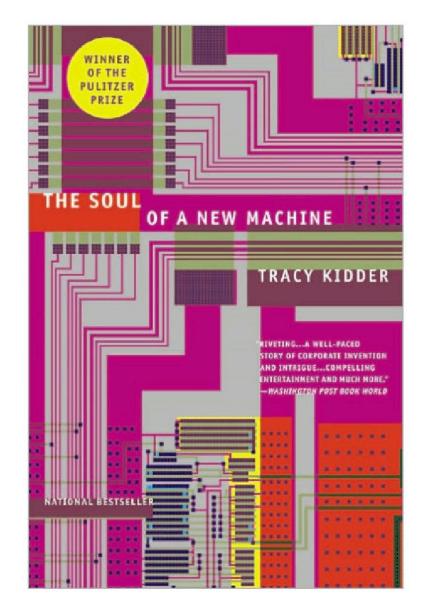
Look Ahead

- Discussion on Reading
- Review of Lab 11
- FPGA Functionality and Incorporation with RTOS



Assignment - Readings

- The Soul Of A New Machine
 - Chapters 7: La Machine
 - Send Me Discussion Topics by 10:00 AM on Thursday, November 14, 2024.





Action Items and Discussion

Al#:	Owner	Slide #	Document	Action